

# ECE 8101: Nonconvex Optimization for Machine Learning

Lecture Note 3-2: Decentralized Optimization for Learning

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Spring 2022

# Outline

In this lecture:

- Key Idea of Decentralized Nonconvex Optimization for Learning
- Representative Techniques
- Convergence Results

# Revisit the Distributed/Federated Learning Problem

- Consider the problem:

$$\min_{\mathbf{x} \in \mathbb{R}^m} f(\mathbf{x}) \triangleq \min_{\mathbf{x} \in \mathbb{R}^d} \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x}),$$

where  $f_i(\mathbf{x}) \triangleq \mathbb{E}_{\xi_i \sim \mathcal{D}_i}[F_i(\mathbf{x}, \xi_i)]$  is nonconvex

- Distributed/Federated Learning: The “summation” in the mini-batched SGD, which implies a **decomposable** and **distributed** implementation:
  - Each stochastic gradient  $\nabla F(\mathbf{x}_k, \xi_i)$  can be computed by a “worker/client”  $i$
  - $B_k$  workers can compute such stochastic gradients **in parallel**
  - A **server** collects the stochastic gradients returned by workers and **aggregate**

But what if we don't have a server?

# Reasons for “Not Having a Server” in Distributed Learning

- Networks Having No Infrastructure

- ▶ Networking protocols based on random access (CSMA, ALOHA, etc.)
- ▶ Ad hoc sensor networks for environmental monitoring
- ▶ Multi-agent systems (autonomous driving, UAVs/UGVs, robotics, etc.)
- ▶ Autonomous swarms on battle field
- ▶ In-situ disaster recovery

- Security/Robustness/Privacy Concerns

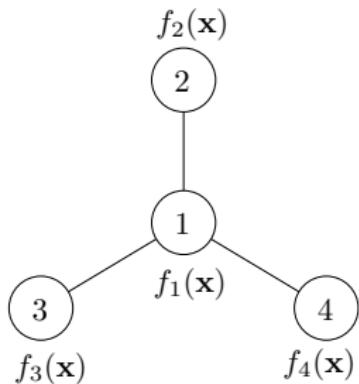
- ▶ Avoid single point of failure
- ▶ Avoid having a single target under cyber-attacks
- ▶ Avoid communication/networking bottleneck
- ▶ Need for information privacy preservation
- ▶ Need for decentralization to avoid being controlled by a single party

- Economics Motivations

- ▶ Competition/collaboration among entities
- ▶ Build trust between multiple parties
- ▶ Fairness guarantees
- ▶ Promote personalization and diversity...

# Decentralization Optimization for Learning: The Setup

- A network represented by a **connected** graph  $\mathcal{G} = (\mathcal{N}, \mathcal{L})$ , with  $|\mathcal{N}| = N$ ,  $|\mathcal{L}| = L$
- $\mathbf{x} \in \mathbb{R}^d$ : a **global** learning model
- Each node/agent  $i$  can only evaluate a local objective function  $f_i(\mathbf{x}) \triangleq \mathbb{E}_{\xi_i \sim \mathcal{D}_i}[F_i(\mathbf{x}, \xi_i)]$
- Global objective function is:  $\frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$
- Goal: To learn the global model **collaboratively in a decentralized fashion** (i.e., w/o needing any server)



# Example: Decentralized Learning in Multi-Agent Systems

- A multi-agent system (drones, robots, soldiers, etc.). Each agent collects high-resolution images  $\{\mathbf{u}_{ij}, \mathbf{v}_{ij}, \theta_{ij}\}_{j=1}^{N_i}$
- $\mathbf{u}_{ij}, \mathbf{v}_{ij}, \theta_{ij}$ : pixels, geographical information, ground-truth label of the  $j$ -th image at agent  $i$ .
- Agents **collaboratively** perform image regression based on linear model with parameters  $\mathbf{x} = [\mathbf{x}_1^\top \mathbf{x}_2^\top]^\top$
- This problem can be written as:  $\min_{\mathbf{x}} f(\mathbf{x}) \triangleq \min_{\mathbf{x}} \sum_{i=1}^N f_i(\mathbf{x})$ , where  $f_i(\mathbf{x}) \triangleq \frac{1}{N_i} \sum_{j=1}^{N_i} (\theta_{ij} - \mathbf{u}_{ij}^\top \mathbf{x}_1 - \mathbf{v}_{ij}^\top \mathbf{x}_2)^2$



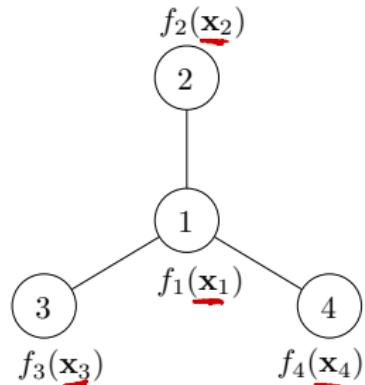
# Consensus Reformulation: The First Step

- Goal: To solve the following optimization problem **distributively & collaboratively**

$$\min_{x \in \mathbb{R}^d} f(\mathbf{x}) = \min_{x \in \mathbb{R}^d} \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$$

- Clearly, this problem can be rewritten in a **consensus** form:

$$\min_{\mathbf{x}_i \in \mathbb{R}^d, \forall i} \left\{ \frac{1}{N} \sum_{i=1}^N f_i(\underline{\mathbf{x}}_i) \middle| \underline{\mathbf{x}}_i = \underline{\mathbf{x}}_j, \forall (i, j) \in \mathcal{L} \right\}$$



The consensus reformulation shares the same spirit with **distributed/federated learning** that each node maintains a **local copy** of the global model

## Recall What We Did When We Have a Server

- In distributed/federated learning: Each node/client  $i$  computes

$$\mathbf{x}_{i,k+1} = \bar{\mathbf{x}}_k - s_k \mathbf{g}_{i,k}$$

where  $\bar{\mathbf{x}}_k \triangleq \frac{1}{N} \sum_{i=1}^N \mathbf{x}_{i,k}$  is the node/client average in iteration  $k$

- This prompts the following natural idea for decentralized learning

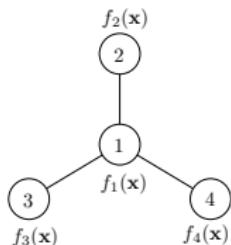
$$\mathbf{x}_{i,k+1} = \text{"Some approximation of } \bar{\mathbf{x}}_k \text{"} - s_k \mathbf{g}_{i,k}$$

- This idea turns out to be the foundation of decentralized consensus optimization
  - ▶ Note: This is an insight in hindsight. Decentralized consensus optimization traces its roots to the seminal work [Tsitsiklis, Ph.D. Thesis@MIT, 1984]!

# A Decentralized Method for Computing Average

Consider a **consensus matrix**  $\mathbf{W} \in \mathbb{R}^{N \times N}$  that satisfies:

- **Doubly stochastic:**  $\sum_{i=1}^N [\mathbf{W}]_{ij} = \sum_{j=1}^N [\mathbf{W}]_{ij} = 1$ .
- Sparsity pattern defined by **network topology**:  $[\mathbf{W}]_{ij} > 0$  for  $\forall (i, j) \in \mathcal{L}$  and  $[\mathbf{W}]_{ij} = 0$  otherwise
- **Symmetric** and hence **real** eigenvalues in  $(-1, 1]$  (thus can be **sorted**). Moreover, easy to see that  $\lambda_{\max} = 1$  with corresponding eigenvector  $\mathbf{1}_N$ .
- W.l.o.g., denote eigenvalues as  $-1 < \lambda_N \leq \dots \leq \lambda_1 = 1$ . Let  $\beta \triangleq \max\{|\lambda_2|, |\lambda_N|\}$  (i.e., **2nd-largest eigenvalue in magnitude**).



$$\mathbf{W} = \begin{bmatrix} 1/4 & 1/4 & 1/4 & 1/4 \\ 1/4 & 3/4 & 0 & 0 \\ 1/4 & 0 & 3/4 & 0 \\ 1/4 & 0 & 0 & 3/4 \end{bmatrix}$$

# A Decentralized Method for Computing Average

- ➊  $k = 0$ . Each node has initial value  $\mathbf{x}_{i,0}$  to be averaged with other nodes
- ➋ In  $k$ -th iteration: Each node shares its local copy to its neighbors.
- ➌ Upon reception of all local copies from its neighbors, each node performs the local updates:

$$\mathbf{x}_{i,k+1} = \sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k},$$

where  $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$ .

