

## I. DEFINITIONS

Sensitivities

$$\bar{x}_\theta = \frac{dx}{d(\log(\theta))} = A \frac{dx}{d\theta}$$

Sensitivity equations

$$\frac{d\bar{x}_\theta}{dt} = \theta \frac{\partial f}{\partial \theta} + \frac{\partial f}{\partial x} \bar{x}_\theta, \quad \text{where } \dot{x} = f(x, \theta, t)$$

Fisher information matrix

$$\frac{d}{dt} I_{ij} = \bar{x}_{\theta_i}^T \Omega \Sigma^{-1} \bar{x}_{\theta_j}, \quad I(0) = \mathbf{0}$$

In calculations I take  $\Omega = \Sigma^{-1} = \mathbf{1}$  (zero noise approximation).

## II. EXAMPLE: SIMPLE HARMONIC OSCILLATOR

The dynamics for a simple harmonic oscillator with amplitude,  $A$ , and time-varying frequency,  $u(t)$ , is given by

$$\dot{x} = \begin{pmatrix} 0 & -(i\dot{u} + u)/A \\ A(i\dot{u} + u) & 0 \end{pmatrix} x, \quad x(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (1)$$

which has the solution

$$x = \begin{pmatrix} \cos(ut) \\ A \sin(ut) \end{pmatrix} \quad (2)$$

Then the sensitivity wrt  $A$  is

$$\bar{x}_A = \begin{pmatrix} 0 \\ A \sin(ut) \end{pmatrix} \quad (3)$$

So that the change in Fisher information is

$$\frac{dI}{dt} = A^2 \sin^2(ut) \quad (4)$$

Then

$$I(u, t) = \int_0^t A^2 \sin^2(ut') dt' \quad (5)$$

Taking  $L(t, u, \dot{u}) = A^2 \sin^2(ut)$  as the Lagrangian, extrema of  $I$  are found by solving the Euler-Lagrange equation

$$\begin{aligned} \frac{\partial L}{\partial u} - \frac{d}{dt} \frac{\partial L}{\partial \dot{u}} &= 0 \\ \Rightarrow 2A^2 t \sin(ut) \cos(ut) &= 0 \\ \Rightarrow \boxed{u = n \frac{\pi}{2t}, \quad n \in \mathbb{Z}^+} \end{aligned}$$

even values of  $n$  give minima of  $I$  whereas odd values of  $n$  give maxima.

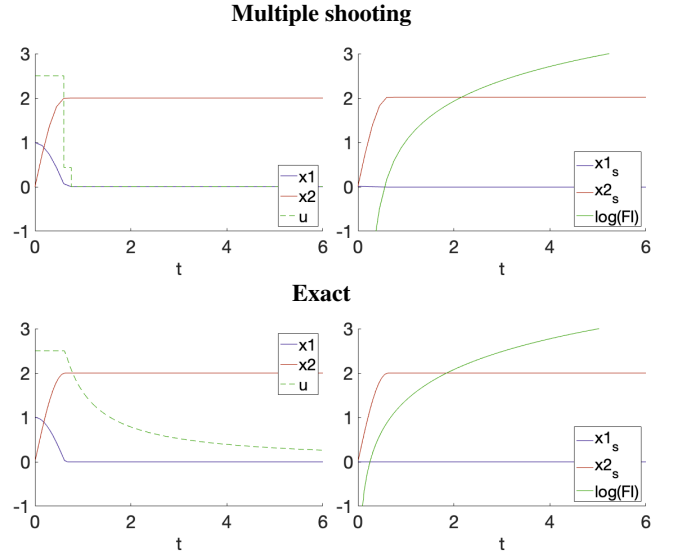


FIG. 1. The parameter value is  $A = 2$ . The constraint on  $u$  is  $0 < u(t) < 2.5$ . (The multiple shooting is actually the optimal solution for (1) if we set  $\dot{u} = 0$ ).