

Project ARI3129 - Object Detection & Localisation using Yolov5 (*Jupyter Notebook #3*)

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Automated Dataset Management with Roboflow and Folder Organization

This script automates the process of managing a dataset using Roboflow. It creates necessary directories, checks for installed dependencies, installs them if missing, and downloads the dataset. It also organizes the dataset into a structured folder hierarchy, ensuring everything is ready for further use.

```
import os
import subprocess
import shutil
import importlib

# Constants for colored output
COLORS = {
    "green": "\033[92m",  # Green text
    "red": "\033[91m",    # Red text
    "reset": "\033[0m"     # Reset to default color
}

# Define the path to the Versions folder and the target subfolder
versions_path = os.path.abspath(os.path.join("../", "Versions"))
target_subfolder = os.path.join(versions_path, "MDD-SDM-Yolov5")

# Check if the Versions folder exists, if not, create it
if not os.path.exists(versions_path):
    os.makedirs(versions_path)
    print(f"[{COLORS['green']}]✓[{COLORS['reset']}] Folder created at: {versions_path}")

# Check if the MDD-SDM-Yolov5 subfolder exists
if os.path.exists(target_subfolder):
    print(f"[{COLORS['green']}]✓[{COLORS['reset']}] The subfolder '{target_subfolder}' already exists. Skipping download!")
else:
    # Check if roboflow is installed
    if importlib.util.find_spec("roboflow") is not None:
        # type: ignore
        print(f"[{COLORS['green']}]✓[{COLORS['reset']}] Roboflow is
```

```

already installed!")
else:
    # Install roboflow using pip
    try:
        subprocess.check_call(["pip", "install", "roboflow"])
        print(f"[{COLORS['green']}]{COLORS['reset']}] Roboflow
successfully installed!")
    except subprocess.CalledProcessError as e:
        print(f"[{COLORS['red']}]{COLORS['reset']}] Failed to
install Roboflow. Please check your setup.")
        raise e

    # Import and use Roboflow
    from roboflow import Roboflow
# type: ignore

    # Prompt the user for their API key
    print("Please enter your Roboflow API key to download the
dataset...")
    api_key = input("Please enter your Roboflow API key: ")

    # Initialize Roboflow with the provided API key
    rf = Roboflow(api_key=api_key)

    # Retrieve project and version
    project = rf.workspace("advanced-cv").project("maltese-domestic-
dataset")
    version = project.version(1)

    # Download the dataset
    dataset = version.download("yolov5")

    current_folder = os.getcwd() # Get the current working directory
    original_folder = os.path.join(current_folder, "Maltese-Domestic-
Dataset--1")
    renamed_folder = os.path.join(current_folder, "MDD-SDM-Yolov5")
    target_folder = os.path.join(versions_path, "MDD-SDM-Yolov5")

    # Check if the original folder exists
    if os.path.exists(original_folder):
        # Rename the folder
        os.rename(original_folder, renamed_folder)

        # Move the renamed folder to ../Versions/
        shutil.move(renamed_folder, target_folder)
        print(f"[{COLORS['green']}]{COLORS['reset']}] Folder
downloaded to: {target_folder}")
    else:
        print(f"[{COLORS['red']}]{COLORS['reset']}] Folder
'{original_folder}' does not exist. No action taken.")

```

```
[✓] The subfolder 'e:\SEAN\Adv_CV\Versions\MDD-SDM-Yolov5' already exists. Skipping download!
```

Automated Library Installer in Python

This script automates checking and installing libraries from a JSON file. It verifies installations, installs missing libraries via pip, and provides clear, colored output for success or errors. With built-in error handling and preloaded common libraries, it simplifies dependency management in Python projects.

```
import json
import importlib.util

# Path to the JSON file
lib_file_path = os.path.join("../", "Libraries", "Task2_SDM_Lib.json")

# Read the libraries from the JSON file
try:
    with open(lib_file_path, 'r') as file:
        libraries = json.load(file)
except FileNotFoundError:
    print(f"[{COLORS['red']}Error: Library file not found at {lib_file_path}]{COLORS['reset']}")
    exit(1)
except json.JSONDecodeError:
    print(f"[{COLORS['red']}Error: Failed to decode JSON from the library file.{COLORS['reset']}]")
    exit(1)

# Function to check and install libraries
def check_and_install_libraries(libraries):
    for lib, import_name in libraries.items():
        # Check if the library is installed by checking its module spec
        if importlib.util.find_spec(import_name) is not None:
            print(f"[{COLORS['green']}]✓[{COLORS['reset']}] Library '{lib}' is already installed.")
        else:
            # If the library is not found, try to install it
            print(f"[{COLORS['red']}]✗[{COLORS['reset']}] Library '{lib}' is not installed. Installing...")
            try:
                subprocess.check_call(["pip", "install", lib])
                print(f"[{COLORS['green']}]✓[{COLORS['reset']}] Successfully installed '{lib}'.")
            except subprocess.CalledProcessError:
                print(f"[{COLORS['red']}]✗[{COLORS['reset']}] Failed to install '{lib}'. Please install it manually.")
```

```

# Execute the function to check and install libraries
check_and_install_libraries(libraries)

# Import necessary libraries
import cv2 # OpenCV for image processing
import time
import random
import matplotlib.pyplot as plt # For plotting and visualisation
import seaborn as sns # For advanced visualisation
import numpy as np # For numerical operations
import matplotlib.patches as patches # For drawing patches on plots
import concurrent.futures
from concurrent.futures import ThreadPoolExecutor, as_completed
from tqdm import tqdm # For progress bars
import torch # PyTorch for Yolov5
import pandas as pd # For handling tabular data
import yaml # For working with data.yaml files
import scipy # For advanced scientific calculations
from pathlib import Path # For handling file paths
from ultralytics import YOLO
from IPython.display import Image, display

[✓] Library 'opencv-python' is already installed.
[✓] Library 'matplotlib' is already installed.
[✓] Library 'tqdm' is already installed.
[✓] Library 'ultralytics' is already installed.
[✓] Library 'torch' is already installed.
[✓] Library 'pandas' is already installed.
[✓] Library 'seaborn' is already installed.
[✓] Library 'pyyaml' is already installed.
[✓] Library 'scipy' is already installed.
[✓] Library 'tensorboard' is already installed.

# Path to the yolov5n.yaml file
model_config_path =
os.path.join(os.path.abspath(os.path.join(os.getcwd(), os.pardir)),
"Versions", "yolov5", "models", "yolov5n.yaml")

# Load the YOLO model
model = YOLO(model_config_path)

print(f"[✓] YOL0v5 model initialized with configuration:
{model_config_path}")

[✓] YOL0v5 model initialized with configuration: e:\SEAN\Adv_CV\
Versions\yolov5\models\yolov5n.yaml

# Path to the data.yaml file
data_yaml_path =
os.path.join(os.path.abspath(os.path.join(os.getcwd(), os.pardir)),

```

```

"Versions", "MDD-SDM-Yolov5", "data.yaml")

# Train the YOLO model with results saved in runs/detect
results = model.train(
    data=data_yaml_path,          # Path to the dataset configuration
    epochs=100,                  # Number of epochs
    imgsz=640,                   # Image size
    batch=16,                     # Batch size
    workers=4,                    # Number of data loader workers
    device='cpu',                # Use CPU (or GPU with '0', '1', etc.)
    project='runs/detect',       # Save results in the detect directory
    name='MDD-SDM-Yolov5-v3',    # Subdirectory for this specific run
    (change run to v2, v3, etc)
    patience = 10,
    pretrained = False
)
# Experiment with patience, learning rate and epochs (epochs is very
# good at 65, so check) or else patience = 10, with epochs at 100
# Runs v1 & v4 epochs 50. v5 epochs 60. v2 epochs 65. v3 epochs 100
patience 10

print(f"[✓] Training completed! Results saved in: {results.save_dir}")

metrics = model.val()
print("Validation Metrics:", metrics)

New https://pypi.org/project/ultralytics/8.3.65 available Update with
'pip install -U ultralytics'
Ultralytics 8.3.64 Python-3.11.9 torch-2.5.1+cpu CPU (Intel Core(TM)
i5-8400 2.80GHz)
engine\trainer: task=detect, mode=train, model=e:\SEAN\Adv_CV\
Versions\yolov5\models\yolov5n.yaml, data=e:\SEAN\Adv_CV\Versions\MDD-
SDM-Yolov5\data.yaml, epochs=100, time=None, patience=10, batch=16,
imgsz=640, save=True, save_period=-1, cache=False, device=cpu,
workers=4, project=runs/detect, name=MDD-SDM-Yolov5-v3,
exist_ok=False, pretrained=False, optimizer=auto, verbose=True,
seed=0, deterministic=True, single_cls=False, rect=False,
cos_lr=False, close_mosaic=10, resume=False, amp=True, fraction=1.0,
profile=False, freeze=None, multi_scale=False, overlap_mask=True,
mask_ratio=4, dropout=0.0, val=True, split=val, save_json=False,
save_hybrid=False, conf=None, iou=0.7, max_det=300, half=False,
dnn=False, plots=True, source=None, vid_stride=1, stream_buffer=False,
visualize=False, augment=False, agnostic_nms=False, classes=None,
retina_masks=False, embed=None, show=False, save_frames=False,
save_txt=False, save_conf=False, save_crop=False, show_labels=True,
show_conf=True, show_boxes=True, line_width=None, format=torchscript,
keras=False, optimize=False, int8=False, dynamic=False, simplify=True,
opset=None, workspace=None, nms=False, lr0=0.01, lrf=0.01,
momentum=0.937, weight_decay=0.0005, warmup_epochs=3.0,

```

```

warmup_momentum=0.8, warmup_bias_lr=0.0, box=7.5, cls=0.5, dfl=1.5,
pose=12.0, kobj=1.0, nbs=64, hsv_h=0.015, hsv_s=0.7, hsv_v=0.4,
degrees=0.0, translate=0.1, scale=0.5, shear=0.0, perspective=0.0,
flipud=0.0, filplr=0.5, bgr=0.0, mosaic=1.0, mixup=0.0,
copy_paste=0.0, copy_paste_mode=flip, auto_augment=randaugment,
erasing=0.4, crop_fraction=1.0, cfg=None, tracker=botsort.yaml,
save_dir=runs\detect\MDD-SDM-Yolov5-v3

      from   n     params   module
arguments
  0           -1   1       1760 ultralytics.nn.modules.conv.Conv
[3, 16, 6, 2, 2]
  1           -1   1       4672 ultralytics.nn.modules.conv.Conv
[16, 32, 3, 2]
  2           -1   1       4800 ultralytics.nn.modules.block.C3
[32, 32, 1]
  3           -1   1      18560 ultralytics.nn.modules.conv.Conv
[32, 64, 3, 2]
  4           -1   2      29184 ultralytics.nn.modules.block.C3
[64, 64, 2]
  5           -1   1      73984 ultralytics.nn.modules.conv.Conv
[64, 128, 3, 2]
  6           -1   3     156928 ultralytics.nn.modules.block.C3
[128, 128, 3]
  7           -1   1     295424 ultralytics.nn.modules.conv.Conv
[128, 256, 3, 2]
  8           -1   1     296448 ultralytics.nn.modules.block.C3
[256, 256, 1]
  9           -1   1    164608
ultralytics.nn.modules.block.SPPF           [256, 256, 5]

  10          -1   1     33024 ultralytics.nn.modules.conv.Conv
[256, 128, 1, 1]
  11          -1   1         0
torch.nn.modules.upsampling.Upsample        [None, 2, 'nearest']

  12          [-1, 6] 1         0
ultralytics.nn.modules.conv.Concat           [1]

  13          -1   1     90880 ultralytics.nn.modules.block.C3
[256, 128, 1, False]
  14          -1   1     8320 ultralytics.nn.modules.conv.Conv
[128, 64, 1, 1]
  15          -1   1         0
torch.nn.modules.upsampling.Upsample        [None, 2, 'nearest']

  16          [-1, 4] 1         0
ultralytics.nn.modules.conv.Concat           [1]

  17          -1   1     22912 ultralytics.nn.modules.block.C3

```

```
[128, 64, 1, False]
18           -1 1    36992 ultralytics.nn.modules.conv.Conv
[64, 64, 3, 2]
19           [-1, 14] 1      0
ultralytics.nn.modules.conv.Concat      [1]

20           -1 1    74496 ultralytics.nn.modules.block.C3
[128, 128, 1, False]
21           -1 1    147712 ultralytics.nn.modules.conv.Conv
[128, 128, 3, 2]
22           [-1, 10] 1      0
ultralytics.nn.modules.conv.Concat      [1]

23           -1 1    296448 ultralytics.nn.modules.block.C3
[256, 256, 1, False]
24           [17, 20, 23] 1    752092
ultralytics.nn.modules.head.Detect      [4, [64, 128, 256]]
```

YOLOv5n summary: 262 layers, 2,509,244 parameters, 2,509,228 gradients, 7.2 GFLOPs

Transferred 427/427 items from pretrained weights

WARNING Comet installed but not initialized correctly, not logging this run. Comet.ml requires an API key. Please provide as the first argument to Experiment(api_key) or as an environment variable named COMET_API_KEY

TensorBoard: Start with 'tensorboard --logdir runs\detect\MDD-SDM-Yolov5-v3', view at <http://localhost:6006/>
Freezing layer 'model.24.dfl.conv.weight'

```
train: Scanning E:\SEAN\Adv_CV\Versions\MDD-SDM-Yolov5\Maltese-Domestic-Dataset--1\train\labels.cache... 748 images, 0 backgrounds, 0 corrupt: 100%|██████████| 748/748 [00:00<?, ?it/s]
val: Scanning E:\SEAN\Adv_CV\Versions\MDD-SDM-Yolov5\Maltese-Domestic-Dataset--1\valid\labels.cache... 70 images, 0 backgrounds, 0 corrupt: 100%|██████████| 70/70 [00:00<?, ?it/s]
```

Plotting labels to runs\detect\MDD-SDM-Yolov5-v3\labels.jpg...

```
optimizer: 'optimizer=auto' found, ignoring 'lr0=0.01' and 'momentum=0.937' and determining best 'optimizer', 'lr0' and 'momentum' automatically...
```

```
optimizer: AdamW(lr=0.00125, momentum=0.9) with parameter groups 69 weight(decay=0.0), 76 weight(decay=0.0005), 75 bias(decay=0.0)
```

TensorBoard: model graph visualization added

Image sizes 640 train, 640 val

Using 0 dataloader workers

Logging results to runs\detect\MDD-SDM-Yolov5-v3

Starting training for 100 epochs...

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	1/100	0G	1.619	1.773	1.821	65
640:	100%	[██████████ 47/47 [03:11<00:00, 4.08s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:07<00:00, 2.36s/it]			
		all	70	228	0.568	0.438
0.433	0.245					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	2/100	0G	1.643	1.865	1.836	93
640:	100%	[██████████ 47/47 [02:59<00:00, 3.81s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.19s/it]			
		all	70	228	0.548	0.392
0.439	0.25					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	3/100	0G	1.638	1.86	1.857	52
640:	100%	[██████████ 47/47 [02:58<00:00, 3.80s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.11s/it]			
		all	70	228	0.512	0.456
0.458	0.265					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	4/100	0G	1.659	1.857	1.847	94
640:	100%	[██████████ 47/47 [02:56<00:00, 3.75s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.12s/it]			
		all	70	228	0.462	0.384
0.383	0.209					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	5/100	0G	1.676	1.883	1.878	60
	100%	[██████████ 47/47 [02:56<00:00, 3.76s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.12s/it]			
			all	70	228	0.433
0.39		0.203				0.43

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	6/100	0G	1.648	1.874	1.855	57
	100%	[██████████ 47/47 [02:56<00:00, 3.76s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.05s/it]			
			all	70	228	0.562
0.433		0.233				0.394

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	7/100	0G	1.641	1.84	1.839	68
	100%	[██████████ 47/47 [02:58<00:00, 3.79s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.11s/it]			
			all	70	228	0.446
0.42		0.234				0.416

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	8/100	0G	1.655	1.786	1.838	62
	100%	[██████████ 47/47 [02:57<00:00, 3.78s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.06s/it]			

		all	70	228	0.497	0.428
0.434	0.24					
<hr/>						
Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	9/100	0G	1.641	1.807	1.827	67
	100% ██████████	47/47 [02:56<00:00, 3.76s/it]				
	Class	Images	Instances	Box(P	R	
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.10s/it]			
		all	70	228	0.534	0.39
0.415	0.231					
<hr/>						
Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	10/100	0G	1.637	1.795	1.825	120
	100% ██████████	47/47 [02:57<00:00, 3.77s/it]				
	Class	Images	Instances	Box(P	R	
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.09s/it]			
		all	70	228	0.524	0.347
0.331	0.162					
<hr/>						
Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	11/100	0G	1.668	1.785	1.843	73
	100% ██████████	47/47 [02:57<00:00, 3.77s/it]				
	Class	Images	Instances	Box(P	R	
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.17s/it]			
		all	70	228	0.518	0.387
0.422	0.235					
<hr/>						
Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	12/100	0G	1.615	1.794	1.833	45
	100% ██████████	47/47 [02:57<00:00, 3.77s/it]				

mAP50	mAP50-95):	Class 100%	Images [██████████ ██████████]	Instances 3/3	Box(P [00:06<00:00, 2.08s/it])	R
		all	70	228	0.446	0.457
0.468	0.275					

Size	Epoch 13/100	GPU_mem 0G	box_loss 1.622	cls_loss 1.726	dfl_loss 1.814	Instances 69
	640: 100%	[██████████ ██████████]	47/47 [02:57<00:00, 3.78s/it]			
mAP50	mAP50-95):	Class 100%	Images [██████████ ██████████]	Instances 3/3	Box(P [00:06<00:00, 2.10s/it])	R
0.468	0.272	all	70	228	0.512	0.438

Size	Epoch 14/100	GPU_mem 0G	box_loss 1.621	cls_loss 1.734	dfl_loss 1.816	Instances 91
	640: 100%	[██████████ ██████████]	47/47 [02:57<00:00, 3.77s/it]			
mAP50	mAP50-95):	Class 100%	Images [██████████ ██████████]	Instances 3/3	Box(P [00:06<00:00, 2.10s/it])	R
0.49	0.281	all	70	228	0.585	0.43

Size	Epoch 15/100	GPU_mem 0G	box_loss 1.619	cls_loss 1.699	dfl_loss 1.79	Instances 60
	640: 100%	[██████████ ██████████]	47/47 [02:57<00:00, 3.79s/it]			
mAP50	mAP50-95):	Class 100%	Images [██████████ ██████████]	Instances 3/3	Box(P [00:06<00:00, 2.25s/it])	R
0.457	0.25	all	70	228	0.579	0.423

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances

16/100	0G	1.604	1.694	1.784	81
640: 100% ██████████ 47/47 [02:58<00:00, 3.81s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.09s/it]					
0.475	all	70	228	0.615	0.422
0.27					

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
Size					
17/100	0G	1.585	1.684	1.791	72
640: 100% ██████████ 47/47 [02:57<00:00, 3.77s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.13s/it]					
0.5	all	70	228	0.608	0.461
0.275					

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
Size					
18/100	0G	1.6	1.628	1.784	65
640: 100% ██████████ 47/47 [02:57<00:00, 3.78s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.08s/it]					
0.487	all	70	228	0.575	0.477
0.274					

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
Size					
19/100	0G	1.577	1.657	1.766	78
640: 100% ██████████ 47/47 [02:57<00:00, 3.78s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.10s/it]					
0.488	all	70	228	0.546	0.442
0.284					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	20/100	0G	1.559	1.621	1.746	84
	100% ██████████	47/47 [02:56<00:00, 3.76s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.07s/it]			
		all	70	228	0.57	0.427
0.463	0.259					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	21/100	0G	1.54	1.626	1.737	40
	100% ██████████	47/47 [02:56<00:00, 3.76s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.07s/it]			
		all	70	228	0.394	0.481
0.419	0.248					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	22/100	0G	1.558	1.622	1.739	122
	100% ██████████	47/47 [02:58<00:00, 3.79s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.11s/it]			
		all	70	228	0.574	0.457
0.475	0.272					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	23/100	0G	1.536	1.636	1.743	62
	100% ██████████	47/47 [02:56<00:00, 3.76s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100% ██████████	3/3 [00:06<00:00, 2.13s/it]			
		all	70	228	0.67	0.44
0.522	0.287					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	24/100	0G	1.554	1.585	1.727	67
640:	100%	[██████████ 47/47 [02:57<00:00, 3.77s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.10s/it]			
			all	70	228	0.569
			0.517	0.283		0.497

