



UniversitätsKlinikum Heidelberg

Optimal Subgroup Selection Rules in Adaptive Oncology Trials with Time-to-Event Outcome

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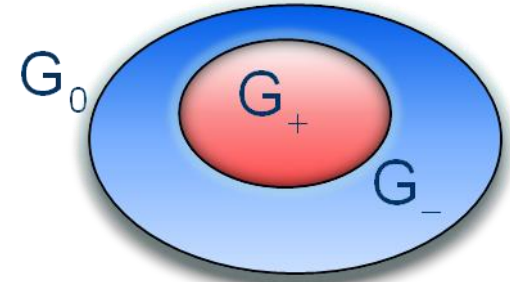
Outline

- Introducing background and basic notation and the statistical model
- Calculating optimal decision rules in case of uncertainty about trial design parameters for the situation of a time-to-event endpoint
- Deriving optimal decision rules based on data from a clinical trial example and comparing them to fixed *ad hoc* rules in terms of correct selection probability



Background

- Total patient population G_0
- Prospectively defined subgroup G_+
 - potentially increased benefit
 - identified by biomarker
- Complementary subgroup $G_- := G_0 \setminus G_+$
- Selection of the target population based on data
 - (pilot / phase II) study A \rightarrow (pivotal / phase III) study B
 - first stage \rightarrow second stage of adaptive seamless design (e.g. Jenkins et al., 2011; Brannath et al., 2011; Friede et al., 2012)

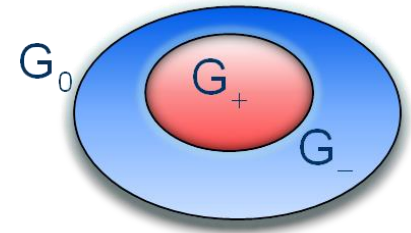




Assumptions and notations

- Assumptions:

- time-to-event-outcome
- two balanced groups T (=treatment), C (=control)

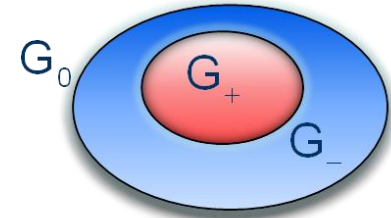


- Notations:

- M_{iP} : median event times for patients from treatment group $i = T, C$ and subgroup G_P with $P = +, -$
- Δ_P : logarithm of the hazard ratio in subgroup G_P with $P = 0, +, -$
- π : prevalence of subgroup G_+
- d : number of accumulated events per stage



Basics



- Let

$$\hat{\Delta}_+ := U_+ \cdot 2/\sqrt{d_+}, \quad \hat{\Delta}_- := U_- \cdot 2/\sqrt{d_-}, \quad \hat{\Delta}_0 := U_0 \cdot 2/\sqrt{d},$$

where U_P and are the „unsquared“ versions of the (stratified) log rank test statistics and, respectively, d_P the accumulated number of events in population $P = 0, +, -$.

- If (Δ_+, Δ_0) are not „too far“ away from 0, $(\hat{\Delta}_+, \hat{\Delta}_0)$ are estimators for the log hazard ratios (Wassmer 2005), and (Brannath et al. 2009) can be assumed to be approximately normal with

$$(\hat{\Delta}_+, \hat{\Delta}_0) | \Delta_+, \Delta_0 \sim N \left[(\Delta_+, \pi\Delta_+ + (1 - \pi)\Delta_-), \begin{pmatrix} 4/\pi d & 4/d \\ 4/d & 4/d \end{pmatrix} \right],$$

assuming πd events occurred in G_+ at interim.



Example for a decision rule

- Decision rule proposed by Jenkins et al. 2011:

Log hazard ratio estimates at interim	$\hat{\Delta}_0 > c_0$	$\hat{\Delta}_0 \leq c_0$
$\hat{\Delta}_+ > c_+$		
$\hat{\Delta}_+ \leq c_+$		

- How to choose (c_0, c_+) in case of uncertain $\Delta_0, \Delta_+, \Delta_-$?



