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Introduction to Raspberry Pi – Part I

Dr. Sudip Misra

Associate Professor

Department of Computer Science and Engineering

IIT KHARAGPUR

Email: smisra@sit.iitkgp.ernet.in

Website: <http://cse.iitkgp.ac.in/~smisra/>

What is Raspberry Pi?

- Computer in your palm.
- Single-board computer.
- Low cost.
- Easy to access.



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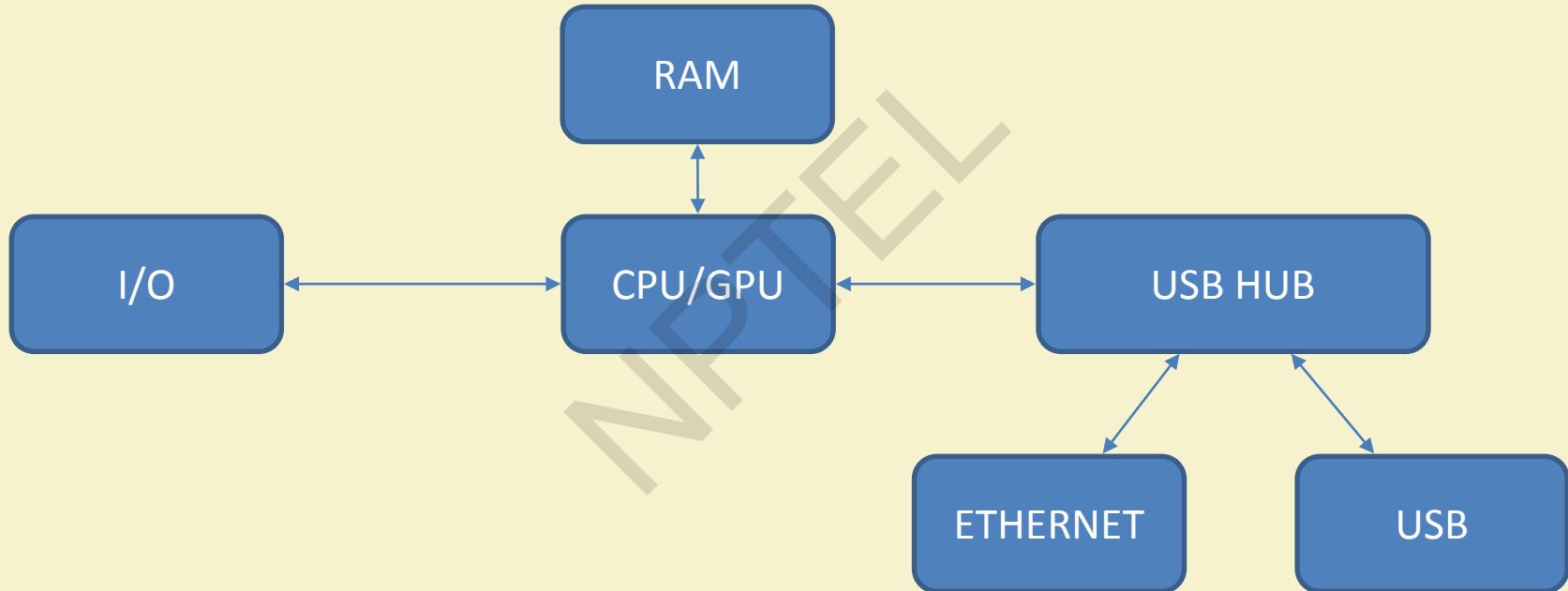
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Specifications

Key features	Raspberry pi 3 model B	Raspberry pi 2 model B	Raspberry Pi zero
RAM	1GB SDRAM	1GB SDRAM	512 MB SDRAM
CPU	Quad cortex A53@1.2GHz	Quad cortex A53@900MHz	ARM 11@ 1GHz
GPU	400 MHz video core IV	250 MHz video core IV	250 MHz video core IV
Ethernet	10/100	10/100	None
Wireless	802.11/Bluetooth 4.0	None	None
Video output	HDMI/Composite	HDMI/Composite	HDMI/Composite
GPIO	40	40	40

Basic Architecture



Raspberry Pi



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Start up raspberry pi



Raspberry Pi GPIO

- Act as both digital output and digital input.
- **Output:** turn a GPIO pin high or low.
- **Input:** detect a GPIO pin high or low.

