

sd UC2



Operator

«actor»  
Camera

«actor»  
System/  
computer

«actor»  
Arduino

«actor»  
Value

loop

[[while state=UC 2 (Stop) is not call]

Live feed from Camera

1. The system Detects an islet

Collect islet

2. Open valve

Start counter

Counter=0

4. Close valve

3. Valve opens

5. Valve closes

Show islet on GUI

