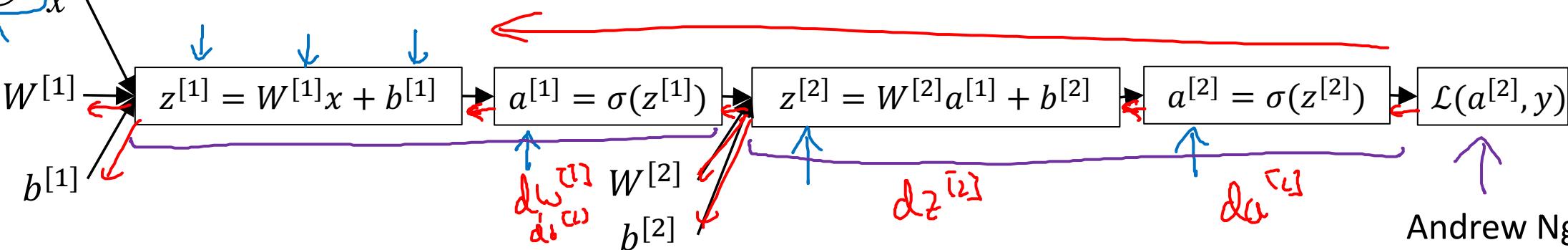
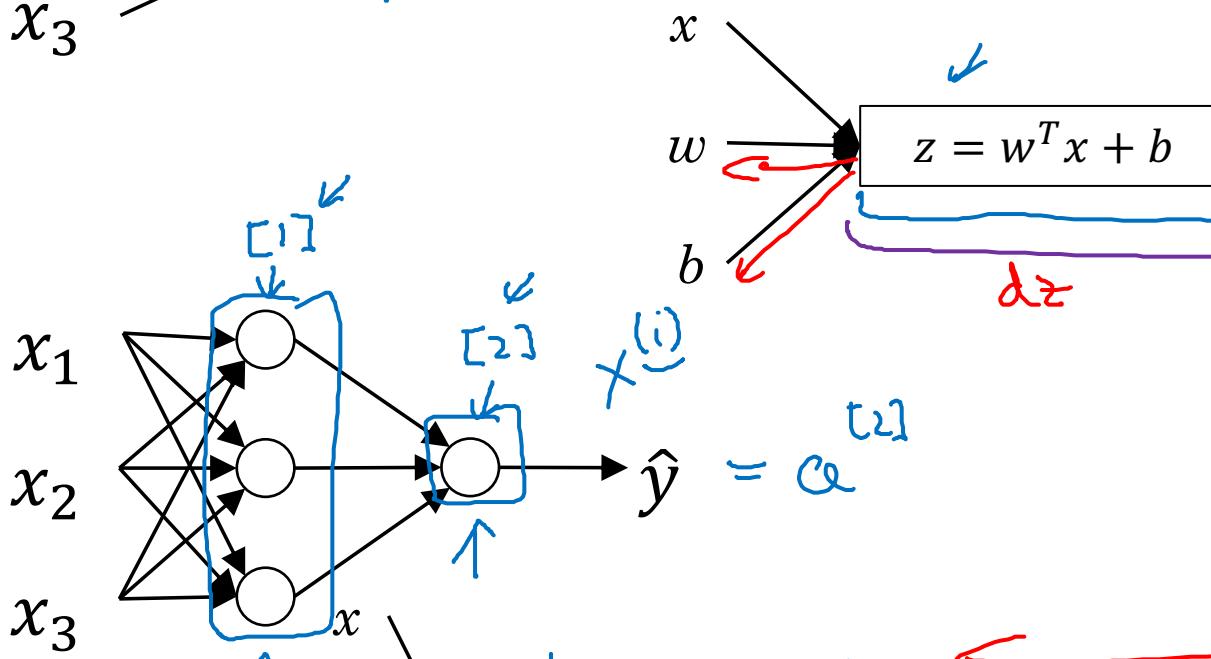
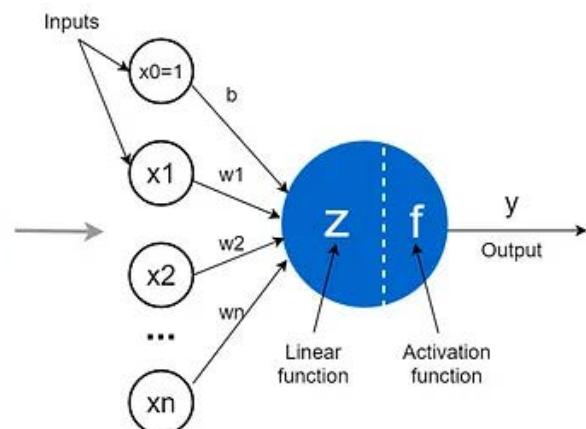