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	25/100	0G	1.56	1.588	1.749	108
640:	100%	[██████████ 47/47 [02:56<00:00, 3.76s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.11s/it]			
			all	70	228	0.574
			0.513	0.298		0.444

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	26/100	0G	1.525	1.528	1.712	46
640:	100%	[██████████ 47/47 [02:57<00:00, 3.78s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.06s/it]			
			all	70	228	0.591
			0.526	0.314		0.488

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	27/100	0G	1.531	1.549	1.73	77
640:	100%	[██████████ 47/47 [02:59<00:00, 3.81s/it]				
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.09s/it]			

		all	70	228	0.622	0.42
0.482	0.284					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
------	-------	---------	----------	----------	----------	-----------

640:	28/100	0G	1.525	1.537	1.718	96
	100%	[██████████ 47/47 [02:58<00:00, 3.79s/it]				
		Class	Images	Instances	Box(P	R
mAP50 mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.12s/it]				

		all	70	228	0.541	0.458
0.486	0.289					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
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640:	29/100	0G	1.508	1.513	1.7	113
	100%	[██████████ 47/47 [02:59<00:00, 3.81s/it]				
		Class	Images	Instances	Box(P	R
mAP50 mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.07s/it]				

		all	70	228	0.531	0.511
0.48	0.268					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
------	-------	---------	----------	----------	----------	-----------

640:	30/100	0G	1.506	1.479	1.693	93
	100%	[██████████ 47/47 [02:58<00:00, 3.80s/it]				
		Class	Images	Instances	Box(P	R
mAP50 mAP50-95):	100%	[██████████ 3/3 [00:06<00:00, 2.10s/it]				

		all	70	228	0.655	0.501
0.52	0.285					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
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640:	31/100	0G	1.514	1.524	1.704	85
	100%	[██████████ 47/47 [03:01<00:00, 3.87s/it]				

mAP50	mAP50-95):	100% ██████████	Class	Images	Instances	Box(P	R
			all	70	228	0.619	0.423
0.487	0.287						

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	
640:	32/100	0G	1.528	1.521	1.728	84	
	100% ██████████	47/47 [02:58<00:00, 3.80s/it]					
mAP50	mAP50-95):	100% ██████████	Class	Images	Instances	Box(P	R
0.522	0.316		all	70	228	0.616	0.468

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	
640:	33/100	0G	1.515	1.522	1.701	61	
	100% ██████████	47/47 [02:57<00:00, 3.77s/it]					
mAP50	mAP50-95):	100% ██████████	Class	Images	Instances	Box(P	R
0.495	0.284		all	70	228	0.499	0.548

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	
640:	34/100	0G	1.491	1.472	1.676	69	
	100% ██████████	47/47 [03:00<00:00, 3.83s/it]					
mAP50	mAP50-95):	100% ██████████	Class	Images	Instances	Box(P	R
0.503	0.287		all	70	228	0.531	0.5

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
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35/100	0G	1.49	1.45	1.674	59
640: 100% ██████████ 47/47 [02:59<00:00, 3.83s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.12s/it]					
0.539	all	70	228	0.57	0.525
0.316					

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
Size					
36/100	0G	1.51	1.478	1.694	105
640: 100% ██████████ 47/47 [03:00<00:00, 3.83s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.13s/it]					
0.485	all	70	228	0.527	0.466
0.279					

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
Size					
37/100	0G	1.491	1.445	1.675	98
640: 100% ██████████ 47/47 [02:58<00:00, 3.80s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.09s/it]					
0.505	all	70	228	0.637	0.509
0.295					

Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
Size					
38/100	0G	1.472	1.436	1.665	46
640: 100% ██████████ 47/47 [02:58<00:00, 3.80s/it]	Class	Images	Instances	Box(P	R
mAP50 mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.16s/it]					
0.511	all	70	228	0.54	0.49
0.309					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	39/100	0G	1.458	1.417	1.663	49
640:	100% ██████████ 47/47 [02:57<00:00, 3.78s/it]	Class	Images	Instances	Box(P)	R
mAP50	mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.08s/it]					
		all	70	228	0.637	0.488
0.537	0.314					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	40/100	0G	1.447	1.447	1.645	39
640:	100% ██████████ 47/47 [02:56<00:00, 3.77s/it]	Class	Images	Instances	Box(P)	R
mAP50	mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.06s/it]					
		all	70	228	0.579	0.501
0.546	0.309					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	41/100	0G	1.479	1.444	1.668	94
640:	100% ██████████ 47/47 [02:59<00:00, 3.83s/it]	Class	Images	Instances	Box(P)	R
mAP50	mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.16s/it]					
		all	70	228	0.57	0.526
0.519	0.302					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
	42/100	0G	1.451	1.414	1.654	70
640:	100% ██████████ 47/47 [02:59<00:00, 3.83s/it]	Class	Images	Instances	Box(P)	R
mAP50	mAP50-95): 100% ██████████ 3/3 [00:06<00:00, 2.14s/it]					
		all	70	228	0.464	0.557
0.517	0.307					

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	43/100	0G	1.434	1.388	1.65	53
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████	47/47 [02:58<00:00, 3.80s/it]	3/3 [00:06<00:00, 2.10s/it]	
		all	70	228	0.527	0.527
	0.521	0.294				

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	44/100	0G	1.432	1.39	1.628	70
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████	47/47 [02:58<00:00, 3.81s/it]	3/3 [00:06<00:00, 2.07s/it]	
		all	70	228	0.554	0.484
	0.477	0.274				

Size	Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances
640:	45/100	0G	1.447	1.396	1.644	32
		Class	Images	Instances	Box(P	R
mAP50	mAP50-95):	100%	[██████████	47/47 [02:57<00:00, 3.78s/it]	3/3 [00:06<00:00, 2.09s/it]	
		all	70	228	0.525	0.512
	0.503	0.306				

EarlyStopping: Training stopped early as no improvement observed in last 10 epochs. Best results observed at epoch 35, best model saved as best.pt.
To update EarlyStopping(patience=10) pass a new patience value, i.e. `patience=300` or use `patience=0` to disable EarlyStopping.

45 epochs completed in 2.316 hours.
Optimizer stripped from runs\detect\MDD-SDM-Yolov5-v3\weights\last.pt,
5.3MB

```
Optimizer stripped from runs\detect\MDD-SDM-Yolov5-v3\weights\best.pt,  
5.3MB
```

```
Validating runs\detect\MDD-SDM-Yolov5-v3\weights\best.pt...  
Ultralytics 8.3.64 Python-3.11.9 torch-2.5.1+cpu CPU (Intel Core(TM)  
i5-8400 2.80GHz)  
YOLOv5n summary (fused): 193 layers, 2,503,724 parameters, 0  
gradients, 7.1 GFLOPs
```

mAP50	mAP50-95):	Class	Images	Instances	Box(P	R
	100% ██████████	3/3 [00:05<00:00, 1.72s/it]				
0.539	0.316	all	70	228	0.567	0.525
0.536	0.286	Mixed Waste	20	67	0.451	0.627
0.648	0.403	Organic Waste	26	53	0.667	0.528
0.202	0.116	Other Waste	23	56	0.484	0.214
0.769	0.462	Recyclable Material	25	52	0.668	0.731

```
Speed: 1.7ms preprocess, 62.7ms inference, 0.0ms loss, 0.6ms  
postprocess per image
```

```
Results saved to runs\detect\MDD-SDM-Yolov5-v3
```

```
[✓] Training completed! Results saved in: runs\detect\MDD-SDM-Yolov5-  
v3
```

```
Ultralytics 8.3.64 Python-3.11.9 torch-2.5.1+cpu CPU (Intel Core(TM)  
i5-8400 2.80GHz)
```

```
YOLOv5n summary (fused): 193 layers, 2,503,724 parameters, 0  
gradients, 7.1 GFLOPs
```

```
val: Scanning E:\SEAN\Adv_CV\Versions\MDD-SDM-Yolov5\Maltese-Domestic-  
Dataset--1\valid\labels.cache... 70 images, 0 backgrounds, 0 corrupt:  
100%|██████████| 70/70 [00:00<?, ?it/s]
```

mAP50	mAP50-95):	Class	Images	Instances	Box(P	R
	100% ██████████	5/5 [00:05<00:00, 1.05s/it]				
0.539	0.316	all	70	228	0.567	0.525
0.536	0.286	Mixed Waste	20	67	0.451	0.627
0.648	0.403	Organic Waste	26	53	0.667	0.528
0.202	0.116	Other Waste	23	56	0.484	0.214
0.769	0.462	Recyclable Material	25	52	0.668	0.731

```
Speed: 2.3ms preprocess, 58.8ms inference, 0.0ms loss, 0.6ms  
postprocess per image
```

```
Results saved to runs\detect\MDD-SDM-Yolov5-v32
Validation Metrics: ultralytics.utils.metrics.DetMetrics object with
attributes:
```

```
ap_class_index: array([0, 1, 2, 3])
box: ultralytics.utils.metrics.Metric object
confusion_matrix: <ultralytics.utils.metrics.ConfusionMatrix object at
0x00000198D0A001D0>
curves: ['Precision-Recall(B)', 'F1-Confidence(B)', 'Precision-
Confidence(B)', 'Recall-Confidence(B)']
curves_results: [[array([
    0,      0.001001,      0.002002,
0.003003,      0.004004,      0.005005,      0.006006,      0.007007,
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0.013013,      0.014014,      0.015015,      0.016016,      0.017017,
0.018018,      0.019019,      0.02002,      0.021021,      0.022022,
0.023023,
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0.052052,      0.053053,      0.054054,      0.055055,      0.056056,
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0.062062,      0.063063,      0.064064,      0.065065,      0.066066,
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0.086086,      0.087087,      0.088088,      0.089089,      0.09009,
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0.17718,      0.17818,      0.17918,      0.18018,      0.18118,
```

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fitness: 0.3387068026201715
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maps: array([ 0.2856,     0.40264,     0.11617,     0.46152])
names: {0: 'Mixed Waste', 1: 'Organic Waste', 2: 'Other Waste', 3:
'Recyclable Material'}
plot: True
results_dict: {'metrics/precision(B)': 0.5673223477717204,

```

```
'metrics/recall(B)': 0.5251049347619785, 'metrics/mAP50(B)': 0.538732151243344, 'metrics/mAP50-95(B)': 0.3164817638842634, 'fitness': 0.3387068026201715}
save_dir: WindowsPath('runs/detect/MDD-SDM-Yolov5-v32')
speed: {'preprocess': 2.29386602129255, 'inference': 58.842590876988005, 'loss': 0.0, 'postprocess': 0.5840744291033063}
task: 'detect'
```

This cell processes YOLOv5 output in the runs/detect directory by identifying folders with specific naming patterns, allowing user selection, and displaying relevant evaluation images and plots. It filters folders ending with "R" and containing "SDM" (my initials, so only sorting folders generated by YOLOv5 since that is my section), sorts them, and prompts the user to choose one. The cell retrieves evaluation images from the selected folder, excluding files named with "val_batch", and displays them alongside visualisations such as confusion matrices, F1-confidence curves, precision-recall curves, and other performance metrics. Additionally, it locates and displays a consolidated results.png file from the non-"R" version of the folder, providing comprehensive insights into the model's performance.

```
# Path to the "runs/detect" folder
detect_folder_path = os.path.join(os.getcwd(), "runs", "detect")

# Get all folders ending with "R" and containing "SDM", and sort them in ascending order
folders_ending_with_R = sorted([
    folder for folder in os.listdir(detect_folder_path)
    if folder.endswith("R") and "SDM" in folder and
    os.path.isdir(os.path.join(detect_folder_path, folder))
])

# Check if there are any folders to choose from
if not folders_ending_with_R:
    print("No Results folders containing 'SDM' found!")
else:
    # Display available folders for user selection
    print("Available folders:")
    for i, folder in enumerate(folders_ending_with_R, start=1):
        print(f"{i}. {folder}")

    # Prompt the user to select a folder
    try:
        choice = int(input("Enter the number corresponding to the folder you want to use: "))
        selected_folder = folders_ending_with_R[choice - 1]
    except (ValueError, IndexError):
        print("Invalid selection. Please restart and try again.")
        raise

    print(f"\nSelected folder: {selected_folder}")
    # Path to the selected folder
```

```

    eval_folder_path = os.path.join(detect_folder_path,
selected_folder)

    # List of evaluation images excluding "val_batch" files
    evaluation_images = [
        img for img in os.listdir(eval_folder_path)
        if img.lower().endswith('.png', '.jpg')) and "val_batch" not
in img
    ]

    # Display images
    if not evaluation_images:
        print("No evaluation images found in the selected folder.")
    else:
        for img_file in evaluation_images:
            img_path = os.path.join(eval_folder_path, img_file)
            display(Image(filename=img_path))

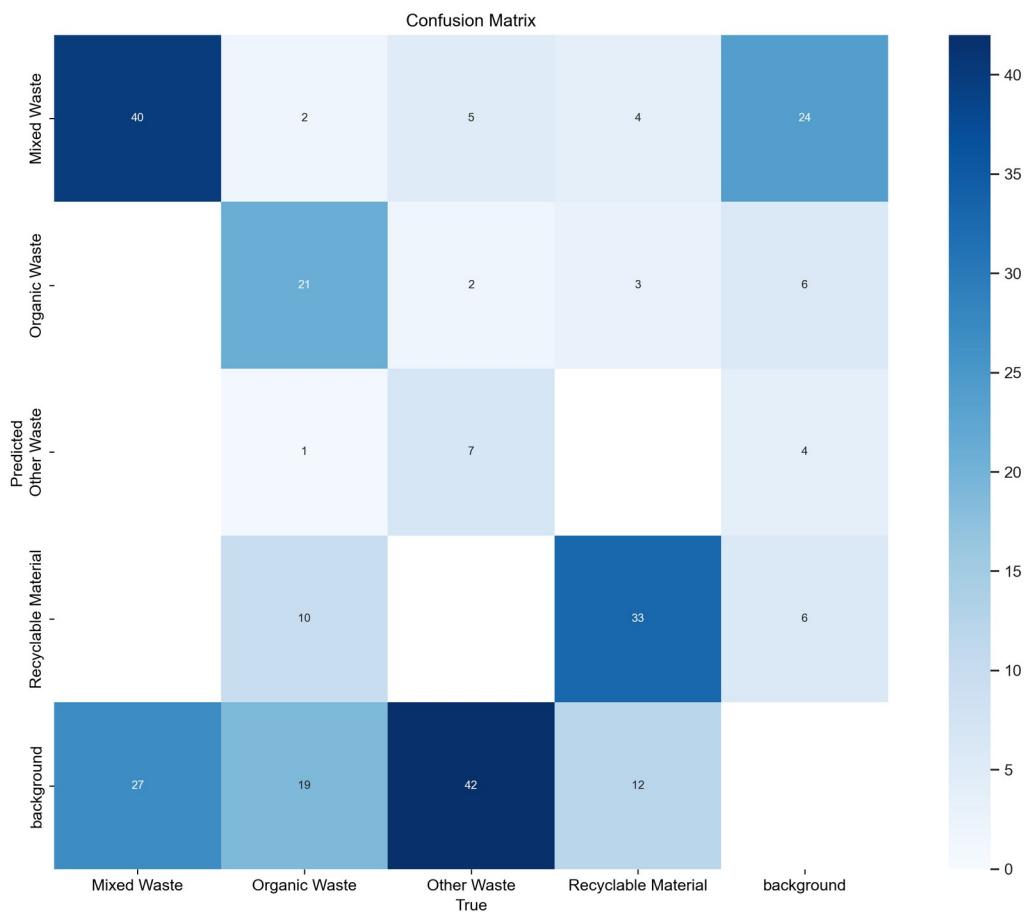
    # Path to the non-R version of the selected folder
    non_r_folder = selected_folder.rstrip("R")
    non_r_folder_path = os.path.join(detect_folder_path, non_r_folder)

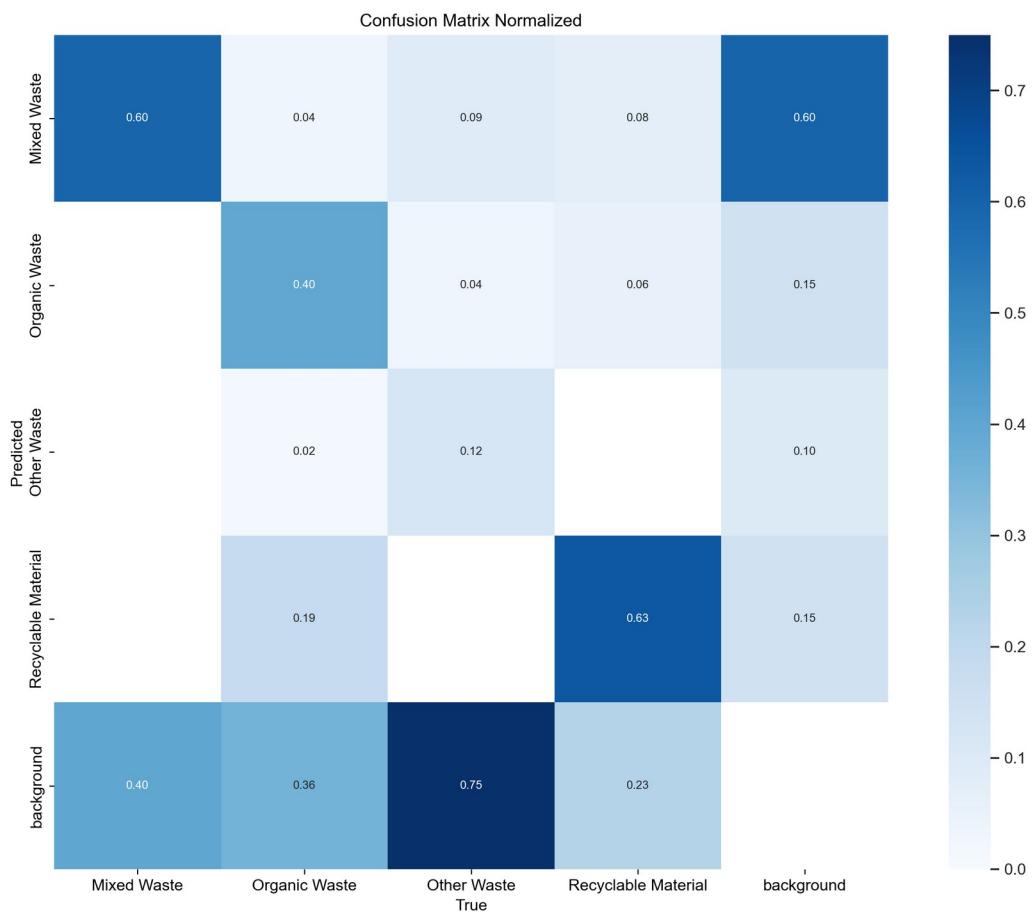
    # Check and display "results.png" if it exists
    results_png_path = os.path.join(non_r_folder_path, "results.png")
    if os.path.exists(results_png_path):
        display(Image(filename=results_png_path))
    else:
        print("No results.png found in the non-R version of the
selected folder.")

