

ESC195 W23 Notes

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29 Partial Derivatives

- Continuity:

$$\lim_{\vec{x} \rightarrow \vec{x}_0} f(\vec{x}) = f(\vec{x}_0).$$

Theorem: The continuity of composite functions are defined as, for any function $g(\vec{x}_0)$, if it is continuous at \vec{x}_0 and function f is continuous at the NUMBER $g(\vec{x}_0)$ then we can say $f(g(\vec{x}))$ is continuous at \vec{x}_0

- if $f(\vec{x})$ is continuous at \vec{x}_0 , then:

$$\begin{aligned}\lim_{x \rightarrow x_0} f(x, y_0) &= f(x_0, y_0) \\ \lim_{y \rightarrow y_0} f(x_0, y) &= f(x_0, y_0).\end{aligned}$$

- If we have the top half of a sphere with radius 5, we have:

$$f = \sqrt{25 - x^2 - y^2}.$$

Suppose we are interested in what is happening when we are moving along the line $y = 2$:

Definition: Partial derivative of $f(x, y)$ is given by:

$$f_x(x, y) = \frac{\partial}{\partial x} f(x, y) = \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h} \quad (1)$$

or the partial derivative with respect to y :

$$f_y(x, y) = \frac{\partial}{\partial y} f(x, y) = \lim_{h \rightarrow 0} \frac{f(x, y+h) - f(x, y)}{h} \quad (2)$$

This can be extended to an arbitrary number of dimensions.

Example 1: Suppose we have a function $f(x, y) = e^{x^2 y^3}$:

$$\begin{aligned}f_x &= y^3 \cdot 2xe^{x^2 y^3} \\ f_y &= 3y^2 x^2 e^{x^2 y^3} \\ &\cdot\end{aligned}$$

At $y = 2$, we have:

$$\begin{aligned}f_x(x, 2) &= 16xe^{8x^2} \\ f_x(1, 2) &= 16e^8 \\ &\cdot\end{aligned}$$

This is equivalent if we take a cross section of this equation on the $y = 2$ plane, and look at the derivative or the slope of tangent at that point.

Example 2: Now we have a 3-D function, $f(x, y, z) = \ln\left(\frac{x}{y}\right) - ye^{xz}$. The partial derivatives are:

$$\begin{aligned}f_x &= \frac{1}{x} - ye^{xz} \\ f_y &= -\frac{1}{y} - e^{xz} \\ f_z &= -xye^{xz} \\ &\cdot\end{aligned}$$

Example 3: Suppose we have $h(r, \theta, \phi) = r^2 \sin \theta \cos \phi$:

$$h_r = 2r \sin \theta \cos \phi$$

$$h_\theta = r^2 \cos \theta \cos \phi$$

$$h_\phi = -r^2 \sin \theta \sin \phi$$

.

- We can also have Mixed Partial:

$$\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) \rightarrow \frac{\partial^2 f}{\partial x^2} = f_{xx}$$

$$\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) \rightarrow \frac{\partial^2 f}{\partial y^2} = f_{yy}$$

$$\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial x \partial y} = f_{xy}$$

Theorem: Clairaut's Theorem says that:

$$\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial^2 f}{\partial x \partial y} \quad (3)$$

on every open set on which f and its partials $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial^2 f}{\partial x \partial y}, \frac{\partial^2 f}{\partial y \partial x}$ are continuous, so we have:

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

$$\frac{\partial^2 f}{\partial z \partial y} = \frac{\partial^2 f}{\partial y \partial z}$$

$$\frac{\partial^2 f}{\partial x \partial z} = \frac{\partial^2 f}{\partial z \partial x}$$

.

Example 4: We have $f(x, y) = \cos(xy^2)$

$$f_x = -y^2 \sin(xy^2)$$

$$f_y = -\sin(xy^2) \cdot 2xy$$

$$\frac{\partial^2 f}{\partial y \partial x} = -2y \sin(xy^2) - y^2 \cos(xy^2) \cdot 2xy$$

$$\frac{\partial^2 f}{\partial x \partial y} = -2y \sin(xy^2) - 2xy \cos(xy^2) \cdot y^2 = \frac{\partial^2 f}{\partial y \partial x}$$

.

- partial derivatives can be used to describe differential equations with multiple variables:

Example 5: Laplace's equation:

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 0 \quad (4)$$

One-dimensional wave equation:

$$\frac{\partial^2 f}{\partial t^2} = a^2 \frac{\partial^2 f}{\partial x^2} \quad (5)$$

Here a represents the speed of the wave.