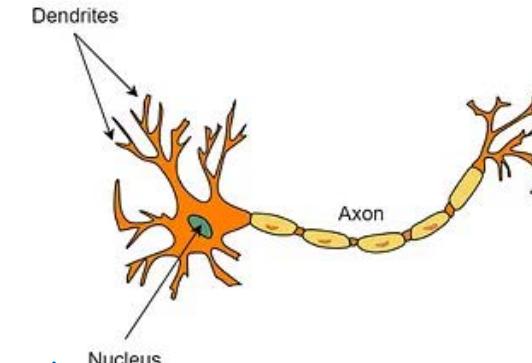
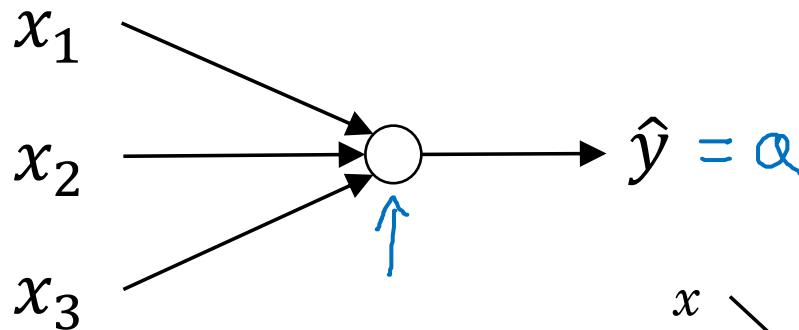
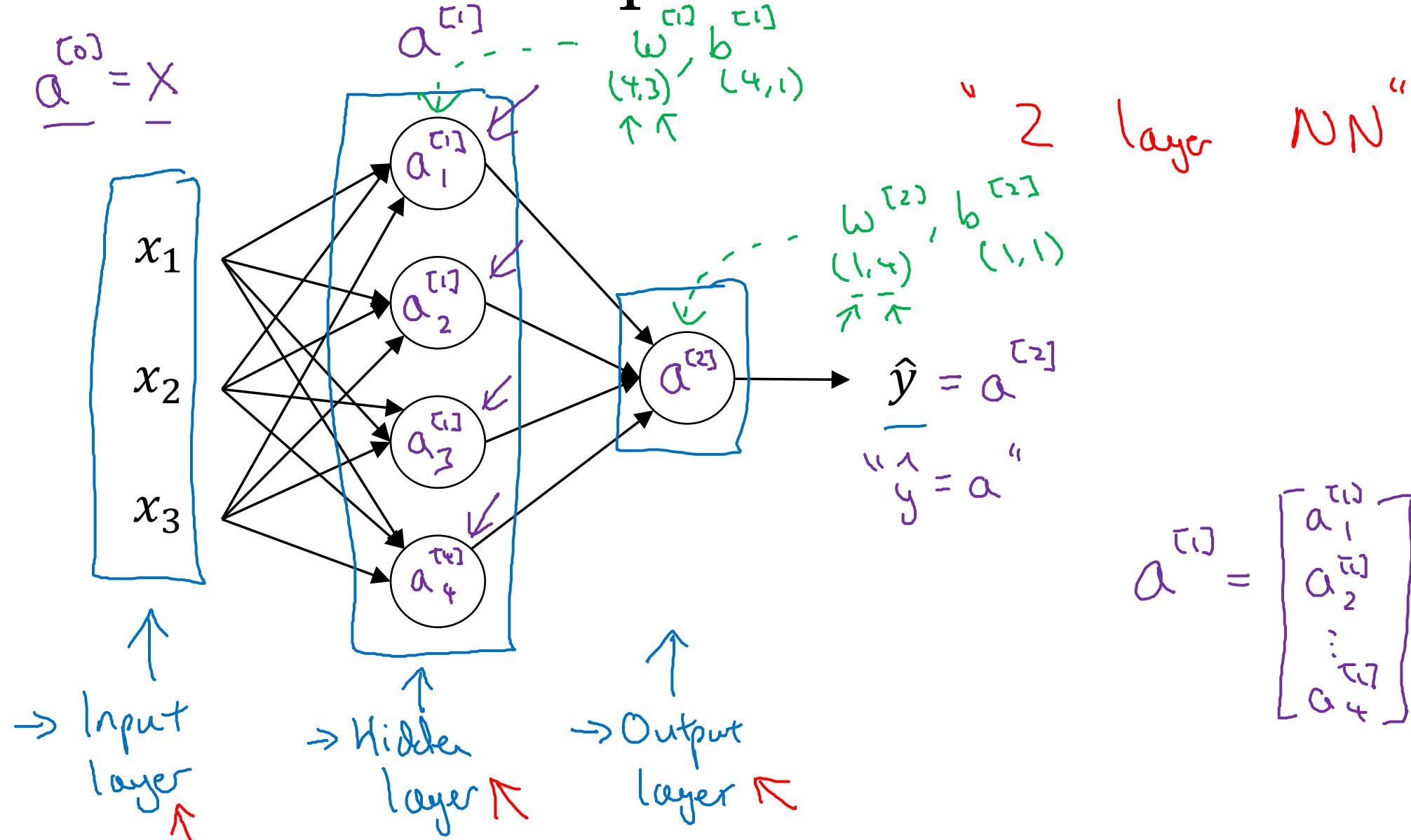


