# Numerical Methods in Economics MIT Press, 1998

# Notes for Chapter 7: Numerical Integration and Differentiation

November 22, 2006

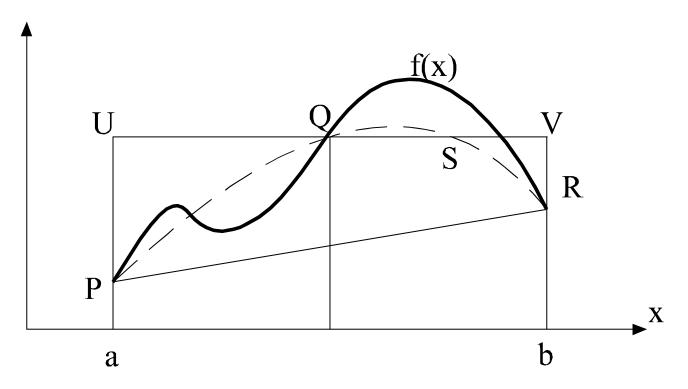
# Integration

- Most integrals cannot be evaluated analytically
- Integrals frequently arise in economics
  - Expected utility
  - Discounted utility and profits over a long horizon
  - Bayesian posterior
  - Likelihood functions
  - Solution methods for dynamic economic models

~

#### Newton-Cotes Formulas

• Idea: Approximate function with low order polynomials and then integrate approximation



- Step function approximation:
  - Compute constant function equalling f(x) at midpoint of [a,b]
  - Integral approximation is aUQVb box
- Linear function approximation:
  - Compute linear function interpolating f(x) at a and b
  - Integral approximation is trapezoid aPRb

- Parabolic function approximation:
  - Compute parabola interpolating f(x) at a, b, and (a + b)/2
  - Integral approximation is area of aPQRb

• Midpoint Rule: piecewise step function approximation

$$\int_{a}^{b} f(x) \ dx = (b-a) \ f\left(\frac{a+b}{2}\right) + \frac{(b-a)^{3}}{24} f''(\xi)$$

– Simple rule: for some  $\xi \in [a, b]$ 

$$\int_{a}^{b} f(x) \ dx = (b-a) \ f\left(\frac{a+b}{2}\right) + \frac{(b-a)^{3}}{24} f''(\xi)$$

- Composite midpoint rule:
  - \* nodes:  $x_j = a + (j \frac{1}{2})h$ , j = 1, 2, ..., n, h = (b a)/n
  - \* for some  $\xi \in [a, b]$

$$\int_{a}^{b} f(x) dx = h \sum_{i=1}^{n} f\left(a + (j - \frac{1}{2})h\right) + \frac{h^{2}(b-a)}{24} f''(\xi)$$

- Trapezoid Rule: piecewise linear approximation
  - Simple rule: for some  $\xi \in [a, b]$

$$\int_{a}^{b} f(x) \ dx = \frac{b-a}{2} \left[ f(a) + f(b) \right] - \frac{(b-a)^{3}}{12} f''(\xi)$$

- Composite trapezoid rule:
  - \* nodes:  $x_j = a + (j \frac{1}{2})h$ , j = 1, 2, ..., n, h = (b a)/n
  - \* for some  $\xi \in [a, b]$

$$\int_{a}^{b} f(x) dx = \frac{h}{2} \left[ f_0 + 2f_1 + \dots + 2f_{n-1} + f_n \right] - \frac{h^2 (b-a)}{12} f''(\xi)$$

~

- Simpson's Rule: piecewise quadratic approximation
  - for some  $\xi \in [a, b]$

$$\int_{a}^{b} f(x) dx = \left(\frac{b-a}{6}\right) \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right] - \frac{(b-a)^{5}}{2880} f^{(4)}(\xi)$$

– Composite Simpson's rule: for some  $\xi \in [a, b]$ 

$$\int_{a}^{b} f(x) dx = \frac{h}{3} \left[ f_0 + 4f_1 + 2f_2 + 4f_3 + \dots + 4f_{n-1} + f_n \right] - \frac{h^4(b-a)}{180} f^{(4)}(\xi)$$

• Obscure rules for degree 3, 4, etc. approximations.

