

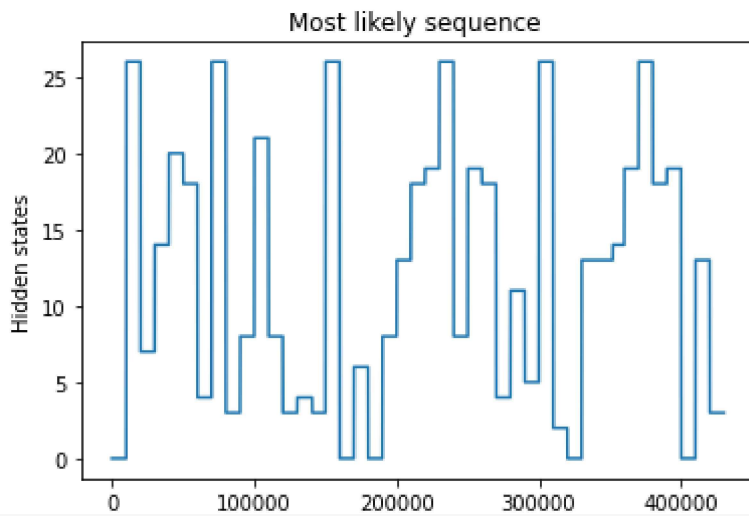
▼ Viterbi Algorithm

```
1 !unzip /content/hw7files.zip
```

```
1 import numpy as np
2 N = 27
3 transition = np.loadtxt("/content/hw7files/transitionMatrix.txt" , dtype = "float")
4 observation = np.loadtxt("/content/hw7files/observations.txt" , dtype = "int").reshape(-1,
5 ISD = np.loadtxt("/content/hw7files/initialStateDistribution.txt" , dtype = "float").resha
6 eM = np.loadtxt("/content/hw7files/emissionMatrix.txt" , dtype = "float")
7 T = len(observation)
8 L_list = np.zeros((27,T))
9
10 for i in range(27):
11     tmp1 = np.log(ISD[i])
12     tmp2 = np.log(eM[i][observation[0]])
13     L_list[i][0] = tmp1 + tmp2
14
15 final = np.zeros((27,T))
16 for i in range(27):
17     L_list[i][0] = np.log(ISD[i]) + np.log(eM[i][observation[0]])
18
19 for t in range(1,T):
20     for j in range(27):
21         final[j][t] = np.argmax(L_list[:,t-1] + np.log(transition[:,j]))
22         L_list[j][t] = np.amax(L_list[:,t-1] + np.log(transition[:,j])) + np.log(eM[j,observat
23
24
25
```

```
1 Viterbi = []
2 for i in (range(T-1,-1,-1)):
3     if i != T-1:
4         Viterbi.append(final[int(Viterbi[-1])][i+1])
5     else:
6         Viterbi.append(np.argmax(L_list[:,T-1]))
7
8 Viterbi = Viterbi[::-1]
9
10 import matplotlib.pyplot as plt
11 plt.plot(Viterbi)
12 plt.title('Most likely sequence ')
13 plt.xlabel('time')
14 plt.ylabel('Hidden states')
```

```
Text(0, 0.5, 'Hidden states')
```



```
1 foo = 'abcdefghijklmnopqrstuvwxy '
2 dick = dict(enumerate(foo))
```

```
1 verify = ""
2 count = 0
3 for t in range(T-1):
4     if Viterbi[t] == Viterbi[t+1]:
5         count += 1
6     else:
7         count = 0
8     if count > 8000:
9         verify += (dick.get(Viterbi[t]))
10    count = 0
11 print(verify)
```

a house divided against itself cannot stand

Hw 7 Andre

7.1 - Python

7.2.

$\theta_{t+2} -$

$$= \frac{\alpha_{it}}{P(S_t)} \cdot P(S_t)$$

$$= \frac{\alpha_{it}}{P(S_t)} \times \frac{P(S_t)}{P(S_t)}$$

$$b) P(S_t = i | S_t)$$

$$= \frac{P(S_t = i, S_t)}{P(S_t = i)}$$

$$P(S_{t+1} = j)$$

(1) is same

$$0): P(S_t)$$


$$0, - 0_{t-1}$$

$$\pi S_t, S_{t+1}, a_t - 0_i = P(S_t, S_{t+1})$$

$$\text{given } S_{t-1}.$$

$$\text{dis sep.}$$

$$= P(S_t, S_{t+1})$$


$$\Rightarrow (c) = \underline{a_i, b_i}$$



7.4

$$a) q_k = P(st = ')$$

$$P(st = ')$$

t) We can rep

$$P(x_t | y_1, \dots)$$

$$= \int dx_{t-1} P$$

$$= \frac{p(y+1)(x+1)}{2x}$$

*

The reason
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