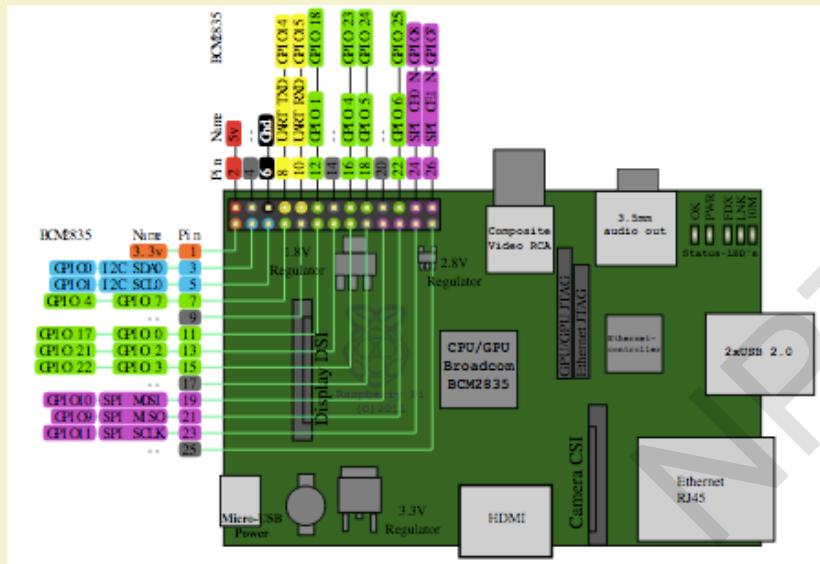


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Raspberry Pi pin configuration



Source: Raspberry Pi PCB Pin Overview, Wikimedia Commons (Online)

Source: [Raspberry Pi GPIO](#), Wikimedia Commons (Online)



Basic Set up for Raspberry Pi

- HDMI cable.
- Monitor.
- Key board.
- Mouse.
- 5volt power adapter for raspberry pi.
- LAN cable .
- Min- 2GB micro sd card



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Basic Set up for Raspberry Pi



Operating System

Official Supported OS :

- Raspbian
- NOOBS

Some of the third party OS :

- UBUNTU mate
- Snappy Ubuntu core
- Windows 10 core
- Pinet
- Risc OS

Source: [Downloads](#), Raspberry Pi Foundation

Raspberry Pi Setup

Download Raspbian:

- Download latest Raspbian image from raspberry pi official site:
<https://www.raspberrypi.org/downloads/>
- Unzip the file and end up with an .img file.



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Raspberry Pi OS Setup

Write Raspbian in SD card :

- Install “Win32 Disk Imager” software in windows machine .
- Run Win32 Disk Imager
- Plug SD card into your PC
- Select the “Device”
- Browse the “Image File”(Raspbian image)
- Write



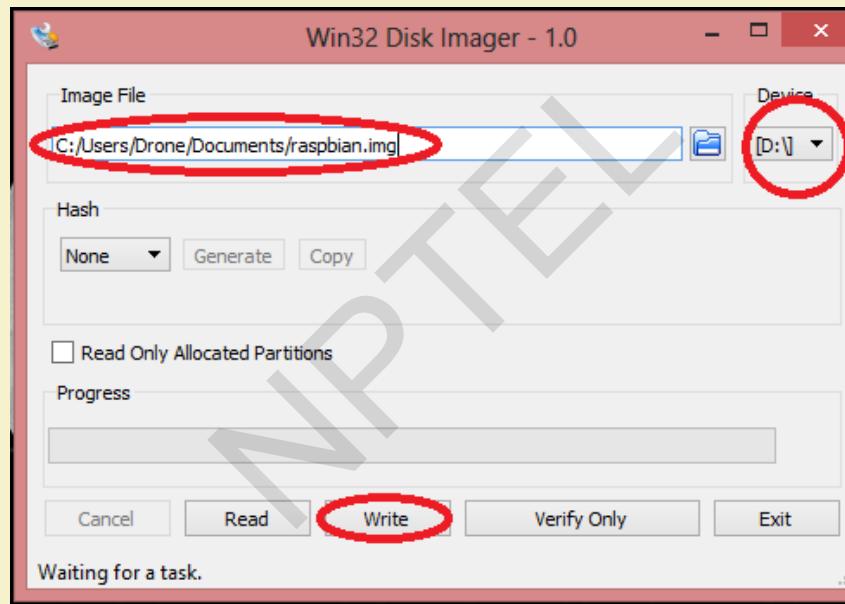
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Raspberry Pi OS Setup



Basic Initial Configuration

Enable SSH

Step1 : Open command prompt and type **sudo raspi-config** and press enter.

Step2: Navigate to SSH in the Advance option.

