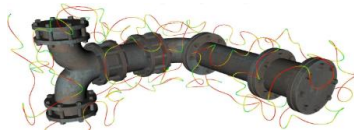


Offline

Coverage
path planner



list of
way points

Collision map
generation



NUVLOX

sdf map

Online

Entanglement
aware path planner

Tether model

P_{tether}

p_{target}

MPC

u

x