# What is a Neural Network?

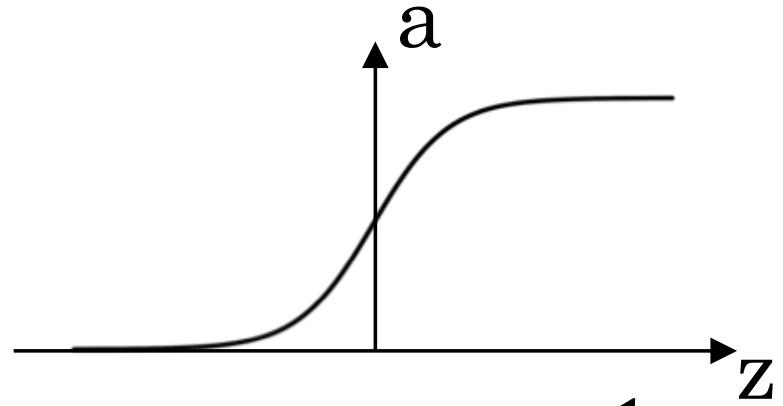


Andrew Ng

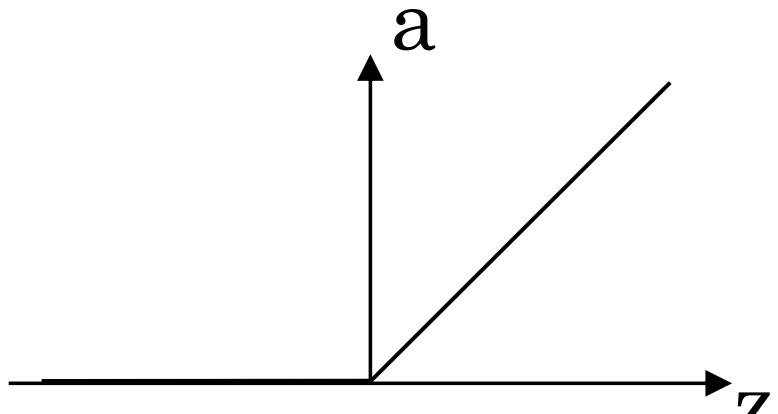
# Neural Network Representation



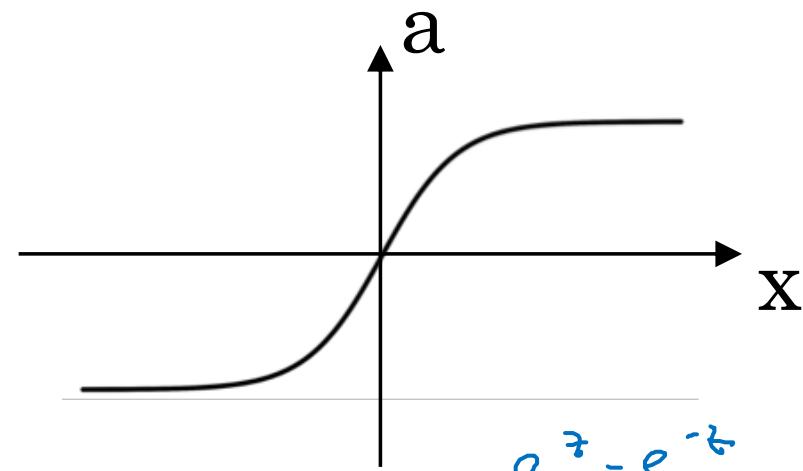
# Pros and cons of activation functions



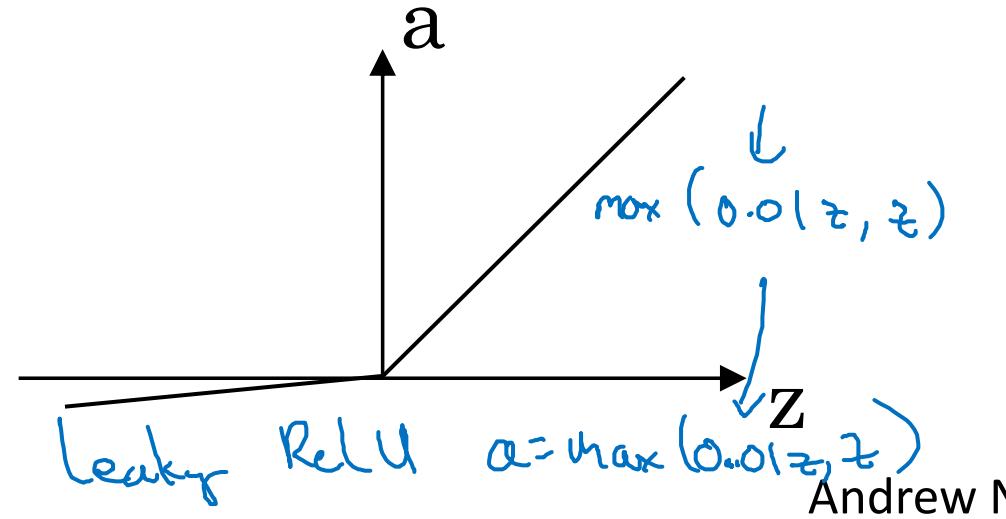
