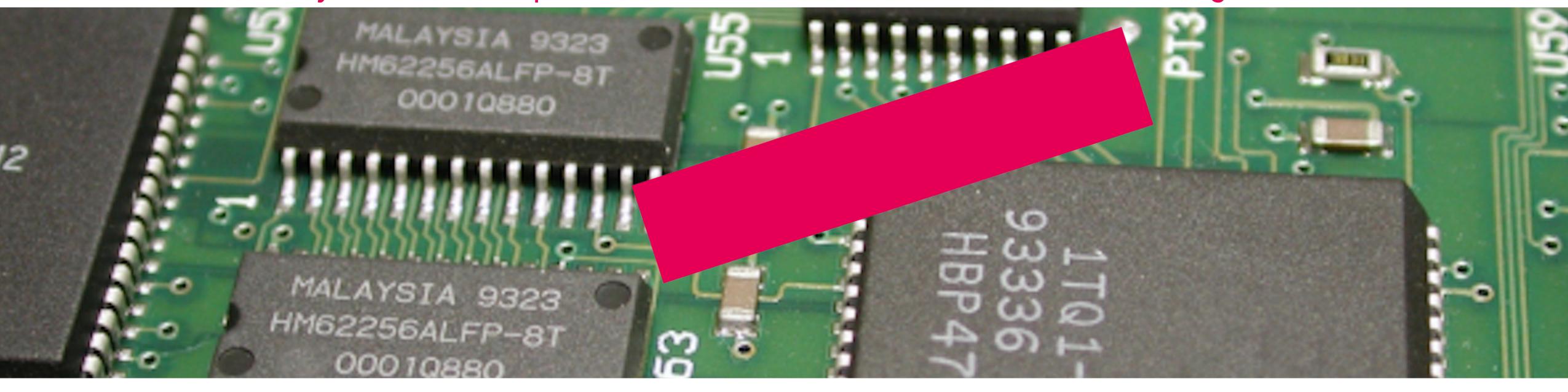
Embedded Systems Development - 7. Constructors, destructors, overriding and unit tests.



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## Schedule (exact info see #00 and roster at insite.han.nl)

		C++	UML
Step 1	Single responsibility	Scope, namespaces, string	Use cases / Class diagram
Step 2	Open-Closed Principle	Constructors, iterators, lambdas	Inheritance / Generalization
Step 3	Liskov Substitution Principle	lists, inline functions, default params	Activities
Step 4	Interface Segregation Principle	interfaces and abstract classes	Depencencies
Step 5	Dependency Inversion Principle	threads, callback	Sequence diagrams
Step 6	Coupling and cohesion	polymorphism	Composition, packages
Step 7	Embedded SOLID	constructors, destructors, const	

#### Next period

Work on your project(s)

Peer reviewing of code

Feedback on diagrams

Feedback on Code

Please fill in the Excel I shared...

Please use <a href="https://github.com/HANEmbedded">https://github.com/HANEmbedded</a>

## Exam preparation (deprecated), use this for final project...

On top of the topics from the previous slide (some items might be on both slides):

#### C++

- constructor and destructor (RAII)
- access (visibility: private / public / protected)
- inheritance: base class, derived class, virtual functions, override
- class / struct
- abstract / interface, Abstract Base Class, abstract member function = 0
- getter / setter
- const-correct
- composite and aggregate
- range based for-loop (foreach) for container classes
- std:: name space, std::vector

#### UML and concepts

- class diagram, composite and aggregate, inheritance
- stereotype / object / actor
- abstract class / interface
- package diagram
- sequence diagram
- polymorphism, polymorphic arrays and vectors
- use cases
- state diagrams, events and states (prior knowledge)

Note: topics from previous C/C++ courses are considered as existing prior knowledge.

Note: the five SOLID principles will not be explicitly asked during the exam but can be helpful during the exam and are considered standard practices for good software engineering.