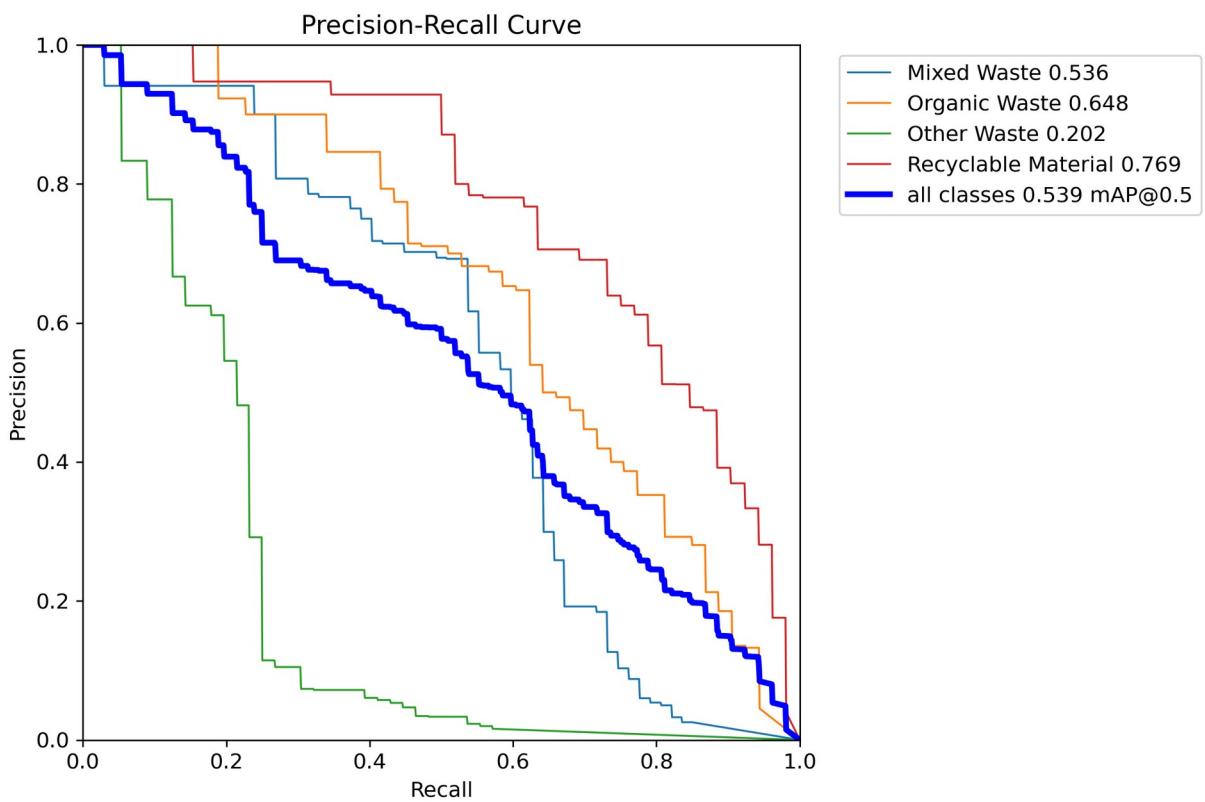
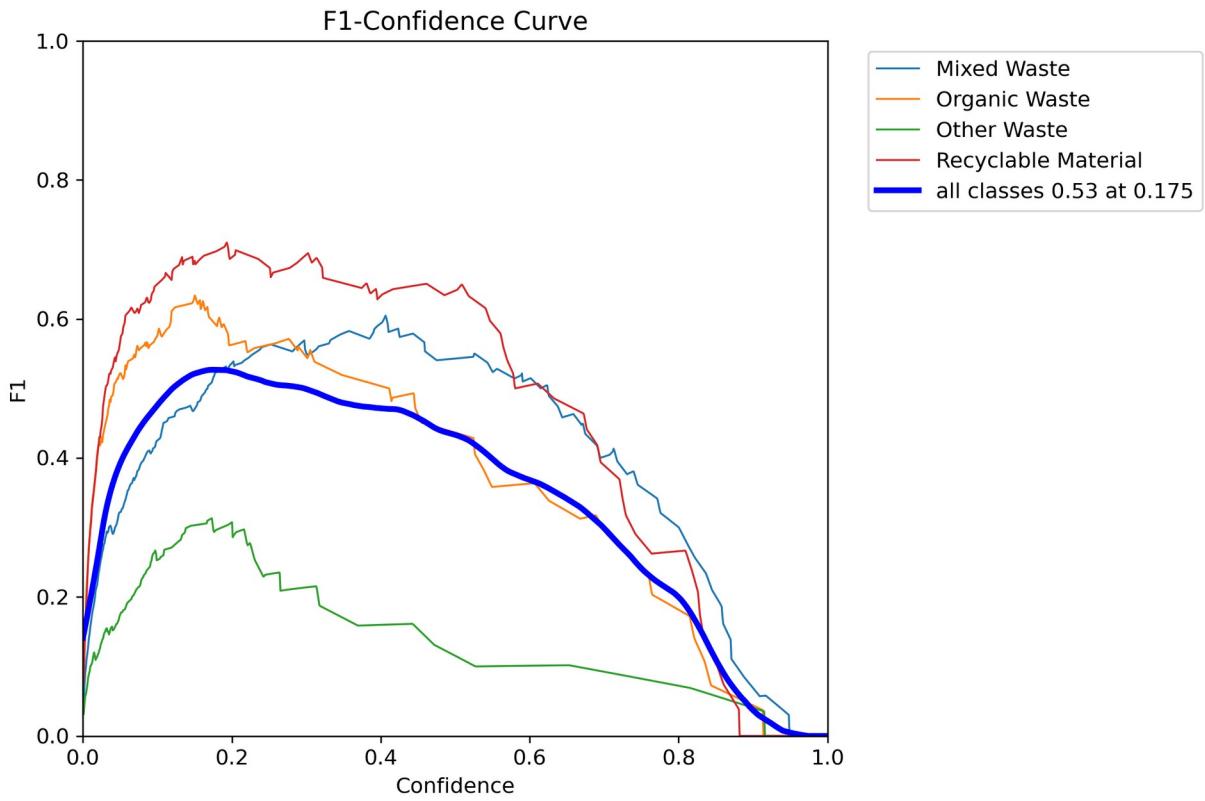
Available folders:
1. MDD-SDM-Yolov5-v2R
2. MDD-SDM-Yolov5-v3R
3. MDD-SDM-Yolov5-v4R
4. MDD-SDM-Yolov5-v5R
5. MDD-SDM-Yolov5_v1R

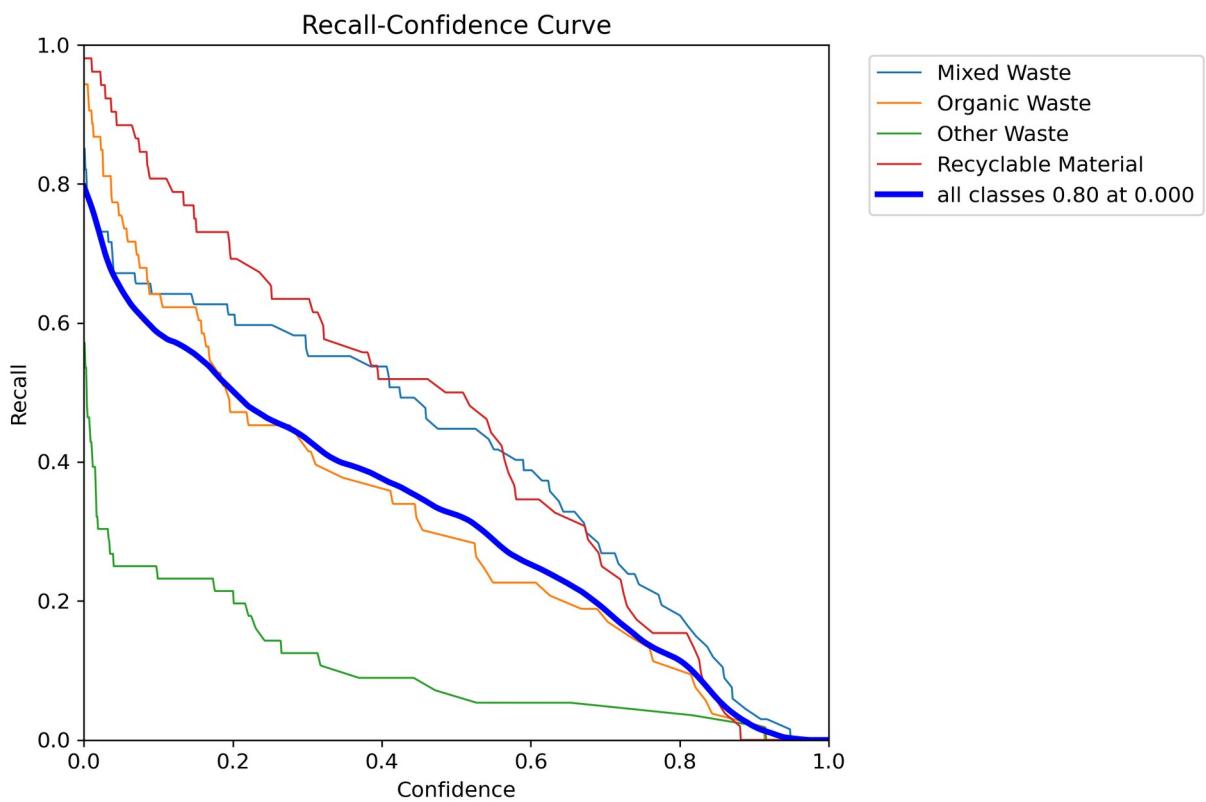
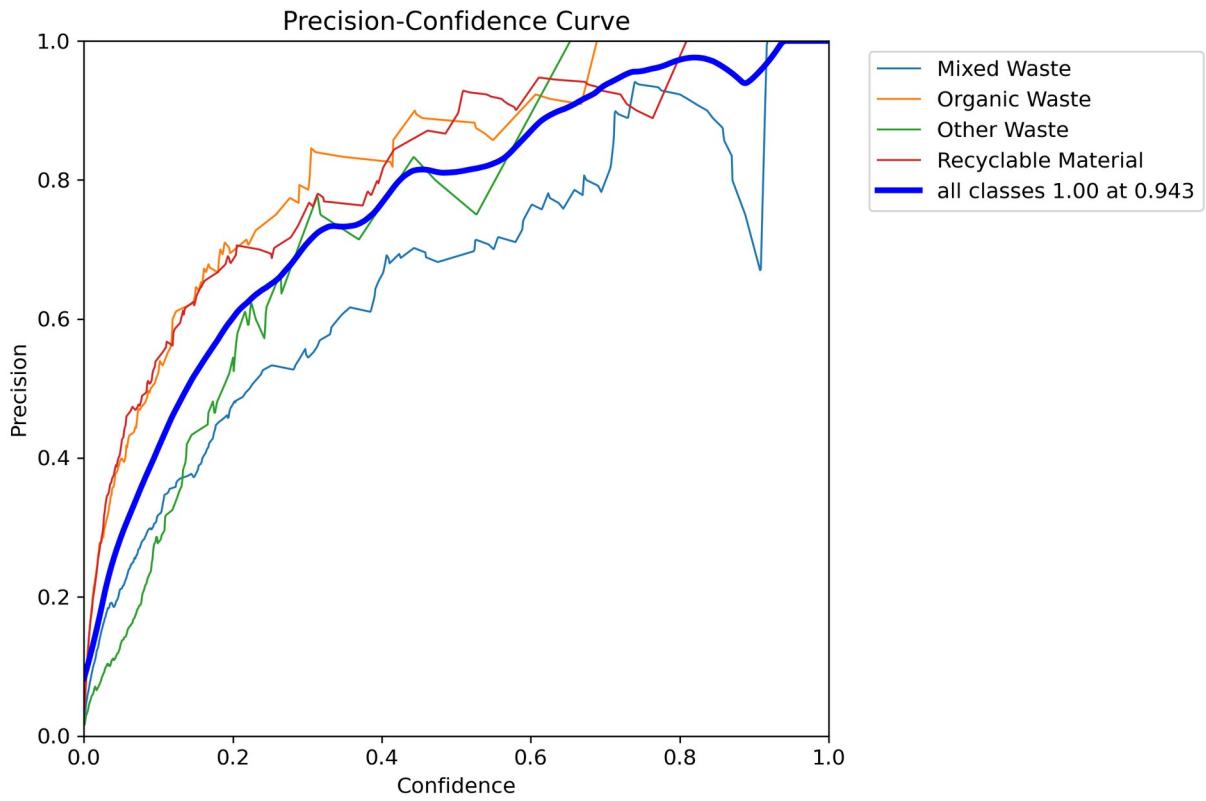
Selected folder: MDD-SDM-Yolov5-v3R

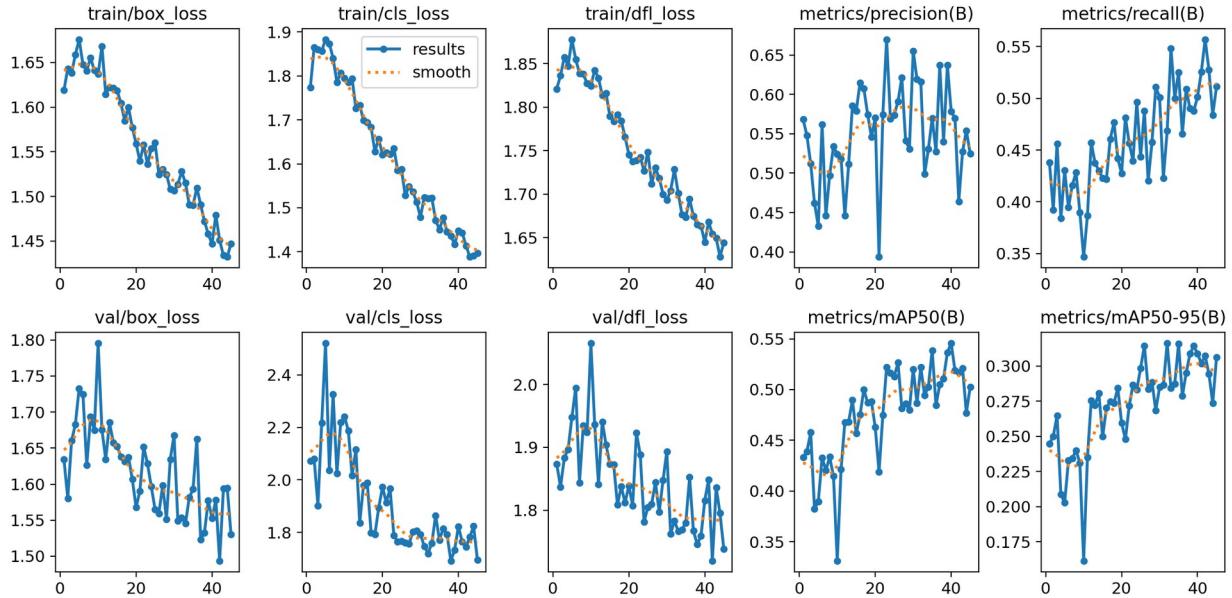
```











This cell serves as the codebase for evaluating YOLOv5 training and validation results. It identifies and selects a version folder within the runs/detect directory based on specific criteria, loads the corresponding results.csv file, and computes both final and average metrics for precision, recall, mAP@50, mAP@50-95, and various losses. The codebase further generates visualisations of key metrics over epochs, including trends in precision, recall, mAP, training and validation losses, learning rate schedules, and loss breakdowns. Additionally, it provides a precision vs recall scatter plot, offering a comprehensive evaluation framework for assessing YOLOv5 model performance.

```
# Path to the "runs/detect" folder
detect_path = os.path.join(os.getcwd(), "runs", "detect")

# Get all available versions containing "SDM" in the "runs/detect" directory & sort in ascending order
available_versions = sorted([
    folder for folder in os.listdir(detect_path)
    if os.path.isdir(os.path.join(detect_path, folder)) and not
    folder.endswith("R") and "SDM" in folder
])

# Check if there are any valid versions to choose from
if not available_versions:
    raise FileNotFoundError("No valid versions containing 'SDM' found in 'runs/detect'.") 

# Display options and prompt user for input
print("Available versions:")
for i, version in enumerate(available_versions, start=1):
    print(f"{i}. {version}")

try:
```

```

    selected_index = int(input("Enter the number of the version you
want to test: ")) - 1
    if selected_index < 0 or selected_index >=
len(available_versions):
        raise ValueError("Invalid selection.")
except ValueError:
    print("Invalid input. Please enter a valid number.")
    raise

# Set the selected version
selected_version = available_versions[selected_index]
weights_path = os.path.join(detect_path, selected_version, "weights",
"best.pt")

# Path to the selected version's folder
selected_version_path = os.path.join(detect_path, selected_version)

# Path to results CSV file
results_csv_path = os.path.join(selected_version_path, "results.csv")

# Ensure the file exists
if not os.path.exists(results_csv_path):
    raise FileNotFoundError(f"'results.csv' not found in the selected
version: {selected_version_path}")

# Load the CSV file
results_df = pd.read_csv(results_csv_path)

# Compute averages for all metrics and losses
average_metrics = {
    "Metric": [
        "Precision", "Recall", "mAP@50", "mAP@50-95",
        "Train Box Loss", "Train Classification Loss",
        "Validation Box Loss", "Validation Classification Loss"
    ],
    "Final Value": [
        results_df['metrics/precision(B)'].iloc[-1],
        results_df['metrics/recall(B)'].iloc[-1],
        results_df['metrics/mAP50(B)'].iloc[-1],
        results_df['metrics/mAP50-95(B)'].iloc[-1],
        results_df['train/box_loss'].iloc[-1],
        results_df['train/cls_loss'].iloc[-1],
        results_df['val/box_loss'].iloc[-1],
        results_df['val/cls_loss'].iloc[-1]
    ],
    "Average Value": [
        results_df['metrics/precision(B)'].mean(),
        results_df['metrics/recall(B)'].mean(),
        results_df['metrics/mAP50(B)'].mean(),
        results_df['metrics/mAP50-95(B)'].mean(),
    ]
}

```

```

        results_df['train/box_loss'].mean(),
        results_df['train/cls_loss'].mean(),
        results_df['val/box_loss'].mean(),
        results_df['val/cls_loss'].mean()
    ]
}

# Convert metrics dictionary to DataFrame
metrics_df = pd.DataFrame(average_metrics)

# Display the title and the table
print(f"YOLO Model Training & Validation Metrics for Version: {selected_version}")
display(metrics_df)

# Plot Precision, Recall, mAP@50, and mAP@50-95 over epochs
plt.figure(figsize=(10, 6))
plt.plot(results_df.index, results_df['metrics/precision(B)'],
label='Precision', marker='o')
plt.plot(results_df.index, results_df['metrics/recall(B)'],
label='Recall', marker='o')
plt.plot(results_df.index, results_df['metrics/mAP50(B)'],
label='mAP@50', marker='o')
plt.plot(results_df.index, results_df['metrics/mAP50-95(B)'],
label='mAP@50-95', marker='o')
plt.title(f"Metrics Over Epochs for Version: {selected_version}")
plt.xlabel("Epoch")
plt.ylabel("Value")
plt.legend()
plt.grid(True)
plt.show()

# Plot Training and Validation Losses over epochs
plt.figure(figsize=(10, 6))
plt.plot(results_df.index, results_df['train/box_loss'], label='Train Box Loss', marker='o')
plt.plot(results_df.index, results_df['train/cls_loss'], label='Train Classification Loss', marker='o')
plt.plot(results_df.index, results_df['val/box_loss'], label='Validation Box Loss', marker='o')
plt.plot(results_df.index, results_df['val/cls_loss'], label='Validation Classification Loss', marker='o')
plt.title(f"Training and Validation Losses Over Epochs for Version: {selected_version}")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.legend()
plt.grid(True)
plt.show()

```

```

# Plot Learning Rate Schedule
plt.figure(figsize=(10, 6))
plt.plot(results_df.index, results_df['lr/pg0'], label='Learning Rate (pg0)', marker='o')
plt.plot(results_df.index, results_df['lr/pg1'], label='Learning Rate (pg1)', marker='o')
plt.plot(results_df.index, results_df['lr/pg2'], label='Learning Rate (pg2)', marker='o')
plt.title(f"Learning Rate Schedule for Version: {selected_version}")
plt.xlabel("Epoch")
plt.ylabel("Learning Rate")
plt.legend()
plt.grid(True)
plt.show()

# Plot Loss Breakdown
plt.figure(figsize=(10, 6))
plt.plot(results_df.index, results_df['train/box_loss'], label='Train Box Loss', marker='o')
plt.plot(results_df.index, results_df['train/cls_loss'], label='Train Classification Loss', marker='o')
plt.plot(results_df.index, results_df['train/dfl_loss'], label='Train DFL Loss', marker='o')
plt.title(f"Training Loss Breakdown for Version: {selected_version}")
plt.xlabel("Epoch")
plt.ylabel("Loss Value")
plt.legend()
plt.grid(True)
plt.show()

# Plot Precision vs. Recall
plt.figure(figsize=(10, 6))
plt.scatter(results_df['metrics/recall(B)'],
            results_df['metrics/precision(B)'], c=results_df.index,
            cmap='viridis', s=100, edgecolor='k')
plt.colorbar(label="Epoch")
plt.title(f"Precision vs Recall Across Epochs for Version: {selected_version}")
plt.xlabel("Recall")
plt.ylabel("Precision")
plt.grid(True)
plt.show()

