

I. Lorentzian geometry

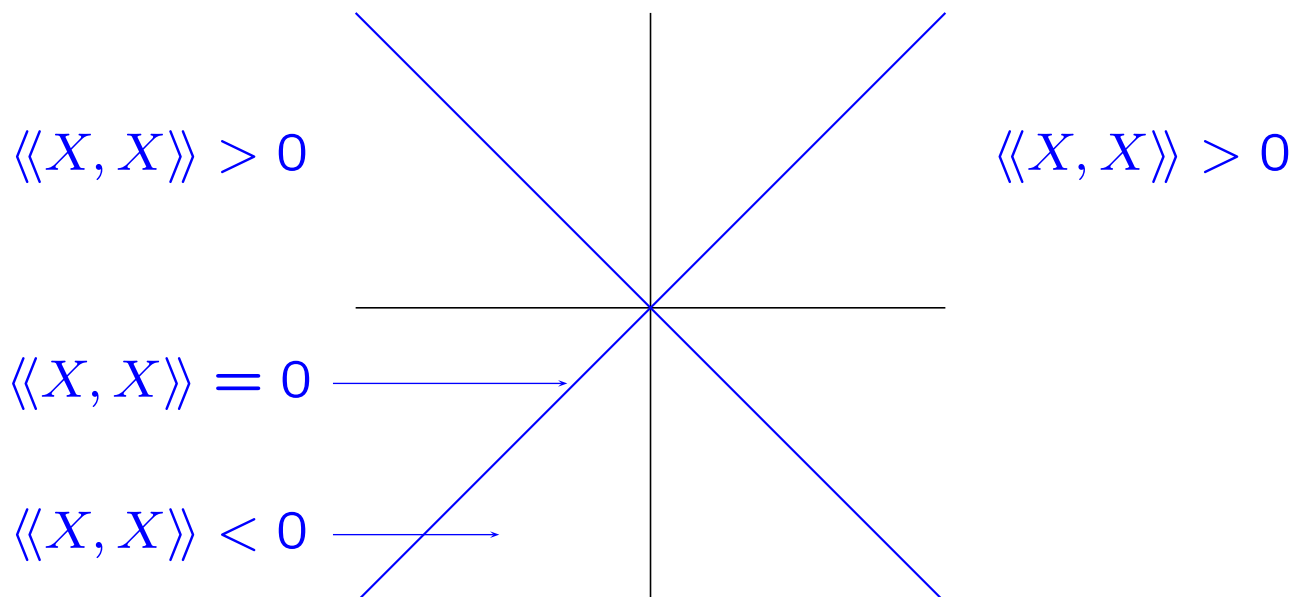
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Lorentzian manifold (M, g) : the metric g_x on $T_x M$ is of signature $(- + + \dots +)$ for every $x \in M$, i.e.: \exists basis $(e_0, e_1, \dots, e_{n-1})$ of $T_x M$ s.t.

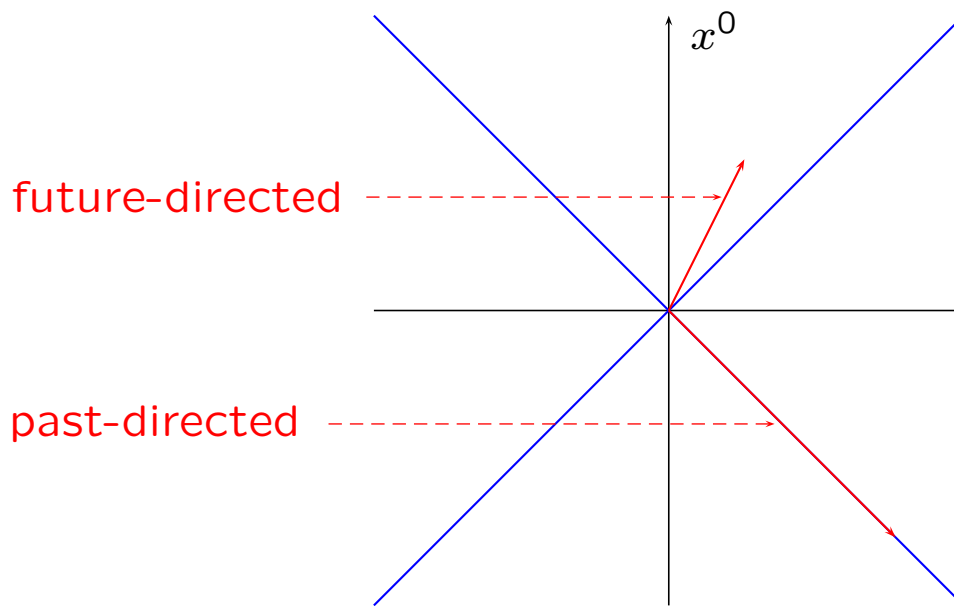
$$g_x = -e_0^* \otimes e_0^* + \sum_{j=1}^{n-1} e_j^* \otimes e_j^*.$$

