시스템 프로그래밍을 위한 C언어 volatile 활용 및 필요성

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Volatile variable

volatile is required when

• representing hardware registers (or memory-mapped I/O) as variables - even if the register will never be read, the compiler must not just skip the write operation thinking "Stupid programmer. Tries to store a value in a variable which he/she will never ever read back. He/she won't even notice if we omit the write." Conversly, even if the program never writes a value to the variable, its value may still be changed by hardware.

Effects of volatile

When a variable is declared volatile the compiler must make sure that every assignment to it in program code is reflected in an actual write operation, and that every read in program code reads the value from (mmapped) memory.

For non-volatile variables, the compiler assumes it knows if/when the variable's value changes and can optimize code in different ways.

For one, the compiler can reduce the number of reads/writes to memory, by keeping the value in CPU registers.





Using volatile in MCU

When reading from a hardware register.

That means, the memory-mapped register itself, part of hardware peripherals inside the MCU. It will likely have some cryptic name like "ADC0DR". This register must be defined in C code, either through some register map delivered by the tool vendor, or by yourself. To do it yourself, you'd do (assuming 16 bit register):

```
#define ADC0DR (*(volatile uint16_t*)0x1234)
```

where 0x1234 is the address where the MCU has mapped the register. Since volatile is already part of the above macro, any access to it will be volatile-qualified. So this code is fine:

```
uint16_t adc_data;
adc_data = ADC0DR;
```

```
uint16_t adc_data = 0;

void adc_stuff (void)
{
   if(adc_data > 0)
   {
      do_stuff(adc_data);
   }
}
```

```
interrupt void ADCO_interrupt (void)
{
  adc_data = ADCODR;
}
```





Using volatile in MCU

```
// adc.c
#include "adc.h"
#define ADC0DR (*(volatile uint16_t*)0x1234)
static volatile bool semaphore = false;
static volatile uint16 t adc val = 0;
uint16 t adc get val (void)
  uint16 t result;
  semaphore = true;
    result = adc val;
  semaphore = false;
  return result;
interrupt void ADCO_interrupt (void)
  if(!semaphore)
    adc val = ADCODR;
```

Memory I/O를 최대한 줄이도록 컴파일됨

ADC_DATA에 값을 write한 뒤 긴 시간 write없어도 스스로 값이 바뀌지 않는다고 생각해야 함 (메모리 값 유지되므로)

```
int ADC_EOC_CHECK() {
    // wait for end of conversion
    // hardware delay emulation
    int a;
    for(int i=0; i<100000; i++)
        a = 10; // do something.
    return 1; // end of conversion
```

```
// ADC DATA = .... will be executed by Hardware
int ADC_DATA=B;
// blocking until status is matched
while(ADC EOC CHECK() == 0);
int compensated ADC = ADC DATA + 7;
printf("ADC DATA is %d\n", compensated ADC);
return 0;
```

```
0000000000001060 <main>:
                                    endbr64
    1060:
            f3 0f 1e fa
    1064: 48 83 ec 08
                                           $0x8,%rsp
                                    sub
                                           $0xa,%edx
    1068:
            ba 0a 00 00 00
                                    mov
    106d:
            bf 01 00 00 00
                                           $0x1,%edi
                                   mov
                                          %eax,%eax
    1072:
           31 c0
                                    xor
    1074:
            48 8d 35 89 0f 00 00
                                    lea
                                           0xf89(%rip),%rsi
            e8 d0 ff ff ff
                                    calla 1050 < printf c
    107b:
```

- 따라서 굳이 ADC_DATA를 메모리로부터 읽어올 필요없음.
- ADC DATA에 값을 쓰고 읽는 코드는 사라지고, 3과 7을 컴파일 타임에 더해서 최종 10을 사용함



명시적으로 Memory I/O를 반드시 수행함

- 변수에 접근 (read/write)하는 코드는 메모리 접근해서 읽고 쓰는 코드로 변환됨
 - 아무리 짧은 구간이든, 아무리 긴 시간이든 c코드에서 그 변수에 assign하지 않더라도 스스로 값이 바뀔수 있다면.. (휘발성, volatile) 명시적으로 메모리로부터 그 값을 읽어오는 것이 맞다. → 접근하는 메모리 주소가 실제 하드웨어에 매핑되어 있다면 (memory mapped I/O) 반드시 그 변수 영역을 volatile로 선언하라.

```
int main() {
    // ADC_DATA = .... will be executed by Hardware
    volatile int ADC DATA=3;
    // blocking until status is matched
    while(ADC EOC CHECK() == 0);
    int compensated ADC = ADC DATA + 7:
    printf("ADC_DATA is %d\n", ( 0000000000001060 <main>:
                                       1060:
                                              f3 Of 1e fa
                                                                    endbr64
                                       1064: 48 83 ec 18
                                                                    sub
                                                                          $0x18,%rsp
    return 0;
                                       1068: 48 8d 35 95 0f 00 00
                                                                    lea
                                                                          0xf95(%rip),%rsi
                                       106f:
                                              bf 01 00 00 00
                                                                          $0x1,%edi
                                                                    mov
                                       1074:
                                              31 c0
                                                                          %eax,%eax
                                                                    xor
                                       1076:
                                              c7 44 24 0c 03 00 00
                                                                          $0x3(0xc(%rsp)
                                                                    movl
                                       107d:
                                              00
                                       107e:
                                              8b 54 24 0c
                                                                          0xc(%rsp),%edx
                                                                    mov
                                                                          $0x7,%edx
                                       1082:
                                              83 c2 07
                                                                    add
                                                                         1050 <__printf_chk@plt>
                                              e8 c6 ff ff ff
NGV ( KNU AI-SoC Lab ( E)
                                       1085:
                                                                    calla
```

Preventing Cache Access, Explictly Read/Write from/to Memory-Mapped HW