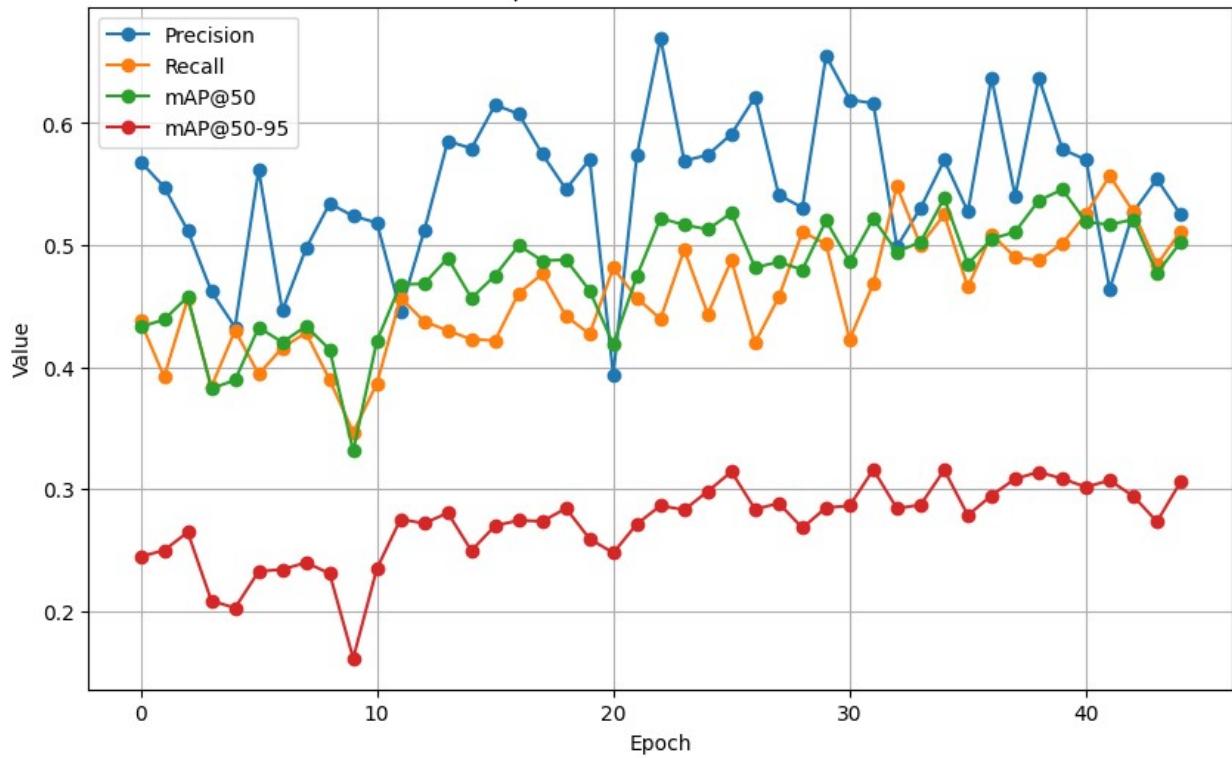
Available versions:
1. MDD-SDM-Yolov5-v2
2. MDD-SDM-Yolov5-v3
3. MDD-SDM-Yolov5-v4
4. MDD-SDM-Yolov5-v5
5. MDD-SDM-Yolov5_v1

```

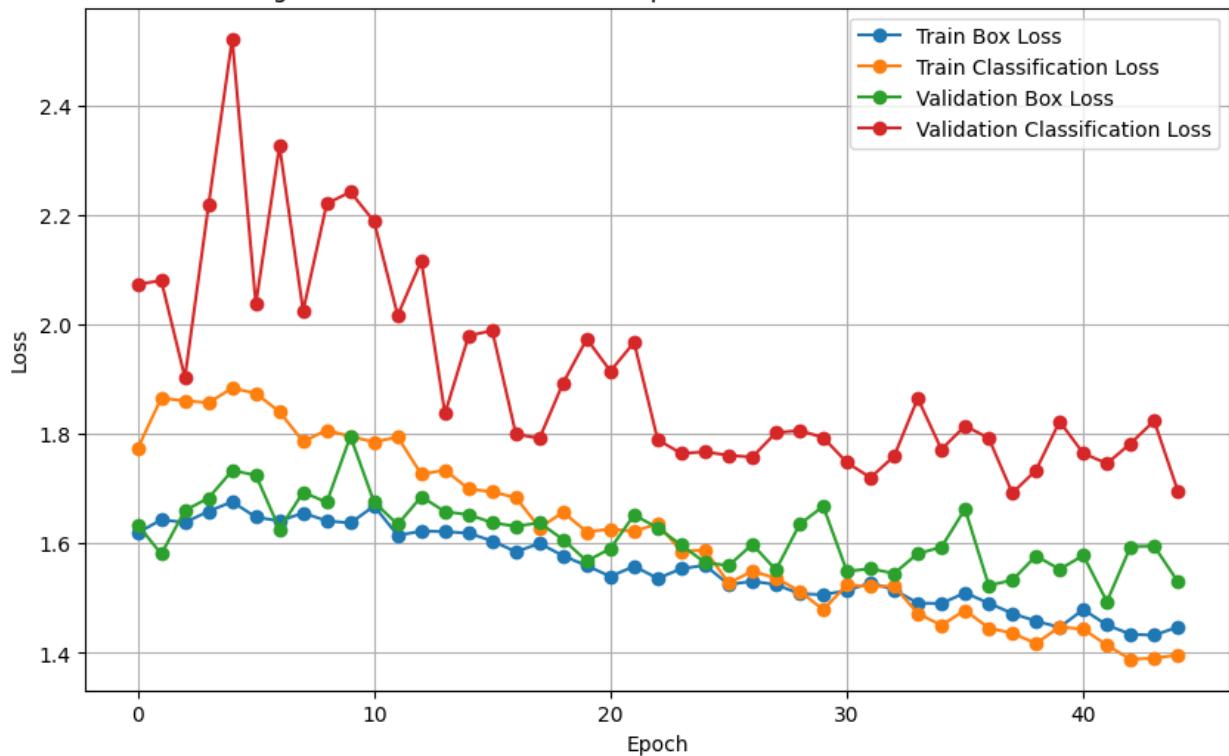
YOLO Model Training & Validation Metrics for Version: MDD-SDM-Yolov5-v3

	Metric	Final Value	Average Value
0	Precision	0.52503	0.550170
1	Recall	0.51151	0.459054
2	mAP@50	0.50250	0.476797
3	mAP@50-95	0.30611	0.272287
4	Train Box Loss	1.44725	1.556195
5	Train Classification Loss	1.39642	1.617128
6	Validation Box Loss	1.53016	1.615458
7	Validation Classification Loss	1.69570	1.908239

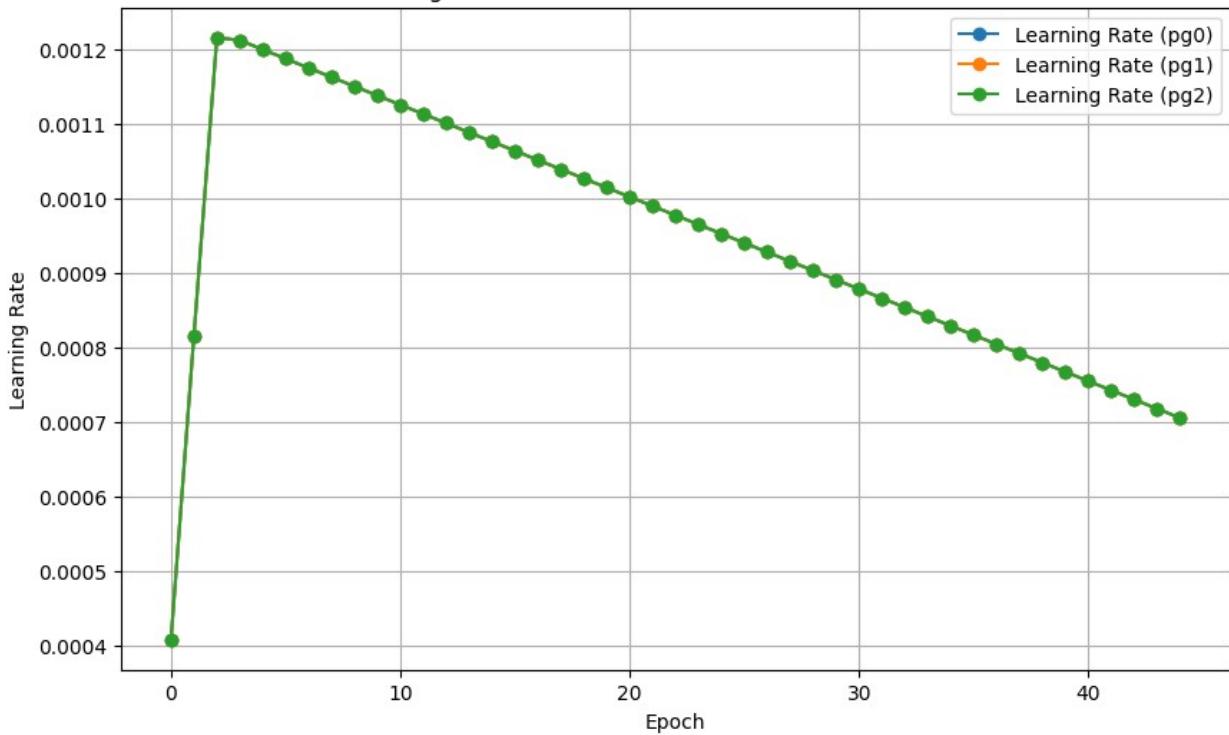
Metrics Over Epochs for Version: MDD-SDM-Yolov5-v3

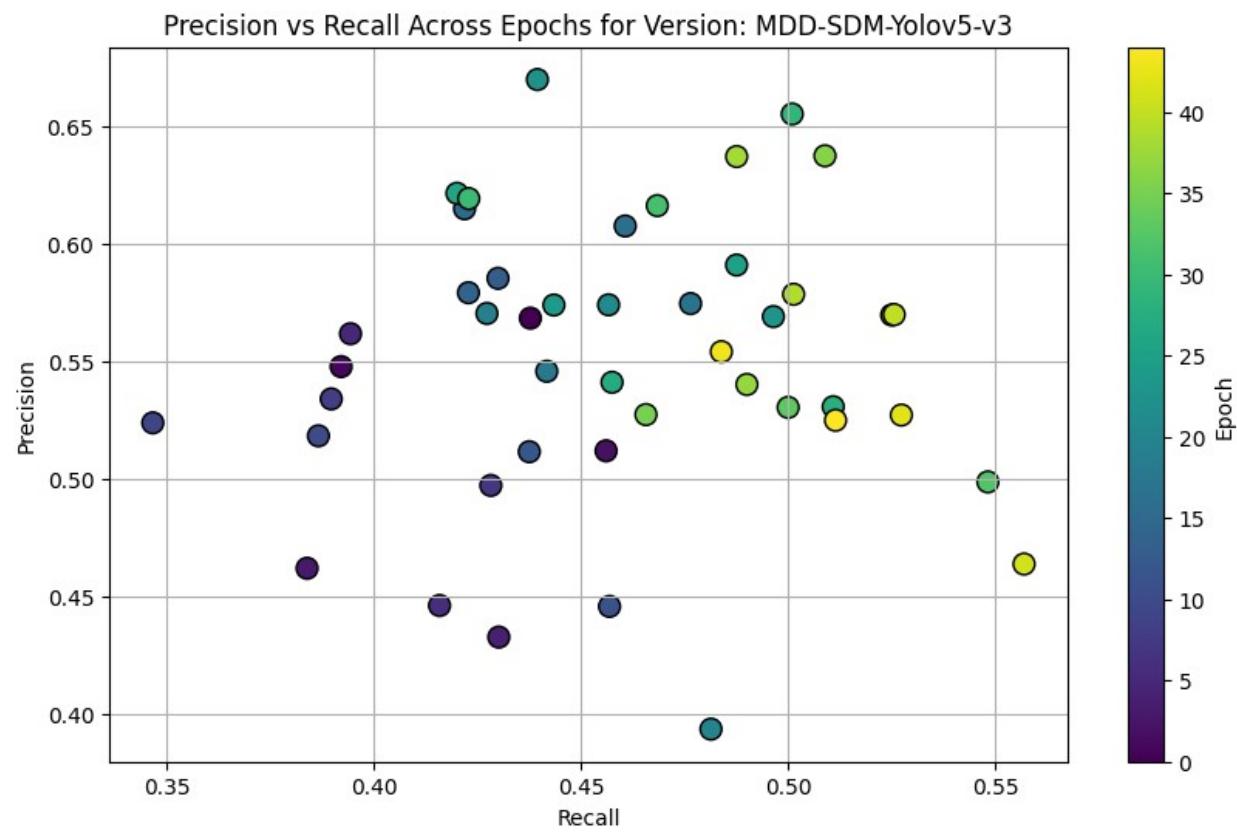
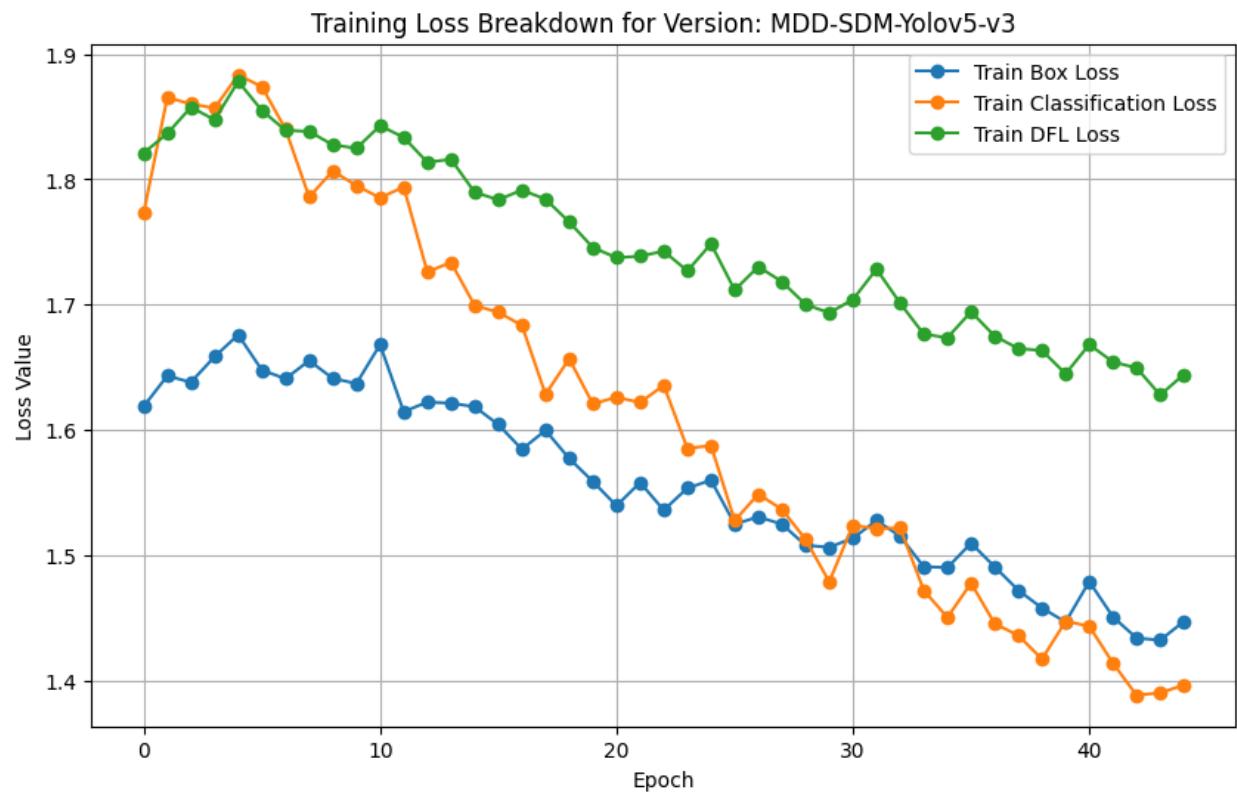


Training and Validation Losses Over Epochs for Version: MDD-SDM-Yolov5-v3



Learning Rate Schedule for Version: MDD-SDM-Yolov5-v3





This cell defines methods for processing and visualising YOLO detection results. The load_model and load_image methods handle model and image loading, while ensure_rgb ensures correct image formatting. Methods like display_images_side_by_side and crop_and_display_boxes_grouped present detection results by displaying images with bounding boxes and cropping detected regions with class labels. The analyze_detections method provides detailed analytics, including object counts, confidence scores, and visualisations like bar charts and scatter plots. When combined, these techniques make it easier to intuitively assess model performance and detection results.

```
# Load the model
def load_model(weights_path):
    if not os.path.exists(weights_path):
        raise FileNotFoundError(f"Weights file not found at {weights_path}.")
    return YOLO(weights_path)

# Load the image
def load_image(image_path):
    if not os.path.exists(image_path):
        raise FileNotFoundError(f"Image file not found at {image_path}.")
    image = cv2.imread(image_path) # Load image in BGR format
    return cv2.cvtColor(image, cv2.COLOR_BGR2RGB) # Convert to RGB

# Ensure images are in RGB format
def ensure_rgb(image):
    if len(image.shape) == 3 and image.shape[2] == 3: # Check if the image has 3 channels
        return cv2.cvtColor(image, cv2.COLOR_BGR2RGB) if not np.array_equal(
            image, cv2.cvtColor(cv2.cvtColor(image, cv2.COLOR_RGB2BGR), cv2.COLOR_BGR2RGB))
        ) else image
    elif len(image.shape) == 2: # Grayscale image
        return cv2.cvtColor(image, cv2.COLOR_GRAY2RGB) # Convert grayscale to RGB
    else:
        raise ValueError("Unsupported image format. Image must have 1 (grayscale) or 3 (RGB/BGR) channels.")

def display_images_side_by_side(original, predicted, results,
confidence_threshold=0.35, titles=("Original Test Image", "Predicted Image with Bounding Boxes")):
    # Ensure both images are in RGB format
    original_rgb = ensure_rgb(original)

    # Filter results to exclude bounding boxes with confidence below threshold
    filtered_boxes = []
    boxes = results[0].boxes # Access the bounding boxes from the
```

```

results
    if boxes is not None:
        for box in boxes:
            x1, y1, x2, y2 = box.xyxy[0].tolist() # Extract
coordinates
            confidence = box.conf.item() # Extract
confidence as a scalar
            class_id = int(box.cls.item()) # Extract class ID
as a scalar
            if confidence >= confidence_threshold:
                filtered_boxes.append((x1, y1, x2, y2, confidence,
class_id))

predicted_rgb = ensure_rgb(predicted)

# Display images side by side
plt.figure(figsize=(12, 6))
plt.subplot(1, 2, 1)
plt.imshow(original_rgb)
plt.title(titles[0])
plt.axis("off")
plt.subplot(1, 2, 2)
plt.imshow(predicted_rgb)
plt.title(titles[1])
plt.axis("off")
plt.tight_layout()
plt.show()

def crop_and_display_boxes_grouped(original_image, results,
confidence_threshold=0.36):
    # Get bounding boxes and their corresponding class names
    boxes = results[0].boxes
    confidences = boxes.conf.cpu().numpy()
    class_ids = boxes.cls.cpu().numpy()

    # Initialize a list to store cropped images
    cropped_images = []
    cropped_titles = []

    # Loop through each bounding box and crop the region
    for i, (box, confidence, class_id) in enumerate(zip(boxes,
confidences, class_ids)):
        if confidence >= confidence_threshold:
            # Get the coordinates of the bounding box
            x1, y1, x2, y2 = box.xyxy[0].tolist()

            # Crop the image around the bounding box
            cropped_image = original_image[int(y1):int(y2),
int(x1):int(x2)]

```

```

# Map class ID to class name
class_name = model.names[int(class_id)]

# Store the cropped image and its title
cropped_images.append(cropped_image)
cropped_titles.append(f"{class_name} - Conf:{confidence:.2f}")

# If there are cropped images, display them in a grid
if cropped_images:
    num_images = len(cropped_images)
    grid_size = int(np.ceil(np.sqrt(num_images))) # Calculate grid size for display