- ➍ Let  $k \leftarrow k + 1$  and go to Step 2

# A Decentralized Method for Computing Average

- Define a stacked matrix of all local copies:

$$\mathbf{X}_k \triangleq \begin{bmatrix} \mathbf{x}_{1,k} & \mathbf{x}_{2,k} & \cdots & \mathbf{x}_{N,k} \end{bmatrix} \in \mathbb{R}^{d \times N}.$$

$\uparrow$   
 $\mathbb{R}^d$

- Then the algorithm in the previous slide can be compactly written as

$$\mathbf{X}_{k+1} = \mathbf{X}_k \mathbf{W}, \quad \underline{\mathbf{X}}_{k+1}^T = \underline{\mathbf{W}} \underline{\mathbf{X}}_k^T$$

(i.e.,  $\mathbf{X}_k = \mathbf{X}_0 \mathbf{W}^k$ ). Similar to a discrete-time finite-state Markov chain.  
*Perron-Frobenius Thm*

- Fact: The stationary distribution of an irreducible aperiodic finite-state Markov chain is uniform iff its transition matrix is doubly stochastic.
- Convergence rate of “averaging”: Let  $\mathbf{W}^\infty = \lim_{k \rightarrow \infty} \mathbf{W}^k$ . Then, we have  $\mathbf{W}^\infty = \frac{1}{N} \mathbf{1}_N \mathbf{1}_N^T$ . Further, it holds that

$$\left[ \begin{array}{c|cc|c} \frac{1}{N} & \cdots & \frac{1}{N} \\ \hline \vdots & \ddots & \vdots & \vdots \\ \frac{1}{N} & \cdots & \frac{1}{N} & \end{array} \right] \left[ \begin{array}{c} x_1 \\ \vdots \\ x_N \end{array} \right] = \left[ \begin{array}{c} \frac{1}{N} \\ \vdots \\ \frac{1}{N} \end{array} \right]$$

$\|\mathbf{W}^\infty \mathbf{e}_i - \mathbf{W}^k \mathbf{e}_i\|^2 \leq \beta^{2k}, \quad \forall i \in \{1, \dots, N\}, k \in \mathbb{N}.$

$\uparrow$   
ith basis vector in  $\mathbb{R}^d$ .

$\frac{\lambda_2}{\lambda_1}$

$$\text{WTS: } \left\| \underbrace{\underline{W}^{\infty} e_i}_{\substack{\text{def} \\ \frac{1}{N} \mathbf{1}_N}} - \underline{W}^k e_i \right\|^2 \leq \beta^{2k} \quad \leftarrow \text{Lemma.}$$

$$\begin{aligned} \text{Proof. } & \left\| \underline{W}^{\infty} e_i - \underline{W}^k e_i \right\|^2 = \left\| (\underline{W}^{\infty} - \underline{W}^k) e_i \right\|^2 \\ & \leq \underbrace{\left\| \underline{W}^{\infty} - \underline{W}^k \right\|^2}_{\text{induced norm}} \cdot \left\| e_i \right\|^2 = \left\| \underline{W}^{\infty} - \underline{W}^k \right\|^2. \end{aligned} \quad (1).$$

Note that  $\underline{W}$  is symmetric  $\Rightarrow$  It has real eigenvalues.

$$\underline{W} = \underline{U} \Lambda \underline{U}^T, \quad \text{where } \underline{\Lambda} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_N \end{bmatrix}, \quad \underline{U} = \begin{bmatrix} | & | & \cdots & | \\ \underline{u}_1 & \underline{u}_2 & \cdots & \underline{u}_N \\ | & | & \cdots & | \end{bmatrix}$$

† unitary,  $\underline{U}^T \underline{U} = \underline{U} \underline{U}^T = \underline{I}$

$$\text{So, } \underline{W}^k = \underbrace{\underline{U} \underline{\Lambda} \underline{U}^T \cdot \underline{U} \underline{\Lambda} \underline{U}^T \cdot \cdots \cdot \underline{U} \underline{\Lambda} \underline{U}^T}_{k \text{ terms}} = \underline{U} \underline{\Lambda}^k \underline{U}^T \quad \begin{bmatrix} \lambda_1^k & & \\ & \ddots & \\ & & \lambda_N^k \end{bmatrix}$$

Also,  $\underline{W}^{\infty} = \frac{1}{N} \mathbf{1} \mathbf{1}^T$ . clearly, it has one eigenvalue 1 and eigenvector  $\mathbf{1}_N$ .

$$\underline{W}^{\infty} = \underline{U}^T \begin{bmatrix} 1 & & \\ 0 & \ddots & \\ & & 0 \end{bmatrix} \underline{U}^T \quad \sum_{i=1}^N \lambda_i \underline{u}_i \underline{u}_i^T$$

$$(1) = \left\| \underline{U} \left( \begin{bmatrix} 1 & & \\ 0 & \ddots & \\ & & 0 \end{bmatrix} - \begin{bmatrix} 1 & & \\ \lambda_2 & \ddots & \\ & \ddots & \lambda_N \end{bmatrix} \right) \underline{U}^T \right\|^2 = \left\| \sum_{i=2}^N \lambda_i \underline{u}_i \underline{u}_i^T \right\|^2$$

$$\leq \beta^{2k} \left\| \sum_{i=1}^N \underline{u}_i \underline{u}_i^T \right\|^2 = \beta^{2k} \underbrace{\left\| \underline{U} \underline{U}^T \right\|^2}_{= \underline{I}} = \beta^{2k}. \quad \blacksquare$$

$\uparrow$   
replace  $\lambda_i \underline{u}_i$   
by  $\beta$ , factor it  
out, adding  $\beta \underline{U} \underline{U}^T$

# Decentralized Stochastic Gradient Descent (DSGD)

The DSGD algorithm [Nedic and Ozdaglar, TAC'09]:  $\begin{matrix} \text{PGD} \\ \text{P-GD} \end{matrix} \quad \begin{matrix} \text{P-SGD} \end{matrix} \quad \left. \begin{matrix} \text{PGD} \\ \text{P-GD} \end{matrix} \right\} \text{PSGD.}$

- ① Initialization: Let  $k = 1$ . Choose initial values for  $\mathbf{x}_{i,1}$  and step-size  $s_1$ .
- ② In  $k$ -th iteration: Each node sends its local copy to its neighbors.
- ③ Upon reception of all local copies from its neighbors, each node updates its local copy:  
*"some approx. \$\bar{\mathbf{x}}\_k\$"*      *run this mult. steps.*

$$\mathbf{x}_{i,k+1} = \underbrace{\sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k}}_{\text{Avg consensus step}} - \underbrace{s_k \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k})}_{\text{Local SGD step}},$$

where  $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$ .

- ④ Let  $k \leftarrow k + 1$  and go to Step 2

*DGD<sup>t</sup>*      *can be done  
+ "rounds".*

# Convergence Results of DSGD

## Assumptions:

- $f_i(\cdot)$ ,  $\forall i$  are  $L$ -smooth
- Unbiased stochastic gradients:  $\mathbb{E}_{\xi_{i,k} \sim \mathcal{D}_i} [\nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k})] = \nabla f_i(\mathbf{x}_{i,k})$ ,  $\forall i, k$
- Bounded local stochastic gradient variance:

$$\mathbb{E}[\|\nabla F_i(\mathbf{x}, \xi) - \nabla f_i(\mathbf{x})\|^2] \leq \sigma^2, \quad \forall i, \mathbf{x}$$

- Bounded gradient dissimilarity: *means  $\nabla f_i(\xi)$  still follows D<sub>i</sub>*

$$\mathbb{E}_{i \sim \mathcal{U}([n])} [\|\nabla f_i(\mathbf{x}) - \nabla f(\mathbf{x})\|^2] \leq \zeta^2, \quad \forall \mathbf{x}$$

- Start from 0:  $\mathbf{X}_0 = \mathbf{0}$  (not necessary, but simplifies the proof w.l.o.g.)