Step3: Enable SSH



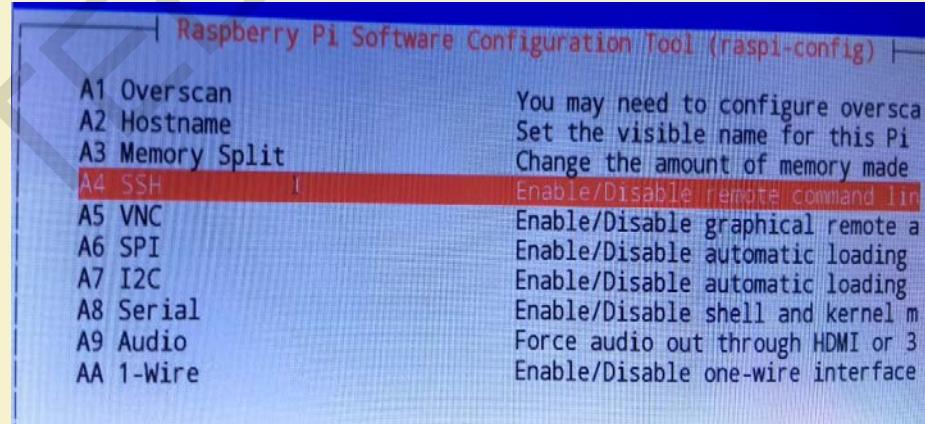
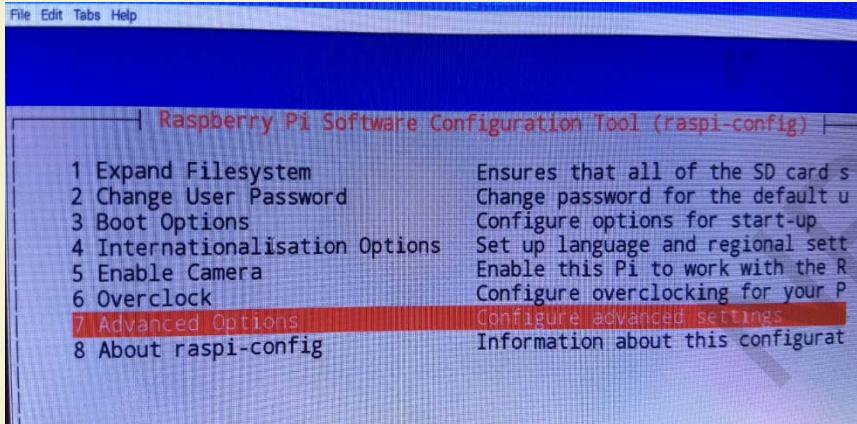
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Basic Initial Configuration



Basic Initial Configuration contd.

Expand file system :

Step 1: Open command prompt and type **sudo raspi-config** and press enter.

Step 2: Navigate to Expand Filesystem

Step 3: Press enter to expand it.

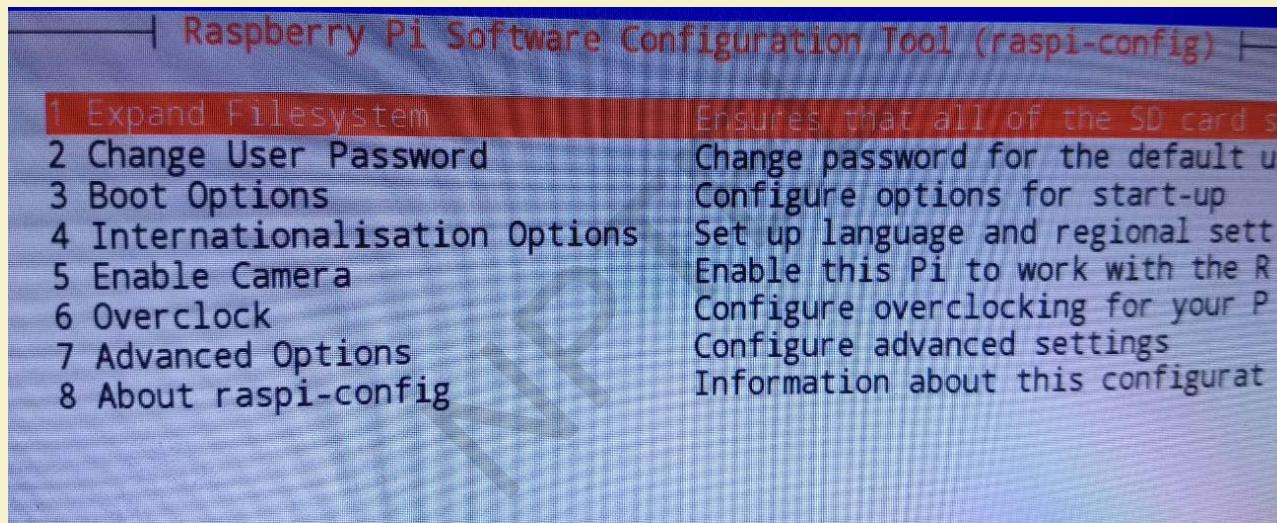


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Basic Initial Configuration contd.



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Programming

Default installed :

- Python
- C
- C++
- Java
- Scratch
- Ruby

Note : Any language that will compile for ARMv6 can be used with raspberry pi.