Optimal decision rules

- Assumptions:

- selection of G_0 desired if $\Delta_0 > \tau_0$
- selection of G_+ desired if $\Delta_+ > \tau_+$
- Normal prior distribution assumed for either

a) (Δ_0, Δ_+) with

$$(\Delta_0, \Delta_+) \sim N \left[(m_0, m_+), \begin{pmatrix} w_0 & \rho_a \sqrt{w_0 w_+} \\ \rho_a \sqrt{w_0 w_+} & w_+ \end{pmatrix} \right] \text{ or}$$

b) (Δ_+, Δ_-) with

$$(\Delta_+, \Delta_-) \sim N \left[(m_+, m_-), \begin{pmatrix} w_+ & \rho_b \sqrt{w_+ w_-} \\ \rho_b \sqrt{w_+ w_-} & w_- \end{pmatrix} \right]$$

- quadratic loss function for wrong decision

→ **optimal decision rule minimizes expected loss (“risk”)**



Optimal decision rules (2)

- Under the previous assumptions, an optimal decision threshold pair (c_0^*, c_+^*) can be explicitly determined:
 - assuming a normal prior for (Δ_0, Δ_+) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(m_0 - \tau_0)}{dw_0} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi dw_+} + \tau_+ \right),$$



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b) assuming a normal prior for (Δ_+, Δ_-) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\pi m_+ + (1 - \pi)m_- - \tau_0)}{d(\pi^2 w_+ + 2\pi(1 - \pi)\rho_b \sqrt{w_+ w_-} + (1 - \pi)^2 w_-)} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi dw_+} + \tau_+ \right).$$



General remarks on optimal decision rules

a) Assuming a normal prior for (Δ_0, Δ_+) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(m_0 - \tau_0)}{\mathbf{d}w_0} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi \mathbf{d}w_+} + \tau_+ \right),$$

b) assuming a normal prior for (Δ_+, Δ_-) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\pi m_+ + (1 - \pi)m_- - \tau_0)}{\mathbf{d}(\pi^2 w_+ + 2\pi(1 - \pi)\rho_b \sqrt{w_+ w_-} + (1 - \pi)^2 w_-)} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi \mathbf{d}w_+} + \tau_+ \right).$$

➤ For an increasing number of events d , (c_0^*, c_+^*) converge towards (τ_0, τ_+) .



General remarks on optimal decision rules (2)

a) Assuming a normal prior for (Δ_0, Δ_+) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\mathbf{m}_0 - \boldsymbol{\tau}_0)}{dw_0} + \tau_0, -\frac{4(\mathbf{m}_+ - \boldsymbol{\tau}_+)}{\pi dw_+} + \tau_+ \right),$$

b) assuming a normal prior for (Δ_+, Δ_-) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\pi \mathbf{m}_+ + (1 - \pi) \mathbf{m}_- - \boldsymbol{\tau}_0)}{d(\pi^2 w_+ + 2\pi(1 - \pi)\rho_b \sqrt{w_+ w_-} + (1 - \pi)^2 w_-)} + \tau_0, -\frac{4(\mathbf{m}_+ - \boldsymbol{\tau}_+)}{\pi dw_+} + \tau_+ \right).$$

➤ Whether c_0^*/c_+^* lies above or below τ_0/τ_+ is determined via the sign of $(\pi m_+ + (1 - \pi)m_-) - \tau_0/m_0 - \tau_0/m_+ - \tau_+$, and the smaller the respective difference, the closer c_i^* will be to τ_i , $i = 0, +$.



General remarks on optimal decision rules (3)

a) Assuming a normal prior for (Δ_0, Δ_+) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(m_0 - \tau_0)}{d\mathbf{w}_0} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi d\mathbf{w}_+} + \tau_+ \right),$$

b) assuming a normal prior for (Δ_+, Δ_-) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\pi m_+ + (1 - \pi)m_- - \tau_0)}{d(\pi^2 \mathbf{w}_+ + 2\pi(1 - \pi)\rho_b \sqrt{\mathbf{w}_+ \mathbf{w}_-} + (1 - \pi)^2 \mathbf{w}_-)} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi d\mathbf{w}_+} + \tau_+ \right).$$

➤ The larger the prior variances w_i , $i = 0, +, -$, the closer the optimal decision thresholds c_i^* are to τ_i , $i = 0, +$.



General remarks on optimal decision rules (4)

a) Assuming a normal prior for (Δ_0, Δ_+) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(m_0 - \tau_0)}{dw_0} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi dw_+} + \tau_+ \right),$$

b) assuming a normal prior for (Δ_+, Δ_-) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\pi m_+ + (1 - \pi)m_- - \tau_0)}{d(\pi^2 w_+ + 2\pi(1 - \pi)\rho_b \sqrt{w_+ w_-} + (1 - \pi)^2 w_-)} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi dw_+} + \tau_+ \right).$$

- Only in case the optimal decision thresholds are modelled via (Δ_+, Δ_-) , they are affected by the prior correlation ρ_b , and for a higher correlation, c_+^* is closer to τ_+ .



