Pricing American Options using Monte Carlo Method



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Abstract

This thesis reviewed a number of Monte Carlo based methods for pricing American options. The least-squares regression based Longstaff-Schwartz method (LSM) for approximating lower bounds of option values and the Duality approach through martingales for estimating the upper bounds of option values were implemented with simple examples of American put options. The effectiveness of these techniques and the dependencies on various simulation parameters were tested and discussed. A computing saving technique was suggested to reduce the computational complexity by constructing regression basis functions which are orthogonal to each other with respect to the natural distribution of the underlying asset price. The orthogonality was achieved by using Hermite polynomials. The technique was tested for both the LSM approach and the Duality approach. At the last, the Multilevel Mote Carlo (MLMC) technique was employed with pricing American options and the effects on variance reduction were discussed. A smoothing technique using artificial probability weighted payoff functions jointly with Brownian Bridge interpolations was proposed to improve the Multilevel Monte Carlo performances for pricing American options.

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Chapter 1

Introduction

American options are widely studied in mathematical finance. As simple examples, an American call/put option written on an underlying asset with strike K and maturity T gives the option holder the right to buy/sell the underlying asset at price of K at any time up to the maturity T. Since the investors can choose an optimal time to exercise the option, the valuations of American type options are relatively more complex than pricing European options, which only can be exercised on maturity and are typically valued using the well-known Black Scholes model^[1] under the arguments of no-arbitrage and perfect hedging by trading the underlying assets.

The value of an American option is the value achieved by exercising optimally. Pricing an American option is essentially an equivalence to a problem of solving an optimal stopping problem by defining the optimal exercise rule. The value of an American option is thus calculated by computing the expected discounted payoff under this rule. It is widely acknowledged that an analytical formula does not exist for the value of an American option. Thus as a result, the valuations of American options mostly rely on numerical simulations and the optimization procedure embedded in the problem makes this a challenge. Simple American type derivatives can be solved by the Finite Difference Method^[2] (FDM) by stating the problem as a Black-Scholes type PDE with free boundaries associated with the early exercise feature. The penalty method^[3] is one of the most popular techniques of pricing American options using FDM. The main drawback of Finite Difference Methods is the restriction to dimensions as the computational cost rapidly increases with the dimensions of the underlying (number of the underlying assets). In the recent years, Monte Carlo based methods^[4] have been intensively developed to overcome the current existing problems with FDM based approaches. These Monte Carlo based methods can be roughly divided into two groups. The first group directly employs a recursive scheme for solving the optimal stopping problem by using backward dynamic programming principle. Different techniques are applied to approximate the nested conditional expectations. The least-squares regression method of Longstaff and Schwartz^{[5][6]} is one of the most popular approaches in this group and has attracted the most interests recently. This method uses simple linear regressions through known basis functions of the current state of underlying asset price to approximate conditional expectations and thus in turn to estimate a lower bound of the value of an American option following a sub-optimal exercise rule. This is what is called the primal approach. The second group comes from the Duality approach developed by Rogers^[7] and independently by Haugh and Kogan^[8]. The approach was implemented by Andersen and Broadie^[9]. The basic idea of this dual approach is to represent the price of an American option through a minimization problem, leading to a high-biased approximation and thus providing upper bounds on prices. The lower bounds provided by the least-squares regression based primal approach and the upper bounds provided by the dual approach contain the true price. Recently, a very interesting extension was presented by Belomestny and Schoenmakers^[10]. These authors combined Andersen and Broadie's algorithm^[9] with Multilevel Monte Carlo Method (MLMC), developed by Mike Giles^[11].

This thesis presents a review of above mentioned Monte Carlo based algorithms for pricing American options and provides implementations with simple examples of American put options. The purpose of the study is to test the effectiveness of these techniques and the dependencies on various simulation parameters. A potentially promising computing saving technique using orthogonal Hermite polynomials is suggested and tested. The Multilevel Mote Carlo method is employed with the algorithms and the effects on variance reduction are discussed. A smoothing technique using artificial probability weighted payoff functions jointly with Brownian Bridge interpolations is proposed to improve the Multilevel Monte Carlo performances for pricing American options. The thesis is organized in the following way.

Chapter 2 reviews the basic theoretical results of the valuation problems of American options. The basic problem formulations based on dynamic programming principle are derived.

Chapter 3 provides an introduction to the least-squares regression based Longstaff-Schwartz method (LSM) for approximating lower bounds of the prices of American options. The algorithms are tested using simple examples of an American put option written on single non-dividend paying stock. The dependencies on the number of Monte Carlo paths and the number of time steps (exercise opportunities) are discussed.

Chapter 4 reviews and implements the Duality approach for estimating the upper bounds of the prices of American options through a martingale technique using approximated value functions and nested Monte Carlo simulations. Various effects of the simulation parameters are discussed.

Chapter 5 suggests a computing saving technique for pricing American options. The technique aims to reduce the computational complexity by constructing regression basis functions which are orthogonal to each other with respect to the natural distribution of the underlying asset price. The orthogonality is achieved by using Hermite polynomials. The technique is tested for the both algorithms of the primal LSM approach and the Duality approach.

Chapter 6 employs the Multilevel Monte Carlo (MLMC) towards the mentioned methods and the effects on variance reduction for both the primal and the dual approaches are tested. A smoothing technique using artificial probability weighted payoff functions and Brownian Bridge interpolations is suggested to improve MLMC performances with the lower bounds estimations through LSM algorithm.

Chapter 2

American Options: the Problem Formulations

By definition, an American option is a derivative written on an underlying asset which can be exercised any time up to its maturity. The discretized version of American option, which is also called Bermudan option, is an American style derivative that can be exercised only on pre-specified dates up to maturity. The value of an American option is the maximum value which can be achieved by optimal exercising. This value can be estimated by defining an optimal exercising rule on the option and computing the expected discounted payoff of the option under this rule. This chapter presents the basic formulations of the valuation of American options.

2.1 American Options

In contrast to an European option, which can only be exercised at maturity T, an American option can be exercised at any time $t \in (0,T]$ although it is usually not exercisable at time 0. For the continuous time case, if we denote the payoff of an American option at any time $t \in (0,T]$ as

$$\tilde{h}(t) = \tilde{h}(S_t, t) \tag{2.1}$$

where S_t is the price process of underlying asset, which is assumed to be a Markovian process, and given a class of admissible stopping times \mathcal{T}_t , which takes values in [t, T] $(t \in [0, T])$, the American option pricing problem can be formulated as^[4]

$$V_0 = \sup_{\tau \in \mathcal{T}_0} \mathbb{E}\left[e^{-\int_0^\tau r(u)\,\mathrm{d}u}\tilde{h}(S_\tau, \tau)\right]$$
(2.2)

where V_0 is the value of option at time t=0, $\{r(t), 0 \le t \le T\}$ is the instantaneous interest rate process and the expectation is taken under the equivalent martingale measure. With this formulation of price for American options, the general no-arbitrage principle holds^[12]. We can also absorb the discount factor $e^{-\int_0^t r(u) du}$ into the payoff function $\tilde{h}(S_t, t)$, and rewrite (2.2) as

$$V_0 = \sup_{\tau \in \mathcal{T}_0} \mathbb{E}\left[h(S_\tau, \tau)\right] \tag{2.3}$$

where $h(S_t, t) = e^{-\int_0^t r(u) du} \tilde{h}(S_t, t)$ is the discounted payoff. Also, if the price process S_t is Markovian, it is natural to assume the class of admissible stopping times $\mathcal{T}_t = \mathcal{T}(S_t)$ depends only on the current state of the price process, i.e., investors can make an exercise decision at time t based on the price process state S_t .

As the simplest example, an American put option written on a single underlying asset S_t with strike K and maturity T gives the option holder the right to sell the underlying asset at price K at any time up to the maturity T. Assume the asset price S_t follows a general geometric Brownian motion process given by

$$dS_t = (r - q)S_t dt + \sigma S_t dW_t$$
(2.4)

where r and q are interest rate and dividend rate respectively, which are assumed to be constants, σ is the volatility and W_t is a standard Brownian motion process. The value of American put option at t = 0 is then given by

$$V_0 = \sup_{\tau \in \mathcal{T}_0} \mathbb{E}\left[e^{-r\tau} \left(K - S_\tau\right)^+\right]$$
(2.5)

Figure 2.1 shows an example of an American put option written on a non-dividends paying stock with strike K=100, interest rate r=5%, volatility $\sigma=0.5$ and maturity T=5 respectively. The value of American option is compared with that of the corresponding European option. The values of American option are calculated using Finite Difference Method (FDM) based penalty approach^[3] and the values of European option are calculated using Black-Scholes formula^[1].

Strictly speaking, an American option is continuously exercisable, i.e. it can be exercised at any time up to maturity T. However, this is not the case for numerical simulations. To numerically price an American option, we need to divide the entire time period [0,T] into a discretized sequence $\{0=t_0 < t_1 < t_2 < \cdots < t_M = T\}$ and assume the American option can only be exercised at this fixed set of dates, which is in fact the case with special name "Bermudan options". Actually, one may expect the value of the discretized version of American option is simply the approximation of the continuous one when the number of time segments $M \to \infty$. In this thesis, we will simply focus on the discretized case. Once we restrict our concern with time discretization, it's necessary to define a way to approximate the underlying Markovian asset price process. We denote $S_i = S(t = t_i), i \in (0, 1, 2, \cdots, M)$ as the state of asset price process at the *i*th exercise opportunity. The Euler-Maruyama scheme^[13] then can be used to approximate the asset price process (2.4), which is given by

$$S_i = S_{i-1} + (r-q)S_{i-1}\Delta t + \sigma S_{i-1}\Delta W_i, \quad i = 1, 2, \dots M$$
(2.6)

where $\Delta t = t_i - t_{i-1}$ is the size of time interval, which is assumed to be constant in this thesis, and $\Delta W_i = W_i - W_{i-1}$ is the independent Brownian increments, which follows a normal distribution $N(0, \sqrt{\Delta t})$. The discretized process S_i given in this way is essentially a Markov chain.

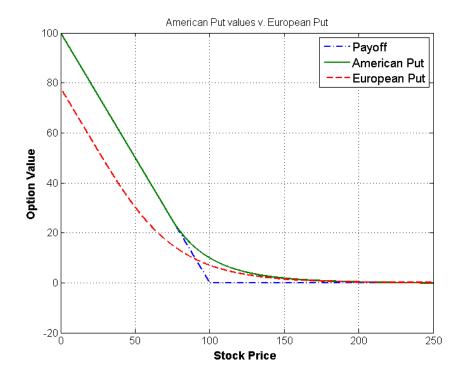


Figure 2.1: The value of American put option compared with the corresponding European option. The value of American option is calculated with Finite Difference Method (FDM). The value of European option is calculated with Black-Scholes formula. Parameters used are K = 100, r = 5%, q = 0%, $\sigma = 0.5$, T = 5.

2.2 Dynamic Programming Principle

Given the discretization setting in Section 2.1, the "dynamic programming principle" introduced by Richard Bellman^[14] provides us an effective tool to price American options. Let's assume at time $t = t_i$, the American option under the question has not been excised before. Thus, according to (2.2), assuming the constant interest rate, we can write the value of an American option at $t = t_i$ as

$$\tilde{V}_i(s) = \sup_{\tau \in \mathcal{T}_i} \mathbb{E}\left[e^{-r(\tau - t_i)}\tilde{h}(S_\tau, \tau) \mid S_i = s\right]$$
(2.7)

which is essentially equivalent to a newly issued option at t_i with the state of asset price starting from $S_i = s$. Now, if we work recursively from $t = t_M = T$, we are able to define a recursion formula for the price of American options. Firstly, let's consider the terminal time at option's maturity T. We know at maturity, the option holder will either choose to exercise the option or let the option expire worthless. Thus, at $t = t_M$, the value of an American option is simply the option's payoff, given by

$$\tilde{V}_M(s) = \tilde{h}(s,T), \quad S_M = s \tag{2.8}$$

where $\tilde{h}(x,t)$ is the payoff function. Now, consider the time $t=t_{M-1}$ with the state of asset price $S_{M-1}=s$, an investor will choose to exercise the option if and only if its current payoff is greater than the discounted expected value to be received if the investor choose not to exercise, thus according to (2.7), the value of option at t_{M-1} is given by

$$\tilde{V}_{M-1}(s) = \max \left\{ \tilde{h}(s, t_{M-1}), \mathbb{E} \left[D_{M-1, M} \tilde{V}_{M}(S_{M}) \mid S_{M-1} = s \right] \right\}$$
 (2.9)

where $D_{M-1,M} = e^{-r(t_M - t_{M-1})}$ is the discount factor from t_{M-1} to t_M . Thus, by dynamic programming principle, we can derive a recursive formulation for the value of American options as blow

$$\begin{cases}
\tilde{V}_{M}(s) = \tilde{h}(s,T), & S_{M} = s \\
\tilde{V}_{i-1}(s) = \max \left\{ \tilde{h}(s,t_{i-1}), \mathbb{E}\left[D_{i-1,i}\tilde{V}_{i}(S_{i}) \mid S_{i-1} = s\right] \right\}, i = 1 \cdots M
\end{cases}$$
(2.10)

This formulation essentially provides the basic principle of optimally exercising an American option, i.e., the exercise desicsion is made at $t = t_{i-1}$ by comparing the immediate exercise payoff $\tilde{h}(s, t_{i-1})$ against the expected present value of continuing. Also, an American option is usually not exercisable at time 0, and this can be done by simply setting $\tilde{h}(s, 0) = 0$.

In (2.10), all the value functions $\tilde{V}_i(s)$ are given in time- t_i currency. However, we are essentially interested in pricing an American option at time 0. So, it's natural to discount all the values to time 0, so that the discount factors $D_{i-1,i}$ can be discarded. Now let

$$h_i(s) = D_{0,i}\tilde{h}(s,t_i), \ V_i(s) = D_{0,i}\tilde{V}_i(s) \quad i = 0,\dots, M$$

where $D_{0,i} = e^{-r(t_i - t_0)}$ is the discount factor from t_0 to t_i . Then, according to (2.10), we have

$$\begin{split} V_0(s) = & \tilde{V}_0(s), \\ V_M(s) = & h_M(s), \\ V_{i-1}(s) = & D_{0,i-1} \tilde{V}_{i-1}(s) \\ = & D_{0,i-1} \max \left\{ \tilde{h}(s,t_{i-1}), \mathbb{E} \left[D_{i-1,i} \tilde{V}_i(S_i) \mid S_{i-1} = s \right] \right\} \\ = & \max \left\{ h_{i-1}(s), \mathbb{E} \left[D_{0,i-1} D_{i-1,i} \tilde{V}_i(S_i) \mid S_{i-1} = s \right] \right\} \\ = & \max \left\{ h_{i-1}(s), \mathbb{E} \left[V_i(S_i) \mid S_{i-1} = s \right] \right\} \end{split}$$

Thus, we can absorb the discount factors into the payoff and value functions, and (2.10) is then simplified as

$$\begin{cases} V_M(s) = h_M(s), & S_M = s \\ V_{i-1}(s) = \max \left\{ h_{i-1}(s), \mathbb{E}\left[V_i(S_i) \mid S_{i-1} = s\right] \right\}, i = 1 \cdots M \end{cases}$$
(2.11)

2.3 Optimal Stopping Rule and Continuation Values

The dynamic programming recursions (2.11) give a way to choose optimal exercise strategy for the American option. Assume for any stopping time $\tau \in \{t_1, t_2, \dots, t_M\}$, a sub-optimal value of American option is defined as

$$V_0^{\tau}(S_0) = \mathbb{E}\left[h_{\tau}(S_{\tau})\right] \tag{2.12}$$

The question here is to choose an optimal stopping time. We know that at any time t_i , a discounted value function $V_i(s)$ is assigned to each state of asset price process $S_i = s$ by the dynamic programming recursions (2.11). Thus, it's natural to choose our optimal stopping time τ^* as the first time when the payoff exceeds the value function, τ^* is thus given by^[4]

$$\tau^* = \min \{ \tau_i \in \{ t_1, \cdots, t_M \} : h_i(S_i) \ge V_i(S_i) \}$$
(2.13)

And on the other hand, at any time t_i , an investor will exercise the option when the state of asset price S_i gives a payoff larger than the value function, given that the option has not been exercised before. And we call the set of asset price states $\{s: h_i(s) \geq V_i(s)\}$ the "exercise region" at time t_i and the complement to this set as "continuation region". With these definitions, the optimal stopping rule (2.13) can be viewed as the first time the underlying asset price process S_i enters an exercise region.

We can now define the "continuation value" of an American option as the value of holding rather than exercising the option. The "continuation value" is simply defined as^[4]

$$\begin{cases}
C_M(s) = 0 \\
C_i(s) = \mathbb{E}\left[V_{i+1}(S_{i+1}) \mid S_i = s\right], \quad i = 0, \dots, M-1
\end{cases}$$
(2.14)

where $V_i(x)$ is defined by dynamic programming recursions (2.11). Thus, according to (2.11) we have

$$V_i(s) = \max\{h_i(s), C_i(s)\}, i = 1, \dots, M$$
 (2.15)

and the optimal stopping rule in (2.13) can be re-written as

$$\tau^* = \min \{ \tau_i \in \{ t_1, \cdots, t_M \} : h_i(S_i) \ge C_i(S_i) \}$$
 (2.16)

and the value of the option is then determined by this rule as

$$V_0^{\tau^*}(S_0) = \mathbb{E}\left[h_{\tau^*}(S_{\tau^*})\right] \tag{2.17}$$

Chapter 3

Longstaff-Schwartz Method: a Lower Bounds Estimator using Least-Squares Regressions

As we have seen in Chapter 2, pricing American options is essentially reduced to a dynamic programming problem with the recursive formulation (2.11). The main difficulty lies in the estimations of the conditional expectations, i.e. the continuation values $C_i(s)$ given by

$$C_i(s) = \mathbb{E}\left[V_{i+1}(S_{i+1}) \mid S_i = s\right], \quad i = 0, \dots, M-1$$
 (3.1)

The most popular approach to estimate the continuation values are based on regression methods, suggested by Longstaff and Schwartz^[5]. The continuation value $C_i(s)$ in (3.1), that essentially is a conditional expectation, is approximated by a linear combination of known functions (basis functions) of the current state of asset price s. Regression method is then used to estimate the optimal coefficients for the approximation. In this thesis, the least-squares based regression is employed.

3.1 Approximating Continuation Values Using Least-Squares Regression

Our aim is to approximate the continuation values $C_i(s)$ by regression, i.e., we want to find an expression of the form

$$C_{i}(s) = \mathbb{E}\left[V_{i+1}(S_{i+1}) \mid S_{i} = s\right] = \sum_{j=1}^{J} \beta_{ij} \psi_{j}(s) = \beta_{i}^{\top} \psi(s)$$
(3.2)

where $\psi(s) = (\psi_1(s), \psi_2(s), \dots, \psi_J(s))^{\top}$ is the vector of some basis functions and $\beta_i = (\beta_{i1}, \beta_{i2}, \dots, \beta_{iJ})^{\top}$ is the vector of the regression coefficients, which depends on time t_i . If we use the least-squares rule, then the regression coefficients is determined by the following theorem.

Theorem 3.1. Least-squares based regression coefficients

If there exists a relationship between the continuation value $C_i(s)$ and current state of asset price s in the form (3.2), the least-squares regression will give the coefficients β_i in the form

$$\beta_i = \left(\mathbb{E} \left[\psi(S_i) \psi(S_i)^\top \right] \right)^{-1} \mathbb{E} \left[\psi(S_i) V_{i+1}(S_{i+1}) \right] \equiv B_{\psi}^{-1} B_{\psi V}$$
(3.3)

where $B_{\psi} = \mathbb{E}\left[\psi(S_i)\psi(S_i)^{\top}\right]$ is a $J \times J$ matrix and $B_{\psi V} = \mathbb{E}\left[\psi(S_i)V_{i+1}(S_{i+1})\right]$ is a vector of length J.