Source: [Programming languages for Raspberry Pi](#), eProseed, Lonneke Dikmans, August 07, 2015

Popular Applications

- Media streamer
- Home automation
- Controlling BOT
- VPN
- Light weight web server for IOT
- Tablet computer

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Introduction to Raspberry Pi – Part II

Dr. Sudip Misra

Associate Professor

Department of Computer Science and Engineering
IIT KHARAGPUR

Email: smisra@sit.iitkgp.ernet.in

Website: <http://cse.iitkgp.ac.in/~smisra/>

Topics Covered

- Using GPIO pins
- Taking pictures using PiCam

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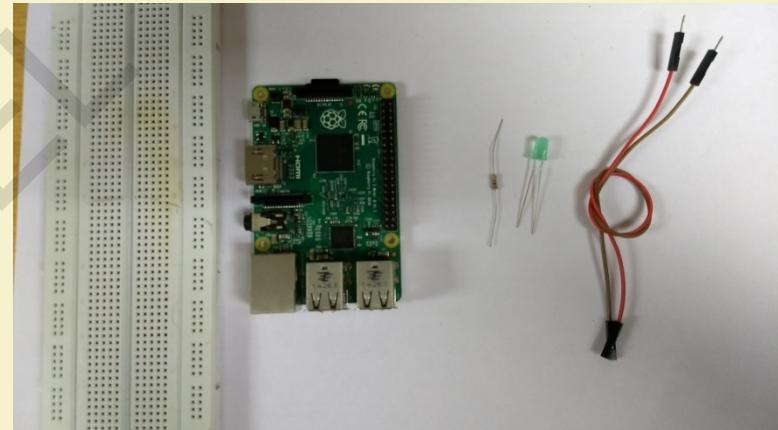


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Blinking LED

- Requirement:
- Raspberry pi
- LED
- 100 ohm resistor
- Bread board
- Jumper cables



Blinking LED (contd..)

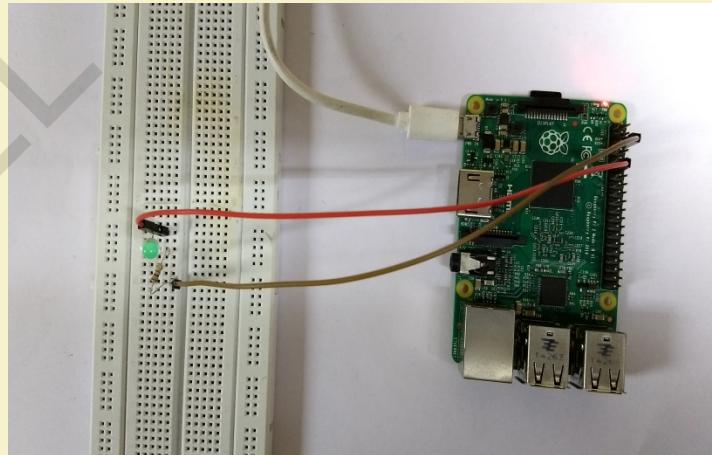
Installing GPIO library:

- Open terminal
- Enter the command “sudo apt-get install python-dev” to install python development
- Enter the command “sudo apt-get install python-rpi.gpio” to install GPIO library.

Blinking LED (contd..)

Connection:

- Connect the negative terminal of the LED to the ground pin of Pi
- Connect the positive terminal of the LED to the output pin of Pi



Blinking LED (contd..)

Basic python coding:

- Open terminal enter the command
`sudo nano filename.py`
- This will open the nano editor where you can write your code
- Ctrl+O : Writes the code to the file
- Ctrl+X : Exits the editor

Blinking LED (contd..)

Code:

```
import RPi.GPIO as GPIO      #GPIO library
import time
GPIO.setmode(GPIO.BOARD)    # Set the type of board for pin numbering
GPIO.setup(11, GPIO.OUT)     # Set GPIO pin 11as output pin
for i in range (0,5):
    GPIO.output(11,True)    # Turn on GPIO pin 11
    time.sleep(1)
    GPIO.output(11,False)
    time.sleep(2)
    GPIO.output(11,True)
GPIO.cleanup()
```

Blinking LED (contd..)

GNU nano 2.2.6

File: BLINK_LED.py

```
import RPi.GPIO as GPIO ## GPIO library
import time
GPIO.setmode(GPIO.BCM) ## Set the type of board for pin numbering
GPIO.setup(11, GPIO.OUT) ## Set GPIO pin 11 as output pin
for i in range (0,5):
    GPIO.output(11,True) ## Turn on GPIO pin 11
    time.sleep(1)
    GPIO.output(11,False)
    time.sleep(2)
    GPIO.output(11,True)
GPIO.cleanup()
```



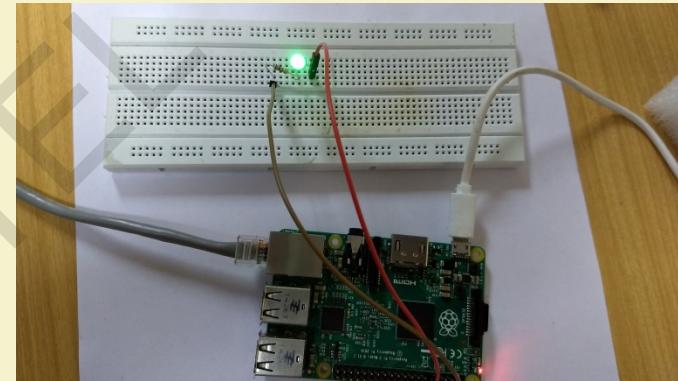
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Blinking LED (contd..)