\_

#### Change of Variables Formula and Infinite Domains

• Problem: How do we approximate integrals with infinite domains?

$$\int_0^\infty f(x)dx \equiv \lim_{b \to \infty} \int_0^b f(x) \, dx$$

• Truncation (a bad idea): For large b, use

$$\int_0^\infty f(x)dx \doteq \int_0^b f(x) \, dx$$

• Change of variables theorem:

**Theorem 1** If  $\phi : \mathbb{R} \to \mathbb{R}$  is a monotonically increasing,  $C^1$  function on the (possibly infinite) interval [a,b], then for any integrable g(y) on [a,b],

$$\int_{a}^{b} g(y) \ dy = \int_{\phi^{-1}(a)}^{\phi^{-1}(b)} g(\phi(x)) \ \phi'(x) \ dx. \tag{7.1.8}$$

~

• COV Objective: find a x(z) function such that

$$\int_0^\infty f(x) \ dx = \int_0^1 f(x(z)) x'(z) dz$$

can be accurately computed.

$$-x:(0,1)\to(0,\infty)$$
:  $x(z)=\frac{z}{1-z}, x'(z)=\frac{1}{(1-z)^2}$ 

\* Example:

$$\int_0^\infty e^{-t}t^n dt = \int_0^1 e^{-z/(1-z)} \left(\frac{z}{1-z}\right)^n (1-z)^{-2} dz.$$

\* All derivatives are bounded, so Newton-Cotes error bound formulas applies.

$$-x:(0,1)\to(-\infty,\infty): x(z)=\ln\left(\frac{z}{1-z}\right), x'(z)=(z(1-z))^{-1}$$

\* Example:  $\int_{-\infty}^{\infty} e^{-x^2} f(x) dx$  becomes

$$\int_{0}^{1} e^{-(\ln \frac{z}{(1-z)})^{2}} f\left(\ln(\frac{z}{1-z})\right) \frac{dz}{(1-z)z}$$

$$= \int_{0}^{1} \left(\frac{1-z}{z}\right)^{\ln \frac{z}{(1-z)}} f\left(\ln(\frac{z}{1-z})\right) \frac{dz}{z(1-z)}$$

- \* Integrand's derivatives are bounded if f is exponentially bounded
- Bad COV formula
  - \*  $x(z) = \left(\ln \frac{z}{1-z}\right)^{1/3} \text{ maps } (0,1) \text{ onto } (-\infty,\infty)$
  - \* Application to  $\int_{-\infty}^{\infty} f(x)e^{-x^2} dx$  often creates an integrand with unbounded derivatives.

#### Gaussian Formulas

• All integration formulas are of form

$$\int_{a}^{b} f(x) dx \doteq \sum_{i=1}^{n} \omega_{i} f(x_{i})$$

$$(7.2.1)$$

for some quadrature nodes  $x_i \in [a, b]$  and quadrature weights  $\omega_i$ .

- Newton-Cotes use arbitrary  $x_i$
- Gaussian quadrature uses good choices of  $x_i$  nodes and  $\omega_i$  weights.
- Exact quadrature formulas:
  - Let  $\mathcal{F}_k$  be the space of degree k polynomials
  - A quadrature formula is exact of degree k if it correctly integrates each function in  $\mathcal{F}_k$
  - Gaussian quadrature formulas use n points and are exact of degree 2n-1

**Theorem 2** Suppose that  $\{\varphi_k(x)\}_{k=0}^{\infty}$  is an orthonormal family of polynomials with respect to w(x) on [a, b].

- 1. Define  $q_k$  so that  $\varphi_k(x) = q_k x^k + \cdots$ .
- 2. Let  $x_i$ , i = 1, ..., n be the n zeros of  $\varphi_n(x)$
- 3. Let  $\omega_i = -\frac{q_{n+1}/q_n}{\varphi'_n(x_i)\,\varphi_{n+1}(x_i)} > 0$

Then

- 1.  $a < x_1 < x_2 < \cdots < x_n < b$ ;
- 2. if  $f \in C^{(2n)}[a, b]$ , then for some  $\xi \in [a, b]$ ,

$$\int_{a}^{b} w(x) f(x) dx = \sum_{i=1}^{n} \omega_{i} f(x_{i}) + \frac{f^{(2n)}(\xi)}{q_{n}^{2}(2n)!};$$

3. and  $\sum_{i=1}^{n} \omega_i f(x_i)$  is the unique formula on n nodes that exactly integrates  $\int_a^b f(x) w(x) dx$  for all polynomials in  $\mathcal{F}_{2n-1}$ .