    # Plot cropped images in a grid
    plt.figure(figsize=(grid_size * 3, grid_size * 3))
    for i, (cropped_image, title) in enumerate(zip(cropped_images, cropped_titles)):
        plt.subplot(grid_size, grid_size, i + 1)
        plt.imshow(cropped_image)
        plt.title(title)
        plt.axis("off")
    plt.tight_layout()
    plt.show()

def crop_and_display_boxes_grouped(original_image, results, confidence_threshold=0.36):
    # Get bounding boxes and their corresponding class names
    boxes = results[0].boxes
    confidences = boxes.conf.cpu().numpy()
    class_ids = boxes.cls.cpu().numpy()

    # Initialize a list to store cropped images
    cropped_images = []
    cropped_titles = []

    # Loop through each bounding box and crop the region
    for i, (box, confidence, class_id) in enumerate(zip(boxes, confidences, class_ids)):
        if confidence >= confidence_threshold:
            # Get the coordinates of the bounding box
            x1, y1, x2, y2 = box.xyxy[0].tolist()

            # Crop the image around the bounding box
            cropped_image = original_image[int(y1):int(y2),
                int(x1):int(x2)]

            # Map class ID to class name
            class_name = model.names[int(class_id)]

```

```

# Store the cropped image and its title
cropped_images.append(cropped_image)
cropped_titles.append(f"{class_name} - Conf:{confidence:.2f}")

# If there are cropped images, display them in a grid
if cropped_images:
    num_images = len(cropped_images)
    grid_size = int(np.ceil(np.sqrt(num_images))) # Calculate
grid size for display

    # Plot cropped images in a grid
    plt.figure(figsize=(grid_size * 3, grid_size * 3))
    for i, (cropped_image, title) in enumerate(zip(cropped_images,
cropped_titles)):
        plt.subplot(grid_size, grid_size, i + 1)
        plt.imshow(cropped_image)
        plt.title(title)
        plt.axis("off")
    plt.tight_layout()
    plt.show()

def analyze_detections(results, model):
    # Get detected boxes and classes
    boxes = results[0].boxes # Bounding box tensor
    num_objects = len(boxes) # Total number of detected objects

    if num_objects == 0:
        print("No (0) objects detected in the image.")
        return

    # Extract class IDs and confidence scores
    class_ids = boxes.cls.cpu().numpy()
    confidences = boxes.conf.cpu().numpy()

    # Map class IDs to class names using model's class names
    class_names = [model.names[int(cls_id)] for cls_id in class_ids]

    # Define fixed classes (ensure consistency in bar chart even if
some classes are missing)
    fixed_classes = ["Mixed Waste", "Organic Waste", "Other Waste",
"Recyclable Material"]
    class_counts = {class_name: 0 for class_name in fixed_classes}
    for class_name in class_names:
        if class_name in class_counts:
            class_counts[class_name] += 1

    # Display analytics
    print("\n==== Image Analytics ===")
    print(f"Total Objects Detected: {num_objects}")

```

```

print("Object Breakdown:")
for class_name, count in class_counts.items():
    print(f" - {class_name}: {count}")
print("Confidence Scores:")
for i, (class_name, confidence) in enumerate(zip(class_names,
confidences)):
    print(f" {i + 1}. {class_name} - Confidence: {confidence:.2f}")

# Plot bar chart for class counts
colors = {
    "Mixed Waste": "lightcoral", # Pastel red
    "Organic Waste": "lightgreen", # Pastel green
    "Other Waste": "sandybrown", # Pastel orange
    "Recyclable Material": "lightskyblue" # Pastel blue
}

plt.figure(figsize=(8, 5))
plt.bar(class_counts.keys(), class_counts.values(),
color=[colors[class_name] for class_name in class_counts.keys()])
plt.title('Object Count per Class')
plt.xlabel('Classes')
plt.ylabel('Count')
plt.yticks(range(0, max(class_counts.values()) + 2, 1)) # Ensure
y-axis increments by 1
plt.show()

# Scatter plot for confidence scores
plt.figure(figsize=(10, 6))
scatter_colors = [colors[class_name] for class_name in
class_names]
plt.scatter(class_names, confidences, c=scatter_colors, alpha=0.7,
edgecolor='k')
plt.title('Confidence Scores by Class')
plt.xlabel('Classes')
plt.ylabel('Confidence Scores')
plt.ylim(0, 1.05) # Confidence scores range from 0 to 1
plt.grid(axis='y', linestyle='--', alpha=0.7)
plt.show()

```

This cell handles object detection on test images using the trained YOLOv5 model selected earlier. It validates the test folder and retrieves all valid image files. The chosen model is loaded from its specified weights file, and each test image is processed iteratively. Predictions are made for each image, with detections filtered based on a confidence threshold of 0.35. The original and predicted images are displayed side by side, highlighting bounding boxes on detected objects. Detection analytics, including object counts and confidence scores, are computed and visualised through bar charts and scatter plots. Detected bounding boxes are also cropped and displayed in a grouped grid, providing detailed insights into the detection results for each test image.

```

# Path to the selected version's folder
weights_path = os.path.join(os.getcwd(), "runs", "detect",
selected_version, "weights", "best.pt")
test_folder_path = os.path.abspath(os.path.join(os.getcwd(), "...",
"Test"))

print(f"Selected weights file: {weights_path}")

# Validate and process all images in the test folder
if not os.path.exists(test_folder_path):
    raise FileNotFoundError(f"Test folder not found at:
{test_folder_path}")

test_images = [img for img in os.listdir(test_folder_path) if
img.lower().endswith('.png', '.jpg', '.jpeg')]
if not test_images:
    raise ValueError(f"No valid image files found in the test folder:
{test_folder_path}")

# Load the YOLO model
model = load_model(weights_path)

# Ensure plots are displayed inline
%matplotlib inline

# Loop through each test image
for test_image in test_images:
    test_image_path = os.path.join(test_folder_path, test_image)
    print(f"Processing test image: {test_image_path}")

    # Perform prediction on the current test image
    results = model.predict(source=test_image_path, device='cpu')

    # Load and process the images
    original_image = load_image(test_image_path) # Ensure this loads
the image in RGB

    # Filter out boxes with confidence less than 0.35
    filtered_boxes = results[0].boxes[results[0].boxes.conf > 0.35]

    # Create a copy of results and replace boxes with filtered ones
    results[0].boxes = filtered_boxes

    # Render the filtered results
    predicted_image = cv2.cvtColor(results[0].plot(),
cv2.COLOR_BGR2RGB) # Convert rendered image to RGB

    # Display the original and predicted images side by side
    display_images_side_by_side(original_image, predicted_image,
results)

```

```

# Analyze and display detection analytics
analyze_detections(results, model)

# Crop and display the detected bounding boxes in a grouped grid
crop_and_display_boxes_grouped(original_image, results)

Selected weights file: e:\SEAN\Adv_CV\Jupyter Notebooks\runs\detect\
MDD-SDM-Yolov5-v3\weights\best.pt
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T1.jpeg

image 1/1 e:\SEAN\Adv_CV\Test\AFL_T1.jpeg: 640x480 2 Organic Wastes,
58.8ms
Speed: 3.0ms preprocess, 58.8ms inference, 1.0ms postprocess per image
at shape (1, 3, 640, 480)

```

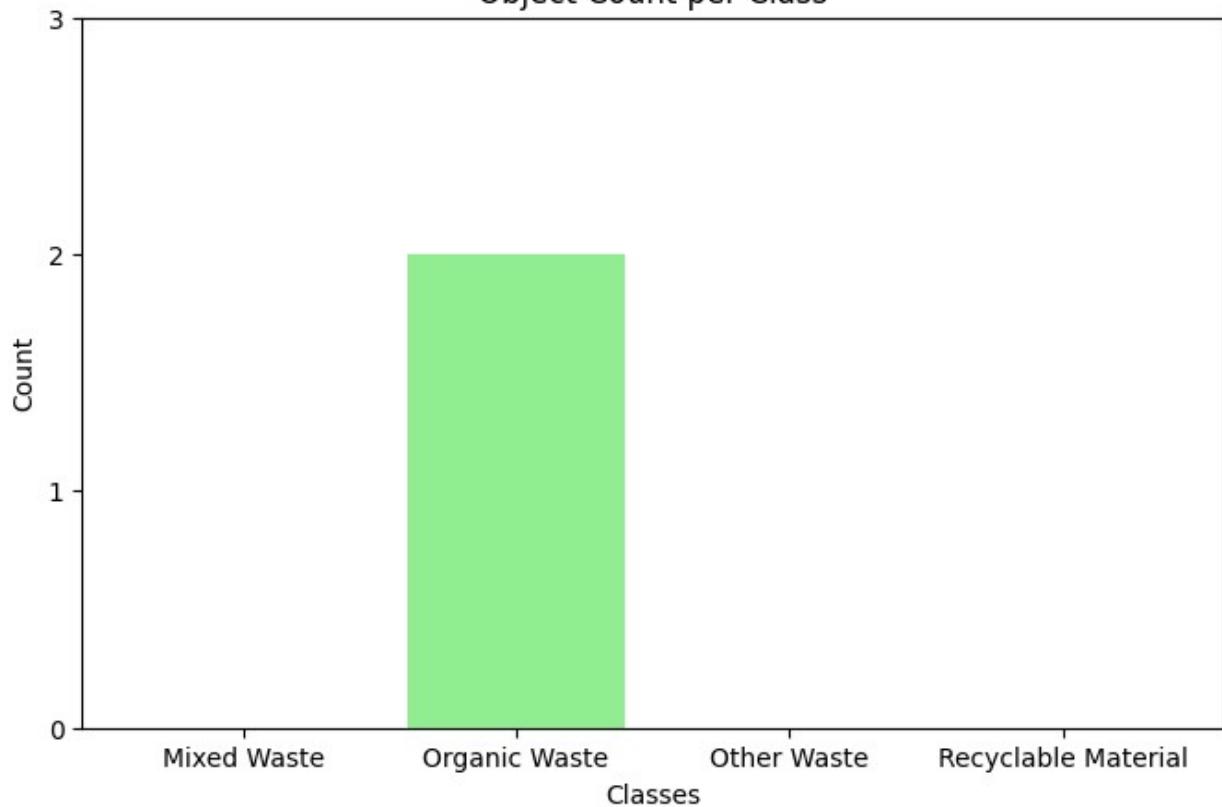


```

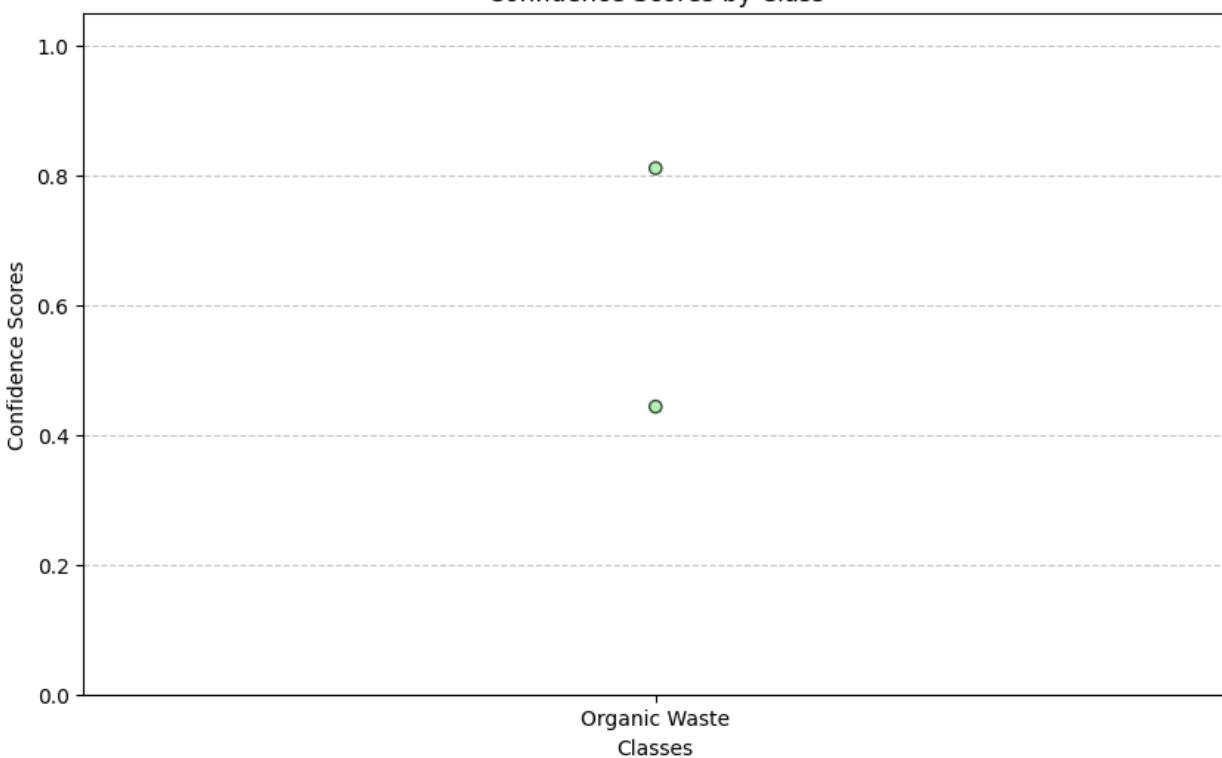
==== Image Analytics ====
Total Objects Detected: 2
Object Breakdown:
  - Mixed Waste: 0
  - Organic Waste: 2
  - Other Waste: 0
  - Recyclable Material: 0
Confidence Scores:
  1. Organic Waste - Confidence: 0.81
  2. Organic Waste - Confidence: 0.44

```

Object Count per Class



Confidence Scores by Class



Organic Waste - Conf: 0.81



Organic Waste - Conf: 0.44



```
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T1N.jpeg
```

```
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T1N.jpeg: 640x480 1 Mixed Waste,  
48.8ms
```

```
Speed: 2.0ms preprocess, 48.8ms inference, 1.0ms postprocess per image  
at shape (1, 3, 640, 480)
```

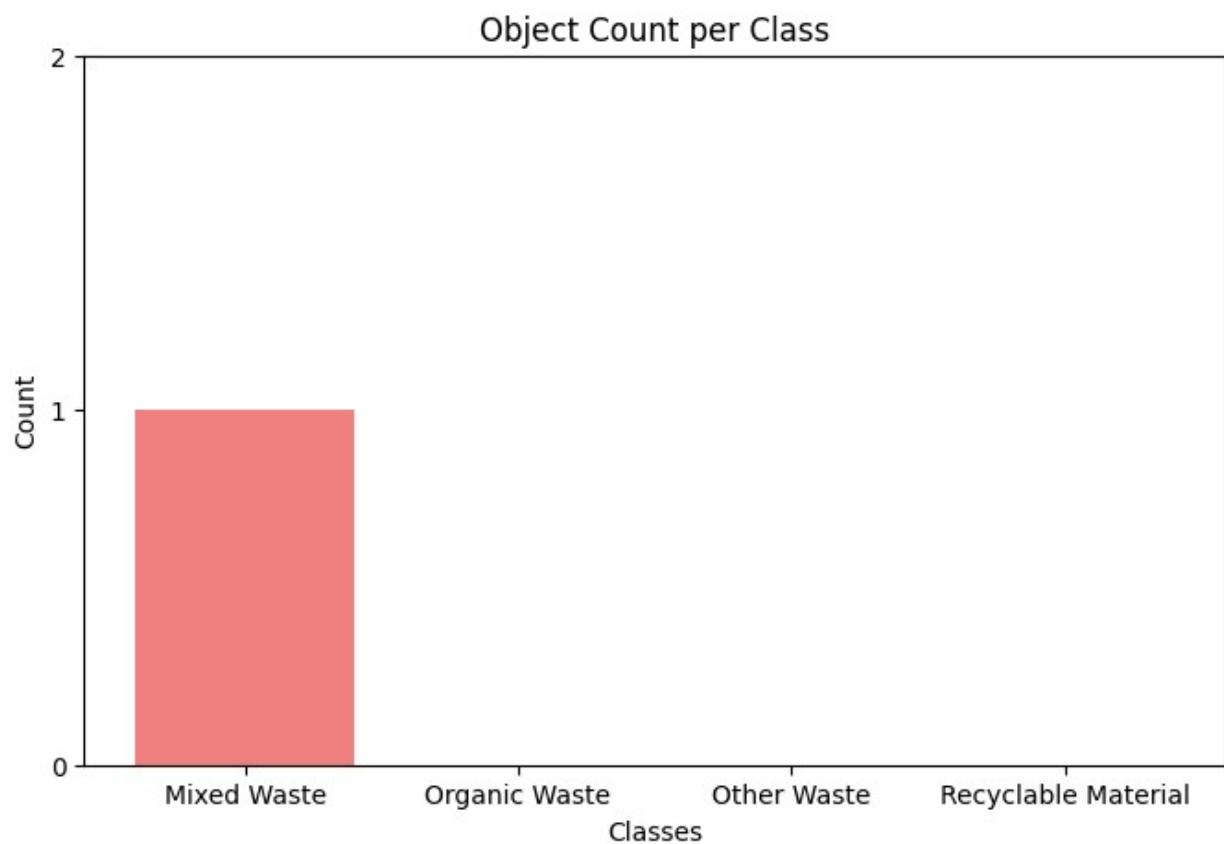
Original Test Image

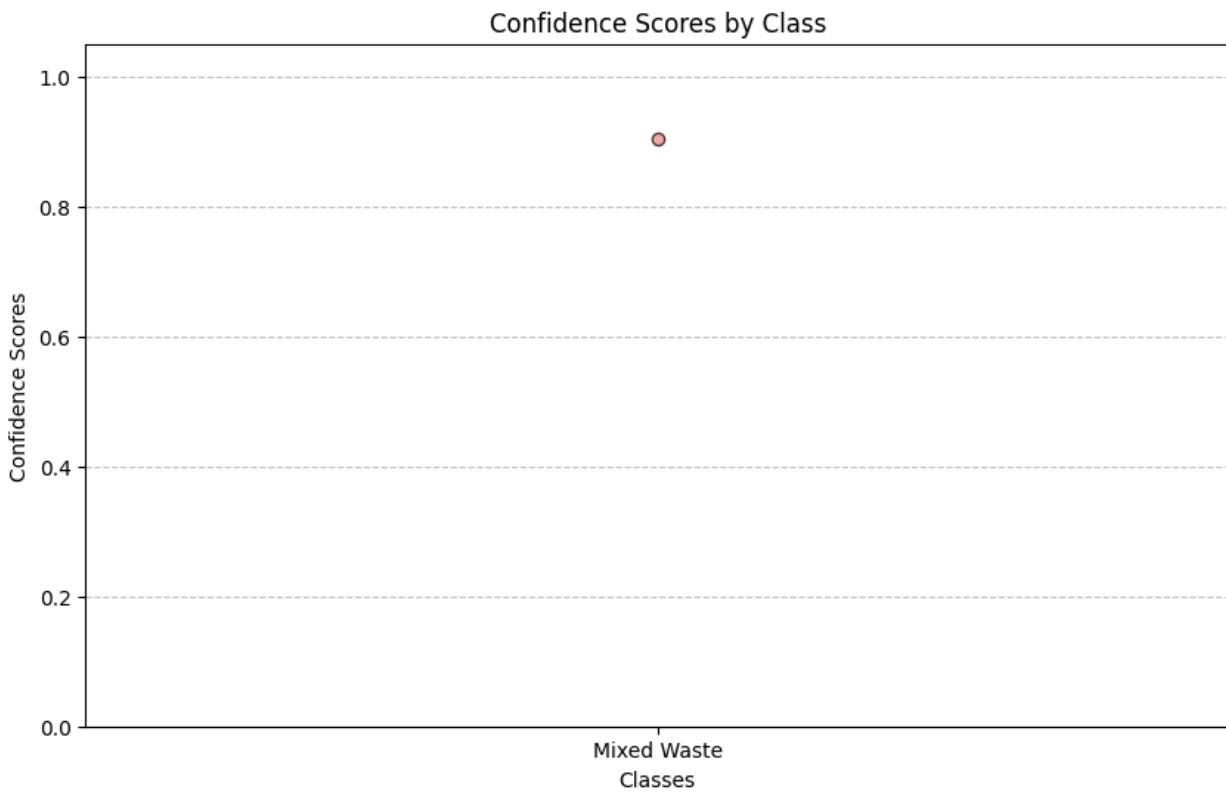


Predicted Image with Bounding Boxes



```
==== Image Analytics ====
Total Objects Detected: 1
Object Breakdown:
- Mixed Waste: 1
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 0
Confidence Scores:
1. Mixed Waste - Confidence: 0.90
```





Mixed Waste - Conf: 0.90