Typically a variable or object exists as long as it is "in scope"

```
#include <iostream>
class IamAlife {
public:
    IamAlife() {
        std::cout << "I was created ex nihilo!" << std::endl;</pre>
    ~IamAlife() {
        std::cout << "My lifecycle ended: IamAlife is no more :(" << std::endl;</pre>
    void shoutAloud() {
        std::cout << "Whoohoo, IamAlife!" << std::endl;</pre>
int main() {
    std::cout << "There we go..." << std::endl;</pre>
    IamAlife toBeOrNotToBe;
    toBeOrNotToBe.shoutAloud();
    std::cout << "Main almost out of scope..." << std::endl;</pre>
```

#### So default lifecycle:

- object is created in a certain scope...
- see the example if you don't or want to check if you understand scope

Note: lifetime is a runtime property of objects.

#### So default lifecycle:

- object is created in a certain scope...
- see the example if you don't or want to check if you understand scope

But what if you create an object using new...

Typically a variable or object exists as long as it is "in scope": in case you use new this is not handled automatically anymore...

```
#include <iostream>
#include <vector>
class IamAlife {
public:
   IamAlife() {
        std::cout << "I was created ex nihilo!" << std::endl;</pre>
   ~IamAlife() {
        std::cout << "My lifecycle ended: IamAlife is no more :(" << std::endl;</pre>
    void shoutAloud() {
        std::cout << "Whoohoo, IamAlife!" << std::endl;</pre>
};
std::vector<IamAlife *> _hamlets;
int main() {
    std::cout << "There we go..." << std::endl;</pre>
    IamAlife *toBeOrNotToBe = new IamAlife(); // requires delete!!!
    toBeOrNotToBe->shoutAloud();
    std::cout << std::endl;</pre>
    std::cout << "Main goes out of scope after this..." << std::endl;</pre>
    std::cout << "Whoops IamAlife is becoming a zombie..." << std::endl;</pre>
    delete toBeOrNotToBe; // phew... just in time...
```

#### C++ Language: constructor and destructor (RAII)

Resource Acquisition Is Initialization (RAII):

- binds the life cycle of a resource to the lifetime of an object
- that must be acquired before use
- use cases: e.g. allocated heap memory, thread of execution, open socket, open file, locked mutex, disk space, database connection

This helps to prevent resource leaks and makes code exception-safe.

- Encapsulate each resource into a class
- Instance ownership
- No manual release

- Encapsulate each resource into a class

The constructor of the class acquires the resource, and the destructor releases it.

- Instance ownership
- No manual release

- Encapsulate each resource into a class
- Instance ownership

Objects are usually instantiated on the stack or through smart pointers, ensuring deterministic destruction.

- No manual release

- Encapsulate each resource into a class
- Instance ownership
- No manual release

Avoid explicitly releasing resources.

Instead, rely on the destructor to do it automatically when the object goes out of scope.

- Encapsulate each resource into a class
- Instance ownership
- No manual release

#### Benefits:

- Memory Management: Helps avoid memory leaks.
- Exception Safety: Ensures that resources are properly cleaned up if an exception is thrown.
- Simpler Code: Reduces the need for manual resource management.

Strategies to avoid memory leaks:

- garbage collection (e.g. Java) see: <a href="https://en.wikipedia.org/wiki/Garbage\_collection">https://en.wikipedia.org/wiki/Garbage\_collection</a> (computer\_science)
- reference counting (C#, Swift, etc)

In C++ one option is to use *smart pointers*...

#### C++ Language: constructor and destructor (RAII)

C++ does <u>not perform reference-counting by default</u>, fulfilling its philosophy of not adding functionality that might incur overheads where the user has not explicitly requested it. Objects that are shared but not owned can be accessed via a reference, raw pointer, or iterator (a conceptual generalisation of pointers).

However, by the same token, C++ provides native ways for users to opt-into such functionality: C++11 provides reference counted smart pointers, via the std::shared\_ptr class, enabling automatic shared memory-management of dynamically allocated objects.

Programmers can use this in conjunction with weak pointers (via std::weak\_ptr) to break cyclic dependencies. Objects that are dynamically allocated but not intended to be shared can have their lifetime automatically managed using a std::unique\_ptr.

In addition, C++11's move semantics further reduce the extent to which reference counts need to be modified by removing the deep copy normally used when a function returns an object, as it allows for a simple copy of the pointer of said object.