Proof. The regression coefficients β_i is determined by the least-squares optimization of

$$\mathbb{E}\left[\left(\psi\left(S_{i}\right)^{\top}\beta_{i} - \mathbb{E}\left[V_{i+1}\left(S_{i+1}\right) \mid S_{i}\right]\right)^{2}\right] \to \min$$

By taking the derivative with respect to β_i and equating to 0, we get

$$\mathbb{E}\left[\psi\left(S_{i}\right)\left(\psi\left(S_{i}\right)^{\top}\beta_{i}-\mathbb{E}\left[V_{i+1}\left(S_{i+1}\right)\mid S_{i}\right]\right)\right]=0$$

By rearranging, we get

$$\mathbb{E}\left[\psi\left(S_{i}\right)\psi\left(S_{i}\right)^{\top}\right]\beta_{i} = \mathbb{E}\left[\psi\left(S_{i}\right)\mathbb{E}\left[V_{i+1}\left(S_{i+1}\right)\mid S_{i}\right]\right]$$
$$= \mathbb{E}\left[\psi\left(S_{i}\right)V_{i+1}\left(S_{i+1}\right)\right]$$

Solving for β_i , we finally get

$$\beta_i = \left(\mathbb{E} \left[\psi(S_i) \psi(S_i)^\top \right] \right)^{-1} \mathbb{E} \left[\psi(S_i) V_{i+1}(S_{i+1}) \right]$$
 (3.4)

The theoretical value of regression coefficients β_i is given by (3.3), which can be estimated in practice by Monte Carlo simulation. Given N independent simulated paths of asset price $\left(S_1^{(n)}, S_2^{(n)}, \dots, S_M^{(n)}\right)$, $n = 1, \dots, N$, which can be obtained by Euler-Maruyama scheme (2.6), and assuming that at t_i the value functions $V_{i+1}\left(S_{i+1}^{(n)}\right)$ are known, the least-squares estimation of the regression coefficients β_i is then given by

$$\hat{\beta}_i = \hat{B}_{\psi,i}^{-1} \hat{B}_{\psi V,i} \tag{3.5}$$

where

$$\hat{B}_{\psi,i} = \frac{1}{N} \sum_{n=1}^{N} \psi(S_i^{(n)}) \psi(S_i^{(n)})^{\top}$$
(3.6)

$$\hat{B}_{\psi V,i} = \frac{1}{N} \sum_{n=1}^{N} \psi(S_i^{(n)}) V_{i+1}(S_{i+1}^{(n)})$$
(3.7)

and $S_i^{(n)}$ and $S_{i+1}^{(n)}$ correspond to the same Monte Carlo trajectory. Also, in practice, V_{i+1} need to be replaced by the estimated values \hat{V}_{i+1} , given by

$$\hat{V}_{i+1}(S_{i+1}) = \max \left\{ h_{i+1}(S_{i+1}), \hat{C}_{i+1}(S_{i+1}) \right\}$$
(3.8)

Then the continuation value $C_i(S_i)$ can be estimated by

$$\hat{C}_i(S_i) = \hat{\beta}_i^{\top} \psi(S_i) \tag{3.9}$$

Now we can summarize the procedure for the regression coefficients estimations as in the following algorithm.

Algorithm 3.2. Backward induction for least-squares regression coefficients estimation

- 1. Simulate N independent trajectories of the asset price process $\{S_1^{(n)}, S_2^{(n)}, \cdots, S_M^{(n)}\},$ $n = 1, \dots, N$.
- 2. At terminal time t_M , set $\hat{V}_M(S_M^{(n)}) = h_M(S_M^{(n)})$.
- 3. Apply backward induction for $i = M-1, \dots, 1$
 - (a) estimate the regression coefficients by $\hat{\beta}_i = \hat{B}_{\psi,i}^{-1} \hat{B}_{\psi V,i}$, where $\hat{B}_{\psi,i}$ and $\hat{B}_{\psi V,i}$ are given by (3.6) and (3.7) respectively.
 - (b) calculate the continuation values $\hat{C}_i(S_i^{(n)}) = \hat{\beta}_i^{\top} \psi(S_i^{(n)}), n = 1, \dots, N.$
 - (c) set $\hat{V}_i^{(n)} = \max \left\{ h_i(S_i^{(n)}), \hat{C}_i(S_i^{(n)}) \right\}, n = 1, \dots, N.$
- 4. Store vectors β_i ready to use.

Once we have the estimations of the regression coefficients β_i , the value of the option can be estimated with the stopping rule defined in (2.16) using the 2nd set of independent Mote Carlo paths.

3.2 Low-biased Estimator Using Optimal Stopping Rule

The estimated regression coefficients $\hat{\beta}_i$ determines the approximations of the continuation values $\hat{C}_i(S_i)$ as in (3.9) at time step t_i , given the state of asset price S_i , which in turn define an optimal stopping strategy given by

$$\hat{\tau} = \min \left\{ \tau_i \in \{t_1, \cdots, t_M\} : h_i(S_i) \ge \hat{C}_i(S_i) \right\}$$
(3.10)

Thus, by simulating a 2nd set of Monte Carlo paths and applying this stopping strategy, the value of the American option can be estimated as

$$\hat{V}_0(S_0) = \mathbb{E}\left[h_{\hat{\tau}}(S_{\hat{\tau}})\right] \tag{3.11}$$

As we can see, the approximated stopping rule given in (3.10) is inevitably sub-optimal, i.e., it departs from the true value given by (2.16). Thus, we must have

$$V_0(S_0) = \sup_{\tau \in \mathcal{T}_0} \mathbb{E}[h_{\tau}(S_{\tau})] \ge \mathbb{E}[h_{\hat{\tau}}(S_{\hat{\tau}})] = \hat{V}_0(S_0)$$
(3.12)

which indicates that the estimator defined in (3.11) is a low-biased estimator which provides a lower bound of the true value. We now summarize the procedure in the following algorithm.

Algorithm 3.3. Low estimator using optimal stopping rule

- 1. Load regression coefficients β_i , $i = 1, \dots, M$
- 2. Simulate N independent paths of the asset price process $\{S_1^{(n)}, S_2^{(n)}, \cdots, S_M^{(n)}\}$, $n = 1, \dots, N$. (This should be a 2nd set of paths independent from the 1st one used to estimate the regression coefficients β_i gien in Algorithm 3.2)
- 3. Apply forward induction for $i = 1, \dots, M-1$, and for each $n = 1, \dots, N$
 - (a) calculate continuation values $\hat{C}_i(S_i^{(n)}) = \hat{\beta}_i^{\top} \psi(S_i^{(n)})$
 - (b) calculate the payoff functions $h_i(S_i^{(n)})$
- 4. For terminal time i = M, set $C_M(S_M^{(n)}) = 0$ and calculate $h_M(S_M^{(n)})$
- 5. Set $\hat{V}_0^{(n)} = h_{i*}(S_{i*}^{(n)}), i^* = \min \left\{ i \in \{1, \dots, M\} : h_i(S_i^{(n)}) \ge \hat{C}_i(S_i^{(n)}) \right\}$
- 6. Calculate the estimated value of option as $\hat{V}_0 = \frac{1}{N} \sum_{n=1}^{N} \hat{V}_0^{(n)}$

3.3 Numerical Examples

In this section, the Longstaff-Schwartz method is tested using a simple numerical example of an American put option written on a single non-dividend paying stock with the srike K = 20, interest rate r = 5%, volatility $\sigma = 0.4$ and maturity T = 1 respectively. For the basis regression functions $\psi_i(x)$, we choose the weighted Laguerre polynomials suggested by Longstaff and Schwartz^[5], which are defined as

$$\psi_j(x) = e^{-x/2} L_k(x), \quad k = j - 1$$
 (3.13)

where $L_k(x)$ is the Laguerre polynomials defined as

$$L_{k}(x) = \frac{e^{x}}{k!} \frac{d^{k}}{dx^{k}} \left(e^{-x} x^{k} \right)$$

$$= \begin{cases} 1, & k = 0 \\ 1 - x, & k = 1 \\ \frac{1}{k} \left((2k - 1 - x) L_{k-1}(x) \right) - (k - 1) L_{k-2}(x), & \text{for } k \ge 1 \end{cases}$$
(3.14)

For the numerical testing, we fixed the number of basis functions J=5. We initially set the number of Monte Carlo paths to be N=10000 and fixed the number of time steps $M=2^5=32$. Figure 3.1 shows the numerical results of Longstaff-Schwartz method (LSM) compared with those given by the penalty approach using Finite Difference Method (FDM)^[3].

For further investigations, we change the number of independent Monte Carlo paths from 5e3 to 1e5. The results are shown in Table 3.1 and compared with those of the Finite Difference Method.

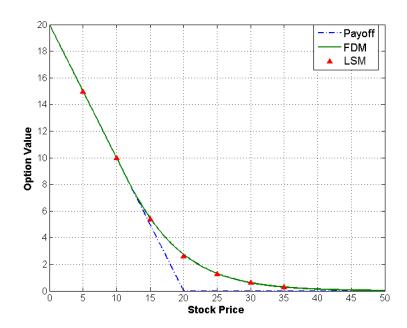


Figure 3.1: Values of American option estimated by Longstaff-Schwartz method compared with the Finite Difference Method (FDM). The parameters used are, K = 20, r = 5%, $\sigma = 0.4$ and T = 1. Number of paths simulated N = 10000, number of time steps M = 32.

		LSM e	estimated	values	Variances of LSM estimator			
$\overline{S_0}$	FDM	N=5e3	N=1e4	N=1e5	N=5e3	N=1e4	N=1e5	
5	15.000	14.974	14.969	14.967	2.48E-05	1.30E-05	1.24E-06	
10	10.000	9.964	9.981	9.971	9.72E-05	4.87E-05	5.02E-06	
15	5.470	5.463	5.410	5.441	1.85E-03	9.41E-04	9.44E-05	
20	2.733	2.745	2.665	2.713	2.18E-03	1.10E-03	1.09E-04	
25	1.306	1.339	1.258	1.326	9.97E-04	5.50E-04	5.26E-05	
30	0.613	0.633	0.638	0.619	5.69E-04	2.52E-04	2.66E-05	
35	0.288	0.291	0.300	0.298	2.39E-04	1.31E-04	1.28E-05	

Table 3.1: Results of Longstaff-Schwartz based Monte Carlo method using different number of simulated paths N, compared with Finite Different Method. The parameters used are, $K=20, r=5\%, \sigma=0.4, T=1$ and number of time steps M=32.

As we can see in the table, all the three sets of results give the similar estimated values of the option, which have the similar accuracy compared with those given by FDM. However, fewer simulated paths will give much higher variances. Another noticeable fact is that the variances of the LSM estimators tend to be larger when the option is close to at-themoney. When the initial stock price $S_0 = 20$, the MC estimator gives the largest variances. It's worth mentioning that, some estimated values using Monte Carlo method are lower than those of the Finite Difference Method while others are higher, especially for the deepout-the-money options. However, we shouldn't consider this as a contradiction with the

argument that the Longstaff-Schwartz method provides a low-biased estimator due to the fact that Monte Carlo method comes with two sources of errors. One is the bias from the method itself and another is from the variance of MC estimators. For deep-out-the-money options, the option values are relatively low, thus the same level variance will give a high biased value even with a low-biased estimator.

Next, to investigate the effects of number of exercise opportunities, we set the number of time steps M=8, 16, 32, 64 and 128 respectively and fix the number of Monte Carlo paths to be N=10000. The results are shown in Tabel 3.2. We notice that, when the time steps increases, the LSM estimated values are generally getting closer to the results given by FDM, which uses a very fine time stepping (500 steps). This is in agreements with the argument that the value of a discretized version of American option will be getting to an approximation of the value of continuous version American option when the number of time steps $M \to \infty$. The variances of the MC estimator are not noticeably affected for most cases. But for deep-in-the-money and deep-out-of-money options, higher number of time steps gives lower variances.

		LSM es	stimate	d value	es	Variances of LSM estimator				
S0 FDM	M=8	M=16	M=32	M=64	M=128	M=8	M = 16	M = 32	M = 64	M=128
5 15.000	14.876	14.937	14.969	14.983	14.992	4.96E-05	2.51E-05	1.30E-05	6.61E-06	3.18E-06
10 10.000	9.860	9.943	9.981	9.990	9.990	1.98E-04	9.87E-05	4.87E-05	2.50E-05	1.28E-05
$15\ 5.470$	5.418	5.441	5.410	5.421	5.449	9.40E-04	9.20E-04	9.41E-04	9.41E-04	$9.99\mathrm{E}\text{-}04$
$20\ 2.733$	2.756	2.742	2.665	2.739	2.728	1.10E-03	1.04E-03	1.10E-03	1.08E-03	1.07E-03
$25 \ 1.306$	1.400	1.348	1.258	1.227	1.289	5.73E-04	5.02E-04	5.50E-04	5.53E-04	$5.90\mathrm{E}\text{-}04$
$30 \ 0.613$	0.672	0.666	0.638	0.641	0.619	2.77E-04	2.93E-04	2.52E-04	2.87E-04	$2.74 \hbox{E-}04$
$35 \ 0.288$	0.331	0.311	0.300	0.302	0.281	1.51E-04	1.35E-04	1.31E-04	1.18E-04	1.19E-04

Table 3.2: Results of Longstaff-Schwartz based Monte Carlo method using different number of time steps M, compared with Finite Difference Method. The parameters used are K=20, r=5%, $\sigma=0.4$, T=1 and number of simulated MC parths N=10000.

Chapter 4

The Duality through Martingales: an Upper Bounds Estimator

As we have seen in Chapter 3, the Longstaff-Schwartz based Monte Carlo method (LSM) provides a low-biased estimator, giving a lower bound of the true value of the option. We call this the "primal" problem. A new direction in Monte Carlo simulation of American options is the dual approach, developed by Rogers^[7] and independently by Haugh and Kogan^[8]. One of the most popular implementations of the method was presented by Andersen and Broadie^[9]. The basic idea of this dual approach is to represent the price of an American option through a minimization problem. The duality minimizes over a class of supermartingales or martingales and leads to a high-biased approximation, providing upper bounds on prices. The lower bounds provided by LSM and the upper bounds provided by the dual approach contain the true price.

4.1 The Duality: a Minimization Problem over Martingales

As we have seen in Chapter 2, the discounted value functions $V_i(S_i)$ satisfies the recursive formulation given by (2.11), which is re-written below

$$\begin{cases} V_M(s) = h_M(s), & S_M = s \\ V_{i-1}(s) = \max \{h_{i-1}(s), \mathbb{E}[V_i(S_i) \mid S_{i-1} = s]\}, i = 1 \cdots M \end{cases}$$
(4.1)

Thus, we have the inequality:

$$V_i(S_i) \ge \mathbb{E}[V_i(S_{i+1}) \mid S_i], \ i = 0, \dots, M-1$$
 (4.2)

which in fact indicates that the value function $V_i(S_i)$ is a supermartingale. And also, we have

$$V_i(S_i) \ge h_i(S_i), \ i = 0, \cdots, M \tag{4.3}$$

The value function process $V_i(S_i)$, $i = 0, \dots, M$ is in fact the minimal supermartingale dominating the discounted payoff functions $h_i(S_i)$ at all exercise times t_i , which is a well-known characterization of American option price [15]. This characterization was extended

by Haugh and Kogan^[8], who proposed a minimization problem to formulate the pricing of American options.

In this thesis, we will employ the major results from Haugh and Kogan with specializations to martingales. Let $\mathcal{M} = \{\mathcal{M}_i, i = 0, \dots, M\}$ be a martingale with $\mathcal{M}_0 = 0$, then the following theorem holds.

Theorem 4.1. Duality through martingales

For any martingales $\mathcal{M} = \{\mathcal{M}_i, i = 0, \dots, M\}$ satisfying $\mathcal{M}_0 = 0$, the price of American option $V_0(S_0)$ satisfies the inequality

$$V_0(S_0) \le \inf_{\mathscr{M}} \mathbb{E} \left[\max_{i=1,\cdots,M} \left\{ h_i(S_i) - \mathscr{M}_i \right\} \right]$$
(4.4)

The equality holds with the optimal martingale \mathscr{M}^* defined by

$$\begin{cases}
\mathcal{M}_0^* = 0, \\
\mathcal{M}_i^* = \sum_{k=1}^i \Delta_k, \text{ for } i = 1, \dots, M
\end{cases}$$
(4.5)

where Δ_i is given by

$$\Delta_i = V_i(S_i) - \mathbb{E}\left[V_i(S_i) \mid S_{i-1}\right] \tag{4.6}$$

Proof. We first prove the inequality (4.4) holds. According to the optional sampling theorem of martingales, for any stopping time $\tau \in \{t_1, t_2, \dots, t_M\}$, $\mathbb{E}[\mathcal{M}_{\tau}] = \mathcal{M}_0 = 0$, and thus we have

$$\mathbb{E}\left[h_{\tau}(S_{\tau})\right] = \mathbb{E}\left[h_{\tau}(S_{\tau}) - \mathcal{M}_{\tau}\right] \leq \mathbb{E}\left[\max_{i=1,\dots,M} \left\{h_{i}(S_{i}) - \mathcal{M}_{i}\right\}\right]$$

By taking the infimum over the martingales \mathcal{M} , we get

$$\mathbb{E}\left[h_{\tau}(S_{\tau})\right] \leq \inf_{\mathscr{M}} \mathbb{E}\left[\max_{i=1,\cdots,M} \left\{h_{i}(S_{i}) - \mathscr{M}_{i}\right\}\right]$$
(4.7)

The inequality (4.7) holds for any stopping times τ , thus it also holds for the supremum over τ . Thus we have proved the inequality

$$V_0(S_0) = \sup_{\tau} \mathbb{E}\left[h_{\tau}(S_{\tau})\right] \le \inf_{\mathscr{M}} \mathbb{E}\left[\max_{i=1,\cdots,M} \left\{h_i(S_i) - \mathscr{M}_i\right\}\right]$$

Next, we prove the equality in (4.4) holds for \mathcal{M}^* defined by (4.5) and (4.6). We first show that \mathcal{M}^* is actually a martingale. Given the definition of the Δ_i , we have

$$\mathbb{E}\left[\Delta_{i} \mid S_{i-1}\right] = \mathbb{E}\left[V_{i}(S_{i}) - \mathbb{E}\left[V_{i}(S_{i}) \mid S_{i-1}\right] \mid S_{i-1}\right] = 0 \tag{4.8}$$

Thus, we have

$$\mathbb{E}\left[\mathcal{M}_{i}^{*} \mid S_{i-1}\right] = \mathbb{E}\left[\sum_{k=1}^{i} \Delta_{k} \mid S_{i-1}\right] = \sum_{k=1}^{i-1} \Delta_{k} = \mathcal{M}_{i-1}^{*}$$

which indicates that \mathcal{M}^* satisfies the martingale property. Next, we use backward induction to prove that

$$V_{i}(S_{i}) = \mathbb{E}[\max\{h_{i}(S_{i}), h_{i+1}(S_{i+1}) - \Delta_{i+1}, h_{i+2}(S_{i+2}) - \Delta_{i+2} - \Delta_{i+1}, \dots h_{M}(S_{M}) - \Delta_{M} - \dots - \Delta_{i+1}\} \mid S_{i}], \quad for \ i = 1, \dots, M$$

$$(4.9)$$

This holds for the terminal time step t_M , since we have $V_M(S_M) = h_M(S_M) = \mathbb{E}[h_M(S_M)|S_M]$. Now, assume (4.9) holds for the time step t_i , then according to (4.1) and (4.6), we have

$$\begin{split} V_{i-1}(S_{i-1}) &= \max \left\{ h_{i-1}(S_{i-1}), \mathbb{E} \left[V_i(S_i) \mid S_{i-1} \right] \right\} \\ &= \mathbb{E} \left[\max \left\{ h_{i-1}(S_{i-1}), \mathbb{E} \left[V_i(S_i) \mid S_{i-1} \right] \right\} \mid S_{i-1} \right] \\ &= \mathbb{E} \left[\max \left\{ h_{i-1}(S_{i-1}), V_i(S_i) - \Delta_i \right\} \mid S_{i-1} \right] \\ &= \mathbb{E} \left[\max \left\{ h_{i-1}(S_{i-1}), h_i(S_i) - \Delta_i, h_{i+1}(S_{i+1}) - \Delta_{i+1} - \Delta_i, \dots h_M(S_M) - \Delta_M - \dots - \Delta_i \right\} \mid S_{i-1} \right] \end{split}$$

which indicates (4.9) also holds for t_{i-1} . Finally, at $t = t_0$, recall that we have assumed the option is not exercisable immediately and $h_0(S_0) = 0$, the option value at t_0 is thus given by

$$V_0(S_0) = \mathbb{E}[V_1(S_1) \mid S_0] = \mathbb{E}[V_1(S_1) - \Delta_1 \mid S_0]$$

and according to (4.9)

$$V_1(S_1) = \mathbb{E}[\max\{h_1(S_1), h_2(S_2) - \Delta_2, h_3(S_3) - \Delta_3 - \Delta_2, \dots h_M(S_M) - \Delta_M - \dots - \Delta_2\} \mid S_1]$$

We then finally get

$$V_0(S_0) = \mathbb{E}\left[\mathbb{E}\left[\max_{i=1,\dots,M} \left\{h_i(S_i) - \mathcal{M}_i^*\right\} \mid S_1\right] \mid S_0\right]$$

$$= \mathbb{E}\left[\max_{i=1,\dots,M} \left\{h_i(S_i) - \mathcal{M}_i^*\right\}\right]$$

$$(4.10)$$

This verifies that equality in (4.4) holds for \mathcal{M}^* defined by (4.5) and (4.6), which is indeed an optimal martingale.