```
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T2.jpeg
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T2.jpeg: 640x480 1 Mixed Waste,
47.9ms
Speed: 2.0ms preprocess, 47.9ms inference, 0.0ms postprocess per image
at shape (1, 3, 640, 480)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

Total Objects Detected: 1

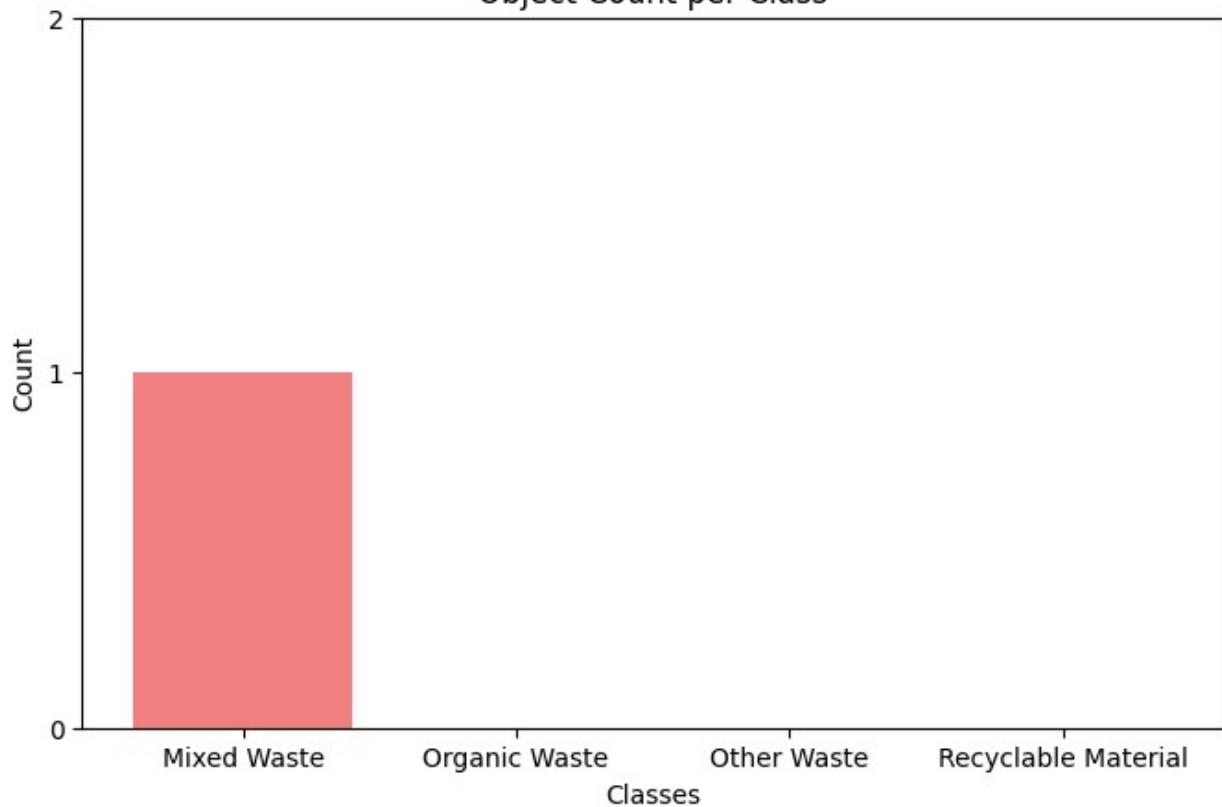
Object Breakdown:

- Mixed Waste: 1
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 0

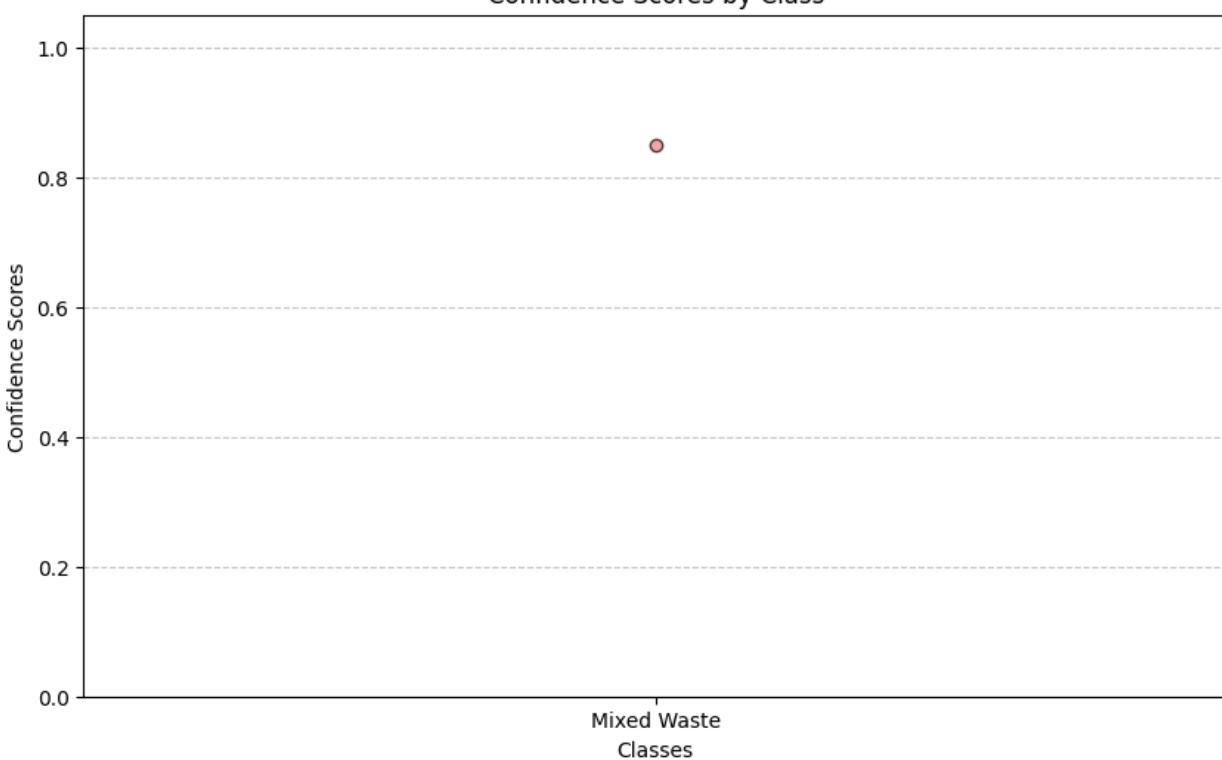
Confidence Scores:

1. Mixed Waste - Confidence: 0.85

Object Count per Class



Confidence Scores by Class



Mixed Waste - Conf: 0.85



```
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T2N.jpeg
```

```
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T2N.jpeg: 640x480 (no detections),  
52.4ms
```

```
Speed: 3.0ms preprocess, 52.4ms inference, 1.0ms postprocess per image  
at shape (1, 3, 640, 480)
```

Original Test Image



Predicted Image with Bounding Boxes



```
No (0) objects detected in the image.
```

```
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T3.jpeg
```

```
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T3.jpeg: 640x480 2 Mixed Wastes,  
63.8ms  
Speed: 2.0ms preprocess, 63.8ms inference, 1.0ms postprocess per image  
at shape (1, 3, 640, 480)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

Total Objects Detected: 1

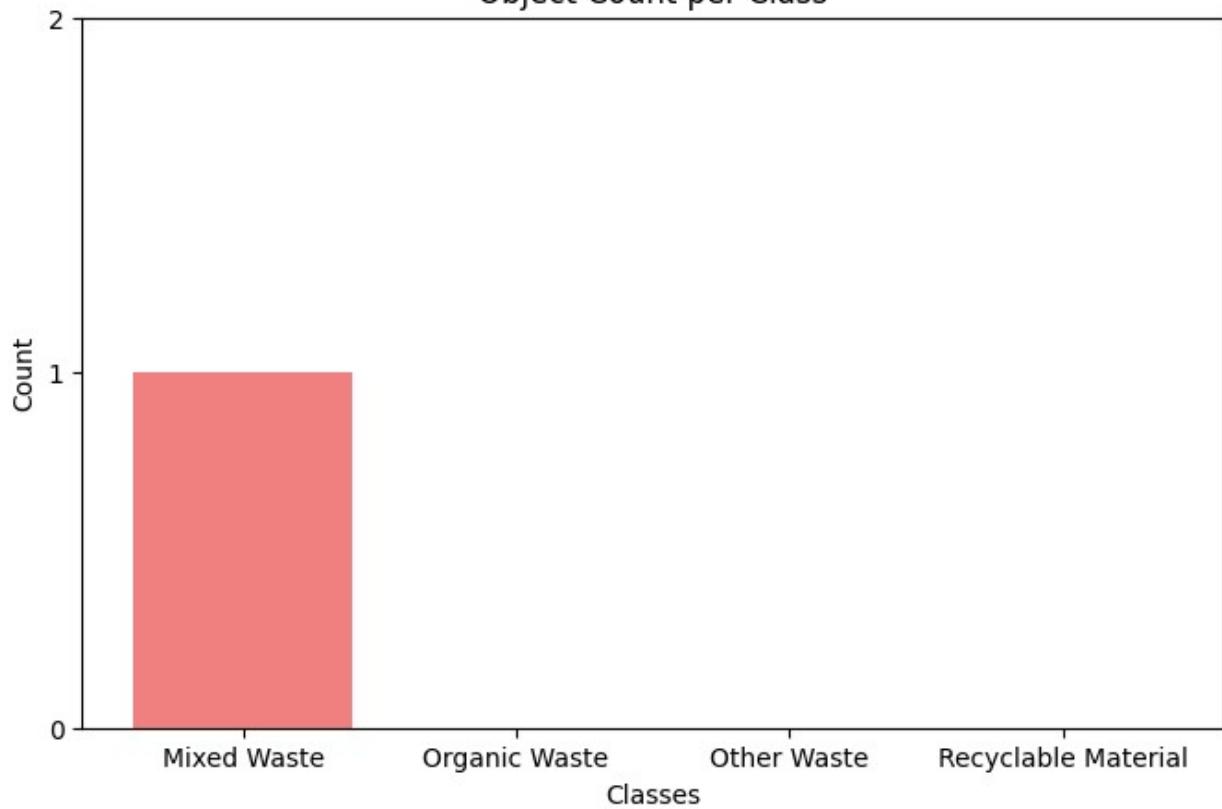
Object Breakdown:

- Mixed Waste: 1
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 0

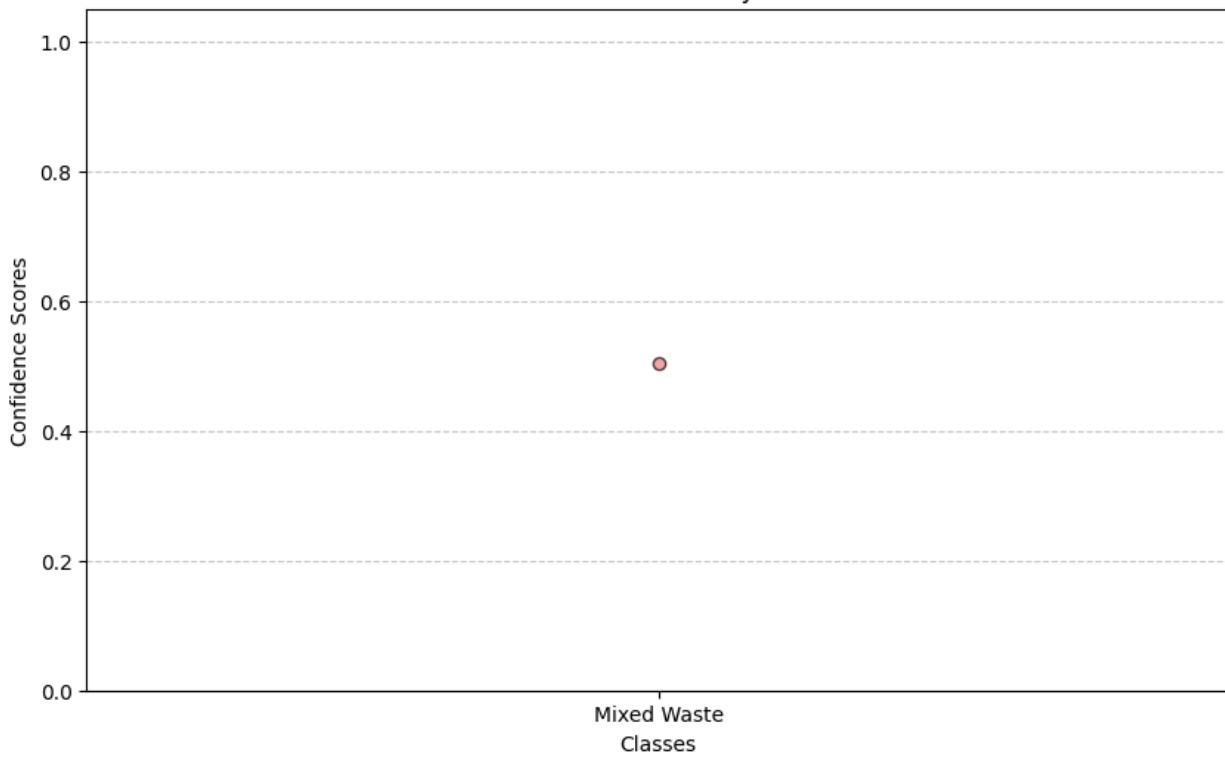
Confidence Scores:

1. Mixed Waste - Confidence: 0.50

Object Count per Class



Confidence Scores by Class



Mixed Waste - Conf: 0.50



Processing test image: e:\SEAN\Adv_CV\Test\AFL_T3N.jpeg

image 1/1 e:\SEAN\Adv_CV\Test\AFL_T3N.jpeg: 640x480 3 Mixed Wastes, 1 Other Waste, 51.9ms

Speed: 3.0ms preprocess, 51.9ms inference, 1.0ms postprocess per image at shape (1, 3, 640, 480)

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

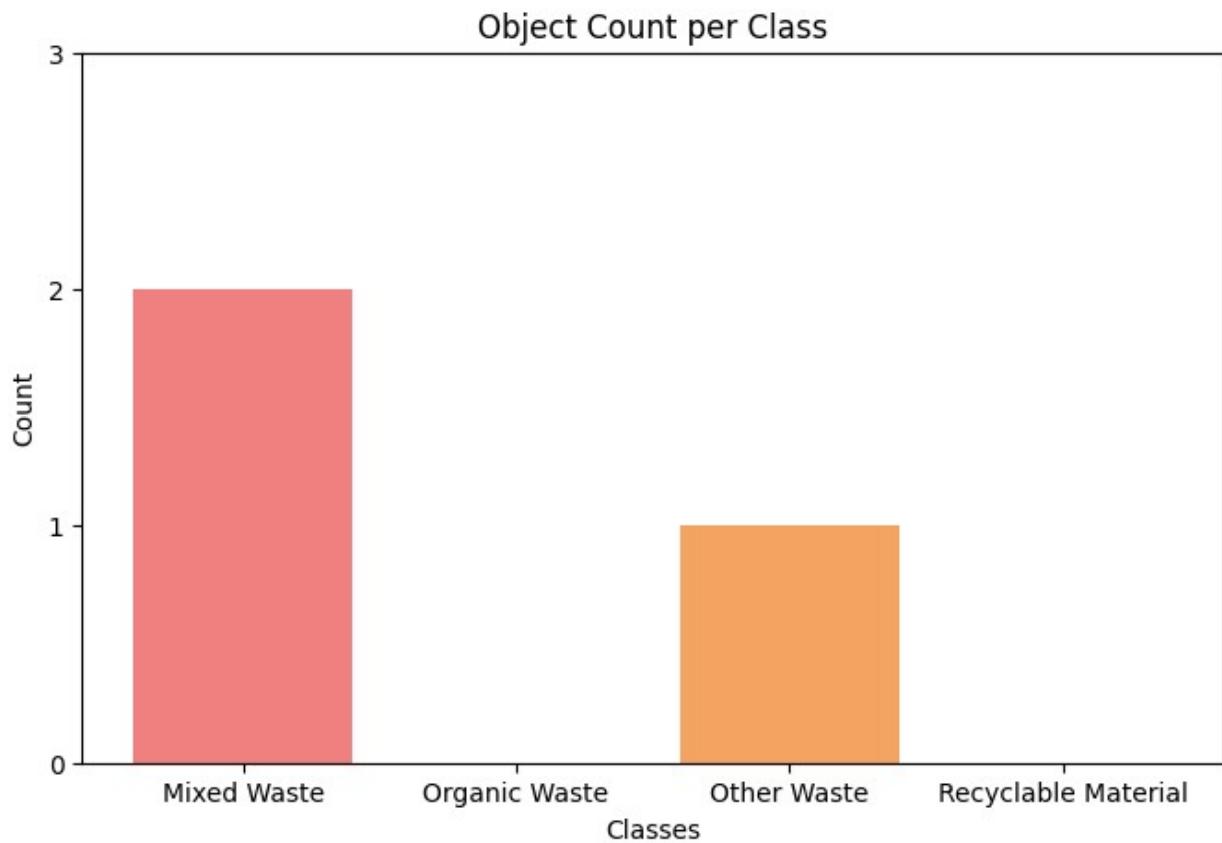
Total Objects Detected: 3

Object Breakdown:

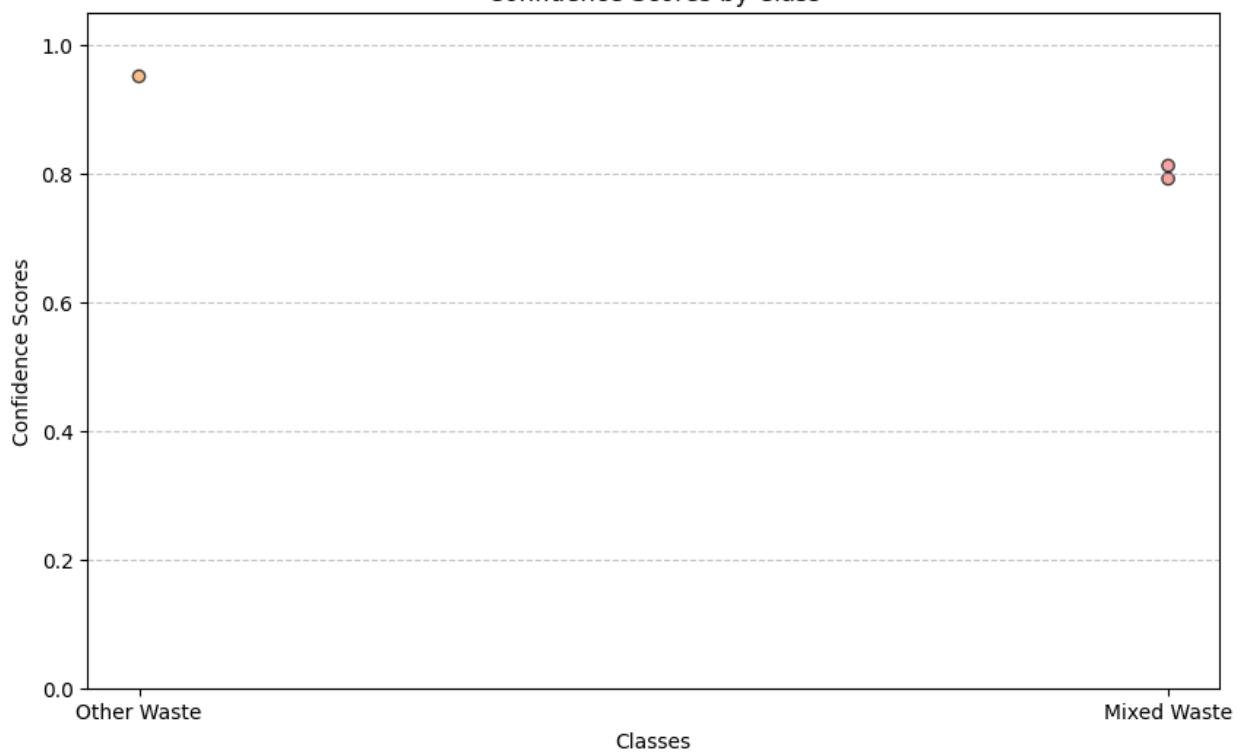
- Mixed Waste: 2
- Organic Waste: 0
- Other Waste: 1
- Recyclable Material: 0

Confidence Scores:

1. Other Waste - Confidence: 0.95
2. Mixed Waste - Confidence: 0.81
3. Mixed Waste - Confidence: 0.79



Confidence Scores by Class



Other Waste - Conf: 0.95



Mixed Waste - Conf: 0.81



Mixed Waste - Conf: 0.79