. .

#### Gauss-Chebyshev Quadrature

• Domain: [-1, 1]

• Weight:  $(1-x^2)^{-1/2}$ 

• Formula:

$$\int_{-1}^{1} f(x)(1-x^2)^{-1/2} dx = \frac{\pi}{n} \sum_{i=1}^{n} f(x_i) + \frac{\pi}{2^{2n-1}} \frac{f^{(2n)}(\xi)}{(2n)!}$$
 (7.2.4)

for some  $\xi \in [-1, 1]$ , with quadrature nodes

$$x_i = \cos\left(\frac{2i-1}{2n}\pi\right), \quad i = 1, ..., n.$$
 (7.2.5)

# Arbitrary Domains

- Want to approximate  $\int_a^b f(x) dx$ 
  - Different range, no weight function
  - Linear change of variables x = -1 + 2(y a)(b a)
  - Multiply the integrand by  $(1-x^2)^{1/2}/(1-x^2)^{1/2}$ .
  - C.O.V. formula

$$\int_{a}^{b} f(y) \ dy = \frac{b-a}{2} \int_{-1}^{1} f\left(\frac{(x+1)(b-a)}{2} + a\right) \frac{\left(1-x^{2}\right)^{1/2}}{\left(1-x^{2}\right)^{1/2}} \ dx$$

- Gauss-Chebyshev quadrature produces

$$\int_{a}^{b} f(y) dy \doteq \frac{\pi(b-a)}{2n} \sum_{i=1}^{n} f\left(\frac{(x_{i}+1)(b-a)}{2} + a\right) \left(1 - x_{i}^{2}\right)^{1/2}$$

where the  $x_i$  are Gauss-Chebyshev nodes over [-1, 1].

# Gauss-Legendre Quadrature

- Domain: [-1, 1]
- Weight: 1
- Formula:

$$\int_{-1}^{1} f(x) dx = \sum_{i=1}^{n} \omega_{i} f(x_{i}) + \frac{2^{2n+1} (n!)^{4}}{(2n+1)! (2n)!} \cdot \frac{f^{(2n)}(\xi)}{(2n)!}$$

for some  $-1 \le \xi \le 1$ .

- Convergence:
  - use  $n! \doteq e^{-n-1} n^{n+1/2} \sqrt{2\pi n}$
  - error bounded above by  $\pi 4^{-n} M$

$$M = \sup_{m} \left[ \max_{-1 \le x \le 1} \frac{f^{(m)}(x)}{m!} \right]$$

- Exponential convergence for analytic functions
- In general,

$$\int_{a}^{b} f(x) \, dx \doteq \frac{b-a}{2} \sum_{i=1}^{n} \omega_{i} f\left(\frac{(x_{i}+1)(b-a)}{2} + a\right)$$

• Use values for Gaussian nodes and weights from tables instead of programs; tables will have 16 digit accuracy

Table 7.2: Gauss – Legendre Quadrature

N	$x_i$	$\omega_i$
2	0.5773502691	0.1000000000(1)
0	0.7745000000	0 55555555
3	0.7745966692	0.555555555
	0.0000000000	0.888888888
5	0.9061798459	0.2369268850
	0.5384693101	0.4786286704
	0.0000000000	0.5688888888
10	0.9739065285	0.6667134430(-1)
	0.8650633666	0.1494513491
	0.6794095682	0.2190863625
	0.4333953941	0.2692667193
	0.1488743389	0.2955242247

#### Life-cycle example:

- $c(t) = 1 + t/5 7(t/50)^2$ , where  $0 \le t \le 50$ .
- Discounted utility is  $\int_0^{50} e^{-\rho t} u(c(t)) dt$
- $\rho = 0.05$ ,  $u(c) = c^{1+\gamma}/(1+\gamma)$ .
- Errors in computing  $\int_0^{50} e^{-.05t} \left(1 + \frac{t}{5} 7\left(\frac{t}{50}\right)^2\right)^{1-\gamma} dt$

	$\gamma =$	.5	1.1	3	10
Truth		1.24431	.664537	.149431	.0246177
Rule:	GLeg 3	5(-3)	2(-3)	3(-2)	2(-2)
	GLeg $5$	1(-4)	8(-5)	5(-3)	2(-2)
	GLeg 10	1(-7)	1(-7)	2(-5)	2(-3)
	GLeg 15	1(-10)	2(-10)	9(-8)	4(-5)
	GLeg 20	7(-13)	9(-13)	3(-10)	6(-7)

. .