# Convergence Results of DSGD

- Let  $s_k = s, \forall k$ , and define two constants:

$$D_1 := \left( \frac{1}{2} - \frac{9s^2 L^2 N}{(1-\beta)^2 D_2} \right), \text{ and } D_2 := \left( 1 - \frac{18s^2}{(1-\beta)^2} N L^2 \right)$$

Theorem 1 ([Lian et al. NeurIPS'17])

Under the stated assumptions, the following convergence rate holds for DSGD:

$$\begin{aligned} & \frac{1}{K} \left( \frac{1-sL}{2} \sum_{k=0}^{K-1} \mathbb{E} \left[ \left\| \frac{\partial f(\mathbf{X}_k) \mathbf{1}_N}{N} \right\|^2 \right] + D_1 \sum_{k=0}^{K-1} \mathbb{E} \left[ \left\| \nabla f \left( \frac{\mathbf{X}_k \mathbf{1}_N}{N} \right) \right\|^2 \right] \right) \\ & \leq \underbrace{\frac{f(\mathbf{0}) - f^*}{sK}}_{\text{converges to zero}} + \frac{sL}{2N} \sigma^2 + \frac{s^2 L^2 N \sigma^2}{(1-\beta^2) D_2} + \frac{9s^2 L^2 N \zeta^2}{(1-\beta)^2 D_2} \end{aligned}$$

$= O(K)$  to some error ball.

$$\bar{x}_k \triangleq \frac{1}{N} \sum_{i=1}^N x_{i,k}$$

# Convergence Results of DSGD

Corollary 2 ([Lian et al. NeurIPS'17])

Under the same assumptions as in Theorem 1, if  $s = \frac{1}{2L + \sigma\sqrt{K/N}}$ , then DSGD achieves the following convergence rate:

$$\frac{1}{K} \sum_{k=0}^{K-1} \mathbb{E} \left[ \left\| \nabla f \left( \frac{\mathbf{z}_k}{N} \right) \right\|^2 \right] \leq \frac{8(f(\mathbf{0}) - f^*)}{K} + \frac{(8f(\mathbf{0}) - 8f^* + 4L)}{\sqrt{KN}}.$$

## Remark 1

If  $K$  is sufficiently large such that

(A)

$$K \geq \frac{4L^4 N^5}{\sigma^2(f(\mathbf{0}) - f^* + L)^2} \left( \frac{\sigma^2}{1 - \beta^2} + \frac{9\zeta^2}{(1 - \beta)^2} \right) \text{ and } K \geq \frac{72L^2 N^2}{\sigma^2(1 - \beta)^2},$$

then the convergence rate of DSGD is  $O\left(\frac{1}{K} + \frac{1}{\sqrt{NK}}\right)$ . ← linear speedup

# Convergence Results of DSGD

Theorem 3 ([Lian et al. NeurIPS'17])

With  $s = \frac{1}{2L + \sigma\sqrt{K/N}}$  and under the same assumptions in Theorem 1, it holds that

$$\frac{1}{KN} \mathbb{E} \left[ \sum_{k=0}^{K-1} \sum_{i=1}^N \left\| \frac{\sum_{i'=1}^N \mathbf{x}_{i',k}}{N} - \mathbf{x}_{i,k} \right\|^2 \right] \leq N s^2 \frac{A}{D_2},$$

where the constant  $A$  is defined as:

$$\begin{aligned} A := & \frac{2\sigma^2}{1-\beta^2} + \frac{18\zeta^2}{(1-\beta)^2} + \frac{L^2}{D_1} \left( \frac{\sigma^2}{1-\beta^2} + \frac{9\zeta^2}{(1-\beta)^2} \right) \\ & + \frac{18}{(1-\beta)^2} \left( \frac{f(\mathbf{0}) - f^*}{sK} + \frac{sL\sigma^2}{2ND_1} \right). \end{aligned}$$

Remark 2

The local copies achieve consensus at the rate  $O(1/K)$

Preparation:

$$\underline{\underline{x}}_k \stackrel{\Delta}{=} \begin{bmatrix} | & | \\ x_{1,k} & \cdots & x_{N,k} \\ | & | \end{bmatrix}_{d \times N}, \quad \underline{\underline{W}} \stackrel{\Delta}{=} \begin{bmatrix} w_{11} & \cdots & w_{1N} \\ | & | \\ w_{N1} & \cdots & w_{NN} \end{bmatrix}_{N \times N}, \quad \partial \underline{\underline{F}}(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k) \stackrel{\Delta}{=} \begin{bmatrix} | & | \\ \nabla f_1(x_{1,k}, \xi_{1,k}) & \cdots & \nabla f_N(x_{N,k}, \xi_{N,k}) \\ | & | \end{bmatrix}_{d \times N}$$

Recall:  $\underline{x}_{i,k+1} = \sum_{\substack{j=1 \\ j \in N(i)}}^N [\underline{\underline{W}}]_{ij} \underline{x}_{j,k} - s \nabla F_i(x_{i,k}, \xi_{i,k}), \forall i$

Concatenating  $\underline{x}_{i,k+1}, \forall i$ , we have:

$$\begin{bmatrix} | & | \\ \underline{x}_{1,k+1} & \cdots & \underline{x}_{N,k+1} \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ \underline{x}_{1,k} & \cdots & \underline{x}_{N,k} \\ | & | \end{bmatrix} \begin{bmatrix} w_{11} & \cdots & w_{1N} \\ | & | \\ w_{N1} & \cdots & w_{NN} \end{bmatrix} - s \begin{bmatrix} | & | \\ \nabla f_1(x_{1,k}, \xi_{1,k}) & \cdots & \nabla f_N(x_{N,k}, \xi_{N,k}) \\ | & | \end{bmatrix}$$

In matrix form:  $\underline{\underline{x}}_{k+1} = \underline{\underline{x}}_k \underline{\underline{W}} - s \partial \underline{\underline{F}}(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k)$ .

$$\Rightarrow \frac{1}{N} \underline{\underline{x}}_{k+1} \underline{\underline{1}}_N = \underbrace{\frac{1}{N} \underline{\underline{x}}_k \underline{\underline{W}} \underline{\underline{1}}_N}_1 - \frac{s}{N} \partial \underline{\underline{F}}(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k) \underline{\underline{1}}_N$$

$$\Rightarrow \bar{x}_{k+1} = \bar{x}_k - \frac{s}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k}).$$

Proof of Thm 1. From descent lemma,

$$\begin{aligned} \mathbb{E}[f(\bar{x}_{k+1})] &= \mathbb{E}\left[f\left(\bar{x}_k - \frac{s}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})\right)\right] \\ &\leq \mathbb{E}[f(\bar{x}_k)] - \frac{s}{N} \mathbb{E}\left[\nabla f(\bar{x}_k)^T \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})\right] + \frac{s^2 L}{2} \mathbb{E}\left[\left\|\frac{1}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})\right\|^2\right] \end{aligned}$$

Consider the quad term:

$$\mathbb{E}\left[\left\|\frac{1}{N} \sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k})\right\|^2\right] = \mathbb{E}\left[\left\|\frac{1}{N} \left(\sum_{i=1}^N \nabla F_i(x_{i,k}, \xi_{i,k}) - \sum_{i=1}^N \nabla f_i(x_{i,k})\right) + \frac{1}{N} \sum_{i=1}^N \nabla f_i(x_{i,k})\right\|^2\right]$$

$$= \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) - \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right] + \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right]$$

$$\Rightarrow \mathbb{E}[f(\bar{x}_{k+1})] \leq \mathbb{E}[f(\bar{x}_k)] - \frac{s}{N} \mathbb{E} \left[ \nabla f(\bar{x}_k)^T \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right] +$$

$$+ \frac{s^2 L}{2} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) - \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right] + \frac{s^2 L}{2} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right]$$

For 2nd last term:

$$\frac{s^2 L}{2} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) - \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right]$$

$$= \frac{s^2 L}{2N^2} \sum_{i=1}^N \mathbb{E} \left[ \underbrace{\left\| \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) - \nabla f_i(\bar{x}_{i,k}) \right\|^2}_{\leq \sigma^2} \right] \quad (\text{unbiasedness}).$$

$$\leq \frac{s^2 L}{2N} \sigma^2 \quad \mathbb{E} \left[ \nabla f(\bar{x}_k)^T \cdot \frac{1}{N} \sum_{i=1}^N \nabla f(\bar{x}_{i,k}) \right] \quad (\text{iter. law of}).$$

$$\mathbb{E}[f(\bar{x}_{k+1})] \leq \mathbb{E}[f(\bar{x}_k)] - s \underbrace{\mathbb{E} \left[ \nabla f(\bar{x}_k)^T \frac{1}{N} \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right]}_{+ \frac{s^2 L \sigma^2}{2N}}$$

$$+ \frac{s^2 L}{2} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right] \quad \underline{a^T b = \frac{1}{2} \|a\|^2 + \frac{1}{2} \|b\|^2 - \frac{1}{2} \|a - b\|^2}$$

$$= \mathbb{E}[f(\bar{x}_k)] - \frac{s - s^2 L}{2} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right] - \frac{s}{2} \mathbb{E} \left[ \left\| \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right\|^2 \right]$$

$$+ \frac{s^2 \sigma^2}{2N} + \frac{s}{2} \mathbb{E} \left[ \left\| \left[ \frac{1}{N} \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right] - \nabla f(\bar{x}_k) \right\|^2 \right], \quad T_1$$