```
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T4.jpeg
```

```
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T4.jpeg: 640x480 1 Recyclable  
Material, 50.9ms
```

```
Speed: 3.0ms preprocess, 50.9ms inference, 0.0ms postprocess per image  
at shape (1, 3, 640, 480)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

Total Objects Detected: 1

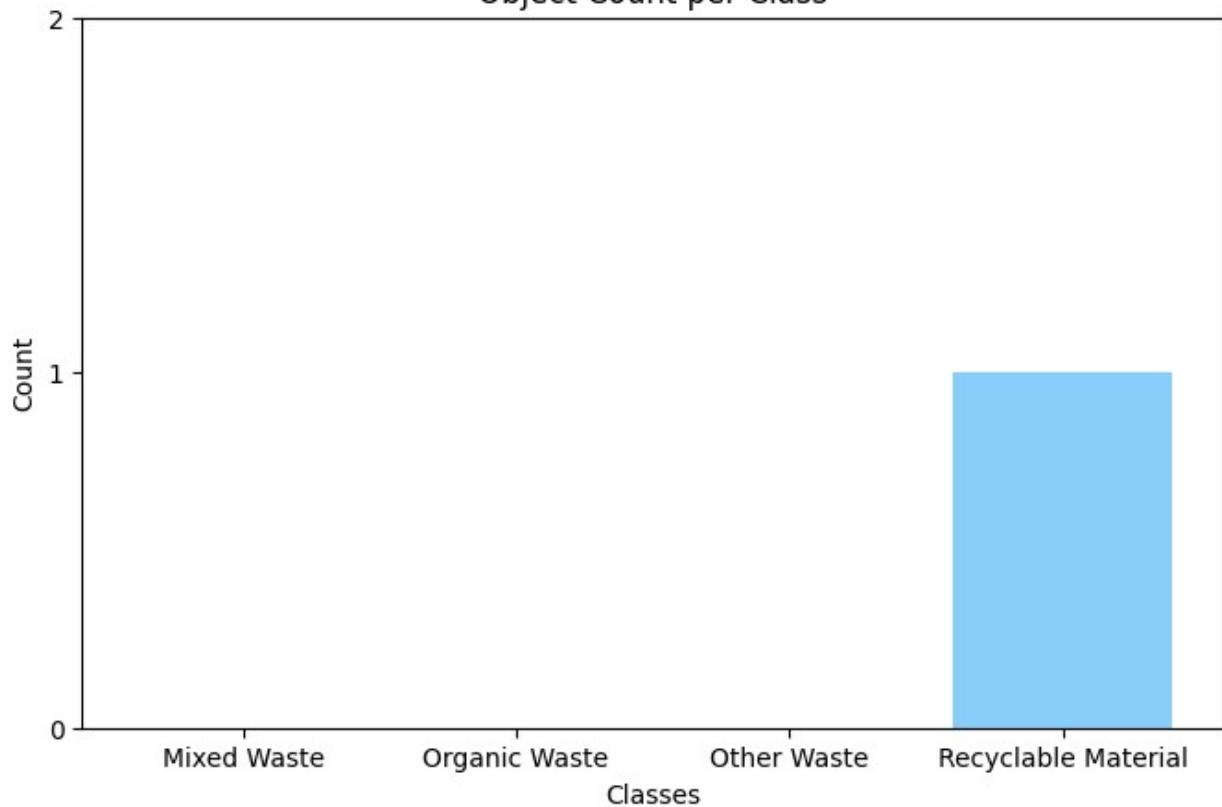
Object Breakdown:

- Mixed Waste: 0
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 1

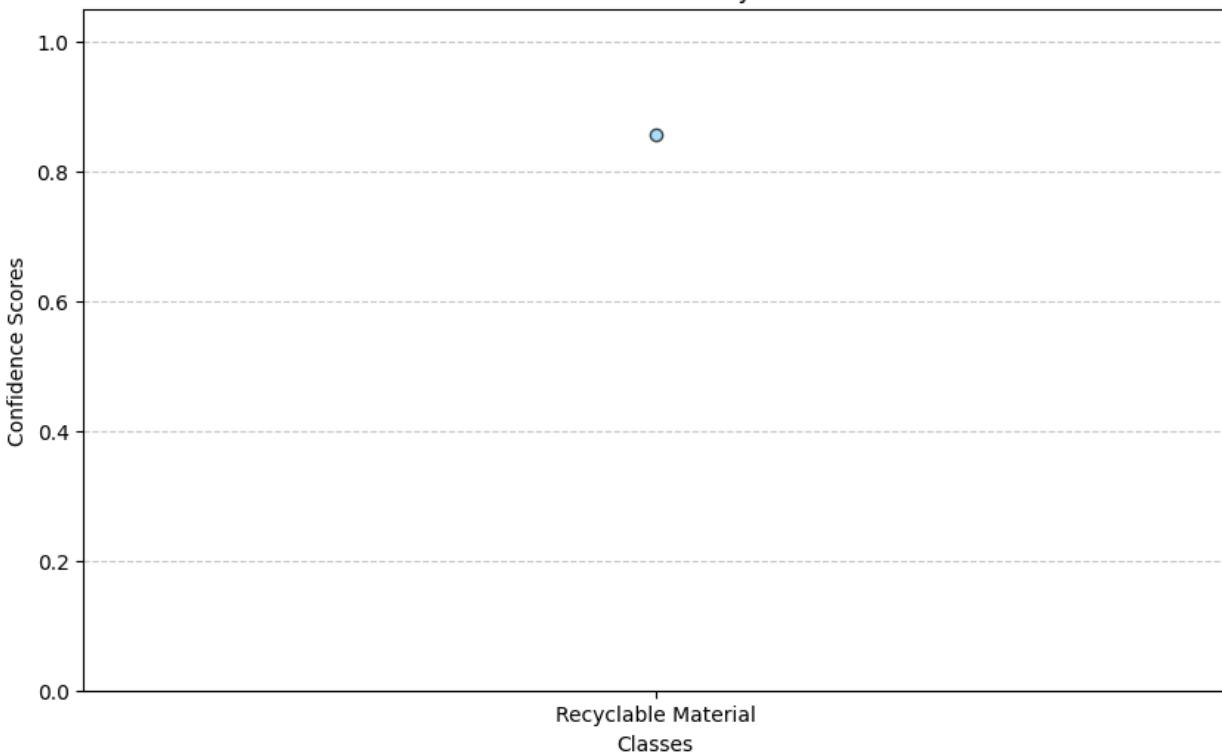
Confidence Scores:

1. Recyclable Material - Confidence: 0.86

Object Count per Class



Confidence Scores by Class



Recyclable Material - Conf: 0.86



Processing test image: e:\SEAN\Adv_CV\Test\AFL_T4N.jpeg

image 1/1 e:\SEAN\Adv_CV\Test\AFL_T4N.jpeg: 416x640 1 Mixed Waste, 1 Organic Waste, 110.2ms
Speed: 2.0ms preprocess, 110.2ms inference, 1.0ms postprocess per image at shape (1, 3, 416, 640)

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ====

Total Objects Detected: 1

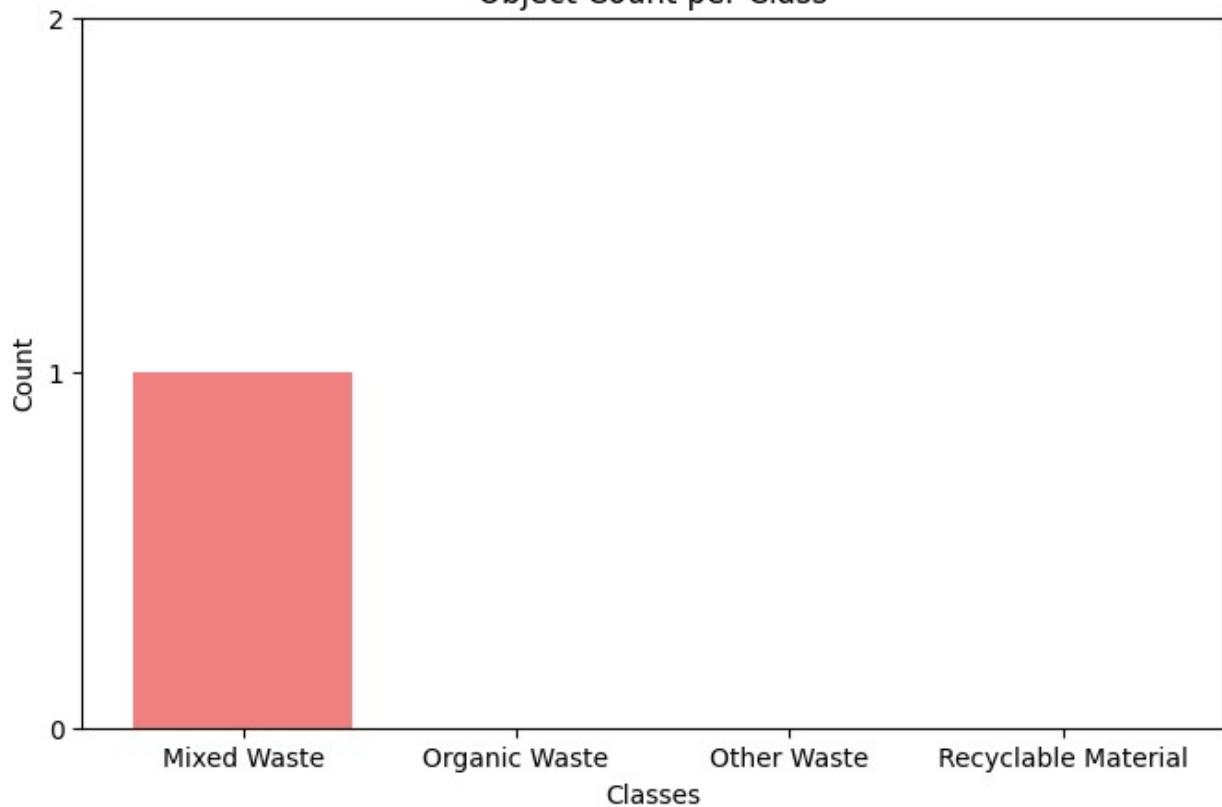
Object Breakdown:

- Mixed Waste: 1
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 0

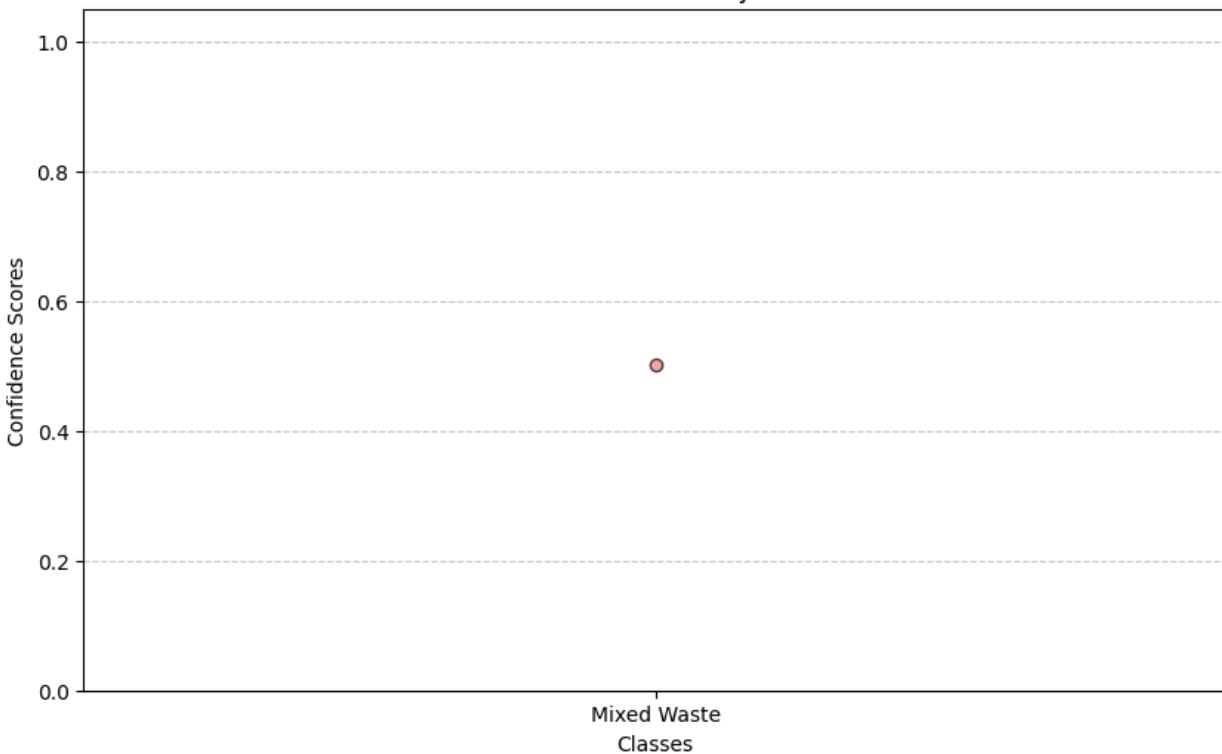
Confidence Scores:

1. Mixed Waste - Confidence: 0.50

Object Count per Class



Confidence Scores by Class



Mixed Waste - Conf: 0.50



Processing test image: e:\SEAN\Adv_CV\Test\AFL_T5.jpeg

```
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T5.jpeg: 640x480 1 Organic Waste, 2  
Recyclable Materials, 130.2ms  
Speed: 2.0ms preprocess, 130.2ms inference, 1.0ms postprocess per  
image at shape (1, 3, 640, 480)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

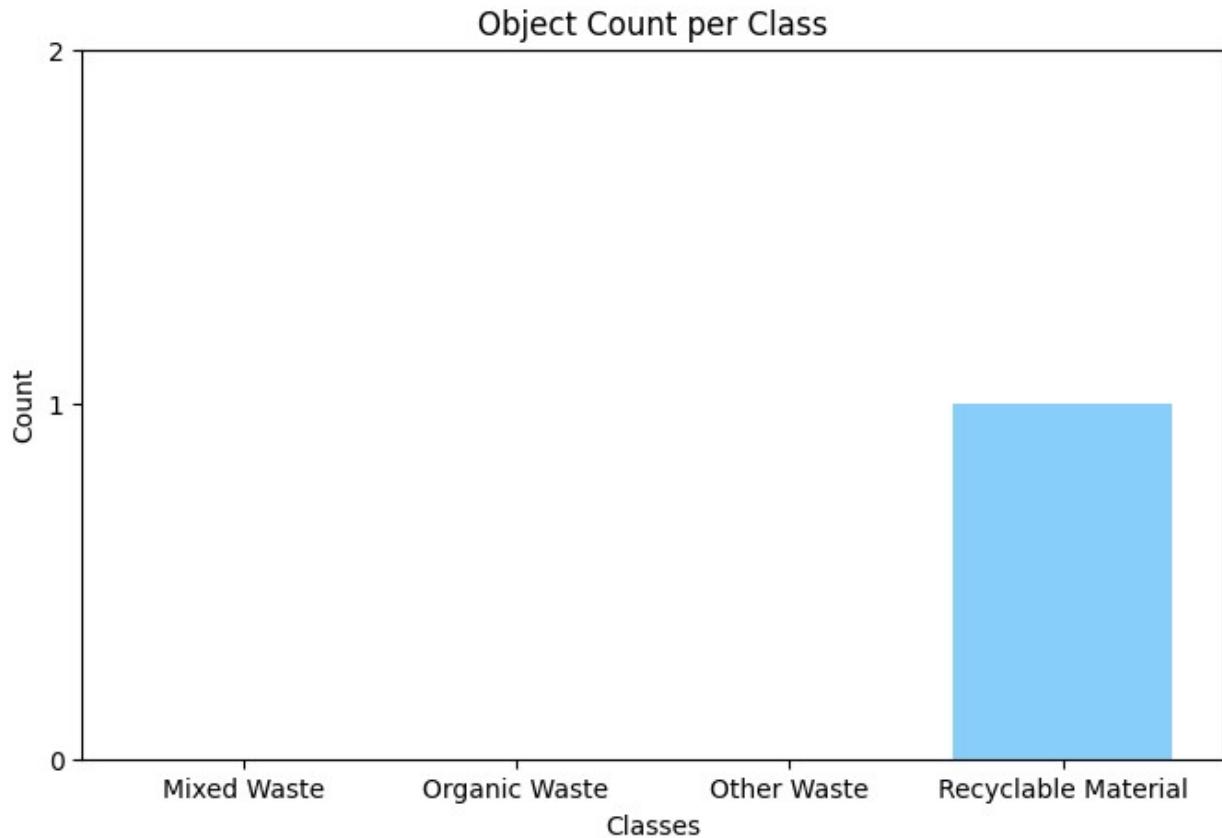
Total Objects Detected: 1

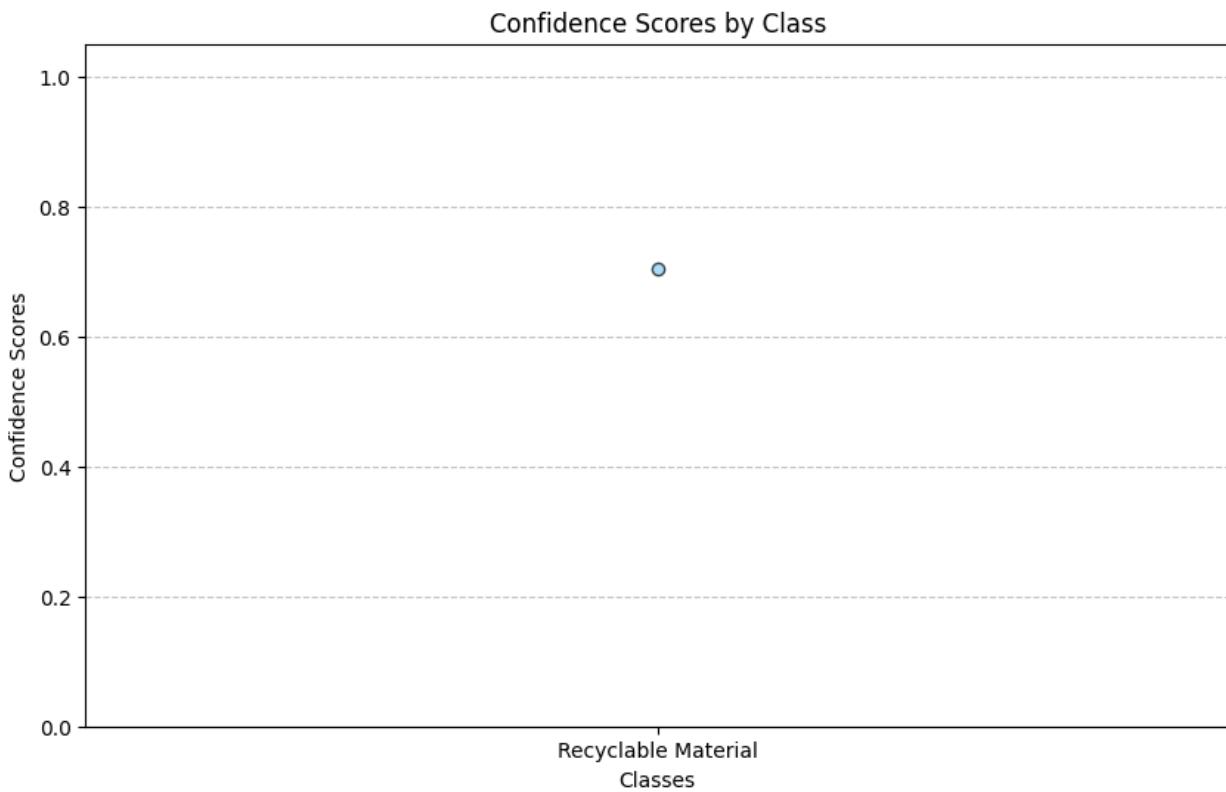
Object Breakdown:

- Mixed Waste: 0
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 1

Confidence Scores:

1. Recyclable Material - Confidence: 0.70





Recyclable Material - Conf: 0.70