General remarks on optimal decision rules (5)

a) Assuming a normal prior for (Δ_0, Δ_+) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(m_0 - \tau_0)}{dw_0} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi dw_+} + \tau_+ \right),$$

b) assuming a normal prior for (Δ_+, Δ_-) , the threshold pair is

$$(c_0^*, c_+^*) = \left(-\frac{4(\pi m_+ + (1 - \pi)m_- - \tau_0)}{d(\pi^2 w_+ + 2\pi(1 - \pi)\rho_b \sqrt{w_+ w_-} + (1 - \pi)^2 w_-)} + \tau_0, -\frac{4(m_+ - \tau_+)}{\pi dw_+} + \tau_+ \right).$$

➤ The larger the subgroup prevalence π , the closer c_+^* is to τ_+ .



Clinical trial example

- Histone deacetylase inhibitors (HDACis) have been shown to overcome resistance to epidermal growth factor receptor tyrosine kinase inhibitors (EGFR-TKIs) linked to epigenetic changes.
- In a randomized phase II trial (n=132) study, the overall survival of erlotinib with and without the isoform selective HDACi, **entinostat**, was evaluated for NSCLC-patients who progressed on a prior chemotherapy. (Witta et al., 2012)



Clinical trial example (2)

- Entinostat showed promising results in both the total patient population as well as in several subgroups (Witta et al. 2012):

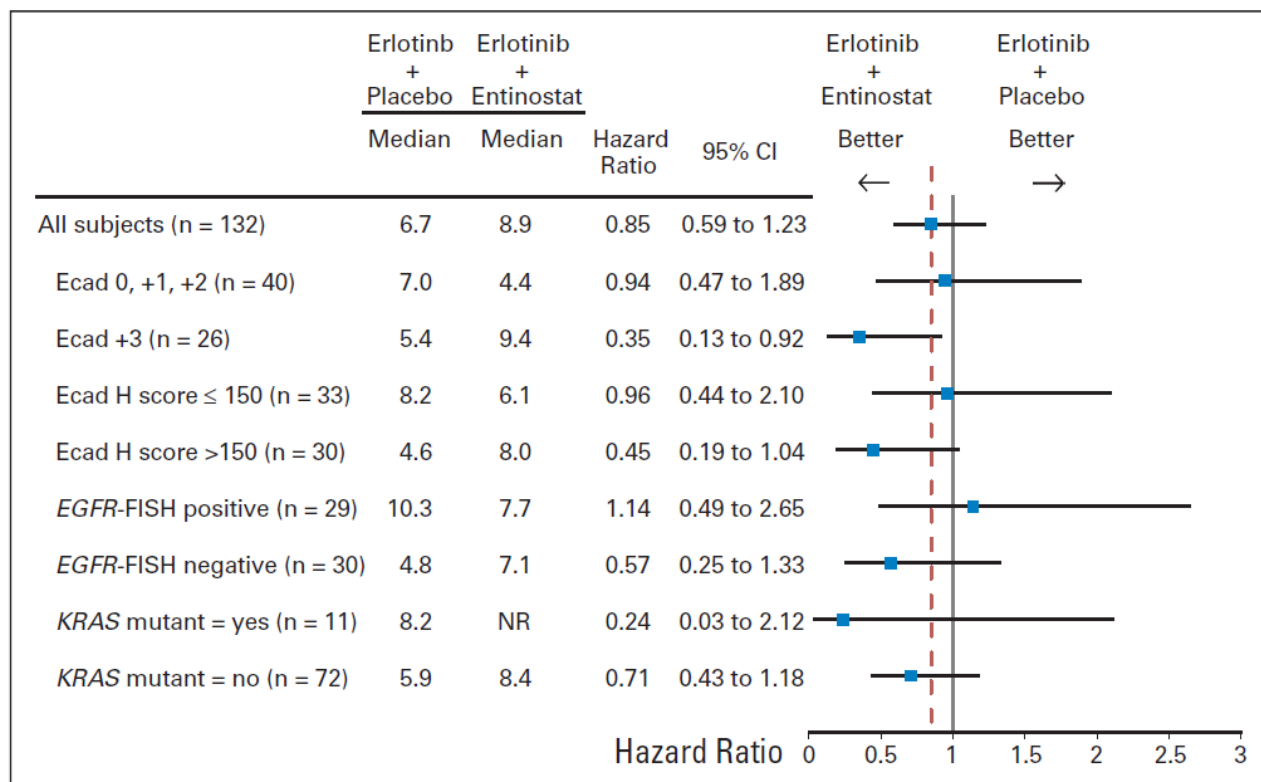


Fig 3. Forest plot of median overall survival and associated hazard ratios by biomarker status. Ecad, E-cadherin; EGFR, epidermal growth factor receptor; FISH, fluorescent in situ hybridization; KRAS, Kirsten rat sarcoma viral oncogene homolog.

