COSC 4364 Spring 2018

Assignment 2

Out: February 1, Due date: February 8.

Problem 1. Solve a system of linear equations Ax=b using Gaussian elimination with and without partial pivoting. Use a matrix size of 1000 x 1000 initialized with random numbers in the interval [-0.5, 0.5]. Initialize the right hand side by computing b=Az with all z values = 1. (Thus, the solution is in fact known.).

Write your own MATLAB function that performs the initialization of A, b and z. The matrix size is chosen with the intent to make the running time long enough for a reasonably good time measurement, but not excessively long. Use *tic* and *toc* to measure execution time.

- a) Write your own MATLAB function in the spirit of the pseudocode in the lecture slides (from the book) that performs Gaussian Elimination *without* partial pivoting and apply it to solve for x in Ax=b with A and b generated by your code as described above. Then compute the mean squared error (MSE) ($\sum (x-1)^2_i$)/N, and the square root thereof (SMSE). Measure the time to compute x. Do not include the time to initialize A, b and z, and the time to compute the average mean squared error ($\sum (x-1)^2_i$)/N, and the square root thereof. Thus, only measure the time to compute x once A and b are known.
 - i) Carry this out in single precision. Report SMSE and time.
 - ii) Carry this out in double precision. Report SMSE and time. Note that by default all variables are represented in double precision. Single precision must be specified explicitly.
- b) Write your own MATLAB function that performs Gaussian Elimination *with* partial pivoting. The coding should be at a comparable level as in a) (i.e., not by using high level MATLAB function calls). Then carry out the same set of computations and measurements as in a) for the same A and b (Do not reinitialize A and b).
- c) Solve Ax=b using the MATLAB built in function Linsolve for the same A and b as in a) and b) using double precision, compute MSE and SMSE and measure the time. Report SMSE and time.

Problem 2. Write a MATLAB function that initializes the matrix such that a(i,j) = 1/(i+j-1) for i,j = 1, 2, ..., 1000. Initialize the vector z with all values 1 as in Problem 1 and compute b=Az as in Problem 1.

- a) Use your MATLAB function for Gaussian Elimination with partial pivoting to compute x in Ax=b, the MSE and SMSE and measure the time.
 - i) Carry this out in single-precision and report SMSE and time.
 - ii) Carry this out in double precision and report SMSE and time.
- b) Use the MATLAB Linsolve function to compute x, then compute MSE and SMSE and measure the time. Report SMSE and time.

The matrix A is known as the Hilbert matrix, which is ill-conditioned.

What to submit: Well commented codes together with a report on error and execution time for the different cases. Explain your results and insights gained from the problems.

Don't forget the UH academic honesty policy