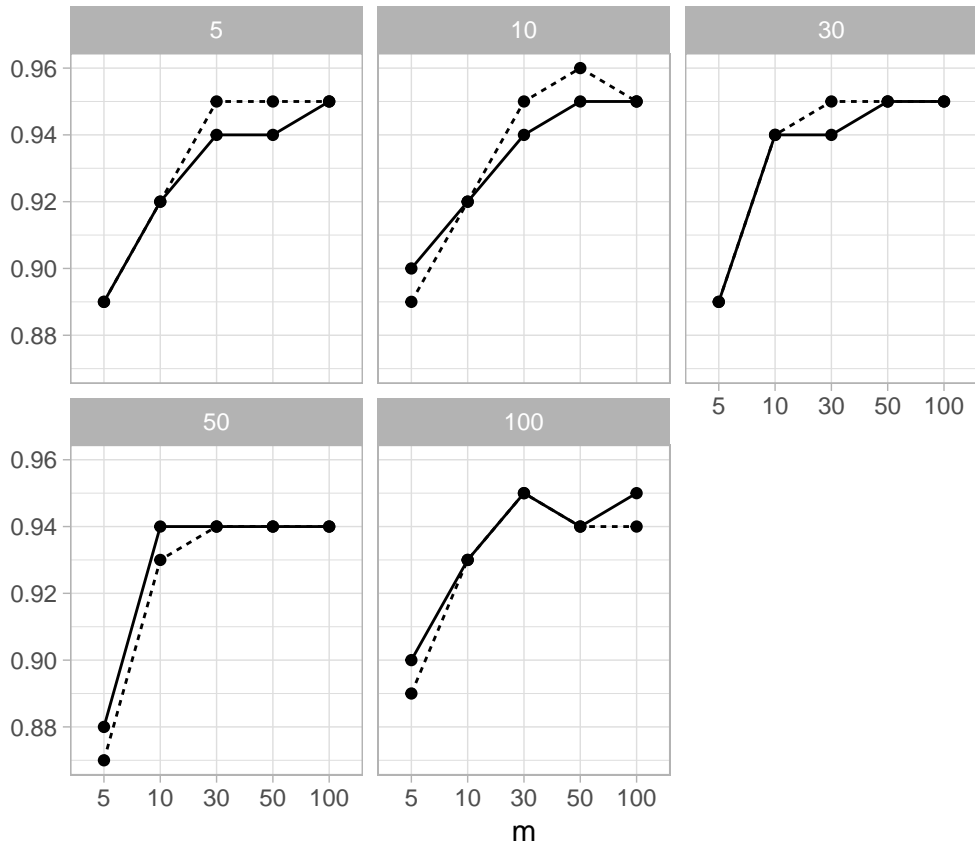


Estimated coverage probability



Method

— Inversion

- - - Wald