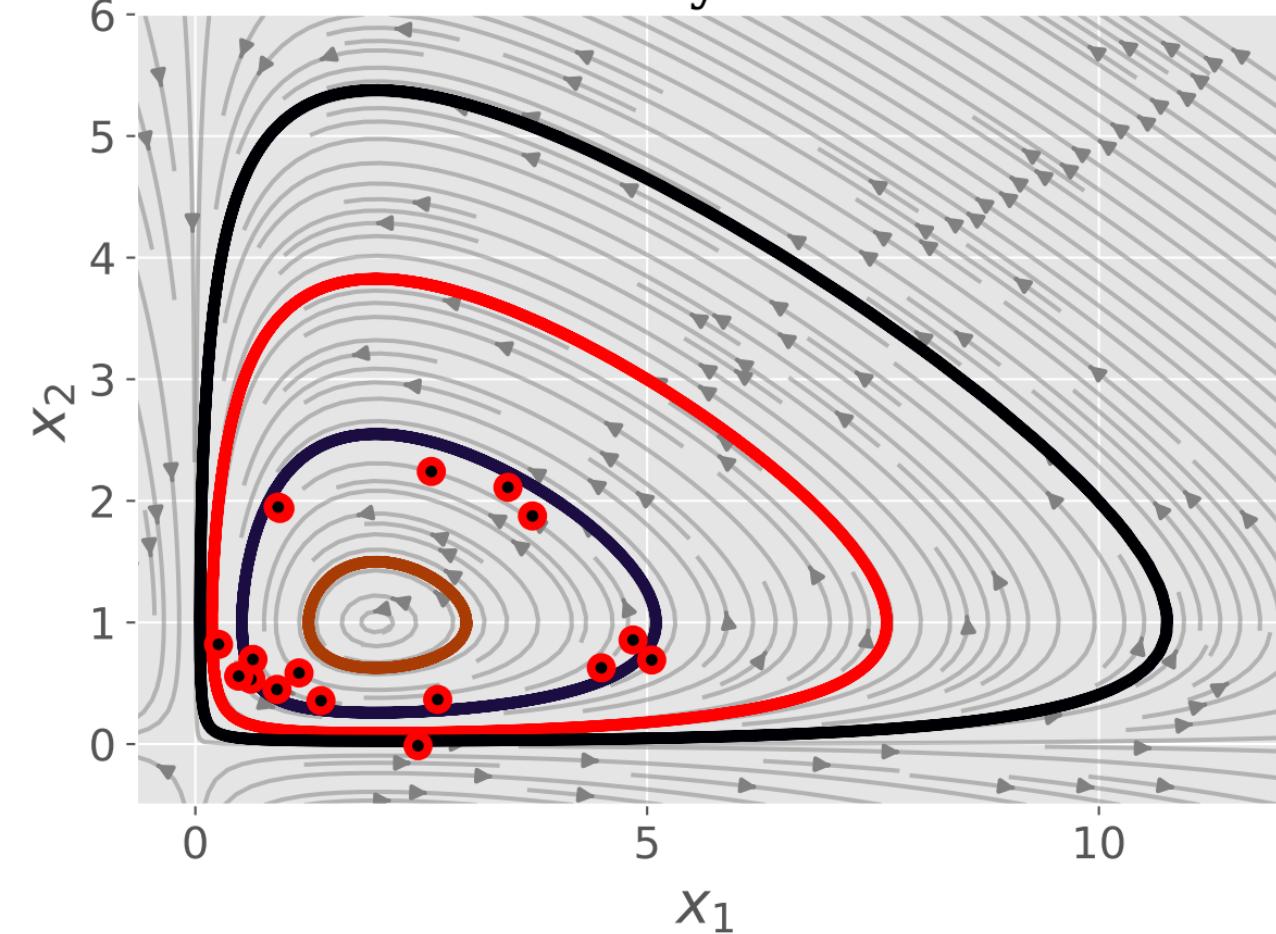
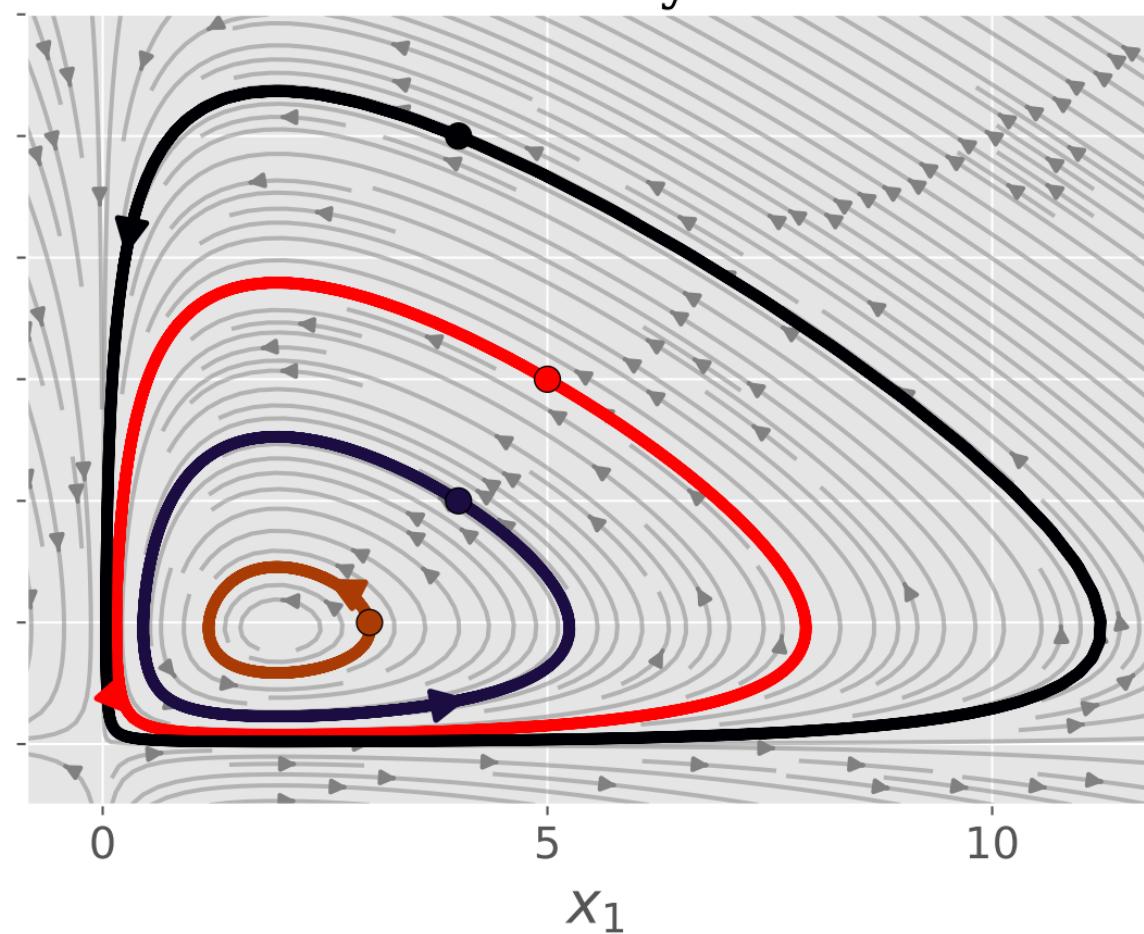


True Dynamics



Simulated Dynamics



- Observations
- $x(0) = (5, 3)$
- $x(0) = (4, 5)$
- $x(0) = (4, 2)$
- $x(0) = (3, 1)$