$\infty \in \mathbb{R}$

30 Directional Derivatives and Gradient Functions

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- A partial derivative:

Definition: A partial derivative of f on x , denoted as $f_x = \frac{\partial f}{\partial x}$ is defined as:

$$\lim_{h \rightarrow 0} \frac{f(x+h, y, z) - f(x, y, z)}{h} \quad (6)$$

only if $\lim_{h \rightarrow 0} \frac{g(h)}{h} = 0 \implies g(h) = o(h)$

Example 6: For a function $f(x) = x^2$, $f(x+h) - f(x) = (x+h)^2 - x^2 = 2xh + h^2$ Note here that

$$\lim_{h \rightarrow 0} \frac{h^2}{h} = \lim_{h \rightarrow 0} h = 0 \quad (7)$$

since the function of h , $g(h)$ satisfies the previous definition, we say that h^2 is an $o(h)$, which further shows that $f'(x) = 2x$

Idea: With this, we can write out the derivative definition using just the numerator part of the derivative

$$f(x+h) - f(x) \quad (8)$$

And the result of this expression will leave us with two types of equations.

$$\text{derivative} \cdot h \quad (9)$$

or

$$\text{something} \cdot o(h) \quad (10)$$

anything that is multiplied by $o(h)$ will be reduced to zero due to the definition of $o(h)$, which is why the first expression gives us the derivative.

This is especially useful when we are trying to find the derivative of a multivariable function.

- differentiability of a multivariable function

Definition: we say f is differentiable at \vec{x} iff there exists \vec{y} s.t.

$$f(\vec{x} + \vec{h}) - f(\vec{x}) = \vec{y} \cdot \vec{h} + o(\vec{h}) \vec{y} = Df(\vec{x}) = \text{the gradient of } f.$$

Example 7: Here we have the function $f(x, y) = x + y^2$ and the h function $\vec{h} = (h_1, h_2)$

$$\begin{aligned} f(\vec{x} + \vec{h}) - f(\vec{x}) &= f(x + h_1, y + h_2) - f(x, y) \\ &= x + h_1 + (y + h_2)^2 - x - y^2 \\ &= h_1 + 2yh_2 + h_2^2 \\ &= (1\hat{i} + 2y\hat{j}) \cdot \vec{h} + h_2^2 \end{aligned}$$

After this, we need to demonstrate that the remaining part of the function, that is h_2^2 , is actually a $o(\vec{h})$ function.

To do that, we define $g(\vec{h}) = h^2 = (h_2\hat{j}) \cdot (h_1\hat{i} + h_2\hat{j}) = h_2\hat{j} \cdot \vec{h}$. So we can write $g(\vec{h}) = h_2\vec{j} \cdot \vec{h}$

$$\frac{|g(\vec{h})|}{\|\vec{h}\|} = \frac{|x||h_2||\vec{h}||\cos\theta|}{\|\vec{h}\|} \leq |xh_2|$$

$$\lim_{h \rightarrow 0} |xh_2| = 0 \implies xh_2h_3 = o(\vec{h})$$

$$\therefore \nabla f(\vec{x}) = yz\hat{i} + xz\hat{j} + xy\hat{k}.$$

We know that $h_2 \rightarrow 0$ as $\vec{h} \rightarrow \vec{0}$. So $g(\vec{h})$ is $o(\vec{h})$ and we can claim that:

$$\nabla f(\vec{x}) = 1\hat{i} + y\hat{j} \quad (11)$$

Example 8: For this example we have $f(x, y, z) = xyz$

$$\begin{aligned} f(\vec{x} + \vec{h}) - f(\vec{x}) &= (x + h_1)(y + h_2)(z + h_3) - xyz \\ &= xyz + xyh_3 + xh_2z + xh_2h_3 + h_1yz + h_1yh_3 + h_1h_2z + h_1h_2h_3 - xyz \\ &= (yz\hat{i} + xz\hat{j} + xy\hat{k}) \cdot \vec{h}. \end{aligned}$$

We consider the case of $xh_2h_3 = g(\vec{h}) = xh_2\hat{k} \cdot \vec{h}$

$$\frac{g(\vec{h})}{\|\vec{h}\|} = \frac{|x||h_2||\vec{h}||\cos\theta|}{\|\vec{h}\|} \leq |xh_2|$$

$$\lim_{h \rightarrow 0} |xh_2| = 0 \implies xh_2h_3 \text{ is } o(\vec{h})$$

$$\therefore \nabla f(\vec{x}) = yz\hat{i} + xz\hat{j} + xy\hat{k}.$$

$$\nabla f(x, y, z) = (f_x, f_y, f_z) \quad (12)$$

Theorem: For cartesian coordinates:

$$\nabla f(x, y, z) = \frac{\partial f}{\partial x}\hat{i} + \frac{\partial f}{\partial y}\hat{j} + \frac{\partial f}{\partial z}\hat{k} \quad (13)$$

Or equally written as:

$$\nabla f(x, y, z) = (f_x, f_y, f_z) \quad (14)$$

- Gradients are the vectors that points steepest way "up the hill"
- \vec{x} is vector
- $f(\vec{x})$ is not vector
- $\nabla f(\vec{x})$ is a vector

Example 9: Suppose we have a temperature function with respect to x and y , and we have $\frac{\partial T}{\partial x} = 3\frac{^\circ C}{m}$ and $\frac{\partial T}{\partial y} = 4\frac{^\circ C}{m}$. From this, we can conclude that:

$$\nabla T = 3\hat{i} + 4\hat{j} \quad (15)$$

And that:

$$|\nabla T| = \sqrt{3^2 + 4^2} = 5 \quad (16)$$

Example 10: For this example we have $f(\vec{x}) = xy^2z^3$, and we can compute their partial derivatives:

$$\begin{aligned} f_x &= y^2z^3 \\ f_y &= 2xyz^3 \\ f_z &= 3xy^2z^2 \end{aligned}$$