Witta SE et al. (2012). Randomized phase II trial of erlotinib with and without entinostat in patients with advanced non–small-cell lung cancer who progressed on prior chemotherapy. *Journal of Clinical Oncology*, **30**(18), 2248-2255.



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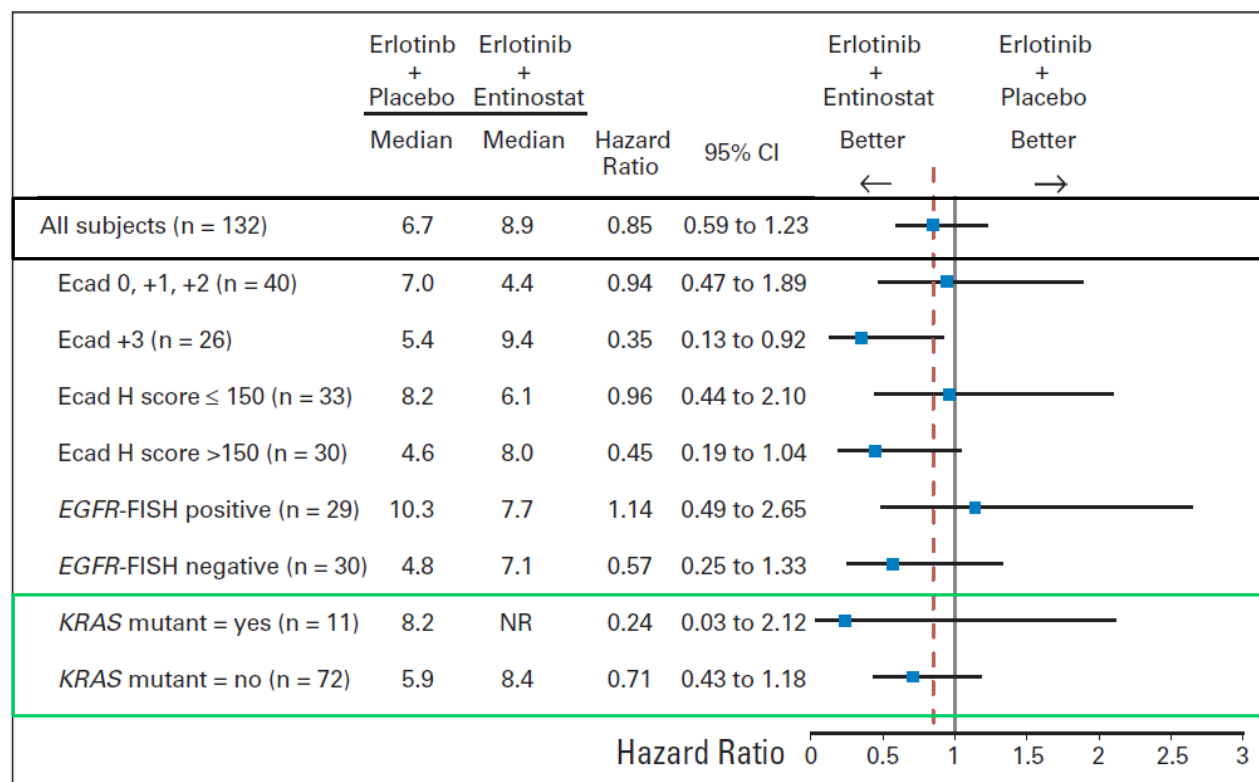


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Clinical trial example: Determination of prior distributions

- Considering the fact that Entinostat showed both a highly increased benefit in the subgroup of KRAS mutant as compared to KRAS wildtype, the proof of efficacy of entinostat within an **adaptive enrichment design** with G_+ being **KRAS mutant** might be pursued.
- Prior distributions can be obtained from the study by Witta et al. 2012 via choosing
 - m_i as the negative logarithm of the reported hazard ratios.
 - w_i as the squared standard error of the estimated log hazard ratios (can be computed from the reported confidence intervals).
- Since the correlation ρ_b can only be meaningfully estimated by several studies at hand, it is set here to 0.