$$\text{sigmoid: } a = \frac{1}{1 + e^{-z}}$$



$$\text{ReLU} \quad a = \max(0, z)$$



$$\tanh: \quad a = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$



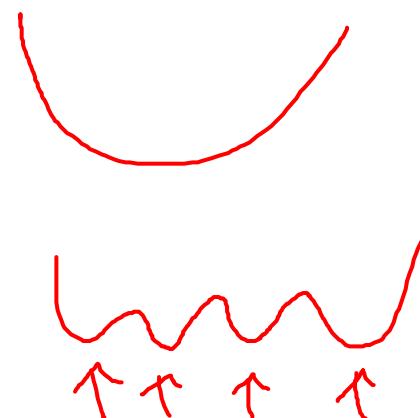
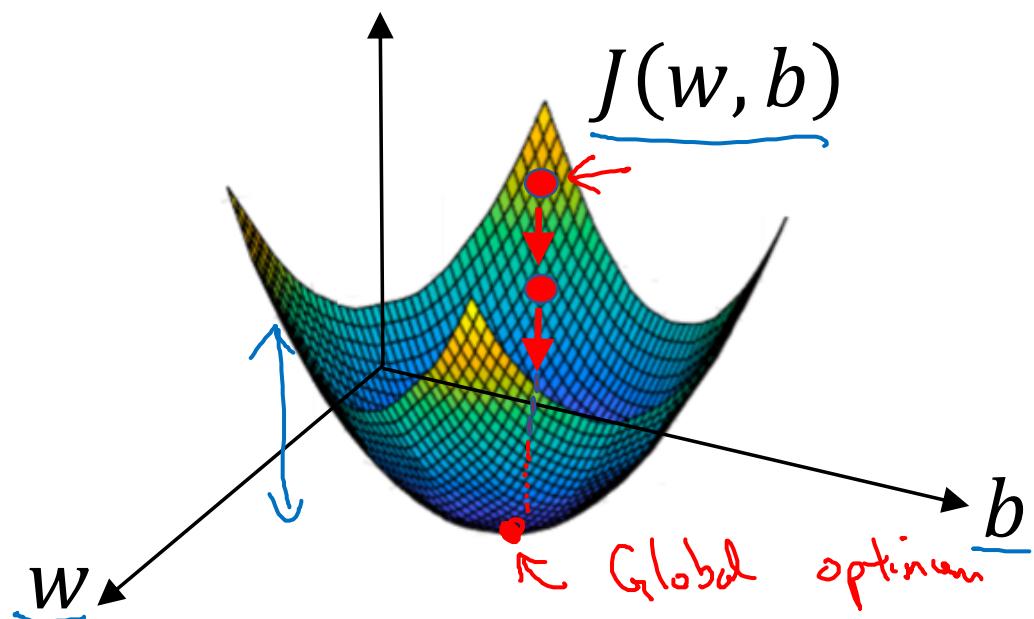
$$\text{Leaky ReLU} \quad a = \max(0.01z, z) \quad \text{Andrew Ng}$$

