3.10 **Time Response of ODEs**

For the given system $G(s) = \frac{4s-6}{s^2+2s-3}$:

- What are the poles, zeros, and DC gain?
- What is the general form of the free response?
- What is the general form of the forced response?

If any poles are complex then express the free/forced response in its "real" form.

Solution:

Poles: $s_1 = -3, s_2 = 1$

Zeros: $s = \frac{6}{4}$

DC Gain: $\vec{G}(0) = \frac{-6}{-3}$ **Free response:** $y(t) = C_1 e^{-3t} + C_2 e^t$ Forced response: $y_p(t)$ depends on u(t)

GPT Answer:

Given the system $G(s) = \frac{4s-6}{s^2+2s-3}$:

- The zeros are at $s = \frac{3}{2}$.
- The poles are at s = -3 and s = 1.
- The DC gain is 2.

The general form of the free response involves exponential terms due to the real poles, represented as a combination of e^{-3t} and e^t . The general form of the forced response depends on the input, shaped by the system's impulse response.

Confidence Level: 95%

Correct

Claude Answer:

To analyze the given system $G(s)=\frac{4s-6}{s^2+2s-3}$, let's find the poles, zeros, DC gain, and the general forms of the free and forced responses.

1. Poles, zeros, and DC gain:

Poles: To find the poles, set the denominator equal to zero and solve for s.

$$s^2 + 2s - 3 = 0 \implies (s+3)(s-1) = 0$$

The poles are at s = -3 and s = 1.

Zeros: To find the zeros, set the numerator equal to zero and solve for s.

$$4s - 6 = 0 \implies s = \frac{6}{4} = 1.5$$

The zero is at s = 1.5.

DC gain: To find the DC gain, evaluate G(s) at s = 0.

$$G(0) = \frac{4(0) - 6}{0^2 + 2(0) - 3} = \frac{-6}{-3} = 2$$

The DC gain is 2.

2. General form of the free response:

The free response is given by:

$$y_f(t) = c_1 e^{-3t} + c_2 e^t$$

where c_1 and c_2 are constants determined by the initial conditions.

3. General form of the forced response:

The forced response depends on the input function u(t). For a general input U(s), the forced response in the s-domain is:

$$Y_F(s) = G(s)U(s) = \frac{4s - 6}{s^2 + 2s - 3}U(s)$$

To find the forced response in the time domain, you would need to perform an inverse Laplace transform on $Y_F(s)$. The specific form of the forced response will depend on the input function u(t).

Since there are no complex poles in this system, the free and forced responses are already in their "real" forms.

Confidence Level: 95%

Correct