# Gauss-Hermite Quadrature

- Domain:  $[-\infty, \infty]$
- Weight:  $e^{-x^2}$
- Formula:

$$\int_{-\infty}^{\infty} f(x)e^{-x^2}dx = \sum_{i=1}^{n} \omega_i f(x_i) + \frac{n!\sqrt{\pi}}{2^n} \cdot \frac{f^{(2n)}(\xi)}{(2n)!}$$

for some  $\xi \in (-\infty, \infty)$ .

. \_

Table 7.4: Gauss – Hermite Quadrature

N	$x_i$	$\omega_i$
2	0.7071067811	0.8862269254
3	0.1224744871(1)	0.2954089751
	0.0000000000	0.1181635900(1)
4	0.1650680123(1)	0.8131283544(-1)
	0.5246476232	0.8049140900
7	0.2651961356(1)	0.9717812450(-3)
	0.1673551628(1)	0.5451558281(-1)
	0.8162878828	0.4256072526
	0.0000000000	0.8102646175
10	0.3436159118(1)	0.7640432855(-5)
	0.2532731674(1)	0.1343645746(-2)
	0.1756683649(1)	0.3387439445(-1)
	0.1036610829(1)	0.2401386110
	0.3429013272	0.6108626337

- Normal Random Variables
  - -Y is distributed  $N(\mu, \sigma^2)$
  - Expectation is integration:

$$E\{f(Y)\} = (2\pi\sigma^2)^{-1/2} \int_{-\infty}^{\infty} f(y)e^{-\frac{(y-\mu)^2}{2\sigma^2}} dy$$

- Use Gauss-Hermite quadrature
  - \* linear COV  $x = (y \mu)/\sqrt{2} \sigma$
  - \* COV formula:

$$\int_{-\infty}^{\infty} f(y)e^{-(y-\mu)^2/(2\sigma^2)} \, dy = \int_{-\infty}^{\infty} f(\sqrt{2}\,\sigma\,x + \mu)e^{-x^2}\sqrt{2}\,\sigma\,dx$$

\* COV quadrature formula:

$$E\{f(Y)\} \doteq \pi^{-\frac{1}{2}} \sum_{i=1}^{n} \omega_i f(\sqrt{2} \sigma x_i + \mu)$$

where the  $\omega_i$  and  $x_i$  are the Gauss-Hermite quadrature weights and nodes over  $[-\infty, \infty]$ .

- Portfolio example
  - An investor holds one bond which will be worth 1 in the future and equity whose value is Z, where  $\ln Z \sim \mathcal{N}(\mu, \sigma^2)$ .
  - Expected utility is

$$U = (2\pi\sigma^2)^{-1/2} \int_{-\infty}^{\infty} u(1+e^z)e^{-(z-\mu)^2/2\sigma^2} dz$$

$$u(c) = \frac{c^{1+\gamma}}{1+\gamma}$$
(7.2.12)

and the certainty equivalent of (7.2.12) is  $u^{-1}(U)$ .

- Errors in certainty equivalents: Table 7.5

Rule 
$$\gamma$$
:  $-.5$   $-1.1$   $-2.0$   $-5.0$   $-10.0$  GH2  $1(-4)$   $2(-4)$   $3(-4)$   $6(-3)$   $3(-2)$  GH3  $1(-6)$   $3(-6)$   $9(-7)$   $7(-5)$   $9(-5)$  GH4  $2(-8)$   $7(-8)$   $4(-7)$   $7(-6)$   $1(-4)$  GH7  $3(-10)$   $2(-10)$   $3(-11)$   $3(-9)$   $1(-9)$  GH13  $3(-10)$   $2(-10)$   $3(-11)$   $5(-14)$   $2(-13)$ 

• The certainty equivalent of (7.2.12) with  $\mu = 0.15$  and  $\sigma = 0.25$  is 2.34. So, relative errors are roughly the same.

- -

# Gauss-Laguerre Quadrature

- Domain:  $[0, \infty]$
- Weight:  $e^{-x}$
- Formula:

$$\int_0^\infty f(x)e^{-x}dx = \sum_{i=1}^n \omega_i f(x_i) + (n!)^2 \frac{f^{(2n)}(\xi)}{(2n)!}$$

for some  $\xi \in [0, \infty)$ .