The LED blinks in a loop with delay of 1 and 2 seconds.



Capture Image using Raspberry Pi



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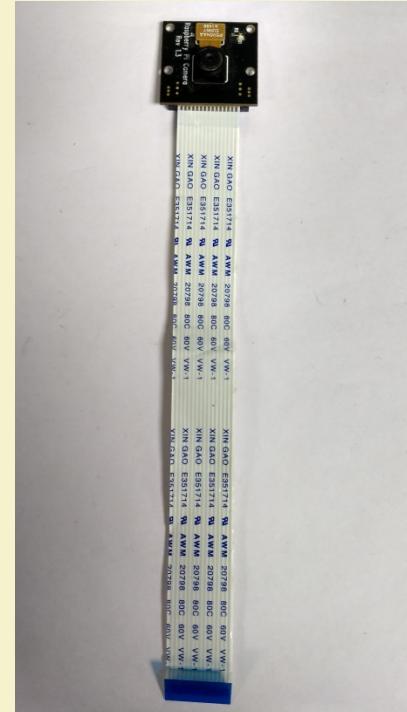
Requirement

- Raspberry Pi
- Raspberry Pi Camera



Raspberry Pi Camera

- Raspberry Pi specific camera module
- Dedicated CSI slot in Pi for connection
- The cable slot is placed between Ethernet port and HDMI port



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Connection

Boot the Pi once the camera is connected to Pi



Configuring Pi for Camera

- In the terminal run the command “sudo raspi-config” and press enter.
- Navigate to “Interfacing Options” option and press enter.
- Navigate to “Camera” option.
- Enable the camera.
- Reboot Raspberry pi.

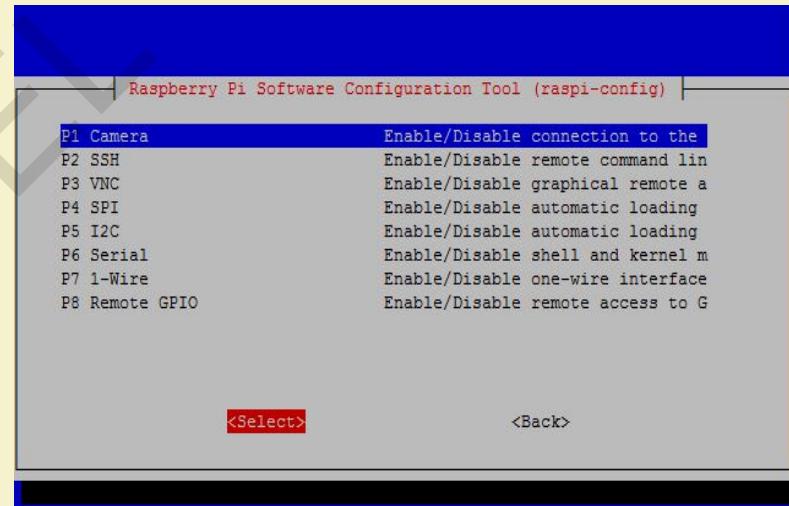
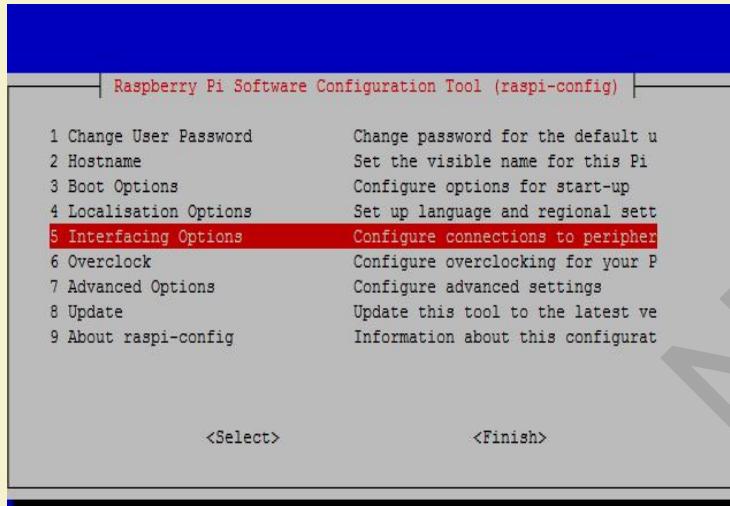


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Configuring Pi for Camera (contd..)



Capture Image

- Open terminal and enter the command-

```
raspistill -o image.jpg
```

- This will store the image as 'image.jpg'



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Capture Image (contd..)

PiCam can also be processed using Python camera module python-picamera

```
sudo apt-get install python-picamera
```

Python Code:

```
Import picamera  
camera = picamera.PiCamera()  
camera.capture('image.jpg')
```

Source: [PYTHON PICAMERA](#), Raspberry Pi Foundation

Capture Image (contd..)

```
pi@raspberrypi:~ $ raspistill -o image.jpg  
pi@raspberrypi:~ $
```



Thank You!!