# Gradient Descent

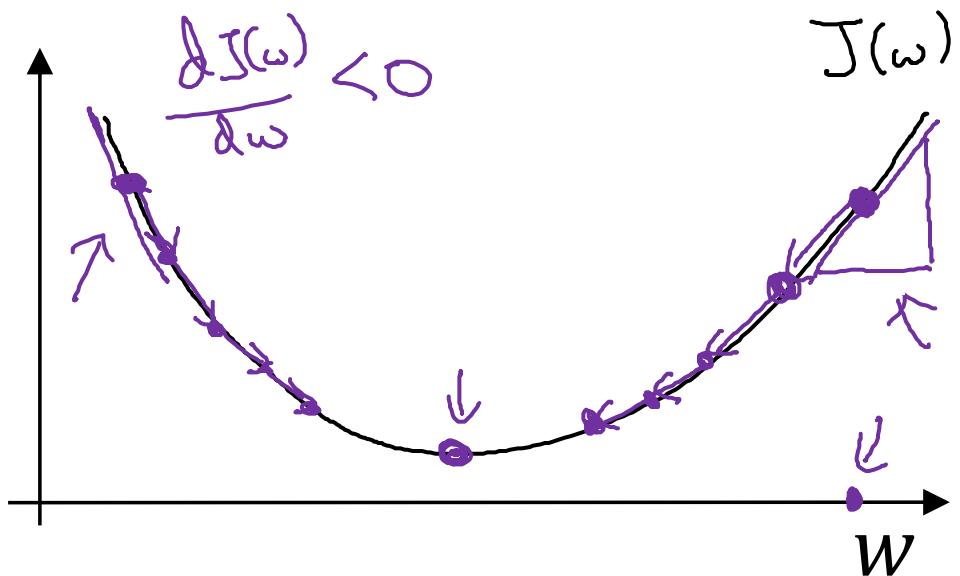
Recap:  $\hat{y} = \sigma(w^T x + b)$ ,  $\sigma(z) = \frac{1}{1+e^{-z}}$  

$$\underline{J(w, b)} = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}^{(i)}, y^{(i)}) = -\frac{1}{m} \sum_{i=1}^m y^{(i)} \log \hat{y}^{(i)} + (1 - y^{(i)}) \log(1 - \hat{y}^{(i)})$$

Want to find  $w, b$  that minimize  $J(w, b)$



# Gradient Descent



Repeat {

$$\omega := \omega - \alpha \frac{dJ(\omega)}{d\omega}$$

}

$\omega := \omega - \alpha \frac{dJ(\omega)}{d\omega}$

learning rate

$\frac{dJ(\omega)}{d\omega} = ?$

---


$$J(\omega, b)$$

$$\omega := \omega - \alpha \frac{dJ(\omega, b)}{d\omega}$$

$$b := b - \alpha \frac{dJ(\omega, b)}{db}$$

$$\frac{\partial J(\omega, b)}{\partial \omega}$$

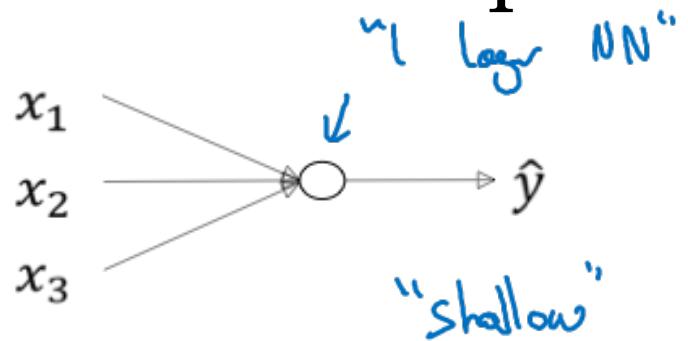
$$\frac{\partial J(\omega, b)}{\partial b}$$