Using smart pointers: <a href="https://www.youtube.com/watch?v=UOB7-B2MfwA">https://www.youtube.com/watch?v=UOB7-B2MfwA</a>

```
#include <iostream>
#include <vector>
#include <memory>
class IamAlife {
public:
    IamAlife() {
        std::cout << "I was created ex nihilo!" << std::endl;</pre>
    ~IamAlife() {
        std::cout << "My lifecycle ended: IamAlife is no more :(" << std::endl;</pre>
    void shoutAloud() {
        std::cout << "Whoohoo, IamAlife!" << std::endl;</pre>
};
std::vector<IamAlife *> _hamlets;
int main() {
    std::cout << "There we go..." << std::endl;</pre>
    std::cout << std::endl;</pre>
    { // local sub scope
        std::unique_ptr<IamAlife> toBeOrNotToBe(new IamAlife());
        toBeOrNotToBe->shoutAloud();
    std::cout << std::endl;</pre>
    std::cout << "Main goes out of scope after this..." << std::endl;</pre>
```

Using smart pointers: <a href="https://www.youtube.com/watch?v=UOB7-B2MfwA">https://www.youtube.com/watch?v=UOB7-B2MfwA</a>

```
// A. unique pointer:
std::unique_ptr<IamAlife> toBeOrNotToBe = std::make_unique<IamAlife>();
toBeOrNotToBe->shoutAloud();

// is preferred over this B.
std::unique_ptr<IamAlife> toBeOrNotToBe(new IamAlife());
toBeOrNotToBe->shoutAloud();
```

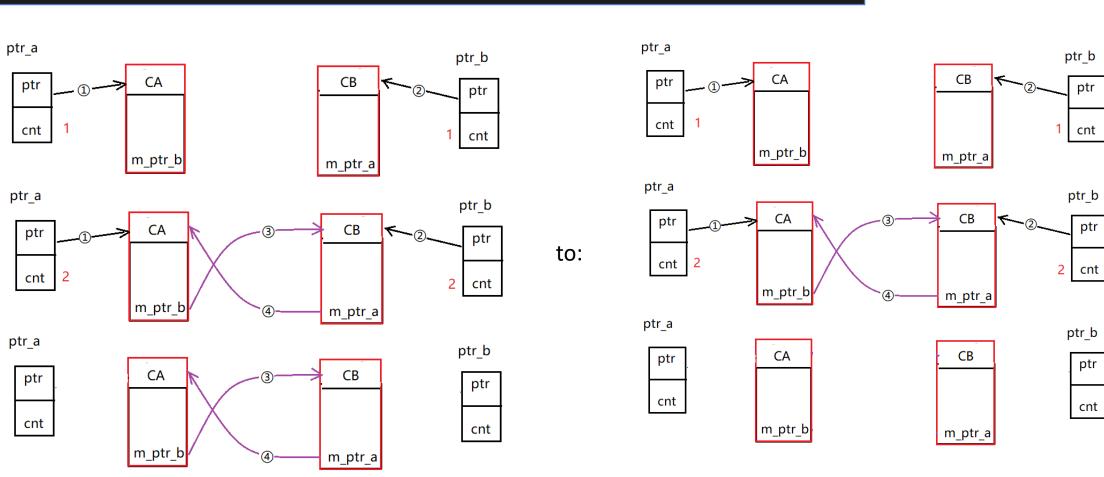
Reason to prefer option A over B is for exception purposes (A is safer / more robust agains exceptions).