Clinical trial example:

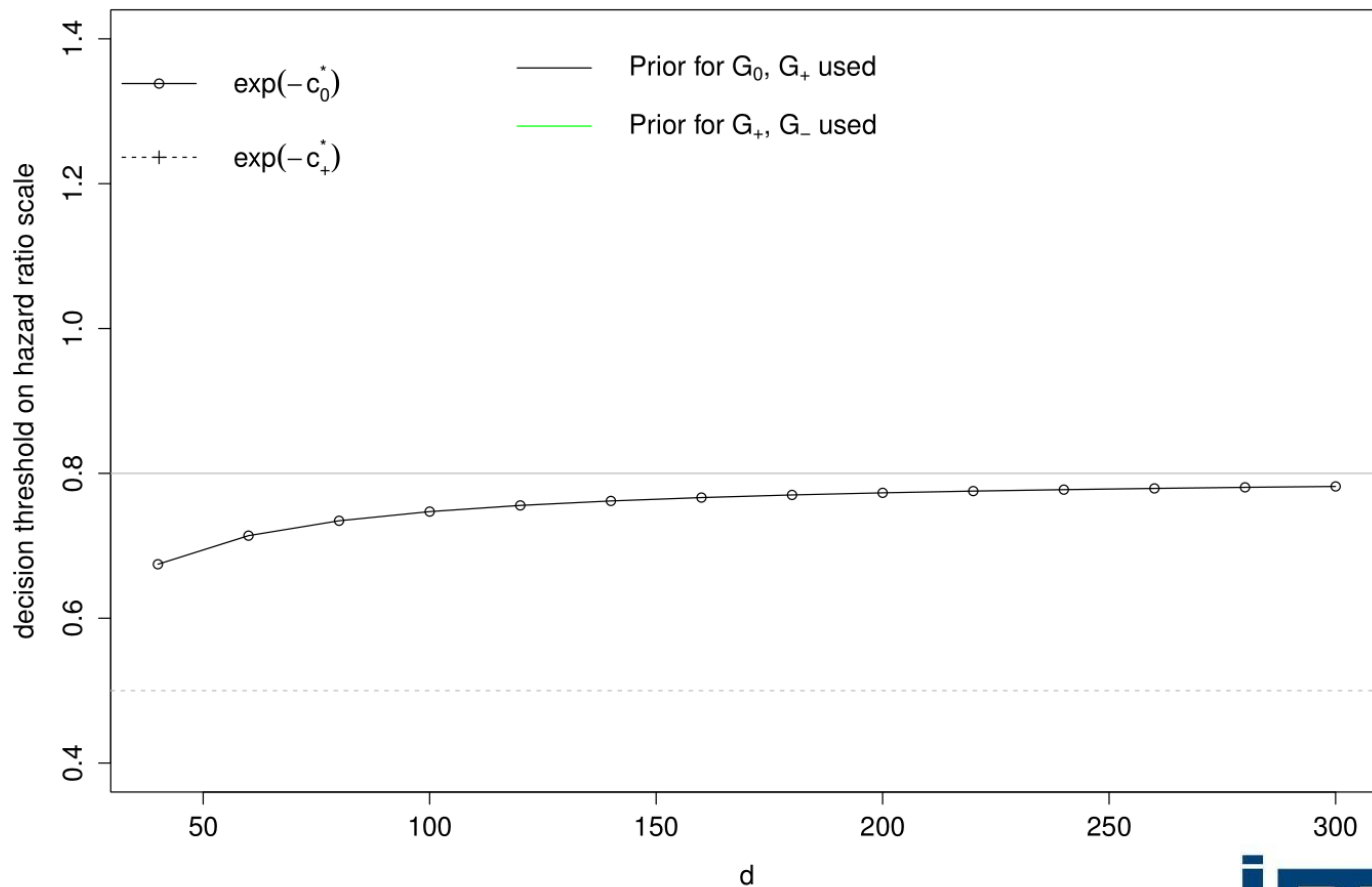
Determination of prior distributions (2)

- This yields the following parameters for the respective priors
 - $m_+ = -\log(0.24) = 1.43, w_+ = 1.24$
 - $m_- = -\log(0.71) = 0.34, w_- = 0.067$
 - $\pi = 0.157$ according to a meta-analysis (Mao et al. 2010, n=1470)
- In case one chooses a prior for G_0 instead of G_- ,
 $m_0 = -\log(0.85) = 0.16, w_0 = 0.04$.
- Relevance thresholds are set to $\tau_0 = -\log(0.8), \tau_+ = -\log(0.5)$.