- General integral
  - Linear COV x = r(y a)
  - COV formula

$$\int_{a}^{\infty} e^{-ry} f(y) \ dy \doteq \frac{e^{-ra}}{r} \sum_{i=1}^{n} \omega_{i} f\left(\frac{x_{i}}{r} + a\right)$$

where the  $\omega_i$  and  $x_i$  are the Gauss-Laguerre quadrature weights and nodes over  $[0, \infty]$ .

\_ .

Table 7.6: Gauss – Laguerre Quadrature

$x_i$	$\omega_i$
0.5857864376	0.8535533905
0.3414213562(1)	0.1464466094
0.4157745567	0.7110930099
0.2294280360(1)	0.2785177335
0.6289945082(1)	0.1038925650(-1)
0.3225476896	0.6031541043
	0.3574186924
0.4536620296(1)	0.3888790851(-1)
0.9395070912(1)	0.5392947055(-3)
0 1930436765	0.4093189517
	0.4218312778
0.2567876744(1)	0.1471263486
0.4900353084(1)	0.2063351446(-1)
0.8182153444(1)	0.1074010143(-2)
0.1273418029(2)	0.1586546434(-4)
0.1939572786(2)	0.3170315478(-7)
	0.5857864376 0.3414213562(1)  0.4157745567 0.2294280360(1) 0.6289945082(1)  0.3225476896 0.1745761101(1) 0.4536620296(1) 0.9395070912(1)  0.1930436765 0.1026664895(1) 0.2567876744(1) 0.4900353084(1) 0.8182153444(1) 0.1273418029(2)

- -

#### • Present Value Example

- Use Gauss-Laguerre quadrature to compute present values.
- Suppose discounted profits equal

$$\eta \left(\frac{\eta - 1}{\eta}\right)^{\eta - 1} \int_0^\infty e^{-rt} m(t)^{1 - \eta} dt.$$

- Errors: Table 7.7

$$r = .05 \quad r = .10 \quad r = .05$$

$$\lambda = .05 \quad \lambda = .05 \quad \lambda = .20$$
Truth: 
$$49.7472 \quad 20.3923 \quad 74.4005$$
Errors: GLag 4 
$$3(-1) \quad 4(-2) \quad 6(0)$$
GLag 5 
$$7(-3) \quad 7(-4) \quad 3(0)$$
GLag 10 
$$3(-3) \quad 6(-5) \quad 2(-1)$$
GLag 15 
$$6(-5) \quad 3(-7) \quad 6(-2)$$
GLag 20 
$$3(-6) \quad 8(-9) \quad 1(-2)$$

- Gauss-Laguerre integration implicitly assumes that  $m(t)^{1-\eta}$  is a polynomial.
  - \* When  $\lambda = 0.05$ , m(t) is nearly constant
  - \* When  $\lambda = 0.20$ ,  $m(t)^{1-\eta}$  is less polynomial-like.

#### General Applicability of Gaussian Quadrature

**Theorem 3** (Gaussian quadrature convergence) If f is Riemann Integrable on [a,b], the error in the n-point Gauss-Legendre rule applied to  $\int_a^b f(x) dx$  goes to 0 as  $n \to \infty$ .

#### Comparisons with Newton-Cotes formulas: Table 7.1

Rule	n	$\int_0^1 x^{1/4} dx$	$\int_1^{10} x^{-2} dx$	$\int_0^1 e^x dx$	$\int_{1}^{-1} (x + .05)^{+} dx$
Trapezoid	4	0.7212	1.7637	1.7342	0.6056
	7	0.7664	1.1922	1.7223	0.5583
	10	0.7797	1.0448	1.7200	0.5562
	13	0.7858	0.9857	1.7193	0.5542
Simpson	3	0.6496	1.3008	1.4662	0.4037
	7	0.7816	1.0017	1.7183	0.5426
	11	0.7524	0.9338	1.6232	0.4844
	15	0.7922	0.9169	1.7183	0.5528
G-Legendre	4	0.8023	0.8563	1.7183	0.5713
	7	0.8006	0.8985	1.7183	0.5457
	10	0.8003	0.9000	1.7183	0.5538
	13	0.8001	0.9000	1.7183	0.5513
Truth		.80000	.90000	1.7183	0.55125

# Multidimensional Integration

- Most economic problems have several dimensions
  - Multiple assets
  - Multiple error terms
- $\bullet$  Multidimensional integrals are much more difficult
  - Simple methods suffer from curse of dimensionality
  - There are methods which avoid curse of dimensionality

\_ . .