And we have

$$\nabla f = (y^2z^3, 2xyz^3, 3xy^2z^2) \quad (17)$$

Example 11: We have function $\vec{r}(x, y, z) \Rightarrow r = \sqrt{x^2 + y^2 + z^2}$ So we then have

$$\begin{aligned} \nabla r &= \nabla \sqrt{x^2 + y^2 + z^2} \\ &= \frac{\frac{1}{2}2x}{\sqrt{x^2 + y^2 + z^2}}\hat{i} + \frac{\frac{1}{2}2y}{\sqrt{x^2 + y^2 + z^2}}\hat{j} + \frac{\frac{1}{2}2z}{\sqrt{x^2 + y^2 + z^2}}\hat{k} \end{aligned}$$

rewriting this gives us:

$$\nabla r = \frac{\vec{r}}{r} \quad (18)$$

- For any directional derivative, we can define it being:

$$\frac{\partial f}{\partial x} = \lim_{h \rightarrow 0} \frac{f(\vec{x}_0 + h\hat{i}) - f(\vec{x}_0)}{h}.$$

Expanding this to any arbitrary direction is:

Definition: Directional derivative of function f at \vec{x}_0 in direction \hat{u}

$$f_{\hat{u}}(\vec{x}_0) = \lim_{h \rightarrow 0} \frac{f(\vec{x}_0 + h\hat{u}) - f(\vec{x}_0)}{h} \quad (19)$$

We also have

$$f_{\hat{u}}(\vec{x}_0) = \nabla f(\vec{x}_0) \cdot \hat{u} \quad (20)$$

Proof. Proving that $f_{\hat{u}}(\vec{x}_0) = \nabla f(\vec{x}_0) \cdot \hat{u}$:

$$f(\vec{x} + \vec{h}) - f(\vec{x}) = \nabla f(\vec{x}) \cdot \vec{h} + o(\vec{h}) \quad (21)$$

Where $\vec{h} = h\hat{u}$. Using this, we can show the above is equal to:

$$\nabla f(\vec{x}) \cdot h\hat{u} + o(\vec{h}) \quad (22)$$

and therefore:

$$\frac{f(\vec{x} + h\hat{u}) - f(\vec{x})}{h} = \nabla f \cdot \hat{u} + \frac{o(\vec{h})}{h} \quad (23)$$

and taking the limit as $h \rightarrow 0$, we have the desired result. \square

Example 12: Using the same temperature example, we have $T(x, y)$ where $\frac{\partial T}{\partial y} = 4\frac{^\circ\text{C}}{m}$ and $\frac{\partial T}{\partial x} = 3\frac{^\circ\text{C}}{m}$. If we want to move in a direction of $\hat{u} = \cos\theta\hat{i} + \sin\theta\hat{j}$

$$T_{\hat{u}} = \left(\frac{\partial T}{\partial x}\hat{i} + \frac{\partial T}{\partial y}\hat{j} \right) (\cos\theta\hat{i} + \sin\theta\hat{j}) = 3\cos\theta + 4\sin\theta \quad (24)$$

Example 13: Suppose we have a parabolic hill described by $z(x, y) = 20 - x^2 - y^2$ and we move straight up, or we can say that $\hat{u} = (0, 1)$.

$$\begin{aligned}\frac{\partial f}{\partial x} &= -2x \\ \frac{\partial f}{\partial y} &= -2y\end{aligned}$$

$$\therefore z_{\hat{u}} = (-2x, -2y) \cdot (0, -1) = 2y \quad (25)$$

(The following is not on that lecture, but from Xue Qilin's notes)

- Note that:

$$\begin{aligned}|f_{\hat{k}}(\vec{x})| &= |\nabla f \cdot \hat{u}| \\ &= \|\nabla f\| \|\hat{u}\| |\cos \theta| \\ &\leq \|\nabla f\|.\end{aligned}$$

Example 14: Suppose that $z = f(x, y) = A + x + 2y + x^2 - 2y^2$ and we wish to find the steepest path down starting from $(0, 0, A)$. We know that:

$$\begin{aligned}\frac{\partial f}{\partial x} &= 1 - 2x \\ \frac{\partial f}{\partial y} &= 2 - 6y\end{aligned}$$

such that:

$$\nabla f = (1 - 2x)\hat{i} + (2 - 6y)\hat{j} \implies -\nabla f = (2x - 1)\hat{i} + (6y - 2)\hat{j}.$$

The curve is given by:

$$\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}.$$

Where $x'(t) = 2x(t) - 1$ and $y'(t) = 6y(t) - 2$. This is in parametric form and we can convert to cartesian form by writing the derivatives as:

$$\frac{dy}{dx} = \frac{6y - 2}{2x - 1} \quad (26)$$

and solving this differential equation to get:

$$3y = (2x - 1)^3 + 1 \quad (27)$$