Clinical trial example: optimal decision rules

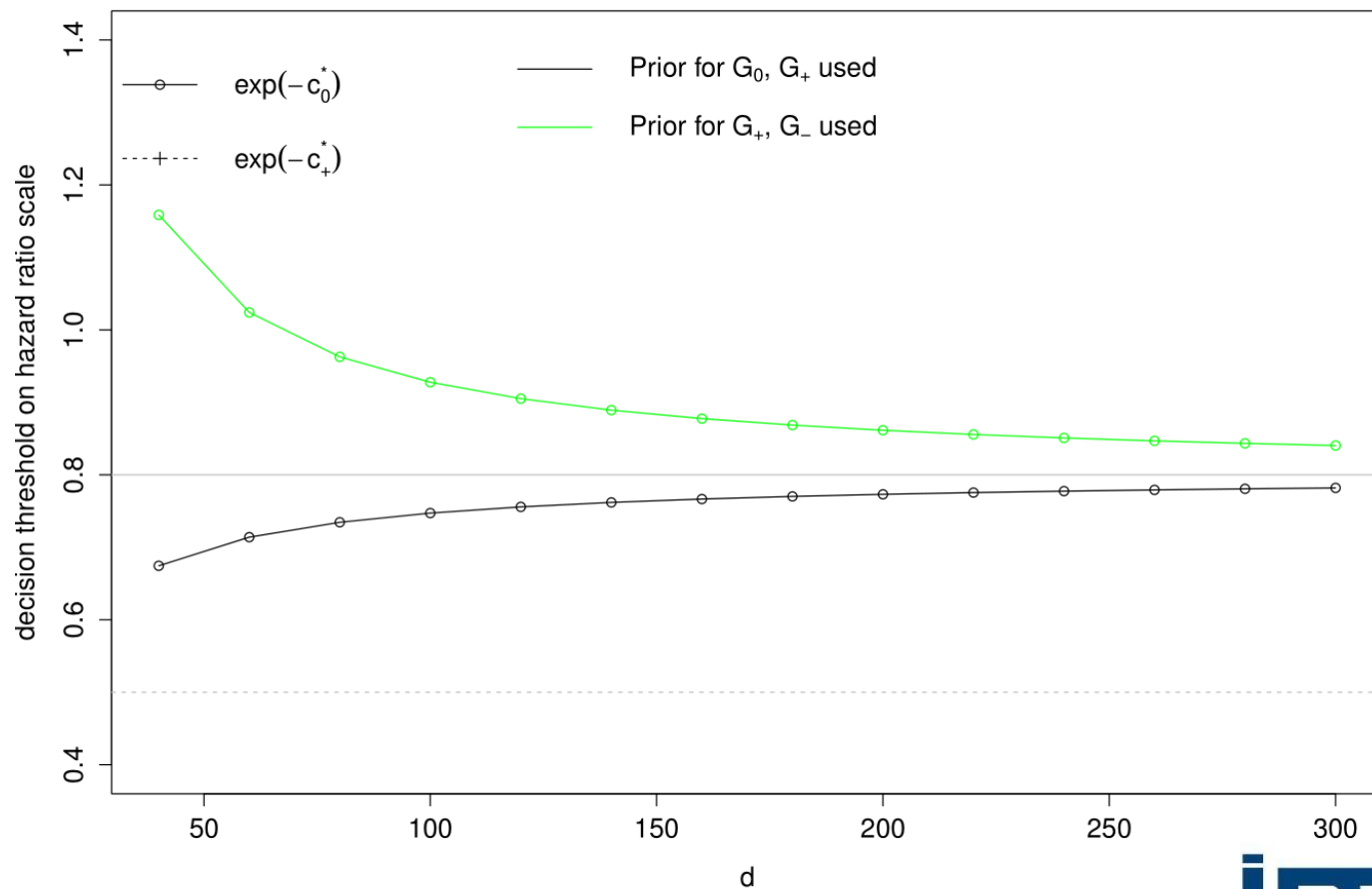
- optimal decision thresholds on the hazard ratio scale in dependence of number of events d