Using smart pointers: <a href="https://www.youtube.com/watch?v=UOB7-B2MfwA">https://www.youtube.com/watch?v=UOB7-B2MfwA</a>

```
// Shared pointer:
std::unique_ptr<IamAlife> toBeOrNotToBe = std::make_shared<IamAlife>();
toBeOrNotToBe->shoutAloud();

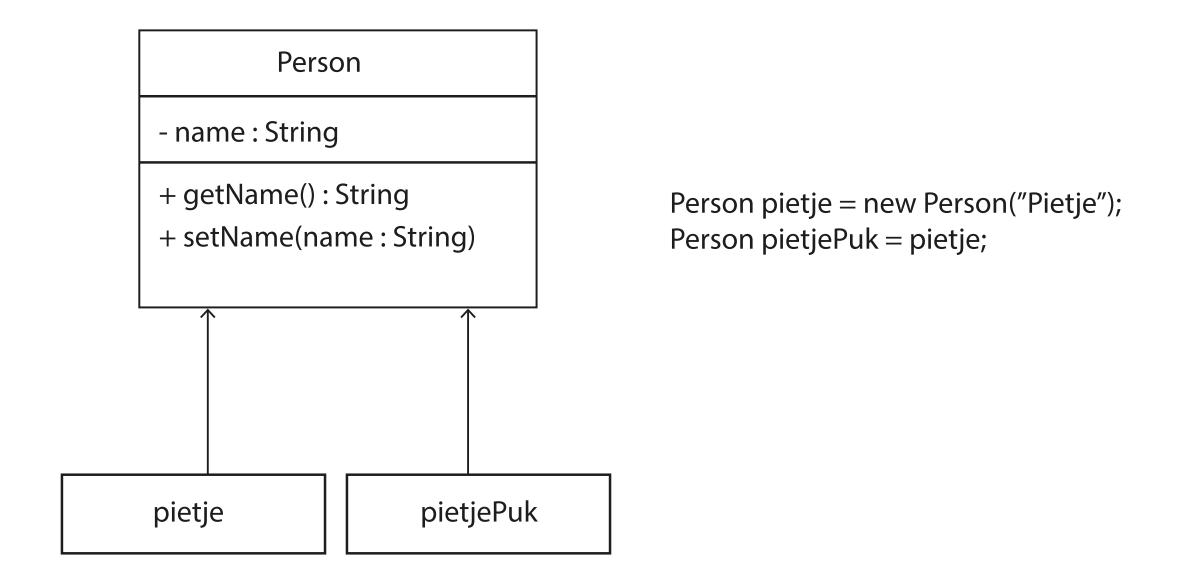
// Weak pointer:
std::weak_ptr<IamAlife> weakPointer = toBeOrNotToBe;
weakPointer->shoutAloud();
```

Weak helps reference counting to work properly and avoid memory leaks:



Note: the following is of course very powerful (useful cases would include doubly linked lists).

This will not work when using unique pointers!



## Let's have a look at the example code...

simpleLifecycle.cpp
smartPointersLifecycle.cpp
moreComplexLifecycle.cpp
betterSmartPointersLifecycle.cpp

### C++ Language: const-correctness (simple variables)

Const-correctness means using the keyword const to prevent const objects from getting mutated (in other words: making them *immutable*).

- the const keyword in front of a property
- const int counter = 10;
- remember: use a constructor to write only once to a const class attribute

# C++ Language: const-correctness (arguments for methods)

Const-correctness means using the keyword const to prevent const objects from getting mutated.

```
Arguments (aka parameters) in methods:
```

```
- void f1(const std::string& s); // Pass by reference-to-const- void f2(const std::string* sptr); // Pass by pointer-to-const
```

```
- void f3(std::string s); // Pass by value
```



#### C++ Language: const-correctness (const methods)

Const-correctness means using the keyword const to prevent const objects from getting mutated.

E.g. if you want to make a calculation using some function (= a method intended to give back a result):

```
int Loan::calcInterest() const
{
    return loan_value * interest_rate;
}
```

#### C++ Language: override

Override will allow to use the same method (including arguments and return) and override it's behavior in the same and/or subclasses.

```
struct A
{
    virtual void foo();
    void bar();
};

struct B : A
{
    void foo() override; // OK: B::foo overrides A::foo
};
```

### C++ Language: override / shadowing

Override will allow to use the same method (including arguments and return) and override it's behavior in the same and/or subclasses.

```
struct Base
{
    virtual void foo();
    void bar();
    Base(); // constructor of Base
};

struct Derived : Base
{
    using Base::foo; // now foo method(s) from Base will become visible in Derived
    using Base::Base; // now we can use the constructor from Base in Derived
};
```

# C++ Language: warning: shadowing/masking

You could get into trouble if you are not careful with overloading (inadvertently typecasting):

```
class Base {
 public:
  int F(int i) { return i; };
};
class Derived : public Base {
 public:
  //using Base::F;
  double F(double d) { return d; };
int main() {
    // Note if you forget using using Base::F, this will still work:
    Derived d = Derived();
    std::cout << std::to_string(d.F(10)) << std::endl;</pre>
                                                            jakorten@mbp-van-ja-2221 Constructors % ./constructors
First output with using Base::F; enabled:
                                                            jakorten@mbp-van-ja-2221 Constructors % c++ constructors.cpp -o constructors
                                                            jakorten@mbp-van-ja-2221 Constructors % ./constructors
Second output with code as shown above:
                                                            jakorten@mbp-van-ja-2221 Constructors % ∏
```

#### C++ Language: override

Making override explicit by adding *override* (C++11 and up) will allow the compiler to check the base class to see if there is a virtual function with this exact signature. And if there is not, the compiler will show an error.