Now, we bound  $T_1$

$$\begin{aligned}
 & \mathbb{E} \left[ \left\| \left[ \nabla f \sum_{i=1}^N \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right] - \nabla f(\bar{x}_k) \right\|^2 \right] \\
 &= \frac{1}{N^2} \mathbb{E} \left[ \left\| \sum_{i=1}^N \left( \nabla f(\bar{x}_k) - \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right) \right\|^2 \right] \quad \left( \begin{array}{l} \mathbb{E}[\|z_1 + \dots + z_n\|^2] \\ \leq n \mathbb{E}[\|z_1\|^2 + \dots + \|z_n\|^2] \end{array} \right) \\
 &\leq \frac{1}{N} \sum_{i=1}^N \mathbb{E} \left[ \left\| \nabla f(\bar{x}_k) - \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right\|^2 \right] \quad w/ n=N. \\
 &\stackrel{*}{=} \frac{1}{N} \sum_{i=1}^N \mathbb{E} \left[ \left\| \nabla f(\bar{x}_k) - \nabla f_i(\bar{x}_{i,k}) + \nabla f_i(\bar{x}_{i,k}) - \nabla F_i(\bar{x}_{i,k}, \xi_{i,k}) \right\|^2 \right] \\
 &= \frac{1}{N} \sum_{i=1}^N \left[ \underbrace{\mathbb{E}[\|\nabla f(\bar{x}_k) - \nabla f_i(\bar{x}_{i,k})\|^2]}_{\leq L^2 \|\bar{x}_k - \bar{x}_{i,k}\|^2} + \underbrace{\mathbb{E}[\|\nabla f_i(\bar{x}_{i,k}) - \nabla F_i(\bar{x}_{i,k}, \xi_{i,k})\|^2]}_{\leq 0^2} \right] \\
 &\leq \frac{1}{N} \sum_{i=1}^N \mathbb{E} \left[ \|\bar{x}_k - \bar{x}_{i,k}\|^2 \right] \quad \text{agent-drift.}
 \end{aligned}$$

To bound the "agent-drift":  $\mathbb{E}[\|\bar{x}_k - \bar{x}_{i,k}\|^2] \triangleq Q_{i,k}$

$$Q_{i,k} = \mathbb{E} \left[ \|\bar{x}_k - \bar{x}_{i,k}\|^2 \right] = \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{j=1}^N \bar{x}_j - \bar{x}_k e_i \right\|^2 \right]$$

$$\begin{aligned}
 & \stackrel{\text{def}}{=} \mathbb{E} \left[ \left\| \frac{1}{N} \left( \sum_{k=1}^N \underbrace{\bar{w}_k \frac{1}{N}}_{=1} - s \nabla F(\bar{x}_k, \xi_k) \frac{1}{N} \right) - \left( \sum_{k=1}^N \bar{w}_k - s \nabla F(\bar{x}_k, \xi_k) \right) e_i \right\|^2 \right]
 \end{aligned}$$

$$= \mathbb{E} \left[ \left\| \frac{1}{N} \left( \sum_{k=1}^N \bar{w}_k \frac{1}{N} - s \nabla F(\bar{x}_k, \xi_k) \frac{1}{N} \right) - \left( \sum_{k=1}^N \bar{w}_k e_i - s \nabla F(\bar{x}_k, \xi_k) e_i \right) \right\|^2 \right]$$

$$\begin{aligned}
 & \text{recursion} \\
 &= \mathbb{E} \left[ \left\| \frac{1}{N} \left( \sum_{i=0}^{k-1} \bar{w}_i \frac{1}{N} - s \sum_{i=0}^{k-1} \nabla F(\bar{x}_i, \xi_i) \frac{1}{N} \right) - \left( \sum_{j=0}^{k-1} \bar{w}_j e_i - s \sum_{j=0}^{k-1} \nabla F(\bar{x}_j, \xi_j) \bar{w}_j e_i \right) \right\|^2 \right]
 \end{aligned}$$

$$\begin{aligned}
&= \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} s \partial f(\underline{x}_j, \xi_j) \left( \frac{1}{N} \underline{1}_N - \underline{w}^{k-j-1} \underline{\epsilon}_i \right) \right\|^2 \right] \\
&= s^2 \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} \partial f(\underline{x}_j, \xi_j) \left( \frac{1}{N} \underline{1}_N - \underline{w}^{k-j-1} \underline{\epsilon}_i \right) \right\|^2 \right] = \left[ \begin{array}{c} \vdots \\ \nabla f_i(\underline{x}_{1,j}) \dots \nabla f_i(\underline{x}_{N,j}) \\ \vdots \end{array} \right] \text{down} \\
&= s^2 \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} \left( \partial f(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) + \partial f(\underline{x}_j) \right) \left( \frac{1}{N} \underline{1}_N - \underline{w}^{k-j-1} \underline{\epsilon}_i \right) \right\|^2 \right] \\
&\leq 2s^2 \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} \left( \partial f(\underline{x}_j, \xi_j) - \partial f(\underline{x}_j) \right) \left( \frac{1}{N} \underline{1}_N - \underline{w}^{k-j-1} \underline{\epsilon}_i \right) \right\|^2 \right] \text{use (x1) w/ n=2} \\
&\quad + 2s^2 \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} \partial f(\underline{x}_j) \left( \frac{1}{N} \underline{1}_N - \underline{w}^{k-j-1} \underline{\epsilon}_i \right) \right\|^2 \right]
\end{aligned}$$

Now, we bound  $T_2$ :

$$\begin{aligned}
 T_2 &= \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} \left( \partial \bar{F}(\bar{x}_j, \xi_j) - \partial f(x_j) \right) \left( \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} e_i \right) \right\|^2 \right] \\
 &\stackrel{\text{unbiasedness}}{\rightarrow} \underset{\text{indep.}}{=} \sum_{j=0}^{k-1} \mathbb{E} \left[ \left\| (\partial \bar{F}(\bar{x}_j, \xi_j) - \partial f(x_j)) \left( \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} e_i \right) \right\|^2 \right] \\
 &\stackrel{\text{cachy-schwarz}}{\leq} \sum_{j=0}^{k-1} \mathbb{E} \left[ \left\| \partial \bar{F}(\bar{x}_j, \xi_j) - \partial f(x_j) \right\|_2^2 \left\| \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} e_i \right\|^2 \right] \\
 &\quad \underbrace{\text{$l_2$-induced norm.} \leq \|\cdot\|_f = \sum_{i=1}^N \|x_{F_i}(\bar{x}_j, \xi_j) - x_{F_i}(x_j)\|^2 \leq N \sigma^2}_{\text{in red}}
 \end{aligned}$$

$$\underline{A} \in \mathbb{R}^{m \times n} \quad (\text{$l_p$-induced norm}): \quad \|\underline{A}\|_2 = \sqrt{\lambda_{\max}(\underline{A}^T \underline{A})} = \sigma_{\max}(\underline{A})$$

$$\|A\|_p = \sup_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_p}$$

$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}| \quad (\text{max abs. col. sum}).$$

$$\|A\|_{\infty} = \max_{1 \leq i \leq m} \sum_{j=1}^n |a_{ij}| \quad (\text{max abs. row sum}).$$

$$\text{"entry-wise" } \|\underline{A}\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2} = \sqrt{\text{Tr}(\underline{A}^T \underline{A})} = \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2(\underline{A})}$$

$$\|\underline{A}\|_2 = \sigma_{\max}(\underline{A}) \leq \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2(\underline{A})} = \|\underline{A}\|_F$$

(Continue to bound  $T_2$ ).

$$T_2 \leq \sum_{j=1}^{k-1} \mathbb{E} \left[ \underbrace{\|\partial f(\underline{x}_j, \underline{z}_j) - \partial f(\underline{x}_j)\|_F^2}_{\leq N\sigma^2} \underbrace{\left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i \right\|^2}_{\leq \beta^{2(k-j-1)}} \right]$$

$$\leq N\sigma^2 \sum_{j=0}^{k-1} \underbrace{\beta^{2(k-j-1)}}_{k \text{ terms}} \leq \frac{N\sigma^2}{1-\beta^2}$$