"partial derivative"  $J$

$d\omega$

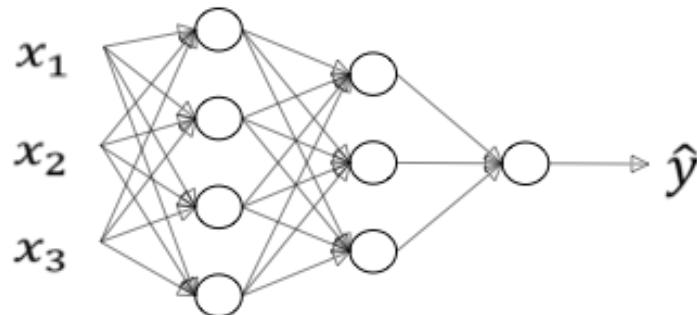
$db$

# What is a deep neural network?

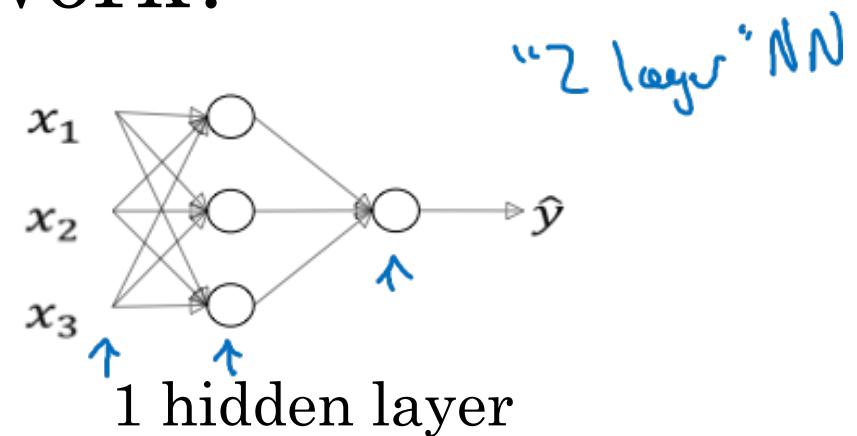


*"Shallow"*

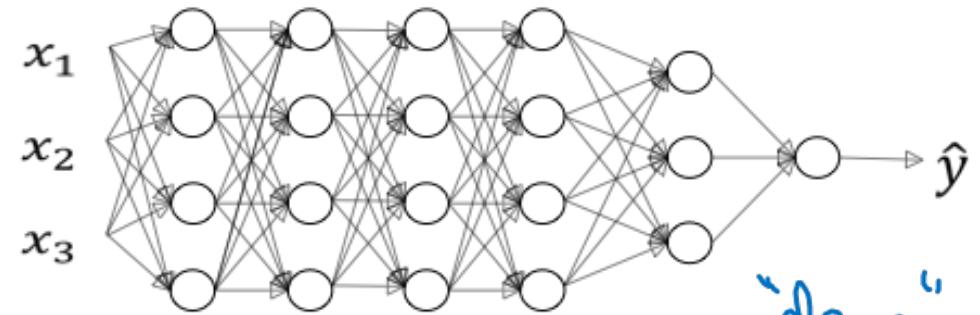
logistic regression



2 hidden layers



1 hidden layer

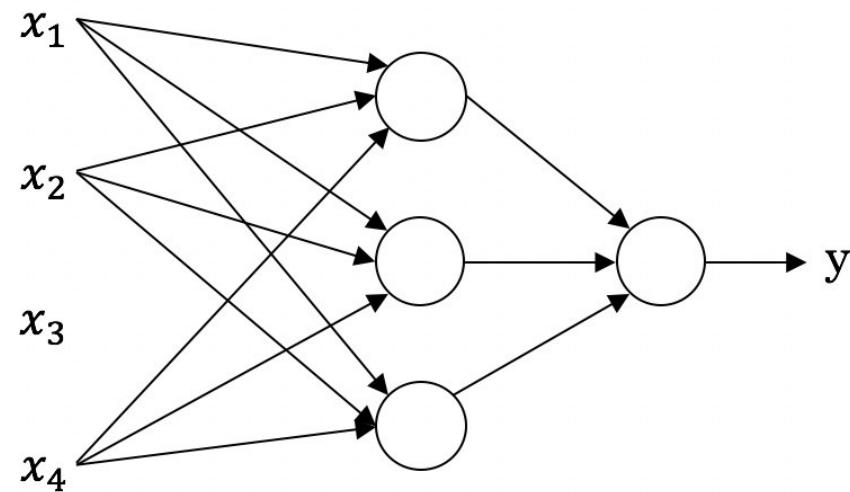


5 hidden layers