1. Causality relation

- In Minkowski space $(V, \langle\langle \cdot, \cdot \rangle\rangle)$: a vector X is
 - **spacelike** iff $\langle\langle X, X \rangle\rangle > 0$,
 - **lightlike** iff $\langle\langle X, X \rangle\rangle = 0$,
 - **timelike** iff $\langle\langle X, X \rangle\rangle < 0$,
 - **causal** iff $\langle\langle X, X \rangle\rangle \leq 0$.



Choice of a **time-orientation** = choice of one of both connected components of $\{\langle X, X \rangle < 0\}$.



- On a Lorentzian manifold:
 - spacelike (resp. timelike,...) tangent vectors, submanifolds (e.g. curves)
 - time-orientation is given by a (C^∞) timelike vector field on M (does not always exist)

*From now on all Lorentzian manifolds will be
(connected and) time-oriented
(“spacetimes”)*

- Causality relation: $x, y \in M$,

$x \leq y :\Leftrightarrow \exists$ future-directed causal curve from x to y
(resp. $x < y :\Leftrightarrow \exists \dots$ timelike \dots)

- Futures/Pasts: $x \in M$

- causal future (resp. past) of x in M :

$$J_+^M(x) := \{y \in M, x \leq y\}$$

(resp. $J_-^M(x) := \{y \in M, y \leq x\}$)

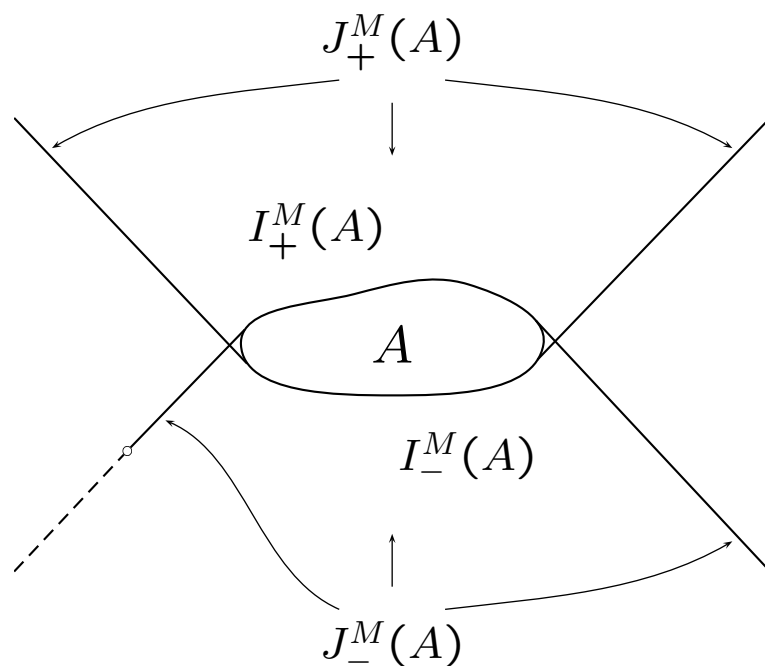
- chronological future (resp. past) of x in M :

$$I_+^M(x) := \{y \in M, x < y\}$$

(resp. $I_-^M(x) := \{y \in M, y < x\}$)

