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Use ElibotDriver to control the actual robot in RoboDK
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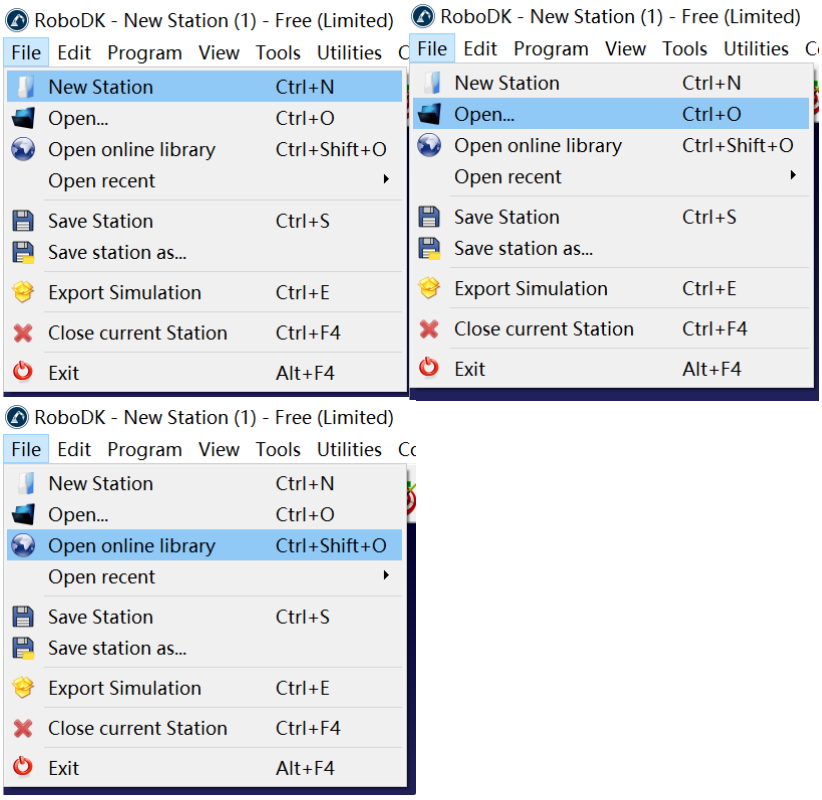
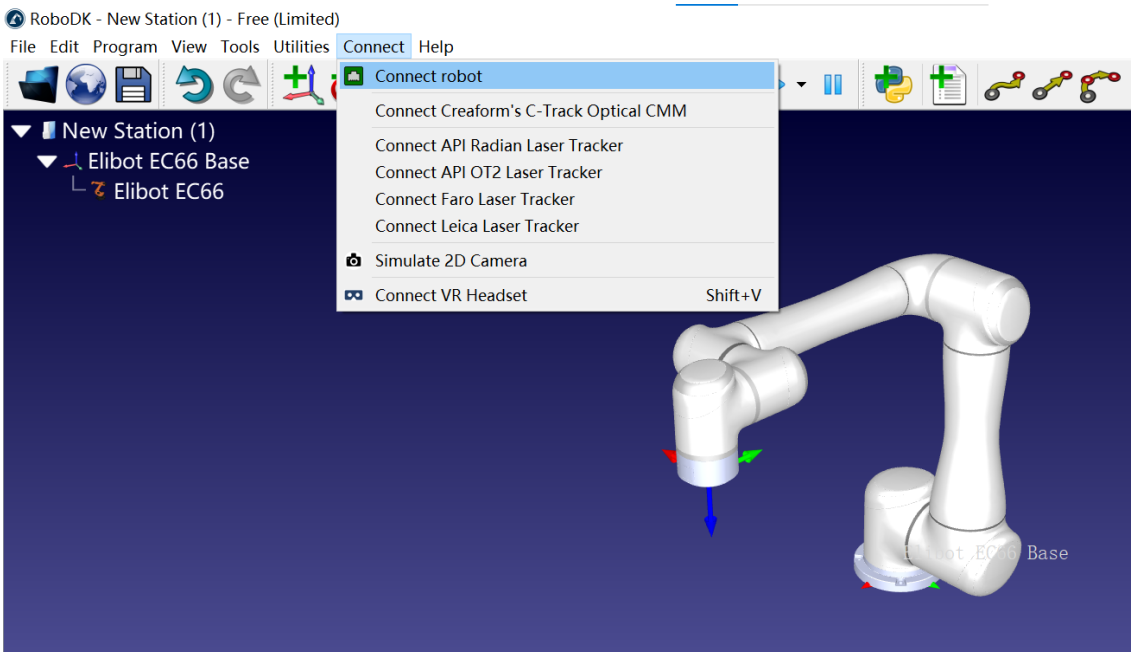
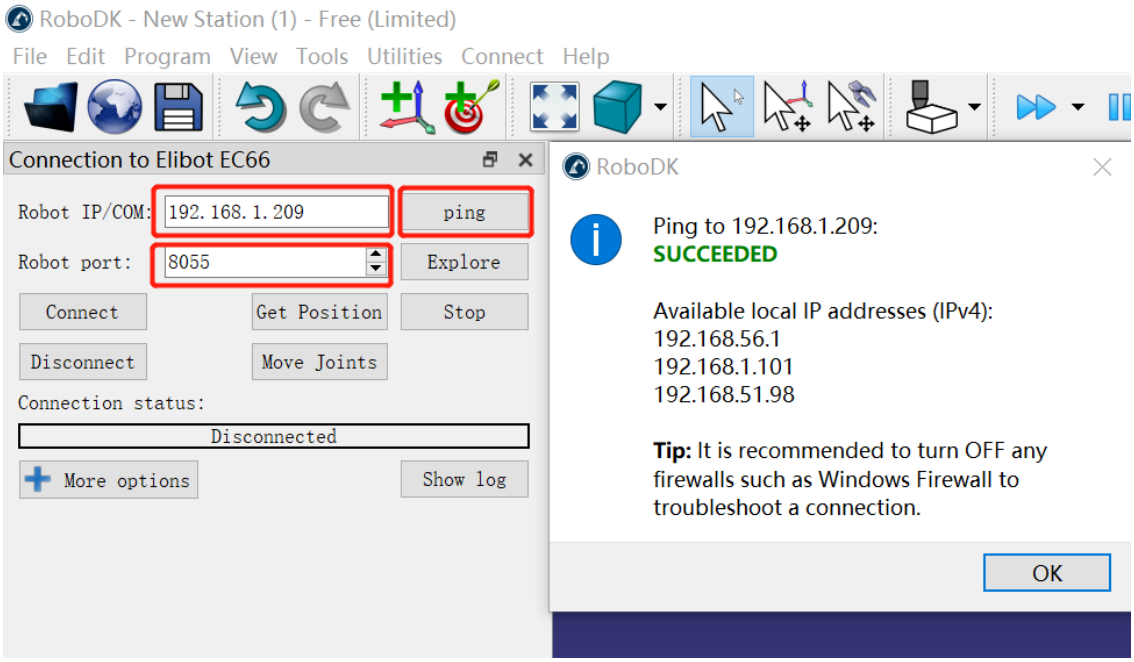
1. Please ensure the robot and the PC are in the same network.
2. Put ElibotDriver.py to the Installation path of robodk，default path：C:\RoboDK\api\Robot
3. Open RoboDK，create a new station and import the corresponding robot model(Elite robot model can be found and downloaded by clicking"Open online Library")