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Implementation of IoT with Raspberry Pi: Part 1

Dr. Sudip Misra

Associate Professor

Department of Computer Science and Engineering
IIT KHARAGPUR

Email: smisra@sit.iitkgp.ernet.in

Website: <http://cse.iitkgp.ac.in/~smisra/>

IOT

Internet Of Things

- Creating an interactive environment
- Network of devices connected together



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Sensor

- Electronic element
- Converts physical quantity into electrical signals
- Can be analog or digital



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Actuator

- Mechanical/Electro-mechanical device
- Converts energy into motion
- Mainly used to provide controlled motion to other components



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System Overview

- Sensor and actuator interfaced with Raspberry Pi
- Read data from the sensor
- Control the actuator according to the reading from the sensor
- Connect the actuator to a device



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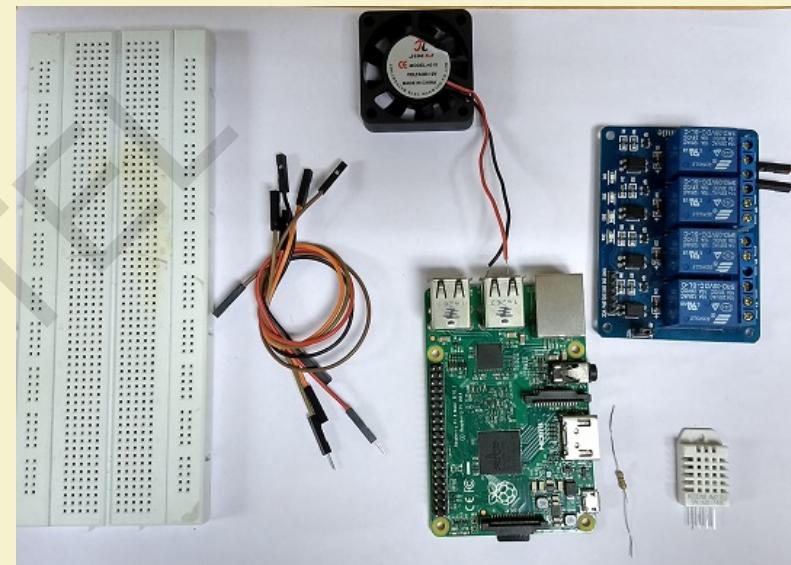


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System Overview (contd..)

Requirements

- DHT Sensor
- 4.7K ohm resistor
- Relay
- Jumper wires
- Raspberry Pi
- Mini fan



DHT Sensor

- Digital Humidity and Temperature Sensor (DHT)
- PIN 1, 2, 3, 4 (from left to right)
 - PIN 1- 3.3V-5V Power supply
 - PIN 2- Data
 - PIN 3- Null
 - PIN 4- Ground



Relay

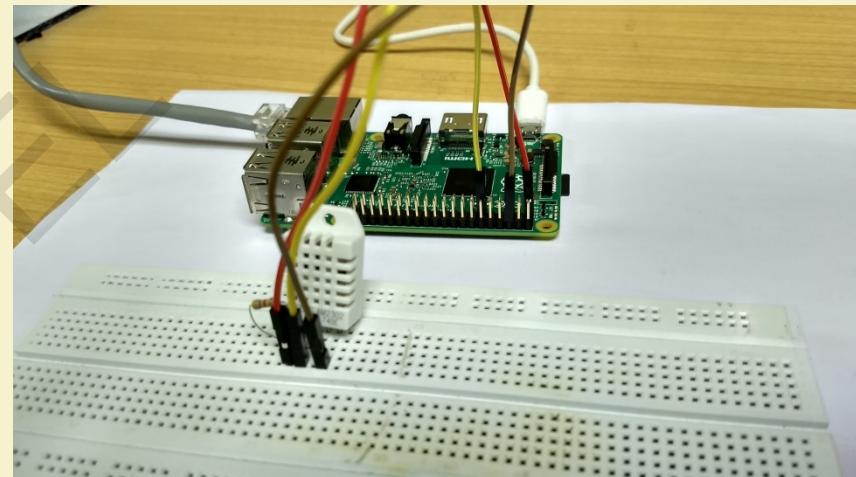
- Mechanical/electromechanical switch
- 3 output terminals (left to right)
 - NO (normal open):
 - Common
 - NC (normal close)



Temperature Dependent Auto Cooling System

Sensor interface with Raspberry Pi

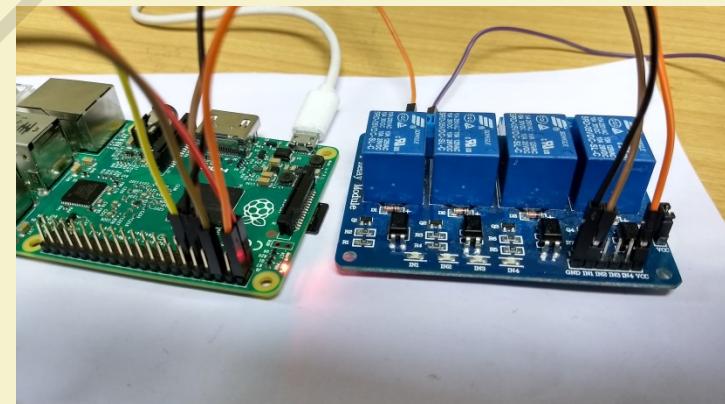
- Connect pin 1 of DHT sensor to the 3.3V pin of Raspberry Pi
- Connect pin 2 of DHT sensor to any input pins of Raspberry Pi, here we have used pin 11
- Connect pin 4 of DHT sensor to the ground pin of the Raspberry Pi



Temperature Dependent Auto Cooling System (contd..)

