### Course Presentation

Planning and Scheduling

Computer Sciences Degree

Computer Engineering Department

Dra. Ma Dolores Rodríguez Moreno





# Teachers and Tutoring hours

Dra. María Dolores R-Moreno	Dr. Pablo Parra Espada
Course leader	
Email: malola.rmoreno@uah.es	Email: pablo.parra@uah.es
Office: E-313	Office: E-235
Phone: 91-885-66-07	Phone: 91-885-69-52
Tutoring hours: Tu: 11-14	Tutoring hours: Tu: 10-12
W: 17-18	Th: 15:00 a 17:00.
Research: AI & ML and robotics	Research: Embedded systems





#### CV

- European PhD in Computer Sciences
- Research interest
  - AI & ML
  - Robotics
- Research Visits
  - BT, UK
  - CNR, Italy
  - NASA Ames, USA
  - JPL-NASA, USA
- Full Professor (2018)
- https://atc1.aut.uah.es/~mdolores/





#### General features

Course 3rd Year

Semester Second

Credits 6 ECTS

Web Aula Virtual

Course Schedule Wed: 10-12 (on-line)

Labs Schedules Wed: 8-10(SA1)

Wed: 12-14 (SA1) and 12-14(E-A8)

Wed: 15-17 (SA1)





## Objectives

#### **General Objective**

Know AI Planning: concept & techniques

#### **Specific Objectives**

- Explain how classic search techniques differ in planning systems
- Explain the differences between planning as search, operator-based planning and propositional planning
- Compare and contrast static planning with those that need dynamic execution
- Know the impact of AI planning in Robotics





### Contents

Pai	rt	Topics
I.	Introduction	<ul><li>Search</li><li>Planning</li></ul>
2.	AI Planning	• Languages & Techniques
3.	AI Scheduling	• Techniques
4.	Application Domains	<ul><li>Robotic</li><li>Space</li></ul>





### Course Scheduling

- Time distribution of the course:
  - Course: on-line & synchronous
  - Labs: on-line and in classroom: SA1/EA8 (details of the excel sheet)
  - 12h/per student of physical attendance



## Labs Assignments







# Methodology

- Theory classes
- Problems solved
- Flipped Learning
  - Please, install SOCRATIVE



#### Continuous Assessment

Instruments Rating		truments Rating	% Mark
	I.	Final Exam	40%
	2.	Testing Lab	30%
	3.	Partial Exam/Assignments	30%





### Testing Lab (30%)

- Each lab assignment has a deadline, upload in a .zip the exercises before that date
- The assignment is compulsory
- You can do it in pairs but better to do it alone
- The lab exam defines the lab mark
- Missing a lab assignment means 1/3 (10%) less of the total lab mark (30%)



### PEP/TA (30%)

- Visualizing ALL videos → 0,25points
- 0,75 points  $\rightarrow$  The rest, by quizzes in the class
- Partial exam (20points)



# Single Assessment

In	struments Rating	% Mark
I.	Final Exam	100%



# Regulation

- Notifications by the e-learning platform
- Contact by e-mail
- Respect and courtesy
- Plagiarism will not be tolerated



### Bibliography

- Malik Ghallab, Dana Nau and Paolo Traverso (2016). Automated Planning and Acting. Cambridge University Press, online ISBN: 9781139583923.
- Stuart Russell y Peter Norvig (2009). Artificial Intelligence: A Modern Approach. (3rd Edition). Ed. Pearsons.
- McDermott, Drew; Ghallab, Malik; Howe, Adele; Knoblock, Craig; Ram, Ashwin; Veloso, Manuela; Weld, Daniel; Wilkins, David (1998). PDDL-The Planning Domain Definition Language. Technical Report CVC TR98003/DCS TR1165. New Haven, CT: Yale Center for Computational Vision and Control.
- Fikes and Nilsson (1971). STRIPS: A New Approach to the Application of Theorem Proving to Problem Solving, Artificial intelligence, 2 (3-4): 189-208.
- A. Blum and M. Furst (1997). Fast Planning Through Planning Graph Analysis. Artificial Intelligence, 90:281-300
- Jörg Hoffmann (2001). FF: The Fast-Forward Planning System. AI Magazine, 22 (3):57-62.





# Questions???

### Planning and Scheduling

Computer Sciences Degree

Computer Engineering Department

Dra. Ma Dolores Rodríguez Moreno





# Socrative Quiz: GIIPLANNING (Room)

Planning and Scheduling

Computer Sciences Degree

Computer Engineering Department

Dra. Ma Dolores Rodríguez Moreno



