

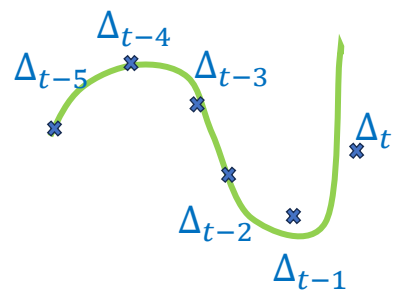
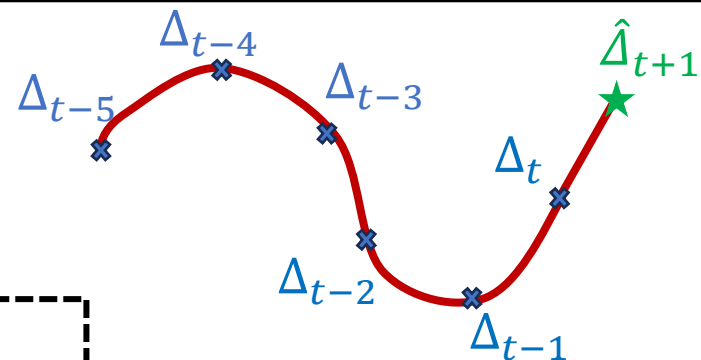
## DF-GP

$$\mu_{DF-GP} = \mu_{gp1} \eta_1^{opt} + \mu_{gp2} \eta_2^{opt} \dots + \mu_{gpK} \eta_K^{opt}$$

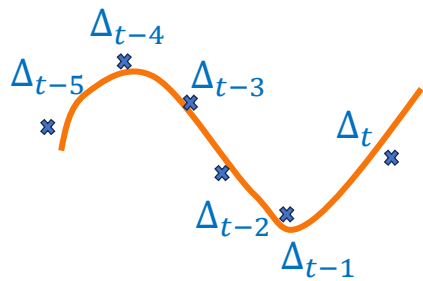
$\eta_j^{opt}$

Dynamic weight optimization (Eq. 25)

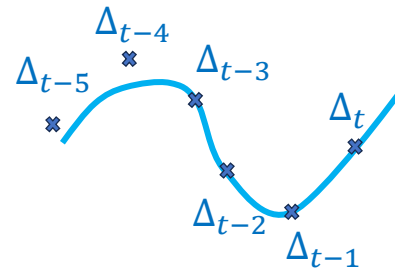
$\mu_{gpj}$



$\mu_{gp1}(x, u, \lambda_1)$



$\mu_{gp2}(x, u, \lambda_2)$



$\mu_{gp3}(x, u, \lambda_3) \dots \mu_{gpK}(x, u, \lambda_K)$

GP prediction