Relay interface with Raspberry Pi

- Connect the VCC pin of relay to the 5V supply pin of Raspberry Pi
- Connect the GND (ground) pin of relay to the ground pin of Raspberry Pi
- Connect the input/signal pin of Relay to the assigned output pin of Raspberry Pi
(Here we have used pin 7)



Temperature Dependent Auto Cooling System (contd..)

Adafruit provides a library to work with the DHT22 sensor

- Install the library in your Pi-
 - Get the clone from GIT

```
git clone https://github.com/adafruit/Adafruit_Python_DHT.g...
```
 - Go to folder Adafruit_Python_DHT

```
cd Adafruit_Python_DHT
```
 - Install the library

```
sudo python setup.py install
```

Source: [ADAFRUIT DHTXX SENSORS](#), Lady Ada, 2012-07-29

Program: DHT22 with Pi

```
import RPi.GPIO as GPIO
from time import sleep
import Adafruit_DHT
# importing the Adafruit library

GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)
sensor = Adafruit_DHT.AM2302
# create an instance of the sensor type
print ('Getting data from the sensor')
#humidity and temperature are 2 variables that store the values received from the sensor

humidity, temperature = Adafruit_DHT.read_retry(sensor,17)
print ('Temp={0:0.1f}*C humidity={1:0.1f}%'.format(temperature, humidity))
```

Program: DHT22 interfaced with Raspberry Pi

Code

```
GNU nano 2.2.6          File: IOTSR.py

import RPi.GPIO as GPIO
from time import sleep

import Adafruit_DHT

GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)

sensor = Adafruit_DHT.AM2302 # create an instance of the sensor type

print ('Getting data from the sensor')

#humidity and temperature are 2 variables that store the values received from the sensor
humidity, temperature = Adafruit_DHT.read_retry(sensor,17)

print ('Temp={0:0.1f}*C humidity={1:0.1f}%'.format(temperature, humidity))
```

Output

```
pi@raspberrypi:~ $ python IOTSR.py
Getting data from the sensor
Temp=26.1*C humidity=65.9%
pi@raspberrypi:~ $
```

Connection: Relay

- Connect the relay pins with the Raspberry Pi as mentioned in previous slides
- Set the GPIO pin connected with the relay's input pin as output in the sketch
GPIO.setup(13,GPIO.OUT)
- Set the relay pin high when the temperature is greater than 30
if temperature > 30:
 GPIO.output(13,0) # Relay is active low
 print('Relay is on')
 sleep(5)
 GPIO.output(13,1) # Relay is turned off after delay of 5 seconds

Connection: Relay (contd..)

```
GNU nano 2.2.6          File: IOTSR.py

import RPi.GPIO as GPIO
from time import sleep

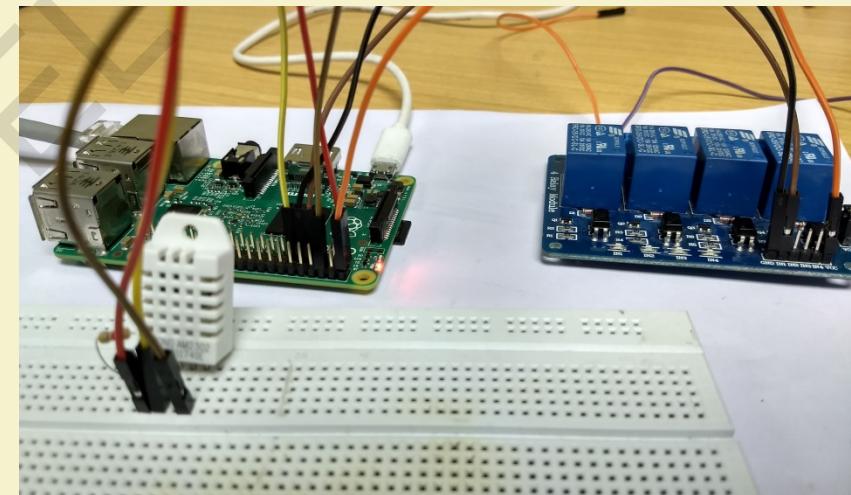
import Adafruit_DHT

GPIO.setmode(GPIO.BOARD)
GPIO.setwarnings(False)
GPIO.setup(7,GPIO.OUT)

sensor = Adafruit_DHT.AM2302 # create an instance of the sensor type
print ('Getting data from the sensor')

#humidity and temperature are 2 variables that store the values received from the sensor
humidity, temperature = Adafruit_DHT.read_retry(sensor,17)

print ('Temp={(0:0.1f)*C humidity={(1:0.1f)}%'.format(temperature, humidity))
if temperature > 20:
    GPIO.output(7,0) # Relay is active low
    print('Relay is on')
    sleep(5)
    GPIO.output(7,1) # Relay is turned off after delay of 5 seconds
```



