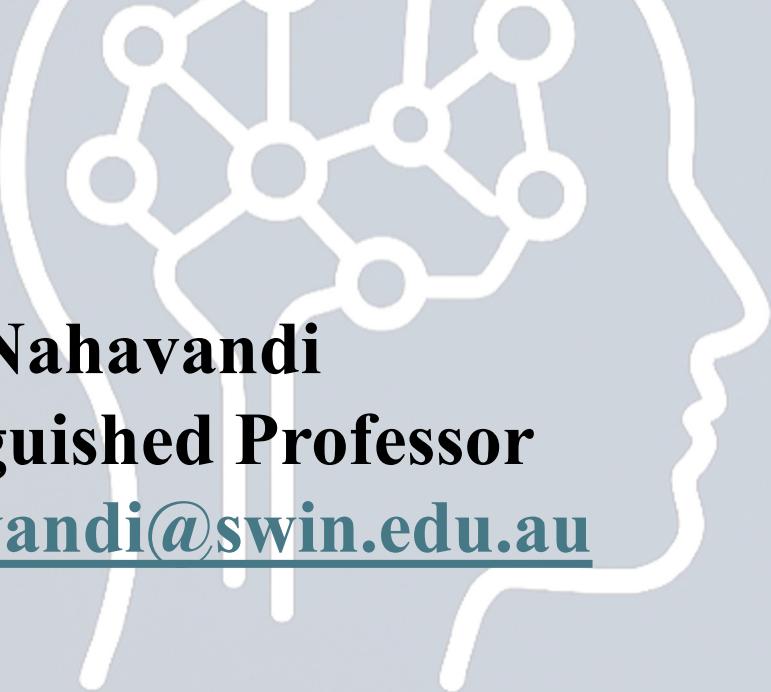
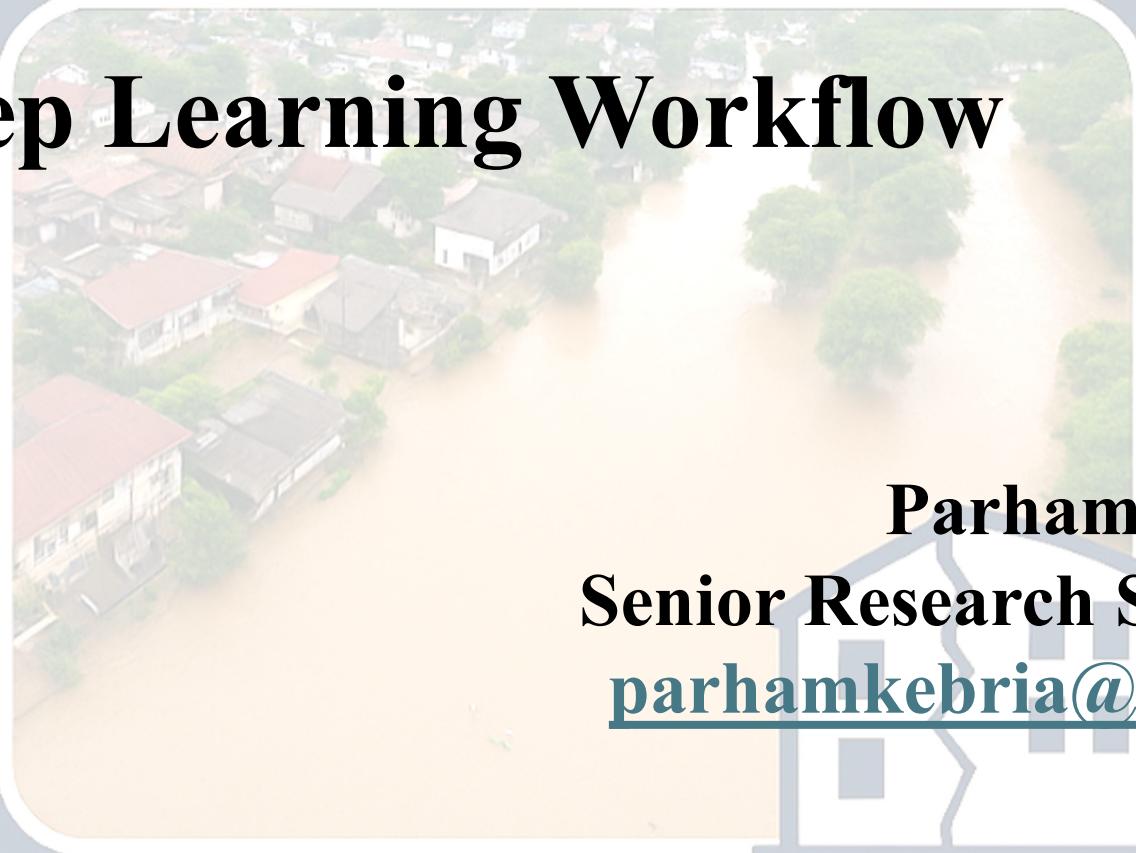