Now, we bound  $T_3$ :

$$T_3 = \mathbb{E} \left[ \left\| \sum_{j=0}^{k-1} \partial f(\underline{x}_j) \left( \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i \right) \right\|^2 \right]$$

$$\stackrel{\text{expand}}{=} \sum_{j=0}^{k-1} \mathbb{E} \left[ \left\| \partial f(\underline{x}_j) \left( \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i \right) \right\|^2 \right] \quad T_4$$

$$+ \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \mathbb{E} \left[ \langle \partial f(\underline{x}_j) \left( \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i \right), \partial f(\underline{x}_{j'}) \left( \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j'-1} \underline{e}_i \right) \rangle \right] \quad T_5$$

To bound  $T_3$ , we need to further bound  $T_4$  &  $T_5$ .

$$T_4 = \sum_{j=0}^{k-1} \mathbb{E} \left[ \left\| \partial f(\underline{x}_j) \left( \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i \right) \right\|^2 \right]$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} \sum_{j=0}^{k-1} \mathbb{E} \left[ \left\| \partial f(\underline{x}_j) \right\|^2 \right] \left\| \frac{1}{N} \mathbf{1}_N - \underline{W}^{k-j-1} \underline{e}_i \right\|^2 \quad (2)$$

introduce a lemma.

$$\text{Lemma 1: } \mathbb{E}[\|\partial f(\bar{x}_j)\|^2] \leq \sum_{h=1}^N 3 \mathbb{E}\left[L^2 \|\bar{x}_j - x_{h,j}\|^2\right] + 3Ns^2 + 3\mathbb{E}\left[\|\nabla f(\bar{x}) \mathbf{1}_N^\top\|^2\right]$$

Proof:  $\mathbb{E}[\|\partial f(\bar{x}_j)\|^2] = \mathbb{E}\left[\|\partial f(\bar{x}_j) - \partial f(\bar{x}_j \mathbf{1}_N^\top) + \partial f(\bar{x}_j \mathbf{1}_N^\top)\|^2\right]$

$$= \mathbb{E}\left[\left\|\begin{matrix} \nabla f_1(\bar{x}_j) & \cdots & \nabla f_N(\bar{x}_j) \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_N} & & \end{matrix}\right\|_{\text{distr}}^2 - \nabla f(\bar{x}_j) \mathbf{1}_N^\top + \nabla f(\bar{x}_j) \mathbf{1}_N^\top\right]^2$$

$$= \mathbb{E}\left[\left\|\partial f(\bar{x}_j) - \partial f(\bar{x}_j \mathbf{1}_N^\top)\right\|^2\right] + \mathbb{E}\left[\left\|\partial f(\bar{x}_j \mathbf{1}_N^\top) - \nabla f(\bar{x}_j) \mathbf{1}_N^\top\right\|^2\right] + 3\mathbb{E}\left[\left\|\nabla f(\bar{x}_j) \mathbf{1}_N^\top\right\|^2\right]$$

$$\leq 3\mathbb{E}\left[\left\|\partial f(\bar{x}_j) - \partial f(\bar{x}_j \mathbf{1}_N^\top)\right\|_F^2\right] + 3\mathbb{E}\left[\left\|\partial f(\bar{x}_j \mathbf{1}_N^\top) - \nabla f(\bar{x}_j) \mathbf{1}_N^\top\right\|_F^2\right] + 3\mathbb{E}\left[\left\|\nabla f(\bar{x}_j) \mathbf{1}_N^\top\right\|^2\right]$$

$$= 3\mathbb{E}\left[\sum_{h=1}^N \left\|\nabla f_h(\bar{x}_j) - \nabla f_h(\bar{x}_j) \mathbf{1}_N^\top\right\|^2\right] + 3\mathbb{E}\left[\sum_{h=1}^N \left\|\nabla f_h(\bar{x}_j) - \nabla f(\bar{x}_j)\right\|^2\right] + 3\mathbb{E}\left[\left\|\nabla f(\bar{x}) \mathbf{1}_N^\top\right\|^2\right]$$

$$\leq L^2 \|\bar{x}_{h,j} - \bar{x}_j\|^2 \quad \text{non-i.i.d.}$$

$$\leq \sum_{h=1}^N 3\mathbb{E}\left[L^2 \|\bar{x}_{h,j} - \bar{x}_j\|^2\right] + 3Ns^2 + 3\mathbb{E}\left[\left\|\nabla f(\bar{x}_j) \mathbf{1}_N^\top\right\|^2\right]. \quad \blacksquare$$

(Continue on bounding  $T_4$ ): Using Lemma 1 in (2):

$$T_4 \leq \sum_{j=0}^{k-1} \sum_{h=1}^N 3\mathbb{E}\left[L^2 \|\bar{x}_{h,j} - \bar{x}_j\|^2\right] + 3Ns^2 + 3\mathbb{E}\left[\left\|\nabla f(\bar{x}_j) \mathbf{1}_N^\top\right\|^2\right] x.$$

$$\left\|\frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} \mathbb{E}_0\right\|^2 \leq \beta^{2(k-j-1)}$$

$$\leq \frac{3N\beta^2}{1-\beta^2} + \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[ L \left[ \underbrace{\mathbb{E}_{\tilde{x}_{h,j}}}_{Q_{h,j}} \left[ \|\tilde{x}_{h,j} - \bar{x}_j\|^2 \right] \right] \right] \left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right\|^2$$

$$+ \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[ \left\| \nabla f(\bar{x}_j) \mathbb{1}_N^\top \right\|^2 \right] \left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right\|^2 \quad (3)$$

Now, we bound  $T_5$ :

$$T_5 = \sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1} \mathbb{E} \left[ \langle \partial f(\bar{x}_j) \left( \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right), \partial f(\bar{x}_{j'}) \left( \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j'+1} e_i \right) \rangle \right]$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} \sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1} \mathbb{E} \left[ \left\| \partial f(\bar{x}_j) \left( \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right) \right\| \cdot \left\| \partial f(\bar{x}_{j'}) \left( \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j'+1} e_i \right) \right\| \right]$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} \sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1} \mathbb{E} \left[ \left\| \partial f(\bar{x}_j) \right\| \cdot \left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right\| \cdot \left\| \partial f(\bar{x}_{j'}) \right\| \cdot \left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j'+1} e_i \right\| \right]$$

$$\stackrel{\text{Young's}}{\leq} ab \leq \frac{1}{2} a^2 + \frac{1}{2} b^2 \sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1} \mathbb{E} \left[ \frac{1}{2} \left\| \partial f(\bar{x}_j) \right\|^2 \underbrace{\left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right\|}_{\leq \beta^{k-j+1}} \cdot \underbrace{\left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j'+1} e_i \right\|}_{\leq \beta^{k-j'+1}} \right]$$

$$+ \sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1} \mathbb{E} \left[ \frac{1}{2} \left\| \partial f(\bar{x}_{j'}) \right\|^2 \underbrace{\left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j+1} e_i \right\|}_{\leq \beta^{k-j+1}} \cdot \underbrace{\left\| \frac{1}{N} \mathbb{1}_N - \underline{W}^{k-j'+1} e_i \right\|}_{\leq \beta^{k-j'+1}} \right]$$

$$\leq \underbrace{\sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1}}_{k^2 \text{ terms}} \mathbb{E} \left[ \left( \frac{1}{2} \left\| \partial f(\bar{x}_j) \right\|^2 + \frac{1}{2} \left\| \partial f(\bar{x}_{j'}) \right\|^2 \right) \beta^{2(k - \frac{j+j'}{2} - 1)} \right]$$

$$= \sum_{j=0}^{k-1} \sum_{j'=0 \pm j}^{k-1} \mathbb{E} \left[ \underbrace{\left\| \partial f(\bar{x}_j) \right\|^2}_{\text{Lemma}} \beta^{2(k - \frac{j+j'}{2} - 1)} \right]$$

$$\begin{aligned}
&\leq \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \left[ \sum_{h=1}^N \mathbb{E} \left[ L^2 \| \bar{x}_{h,j} - \bar{x}_{j'} \|^2 \right] + 3N\delta^2 + 3 \mathbb{E} \left[ \| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \|^2 \right] \right] \times \\
&\quad \beta^{2(k-\frac{j+j'}{2}-1)} \\
&= \underbrace{\sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} 3N\delta^2 \beta^{2(k-\frac{j+j'}{2}-1)}}_{T_6} + \underbrace{3 \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \left[ \sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] + \mathbb{E} [\| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \|^2] \right]}_{T_7} \times \beta^{2(k-\frac{j+j'}{2}-1)}
\end{aligned}$$