Equation (4.10) provides an estimator for pricing American options. If we can find a martingale $\hat{\mathcal{M}}$ that is close to the optimal martingale \mathcal{M}^* , then we can estimate the value of an American option by

$$\hat{V}_0(S_0) = \mathbb{E}\left[\max_{i=1,\cdots,M} \left\{ h_i(S_i) - \hat{\mathcal{M}}_i \right\} \right]$$
(4.11)

which is indeed our duality estimator. Notice that the martingale $\hat{\mathscr{M}}$ is inevitably suboptimal and thus (4.11) provides a high-biased estimator, providing an upper bound for the option price. This, conjunct with the lower bound given by LSM approach, gives a range containing the true price of the American option.

4.2 The Duality Estimation Using Martingales from Approximated Value Functions

As we have seen in the previous section, we can use (4.11) to estimate the duality by constructing a martingale $\hat{\mathcal{M}}$ that is close to the optimal martingale $\hat{\mathcal{M}}^*$. This can be done by constructing the martingales based on the approximated value functions $\hat{V}_i(S_i)$. Given the definition of the optimal martingale $\hat{\mathcal{M}}^*$ in (4.5) and (4.6), it's natural to define the approximation $\hat{\mathcal{M}}$ as

$$\begin{cases} \hat{\mathcal{M}}_0 = 0, \\ \hat{\mathcal{M}}_i = \sum_{k=1}^i \hat{\Delta}_k, \text{ for } i = 1, \dots, M \end{cases}$$

$$(4.12)$$

where $\hat{\Delta}_i$ is given by

$$\hat{\Delta}_i = \hat{V}_i(S_i) - \mathbb{E}\left[\hat{V}_i(S_i) \mid S_{i-1}\right]$$
(4.13)

It easy to verify that $\hat{\mathcal{M}}$ defined by (4.12) and (4.13) satisfies the general martingale property. Recall that $\hat{V}_i(S_i)$ is given by

$$\hat{V}_i(S_i) = \max\left\{h_i(S_i), \hat{C}_i(S_i)\right\} \tag{4.14}$$

and $\hat{C}_i(S_i)$ is the estimation of the continuation value, given by

$$\hat{C}_i(S_i) = \hat{\mathbb{E}}\left[V_{i+1}(S_{i+1})|S_i\right] = \hat{\beta}_i^{\top} \psi(S_i)$$
(4.15)

where $\hat{\beta}_i$ is the vector of LSM regression coefficients and $\psi(x)$ is the vector of our basis functions. One might think of replacing the conditional expectation $\mathbb{E}\left[\hat{V}_i(S_i)|S_{i-1}\right]$ in (4.13) with $\hat{C}_{i-1}(S_{i-1})$. However, this will not give a valid construction of martingales. The reason is that $\hat{C}_{i-1}(S_{i-1})$ is the estimation of the conditional expectation of true value functions, i.e. $\hat{C}_{i-1}(S_{i-1}) = \hat{\mathbb{E}}\left[V_i(S_i)|S_{i-1}\right]$, which is generally not equivalent to an estimation of $\mathbb{E}[\hat{V}_i(S_i)|S_{i-1}]$, which is the conditional expectation of approximated value functions. Thus, to construct a valid martingale, we need to use a nested simulation^[4].

Assume we have simulated the main Monte Carlo paths $\{S_i^{(n)}: n=1,\cdots,N\}$, at each step S_{i-1} , we simulate m sub-successors $\{\tilde{S}_i^{(k)}: k=1,\cdots,m\}$ and estimate the conditional expectation $\mathbb{E}[\hat{V}_i(S_i)|S_{i-1}]$ by

$$\hat{\mathbb{E}}[\hat{V}_i(S_i)|S_{i-1}] = \frac{1}{m} \sum_{k=1}^m \hat{V}_i(\tilde{S}_i^{(k)})$$
(4.16)

where $\hat{V}_i(\tilde{S}_i^{(k)})$ is calculated in the same way as given in (4.14). Equation (4.16) gives a conditionally unbiased estimator of $\mathbb{E}[\hat{V}_i(S_i)|S_{i-1}]$ given S_{i-1} , thus providing a valid way to construct the martingales as in (4.12) and (4.13), which in turn gives a valid duality estimator as in (4.11). We summarize the procedure in the following algorithm.

Algorithm 4.2. Duality estimation using martingales based on approximated value functions

- 1. Load regression coefficients β_i , $i = 1, \dots, M$, which are given by Algorithm 3.2.
- 2. Simulate N independent paths of the asset price process $\{S_1^{(n)}, S_2^{(n)}, \cdots, S_M^{(n)}\}$, $n = 1, \dots, N$. (This should be a 2nd set of paths independent from the 1st one used to estimate the regression coefficients β_i gien in Algorithm 3.2)
- 3. Set the initial martingale $\hat{\mathcal{M}}_0 = 0$
- 4. Apply forward induction for $i = 1, \dots, M-1$, and for each $n = 1, \dots, N$
 - (a) calculate continuation values $\hat{C}_i(S_i^{(n)}) = \hat{\beta}_i^{\top} \psi(S_i^{(n)})$
 - (b) calculate the payoff functions $h_i(S_i^{(n)})$
 - (c) calculate the approximated value functions $\hat{V}_i(S_i^{(n)}) = \max \left\{ h_i(S_i^{(n)}), \hat{C}_i(S_i^{(n)}) \right\}$
 - (d) simulate m independent sub Monte Carlo successors $\{\tilde{S}_i^{(1)}, \tilde{S}_i^{(2)}, \cdots, \tilde{S}_i^{(m)}\}$ from the previous time step $S_{i-1}^{(n)}$
 - (e) calculate the estimation of martingale differential by $\hat{\Delta}_i^{(n)} = \hat{V}_i(S_i^{(n)}) \frac{1}{m} \sum_{k=1}^m \hat{V}_i(\tilde{S}_i^{(k)})$

where $\hat{V}_i(\tilde{S}_i^{(k)})$ are calculated similarly using regression.

- (f) calculate the martingales $\hat{\mathcal{M}}_i^{(n)} = \hat{\mathcal{M}}_{i-1}^{(n)} + \hat{\Delta}_i^{(n)}$
- 5. For terminal time i = M, for each $n = 1, \dots, N$
 - (a) set $C_M(S_M^{(n)}) = 0$ and calculate $h_M(S_M^{(n)})$
 - (b) set $\hat{V}_M(S_M^{(n)}) = h_M(S_M^{(n)})$
 - (c) simulate m independent sub Monte Carlo successors $\{\tilde{S}_{M}^{(1)}, \tilde{S}_{M}^{(2)}, \cdots, \tilde{S}_{M}^{(m)}\}$ from the previous time step $S_{M-1}^{(n)}$
 - (d) calculate the estimation of martingale differential by

$$\hat{\Delta}_{M}^{(n)} = \hat{V}_{M}(S_{M}^{(n)}) - \frac{1}{m} \sum_{k=1}^{m} \hat{V}_{M}(\tilde{S}_{M}^{(k)})$$
where $\hat{V}_{M}(\tilde{S}_{M}^{(k)}) = h_{M}(\tilde{S}_{M}^{(k)})$.

- (e) calculate the martingale $\hat{\mathcal{M}}_{M}^{(n)} = \hat{\mathcal{M}}_{M-1}^{(n)} + \hat{\Delta}_{M}^{(n)}$
- 6. Set $\hat{V}_0^{(n)} = \max_{i=1,\dots,M} \left(h_i(S_i^{(n)}) \hat{\mathcal{M}}_i^{(n)} \right)$
- 7. Calculate the estimated value of duality as $\hat{V}_0 = \frac{1}{N} \sum_{n=1}^{N} \hat{V}_0^{(n)}$

4.3 Numerical Examples

We now test the algorithm 4.2 using the same example provided in Section 3.3. The American put option is written on a single non-dividend paying stock with the srike K=20, interest rate r=5%, volatility $\sigma=0.4$ and maturity T=1 respectively. The weighted Laguerre polynomials defined in (3.13) and (3.14) are used as our regression basis functions. For the numerical testing, we fixed the number of basis functions J=5. Again, we fixed the number of time steps M=32 and change the number of main Monte Carlo paths from 5e3 to 1e5. The number of simulated sub-successors for the construction of martingales are fixed with m=100. The results are shown in Table 4.1. As we can see, the duality estimations are generally higher than the results either by the LSM or by the Finite Difference Method, which confirms the argument that the duality approach provides a high-biased estimator, thus giving a upper bound of the true price. When we change the number of main Monte Carlo paths, the fewer simulated paths again give higher variances and the highest variances tend to be with the at-the-money options. Another noticeable fact is that the variances of duality estimators are generally much smaller than those of the LSM, which provides the lower bounds.

	MC estimated values										
		N=	:5e3	N=	1e4	N=1e5					
S_0	FDM	LSM	DUAL	LSM	DUAL	LSM	DUAL				
5	15.000	14.974	14.983	14.969	14.983	14.967	14.983				
10	10.000	9.964	10.061	9.981	10.062	9.971	10.062				
15	5.469	5.463	5.617	5.410	5.618	5.441	5.610				
20	2.726	2.745	2.836	2.665	2.841	2.713	2.831				
25	1.306	1.339	1.352	1.258	1.343	1.326	1.359				
30	0.613	0.633	0.648	0.638	0.642	0.619	0.648				
35	0.288	0.291	0.313	0.300	0.307	0.298	0.310				

	Variances of MC estimators										
	N=	:5e3	N=	1e4	N=1e5						
S0	LSM	DUAL	LSM	DUAL	LSM	DUAL					
5	2.48E-05	7.33E-08	1.30E-05	3.38E-08	1.24E-06	3.03E-09					
10	9.72E-05	5.37E-06	4.87E-05	2.63E-06	5.02E-06	2.73E-07					
15	1.85E-03	2.25E-05	9.41E-04	1.10E-05	9.44E-05	1.12E-06					
20	2.18E-03	3.01E-05	1.10E-03	1.42E-05	1.09E-04	1.41E-06					
25	9.97E-04	1.60E-05	5.50E-04	8.01E-06	5.26E-05	8.97E-07					
30	5.69E-04	1.59E-05	2.52E-04	3.48E-06	2.66E-05	3.67E-07					
35	2.39E-04	1.17E-05	1.31E-04	3.77E-06	1.28E-05	1.40E-07					

Table 4.1: Results of duality approach using different number of simulated paths N, compared with Finite Different Method. The parameters used are, K = 20, r = 5%, $\sigma = 0.4$, T = 1, number of time steps M = 32 and number of sub-successors m = 100.

To investigate the effects of the number of sub-successors m for the construction of martingales, we fixed the number of main Monte Carlo paths N=1e4 and the number of time steps M=32. We set the number of sub-successors as m=50,100, and 200 respectively. The results are shown in Table 4.2. As we can see, when the number of sub-successors increases, the estimated duality values decrease, giving smaller upper bounds and thus tighter ranges containing the true price, conjunct with the lower bounds given by LSM. This is reasonable because larger number of sub-successors gives better estimation of the conditional expectation $\mathbb{E}[\hat{V}_i(S_i)|S_{i-1}]$, which in turn gives higher accuracy in the estimations of the martingales $\hat{\mathcal{M}}$. Another interesting fact is that higher number of sub-successors also gives lower overall variances of the estimator, which again is the outcome of the better estimations of the conditional expectations.

	MC estimated values								
$\overline{S_0}$	FDM	LSM	DUAL/m=50	DUAL/m=100	DUAL/m=200				
5	15.000	14.969	14.996	14.983	14.978				
10	10.000	9.981	10.123	10.062	10.030				
15	5.469	5.410	5.689	5.618	5.570				
20	2.726	2.665	2.879	2.841	2.817				
25	1.306	1.258	1.374	1.343	1.338				
30	0.613	0.638	0.654	0.642	0.639				
35	0.288	0.300	0.323	0.307	0.304				

	Variances of MC estimator									
S_0	LSM	DUAL/m=50	DUAL/m=100	DUAL/m=200						
5	1.30E-05	7.33E-08	3.38E-08	8.37E-09						
10	4.87E-05	5.37E-06	2.63E-06	1.79E-06						
15	9.41E-04	2.25E-05	1.10E-05	7.76E-06						
20	1.10E-03	3.01E-05	1.42E-05	1.11E-05						
25	5.50E-04	1.60E-05	8.01 E-06	7.41E-06						
30	2.52E-04	1.59E-05	3.48E-06	3.27E-05						
35	1.31E-04	1.17E-05	3.77E-06	2.02E-06						

Table 4.2: Results of duality approach using different number of sub-successors m for the construction of martingales, compared with Finite Different Method. The parameters used are, $K=20, r=5\%, \sigma=0.4, T=1$, number of main Monte Carlo paths N=1e4, number of time steps M=32.

Finally, we investigated the effects of number of time steps while fixing the number of main Monte Carlo paths N=1e4 and the number of sub-successors m=100. We set M=32,64 and 128 respectively. The results are shown in Table 4.3. As shown in the table, while the LSM estimates are getting closer to the results given by the Finite Difference Method, the estimates of duality have a trend of increasing, which means the ranges provided by the upper-lower bounds are getting wider. The reason behind this

phenomena is still unknown. Again, the variances of the MC estimators are not noticeably affected by the number of time steps for most cases.

	MC estimated values									
		M=	=32	M=	=64	M=128				
$S_0 \\ 5$	FDM	LSM	DUAL	LSM	DUAL	LSM	DUAL			
5	15.000	14.969	14.983	14.983	14.997	14.992	15.006			
10	10.000	9.981	10.062	9.990	10.083	9.990	10.095			
15	5.470	5.410	5.618	5.421	5.653	5.449	5.671			
20	2.733	2.665	2.841	2.739	2.882	2.728	2.900			
25	1.306	1.258	1.343	1.227	1.387	1.289	1.401			
30	0.613	0.638	0.642	0.641	0.663	0.619	0.683			
35	0.288	0.300	0.307	0.302	0.317	0.281	0.339			

	Variances of MC estimator										
	M=	=32	M=	=64	M=128						
S_0	LSM	DUAL	LSM	DUAL	LSM	DUAL					
5	1.30E-05	3.38E-08	6.61E-06	4.02E-08	3.18E-06	4.49E-08					
10	4.87E-05	2.63E-06	2.50E-05	3.06E-06	1.28E-05	3.25E-06					
15	9.41E-04	1.10E-05	9.41E-04	1.18E-05	9.99E-04	1.15E-05					
20	1.10E-03	1.42E-05	1.08E-03	1.40E-05	1.07E-03	1.51E-05					
25	5.50E-04	8.01E-06	5.53E-04	8.05E-06	5.90E-04	8.24E-06					
30	2.52E-04	3.48E-06	2.87E-04	3.89E-06	2.74E-04	9.28E-06					
35	1.31E-04	3.77E-06	1.18E-04	1.95E-06	1.19E-04	2.33E-06					

Table 4.3: Results of duality approach using different time steps M, compared with Finite Different Method. The parameters used are, $K=20, r=5\%, \sigma=0.4, T=1$, number of main Monte Carlo paths N=1e4, number of sub-successors m=100.

Chapter 5

Orthogonality of Hermite Polynomials: A Computing Saving Technique

As we have seen in the previous chapters. For pricing American options, both the Longstaff-Schwartz method estimating lower bounds (Algorithm 3.3) and the duality method estimating upper bounds (Algorithm 4.2) rely on the regression based estimations of continuation values C(S), which in turn depend on the quality of estimations of the regression coefficients β . Thus, for both methods, certain efforts are made towards the computing of regression coefficients, which is fulfilled by a pre-processing procedure (Algorithm 3.2). Recall that the regression coefficients β are estimated by backward induction using

$$\hat{\beta}_i = \hat{B}_{\psi,i}^{-1} \hat{B}_{\psi V,i}, \quad i = M-1, \cdots, 1$$
 (5.1)

where

$$\hat{B}_{\psi,i} = \hat{\mathbb{E}}\left[\psi(S_i)\psi(S_i)^{\top}\right] = \frac{1}{N} \sum_{n=1}^{N} \psi(S_i^{(n)}) \psi(S_i^{(n)})^{\top}$$
(5.2)

$$\hat{B}_{\psi V,i} = \hat{\mathbb{E}}\left[\psi(S_i)\hat{V}_{i+1}(S_{i+1})\right] = \frac{1}{N} \sum_{n=1}^{N} \psi(S_i^{(n)})\hat{V}_{i+1}(S_{i+1}^{(n)})$$
(5.3)

and $\hat{V}_{i+1}(S_{i+1}) = \max \left\{ h_{i+1}(S_{i+1}), \hat{C}_{i+1}(S_{i+1}) \right\}$ are estimated value functions and $\hat{C}_{i+1}(S_{i+1}) = \hat{\beta}_{i+1}^{\top} \psi(S_{i+1})$ are estimated continuation functions.

As we can see, for good estimations of β , a lot effort is made towards the estimations of $\hat{B}_{\psi,i}$ given by (5.2), which requires computing the sum of N J×J matrices, where J is the number of basis functions. Usually, to achieve sufficient accuracy in β , the number of main Monte Carlo paths N is required to be large. This will cause extremely slow computing with respect to Equation (5.2). However, if we can find a way to construct our basis functions $\psi(x)$ such that the matrix $B_{\psi,i} = \mathbb{E}\left[\psi(S_i)\psi(S_i)^{\top}\right]$ is a J×J identity matrix

I and the estimation $\hat{B}_{\psi,i}$ is close to an identity matrix. Then we can simply discard $\hat{B}_{\psi,i}$ from (5.1) and construct a simplified estimator as

$$\hat{\beta}_i = \hat{B}_{\psi V,i} \tag{5.4}$$

which will give significant computing saving.

Notice that the qr entry of the matrix $B_{\psi,i}$ is given by

$$(B_{\psi,i})_{qr} = \mathbb{E}\left[\left(\psi(S_i)\psi(S_i)^{\top}\right)_{qr}\right] = \mathbb{E}\left[\psi_q(S_i)\psi_r(S_i)\right], \quad q, r \in \{1, \dots, J\}$$
 (5.5)

Thus, if we can construct our basis functions with the orthogonality such that

$$\mathbb{E}\left[\psi_q(S_i)\psi_r(S_i)\right] = \int_{-\infty}^{+\infty} \psi_q(S_i)\psi_r(S_i)p(S_i) \,\mathrm{d}S_i = \delta_{qr} = \begin{cases} 1 & q = r \\ 0 & q \neq r \end{cases}$$
(5.6)

where $p(S_i)$ is the unconditional probability density function of asset price state S_i , the simplified estimator (5.4) will then be valid. "Hermite polynomials" are promising candidates for the constructions of our basis functions due to the natural orthogonality inherent.

5.1 Hermite Polynomials

The probabilists' "Hermite Polynomials" are a classical orthogonal polynomial sequence named after Charles Hermite $^{[16]}$, defined by

$$H_k(x) = (-1)^k e^{x^2/2} \frac{\mathrm{d}^k}{\mathrm{d}x^k} e^{-x^2/2} = \begin{cases} 1, & k = 0\\ x, & k = 1\\ xH_{k-1}(x) - (k-1)H_{k-2}(x), & \text{for } k \ge 1 \end{cases}$$
(5.7)

The The most noticeable property of "Hermite Polynomials" is that they are orthogonal with respect to the weight function

$$w(x) = e^{-x^2/2} (5.8)$$

And the following equation holds for all probabilists' "Hermite Polynomials" [17].

$$\int_{-\infty}^{+\infty} H_q(x) H_r(x) e^{-x^2/2} \, \mathrm{d}x = \sqrt{2\pi} q! \delta_{qr}$$
 (5.9)

By rearranging, we get

$$\int_{-\infty}^{+\infty} \frac{H_q(x)}{\sqrt{q!}} \frac{H_r(x)}{\sqrt{r!}} \frac{e^{-x^2/2}}{\sqrt{2\pi}} dx = \delta_{qr}$$
 (5.10)

Notice that $\phi(x) = \frac{e^{-x^2/2}}{\sqrt{2\pi}}$ is the probability density of a standard normal distribution and let

$$\widetilde{\psi}_k(x) = \frac{H_k(x)}{\sqrt{k!}} \tag{5.11}$$

we get

$$\mathbb{E}\left[\widetilde{\psi}_q(x)\widetilde{\psi}_r(x)\right] = \int_{-\infty}^{+\infty} \widetilde{\psi}_q(x)\widetilde{\psi}_r(x)\phi(x) \,\mathrm{d}x = \delta_{qr}$$
 (5.12)

where the expectation is taking with respect to random a variable $x \sim N(0, 1)$. Comparing (5.12) with (5.6), we find that $\widetilde{\psi}_k(x)$ is a good candidate for our basis functions. The only thing we need to do is to convert our asset price state S_i to a random variable following a standard normal distribution.