#### SOLID in an Embedded Context

SOLID principles in embedded systems may have (additional) challenges.

However it can significantly enhance the *design*, *scalability*, and *maintainability* of embedded software, leading to more **robust** and **reliable** embedded systems.

#### SOLID in an Embedded Context

SOLID principles in embedded systems may have (additional) challenges.

However it can significantly enhance the *design*, *scalability*, and *maintainability* of embedded software, leading to more **robust** and **reliable** embedded systems.

## **S**OLID in an Embedded Context: Single Responsibility Principle (SRP)

#### **Embedded Context:**

#### Modularize your code:

- Write functions and modules with a single responsibility. For example, separate the code that handles hardware interfacing from the business logic.

Use clear and concise naming conventions:

- This makes it easy to understand what each module or function is responsible for, enhancing maintainability.

### SOLID in an Embedded Context: Open/Closed Principle (OCP)

#### **Embedded Context:**

Leverage polymorphism for hardware abstraction:

- You can define a base class (or interface) for a hardware device (HAL), and then extend it for specific device implementations.
- This way, your code remains open for extension but closed for modification.

Use function pointers or callbacks:

- This allows you to change behavior without modifying existing code.

(e.g. use patterns including Depency Injection)

#### SOLID in an Embedded Context: Liskov Substitution Principle (LSP)

#### **Embedded Context:**

Ensure compatibility of derived classes:

- If using object-oriented programming, make sure that derived classes can be used in place of their base classes without causing unexpected behavior.

Carefully manage hardware dependencies:

- Ensure that derived classes do not introduce hardware dependencies that could break the substitutability principle.

## SOLID in an Embedded Context: Interface Segregation Principle (ISP)

#### **Embedded Context:**

Provide device-specific interfaces:

- For hardware drivers and peripherals, offer interfaces tailored to the specific functionalities each component uses, rather than a monolithic interface.
- Minimize dependencies: Ensure that each module or component only includes the minimal interface it needs, reducing the footprint and complexity.

#### SOLID in an Embedded Context: Dependency Inversion Principle (DIP)

#### **Embedded Context:**

Use abstract interfaces for hardware components:

- This allows high-level modules to depend on abstractions rather than concrete implementations, facilitating testing and system modifications.

#### Employ dependency injection:

- Pass dependencies (e.g., hardware interfaces) as parameters to functions or objects, allowing you to easily substitute different implementations for testing or system configuration.

(e.g. use patterns including Depency Injection)

#### SOLID in an Embedded Context: Considerations

- Memory Constraints
- Performance Constraints
- Testing and Simulation
- Documentation and Code Comments

#### - Memory Constraints

Be mindful of the memory overhead introduced by abstractions and object-oriented features. Optimize data structures and minimize dynamic memory allocation.

- Performance Constraints
- Testing and Simulation
- Documentation and Code Comments

- Memory Constraints
- Performance Constraints

Evaluate the performance impact of abstractions and interface layers, ensuring that the system meets its real-time requirements.

- Testing and Simulation
- Documentation and Code Comments

- Memory Constraints
- Performance Constraints
- Testing and Simulation

Use the abstraction layers to facilitate unit testing and hardware-in-the-loop simulation by substituting real hardware interfaces with mock or simulated implementations.

- Documentation and Code Comments

- Memory Constraints
- Performance Constraints
- Testing and Simulation
- Documentation and Code Comments

Maintain thorough documentation and inline comments to help developers understand the design principles and interfaces, contributing to easier maintenance and enhancements.

(May I suggest you to use Doxygen?!)

# Introduction to testing.

First of all: What is the difference between debugging and testing?