Clinical trial example: optimal decision rules

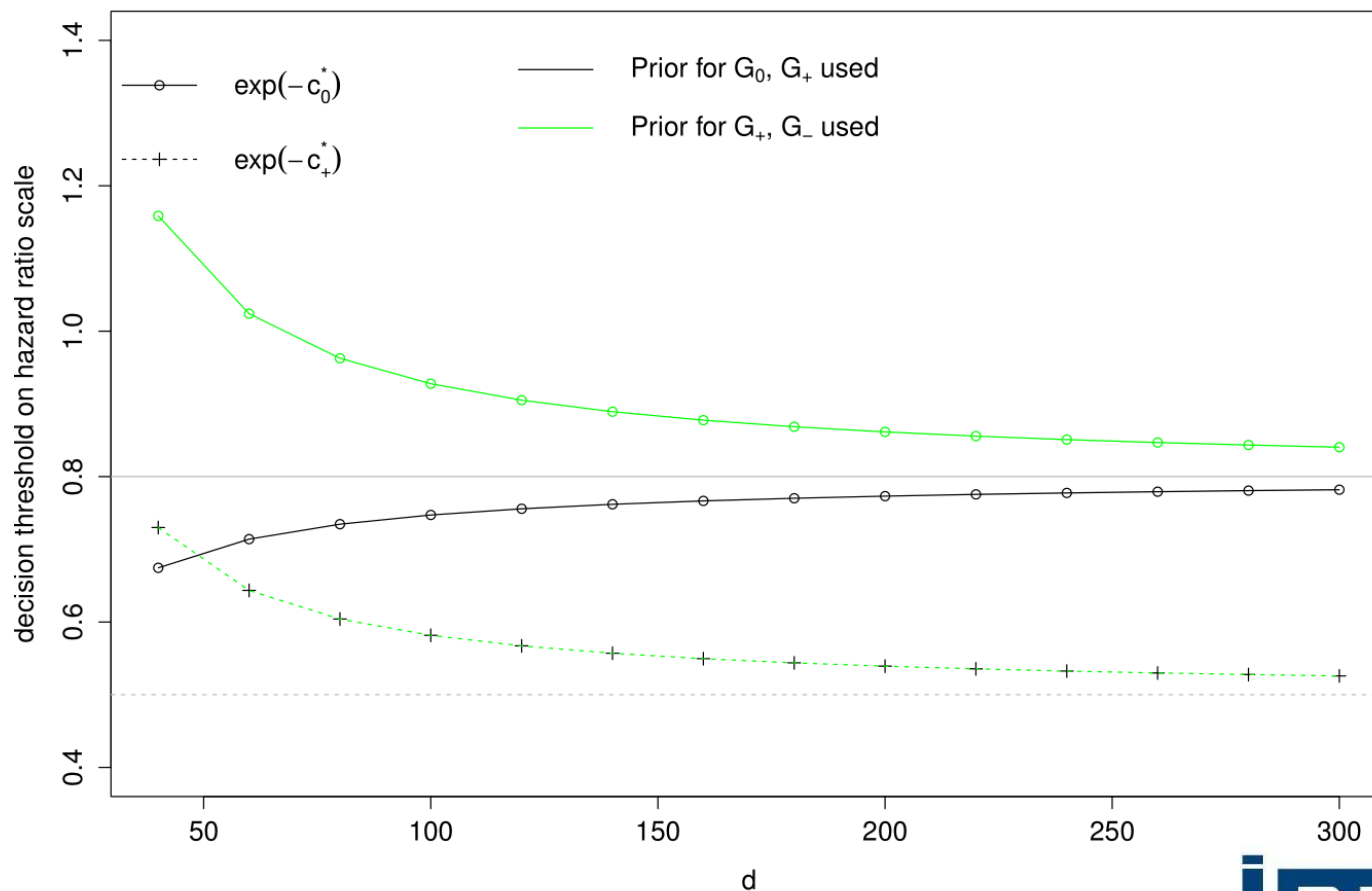
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Clinical trial example: optimal decision rules