- future (past) of a subset A of M :

$$J_{\pm}^M(A) := \bigcup_{x \in A} J_{\pm}^M(x)$$



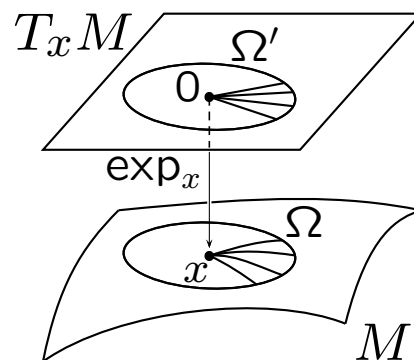
- Topological properties:

- $I_{\pm}^M(A)$ is open $\subset J_{\pm}^M(A)$ which is **not always** closed.

But: A compact and “ \leq ” closed $\Rightarrow J_{\pm}^M(A)$ closed

2. Convex subsets

- $\Omega \subset M$ is **geodesically starshaped** w.r.t. $x \in \Omega$: $\iff \exists \Omega' \subset T_x M$ starshaped w.r.t. 0 s.t. $\exp_x : \Omega' \longrightarrow \Omega$ is a diffeomorphism.



- $\Omega \subset M$ is **convex** : $\iff \Omega$ is geodesically starshaped w.r.t. all of its points.
- Convexity and causality: let $\Omega \subset M$ be geodesically starshaped w.r.t. $x \in \Omega$:

- $\exp_x(J_{\pm}^{\Omega'}(0)) = J_{\pm}^{\Omega}(x)$
- $dV_g = \mu_x \cdot (\exp_x^{-1})^* d\text{vol}_{g_x}$ ($\mu_x = \sqrt{|\det(g_{ij})|}$ in normal coordinates about x)

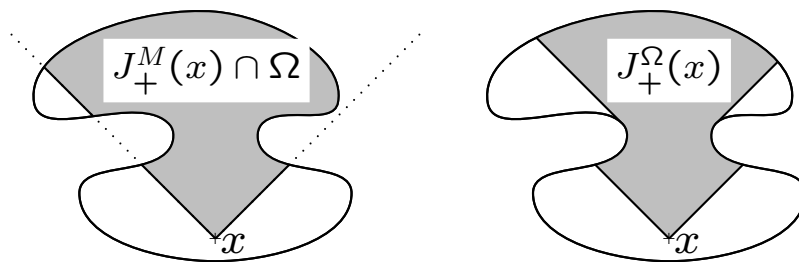
3. Subsets and causality

- $\Omega \subset M$ is **causally compatible** iff

$$J_{\pm}^{\Omega}(x) = J_{\pm}^M(x) \cap \Omega$$

for every $x \in \Omega$.

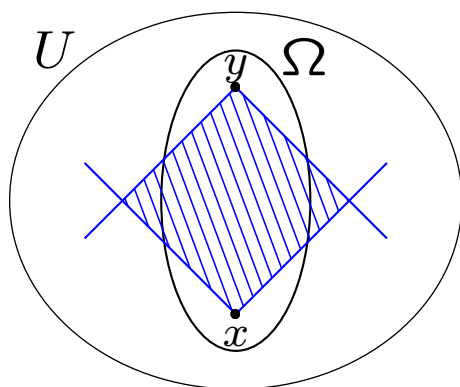
- ex.: $\Omega \subset M$ convex
- c-ex.:



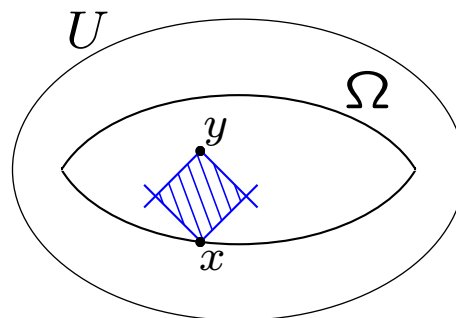
Ω is *not* causally compatible in M

- $\Omega \subset M$ is **causal** iff $\exists U \subset M$ convex with
 - $\overline{\Omega} \subset U$
 - $J_+^U(x) \cap J_-^U(y)$ is compact and contained in $\overline{\Omega}$ for all $x, y \in \overline{\Omega}$.

