Planning.Domains

Christian Muise · cjmuise@mit.edu · www.haz.ca · MIT

API.PLANNING.DOMAINS

v0.2

General guery path for GET and POST requests (API PATH):

GET api.planning.domains/:format/classical

: format can be **xml** or **json**. General JSON response format:

```
{ "error": False,
   "message": "Success!",
   "result": ... }
```

Get incumbent plan:

GET API_PATH/plan/{prob-id}

Submit new plan with parameters:

POST API_PATH/submitplan/{prob-id}

plan String of IPC-style plan

email User email (for the glory!)

Collections

Collections represent a set of domains.

Collection Object Attributes

collection_id Unique ID

collection_name Name of the collection

description Short description domain set List of domain ID's

tags List of tags

Get a list of all collections:

GET API PATH/collections

Get a particular collection:

GET API_PATH/collection/{col-id}

Search using the following attributes:

GET API_PATH/collections/search?opt1=val1&opt2=val2

collection_name Name to match the collection on

ags Comma separated tag list

Domains

Domains represent a set of problems.

Domain Object Attributes

domain_id Unique ID

domain_name Name of the collection

description Description of domain origin

tags List of tags

Get a list of all domains:

GET API_PATH/domains

Get a list of all domains in a collection:

GET API_PATH/domains/{col-id}

Get a particular domain:

GET API_PATH/domain/{dom-id}

Search using the following attributes:

GET API_PATH/domains/search?opt1=val1&opt2=val2

domain_name Name to match the domain on tags Comma separated tag list

Problems

Problems represent a domain / problem PDDL pair

Problem Object Attributes

ID of this problem problem_id domain id ID of this problem's domain domain Name of the domain for this problem Name of problem (e.g., prob1.pddl) problem domain url Remote location of the domain file Remote location of the problem file problme_url Relative path to the domain file domain path Relative path to the problem file problem_path List of tags for the problem

Additionally, the following statistics are included in a problem object, with _description appended for more info:

upper_bound Upper bound on the optimal plan
lower_bound Lower bound on the optimal plan
Lower bound on the optimal plan
Average classical planning width
Maximum classical planning width

Get a list of all problems:

GET API_PATH/problems

Get a list of all problems in a domain:

GET API_PATH/problems/{dom-id}

Get a particular problem:

GET API_PATH/problem/{prob-id}

Search using the following attributes:

GET API_PATH/problems/search?opt1=val1&opt2=val2

Matches a given domain id domain domain name Matches on the domain name Matches on the problem name problem name Set the average width average_effective_width max effective width Set the max width Floor on the lower bound min_lower_bound Ceiling on the lower bound max lower bound Floor on the upper bound min_upper_bound Ceiling on the upper bound max_upper_bound Comma separated tag list (=[0,1]) Problems with open openbounds or closed lower/upper bounds

As an example, the following finds all problems with an maximum width of 1 (i.e., "easy" to find a solution for), and also have open bounds (i.e., "hard" to prove optimality for):

http://api.planning.domains/json/classical/problems/ search?max_effective_width=1&openbounds=1

SOLVER.PLANNING.DOMAINS

The solver can be used to compute plans for classical problems through a JSON interface. Simple tests can also be done by going to the following URL with appropriate paths:

http://solver.planning.domains/solve
 ?domain=<domain url>&problem=<prob url>

General JSON POST queries:

POST solver.planning.domains/solve
POST solver.planning.domains/validate
POST solver.planning.domains/solve-and-validate

JSON Query Parameters

```
domain

problem

probID

is_url

plan

Either URL or raw PDDL for domain

Either URL or raw PDDL for problem

API ID to supersede domain and problem

Set to true if using URLs

IPC format plan (just for /validate)
```

Depending on the endpoint, various attributes will be returned. If a plan was computed, the service will attempt to produce a grounding of all plan actions. The returned object will have status set to either **ok** or **error** and result set to either an error message or an object using the following attributes:

Solved Object Attributes

```
length Number of actions
      output
                Planner output
               Status of the plan parsing (e.g., ok)
parse_status
                Either simple or full
        cost
               Total plan cost
               VAL standard output
  val stdout
  val stderr VAL standard error
  val status
               Either valid or err
               Indication of any VAL error
       error
        plan List of action objects which are
                just action names (if type is simple)
                or objects with attributes name and
                action (the latter being a string for
                the ground action)
```

EDITOR.PLANNING.DOMAINS (PLUGINS)

Plugins can be loaded dynamically using only a URL.

```
Anatomy of a Plugin (JavaScript file)
define (function () {
  return {
    name: "Plan-o-matic 1000",
    author: "John Smith",
    email: "yeah@right.com",
    description: "A plugin template.",
    // Called when loaded or enabled
    initialize: function() { },
    // Called when disabled
    disable: function() { },
    // Used to save settings
    save: function() { return {}; },
    // Restore any previous settings
    load: function(settings) { }
  };
});
```

Menu Interface

Used to modify the top menu bar

```
window.add menu(name, id, icon);
              Name for the menu
              HTML ID for later reference
              Bootstrap glyphicon string<sup>1</sup>
       icon
 window.add menu button( /*args*/ );
              Name for the menu
       name
              HTML id for later reference
              Bootstrap glyphicon string<sup>1</sup>
       icon
              String of function call (no "permitted)
  cb_string
              (optional) ID for parent menu
parent menu
 window.remove menu or button(id);
         id HTML ID for menu or button
```

Collection of Plugins

A meta plugin can be used to load other (meta or standard) plugins, along with predefined plugin-specific settings.

Generate code snippets for the editor:

```
window.add_snippet(snippet, trigger);
snippet Cloud9 style snippet<sup>2</sup>
trigger Text to trigger the auto-complete
```

Create new tabs for custom views:

```
window.new_tab(name, callback);
name Name for the new tab
callback Function that is called with the new view's
HTML ID (shown when tab is selected)
```

Inject custom CSS styling:

```
window.inject_styles(css_style);
css_style String of CSS to be included
```

^{1:} http://getbootstrap.com/components/#glyphicons
2: https://cloud9-sdk.readme.io/docs/snippets