```
Processing test image: e:\SEAN\Adv_CV\Test\AFL_T5N.jpeg
image 1/1 e:\SEAN\Adv_CV\Test\AFL_T5N.jpeg: 640x480 1 Mixed Waste,
107.7ms
Speed: 2.0ms preprocess, 107.7ms inference, 0.0ms postprocess per
image at shape (1, 3, 640, 480)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

Total Objects Detected: 1

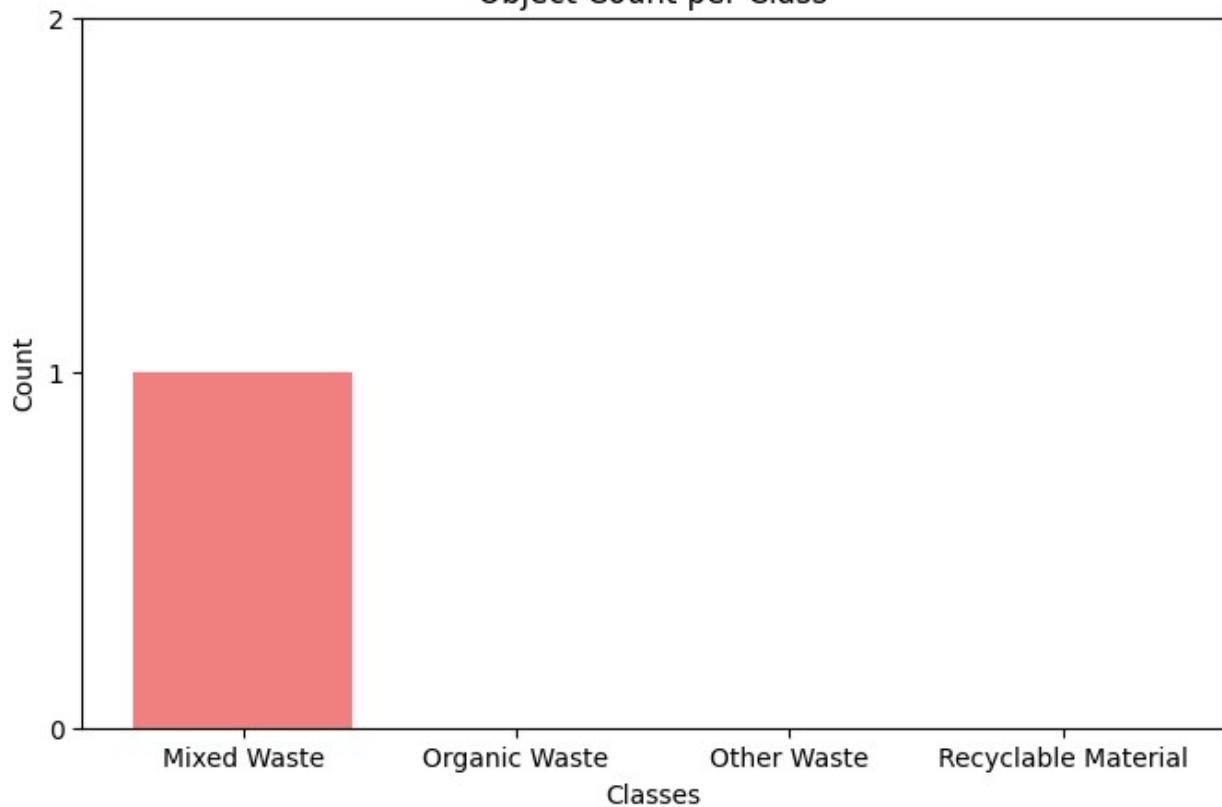
Object Breakdown:

- Mixed Waste: 1
- Organic Waste: 0
- Other Waste: 0
- Recyclable Material: 0

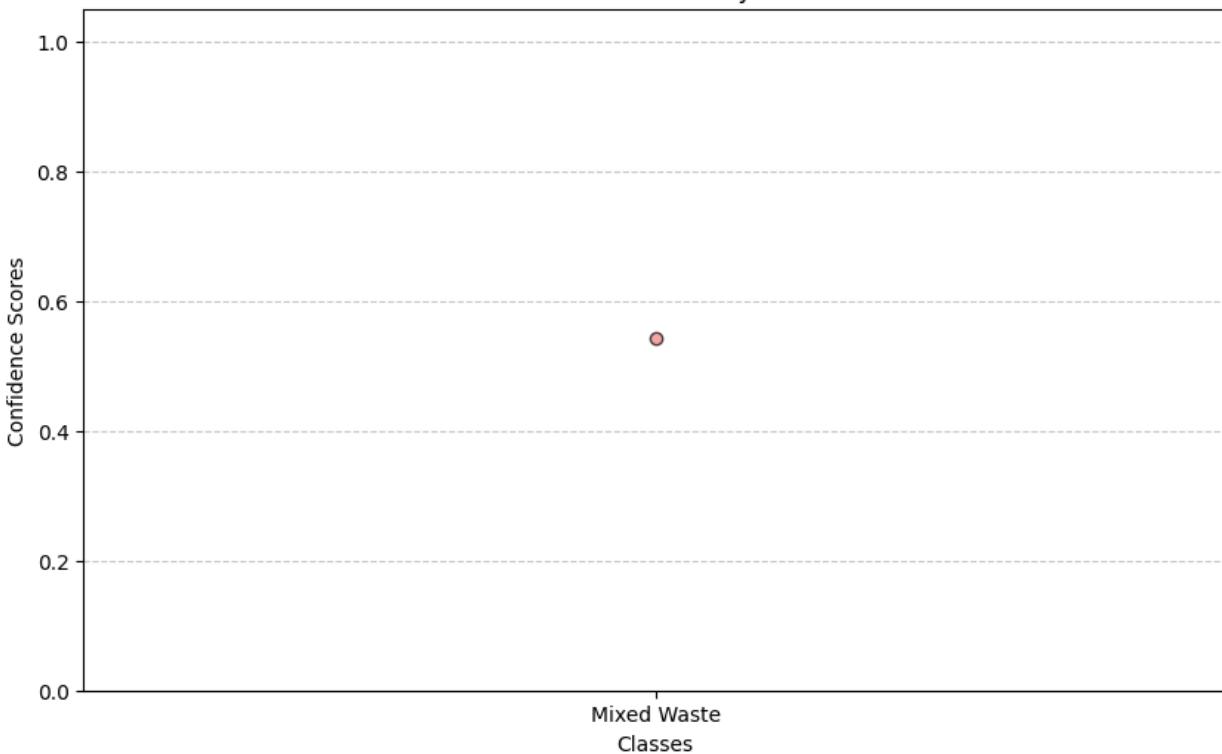
Confidence Scores:

1. Mixed Waste - Confidence: 0.54

Object Count per Class



Confidence Scores by Class



Mixed Waste - Conf: 0.54



```
Processing test image: e:\SEAN\Adv_CV\Test\SDM_T1.jpg
image 1/1 e:\SEAN\Adv_CV\Test\SDM_T1.jpg: 640x320 1 Organic Waste,
47.9ms
Speed: 1.0ms preprocess, 47.9ms inference, 1.0ms postprocess per image
at shape (1, 3, 640, 320)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

Total Objects Detected: 1

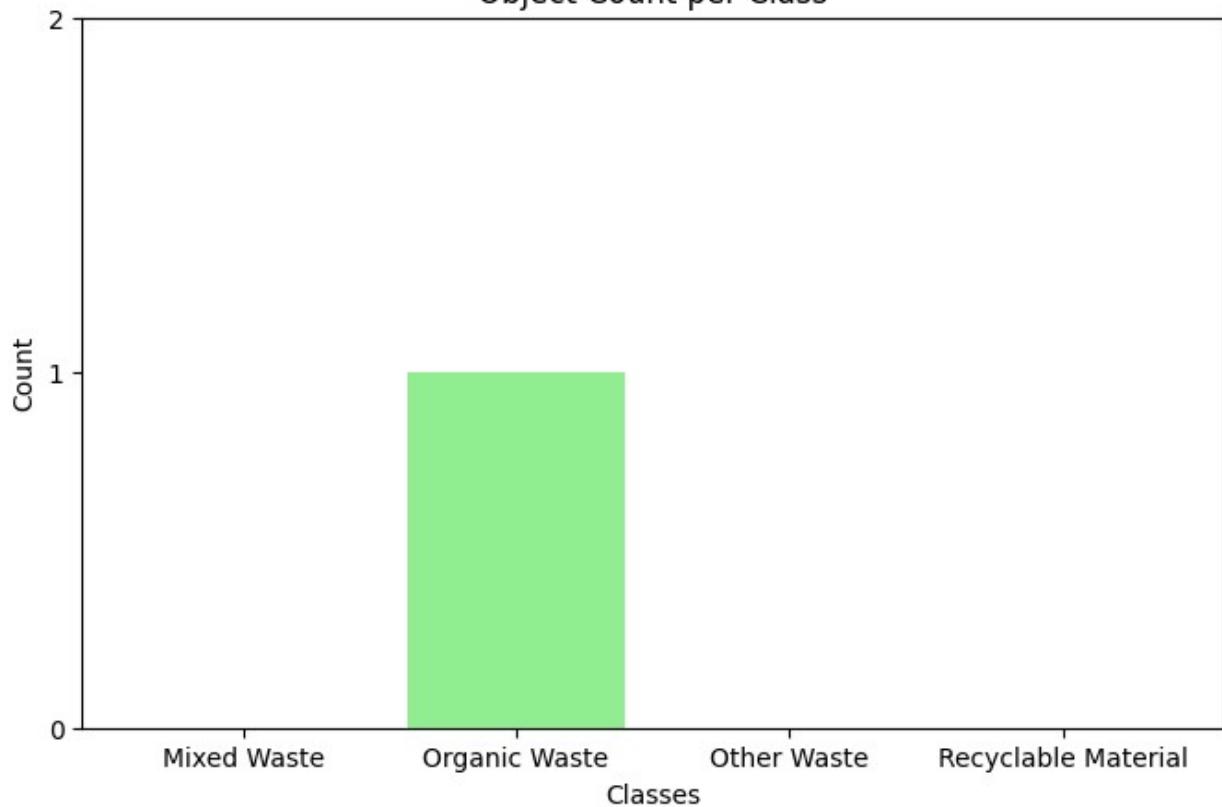
Object Breakdown:

- Mixed Waste: 0
- Organic Waste: 1
- Other Waste: 0
- Recyclable Material: 0

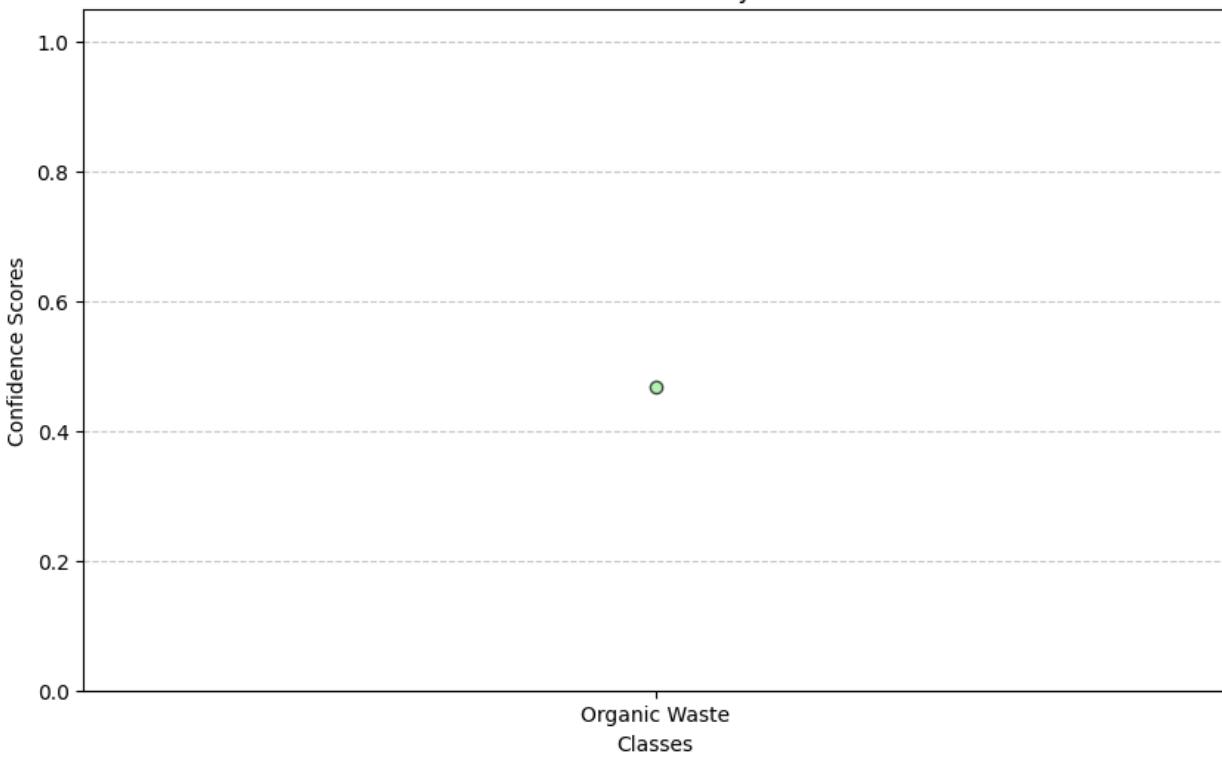
Confidence Scores:

1. Organic Waste - Confidence: 0.47

Object Count per Class



Confidence Scores by Class



Organic Waste - Conf: 0.47



```
Processing test image: e:\SEAN\Adv_CV\Test\SDM_T2.jpg
```

```
image 1/1 e:\SEAN\Adv_CV\Test\SDM_T2.jpg: 640x320 1 Other Waste, 1  
Recyclable Material, 36.9ms  
Speed: 2.0ms preprocess, 36.9ms inference, 1.0ms postprocess per image  
at shape (1, 3, 640, 320)
```

Original Test Image



Predicted Image with Bounding Boxes



==== Image Analytics ===

Total Objects Detected: 2

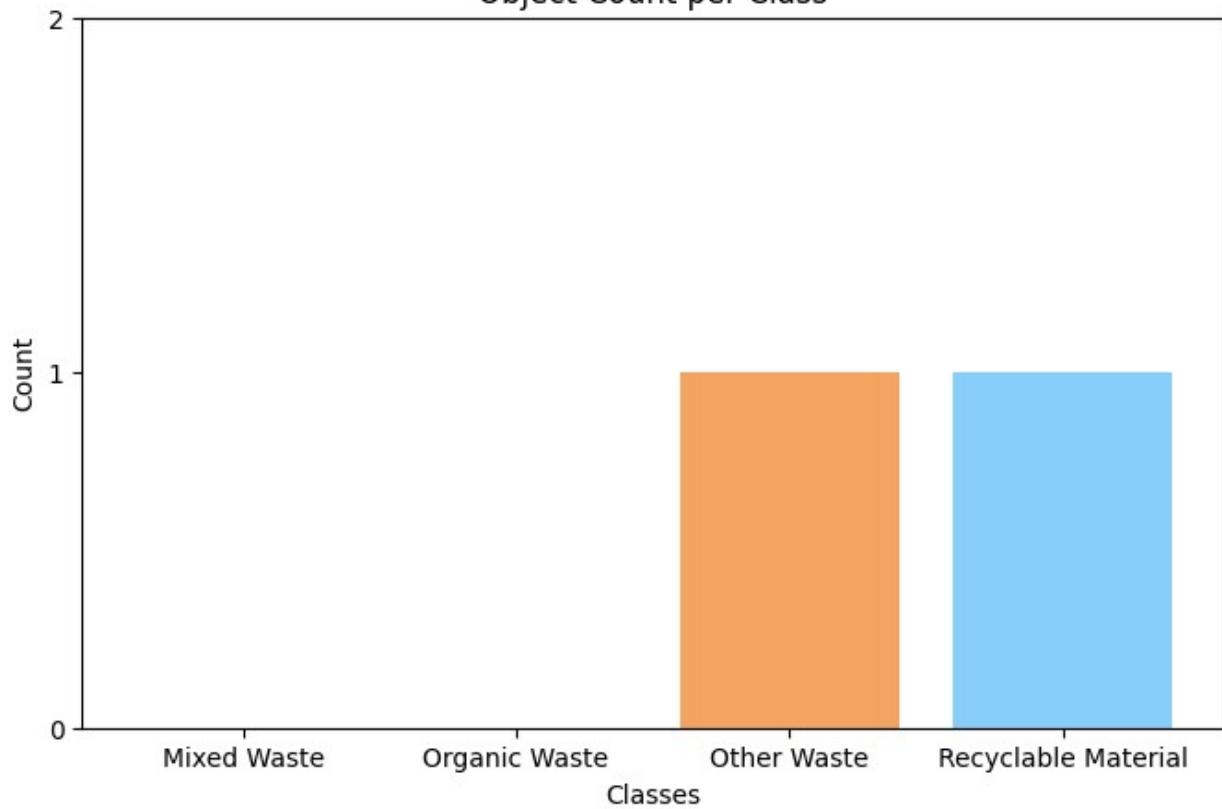
Object Breakdown:

- Mixed Waste: 0
- Organic Waste: 0
- Other Waste: 1
- Recyclable Material: 1

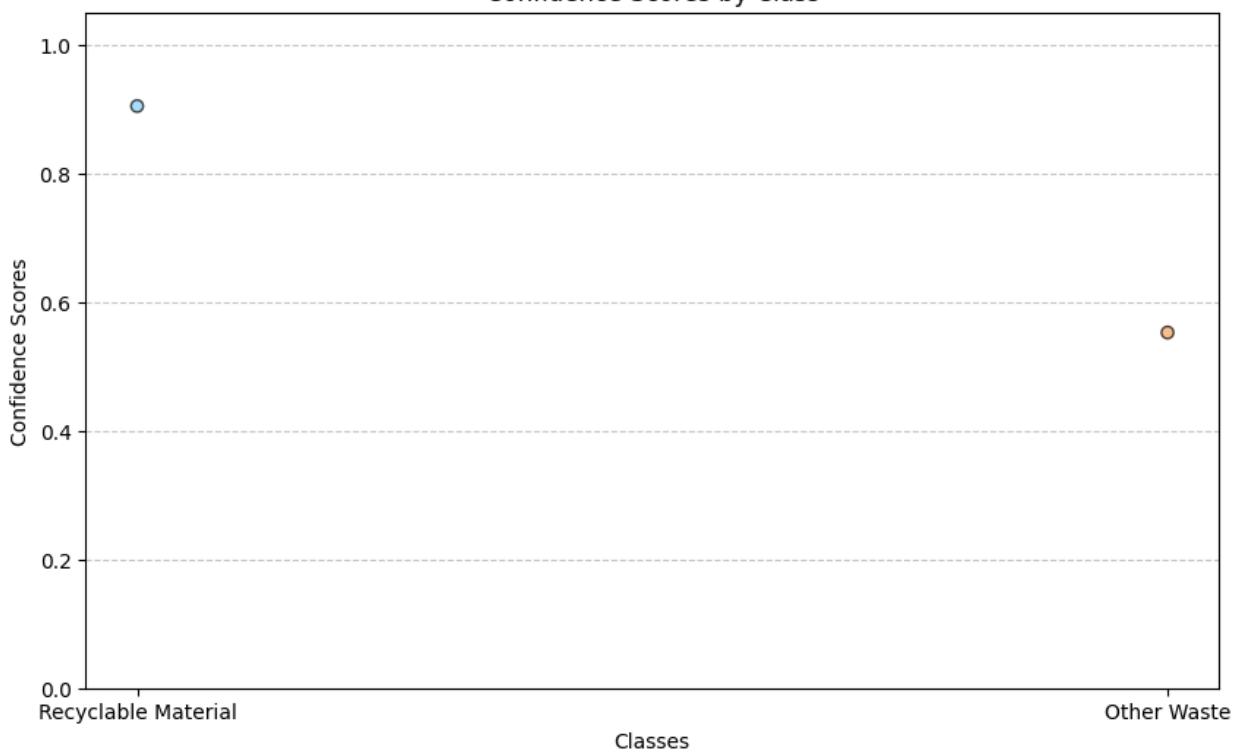
Confidence Scores:

1. Recyclable Material - Confidence: 0.90
2. Other Waste - Confidence: 0.55

Object Count per Class



Confidence Scores by Class



Recyclable Material - Conf: 0.90



Other Waste - Conf: 0.55