ex. and c-ex.:

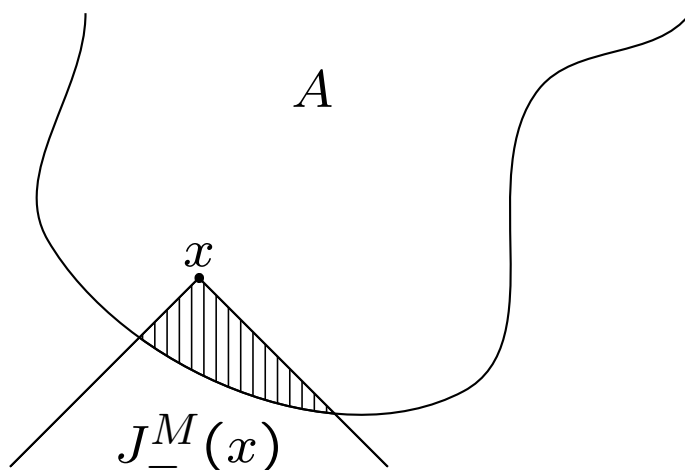


convex, but not
causal



causal

- $A \subset M$ is **past-compact** iff $J_-^M(x) \cap A$ is compact for every $x \in M$.



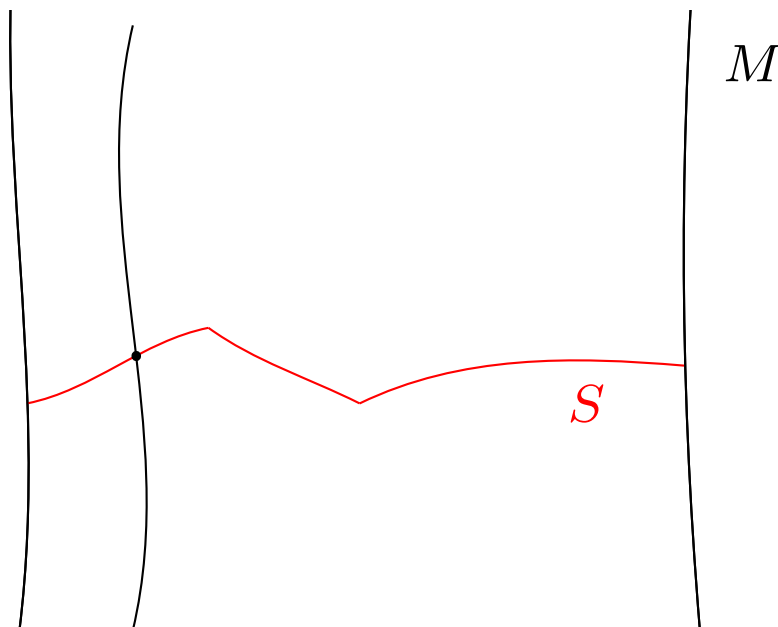
Lemma: A past-compact $\Rightarrow \overline{A \cap J_-^M(K)}$ compact for every $K \subset M$ compact

4. Cauchy hypersurfaces and globally hyperbolic manifolds

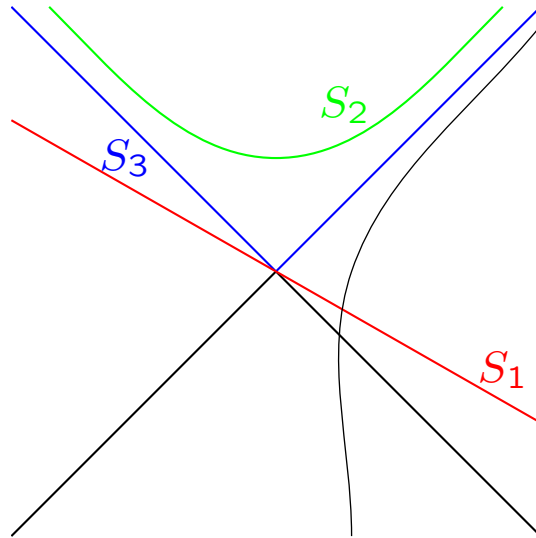
- $S \subset M$ is **achronal** (resp. **acausal**) iff every inextendible timelike (resp. causal) curve hits S *at most once*.