End-to-End Deep Learning Workflow



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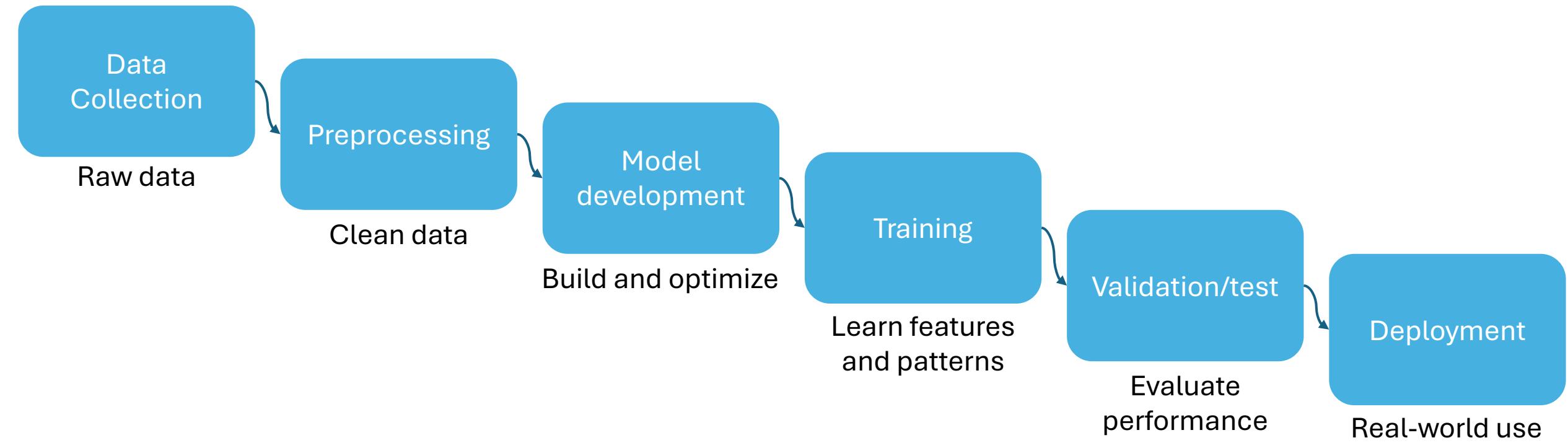
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Advanced Study Institute: Artificial Intelligence for Disaster Management
Orlando, November 17 – 25, 2025



*This activity
is supported by:* The NATO **Science for Peace**
and **Security** Programme

What is a Deep Learning Workflow?



Why an End-to-End Pipeline Matters

- Real-world data is messy, not like curated benchmarks
- Most project times spent on *data* and *validation*
- Deployment ensures the model's value is realized

An End-to-End example:

Drone detecting flood-affected areas

- insights delivered via mobile dashboard
- response actions to be taken based on the insights

→ Data Sources Identified & Collected



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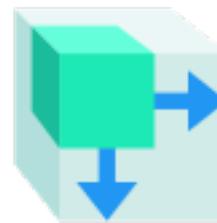