5.2 Constructing Orthogonal Basis Functions through Hermite Polynomials

As we have seen in the previous section, if we can convert our state of the asset price S_i into a standard normal random variable, we are able to use (5.11) to construct a set of basis functions which are orthogonal to each other. For this purpose, instead of using Euler-Maruyama scheme as given in (2.6), we change our method to simulate the Monte Carlo paths using the exact solutions to SDE (2.4), given by

$$S_i = S_{i-1} \exp\left(\left(r - q - \frac{\sigma^2}{2}\right)\Delta t + \sigma \Delta W_i\right), \quad i = 1, \dots, M$$
(5.13)

Here, we assume the entire time horizon is equally divided. Under this method, the price state S_i has an explicit relation with the initial value S_0 , given by

$$S_i = S_0 \exp\left((r - q - \frac{\sigma^2}{2})i\Delta t + \sigma \sum_{k=1}^i \Delta W_k\right)$$
 (5.14)

Notice that the Brownian increments ΔW_k in (5.14) are independent to each other, S_i thus has an explicit log-normal distribution and $\log(S_i)$ follows a normal distribution

$$\log(S_i) \sim N\left(\log(S_0) + (r - q - \frac{\sigma^2}{2})i\Delta t, \sigma^2 i\Delta t\right)$$
(5.15)

Now, we can easily convert S_i into a standard normal random variable Y_i by

$$Y_i = \frac{\log(S_i) - \log(S_0) - (r - q - \frac{\sigma^2}{2})i\Delta t}{\sigma\sqrt{i\Delta t}} \sim N(0, 1)$$
(5.16)

Finally, we construct our basis functions through

$$\psi_j(S_i) = \widetilde{\psi}_k(Y_i) = \frac{H_k(Y_i)}{\sqrt{k!}}, \quad k = j - 1, \ j = 1, \dots, J$$
 (5.17)

where $H_k(x)$ is the "Hermite Polynomials" given by (5.7). By doing this, it's easy to verify that

$$\mathbb{E}\left[\psi_q(S_i)\psi_r(S_i)\right] = \mathbb{E}\left[\widetilde{\psi}_{q-1}(Y_i)\widetilde{\psi}_{r-1}(Y_i)\right] = \delta_{qr}$$
(5.18)

Thus, we essentially construct a set of basis functions who are orthogonal to each other with respect to the natural distribution of the underlying asset price sate S_i . To estimate the regression coefficients with these orthogonal basis functions, the simplified estimator (5.4) can be used, providing large amounts of computing saving.

5.3 Numerical Examples

To test the idea, we use the same example of an American put option written on a single non-dividend paying stock with the initial price $S_0 = 20$, the srike K = 20, interest rate r = 5%, volatility $\sigma = 0.4$ and maturity T = 1 respectively. As mentioned earlier, we do not use regression on the terminal time step t_M since the value functions are simply set as equal to the payoff functions at t_M . So, we start from the simplest case with 2 time steps and focus on the middle time step t_1 . We tested the Algorithm 3.2 using the orthogonal basis functions given in (5.17). For comparison, we tested both the usual estimator given by (5.1) and the simplified estimator given by (5.4). We first computed the estimated matrix $\hat{B}_{\psi,1} = \hat{\mathbb{E}}\left[\psi(S_1)\psi(S_1)^{\top}\right]$ and set the number of Monte Carlo paths as N=1e4, 1e5 and 1e6 respectively. We also fixed the number of basis functions as J=5. The results are shown in Table 5.1 below. As we can see, by using the orthogonal basis functions, the estimated matrix $\hat{B}_{\psi,1} = \hat{\mathbb{E}}\left[\psi(S_1)\psi(S_1)^{\top}\right]$ is close to an identity matrix I, as expected. The quality of this similarity with identity matrix improves with larger number of Monte Carlo paths N.

		N=1e4		
	0.001659	-0.01207	0.014806	0.006298 \
0.001659	0.982932	0.027992	-0.00831	0.043112
-0.01207	0.027992	0.981291	0.084783	-0.02209
0.014806	-0.00831	0.084783	0.962568	0.077781
0.006298	0.043112	-0.02209	0.077781	0.896297
		N=1e5		
/ 1	-0.0008	-0.00443	0.001724	-0.00217 \
-0.0008	0.993736	0.001858	-0.01202	0.019144
-0.00443	0.001858	0.982148	0.02813	-0.02248
0.001724	-0.01202	0.02813	0.966005	0.074931
$\setminus -0.00217$	0.019144	-0.02248	0.074931	0.936065
		N=1e6		
	0.000946	-0.00045	0.000104	0.000853 \
0.000946	0.999371	0.001517	0.000935	0.000187
-0.00045	0.001517	1.00083	0.002049	0.006765
0.000104	0.000935	0.002049	1.007879	0.008535
0.000853	0.000187	0.006765	0.008535	1.023918

Table 5.1: The estimated matrix $\hat{B}_{\psi} = \hat{\mathbb{E}} \left[\psi(S) \psi(S)^{\top} \right]$ using orthogonal basis functions. The parameters used are $S_0 = 20$, K = 20, r = 5%, $\sigma = 0.4$, T = 1, number of time steps M=2 and number of basis functions J=5.

Table 5.2 gives the estimated regression coefficients $\hat{\beta}_1$ and the corresponding computing time using the simplified estimator (5.4) compared with those given by the standard estimator (5.1). Again we set the number of Monte Carlo paths as N=1e4, 1e5 and 1e6

respectively. As shown in the table, the coefficients given by the simplified method are reasonably close to those obtained from the standard approach, and better accuracy was achieved with larger number of Monte Carlo paths. Also, by comparing the computing time used, we found the simplified approach was much faster than the standard approach, as expected.

	N=	1e4	N=	=1e5	N=1e6	
\hat{eta}_1	$ \begin{pmatrix} Standard \\ 2.618 \\ -2.137 \\ 0.678 \\ 0.149 \\ -0.162 \end{pmatrix} $	Simple $\begin{pmatrix} 2.607 \\ -2.085 \\ 0.590 \\ 0.245 \\ -0.224 \end{pmatrix}$	$ \begin{pmatrix} 2.621 \\ -2.109 \\ 0.662 \\ 0.126 \\ -0.137 \end{pmatrix} $	Simple $ \begin{pmatrix} 2.620 \\ -2.101 \\ 0.641 \\ 0.160 \\ -0.180 \end{pmatrix} $	$ \begin{array}{c} \text{Standard} \\ $	Simple $ \begin{pmatrix} 2.628 \\ -2.101 \\ 0.643 \\ 0.138 \\ -0.127 \end{pmatrix} $
Time(s)	0.0376	0.0072	0.3176	0.0571	3.386	0.6241

Table 5.2: The estimated regression coefficients $\hat{\beta}$ and the corresponding computing time based on orthogonal basis functions using simplified estimator $\hat{\beta}_i = \hat{B}_{\psi V,i}$ compared with those given by the standard estimator $\hat{\beta}_i = \hat{B}_{\psi,i}^{-1} \hat{B}_{\psi V,i}$. The parameters used are $S_0 = 20$, K = 20, r = 5%, $\sigma = 0.4$, T = 1, number of time steps M=2 and number of basis functions J=5. Platform used: Lenovo T400 laptop, Intel Core 2 Duo Pro 2.8Ghz, 4GB RAM.

Next, we tested the idea together with the LSM approach (Algorithm 3.3) and the duality approach (Algorithm 4.2) to see how well it works with pricing American options. We used two different number of main Monte Carlo paths. Because the accuracy in regression coefficients β is essential, we set N=1e6 for the pre-processing procedure for β estimations (Algorithm 3.2). Then we reset N=1e4 for fast processing with LSM and duality simulations. The approaches using orthogonal basis functions based on Hermite polynomials (both standard and simplified) were tested, compared with the results given by the weighted Laguerre polynomials defined as in (3.13). Other simulations settings used are the number of time steps M=32, the number of sub-successors for the duality estimations m=100 and the number of basis functions J=5. The results are presented in Table 5.3. As shown in the table, the results under different approaches are close to each other. While giving similar accuracies, the use of orthogonal basis functions generally gives smaller lower bounds from LSM and larger upper bounds from Duality, indicating wider lower-upper price ranges compared with those given by the basis functions using weighted Laguerre polynomials. Also, as expected, when using orthogonal basis functions, the simplified approach gives very close results compared with those obtained from the standard approach but with much faster speed.

To test the effects of time steps, we set the time steps as M=8, 16, 20, 24, 28, 32, 48 and 64 respectively and fixed other parameters as $S_0=15$, number of basis functions J=5. The number of Mote Carlo paths is set as N=1e4 for both the pre-processing of β estimations and the LSM and Duality calculations. The results are shown in Table 5.4.

	LSM				DUAL			
S_0	FDM	Weighted Laguerre	Orthogonal	Orthogonal Simplified	Weighted Laguerre	Orthogonal	Orthogonal Simplified	
10	10.000	9.965	9.962	9.962	10.047	10.033	10.037	
15	5.470	5.372	5.341	5.317	5.632	5.687	5.700	
20	2.733	2.671	2.630	2.682	2.860	2.933	2.944	
25	1.306	1.274	1.267	1.271	1.395	1.496	1.504	
Mean time (s)		Weighted Laguerre 111.06		Orthogonal 101.14		Orthogonal Simplified 20.22		

Table 5.3: Estimated lower bounds given by LSM and upper bounds given by Duality approach using the orthogonal basis functions based on Hermite polynomials, compared with the results based on weighed Laguerre polynomials and Finite Difference Method. The parameters used are $K=20,\ r=5\%,\ \sigma=0.4,\ T=1,\ \text{number of time steps}\ M=32,$ the number of basis functions J=5 and the number of sub-successors m=100 for duality estimations. The number of main Mote Carlo paths is set as N=1e6 for β estimations and N=1e4 for LSM and Duality estimations. The mean computing time used are listed in the last row.

		LSM			DUAL	
M 8 16 20 24 28 32 48 64	Weighted Laguerre 5.405 5.451 5.439 5.417 5.436 5.404 5.388 5.457	Orthoganal 5.387 5.436 5.433 5.432 5.432 5.403 5.373 5.422	Orthogonal Simplified 5.376 5.326 5.266 5.271 5.224 5.175 4.913 4.804	Weighted Laguerre 5.539 5.587 5.601 5.612 5.623 5.635 5.653 5.665	Orthoganal 5.562 5.622 5.643 5.666 5.681 5.704 5.724 5.735	Orthogonal Simplified 5.558 5.872 6.640 7.041 7.122 7.208 9.975 15.000
				ı		FDM=5.470

Table 5.4: Effects of time steps on the estimated lower bounds given by LSM and upper bounds given by Duality approach using the orthogonal basis functions based on Hermite polynomials, compared with the results based on weighed Laguerre polynomials. The parameters used are $S_0 = 15$, K = 20, r = 5%, $\sigma = 0.4$, T = 1, the number of basis functions J=5 and the number of sub-successors m=100 for duality estimations. The number of Mote Carlo paths is set as N=1e4 for both the pre-processing of β estimations and the LSM and Duality calculations. The Finite Difference Method gives a value of 5.470.

It's interesting to notice that the results given by the simplified approach using the orthogonal basis functions are very sensitive with respect to time steps. As shown in the table, when the number of time steps getting larger, the results obtained from the simplified orthogonal approach start to give unacceptable accuracies, especially in duality values. Recall that the effectiveness of the simplified approach depends on the accuracy of β estimations, which in turn depends on the similarity between the matrix $\hat{B}_{\psi} = \hat{\mathbb{E}} \left[\psi(S) \psi(S)^{\top} \right]$

and identity matrix I. This similarity depends on the number of Monte Carlo paths N, as shown in Table 5.1. In this case, we only set the number of Monte Carlo paths N=1e4 for the β estimations, which will give poor accuracy. On the other hand, the regression coefficients β are estimated by backward induction, as given by Algorithm 3.2. Thus, the errors in the estimations of β s will be accumulated step by step. This is the main reason why the results show larger errors with more time steps. To make the simplified orthogonal approach working with large number of time steps, we have to set a large number of Monte Carlo paths for the pre-processing of β estimation. Table 5.5 shows this effect. As we can see, when we increase N to be 1e6, the simplified approach worked again. This seems a main drawback of the simplified technique using the orthogonal basis functions and improvements are needed. But the technique presented here is still potentially beneficial for computational complexity reduction.

	LSM			DUAL		
N	Weighted Laguerre	Orthoganal	Orthogonal Simplified	Weighted Laguerre	Orthoganal	Orthogonal Simplified
1e4	5.457	5.422	4.804	5.665	5.735	15.000
1e6	5.460	5.476	5.413	5.654	5.736	5.759
Time used (s)	Weighted Laguerre		Orthoganal		Orthogonal Simplified	
N=1e4	1.93		1.74		0.34	
N=1e6	215.99		185.49		40.22	
					M = 64	$\overline{\mathrm{FDM} = 5.470}$

Table 5.5: Increased accuracy with simplified approach when using larger number of Monte Carlo paths. The parameters used are $S_0=15,~K=20,~r=5\%,~\sigma=0.4,~T=1,$ the number of basis functions J=5, the number of time steps M=64 and the number of sub-successors m=100 for duality estimations.

Chapter 6

Multilevel Monte Carlo Approach

Multilevel Monte Carlo (MLMC) is a technique originally suggested by Michael Giles^[11] in 2008. The technique can be used to achieve greater accuracy (reduce the variance of the Monte Carlo estimators) for the same computational cost. Since its first introduction, the Multilevel Monte Carlo technique has been rapidly developed for a variety of applications in computational finance. The main idea behind MLMC is to employ multiple sets of simulations with different time-steps (called levels) of the Monte Carlo paths. By constructing an unbiased estimator using the sum of these simulations under different levels, the variance of the estimator is expected to be reduced for a fixed computational cost, given the high correlations between the simulations under different levels. In this chapter, we are going to apply the MLMC technique into our problem of pricing American options and to test its effectiveness with variance reduction.

6.1 An Analysis of Standard Monte Carlo

We start with the standard Monte Carlo. Under the standard Monte Carlo framework, the aim is to numerically estimate the expectation $\mathbb{E}[Y]$, where Y = P(S) is a functional of a random variable S that follows a stochastic differential equation given by

$$dS(t) = \mu(S, t) dt + \sigma(S, t) dt$$
(6.1)

In finance, the random variable S is usually the state of the asset price process and the interested functionals are usually payoff functions. In the case of pricing American options, the functional Y becomes the optimal stopped payoff $h_{\tau}(S_{\tau})$ for the lower bounds estimations under Longstaff-Schwartz approach and $\max_{i=1,\cdots,M} \{h_i(S_i) - \mathscr{M}_i^*\}$ for the upper bounds estimation under Duality approach. Without the lost of generality, we will simply denote the target functional as Y.

Standard Monte Carlo aims to simulate the underlying random variable S by stepping, i.e., we approximate the continuous stochastic process S_t with a sequence of random variables $S_{\Delta t} = \{S_0, S_1, S_2 \cdots\}$ by dividing the time horizon with step Δt . This discretization can be achieved by various stepping schemes, such as Euler-Maruyama scheme (2.6). We

denote the target functional under this discretization as $Y_{\Delta t}$ and expect $\mathbb{E}[Y_{\Delta t}] \to E[Y]$ when $\Delta t \to 0$. Then, by sampling N paths of the underlying random variable S_i , the standard Monte Carlo estimator of the expected functional Y is given by

$$\hat{Y} = \frac{1}{N} \sum_{n=1}^{N} Y_{\Delta t}^{(n)} = \frac{1}{N} \sum_{n=1}^{N} P(S_{\Delta t}^{(n)})$$
(6.2)

where $Y_{\Delta t}^{(n)}$ refers the observed value with each individual sampled path $S_{\Delta t}^{(n)}$. By standard Monte Carlo results $\hat{Y} \to \mathbb{E}[Y]$, when $\Delta t \to 0$ and $N \to \infty$. But we could not make Δt to be 0 in practice. The standard Monte Carlo is usually performed with certain $\Delta t > 0$ and finite N, which will produce a mean square error defined by

$$MSE \equiv \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[Y]\right)^2\right] \tag{6.3}$$

The major concern when performing Monte Carlo simulations is to make the root mean square error small, i.e. to estimate Y with accuracy ϵ such that $\sqrt{\text{MSE}} \leq \epsilon$ as efficiently as possible. That is to minimize the computational complexity required to achieve the required mean square error. We can rewrite the definition of mean square error as

$$MSE = \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[Y]\right)^{2}\right]$$

$$= \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[\hat{Y}] + \mathbb{E}[\hat{Y}] - \mathbb{E}[Y]\right)^{2}\right]$$

$$= \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[\hat{Y}]\right)^{2}\right] + \left(\mathbb{E}[\hat{Y}] - \mathbb{E}[Y]\right)^{2}$$
(6.4)

where the first term is the variance of the Monte Carlo estimator, given by

$$\operatorname{Var}[\hat{Y}] = \frac{1}{N^2} \operatorname{Var} \left[\sum_{n=1}^{N} P(S_{\Delta t}^{(n)}) \right] = \frac{1}{N} \operatorname{Var}[P(S_{\Delta t})]$$
(6.5)

and the second term is the square of the bias due to discretization approximation. The discretization like Euler-Maruyama scheme (2.6) gives a bias $|\mathbb{E}[\hat{Y}] - \mathbb{E}[Y]| = O(\Delta t)$, and thus the mean square error given by the standard Monte Carlo will be

$$MSE = \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[Y]\right)^2\right] = O(\frac{1}{N}) + O(\Delta t^2)$$
(6.6)

What we need is to make the root mean square error proportional to ϵ , that is MSE = $O(\epsilon^2)$, which gives

$$\frac{1/N = O(\epsilon^2)}{\Delta t^2 = O(\epsilon^2)} \Rightarrow \frac{N = O(\epsilon^{-2})}{\Delta t = O(\epsilon)}$$
(6.7)

The number of time steps for the discretization is $M = O(\Delta t^{-1})$ and thus the computational cost of standard Monte Carlo is given by

$$C = NM = O(\epsilon^{-3}) \tag{6.8}$$

On the other hand, given a fixed computational cost C = NM, the mean square error is approximately given by

$$MSE \approx \frac{c_1}{N} + \frac{c_2}{M^2} = \frac{c_1}{N} + \frac{c_2 N^2}{C^2}$$
 (6.9)

where c_1 and c_2 are positive constants. To minimize MSE, we take the derivative of (6.9) with respect to N and equate the resulted equation to 0 and finally get

$$N = \left(\frac{c_1 C^2}{2c_2}\right)^{1/3}, \ M = \left(\frac{2c_2 C}{c_1}\right)^{1/3} \tag{6.10}$$

and thus

$$\frac{c_1}{N} = \left(\frac{2c_1^2c_2}{C^2}\right)^{1/3}, \ \frac{c_2}{M^2} = \left(\frac{c_1^2c_2}{4C^2}\right)^{1/3} \tag{6.11}$$

indicating that the mean square error comes from the variance of the Monte Carlo estimator is twice as the square of the bias due to discretization.

6.2 Multilevel Monte Carlo

Multilevel Monte Carlo (MLMC) uses different time resolutions, i.e. number of time steps at different levels, which might have the form $M_l = 2^l$, $l = 0, 1, \dots, L$ and the corresponding time interval is $\Delta t_l = 2^{-l}T$, $l = 0, 1, \dots, L$. Denote P as our target functional, which might be a payoff function. For American options, the target functional P will be the optimal stopped payoff $h_{\tau}(S_{\tau})$ for the lower bounds estimations under Longstaff-Schwartz approach and $\max_{i=1,\dots,M} \{h_i(S_i) - \mathcal{M}_i^*\}$ for the upper bounds estimation under Duality approach respectively.

Let P_l be the approximation of our target functional on level l, then the expected value $\mathbb{E}[P_L]$ on the finest level can be constructed by

$$\mathbb{E}[P_L] = \mathbb{E}[P_0] + \sum_{l=1}^{L} \mathbb{E}[P_l - P_{l-1}]$$
(6.12)

which provides a basic estimator under the MLMC framework.