Note: S acausal \Rightarrow S achronal (“ \Leftarrow ” true if e.g. S is a *spacelike hypersurface*)

- $S \subset M$ is a **Cauchy-hypersurface** iff every inextendible timelike curve hits S *exactly once*.



- Ex. and c-ex. in Minkowski space:



- Properties of Cauchy-hypersurfaces: let S be a Cauchy-hypersurface of M , then:
 - S is an achronal **topological** hypersurface of M and is hit by any inextendible causal curve,
 - any further Cauchy-hypersurface is homeomorphic to S ,
 - for every $K \subset M$ compact, $J_{\pm}^M(S) \cap J_{\mp}^M(K)$ is compact.

- M is **globally hyperbolic** iff
 - $J_+^M(x) \cap J_-^M(y)$ is compact for all $x, y \in M$,
 - there is no almost closed causal curve in M :
 $\forall x \in M$ and \forall neighbourhood V of x , \exists neighbourhood $U \subset V$ of x s.t. every *causal* curve starting *and* ending in U lies in V .



- Equivalently: M is globally hyperbolic iff one of the following holds:
 - M admits a Cauchy-hypersurface,
 - $(M, g) \stackrel{\text{isom.}}{\simeq} (\mathbb{R} \times S, -\beta dt^2 + g_t)$ where β is a smooth positive function, g_t is a Riemannian metric on S depending smoothly on $t \in \mathbb{R}$ and each $\{t\} \times S$ is a **smooth space-like** Cauchy hypersurface in M ,
 - there exists a time-function on M .

- Important property: on any globally hyperbolic manifold M the causality relation \leq is closed (in particular $J_+^M(K) \cap J_-^M(K')$ is compact for all $K, K' \subset M$ compact).

- Examples:

- the Minkowski space is globally hyperbolic,
- every causal domain is globally hyperbolic,
- the *anti-deSitter space* is *not* globally hyperbolic.

5. Normally hyperbolic operators

Let E be a complex vector bundle over M .

- A **normally hyperbolic** operator is a second-order differential operator P on E of which symbol is given by minus the metric.

In local coordinates:

$$P = - \sum_{i,j=1}^n g^{ij}(x) \frac{\partial^2}{\partial x^i \partial x^j} + \sum_{j=1}^n A_j(x) \frac{\partial}{\partial x^j} + B_1(x)$$

where A_j and B_1 are matrix-valued coefficients depending smoothly on x .

- Example: the **d'Alembert operator** is defined on smooth functions by

$$\square f := -\text{tr}(\text{Hess}(f)),$$

where $\text{Hess}(f)(X, Y) := \langle \nabla_X \text{grad} f, Y \rangle$.

In normal coordinates:

$$\square f = -\mu_x^{-1} \sum_{i=1}^n \frac{\partial}{\partial x^i} (\mu_x (\text{grad} f)_i)$$

- *Lemma*: for every normally hyperbolic operator P on E there exists a unique connection ∇ (called the *P -compatible* one) on E and a unique endomorphism field B of E such that

$$P = \square^\nabla + B,$$

where

$$\begin{aligned} \square^\nabla &:= -\text{tr}(\nabla^2) \\ &= - \sum_{i,j=1}^n g^{ij} \left(\nabla_{\frac{\partial}{\partial x^i}} \nabla_{\frac{\partial}{\partial x^j}} - \nabla_{\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j}} \right). \end{aligned}$$

- Aim in the following: solve, for some given $f \in C^\infty(M, E)$,

$$Pu = f$$

with “adapted” initial conditions.