→ Data Preprocessing & Augmentation for Training

→ Data Sources Identified & Collected

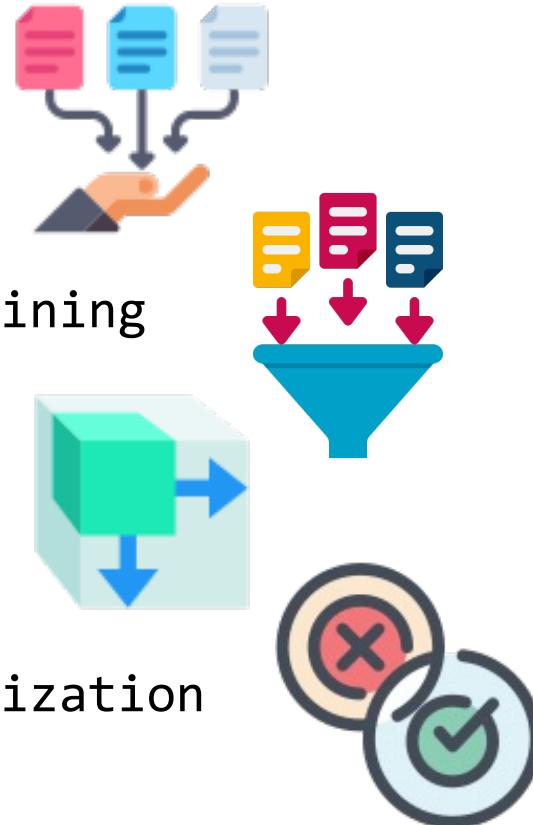


→ Data Preprocessing & Augmentation for Training



→ Design & Develop the Model Architecture

→ Data Sources Identified & Collected

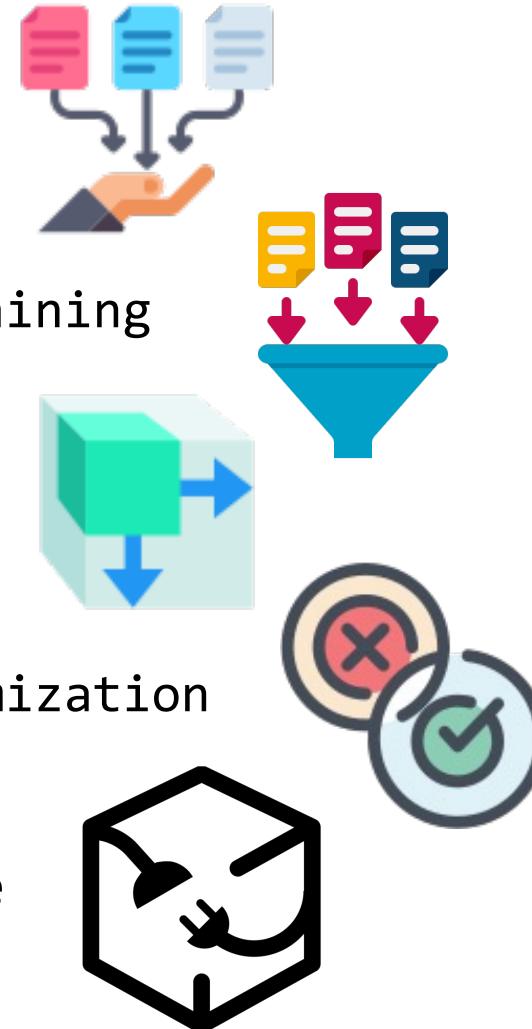


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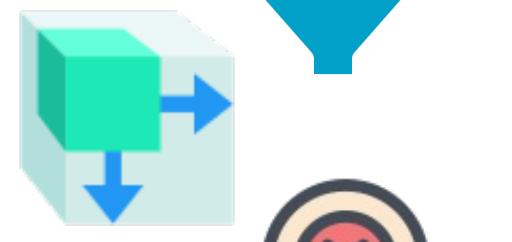
→ Model Training & Validation → Model Optimization

→ Data Sources Identified & Collected



→ Data Preprocessing & Augmentation for Training

→ Design & Develop the Model Architecture



→ Model Training & Validation → Model Optimization

→ Deployment of the Final Model in Practice



Sources:

- Sentinel-2, Landsat, Planet Labs, Kaggle, etc.

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- Manual annotation (slow but accurate)
- Crowdsourcing (Amazon MTurk, LabelBox)
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Handling Noisy Labels

Problem:

- Mislabeling
- Unclear boundaries
- Class imbalance

Solution:

- Cross-check with multiple annotators
- Use polygon-based labeling
- Oversampling/class weights

Tip:

Always inspect a subset of your data visually

Preprocessing Essentials:

- Resize all images to a common input shape
- Normalize pixel values ($[0,1]$ or $[-1,1]$)
- Split dataset \rightarrow Train / Val / Test

Common Augmentations:

Technique	Example	Purpose
Flip/Rotate	90°, 180°	Orientation invariance
Random Crop	Random patch	Simulate zooming
Color Jitter	Vary brightness/contrast	Lighting robustness
Gaussian Noise	Add small noise	Robustness to sensor noise



```
import torchvision.transforms as T

transform = T.Compose([
    T.Resize((224, 224)),
    T.ToTensor(),
    T.Normalize(mean=[0.485, 0.456, 0.406],
                std=[0.229, 0.224, 0.225]))
```



```
from tensorflow.keras.preprocessing.image import ImageDataGenerator

datagen = ImageDataGenerator(
    rescale=1./255,
    rotation_range=15,
    horizontal_flip=True,
    zoom_range=0.1)
```



Deployment Options:

<i>Platform</i>	<i>Use Case</i>	<i>Tools</i>
Mobile App	On-device detection	TensorFlow Lite / Core ML
Drone	Real-time edge inference	NVIDIA Jetson / ONNX
Web API	REST-based model serving	FastAPI / Flask + TorchServe

This Session:

- ❖ Deep learning = pipeline, not just model
- ❖ Data quality >> Model complexity
- ❖ Always visualize and validate at each step
- ❖ Deployment ensures real-world impact

Previous sessions:

- ✓ Image Classification Fundamentals
- ✓ CNN Architectures
- ✓ Transfer Learning & Fine-Tuning
- ✓ Full pipeline integration

1. What is the most time-consuming stage of a deep learning project?
 - a) Training
 - b) Data collection and cleaning
 - c) Deployment

2. Why is normalization important before training?
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 - c) Reduces dataset size

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(Q&A)

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