# 10.4 Lyapunov Stability

Determine sufficient conditions for the stability of the origin of the nonlinear discrete-time system described by

$$x_1(k+1) = x_1(k) - f[x_1(k)]$$

### **Solution:**

Let  $V[x(k)] = [x_1(k)]^2$ , which is greater than 0 for all  $x \neq 0$ . Then,

$$\Delta V = x_1^2(k+1) - x_1^2(k) = (x_1(k) - f[x_1(k)])^2 - x_1^2(k)$$
(285)

$$= x_1(k)f[x_1(k)] \left(\frac{f[x_1(k)]}{x_1} - 2\right)$$
 (286)

Therefore sufficient conditions for  $\Delta V \leq 0$  and thus stability of the system are

$$x_1 f(x_1) \ge 0$$

and

$$\frac{f(x_1)}{x_1} \le 2 \quad \text{for all} \quad x_1$$

#### **GPT Answer:**

To determine sufficient conditions for the stability of the origin of the given nonlinear discrete-time system

$$x_1(k+1) = x_1(k) - f[x_1(k)]$$

we apply the concept of Lyapunov stability for discrete-time systems. A system is said to be stable at the origin if, for every  $\epsilon > 0$ , there exists a  $\delta > 0$  such that if  $||x_1(0)|| < \delta$ , then  $||x_1(k)|| < \epsilon$  for all  $k \ge 0$ .

One common approach to establish stability is to find a Lyapunov function  $V(x_1)$  that satisfies the following conditions: 1. V(0) = 0, 2.  $V(x_1) > 0$  for all  $x_1 \neq 0$ , and 3.  $\Delta V(x_1) = V[x_1(k+1)] - V[x_1(k)] < 0$  for all  $x_1 \neq 0$ .

A sufficient condition for stability can be derived by ensuring that the function  $f[x_1(k)]$  satisfies certain properties which would guarantee that the change in the Lyapunov function  $\Delta V(x_1)$  is negative for all  $x_1 \neq 0$ . Specifically, for the system given, a potential Lyapunov function could be  $V(x_1) = x_1^2$ , which is positive for all  $x_1 \neq 0$  and zero at the origin.

The change in V due to the system dynamics is:

$$\Delta V(x_1) = V[x_1(k+1)] - V[x_1(k)] = [x_1(k) - f[x_1(k)]]^2 - x_1(k)^2$$

For  $\Delta V(x_1) < 0$ , the function  $f[x_1(k)]$  must be such that:

$$[x_1(k) - f[x_1(k)]]^2 < x_1(k)^2$$

This implies that  $f[x_1(k)]$  should not be zero for  $x_1(k) \neq 0$  and must have the same sign as  $x_1(k)$  to ensure that the magnitude of  $x_1(k) - f[x_1(k)]$  is less than the magnitude of  $x_1(k)$ , thereby reducing the value of the Lyapunov function over time.

Thus, a sufficient condition for the stability of the origin is that  $f[x_1(k)]$  is a continuous function that satisfies f(0) = 0 and  $x_1(k) \cdot f[x_1(k)] > 0$  for all  $x_1(k) \neq 0$ . This ensures that the system's state moves closer to the origin over time, leading to stability.

## **Confidence Level: 90%**

#### Correct

## **Claude Answer:**

To determine the stability of the origin for the given nonlinear discrete-time system, we can use Lyapunov's second method (also known as the direct method of Lyapunov). The system is described by:

$$x_1(k+1) = x_1(k) - f[x_1(k)]$$

Let's assume that the function  $f(x_1)$  satisfies the following conditions:

- 1. f(0) = 0, which means the origin is an equilibrium point of the system.
- 2.  $f(x_1)$  is continuous in a neighborhood of the origin.
- 3.  $x_1 f(x_1) > 0$  for all  $x_1 \neq 0$  in a neighborhood of the origin.

Now, consider a Lyapunov function candidate:

$$V(x_1) = \frac{1}{2}x_1^2$$

This function is positive definite, radially unbounded, and continuous.

The forward difference of  $V(x_1)$  along the system trajectories is:

$$\Delta V(x_1) = V(x_1(k+1)) - V(x_1(k))$$

$$= \frac{1}{2} [x_1(k) - f(x_1(k))]^2 - \frac{1}{2} x_1(k)^2$$

$$= -x_1(k) f(x_1(k)) + \frac{1}{2} f^2(x_1(k))$$

If we add the condition:

4.  $|f(x_1)| < |x_1|$  for all  $x_1 \neq 0$  in a neighborhood of the origin.

Then, we have:

$$\Delta V(x_1) < -x_1(k)f(x_1(k)) + \frac{1}{2}x_1^2(k) = -\frac{1}{2}x_1^2(k) < 0$$

for all  $x_1 \neq 0$  in a neighborhood of the origin.

Therefore, if conditions 1-4 are satisfied, the origin of the nonlinear discrete-time system is asymptotically stable in the sense of Lyapunov.

In summary, the sufficient conditions for the stability of the origin are:

1. f(0) = 0 2.  $f(x_1)$  is continuous in a neighborhood of the origin 3.  $x_1 f(x_1) > 0$  for all  $x_1 \neq 0$  in a neighborhood of the origin 4.  $|f(x_1)| < |x_1|$  for all  $x_1 \neq 0$  in a neighborhood of the origin **Confidence level: 95%** 

**Correct**