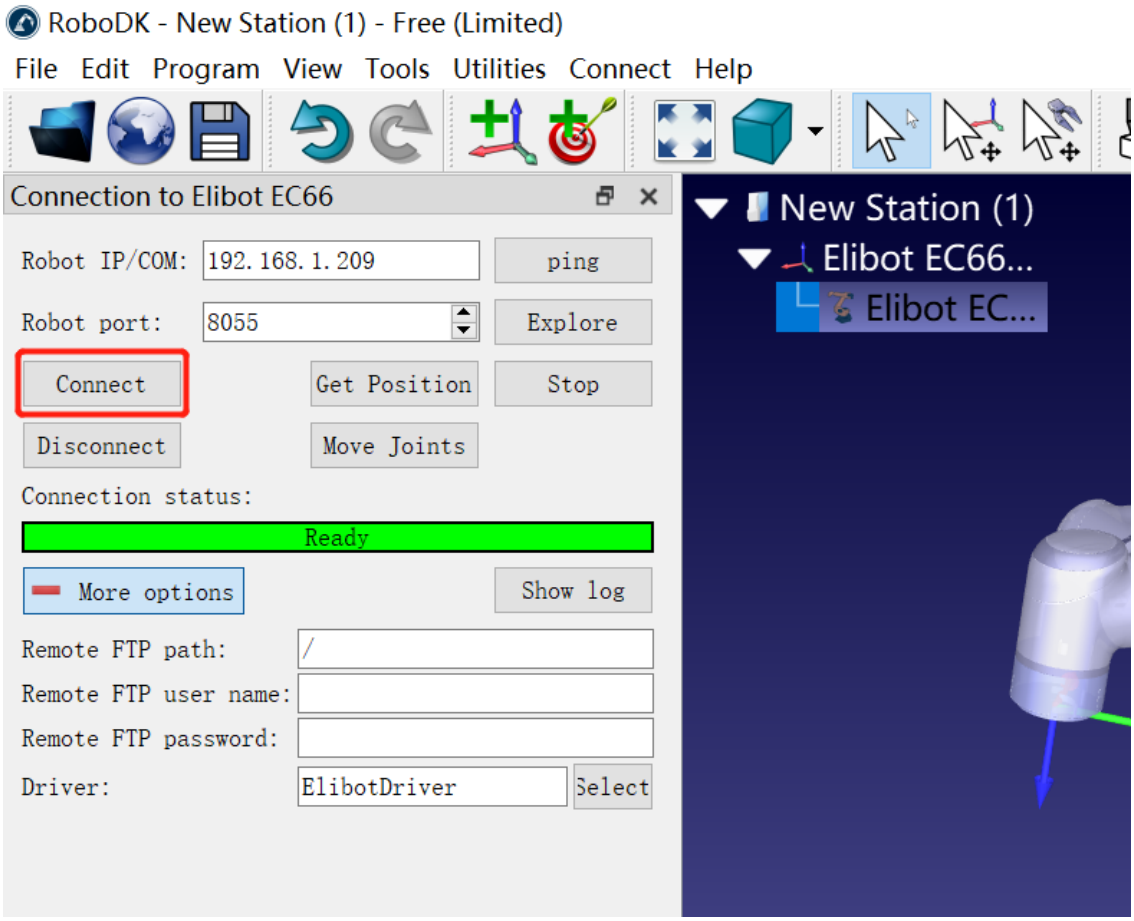


4. Click "Connect-Connect robot" in the menu bar，Enter the corresponding robot IP and port(8055)，as shown in the picture below. Click "ping" to check.

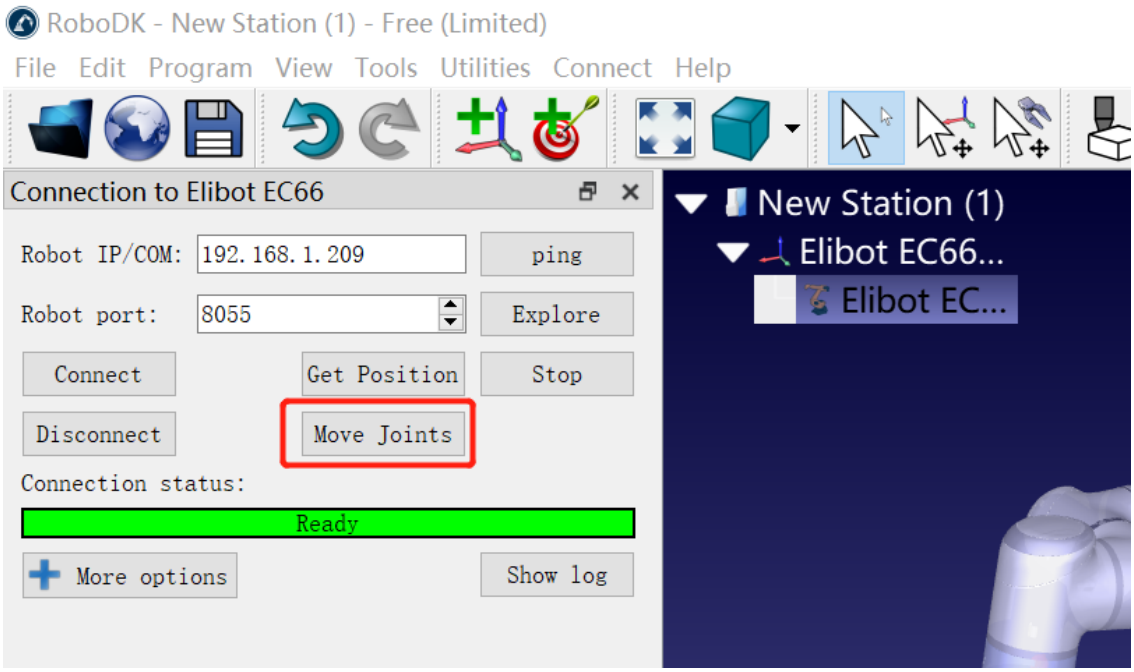




5. Then click "Connect". Once the connection is successful, the robot model will automatically synchronize the current pose of the actual robot



6. You can now drag the robot model in RoboDK and click on "Move Joints" or "Line Motion" (The robot needs to be in remote mode and servo on) The robot will automatically move to the corresponding location


RoboDK - New Station (1) - Free (Limited)
File Edit Program View Tools Utilities Connect Help
Connection to Elibot EC66
Robot IP/COM: 192.168.1.209
ping
Robot port: 8055
Explore
Connect
Get Position
Stop
Disconnect
Move Joints
Connection status:
Ready
More options
Show log
New Station (1)
Elibot EC66...
Elibot EC...