The idea behind MLMC is to estimate each of the expectations on the right hand side of (6.12) independently in a way which minimizes the overall variance for a given fixed computational cost or minimizes the computational cost at a given variance requirement. Now, denote \hat{Y}_0 as the estimator of $\mathbb{E}[P_0]$ with N_0 sample paths, and \hat{Y}_l , $l=1,2,\cdots L$ be the estimator of $\mathbb{E}[P_l-P_{l-1}]$ using N_l samples paths. The simplest way to construct these estimators is a mean of N_l independent paths, given by

$$\hat{Y}_l = \frac{1}{N_l} \sum_{n=1}^{N_l} (P_l^{(n)} - P_{l-1}^{(n)})$$
(6.13)

What's important here is that $P_l^{(n)} - P_{l-1}^{(n)}$ should come from two different discrete approximations but the same underlying Monte Carlo path^[18]. By doing this, the difference is

small on finer levels and so is its variance. Hence very few samples will be required on finer levels to achieve acceptable accuracies in the expected value.

By these notations, we can finally write the MLMC estimator as

$$\hat{Y} = \sum_{l=0}^{L} \hat{Y}_l \tag{6.14}$$

It's easy to verify that

$$\mathbb{E}[\hat{Y}_l] = \frac{1}{N_l} \sum_{n=1}^{N_l} \mathbb{E}[P_l^{(n)} - P_{l-1}^{(n)}] = \mathbb{E}[P_l - P_{l-1}]$$
(6.15)

and

$$\mathbb{E}[\hat{Y}] = \sum_{l=0}^{L} \mathbb{E}[\hat{Y}_{l}] = \mathbb{E}[P_{0}] + \sum_{l=1}^{L} \mathbb{E}[P_{l} - P_{l-1}] = \mathbb{E}[P_{L}]$$
(6.16)

This indicates that MLMC provides an unbiased estimator with respect to the finest level approximation and thus the final accuracy depends on the accuracy of the finest level L. The variance of the MLMC estimator is given by

$$\operatorname{Var}\left[\hat{Y}\right] = \sum_{l=0}^{L} \operatorname{Var}\left[\hat{Y}_{l}\right] = \sum_{l=0}^{L} \frac{1}{N_{l}} \mathbb{V}_{l}$$
(6.17)

where $V_l = \text{Var}[P_l - P_{l-1}]$ is the variance at each level.

Michael Giles proved the following complexity theorem^[11] with respect to the MLMC approach, which we give here without proof.

Theorem 6.1. Complexity theorem of $MLMC^{[11]}$

Let P denote a functional of the solution of SDE (6.1) for a given Brownian path W(t), and let P_l denote the corresponding level l numerical approximation with the time discretization using interval $\Delta t_l = \frac{T}{M_l} = \frac{T}{2^l}$ steps. If there exit independent estimators \hat{Y}_l based on N_l Monte Carlo sample paths, and positive constants $\alpha \geq \frac{1}{2}$, β , c_1 , c_2 , c_3 such that

(i)
$$\mathbb{E}[P_l - P] \le c_1 \Delta t_l^{\alpha}$$

(ii)
$$\mathbb{E}[\hat{Y}_l] = \begin{cases} \mathbb{E}[P_0], \ l = 0 \\ \mathbb{E}[P_l - P_{l-1}], \ l > 0 \end{cases}$$

(iii)
$$\mathbb{E}[\hat{Y}_l] \le c_2 N_l^{-1} \Delta t_l^{\beta}$$

(iv) C_l , the computational complexity of \hat{Y}_l , is bounded by $C_l \leq c_3 N_l \Delta t_l^{-1}$

then there exists a positive constant c_4 such that for any $\epsilon < e^{-1}$, there are values L and N_l for which the multilevel estimator

$$\hat{Y} = \sum_{l=1}^{L} \hat{Y}_{l}$$

has an MSE with bound

$$\mathrm{MSE} \equiv \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[P]\right)^2\right] < \epsilon^2$$

with a computational complexity C with bound

$$C \le \begin{cases} c_4 \epsilon^{-2}, \ \beta > 1 \\ c_4 \epsilon^{-2} (\log \epsilon)^2, \ \beta = 1 \\ c_4 \epsilon^{-2 - (1 - \beta)/\alpha}, \ 0 < \beta < 1 \end{cases}$$

As we can see from the above theorem, the complexity of MLMC given a root mean square error ϵ is reduced to $O(\epsilon^{-2})$ compared with that of the standard Monte Carlo, which is $O(\epsilon^{-3})$. What we are more interested here is that, given a fixed computational complexity, how to minimize the variance of the combined estimator \hat{Y} . Recall that the mean square error is given by

$$MSE = \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[P]\right)^{2}\right]$$

$$= \mathbb{E}\left[\left(\hat{Y} - \mathbb{E}[\hat{Y}]\right)^{2}\right] + \left(\mathbb{E}[\hat{Y}] - \mathbb{E}[P]\right)^{2}$$
(6.18)

where the first term is the variance of the estimator given by

$$\operatorname{Var}\left[\hat{Y}\right] = \sum_{l=0}^{L} \operatorname{Var}\left[\hat{Y}_{l}\right] = \sum_{l=0}^{L} \frac{1}{N_{l}} \mathbb{V}_{l} = \sum_{l=0}^{L} \frac{1}{N_{l}} \operatorname{Var}[P_{l} - P_{l-1}]$$

and the second term is the bias term. Giles^[11] proved that the upper bounds of the variance and bias errors are both $\frac{1}{2}\epsilon^2$, given the conditions in Theorem 6.1 hold.

For given computational cost of $C = \sum_{l=0}^{L} N_l \Delta t_l^{-1} T$, to minimize the variance of \hat{Y} , we can set up a Lagrangian function to find minimum

$$L = \sum_{l=0}^{L} \frac{1}{N_l} \mathbb{V}_l + \lambda \left(\sum_{l=0}^{L} N_l \Delta t_l^{-1} T - C \right)$$

Taking the first order derivative with respect to N_l and equating to 0, we get

$$N_l = \lambda^{-\frac{1}{2}} \sqrt{\frac{\mathbb{V}_l \Delta t_l}{T}}$$

therefore

$$\operatorname{Var}\left[\hat{Y}\right] = \sum_{l=0}^{L} \frac{1}{N_l} \mathbb{V}_l = \sum_{l=0}^{L} \frac{\sqrt{\lambda T}}{\sqrt{\mathbb{V}_l \Delta t_l}} \mathbb{V}_l$$

What we want is $Var[\hat{Y}] \leq \epsilon^2/2$ and thus we can get

$$\lambda^{-\frac{1}{2}} \ge 2\epsilon^{-2} \sum_{l=0}^{L} \sqrt{\mathbb{V}_l T / \Delta t_l}$$

and the optimal number of sample paths for each level is

$$N_l = 2\epsilon^{-2} \sqrt{\mathbb{V}_l \Delta t_l} \sum_{l=0}^{L} \sqrt{\mathbb{V}_l / \Delta t_l}$$
(6.19)

We notice that the optimal number of level paths N_l is proportional to $\sqrt{\mathbb{V}_l \Delta t_l}$. In practice, we fix the overall computational cost as C and let $N_l = c_1 \sqrt{\mathbb{V}_l \Delta t_l}$, thus we will have

$$C = \sum_{l=0}^{L} N_l \Delta t_l^{-1} T = c_1 \sum_{l=0}^{L} \sqrt{\frac{\mathbb{V}_l}{\Delta t_l}} T$$

Solving for c_1 we get

$$c_1 = \frac{C}{\sum_{l=0}^{L} \sqrt{\frac{\mathbb{V}_l}{\Delta t_l}} T}$$

Then finally, the optimal number of sample paths for each level with a fixed computational cost C is

$$N_l = \frac{C\sqrt{\mathbb{V}_l\Delta t_l}}{\sum_{l=0}^L \sqrt{\frac{\mathbb{V}_l}{\Delta t_l}}T}$$

If the time interval for each level is given by $\Delta t_l = T/2^l$, then we finally get

$$N_{l} = \frac{C\sqrt{\mathbb{V}_{l}2^{-l}}}{\sum_{l=0}^{L}\sqrt{\mathbb{V}_{l}2^{l}}}$$
(6.20)

In practice, the variance at each level V_l can be estimated by a pilot run of the MLMC estimator using a fixed number of sample paths \tilde{N}_l at each level. Then, the optimal number N_l can be calculated using (6.20), which in turn can be used to implement the actual MLMC algorithm. Furthermore, notice that

$$V_{l} = \text{Var}[P_{l} - P_{l-1}] = \text{Var}[P_{l}] + \text{Var}[P_{l-1}] - \text{Cov}[P_{l}, P_{l-1}]$$
(6.21)

thus the MLMC method will give better variance reduction if the approximations of our target functional P are highly correlated between levels.

6.3 Numerical Examples

As we did in the previous chapters, we are going to apply the Multilevel Monte Carlo technique into our problem of pricing American options. We continue to use the same simple example of an American put option written on a single non-dividend paying stock with the srike K=20, interest rate r=5%, volatility $\sigma=0.4$ and maturity T=1 respectively. Recall that the pricing is a 2-stage process. Firstly, we need to use the regression method to estimate the regression coefficients β for the purpose of estimating the continuation values, which is done by the pre-processing by backward induction (Algorithm 3.2). After that, we can either estimate a lower bound of the American option price using the Longstaff-Schwartz (LSM) optimal stopping algorithm (Algorithm 3.3) or estimate an upper bound

of the price using the Duality approach through martingales (Algorithm 4.2). Usually, the first stage of β estimations is a prerequisite for good estimations of either lower bounds or upper bounds. Thus, we are not going to test the MLMC on this stage and will use the standard Monte Carlo with the finest level settings to estimate regression coefficients β which are available for all other levels to use. Our testing with MLMC is on the second stage, i.e. the estimations of lower or upper bounds and our target functionals at each level are given by

$$P_{l} = \begin{cases} h_{\tau_{l}^{*}}(S_{\tau_{l}^{*}}), \tau_{l}^{*} = \min \left\{ \tau_{i} \in \{t_{1}, \cdots, t_{M_{l}}\} : h_{i}(S_{i}) \geq C_{i}(S_{i}) \right\}, & \text{for LSM} \\ \max_{i=1, \cdots, M_{l}} \left\{ h_{i}(S_{i}) - \mathscr{M}_{i}^{*} \right\}, & \text{for Duality} \end{cases}$$

$$(6.22)$$

where $M_l = 2^l$, $l \in \{1, \dots, L\}$ is the number of time steps at each level. We fixed the overall computational as $C = NM_L$, where N = 1e5 is fixed and we also fix the finest level as L=7. We use (6.20) to calculate the optimal number of sample paths at each level through a pilot run with $\tilde{N}_l=1e4$. Here, we start our level from l=1 since l=0 corresponds to an European option, which is not applicable in our problem. Our MLMC estimator thus becomes

$$\mathbb{E}[P_L] = \mathbb{E}[P_1] + \sum_{l=2}^{L} \mathbb{E}[P_l - P_{l-1}]$$
(6.23)

For faster processing, instead of using the weighted Laguerre polynomials, we use simple Laguerre polynomials as our basis functions. The initial stock prices were set as $S_0=12.5$, 20 and 25 respectively, representing the in-the-money, at-the-money and out-of-the-money options. The results are listed in Table 6.1.

As we can see from the results, the MLMC approach gives very close price estimations for both the lower bounds using LSM method and the upper bounds using the Duality method, which confirms that the MLMC estimator is unbiased. By comparing the variances, we notice that the variances are noticeably reduced with MLMC for the LSM estimations with the cases of at-the-money option $(S_0=20)$ and out-of-the-money option $(S_0=25)$. For these cases, the variances of MLMC are about only 30% of those with standard MC. This is indeed what we expected. By looking at the variances \mathbb{V}_l at each level for these two cases, we notice that the variances are dramatically decreasing when we move forward to higher levels. Recall that the variances at each level depend on the correlations between the functionals at adjacent coarse and fine levels $\rho(P_l, P_{l-1})$ (see Equation (6.21)). Higher correlations between P_l and P_{l-1} will cause lower variances at each level, which in turn cause the optimal number of sample paths at each level N_l to be smaller (recall that N_l is proportional to $\sqrt{\mathbb{V}_l\Delta t_L}$). Notice that these correlations are all very close to 1 for the two cases and increase with levels, giving good overall variance reduction under MLMC. As for the in-the-money case $(S_0 = 12.5)$, the situation changed. Although the correlations $\rho(P_l, P_{l-1})$ still increase with levels, they become much weaker, especially for lower levels. This in turn causes much higher level variances \mathbb{V}_l compared with the other two cases. And thus, the variance under MLMC is even larger than its standard counterpart, about 170%.

CASE1:	CASE1: $S_0 = 12.5$ FDM = 7.528									
	LS	$_{\mathrm{SM}}$		DUAL						
level	N_l	\mathbb{V}_{l}	$\rho(P_l, P_{l-1})$	level	N_l	\mathbb{V}_{l}	$\rho(P_l, P_{l-1})$			
1	$858\dot{9}70$	17.876	N/A	1	345730	0.171	N/A			
2	259758	3.365	0.902	2	268972	0.208	0.252			
$\frac{2}{3}$	170270	2.870	0.902	$\frac{2}{3}$	153913	0.137	0.225			
4	99154	1.974	0.922	4	93679	0.102	0.170			
5	57649	1.270	0.943	5	62551	0.087	0.119			
6	37267	1.039	0.949	6	41468	0.080	0.089			
7	22379	0.709	0.962	7	28491	0.075	0.085			
$\overline{\mathrm{LSM}_{\mathrm{MLMC}}}$	7.448	$\mathbb{V}_{\mathrm{MLMC}}$	1.52E-04	DUAL _{MLMC}	7.737	$\mathbb{V}_{\mathrm{\underline{M}LMC}}$	9.17E-06			
LSM_{std}	7.456	$\mathbb{V}_{\mathrm{std}}$	8.81E-05	$\mathrm{DUAL}_{\mathrm{std}}$	7.741	$\mathbb{V}_{\mathrm{std}}$	4.06E-07			
CASE2:	$\mathbf{S_0} \!=\! 20$	$\overline{\mathbf{FDM}} = 2$.733							
	LS	$_{ m SM}$		DUAL						
level	N_l	\mathbb{V}_{l}	$\rho(P_l, P_{l-1})$	level	N_l	\mathbb{V}_{l}	$\rho(P_l, P_{l-1})$			
1	1724635	14.287	N/A	1	370052	0.291	N/A			
2	234803	0.535	0.982	2	259579	0.411	0.101			
$\frac{2}{3}$	135814	0.347	0.986	$\frac{2}{3}$	144198	0.236	0.260			
4	91932	0.325	0.986	4	89784	0.189	0.426			
5	51647	0.204	0.991	5	61105	0.170	0.469			
6	28273	0.139	0.994	6	41872	0.161	0.464			
7	18687	0.111	0.995	7	29658	0.160	0.435			
$\overline{\mathrm{LSM}_{\mathrm{MLMC}}}$	2.651	$\mathbb{V}_{ ext{MLMC}}$	3.15E-05	$\mathrm{DUAL}_{\mathrm{MLMC}}$	3.031	$\mathbb{V}_{\mathrm{\underline{M}LMC}}$	1.81E-05			
LSM_{std}	2.639	$\mathbb{V}_{\mathrm{std}}$	1.09E-04	$\mathrm{DUAL}_{\mathrm{std}}$	3.031	$\mathbb{V}_{\mathrm{std}}$	1.39E-06			
CASE3:	$\mathbf{S_0}\!=\!25$	$\overline{\mathrm{FDM}} = 1$.306	•						
	LS	$_{ m SM}$		DUAL						
level	N_l	\mathbb{V}_{l}	$\rho(P_l, P_{l-1})$	level	N_l	\mathbb{V}_{l}	$\rho(P_l, P_{l-1})$			
1	1749086	9.212	N/A	1	311562	0.167	N/A			
2	291308	0.532	0.973	2	267823	0.253	0.207			
$\frac{2}{3}$	157964	0.279	0.982	$\frac{2}{3}$	159286	0.164	0.510			
4	86714	0.176	0.987	4	96102	0.118	0.674			
5	46791	0.107	0.992	5	61579	0.099	0.713			
6	30232	0.078	0.994	6	41574	0.091	0.712			
7	16042	0.050	0.996	7	28612	0.088	0.699			
$\frac{\mathrm{LSM}_{\mathrm{MLMC}}}{\mathrm{LSM}_{\mathrm{std}}}$	1.281 1.280	$\mathbb{V}_{ ext{MLMC}}$ $\mathbb{V}_{ ext{std}}$	1.88E-05 5.86E-05	$\begin{array}{c c} DUAL_{MLMC} \\ DUAL_{std} \end{array}$	1.695 1.697	$\mathbb{V}_{\substack{\mathrm{MLMC} \\ \mathbb{V}_{\mathrm{std}}}}$	1.06E-05 1.41E-06			

Table 6.1: The MLMC pricing of American put options. The parameters used in simulations are $K=20, r=5\%, \sigma=0.4, T=1$, the number of basis functions J=5 and the number of sub-successors m=100 for duality estimations. The number of finest levels is set as L=7 and total computational cost is fixed at $C=NM_L=1e4\times2^7$. In the table, N_l , \mathbb{V}_l and $\rho(P_l,P_{l-1})$ represent the number of sample paths at each level, the variance at each level and the correlation coefficients between the functionals at adjacent coarse and fine levels. LSM_{MLMC} and LSM_{std} represent the lower bound estimations using LSM method under MLMC and standard Mote Carlo respectively. DUAL_{MLMC} and DUAL_{std} are corresponding upper bound estimations using Duality approach. \mathbb{V}_{MLMC} and \mathbb{V}_{std} are corresponding variances.

Recall that higher levels, i.e. finer time steps correspond to more exercise opportunities for our American options under the question. The simulation results given here indicate that the lower bounds of the price of an American option (i.e. the optimal stopping values given by the LSM approach) are generally highly correlated with respect to the number of exercises opportunities and this correlation becomes weaker when we move from out-of-money options to in-the-money options.

What surprised us is that the MLMC method is not working well with the Duality estimations. Although it still gives an unbiased estimation and overally gives smaller variances with respect to those given by LSM, its variances are much higher if compared with those given by standard Monte Carlo, about 7.5 times for out-the-money case, 13 times for the at-the-money case and 22.5 times for the in-the-money case respectively. The direct reason behind is that there are much weaker correlations exist between P_l and P_{l-1} for the Duality estimations. The maximum correlation is only about 0.7 and the minimum is extremely small with a value of 0.085, which in turn causes relatively high level variances V_l . On the other hand, the correlations $\rho(P_l, P_{l-1})$ do not generally increase with levels and they even decrease with levels for the in-the-money case, which is in contrary with our expectation. The results shown here indicates that the duality values are relatively weakly correlated with different number of exercise opportunities. The actual reason behind this is still unclear.

6.4 Improved MLMC for Lower Bounds Estimation using Probability Weighted Payoff Functions and Brownian Bridge Interpolations

As we have seen in the previous section, the MLMC method worked relatively poor with the lower bounds estimations under LSM approach for the case of in-the-money option. The main reason is that the correlations between the functionals at adjacent coarse and fine levels $\rho(P_l, P_{l-1})$ become relatively weaker. Recall that for the lower bounds estimation, our target functional is given by

$$P_{l} = h_{\tau_{l}^{*}}(S_{\tau_{l}^{*}}) = \sum_{i=1}^{M_{l}} h_{i}(S_{i}) \mathbb{1}_{[t_{i} = \tau_{l}^{*}]}$$

$$(6.24)$$

where $\tau_l^* = \min \{ \tau_i \in \{t_1, \dots, t_{M_l}\} : h_i(S_i) \geq C_i(S_i) \}$ is the optimal stopping time under level l. Thus, we can see the functional P_l is non-smooth with respect to every individual simulated sample path S_i . Thus, in order to increase the correlations of our functionals between adjacent coarse and fine levels, we need to find a way to smooth P_l . This can be done by assigning a weight to the payoffs at every time steps $h_i(S_i)$ and summing them up instead of using the single stopped value with $h_{\tau}^*(S_{\tau}^*)$. We construct the weights using a probabilistic approach. As we know, an investor will choose to exercise an American option when the payoff $h_i(S_i)$ exceeds the continuation value $C_i(S_i)$ for the first time. We slightly

changed this rule by assigning an artificial conditional probability of exercising at every time step given that option has not been exercised before. This probability should depend on the difference between $h_i(S_i)$ and $C_i(S_i)$. The greater difference gives larger probability. We define this probability by

$$\begin{cases}
\mathbb{P}_{i}(S_{i}) = \Phi\left(\lambda\left(h_{i}(S_{i}) - C_{i}(S_{i})\right)\right), & i = 1, \dots, M_{l} - 1 \\
\mathbb{P}_{M_{l}}(S_{M_{l}}) = 1
\end{cases}$$
(6.25)

where $\Phi(x)$ is the standard normal cumulative distribution function and λ is a controlling parameter for smoothing. And we define our target functional P_l as

$$P_{l} = \sum_{i=1}^{M_{l}} W_{i}(S_{i}) h_{i}(S_{i}) = \sum_{i=1}^{M_{l}} \left\{ \mathbb{P}_{i}(S_{i}) \prod_{j=1}^{i-1} \left[1 - \mathbb{P}_{j}(S_{j})\right] \right\} h_{i}(S_{i})$$
(6.26)

By doing this, we essentially assign a weighting on payoffs along the entire Monte Carlo path. As we can see, when $\lambda \to \infty$, the probability defined above will be 1 for any case that $h_i(S_i) > C_i(S_i)$ and 0 otherwise. Thus, for extremely large λ , the functional P_l defined by (6.26) is a coincidence with the original optimal stopping value defined by (6.24). And smaller λ will smooth the payoff along the sample path and thus increase the correlations between different levels. In practice with MLMC, to keep the estimator's unbiasedness, we will replace the original functional with (6.26) and gradually increase λ along the levels. At lower levels, we make λ small to increase correlations between P_l and P_{l-1} . At highest level L, we set a very large λ so as to make P_L a close approximation to the original problem and our MLMC estimator $\mathbb{E}[P_L] = \mathbb{E}[P_1] + \sum_{l=2}^{L} \mathbb{E}[P_l - P_{l-1}]$ will keep to be unbiased.

