

Machine Learning

Logistic Regression

Advanced optimization

Optimization algorithm

Cost function $\underline{J(\theta)}$. Want $\min_{\theta} J(\underline{\theta})$.

Given θ , we have code that can compute

Gradient descent:

$$\rightarrow \theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta)$$

Optimization algorithm

Given θ , we have code that can compute

$$-J(\theta)$$

$$-\frac{\partial}{\partial \theta_j}J(\theta)$$
(for $j=0,1,\ldots,n$)

Optimization algorithms:

- Gradient descent
 - Conjugate gradient
 - BFGS
 - L-BFGS

Advantages:

- No need to manually pick α
- Often faster than gradient descent.

Disadvantages:

More complex

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Example: min 3(0)
                                                function [jVal, gradient]
\Rightarrow \theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \quad \text{o.s.} \quad \text{o.s.}
                                                               = costFunction(theta)
                                                   jVal = (\underline{theta(1)-5)^2} + \dots
                                                               (theta(2)-5)^2;
J(\theta) = (\theta_1 - 5)^2 + (\theta_2 - 5)^2
                                                   gradient = zeros(2,1)_;
\rightarrow \frac{\partial}{\partial \theta_1} J(\theta) = 2(\theta_1 - 5)
                                                  gradient(1) = 2*(theta(1)-5);
                                                  f gradient(2) = 2*(theta(2)-5);
\rightarrow \frac{\partial}{\partial \theta_2} J(\theta) = 2(\theta_2 - 5)
-> options = optimset(\(\frac{\GradObj', \on'}{\on'}\), \(\frac{\MaxIter', \on'}{\OMBOSON}\));
\rightarrow initialTheta = zeros(2,1);
  [optTheta, functionVal, exitFlag] ...
       = fminunc(@costFunction, initialTheta, options);
                                         Ochd d>2
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\begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} = \begin{cases} \text{theta(i)} \\ \text{theta(2)} \\ \text{theta(nti)} \end{cases}
function (jVal) gradient) = costFunction(theta)
           jVal = [code to compute J(\theta)];
          gradient(1) = [code to compute \frac{\partial}{\partial \theta_0} J(\theta)
          gradient(2) = [code to compute \frac{\partial}{\partial \theta_1} J
          gradient(n+1) = [code to compute \frac{\partial}{\partial \theta_n} J(\theta)
```