Note  $T_6$  can be bounded as:

$$\begin{aligned}
T_6 &= \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} 3N\delta^2 \beta^{2(k-\frac{j+j'}{2}-1)} = 6N\delta^2 \sum_{j=0}^{k-1} \sum_{j'>j}^{k-1} \beta^{2(k-\frac{j+j'}{2}-1)} \\
&= 6N\delta^2 \sum_{j=0}^{k-1} \beta^{k-j-1} \sum_{j'>j}^{k-1} \beta^{k-j'-1} = 6N\delta^2 \sum_{j=0}^{k-1} \beta^{k-j-1} [1 + \beta + \dots + \beta^{k-j-2}] \\
&= 6N\delta^2 \sum_{j=0}^{k-1} \beta^{k-j-1} \frac{1-\beta^{k-j-1}}{1-\beta} = \frac{6N\delta^2}{1-\beta} \left[ \underbrace{\sum_{j=0}^{k-1} \beta^{k-j-1}}_{k \text{ terms.}} - \underbrace{\sum_{j=k}^{k-1} \beta^{2(k-j-1)}}_{k \text{ terms.}} \right] \\
&= \frac{6N\delta^2}{1-\beta} \left[ \frac{1-\beta^k}{1-\beta} - \frac{1-\beta^{2k}}{1-\beta^2} \right] \stackrel{\leq 1}{=} 6N\delta^2 \frac{(1-\beta^k)(\beta-\beta^k)}{(1-\beta)^2(1+\beta)} \stackrel{\leq 1}{>} \frac{6N\delta^2}{(1-\beta)^2}
\end{aligned}$$

Now, we bound  $T_7$ .

$$\begin{aligned}
T_7 &= 3 \sum_{j=0}^{k-1} \sum_{j'=0 \neq j}^{k-1} \left[ \sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] + \mathbb{E} [\| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \|^2] \right] \beta^{2(k-\frac{j+j'}{2}-1)} \\
&= 6 \sum_{j=0}^{k-1} \left[ \sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] + \mathbb{E} [\| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \|^2] \right] \underbrace{\sum_{j'=j+1}^{k-1} \beta^{2(k-\frac{j+j'}{2}-1)}}_{k-j-1 \text{ terms.}}
\end{aligned}$$

$$\leq 6 \sum_{j=0}^{k-1} \left[ \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] + \mathbb{E}\left[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2\right] \right] \frac{\beta^{k-j-1}}{1-\beta}$$

Plug  $T_6, T_7$  into  $T_5$ , and then plugging  $T_5 & T_4$  into  $T_3$  yields:

$$T_3 \leq 3 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] \left\| \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} \mathbf{e}_0 \right\|^2$$

$$+ 3 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}\left[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2\right] \left\| \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} \mathbf{e}_0 \right\|^2$$

$$+ 6 \sum_{j=0}^{k-1} \left[ \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] + \mathbb{E}\left[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2\right] \right] \frac{\beta^{k-j-1}}{1-\beta}$$

$$+ \boxed{\frac{3Ns^2}{1-\beta^2} + \frac{6Ns^2}{(1-\beta)^2}} \leq \frac{9Ns^2}{(1-\beta)^2}$$

$(1-\beta)(1+\beta) \geq (1-\beta)^2$

Putting the bounds for  $T_2 & T_3$  back to  $Q_{i,k}$ :

$$Q_{i,k} \leq \underbrace{\frac{2s^2 N \beta^2}{1-\beta^2}}_{\leq 2s^2 T_2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] \left\| \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} \mathbf{e}_0 \right\|^2$$

$$+ 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}\left[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2\right] \left\| \frac{1}{N} \mathbf{1}_N - \mathbb{W}^{k-j-1} \mathbf{e}_0 \right\|^2$$

$$+ 12s^2 \sum_{j=0}^{k-1} \left[ \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] + \mathbb{E}\left[\|\nabla f(\bar{x}_j) \mathbf{1}_N\|^2\right] \right] \frac{\beta^{k-j-1}}{1-\beta} + \frac{18s^2 N \beta^2}{(1-\beta)^2}$$

$$\leq \frac{2s^2 N \beta^2}{1-\beta^2} + \frac{18s^2 N \beta^2}{(1-\beta)^2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}[L^2 Q_{h,j}] \beta^{2(k-j-1)}$$

$$+ 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[ \left\| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \right\|^2 \right] \beta^{2(k-j-1)}$$

$$+ 12s^2 \sum_{j=0}^{k-1} \left[ \sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] + \mathbb{E} \left[ \left\| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \right\|^2 \right] \right] \frac{\beta^{k-j-1}}{1-\beta}$$

$$= \frac{2s^2 N \delta^2}{1-\beta^2} + \frac{(8s^2 N)^2}{(1-\beta)^2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} [L^2 Q_{h,j}] \left( \beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta} \right)$$

$$+ 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E} \left[ \left\| \nabla f(\bar{x}_j) \mathbf{1}_N^\top \right\|^2 \right] \left( \beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta} \right).$$

$$\text{Thus: } T_1 \leq \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} \left[ \left\| \bar{x}_k - x_{i,k} \right\|^2 \right] = \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} [Q_{i,k}]$$

Recall:

$$\begin{aligned} \mathbb{E} [f(\bar{x}_{k+1})] &\leq \mathbb{E} [f(\bar{x}_k)] - \frac{s-s^2 L}{2} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right] \\ &\quad - \frac{s}{2} \mathbb{E} \left[ \left\| \nabla f(\bar{x}_k) \right\|^2 \right] + \frac{s^2 L \delta^2}{2N} + \frac{s}{2} \mathbb{E} [T_1] \end{aligned} \quad (4)$$

Summing  $k=0, \dots, k-1$  yields:

$$\begin{aligned} &\frac{s-s^2 L}{2} \sum_{k=0}^{k-1} \mathbb{E} \left[ \left\| \frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k}) \right\|^2 \right] + \frac{s}{2} \sum_{k=0}^{k-1} \mathbb{E} \left[ \left\| \nabla f(\bar{x}_k) \right\|^2 \right] \\ &\leq f(0) - f^* + \sum_{k=0}^{k-1} \frac{s^2 L \delta^2}{2N} + \frac{s}{2} \sum_{k=0}^{k-1} \mathbb{E} [T_1] \\ &\leq \frac{L^2}{N} \sum_{i=1}^N \mathbb{E} [Q_{i,k}] = L^2 \mathbb{E} [M_k] \end{aligned}$$

$M_k \triangleq \frac{1}{N} \sum_{i=1}^N Q_{i,k}$ .

Now, need to bnd  $\mathbb{E}[M_k]$ :

$$\mathbb{E}[M_k] = \frac{1}{N} \mathbb{E}\left[\sum_{i=1}^N Q_{i,k}\right]$$

$$\leq \frac{2s^2N\sigma^2}{1-\beta^2} + \frac{(8s^2N)^2}{(1-\beta)^2} + 6s^2 \sum_{j=0}^{k-1} \sum_{h=1}^N \mathbb{E}\left[\|\nabla f(\bar{x}_j) \mathbf{1}_N^\top\|^2\right] \times \\ \left(\beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta}\right).$$

$$+ 6s^2NL \sum_{j=0}^{k-1} \mathbb{E}[M_j] \left(\beta^{2(k-j-1)} + \frac{2\beta^{k-j-1}}{1-\beta}\right)$$

Summing the above from  $k=0$  to  $k-1$ , and rearranging:

$$\sum_{k=0}^{k-1} \mathbb{E}[M_k] \leq \frac{2s^2N\sigma^2}{(1-\beta^2)\left(1 - \frac{(8s^2NL)^2}{(1-\beta)^2}\right)} k + \frac{18s^2N\sigma^2}{(1-\beta)^2\left(1 - \frac{(8s^2NL)^2}{(1-\beta)^2}\right)} k \\ + \frac{(8s^2N)}{(1-\beta)^2\left(1 - \frac{(8s^2NL)^2}{(1-\beta)^2}\right)} \sum_{k=0}^{k-1} \mathbb{E}\left[\|\nabla f(\bar{x}_k)\|^2\right] \quad (5)$$