## Introduction to testing in VS Code

#### Debugger in VS Code:

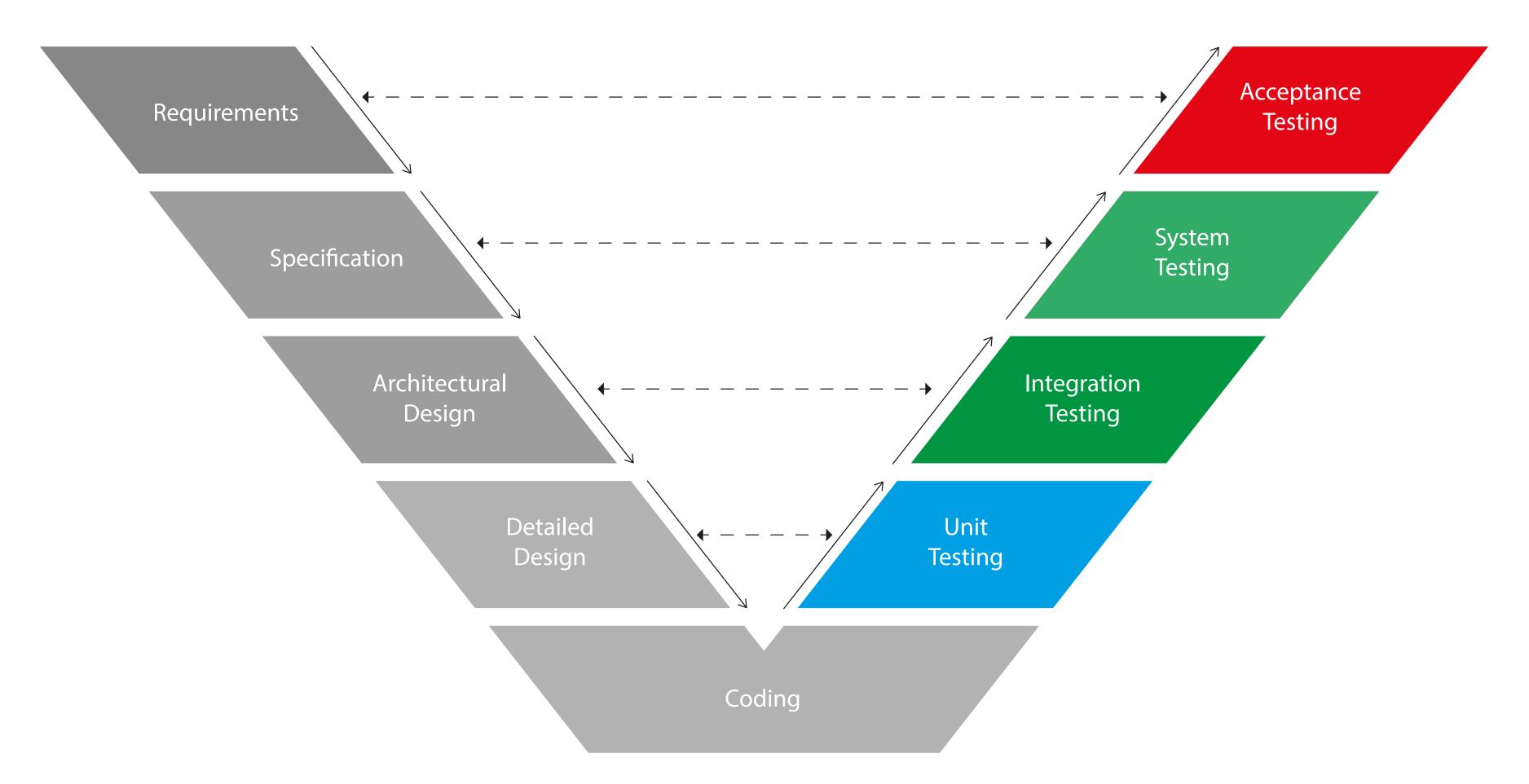
- https://code.visualstudio.com/docs/cpp/launch-json-reference
- https://code.visualstudio.com/docs/editor/debugging