#### Product Rules

- Build product rules from one-dimension rules
- Let  $x_i^{\ell}$ ,  $\omega_i^{\ell}$ ,  $i = 1, \dots, m$ , be one-dimensional quadrature points and weights in dimension  $\ell$  from a Newton-Cotes rule or the Gauss-Legendre rule.
- The product rule

$$\int_{[-1,1]^d} f(x)dx \doteq \sum_{i_1=1}^m \cdots \sum_{i_d=1}^m \omega_{i_1}^1 \omega_{i_2}^2 \cdots \omega_{i_d}^d f(x_{i_1}^1, x_{i_2}^2, \cdots, x_{i_d}^d)$$

- Gaussian structure prevails
  - Suppose  $w^{\ell}(x)$  is weighting function in dimension  $\ell$
  - Define the d-dimensional weighting function.

$$W(x) \equiv W(x_1, \cdots, x_d) = \prod_{\ell=1}^d w^{\ell}(x_{\ell})$$

- Product Gaussian rules are based on product orthogonal polynomials.
- Curse of dimensionality:
  - $-m^d$  functional evaluations is  $m^d$  for a d-dimensional problem with m points in each direction.
  - Problem worse for Newton-Cotes rules which are less accurate in  $\mathbb{R}^1$ .

# Monomial Formulas: A Nonproduct Approach

- Method
- Choose  $x^i \in D \subset \mathbb{R}^d$ , i = 1, ..., N
- Choose  $\omega_i \in \mathbb{R}, i = 1, ..., N$
- Quadrature formula

$$\int_{D} f(x) dx \doteq \sum_{i=1}^{N} \omega_{i} f(x^{i})$$

$$(7.5.3)$$

• A monomial formula is complete for degree  $\ell$  if

$$\sum_{i=1}^{N} \omega_i \, p(x^i) = \int_D p(x) \, dx \tag{7.5.3}$$

for all polynomials p(x) of total degree  $\ell$ ; recall that  $\mathcal{P}_{\ell}$  was defined in chapter 6 to be the set of such polynomials.

• For the case  $\ell = 2$ , this implies the equations

$$\sum_{i=1}^{N} \omega_{i} = \int_{D} 1 \cdot dx$$

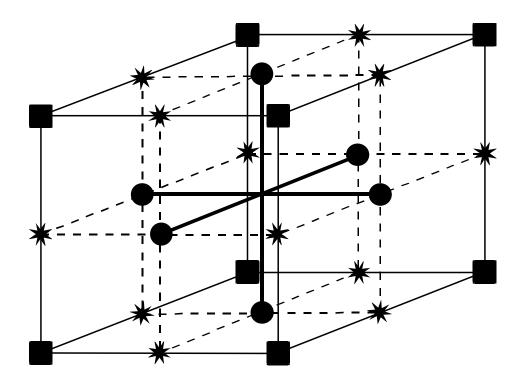
$$\sum_{i=1}^{N} \omega_{i} x_{j}^{i} = \int_{D} x_{j} dx, \ j = 1, \dots, d$$

$$\sum_{i=1}^{N} \omega_{i} x_{j}^{i} x_{k}^{i} = \int_{D} x_{j} x_{k} dx, \ j, k = 1, \dots, d$$
(7.5.4)

- $-1+d+\frac{1}{2}d(d+1)$  equations
- -N weights  $\omega_i$  and the N nodes  $x^i$  each with d components, yielding a total of (d+1)N unknowns.