Plugging (5) into (4), we have:

$$\frac{s-s^2L}{2} \sum_{k=0}^{k-1} \mathbb{E}\left[\left\|\frac{1}{N} \sum_{i=1}^N \nabla f_i(\bar{x}_{i,k})\right\|^2\right] + \frac{s}{2} \sum_{k=1}^{k-1} \mathbb{E}\left[\|\nabla f(\bar{x}_k)\|^2\right] \\ \leq f(\mathbf{0}) - f^* + \frac{s^2KL\sigma^2}{2N} + \frac{s^3L^2N\sigma^2}{(1-\beta^2)D_2} + \frac{9Ns^3L^2}{(1-\beta)^2 D_2} \\ + \frac{9Ns^3L^2}{(1-\beta)^2 D_2} \sum_{k=0}^{k-1} \mathbb{E}\left[\|\nabla f(\bar{x}_k)\|^2\right] \quad \text{and defining } D_1 = \frac{1}{2} - \frac{9s^2L^2N}{(1-\beta)^2 D_2}$$

Rearranging & dividing both sides by  $sK$ , arrives at stated result. 

$$\left(\frac{1}{L}, \frac{2}{L}\right)$$

Proof of Corollary 2. If  $s = \frac{1}{2L + \sigma\sqrt{K/N}} < \frac{1}{L}$ , then  $\frac{1-sL}{2} > 0$

Dropping the term associated w/  $\left\| \nabla \sum_{i=1}^N \nabla f(x_i, k) \right\|^2$ , we have:

$$\begin{aligned} \frac{D_1}{K} \sum_{k=1}^{K-1} \mathbb{E} [\|\nabla f(\bar{x}_k)\|^2] &\leq \frac{\gamma(f(0) - f^*)L}{K} + \frac{(f(0) - f^*)\sigma}{\sqrt{KN}} + \frac{L\sigma^2}{4NL + 2\sigma\sqrt{KN}} \\ &\quad + \frac{L^2 N}{(2L + \sigma\sqrt{K/N})^2 D_2} \left( \frac{\sigma^2}{1-\beta^2} + \frac{9S^2}{(1-\beta)^2} \right) \\ &\leq \frac{\gamma(f(0) - f^*)L}{K} + \frac{(f(0) - f^* + 4/2)\sigma}{\sqrt{KN}} + \frac{L^2 N}{(\sigma\sqrt{K/N})^2 D_2} \left( \frac{\sigma^2}{1-\beta^2} + \frac{9S^2}{(1-\beta)^2} \right) \end{aligned} \tag{6}$$

$$\text{Recall } D_1 = \frac{1}{2} - \frac{9S^2 L^2 N}{(1-\beta)^2 D_2}, \quad D_2 = 1 - \frac{18s^2}{(1-\beta)^2} NL^2$$

$$\left. \begin{array}{l} \text{If } s^2 \leq \frac{(1-\beta)^2}{36NL^2} \Rightarrow D_2 \geq \frac{1}{2}, \quad s^2 \leq \frac{(1-\beta)^2}{72NL^2} \Rightarrow D_1 \geq \frac{1}{4}. \end{array} \right\} \Rightarrow$$

$$\text{Since } s = \frac{1}{2L + \sigma\sqrt{K/N}} \leq \frac{1}{\sigma\sqrt{K/N}} \Rightarrow s^2 \leq \frac{N}{\sigma^2 K}$$

$$\text{If } \frac{N}{\sigma^2 K} \leq \min \left\{ \frac{(1-\beta)^2}{36NL^2}, \frac{(1-\beta)^2}{72NL^2} \right\}, \text{ then } D_2 \geq \frac{1}{2}, D_1 \geq \frac{1}{4}.$$

Now, replacing  $D_1$  &  $D_2$  by  $\frac{1}{4}$  &  $\frac{1}{2}$ , resp., in (6):

$$\begin{aligned} \frac{1}{4K} \sum_{k=0}^{K-1} \mathbb{E} [\|\nabla f(\bar{x}_k)\|^2] &\leq \frac{\gamma(f(0) - f^*)L}{K} + \frac{(f(0) - f^* + 4/2)\sigma}{\sqrt{KN}} \\ &\quad + \frac{2L^2 N}{(\sigma\sqrt{K/N})^2} \left( \frac{\sigma^2}{1-\beta^2} + \frac{9S^2}{(1-\beta)^2} \right) \\ &\leq \frac{(4f(0) - 4f^* + 2L)\sigma}{\sqrt{KN}} \quad \text{if (A) is true} \end{aligned}$$

combine these  
two yields  
the stated  
result.



Proof of Thm 3: With  $s = \frac{1}{2L + \sigma\sqrt{K/N}}$ , we have from (5):

$$\begin{aligned} \frac{1}{K} \sum_{k=0}^{K-1} \mathbb{E}[M_k] &\leq \frac{2s^2 N \sigma^2}{(1-\beta)^2 D_2} + \frac{18s^2 N \sigma^2}{(1-\beta)^2 D_2} \\ &\quad + \frac{(8s^2 N)^2}{(1-\beta)^2 D_2 K} \sum_{k=0}^{K-1} \mathbb{E}[\|\nabla f(\bar{x}_k)\|^2] \end{aligned} \quad (5)$$

avg agent  
drift.

Corollary

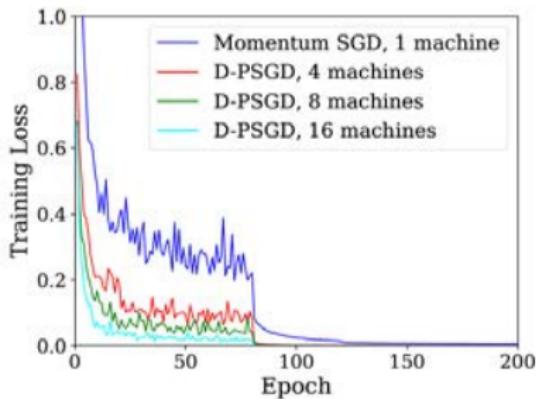
$$\begin{aligned} &\leq \frac{2s^2 N \sigma^2}{(1-\beta)^2 D_2} + \frac{18s^2 N \sigma^2}{(1-\beta)^2 D_2} + \frac{s^2 L^2 N}{D_1 D_2} \left( \frac{\sigma^2}{1-\beta^2} + \frac{9\sigma^2}{(1-\beta)^2} \right) + \frac{(8s^2 N)^2}{(1-\beta)^2 D_2} \left( \frac{f(x)^* - s^2 D^2}{s^2 k} + \frac{s^2 D^2}{2N D_1} \right) \\ &\triangleq N s^2 \frac{A}{D_2} \end{aligned}$$

. 

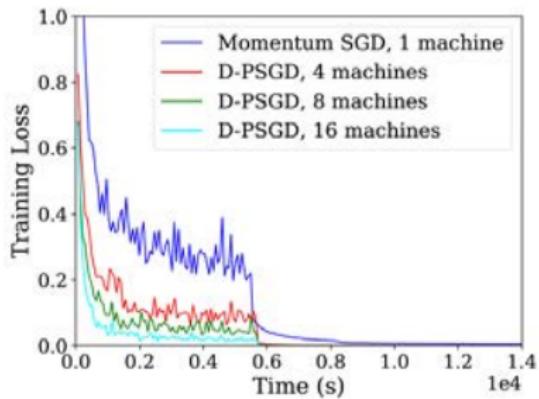
# Numerical Results of DSGD

- Linear Speedup Effect

- ▶ 32-layer residual network and CIFAR-10 dataset
- ▶ Up to 16 machines; each machine includes two Xeon E5-2680 8-core processors and a NVIDIA K20 GPU



(a) Iteration vs Training Loss



(b) Time vs Training Loss

# A “Tug of War” in DSGD

Revisit the DSGD algorithm:

- The algorithmic update at each agent is:

$$\mathbf{x}_{i,k+1} = \underbrace{\sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k}}_{\text{Avg consensus step}} - \underbrace{s_k \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k})}_{\text{Local SGD step}},$$

where  $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$ .

The average consensus step and the local SGD step “conflict” with each other.  
Can we do better?