Connection: Fan

- Connect the Li-po battery in series with the fan
 - NO terminal of the relay -> positive terminal of the Fan.
 - Common terminal of the relay -> Positive terminal of the battery
 - Negative terminal of the battery -> Negative terminal of the fan.
- Run the existing code. The fan should operate when the surrounding temperature is greater than the threshold value in the sketch

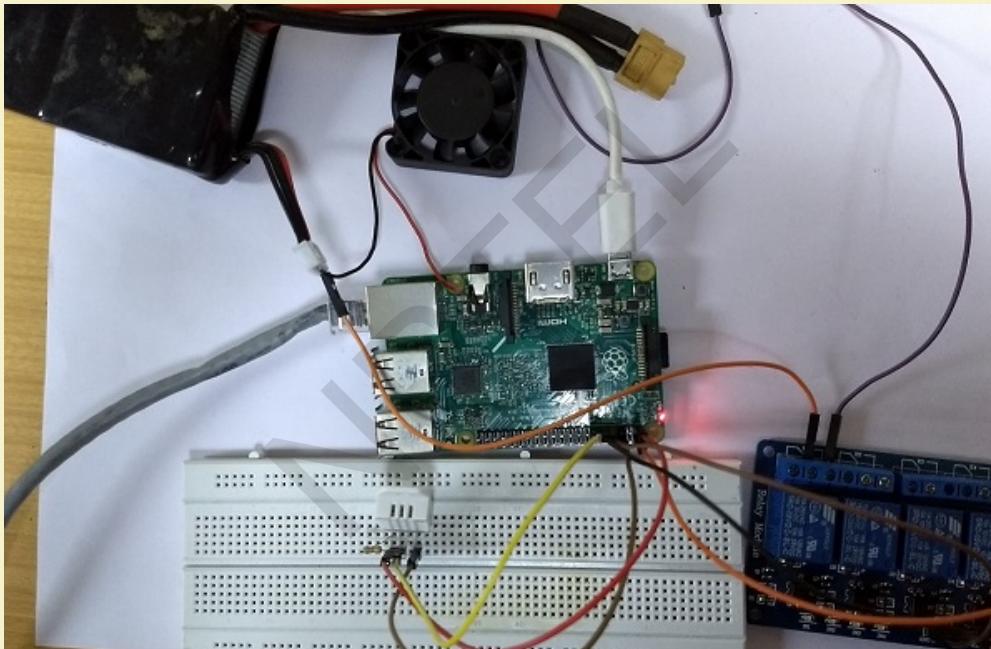


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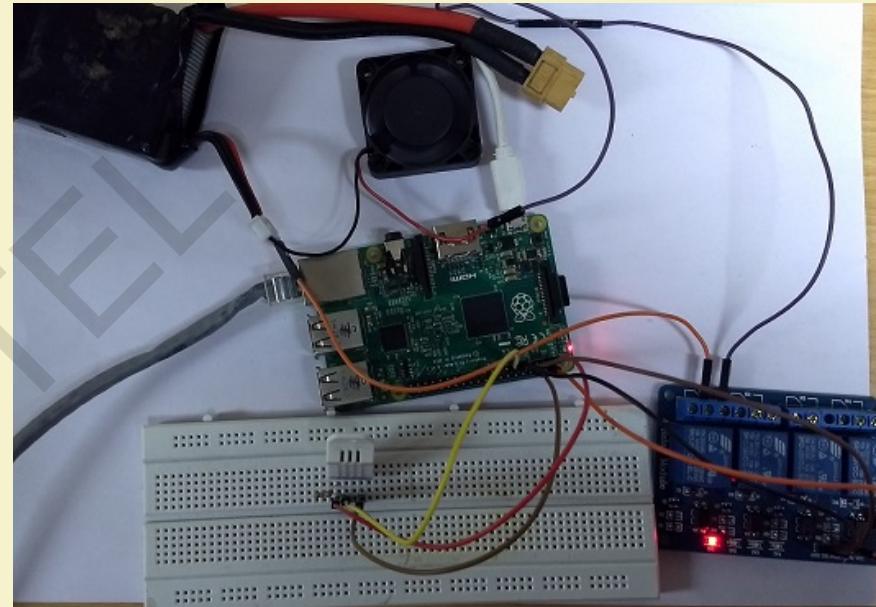
Connection: Fan (contd..)



Result

The fan is switched on whenever the temperature is above the threshold value set in the code.

Notice the relay indicator turned on.



Thank You!!



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