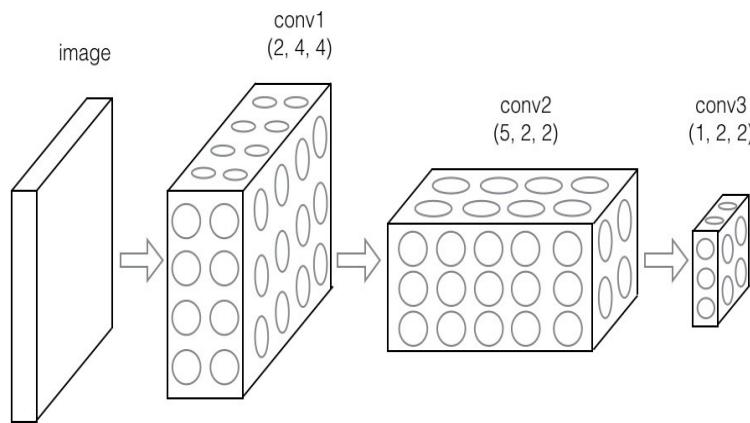
*"deep"*

Andrew  
n.t

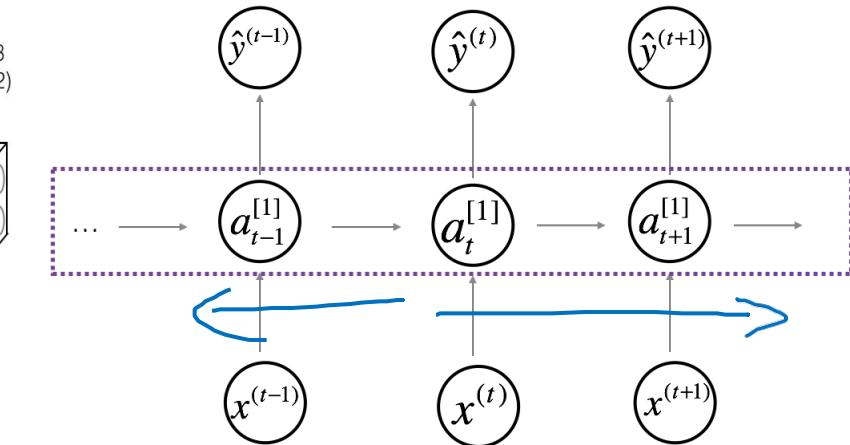
# Neural Network examples



Standard NN



Convolutional NN



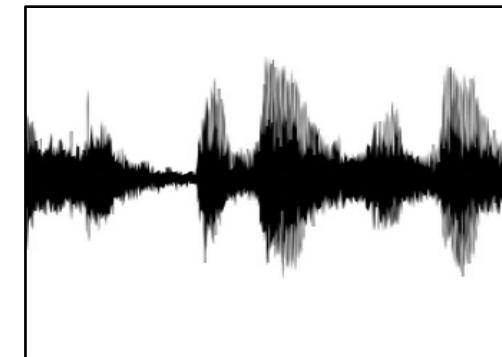
Recurrent NN

# Supervised Learning

Structured Data

Size	#bedrooms	...	Price (1000\$)
2104	3		400
1600	3		330
2400	3		369
...	...		...
3000	4		540