We can now enhance the correlations $\rho(P_l, P_{l-1})$ further by "Brownian Bridge interpolations". As we know, the functionals at coarse level P_{l-1} are constructed on Monte Carlo points $S_i^{l-1}, i \in \{0, 1, \dots, M_{l-1} = 2^{l-1}\}$. Comparing with the functionals at fine level P_l , which are constructed on points $S_i^l, i \in \{0, \dots, M_l = 2^l\}$, we have fewer number of points at coarse level. These missing points will relatively reduce the correlations $\rho(P_l, P_{l-1})$. In order to make the points at coarse level coincident to those at fine level, we use Brownian Bridge interpolations to construct extra MC points between S_i^{l-1} and S_{i+1}^{l-1} . By definition, the Brownian Bridge interpolation at time $t \in (i\Delta t_{l-1}, (i+1)\Delta t_{l-1})$ for $i \in \{0, \dots, 2^{l-1}-1\}$ is given by [19]

$$S_t^{l-1} = S_i^{l-1} + \alpha (S_{i+1}^{l-1} - S_i^{l-1}) + \sigma S_i^{l-1} \left(W_t^{l-1} - W_{i \Delta t_{l-1}}^{l-1} - \alpha \Delta W_{i+1}^{l-1} \right)$$

where, $\alpha = (t - i\Delta t_{l-1})/\Delta t_{l-1}$, and ΔW_{i+1}^{l-1} is the corresponding Brownian increments at coarse level. If we construct the interpolation exactly at the mid-point of the time interval, we will have $\alpha = 1/2$ and the interpolation now becomes

$$\begin{split} S_{i+\frac{1}{2}}^{l-1} &= S_{i}^{l-1} + \frac{1}{2} (S_{i+1}^{l-1} - S_{i}^{l-1}) + \sigma S_{i}^{l-1} \left(W_{(i+\frac{1}{2})\Delta t_{l-1}}^{l-1} - W_{i\Delta t_{l-1}}^{l-1} - \frac{1}{2} \Delta W_{i+1}^{l-1} \right) \\ &= \frac{1}{2} \left(S_{i}^{l-1} + S_{i+1}^{l-1} \right) + \sigma S_{i}^{l-1} \left(\Delta W_{2i+1}^{l} - \frac{1}{2} \left(\Delta W_{2i+1}^{l} + \Delta W_{2i+2}^{l} \right) \right) \\ &= \frac{1}{2} \left[S_{i}^{l-1} + S_{i+1}^{l-1} + \sigma S_{i}^{l-1} \left(\Delta W_{2i+1}^{l} - \Delta W_{2i+2}^{l} \right) \right] \quad \text{for } i \in \{0, \dots, 2^{l-1} - 1\} \end{split}$$

where ΔW_{2i+1}^l and ΔW_{2i+2}^l are corresponding Brownian increments used to construct MC points at fine level. Finally, we construct our functional P_{l-1} on the MC points S_i^{l-1} together with the interpolations $S_{i+1/2}^{l-1}$ using the same weighted payoff functions defined in (6.26). By doing this, we essentially introduce extra points at level l-1 such that the time stepping is exactly same between levels l and l-1 and the correlations between P_l and P_{l-1} are expected to be increased.

The same example of the American put option was used to test the ideas. We set the controlling parameter $\lambda = \{1, 5, 10, 50, 250, 1000, 100000\}$ respectively for the different levels. And also, for improving accuracies, we simulated the MC paths using the exact SDE solution (5.13) instead of using Euler-Maruyama scheme. The results are shown in Table 6.2. We tested both the probability weighted functions with and without Brownian Bridge interpolations. As expected, the probability weighted payoff functions are better fit into the MLMC method. For the case without Brownian Bridge interpolation, the correlations $\rho(P_l, P_{l-1})$ are relatively higher with the weighted payoff functions, especially for the inthe-money case $(S_0=12.5)$, giving lower variances V_l at each level. As a result, the overall variances are reduced by about 40%~50% compared to those with the original non-smooth payoff functions. For the in-the-money case $(S_0=12.5)$, the MLMC slightly overperformed the standard MC with the use of probability weighted payoff functions while it originally underperformed the standard MC with the non-smooth payoff functions. The most promising results were provided by the Brownian Bridge interpolations. As we can see from the results, although the interpolation method produced relatively smaller estimations of the option values, the correlations $\rho(P_l, P_{l-1})$ were significantly improved with the interpolations. The correlation coefficients were all very close to 1. As a result, the variances were reduced further, giving an average reduction of about 90% compared with the standard MC method. This confirms that the weighted payoff functions jointly with the Brownian Bridge interpolation technique will significantly improve the MLMC performances.

	ORIGINAL			WEIGHTED			WEIGHTED INTERPOLATION			
level 1 2 3 4 5 6 7	N_l 858970 259758 170270 99154 57649 37267 22379	\mathbb{V}_l 17.876 3.365 2.870 1.974 1.270 1.039 0.709	$\rho(P_l, P_{l-1})$ N/A 0.902 0.902 0.922 0.943 0.949 0.962	$ \begin{array}{c c} N_l \\ 952024 \\ 212153 \\ 133481 \\ 79237 \\ 56089 \\ 40084 \\ 26184 \end{array} $	$\begin{array}{c} \mathbb{V}_l \\ 12.220 \\ 1.210 \\ 0.961 \\ 0.726 \\ 0.657 \\ 0.763 \\ 0.552 \end{array}$	$\begin{array}{c} \rho(P_l,P_{l-1}) \\ \text{N/A} \\ 0.960 \\ 0.961 \\ 0.968 \\ 0.969 \\ 0.961 \\ 0.970 \end{array}$	$\begin{array}{c} N_l \\ 2921330 \\ 99807 \\ 43612 \\ 29881 \\ 26756 \\ 24230 \\ 25970 \\ \end{array}$	0.0312 0.0113 0.0107 0.0179 0.0276 0.0223	$\begin{array}{c} \rho(P_l,P_{l-1}) \\ \text{N/A} \\ 0.9986 \\ 0.9994 \\ 0.9994 \\ 0.9991 \\ 0.9985 \\ 0.9988 \end{array}$	
	$egin{array}{c} \operatorname{LSM}_{\operatorname{MLMC}} \ \mathbb{V}_{\operatorname{MLMC}} \end{array}$		7.448 1.52E-04	$\begin{array}{c c} LSM_{MLMC} \\ \mathbb{V}_{MLMC} \end{array}$		7.513 8.67E-05	$\begin{array}{c c} \operatorname{LSM}_{\operatorname{MLMC}} \\ \mathbb{V}_{\operatorname{MLMC}} \end{array}$		7.314 7.78E-06	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$										
	ORIGINAL		WEIGHT		ГЕО	WEIGHT INTERPOL				
level 1 2 3 4 5 6 7	N_l 1724635 234803 135814 91932 51647 28273 18687	0.535 0.347 0.325 0.204 0.139 0.111	$\rho(P_l, P_{l-1})$ N/A 0.982 0.986 0.986 0.991 0.994 0.995	1942950 145718 91552 78555 51840 29798 21687	V_l 9.446 0.106 0.084 0.127 0.099 0.081 0.085	$\rho(P_l, P_{l-1})$ N/A 0.995 0.996 0.994 0.996 0.996 0.996	$ \begin{vmatrix} N_l \\ 4264546 \\ 143460 \\ 60162 \\ 41234 \\ 24260 \\ 10012 \\ 8898 \end{vmatrix} $	$\begin{array}{c} \mathbb{V}_l \\ 9.4384 \\ 0.0211 \\ 0.0065 \\ 0.0055 \\ 0.0059 \\ 0.0032 \\ 0.0051 \end{array}$	$\begin{array}{c} \rho(P_l,P_{l-1}) \\ N/A \\ 0.9990 \\ 0.9997 \\ 0.9998 \\ 0.9997 \\ 0.9999 \\ 0.9998 \\ \end{array}$	
	$ig egin{array}{c} \mathrm{LSM}_{\mathrm{MLMC}} \ \mathbb{V}_{\mathrm{MLMC}} \end{array}$		2.651 3.15E-05	$\begin{array}{c c} \operatorname{LSM}_{\operatorname{MLMC}} \\ \mathbb{V}_{\operatorname{MLMC}} \end{array}$		2.636 1.67E-05	$\left \begin{array}{c} \mathrm{LSM}_{\mathrm{MLMC}} \\ \mathbb{V}_{\mathrm{MLMC}} \end{array}\right $		2.576 3.74E-06	
	CAS	E3: S	$_0 = 25$ FD	$\mathbf{M} = 1.30$	6 LSI	$\overline{\mathrm{M_{std}}\!=\!1.28}$	0 $\mathbb{V}_{\mathrm{std}}$ $=$	5.86E-	05	
	ORIGINAL		WEIGHTEI		ГЕО	WEIGHT INTERPOL				
level 1 2 3 4 5 6 7	1749086 291308 157964 86714 46791 30232 16042	V_l 9.212 0.532 0.279 0.176 0.107 0.078 0.050	$\begin{array}{c} \rho(P_l,P_{l-1}) \\ \text{N/A} \\ 0.973 \\ 0.982 \\ 0.987 \\ 0.992 \\ 0.994 \\ 0.996 \end{array}$	1822150 97492 76879 58904 55953 39296 22678	$\begin{array}{c} \mathbb{V}_l \\ 5.331 \\ 0.027 \\ 0.036 \\ 0.049 \\ 0.069 \\ 0.077 \\ 0.042 \end{array}$	$\rho(P_l, P_{l-1})$ N/A 0.998 0.997 0.996 0.994 0.993 0.996	$ \begin{array}{ c c } N_l \\ 4068118 \\ 180223 \\ 71114 \\ 30686 \\ 19447 \\ 10134 \\ 12595 \\ \end{array} $	0.0198 0.0049 0.0026 0.0028 0.0025 0.0016	$\begin{array}{c} \rho(P_l,P_{l-1}) \\ \text{N/A} \\ 0.9983 \\ 0.9996 \\ 0.9998 \\ 0.9998 \\ 0.9998 \\ 0.9999 \\ \end{array}$	
	$\begin{array}{ c c c } LSM_{MLMC} & 1.281 \\ \mathbb{V}_{MLMC} & 1.88E\text{-}05 \end{array}$		$egin{array}{c} \mathrm{LSM}_{\mathrm{MLMC}} \ \mathbb{V}_{\mathrm{MLMC}} \end{array}$		1.278 9.54E-06			1.212 2.09E-06		

Table 6.2: The MLMC pricing of American put options using weighted payoff functions and Brownian bridge interpolations. The parameters used in simulations are K=20, r=5%, $\sigma=0.4$, T=1 and the number of basis functions J=5. The number of finest levels is set as L=7 and total computational cost is fixed at $C=NM_L=1e4\times2^7$. In the table, N_l , \mathbb{V}_l and $\rho(P_l,P_{l-1})$ represent the number of sample paths at each level, the variance at each level and the correlation coefficients between the functionals at adjacent coarse and fine levels. LSM_{MLMC} and LSM_{std} represent the lower bound estimations using LSM method under MLMC and standard Mote Carlo respectively. \mathbb{V}_{MLMC} and \mathbb{V}_{std} are corresponding variances. The controlling parameters are set as $\lambda=\{1,5,10,50,250,1000,100000\}$ for different levels.

Chapter 7

Conclusions

This thesis reviewed and implemented a number of Monte Carlo based techniques for pricing American options. The applicabilities of these techniques and the dependencies on various simulation parameters were tested. A computing saving technique using orthogonal Hermite polynomials was suggested and tested. The Multilevel Mote Carlo method was applied with the algorithms and the effectiveness on variance reduction is discussed. A smoothing technique using probability weighted payoff functions was proposed to improve the Multilevel Monte Carlo performances for pricing American options.

Chapter 2 reviewed the main theoretical results of the valuation problems of American options and the basic problem formulations were derived through the dynamic programming principle.

Chapter 3 provided an introduction of Longstaff-Schwartz method (LSM) for approximating lower bounds of the prices of American options. The least-squares based regression method was employed to estimate the conditional expectations of the value of American options. A backward induction (Algorithm 3.2) was used to estimate the optimal regression coefficients and a forward induction (Algorithm 3.3) was used to estimate the corresponding lower bounds of the values of options through a sub-optimal stopping rule. The algorithms were tested using a simple example of an American put option written on a single non-dividend paying stock. It was found that the LSM method produced similar estimated values of American options compared with those given by Finite Difference Method (FDM). The variances of the LSM estimators depend on the number of Monte Carlo paths used in the simulations. Fewer simulated paths gave much higher variances. It was found that the variances of the LSM estimators tended to be larger when the option was close to at-themoney. The effects of number of time steps (exercise opportunities) were also tested. The results showed that, when the time steps increased, the LSM estimated values were generally getting closer to the results given by FDM. The variances were not noticeably affected by the number of time steps for most cases. But for deep-in-the-money and deep-out-of-money options, higher number of time steps resulted in lower variances.

Chapter 4 reviewed and implemented the Duality approach for estimating the upper bounds of the prices of American options through martingales constructed with the approximated value functions and the corresponding conditional expectations estimated by nested Monte Carlo simulations (Algorithm 4.2). Various effects of the simulation parameters were tested. The simulations results showed that the duality estimations were generally larger than the results obtained either by the LSM or by the Finite Difference Method, confirming that the Duality approach provides estimations of upper bounds of the true prices. It was found that the variances of duality estimators were generally much smaller than those of the LSM. Again, fewer simulated Monte Carlo paths caused higher variances and the highest variances tended to be with the at-the-money options. The effects of number of sub-successors for nested MC simulations was also tested. The numerical results indicated that the estimated duality values decreased when the number of sub-successors increased, giving smaller upper bounds and thus tighter ranges containing the true price, conjunct with the lower bounds given by LSM. This was the direct outcome of the better estimations of the conditional expectations. The higher number of sub-successors also resulted in lower overall variances. The effects of the number of time steps were also investigated. The results showed that the duality estimations were getting lager with more time steps, causing wider upper-lower price ranges. The reason behind this phenomena is unclear. The variances of the duality estimators were not noticeably affected by the number of time steps for most cases.

Chapter 5 suggested a computing saving technique for pricing American options. By converting the underlying asset price into a standard normal random variable and using the Hermite polynomials, we were able to construct a set of regression basis functions which are orthogonal to each other with respect to the natural distribution of the underlying asset price. This orthogonality made the expectation $\mathbb{E}\left[\psi(S)\psi(S)^{\top}\right]$ to be an identity matrix I, which in turn simplified the procedure of estimating the regression coefficients β and thus provided large amounts of computing saving. A simple numerical example showed that the estimated matrix $\hat{B}_{\psi} = \mathbb{E}\left[\psi(S)\psi(S)^{\top}\right]$ was very similar to an identity matrix I. The quality of this similarity improved with larger number of Monte Carlo paths. The estimated regression coefficients $\hat{\beta}$ with this simplified technique were reasonably close to those obtained by the standard approach but with much faster computing speed. The technique was then tested with both the algorithms of LSM and Duality approaches. Simulation results showed that this simplified technique produced similar accuracies as those under the standard approaches but with much faster speed. While giving similar accuracies, the use of orthogonal basis functions generally resulted in smaller lower bounds from LSM approach and larger upper bounds from Duality approach, indicating slightly wider lower-upper price ranges. The effects of time steps with this simplification were also investigated. It was found that the results given by the simplified approach using the orthogonal basis functions were very sensitive with respect to time steps. When the number of time steps getting larger, the results obtained from the simplified orthogonal approach started to give unacceptable accuracies if we worked with a relatively low number of main Monte Carlo paths. This was due to the built-up errors with over-simplification coming from the relatively poor similarity between $\mathbb{E}\left[\psi(S)\psi(S)^{\top}\right]$ and the identity I and the backward induction for estimating regression coefficients. This problem can be resolved by using larger number of main Monte Carlo paths.

Chapter 6 employed the Multilevel Monte Carlo (MLMC) technique with pricing American options. The effects in variance reductions for both the primal and the dual approaches were tested. The numerical examples confirmed that MLMC approach produced unbiased estimations for both the lower bounds using LSM method and the upper bounds using the Duality method. As for the lower bounds estimations through LSM approach, the variances were noticeably reduced under MLMC with the cases of at-the-money option and out-ofthe-money option and gave a reduction up to 70% with respect to standard Monte Carlo. This is mainly because of the high correlations between the functionals at adjacent coarse and fine levels $\rho(P_l, P_{l-1})$. However, the situation changed for the in-the-money option, in which case the correlations became weaker and the overall variance was about 170% as large as that of the standard counterpart. The most surprising fact was that the MLMC method worked poorly with the Duality estimations. Although it still gave an unbiased estimation, its variances were much higher if compared with those given by standard Monte Carlo. The main reason behind is that there were much weaker correlations exist between P_l and P_{l-1} for the Duality estimations, indicating that the duality values are relatively weakly correlated with different number of exercise opportunities. A smoothing technique using artificial-probability weighted payoff functions jointly with Brownian Bridge interpolations was suggested to improve MLMC performances with the lower bounds estimations through LSM algorithm. The numerical results showed that the probability weighted payoff function, which closely approximated the non-smooth optimal stopped value obtained from LSM at higher levels, better fitted into the MLMC method. The correlations $\rho(P_l, P_{l-1})$ were relatively higher with the weighted payoff functions, especially for the in-the-money case. As a result, the overall variances were reduced by about $40\% \sim 50\%$ compared to those with the original non-smooth payoff functions. The most promising results were obtained when we employed the method of the weighted payoff functions together with the Brownian Bridge interpolations for coarse levels. The correlations $\rho(P_l, P_{l-1})$ were significantly improved with values close to 1 for all the cases. As a result, the variances were reduced further, giving an average reduction of about 90% compared with the standard MC method. This confirms that the weighted payoff functions jointly with the Brownian Bridge interpolation technique will significantly improve the MLMC performances.