#### Breakpoints, locals and watches:

Note: (at least on macOS) it seems to require clang++ and llvm

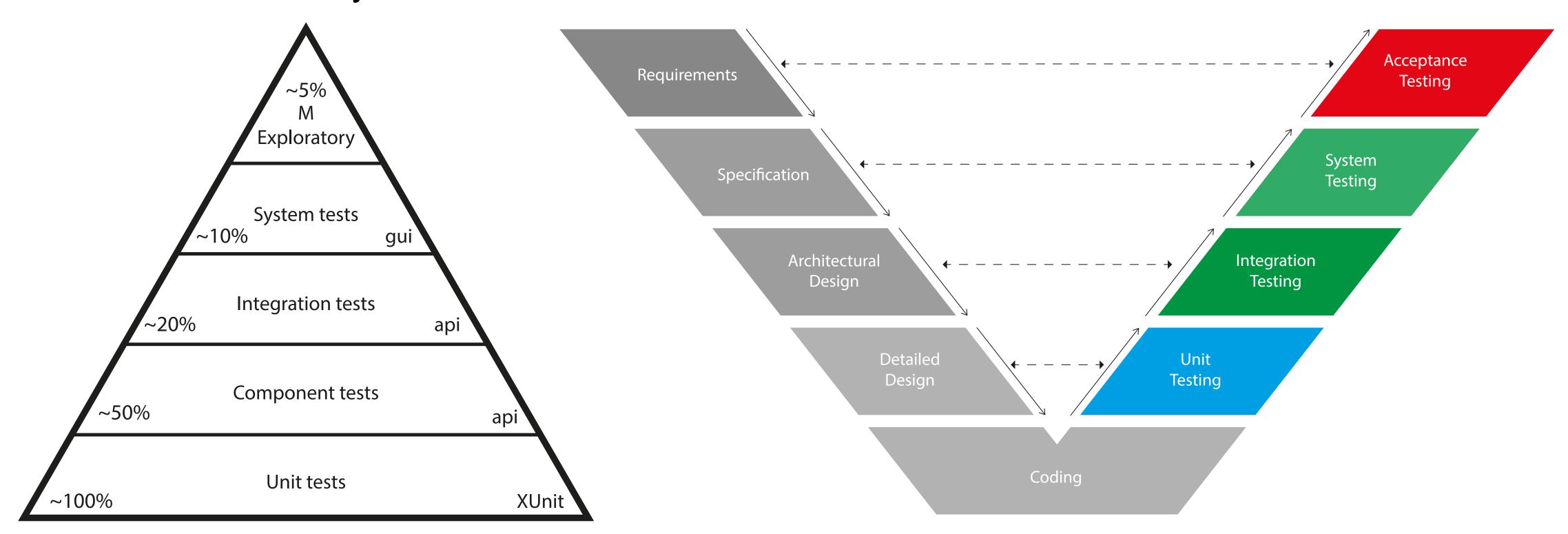


## Testing in an Embedded Systems Software Engineering context



## Testing

Martin (2011, p.115)
provides us with
the "Test Automation Pyramid":



### Testing: Basic Unit testing in C++

For this period we will only introduce Unit testing.

#### Some basic rules for Unit tests:

- Testing uses exactly one assert per test.
- Avoid if-statements.
- Unit tests only "new()" the unit under test.
- Unit tests do not contain hard-coded values unless they have a specific meaning.
- Unit tests are stateless.
- Unit test should be fallible (read: are only useful if they can fail in the first place).

### Testing: Basic Unit testing in C++

https://code.visualstudio.com/api/working-with-extensions/testing-extension
https://marketplace.visualstudio.com/items?itemName=drleq.vscode-cpputf-test-adapter

Note: For some reason I need to add #include <cmath> to CppUnitTestFramework.hpp

## Testing: Basic Unit testing in C++

```
#define GENERATE_UNIT_TEST_MAIN
#include "CppUnitTestFramework.hpp"
#include <iostream>
class TestMe {
public:
    const int age = 10;
    TestMe() {
        std::cout << "I was created ex nihilo!" << std::endl;</pre>
    ~TestMe() {
        std::cout << "My lifecycle ended: TestMe is no more :(" << std::endl;</pre>
};
TestMe iLoveTesting;
TEST_CASE(TestMe, Test1) {
        CHECK_EQUAL(age, 9);
```

# One more thing:

Remember to use doxygen for your documentation.