- -

# Quadrature Node Sets



#### • Natural types of nodes:

- The center
- The circles: centers of faces
- The stars: centers of edges
- The squares: vertices

- Some monomial formulas will take some combinations of these sets
- Other types of collections are possible

- Simple examples
  - Let  $e^j \equiv (0, \dots, 1, \dots, 0)$  where the '1' appears in column j.
  - -2d points and exactly integrates all elements of  $\mathcal{P}_3$  over  $[-1,1]^d$

$$\int_{[-1,1]^d} f \doteq \omega \sum_{i=1}^d \left( f(ue^i) + f(-ue^i) \right)$$
$$u = \left( \frac{d}{3} \right)^{1/2}, \ \omega = \frac{2^{d-1}}{d}$$

– For  $\mathcal{P}_5$  the following scheme works:

$$\int_{[-1,1]^d} f \doteq \omega_1 f(0) + \omega_2 \sum_{i=1}^d \left( f(ue^i) + f(-ue^i) \right) \\
+ \omega_3 \sum_{\substack{1 \leq i < d, \\ i < j \leq d}} \left( f(u(e^i \pm e^j)) + f(-u(e^i \pm e^j)) \right)$$

where

$$\omega_1 = 2^d (25 \ d^2 - 115 \ d + 162), \quad \omega_2 = 2^d (70 - 25d)$$
  
 $\omega_3 = \frac{25}{324} \ 2^d, \quad u = (\frac{3}{5})^{1/2}.$ 

• Smolyak (a.k.a., sparse) grids (see pictures on next slide)

#### Existence Result for Monomial Formulas

**Theorem 4** (Mysovskikh) Let w(x) be a nonnegative weighting function on  $D \subset \mathbb{R}^d$  such that each moment

$$\int_D w(x)x_1^{i_1}\cdots x_d^{i_d}\ dx_1\cdots dx_d$$

exists for  $i_1, \dots, i_d \geq 0$ ,  $i_1 + \dots + i_d \leq m$ . Then, for some  $N \leq (m+d)!/(m!d!)$ , there exists N positive weights,  $\omega_i$ , and N nodes,  $x^i$ , such that for each multi-index  $|\alpha| \leq m$ ,

$$\int_D w(x)x^{\alpha} dx = \sum_{i=1}^N \omega_i(x^i)^{\alpha}.$$

- Purely existential
- Solving equations is difficult
- Formulas do not suffer from curse of dimensionality
- See Stroud and Secrest book for a large list of formulas.

~ .

#### Numerical Differentiation

• One-sided formula

$$f'(x) \doteq \frac{f(x+h) - f(x)}{h}$$
 (7.7.1)

- What should h be in light of computer errors?
- Error Analysis when  $\hat{f}$  is computer version of f
  - Suppose  $|f(x) \hat{f}(x)| \le \varepsilon$ ,
  - Actual machine approximation is

$$D(h) = \frac{\hat{f}(x+h) - \hat{f}(x)}{h}$$

- Error bound is

$$\left| D(h) - \frac{f(x+h) - f(x)}{h} \right| \le \frac{2\varepsilon}{h}$$

- Taylor's theorem: for some  $\xi \in [x, x+h]$ 

$$f'(x) = \frac{f(x+h) - f(x)}{h} - \frac{h}{2} f''(\xi)$$

- If  $M_2 > 0$  is an upper bound on |f''| near x, then error bound is

$$|f'(x) - D(h)| \le \frac{2\varepsilon}{h} + \frac{h}{2}M_2 \tag{7.7.2}$$

- Upper bound on error is minimized at

$$h^* = 2\sqrt{\frac{\varepsilon}{M_2}} \tag{7.7.3}$$

- The upper bound on error equals  $2\sqrt{\varepsilon M_2}$ .

#### • Two-Sided Difference Formula

- Two-sided formula

$$f'(x) \doteq \frac{f(x+h) - f(x-h)}{2h}$$
 (7.7.4)

- Error is  $\frac{h^2}{6} f'''(\xi)$  for some  $\xi \in [x h, x + h]$ .
- Round-off error of the approximation error is  $\varepsilon/h$
- Total error of

$$\frac{M_3h^2}{6} + \frac{\varepsilon}{h}$$

if  $M_3 > |f'''|$  near x.

- Optimal h is  $\frac{3\varepsilon}{M_3}^{1/3}$  with error upper bound of  $2\varepsilon^{2/3} M_3^{1/3} 9^{1/3}$ .
- Two-sided formula reduced error from order  $\varepsilon^{1/2}$  to order  $\varepsilon^{2/3}$ .
- On a twelve-digit machine: eight-digit accuracy versus six-digit accuracy.

#### • General Problem

- Find n-point difference approximation for  $f^{(k)}(x)$
- Optimal step size can be determined by Taylor-series expansions and linear equations.