Appendix A

Matlab Codes

A.1 Sub-codes and Functions

A.1.1 Cumulative Normal Density Function

```
1 %Cumulative Normal Density Functions
2
3 function [ Y ] = NormalCDF( X )
4
5 Y=0.5*(1+erf(X/sqrt(2)));
6
7 end
```

A.1.2 Regression Basis Functions Using Laguerre Polynomials

```
% J: number of basis functions
3 function Y=Basis_laguerre(X, J)
       Y=zeros(J,length(X));
       for j=1:J
        Y(j,:) = Laguerre(X, j-1);
9
10
11 end
   function Y=Basis_weighted_laguerre(X, J)
14
       Y=zeros(J, length(X));
15
16
       for j=1:J
17
           Y(j,:) = \exp(-X./2).*Laguerre(X, j-1);
18
19
20
21 end
23 function Y = Laguerre(X, k)
```

A.1.3 Orthogonal Basis Functions Based on Hermite Polynomials

```
1 % r: interest rate
   % q: dividend rate
   % sig: volatility
   % T: maturity
   % M: number of time intervals
  % S: stock price process S(M+1,N)
7 % SO: initial stock price
8 % m: current time index
  % J: number of basis functions
11 function Phi=Basis_Hermite_converted(r,q,sig,T,M,S,S0,m,J)
12
       Phi=zeros(J,length(S));
13
14
       dt=T/M;
       i=m-1;
^{17}
       mu = log(S0) + (r-q-0.5*sig^2)*i*dt;
19
20
       sigma=sig*sqrt(i*dt);
21
22
       Y=(log(S)-mu)/sigma;
23
^{24}
       Phi(1,:)=1;
^{26}
       Phi(2,:)=Y;
27
28
       for j=3:J
29
           Phi(j,:) = sqrt(1/(j-1)) *Y.*Phi(j-1,:) - sqrt((j-2)/(j-1)) *Phi(j-2,:);
30
31
32
33 end
```

A.1.4 Discounted Payoff Functions of American Put Option

```
1 % Discounted Payoff function of put
2 % K: strike
3 % M: number of time intervals
4 % N: number of MC paths
5
```

```
6 function h = Payoff_put(r,T,S,K,M,N)
       dt=T/M;
8
       h=zeros(M, N);
9
       h(M,:) = exp(-r*T)*max(K-S(M+1,:),0);
10
11
       for i=1:M
12
                     %current time index (exercise dates)
13
            m=i+1;
            time=(m-1)*dt;
14
            h(i,:) = \exp(-r * time) * \max(K-S(m,:),0);
15
       end
17
18 end
```

A.1.5 Estimating Regression Coefficients Using Backward Induction

```
-Backward induction for estimating regression coefficients-
        ---The code is written on simple laguerre polynomials, which can-
        —be replaced with other interested basis functions.-
        —S: Stock price process S(M+1,N); h: Payoff functions h(M,N)
4
         -Beta: Regression coefficients Beta(J,M)
6
   function Beta = Regression_Beta(S,h,M,N,J)
7
8
       Beta=zeros(J,M); % regression coefficients
       c=zeros(M,N);
                        % continuation values
11
       V=h(M,:); % set the value function to the terminal payoff
12
13
       for i = (M-1):-1:1
14
15
           m=i+1; % current time index (exercise dates)
16
17
           % basis functions, different basis functions can
18
19
            % be used here by replacing with corresponding functions
20
           Phi=Basis_laguerre(S(m,:),J);
^{21}
           sum1=0;
22
           sum2=0;
^{23}
24
           for j=1:N
25
               sum1=sum1+Phi(:,j)*Phi(:,j)';
26
                sum2=sum2+Phi(:,j)*V(j);
27
           end
28
29
           Beta(:,i)=sum1\sum2;
30
31
32
           c(i,:) = (Beta(:,i)') *Phi;
33
34
           V=\max(h(i,:),c(i,:));
35
36
       end
37
     end
38
```

A.1.6 Regression Coefficients Using Simplified Approach Based on Orthogonality

```
1 function Beta_direct = Regression_Beta_Hermite_direct(r,q,siq,T,S,h,M,N,J)
2
3
4
       Beta_direct=zeros(J,M);
5
6
                        %continuation values
       c=zeros(M,N);
       V=h(M,:); %set the value function to the terminal payoff
10
11
       for i = (M-1):-1:1
12
           m=i+1; %current time index (exercise dates)
           Phi_direct=Basis_Hermite_converted(r,q,sig,T,M,S(m,:),S(1,:),m,J); ...
                  %basis functions
16
            sum1=0;
17
18
           for j=1:N
19
                sum1=sum1+Phi_direct(:, j) *V(j);
20
           end
21
22
           Beta_direct(:,i) = (sum1) /N;
           c(i,:)=(Beta_direct(:,i)')*Phi_direct;
26
           V=\max(h(i,:),c(i,:));
27
28
       end
29
30
31 end
```

A.1.7 LSM Estimator

```
-LSM estimator using optimal stopping rule using standard MC-
     ----M: number of time intervals; N: number of MC paths
   %-----S: Stock price process S(M+1,N); h: Payoff functions h(M,N)
     Beta: Regression coefficients Beta(J,M)
  function [Vec_rule, V, c] = LSM_Low_std_MC(S, h, M, N, J, Beta)
       V=zeros(M,N); %value function vecter
8
       c=zeros(M,N); %continuation values
9
10
       for i=1:M
11
12
13
           m=i+1;
                  %current time index (exercise dates)
14
15
```

```
if (i==M) %final time step treatment
16
17
                V(i,:) = h(i,:);
           else
18
                Phi=Basis_laguerre(S(m,:),J); % basis functions, can be ...
19
                    replaced with other basis functions
                c(i,:) = (Beta(:,i)') *Phi;
20
21
                V(i,:) = \max(h(i,:),c(i,:));
       end
25
       Vec_rule=zeros(1,N); %value function vector V(i) optimal stopping values
26
27
       for n=1:N
28
           Vec_rule(n) = h(find(h(:,n) > = c(:,n),1),n);
29
30
31
32 end
```

A.1.8 Duality Estimator

```
1 %----Estimating Duality value through martingales using standard MC-
      ---M: number of time intervals; N: number of MC paths
        -S: Stock price process S(M+1,N); h: Payoff functions h(M,N)
4 %——Beta: Regression coefficients Beta(J,M)
       ----NS: number of MC sub-sucessors for nested MC
7 function [Vec_da,V,c]= LSM_Dual_std_MC(r,q,sig,K,T,S,h,M,N,J,NS,Beta)
8
      dt=T/M;
9
10
      V=zeros(M,N); %value function vecter
11
      c=zeros(M,N);
                      %continuation values
12
13
14
      Mar=zeros(M, N); %duality martingales M(i)
      Da=zeros(M,N); %duality values (h(i)-M(i))
17
      for i=1:M
18
19
          m=i+1; %current time index (exercise dates)
20
          time=i*dt;
21
22
          if (i==M) %final time step treatment
23
24
              V(i,:) = h(i,:);
          else
25
              Phi=Basis_laguerre(S(m,:),J); % basis functions, can be ...
                  replaced with other basis functions
27
              c(i,:) = (Beta(:,i)') *Phi;
28
              V(i,:) = \max(h(i,:),c(i,:));
29
           end
30
          %generating sub paths for estimating dual value
31
          32
33
```

```
%continuation values of sub-paths
34
           cs=zeros(NS,N);
                                 %payoff functions of sub-paths
           hs=zeros(NS,N);
35
36
           for k=1:NS
37
                dW=sqrt(dt) *randn(1,N);
38
                Ss(k,:)=S(m-1,:).*(1+(r-q)*dt+sig*dW); % generating ...
39
                    sub-paths using the previous stock price
                hs(k,:) = exp(-r*time)*max(K-Ss(k,:),0);
40
                if (i==M)
41
                    Vs(k,:) = hs(k,:);
                else
                    Phi=Basis_laguerre(Ss(k,:),J); % basis functions, can be ...
44
                        replaced with other basis functions
                    cs(k,:) = (Beta(:,i)') *Phi;
45
                    Vs(k,:) = max(hs(k,:), cs(k,:));
46
                end
47
           end
48
49
           Diff=V(i,:)-sum(Vs,1)/NS; % martingale differential
50
51
           if (i==1)
               Mar(i,:)=Diff;
53
           else
               Mar(i,:) = Mar(i-1,:) + Diff;
54
           end
55
56
           Da(i,:)=h(i,:)-Mar(i,:);
57
58
       end
59
60
       Vec_da=max(Da,[],1); % vecoer storing duality values
61
62
63 end
```

A.1.9 LSM Estimator Using Probability Weighted Payoff Functions

```
1 % LSM Estimator using smoothed Probability Weighted Payoff Functions
2 % lamda: tsmoothing controlling paramter
4 function [Vec_rule, V, c] = LSM_weighted(S, h, M, N, J, Beta, lamda)
5
       V=zeros(M,N); %value function vecter
6
       c=zeros(M,N); %continuation values
7
       P=zeros(M,N);
                      %conditional probability of exercise
8
       sum1=0;
10
       prod=1;
11
       for i=1:M
14
15
           m=i+1; %current time index (exercise dates)
16
           if (i==M) %final time step treatment
17
               V(i,:) = h(i,:);
18
               c(i,:) = V(i,:);
19
20
           else
```

```
Phi=Basis_laguerre(S(m,:),J);
21
                c(i,:)=(Beta(:,i)')*Phi;
22
                V(i,:) = \max(h(i,:),c(i,:));
23
            end
24
25
           if (i == M)
26
               P(i,:)=1;
27
            else
28
                P(i,:) = NormalCDF(lamda*(h(i,:)-c(i,:)));
29
            end
           if (i ~=1)
32
                prod=prod.*(1-P(i-1,:));
33
            end
34
35
            sum1=sum1+h(i,:).*P(i,:).*prod;
36
37
       end
38
39
       Vec_rule=sum1; %value function vector V(i) weighted payoff functions
40
41
42 end
```

A.1.10 FDM penalty method

```
1 % Pricing Amercian Option Using FDM Penalty Method
3 function V=American_put_FDM_penalty(S0,K,r,sigma,T)
5 %
6 % look at variation with J, with N=J
7 %
9 Smax = 10*S0;
10 J
      = 1000;
       = 500;
11 N
13 S = linspace(0, Smax, J+1)';
14
15 %
16 % set up various constants
17 %
18
19 dS
         = S(2)-S(1);
         = T/N;
20 dt
122 lambda = 0.5*sigma^2*S.^2/dS^2;
23 gamma = 0.5 \times r \times S/dS;
^{24}
25 %
{\bf 26} % define coefficients of tridiagonal matrix
27 %
28
          lambda — gamma;
29 a =
30 b = -2*lambda - r;
```

```
31 c = lambda + gamma;
32
33 %
34 % special treatment of last point, based on d^2u/dS^2=0
35 %
36
a = -2 \cdot gamma \cdot (end);
38 b(end) = 2*gamma(end) - r;
39 c (end) = 0;
41 %
42 % call function to create sparse tri-diagonal matrix
43 %
44
45 L = sparse_tri(a,b,c);
46 I = speye(length(S));
47
48 %
49 % now do time-marching
u = max(0, K-S);
53 payoff=u;
54
55 cnt = zeros(1,N);
_{56} ue = zeros(1,N+1);
57 \text{ ue}(1) = K;
58
59 \text{ rho} = 10000;
60
61 \text{ for } n = 1:N
rhs = (I+0.5*dt*L)*u;
63
   u_old = u;
64
   conv = 0;
65
   count = 0;
66
    while ~conv
67
      P = \max(0, K-S-u);
68
       PP = spdiags(-sign(P), 0, J+1, J+1);
69
       du = (I-0.5*dt*L-rho*dt*PP) \setminus (rhs-(I-0.5*dt*L)*u+rho*dt*P);
70
       u = u + du;
71
       conv = max(abs(du))<1e-10;
72
73
      count = count + 1;
74
     end
75
76
   cnt(n) = count;
77
   ue(n+1) = S(min(find(u > (K-S))));
78
79
80 end
81
u0 = u(1 + J*S0/Smax);
84 V=u0;
85
87 % function to construct tridiagonal matrix
88 % from 3 vectors defining its diagonals
89 %
```

```
90

91  function A = sparse_tri(a,b,c)

92

93  A = spdiags([c b a],[-1 0 1],length(a),length(a))';
```

A.2 Main Codes

A.2.1 Lower Bounds Estimation Using LSM

```
1 %Estimating Lower Bounds for American Put Option
2 %using LSM method
4 clear all; close all; clc;
5 rng('default')
7 % problem parameters
8 r=0.05; %interest rate
9 q=0.0;
               %dividend rate
10 sig=0.4;
             %volativity
           %initial stock values
11 S0=20;
12 K=20;
             %strike
13 T=1;
                 %maturity
15 N=1e4; % number of paths for standard MC
16 M=2^5; % number of time steps
17
            %number of basis functions
18 J=5;
19
20 dt=T/M; %length of time step
21
v_fdm=American_put_FDM_penalty(S0,K,r,sig,T);
23
24 %Generating independent paths using Euler-Maruyama scheme for estimating
25 %regression coefficients using standard MC
26 S=zeros(M+1,N); % every column corresponds to an individual path
27
28 S(1,:)=S0*ones(1,N);
29
30 for m=2:M+1
       dW=sqrt(dt) *randn(1,N);
31
32
       S(m,:) = S(m-1,:) .* (1+(r-q)*dt+sig*dW);
33 end
35 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
37 %———Calculating Regression Coefficients with Longstaff ...
      Algorithm-
38 Beta = Regression_Beta(S,h,M,N,J);
39
40 %----Estimating value using optimal stopping rule using standard MC
41 %----through the 2nd set of independent Monte Carlo paths-
43 % generating the 2nd set of main paths
44 for m=2:M+1
        dW=sqrt(dt)*randn(1,N);
```

```
S(m,:) = S(m-1,:) .* (1+(r-q)*dt+sig*dW);
47 end
48
49 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
50
51 % calculating optimal stopping value
52 [Vec_rule, V, c] = LSM_Low_std_MC(S, h, M, N, J, Beta);
54 V_rule=sum(Vec_rule)/N;
56 Var_rule=(sum(Vec_rule.^2)/N-V_rule^2)/N;
57
58 disp('The value of option using FDM');
59 disp(V_fdm);
60 disp('The value of option using standard LSM');
61 disp(V_rule);
62 disp('Variance LSM estimator')
63 disp(Var_rule);
```

A.2.2 Upper Bounds Estimation Using Duality Method

```
1 %Estimating Upper Bounds for American Put Option
2 %using Duality method
4 clear all; close all; clc;
5 rng('default')
7 % problem parameters
8 r=0.05; %interest rate
9 q=0.0;
              %dividend rate
             %volativity
10 sig=0.4;
11 S0=20;
             %initial stock values
12 K=20;
            %strike
13 T=1;
               %maturity
15 N=1e4; % number of paths for standard MC
16 M=2^5;
          % number of time steps
17 NS=200; %number of sub-paths for duality calculation
            %number of basis functions
18 J=5;
19
20 dt=T/M; %length of time step
21
22 V_fdm=American_put_FDM_penalty(S0,K,r,sig,T);
23
24 %Generating independent paths using Euler-Maruyama scheme for estimating
25 %regression coefficients using standard MC
26 S=zeros(M+1,N); % every column corresponds to an individual path
27
28 S(1,:)=S0*ones(1,N);
29
30 for m=2:M+1
        dW=sqrt(dt)*randn(1,N);
31
        S(m,:) = S(m-1,:) .* (1+(r-q)*dt+sig*dW);
32
33 end
34
```

```
35 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
37 %———Calculating Regression Coefficients with Longstaff ...
      Algorithm-
38 Beta = Regression_Beta(S,h,M,N,J);
39
40 %----Estimating duality value using standard MC
41 %----through the 2nd set of independent Monte Carlo paths-
43 % generating the 2nd set of main paths
44 for m=2:M+1
        dW=sqrt(dt) *randn(1,N);
        S(m,:) = S(m-1,:) .* (1+(r-q)*dt+sig*dW);
46
47 end
49 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
51 % calculating Duality values
52 [Vec_dual, V, c] = LSM_Dual_std_MC(r,q,siq,K,T,S,h,M,N,J,NS,Beta);
54 V_dual=sum(Vec_dual)/N;
56 Var_dual=(sum(Vec_dual.^2)/N-V_dual^2)/N;
57
58 disp('The value of option using FDM');
59 disp(V_fdm);
60 disp('The Duality value of option');
61 disp(V_dual);
62 disp('Variance of Duality estimator')
63 disp(Var_dual);
```