# The Gradient Tracking Idea

[Lorenzo-Scatari, TSPN'16]  
"full grad":

Gradient-Tracking DSGD: [Lu et al., DSW'19]:

- ① Initialization: Let  $k = 1$ . Choose initial values for  $\mathbf{x}_{i,1}$  and step-size  $s_1$ . Define an auxiliary variable  $\mathbf{y}_{i,k}$  with  $\mathbf{y}_{i,1} = \nabla F_i(\mathbf{x}_{i,1}, \xi_{i,1})$ .
- ② In  $k$ -th iteration: Each node sends its local copy to its neighbors.
- ③ Upon reception of all local copies from its neighbors, each node updates its local copy:  
*and  $\mathbf{y}_{i,k}$*

$$\mathbf{x}_{i,k+1} = \sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{x}_{j,k} - s_k \mathbf{y}_{i,k},$$

$$\mathbf{y}_{i,k+1} = \sum_{j \in \mathcal{N}_i} [\mathbf{W}]_{ij} \mathbf{y}_{j,k} + \nabla F_i(\mathbf{x}_{i,k+1}, \xi_{i,k+1}) - \nabla F_i(\mathbf{x}_{i,k}, \xi_{i,k}).$$

*tracking avg stochastic grad.*

where  $\mathcal{N}_i \triangleq \{j \in \mathcal{N} : (i, j) \in \mathcal{L}\}$ .

- ④ Let  $k \leftarrow k + 1$  and go to Step 2

Notation:

$$\underline{\underline{x}}_k = \begin{bmatrix} \underline{x}_{1,k} & \cdots & \underline{x}_{N,k} \end{bmatrix}_{dxN}, \quad \underline{\underline{y}}_k = \begin{bmatrix} \underline{y}_{1,k} & \cdots & \underline{y}_{N,k} \end{bmatrix}_{dxN},$$

$$\underline{\underline{\delta F}}(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k) = \begin{bmatrix} \nabla F_1(\underline{x}_{1,k}, \xi_{1,k}) & \cdots & \nabla F_N(\underline{x}_{N,k}, \xi_{N,k}) \end{bmatrix}_{dxN}.$$

$$\bar{x}_k = \frac{1}{N} \sum_{i=1}^N \underline{x}_{i,k}, \quad \bar{y}_k = \frac{1}{N} \sum_{i=1}^N \underline{y}_{i,k}.$$

In matrix form:

$$\begin{cases} \underline{\underline{x}}_{k+1} = \underline{\underline{x}}_k \underline{\underline{W}} - s_k \underline{\underline{Y}}_k \\ \underline{\underline{Y}}_{k+1} = \underline{\underline{Y}}_k \underline{\underline{W}} + \underline{\underline{\delta F}}(\underline{\underline{x}}_{k+1}, \underline{\underline{\xi}}_{k+1}) - \underline{\underline{\delta F}}(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k). \end{cases}$$

Right multiply both eqns by  $\frac{1}{N} \underline{\underline{1}}_N$ :

$$\Rightarrow \begin{cases} \frac{1}{N} \underline{\underline{x}}_{k+1} \underline{\underline{1}}_N = \frac{1}{N} \underline{\underline{x}}_k \underline{\underline{W}} \underline{\underline{1}}_N - \frac{s_k}{N} \underline{\underline{Y}}_k \underline{\underline{1}}_N \\ \frac{1}{N} \underline{\underline{Y}}_{k+1} \underline{\underline{1}}_N = \frac{1}{N} \underline{\underline{Y}}_k \underline{\underline{W}} \underline{\underline{1}}_N + \frac{1}{N} \underline{\underline{\delta F}}(\underline{\underline{x}}_{k+1}, \underline{\underline{\xi}}_{k+1}) \underline{\underline{1}}_N - \frac{1}{N} \underline{\underline{\delta F}}(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k) \underline{\underline{1}}_N \end{cases}$$

$$\Rightarrow \begin{cases} \bar{x}_{k+1} = \bar{x}_k - s_k \bar{y}_k & \text{(1)} \\ \bar{y}_{k+1} = \bar{y}_k + \frac{1}{N} \sum_{i=1}^N \nabla F_i(\underline{\underline{x}}_{k+1}, \underline{\underline{\xi}}_{k+1}) - \frac{1}{N} \sum_{i=1}^N \nabla F_i(\underline{\underline{x}}_k, \underline{\underline{\xi}}_k) & \text{(2)} \end{cases}$$

From (2), by recursion on  $\bar{y}_k$ :

$$\bar{y}_{k+1} = \frac{1}{N} \sum_{i=1}^N \nabla F_i(\underline{\underline{x}}_{k+1}, \underline{\underline{\xi}}_{k+1}). \quad \text{From (1):}$$

$$\bar{x}_{k+1} = \bar{x}_k - \frac{s_k}{N} \sum_{i=1}^N \nabla F_i(\underline{\underline{x}}_{i,k}, \underline{\underline{\xi}}_{i,k}).$$

Exactly the same as  
DSGD.

# Convergence Results for GT-DSGD

$$\underline{A} \in \mathbb{R}^{m \times n}, \underline{B} \in \mathbb{R}^{n \times p}$$

$$\underline{A} \otimes \underline{B} = \begin{bmatrix} a_{11} \underline{B} & \cdots & a_{1n} \underline{B} \\ \vdots & & \vdots \\ a_{m1} \underline{B} & \cdots & a_{mn} \underline{B} \end{bmatrix} \in \mathbb{R}^{mp \times nq}$$

- Define  $P^k \triangleq \mathbb{E}[f(\bar{\mathbf{x}}_k)] + \mathbb{E}[\|\mathbf{x}_k - \mathbf{1}_N \otimes \bar{\mathbf{x}}_k\|^2] + Q\mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|^2]$

## Theorem 4 (Convergence of Agent-Average [Lu et al. DSW'19])

If the step-size is set to  $\frac{C_0}{\sqrt{T}}$ , then it holds that:

Kronecker product

$$C_1 \mathbb{E}[\|\bar{\mathbf{y}}_k\|^2] + \frac{C_2}{C_0} \mathbb{E}[\|\mathbf{x}_t - \mathbf{1}_N \otimes \bar{\mathbf{x}}_t\|^2] \leq \left( \frac{P^0 - P^*}{C_0} + C_4 C_0 \sigma^2 \right) \frac{1}{\sqrt{T}}$$

$$\begin{bmatrix} \underline{\mathbf{x}}_{1,t} \\ \vdots \\ \underline{\mathbf{x}}_{N,t} \end{bmatrix} \quad \begin{bmatrix} \bar{\mathbf{x}}_t \\ \vdots \\ \bar{\mathbf{x}}_T \end{bmatrix}$$

[Zhang, Liu, Zhu, Bentley Infocom'19]

$O(\frac{1}{T})$ .

$\sim \sim \sim \sim \sim$  ~, Mobility [20]

[Liu, Zhang, Liu, Lu, Neogi PS'21], "MARL", "single-loop",  $O(\frac{1}{T})$

# Convergence Results for GT-GSGD

Theorem 5 (Contraction of Consensus Gap [Lu et al. DSW'19])

Let  $\rho$  be some constant such that  $(1 + \rho)\beta^2 < 1$ . It holds that:

$$\mathbb{E}[\|\mathbf{x}_{k+1} - \mathbf{1}_N \otimes \bar{\mathbf{x}}_{k+1}\|] \leq (1 + \rho)\beta^2 \mathbb{E}[\|\mathbf{x}_k - \mathbf{1}_N \otimes \bar{\mathbf{x}}_k\|^2]$$

$$+ 3 \left(1 + \frac{1}{\rho}\right) s^2 \mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|^2] + 6 \left(1 + \frac{1}{\rho}\right) s^2 \kappa \sigma^2,$$

$$\mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|] \leq \frac{4L^2 s^2}{N} \left(1 + \frac{1}{\beta}\right)^2 \|\bar{\mathbf{y}}_k\|^2$$

$$+ \left(\frac{L^2}{N^2} \beta^2 (1 + \rho) \left(1 + \frac{1}{\rho}\right) + \frac{4L^2}{N^2} \left(1 + \frac{1}{\rho}\right)^2\right) \mathbb{E}[\|\mathbf{x}_k - \mathbf{1}_N \otimes \bar{\mathbf{x}}_k\|^2]$$

$$+ \left((1 + \rho)\beta^2 + \frac{4L^2 s^2}{N^2} \left(1 + \frac{1}{\rho}\right)^2\right) \mathbb{E}[\|\mathbf{y}_k - \mathbf{1}_N \otimes \bar{\mathbf{y}}_k\|^2]$$

$$\frac{4L^2 s^2}{N^2} \left(1 + \frac{1}{\rho}\right)^2 \kappa \sigma^2.$$

## Next Class

### Zeroth-Order Methods