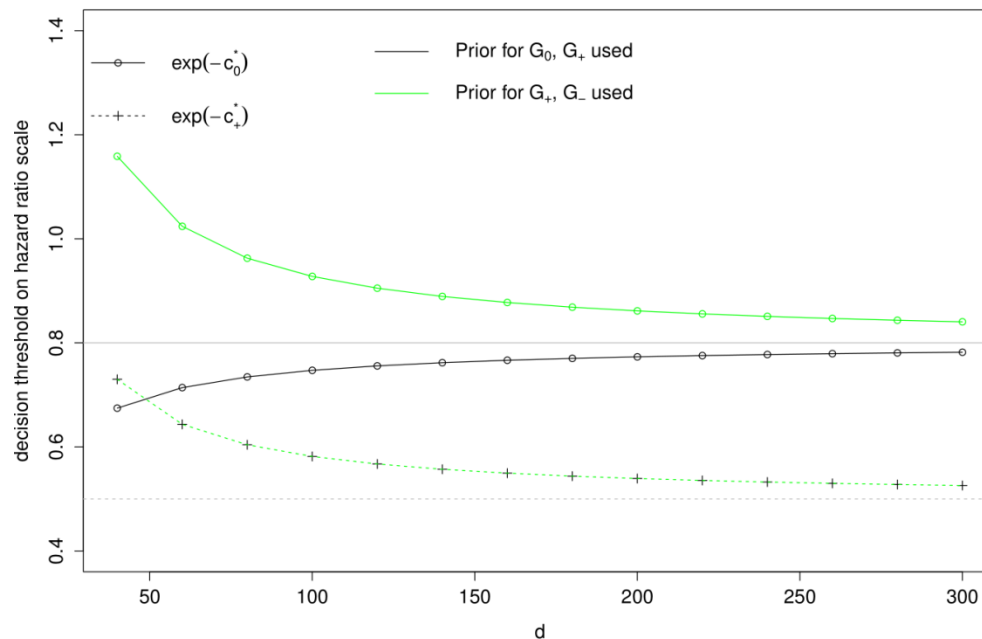
- optimal decision thresholds on the hazard ratio scale in dependence of number of events d





Clinical trial example: remarks on optimal decision rules

- Relatively generous decision thresholds c_+^*
- If prior for G_0 is used, $\exp(-c_0^*)$ is smaller than 0.8, in contrast to the scenarios where a prior for G_- is applied
- The larger the number of events, the closer the optimal decision thresholds c_0^*, c_+^* are to the relevance thresholds τ_0, τ_+





Assumptions for simulation study

- Assume that it is planned to investigate the efficacy of entinostat within an adaptive enrichment design with
 - subgroup selection at interim based on $d = 200$ observed events
 - subgroup prevalence from the meta-analysis holds true
- This would result in the following optimal decision thresholds:
 - a) Based on a prior for G_+, G_- : $\exp(-c_0^*) = 0.862, \exp(-c_+^*) = 0.539$
 - b) Based on a prior for G_+, G_0 : $\exp(-c_0^*) = 0.773, \exp(-c_+^*) = 0.539$



Assumptions for simulation study (2)

- Furthermore assume exponentially distributed survival times and the following median survival times in months:

$$M_{T+} = 12, M_{C+} = 8, M_{T-} = 8, M_{C-} = 6$$

$$\Rightarrow \Delta_0 \approx -\log(0.74), \Delta_+ \approx -\log(0.67),$$

- Now, 3 different types of decision thresholds can be considered for each scenario:
 - (a) *ad hoc* decision thresholds $(\tau_0, \tau_+) = (-\log(0.8), -\log(0.5))$
 - (b) optimal decision thresholds with c_0^* based on a prior for G_+, G_-
 - (c) optimal decision thresholds with c_0^* based on a prior for G_0
- Selection probabilities were evaluated using 1,000,000 simulated studies per scenario



Selection probabilities

decision thresholds on HR scale probability	(a) (0.8, 0.5)	(b) (0.862, 0.539)	(c) (0.773, 0.539)
select G_0 and G_+	0.1969		
select G_0 only	0.5169		
select G_+ only	0.0311		
stop for futility	0.2551		



Selection probabilities

decision thresholds on HR scale probability	(a) (0.8, 0.5)	(b) (0.862, 0.539)	(c) (0.773, 0.539)
select G_0 and G_+	0.1969	0.2743	
select G_0 only	0.5169	0.5876	
select G_+ only	0.0311	0.0164	
stop for futility	0.2551	0.1217	



Selection probabilities

decision thresholds on HR scale probability	(a) (0.8, 0.5)	(b) (0.862, 0.539)	(c) (0.773, 0.539)
select G_0 and G_+	0.1969	0.2743	0.2282
select G_0 only	0.5169	0.5876	0.3982
select G_+ only	0.0311	0.0164	0.0624
stop for futility	0.2551	0.1217	0.3112

- Rule (b) shows the overall best performance as compared to rules (a) and (c)
- Relatively high probability for a futility stop for both rules (a) and (c)
- Due to the relatively strict threshold for G_0 , rule (c) performs worst.



Conclusion

- Optimal decision rules incorporate various aspects of the design of a clinical trial with subgroup selection.
- These rules can either be modelled via prior knowledge in the two subgroups, or in the total population and subgroup of interest
- If there is prior knowledge on treatment effects, optimal decision rules may lead to an increased probability for a correct selection of the target population, which in turn positively influences the power of the trial (Krisam & Kieser 2015)



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