A.2.3 Multilevel Monte Carlo for Pricing American Put Options

```
1 % MLMC for pricing American put options
_{2} % The code is written on LSM estimator and Laguerre basis functions.
_{3} % For estimating Duality values, users can repalce the LSM estimators with
4 % the Duality estimators. Users can also replace the Laguerre basis \dots
      functions with
5 % other interested basis functions.
7 clear all; close all; clc;
8 rng('default')
10 % problem parameters
11 r=0.05; %interest rate
q=0.0;
              %dividend rate
13 sig=0.4;
             %volativity
14 S0=20; %initial stock values
15 K=20; %strike
16 T=1;
                 %maturity
17
18 V_fdm=American_put_FDM_penalty(S0,K,r,sig,T);
19
20 L=7;
        % number of levels of MLMC
21 N=1e5; % number of paths for standard MC
```

```
22 M=2^L; % number of time steps
           %Compuational cost for standard MC
23 C=N*M;
24
25 NS=100; %number of sub-paths for duality calculation
26
27 J=5;
            %number of basis functions
28
29 dt=T/M; %length of time step
30
31 %Generating independent paths using Euler-Maruyama scheme for estimating
32 %regression coefficients using standard MC
33 S=zeros(M+1,N); % every column corresponds to an individual path
34
35 S(1,:)=S0*ones(1,N);
36
37 for m=2:M+1
       dW=sqrt(dt) *randn(1,N);
38
       S(m,:) = S(m-1,:) .* (1+(r-q)*dt+siq*dW);
39
40 end
41
42 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
        ---Calculating Regression Coefficients -
45 Beta = Regression_Beta(S,h,M,N,J);
46
47 % generating the 2nd set of main paths
48 for m=2:M+1
       dW=sqrt(dt) *randn(1,N);
49
       S(m,:) = S(m-1,:) .* (1+(r-q)*dt+siq*dW);
50
51 end
53 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
55 % calculating option values using standard MC
56 [Vec_rule, V, c] = LSM_Low_std_MC(S, h, M, N, J, Beta);
57
58 V_rule=sum(Vec_rule)/N;
59
60 Var_rule=(sum(Vec_rule.^2)/N-V_rule^2)/N;
61
   %----MLMC starts from here-
62
64 Nl_rule=1e4*ones(1,L); %number of independent Monte Carlo paths at each ...
      level (initial value 1e4 for pilot run)
65
66 Ml=zeros(1,L); % number of time steps at each level
67 for l=1:L
       M1(1)=2^1;
68
69 end
71 Yl_rule=zeros(1,L); % this vector records estimated option values at ...
      each level
72 Varl_rule=zeros(1,L); % this vector records variances of option value at ...
      each level
73 Cov_level=zeros(1,L); %this vector records co-variance between fine and ...
      coarse levels
74 Corr_level=zeros(1,L); %this vector records correlation coefficients ...
     between fine and coarse levels
```

```
75 Sum_rule=0.0;
                    % the sum required in the calculation of optimal number ...
        of paths
76
77
78 % MLMC pilot run
79 Nl=Nl_rule;
80 for l=1:L
        S_{\text{fine}}=zeros(Ml(1)+1,Nl(1)); % stock path at level 1
81
        S_{\text{-fine}}(1,:) = S0 * ones(1,Nl(1));
82
        Beta_fine=zeros(J,Ml(1));
                                         % recording regression coefficients at ...
83
            fine level
84
        for i=1:M1(1)
85
                                    % global index corresponding to the global ...
            ind=i*Ml(L)/Ml(l);
86
                highest level
            Beta_fine(:,i) = Beta(:,ind); % copying golobal Betas to the ...
87
                 local fine level (1)
        end
88
 89
        if (1 ~= 1)
 90
91
             S_{coarse=zeros(Ml(l-1)+1,Nl(l))}; %stock path at level (l-1)
92
             S_{coarse(1,:)} = S0 * ones(1,Nl(1));
                                                 % recording regression ...
93
            Beta_coarse=zeros(J, Ml(l-1));
                codfficients at coarse level
94
            for i=1:M1(1-1)
95
                  ind=i*Ml(L)/Ml(l-1);
                                            % global index corresponding to the ...
96
                      global highest level
                 Beta_coarse(:,i) = Beta(:,ind); % copying golobal Betas to ...
97
                     the local coarse level (1-1)
98
            end
         end
99
100
        dt_l=T/Ml(l); % time interval at level l (fine level)
101
102
        % generating the main MC paths
103
        if (1 ~=1)
104
             for m=2:M1(1-1)+1
105
                 m_fine=2*m-2;
106
                 dW1=sqrt(dt_l)*randn(1,Nl(l));
107
                 S_fine (m_fine_{,:}) = S_fine_{,:} (m_fine_{-1,:}) \cdot * (1 + (r-q) * dt_{-1} + sig * dW1);
108
                 dW2=sqrt(dt_l)*randn(1,Nl(l));
109
110
                 S_{\text{fine (m_fine+1,:)}} = S_{\text{fine (m_fine,:)}} \cdot \star (1 + (r-q) \star dt_1 + sig \star dW2);
                 111
112
            end
            \label{eq:h_fine} $$h_fine=Payoff_put(r,T,S_fine,K,Ml(l),Nl(l)); $$ $$discoundted ...$
113
                 payoff functions at fine level (1)
            h\_coarse=Payoff\_put(r,T,S\_coarse,K,Ml(l-1),Nl(l)); % discounted ...
1114
                 payoff functions at coarse level (1-1)
        else
115
             for m=2:M1(1)+1
116
                 dW=sqrt(dt_l)*randn(1,Nl(l));
117
                 S_{fine}(m,:) = S_{fine}(m-1,:) .* (1+(r-q)*dt_1+sig*dW);
118
119
            end
            h_fine=Payoff_put(r,T,S_fine,K,Ml(1),Nl(1)); % discounted ...
120
                 payoff functions at fine level (1)
        end
121
122
123
        if (1==1)
```

```
124
              [Vec_rule_ML, V_ML, c_ML] = ...
                  LSM_Low_std_MC(S_fine, h_fine, Ml(l), Nl(l), J, Beta_fine);
125
126
        else
127
             [Vec_rule_fine, V_fine, c_fine] = ...
                 LSM-Low-std-MC(S-fine, h-fine, Ml(l), Nl(l), J, Beta-fine);
128
129
             [Vec_rule_coarse, V_coarse, c_coarse] = . . .
130
                 LSM_Low_std_MC(S_coarse, h_coarse, M1(1-1), N1(1), J, Beta_coarse);
             Vec_rule_ML=Vec_rule_fine-Vec_rule_coarse;
131
132
        end
133
134
        Yl_rule(1) = sum(Vec_rule_ML)/Nl(1);
135
        Varl_rule(1) = (sum(Vec_rule_ML.^2)/Nl(1)-Yl_rule(1)^2);
136
137
        Sum_rule=Sum_rule+sqrt(Varl_rule(1)*T*M1(1));
138
139
140 end
141
142 for l=1:L
143
        Nl_rule(1) = int64(C*sqrt(Varl_rule(1)*T/Ml(1))/Sum_rule);
144 end
145
146 % MLMC optimal run
147 Nl=Nl_rule;
148 for l=1:L
        S_{\text{fine}}=zeros(Ml(1)+1,Nl(1));
                                         % stock path at level 1
149
        S_{\text{fine}}(1,:) = S0 * ones(1,Nl(1));
150
151
        Beta_fine=zeros(J,Ml(1));
                                         % recording regression coefficients at ...
            fine level
152
        for i=1:M1(1)
153
             ind=i*Ml(L)/Ml(l);
                                   % global index corresponding to the global ...
154
                 highest level
155
            Beta_fine(:,i)=Beta(:,ind); % copying golobal Betas to the ...
                 local fine level (1)
156
        end
157
        if (1 = 1)
158
             S_coarse=zeros(Ml(l-1)+1,Nl(l)); %stock path at level (l-1)
159
             S_{coarse(1,:)} = S0 * ones(1,Nl(1));
160
             Beta_coarse=zeros(J, Ml(l-1));
                                                 % recording regression ...
161
                 codfficients at coarse level
             for i=1:M1(1-1)
163
                  ind=i*Ml(L)/Ml(l-1);
                                           % global index corresponding to the ...
164
                      global highest level
                 Beta_coarse(:,i) = Beta(:,ind); % copying golobal Betas to ...
165
                     the local coarse level (1-1)
            end
166
167
         end
168
        dt_l=T/Ml(l); % time interval at level l (fine level)
169
170
171
        % generating the main MC paths
        if (1 ~=1)
172
            for m=2:M1(1-1)+1
173
                 m_fine=2*m-2;
174
                 dW1=sqrt(dt_l)*randn(1,Nl(l));
175
176
                 S_{fine}(m_{fine}, :) = S_{fine}(m_{fine}-1, :) .* (1+(r-q)*dt_1+sig*dW1);
```

```
177
                 dW2=sqrt(dt_l)*randn(1,Nl(l));
178
                 S_fine (m_fine+1,:) = S_fine (m_fine,:) .* (1+(r-q)*dt_1+siq*dW2);
                 S_{coarse(m,:)} = S_{coarse(m-1,:)} * (1+(r-q)*2*dt_1+sig*(dW1+dW2));
179
            end
180
            h_fine=Payoff_put(r,T,S_fine,K,Ml(l),Nl(l)); % discoundted ...
181
                 payoff functions at fine level (1)
182
            h_{coarse}=Payoff_{put}(r,T,S_{coarse},K,Ml(1-1),Nl(1)); % discounted ...
                 payoff functions at coarse level (1-1)
        else
183
             for m=2:M1(1)+1
184
                 dW=sqrt(dt_l)*randn(1,Nl(l));
185
186
                 S_{fine}(m, :) = S_{fine}(m-1, :) .* (1+(r-q)*dt_1+siq*dW);
             end
187
            h_fine=Payoff_put(r,T,S_fine,K,Ml(l),Nl(l)); % discounted ...
188
                 payoff functions at fine level (1)
        end
189
190
        if (1==1)
191
192
              [Vec_rule_ML, V_ML, c_ML] = ...
193
                  LSM_Low_std_MC(S_fine, h_fine, Ml(l), Nl(l), J, Beta_fine);
194
        else
195
             [Vec_rule_fine, V_fine, c_fine] = ...
                 LSM_Low_std_MC(S_fine, h_fine, Ml(l), Nl(l), J, Beta_fine);
196
             [Vec_rule_coarse, V_coarse, c_coarse] = . . .
197
                 LSM_Low_std_MC(S_coarse, h_coarse, Ml(l-1), Nl(l), J, Beta_coarse);
198
            Vec_rule_ML=Vec_rule_fine-Vec_rule_coarse;
199
             cov_l=cov(Vec_rule_fine, Vec_rule_coarse, 1);
200
             Cov_level(1) = cov_l(1,2);
201
             Corr_level(1) = cov_l(1, 2) / sqrt(cov_l(1, 1) * cov_l(2, 2));
202
203
204
        Yl_rule(1) = sum(Vec_rule_ML)/Nl(1);
205
206
        Varl_rule(1) = (sum(Vec_rule_ML.^2)/Nl(1)-Yl_rule(1)^2);
207
208
        Sum_rule=Sum_rule+sqrt(Varl_rule(1)*T*Ml(1));
209
   end
210
211
212 V_rule_MLMC=sum(Yl_rule);
213
214 Var_rule_MLMC=0;
215
216 for l=1:L
217
        Var_rule_MLMC=Var_rule_MLMC+Varl_rule(1)/N1(1);
218 end
219
220 disp('The value of option using FDM:');
221 disp(V_fdm);
222 disp('The value of option using standard MC');
223 disp(V_rule);
224 disp('The value of option using MLMC');
225 disp(V_rule_MLMC);
226 disp('Variance of standard MC')
227 disp(Var_rule);
228 disp('Variance of MLMC')
229 disp(Var_rule_MLMC);
230 disp('Number of MC paths at each level')
231 disp(Nl_rule);
232 disp('Variances at each level')
```

```
disp(Varl_rule);
disp('Correlations between fine and coarse levels');
disp(Corr_level);
```

A.2.4 Multilevel Monte Carlo Using Probability Weighted Payoff Functions jointly with Brownian Bridge Interpolations

```
1 % MLMC for pricing American put options
{\bf 2} % based on smoothed probability weighted payoff functions
3 % and the Brownian Bridge Interpolations
5 clear all; close all; clc;
6 rng('default')
8 % problem parameters
9 r=0.05; %interest rate
10 q=0.0;
               %dividend rate
             %volativity
11 sig=0.4;
12 S0=20; %initial stock values
13 K=20; %strike
14 T=1;
                 %maturity
15
V_fdm=American_put_FDM_penalty(S0,K,r,sig,T);
17
18 L=7;
        % number of levels of MLMC
19 N=1e5; % number of paths for standard MC
20 M=2^L; % number of time steps
          %Compuational cost for standard MC
21 C=N*M;
22
23 NS=100; %number of sub-paths for duality calculation
24
25 J=5;
            %number of basis functions
26
27 lamda=[1,5,10,50,250,1000,100000]; % parameters for smoothing
28
29 dt=T/M; %length of time step
31 %Generating independent paths
32 S=zeros(M+1,N); % every column corresponds to an individual path
33
34 S(1,:)=S0*ones(1,N);
35
36 for m=2:M+1
37
       dW=sqrt(dt) *randn(1,N);
       S(m,:) = S(m-1,:).*exp((r-q-0.5*sig^2)*dt+sig*dW);
38
39 end
41 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
42
        -- Calculating Regression Coefficients with Longstaff ...
43 %----
     Algorithm-
44 Beta = Regression_Beta(S,h,M,N,J);
45
46 % generating the 2nd set of main paths
47 for m=2:M+1
```

```
dW=sqrt(dt)*randn(1,N);
49
       S(m,:) = S(m-1,:) .*exp((r-q-0.5*sig^2)*dt+sig*dW);
50 end
51
52 h = Payoff_put(r,T,S,K,M,N); %payoff_functions
54 % calculating optimal stopping value and duality value
55 [Vec_rule, V, c] = LSM_Low_std_MC(S, h, M, N, J, Beta);
56
57 V_rule=sum(Vec_rule)/N;
59 Var_rule=(sum(Vec_rule.^2)/N-V_rule^2)/N;
60
        -MLMC starts from here-
61 %—
62
63 Nl_rule=1e4*ones(1,L); %number of independent Monte Carlo paths at each ...
       level (initial value 1e4 for pilot run)
64
65 Ml=zeros(1,L);
                    % number of time steps at each level
66 for l=1:L
       M1(1)=2^1;
68 end
70 Yl_rule=zeros(1,L); % this vector records estimated option values at ...
       each level
71 Varl_rule=zeros(1,L); % this vector records variances of option value at ...
      each level
72 Cov_level=zeros(1,L); %this vector records co-variance between fine and ...
      coarse levels
73 Corr_level=zeros(1,L); %this vector records correlation coefficients ...
      between fine and coarse levels
74 Sum_rule=0.0;
                  % the sum required in the calculation of optimal number ...
      of paths
75
76 % MLMC pilot run
   N1=N1_rule;
77
  for 1=1:L
78
79
       S_fine=zeros(Ml(l)+1,Nl(l)); % stock path at level l
80
       S_{\text{fine}}(1,:) = S0 * ones(1,Nl(1));
81
       Beta_fine=zeros(J,Ml(l));
                                    % recording regression coefficients at ...
82
           fine level
       for i=1:M1(1)
84
           ind=i*Ml(L)/Ml(l);
                                 % global index corresponding to the global ...
85
               highest level
           Beta_fine(:,i) = Beta(:,ind); % copying golobal Betas to the ...
86
               local fine level (1)
       end
87
88
       if (1 = 1)
89
           S_coarse=zeros(M1(1-1)+1, N1(1)); %stock path at level (1-1)
90
           S_inter=zeros(M1(1)+1,N1(1)); % stock path at level (1-1) ...
               combined with interpolations
           S_{coarse(1,:)} = S0 * ones(1,Nl(1));
92
93
           S_{inter(1,:)} = S0 * ones(1,Nl(1));
           Beta_coarse=zeros(J, Ml(l-1));
                                             % recording regression ...
94
               codfficients at coarse level
95
```

```
96
             for i=1:M1(1-1)
                  ind=i*Ml(L)/Ml(l-1);
                                            % global index corresponding to the ...
97
                       global highest level
                 Beta_coarse(:,i) = Beta(:,ind);
                                                    % copying golobal Betas to ...
98
                     the local coarse level (1-1)
             end
99
100
         end
101
        dt_l=T/M1(1); % time interval at level 1 (fine level)
102
103
         % generating the main MC paths
104
        if (1 ~=1)
105
             for m=2:M1(1-1)+1
106
                 m_fine=2*m-2;
107
                 dW1=sqrt(dt_l)*randn(1,Nl(l));
108
                 S_fine(m_fine,:)=...
109
                      S_fine (m_fine-1,:).*exp((r-q-0.5*sig^2)*dt_l+sig*dW1);
110
                 dW2=sqrt(dt_l)*randn(1,Nl(l));
111
                 S_{\text{fine}}(m_{\text{fine}}+1,:)=...
112
113
                      S_fine (m_fine, :) .*exp((r-q-0.5*sig^2)*dt_l+sig*dW2);
114
                 S_{coarse}(m,:) = ...
115
                      S_coarse (m-1,:).*exp((r-q-0.5*sig^2)*2*dt_1+sig*(dW1+dW2));
116
                 %Brownian interpolations
117
                 S_{inter}(m_{fine},:) = ...
118
                      0.5*(S_{coarse}(m,:)+S_{coarse}(m-1,:)...
119
                         +(S_coarse(m-1,:).*sig).*(dW1-dW2));
120
                 S_inter(m_fine+1,:)=S_coarse(m,:);
121
122
123
             h_fine=Payoff_put(r,T,S_fine,K,Ml(1),Nl(1)); % discoundted ...
                 payoff functions at fine level (1)
             h_{coarse}=Payoff_{put}(r,T,S_{coarse},K,Ml(1-1),Nl(1)); % discounted ...
124
                 payoff functions at coarse level (1-1)
125
             h_inter=Payoff_put(r,T,S_inter,K,Ml(1),Nl(1)); % discoundted ...
                 payoff functions at coarse level (1-1) combined with ...
                 interpolations
        else
126
             for m=2:M1(1)+1
127
                 dW=sqrt(dt_l)*randn(1,Nl(l));
128
                 S_{\text{fine}}(m,:) = S_{\text{fine}}(m-1,:) \cdot \exp((r-q-0.5*\sin^2 2)*dt_1! + \sin^2 4W);
129
130
             h_fine=Payoff_put(r,T,S_fine,K,Ml(l),Nl(l)); % discounted ...
131
                 payoff functions at fine level (1)
132
        end
133
        if (1==1)
134
            [Vec_rule_ML, V_ML, c_ML] = ...
135
                 LSM_weighted(S_fine, h_fine, Ml(1), Nl(1), J, Beta_fine, lamda(1));
136
137
138
            [Vec_rule_fine, V_fine, c_fine] = ...
                LSM_weighted(S_fine, h_fine, M1(1), N1(1), J, Beta_fine, lamda(1));
139
140
           [Vec_rule_coarse, V_coarse, c_coarse] = . . .
               LSM_weighted(S_inter, h_inter, M1(1), N1(1), J, Beta_fine, lamda(1));
141
142
         Vec_rule_ML=Vec_rule_fine-Vec_rule_coarse;
143
144
        Yl_rule(1) = sum(Vec_rule_ML)/Nl(1);
145
        Varl_rule(1) = (sum(Vec_rule_ML.^2)/N1(1)-Y1_rule(1)^2);
146
147
```

```
148
        Sum_rule=Sum_rule+sqrt(Varl_rule(1)*T*M1(1));
149 end
150
151 for l=1:L
        Nl_rule(1)=int64(C*sqrt(Varl_rule(1)*T/Ml(1))/Sum_rule);
152
153 end
154
155
156 % MLMC optimal run
        N1=N1_rule;
157
158 for l=1:L
159
        S_fine=zeros(Ml(l)+1,Nl(l)); % stock path at level l
160
        S_{\text{fine}}(1,:) = S0 * ones(1,Nl(1));
161
        Beta_fine=zeros(J,Ml(l));
                                        % recording regression coefficients at ...
162
            fine level
163
        for i=1:M1(1)
164
             ind=i*Ml(L)/Ml(l);
                                    % global index corresponding to the global ...
165
                highest level
166
            Beta_fine(:,i)=Beta(:,ind); % copying golobal Betas to the ...
                local fine level (1)
167
        end
168
        if (1 ~= 1)
169
             S_coarse=zeros(Ml(l-1)+1,Nl(l)); %stock path at level (l-1)
170
             S_inter=zeros(Ml(1)+1,Nl(1)); % stock path at level (1-1) ...
171
                combined with interpolations
172
            S_{coarse(1,:)} = S0 * ones(1,Nl(1));
             S_{inter(1,:)} = S0 * ones(1,N1(1));
173
            Beta_coarse=zeros(J, Ml(l-1));
                                                 % recording regression ...
174
                 codfficients at coarse level
175
176
             for i=1:M1(1-1)
177
                  ind=i*Ml(L)/Ml(l-1);
178
                                           % global index corresponding to the ...
                      global highest level
                 Beta_coarse(:,i) = Beta(:,ind); % copying golobal Betas to ...
179
                     the local coarse level (1-1)
            end
180
         end
181
182
        dt_l=T/M1(1); % time interval at level 1 (fine level)
183
184
        % generating the main MC paths
185
        if (1 ~=1)
186
             for m=2:M1(1-1)+1
187
                 m_fine=2*m-2:
188
                 dW1=sqrt(dt_l)*randn(1,Nl(l));
189
190
                 S_{\text{fine}}(m_{\text{fine}},:) = \dots
                     S_fine (m_fine-1,:).*exp((r-q-0.5*sig^2)*dt_l+sig*dW1);
191
                 dW2=sqrt(dt_l)*randn(1,Nl(l));
192
                 S_{\text{fine}}(m_{\text{fine}}+1,:)=...
193
                     S_fine(m_fine,:).*exp((r-q-0.5*sig^2)*dt_l+sig*dW2);
194
195
                 S_{coarse}(m, :) = ...
                     S_coarse (m-1,:).*exp((r-q-0.5*sig^2)*2*dt_1+sig*(dW1+dW2));
196
197
                 %Brownian interpolations
198
199
                 S_inter(m_fine,:)=...
```

```
200
                     0.5*(S_{coarse}(m,:)+S_{coarse}(m-1,:)+...
                                (S_coarse(m-1,:).*sig).*(dW1-dW2));
201
                 S_inter(m_fine+1,:)=S_coarse(m,:);
202
            end
203
            h_fine=Payoff_put(r,T,S_fine,K,Ml(l),Nl(l)); % discoundted ...
204
                payoff functions at fine level (1)
            h_{coarse}=Payoff_{put}(r,T,S_{coarse},K,Ml(1-1),Nl(1)); % discounted ...
205
                payoff functions at coarse level (1-1)
            h_inter=Payoff_put(r,T,S_inter,K,M1(1),N1(1)); % discoundted ...
206
                payoff functions at coarse level (1-1) combined with ...
                interpolations
207
        else
             for m=2:M1(1)+1
208
                 dW=sqrt(dt_l)*randn(1,Nl(l));
209
                 S_{fine}(m,:) = S_{fine}(m-1,:).*exp((r-q-0.5*sig^2)*dt_l+sig*dW);
210
            end
211
            h_fine=Payoff_put(r,T,S_fine,K,Ml(l),Nl(l)); % discounted ...
212
                payoff functions at fine level (1)
        end
213
214
215
        if (l==1)
216
             [Vec_rule_ML, V_ML, c_ML] = ...
                  LSM_weighted(S_fine, h_fine, M1(1), N1(1), J, Beta_fine, lamda(1));
217
218
        else
             [Vec_rule_fine, V_fine, c_fine] = ...
219
                 LSM_weighted(S_fine, h_fine, Ml(1), Nl(1), J, Beta_fine, lamda(1));
220
              [Vec_rule_coarse, V_coarse, c_coarse] = . . .
221
                  LSM_weighted(S_inter, h_inter, M1(1), N1(1), J, Beta_fine, lamda(1));
222
            Vec_rule_ML=Vec_rule_fine-Vec_rule_coarse;
223
            cov_l=cov(Vec_rule_fine, Vec_rule_coarse, 1);
224
            Cov_level(1) = cov_l(1, 2);
225
            Corr_level(1) = cov_l(1, 2) / sqrt(cov_l(1, 1) * cov_l(2, 2));
226
227
         end
228
229
        Yl_rule(1) = sum(Vec_rule_ML)/Nl(1);
        Varl_rule(1) = (sum(Vec_rule_ML.^2)/Nl(1)-Yl_rule(1)^2);
230
231
        Sum_rule=Sum_rule+sqrt(Varl_rule(1)*T*Ml(1));
232
233 end
234
   V_rule_MLMC=sum(Yl_rule);
235
236
237 Var_rule_MLMC=0;
238
239 for l=1:L
        Var_rule_MLMC=Var_rule_MLMC+Varl_rule(1)/N1(1);
240
241 end
242
243 disp('The value of option using FDM:');
244 disp(V_fdm);
245 disp('The value of option using standard MC');
246 disp(V_rule);
247 disp('The value of option using MLMC');
248 disp(V_rule_MLMC);
249 disp('Variance of standard MC')
250 disp(Var_rule);
251 disp('Variance of MLMC')
252 disp(Var_rule_MLMC);
253 disp('Number of MC paths at each level')
```

```
disp(Nl_rule);
disp('Variances at each level')
disp(Varl_rule);
disp('Correlations between fine and coarse levels');
disp(Corr_level);
```

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