Unstructured Data



Audio

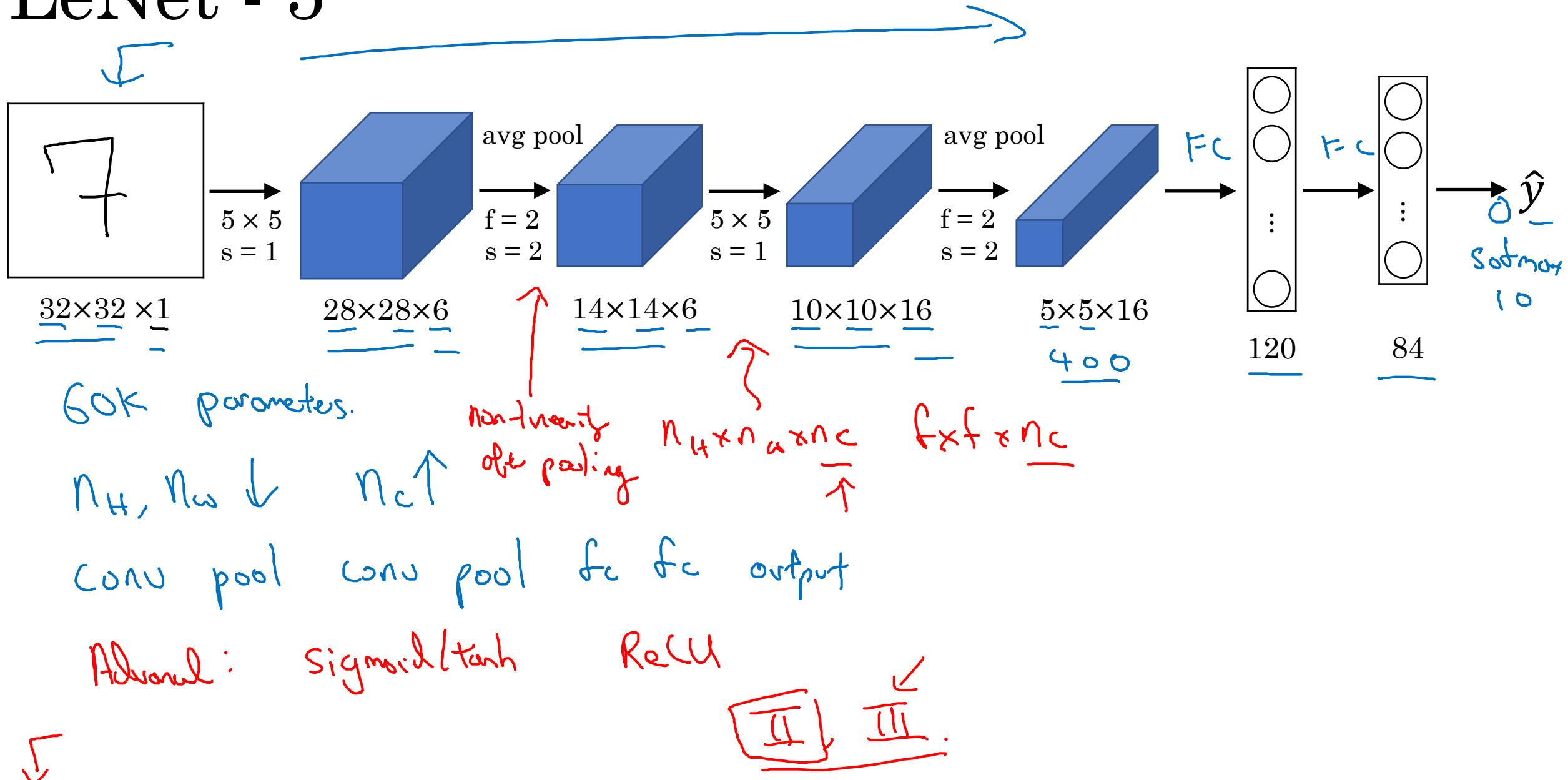
Image

User Age	Ad Id	...	Click
41	93242		1
80	93287		0
18	87312		1
...	...		...
27	71244		1

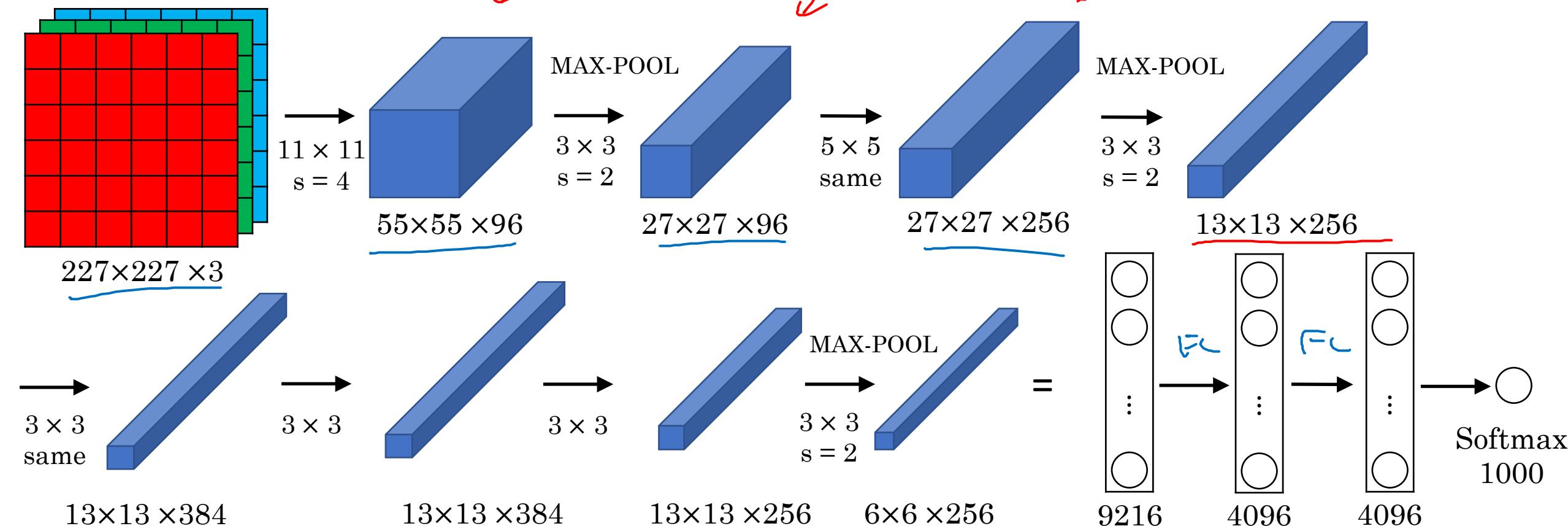
Four scores and seven years ago...

Text

# LeNet - 5

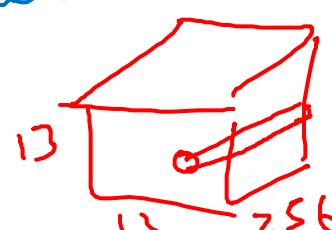


# AlexNet



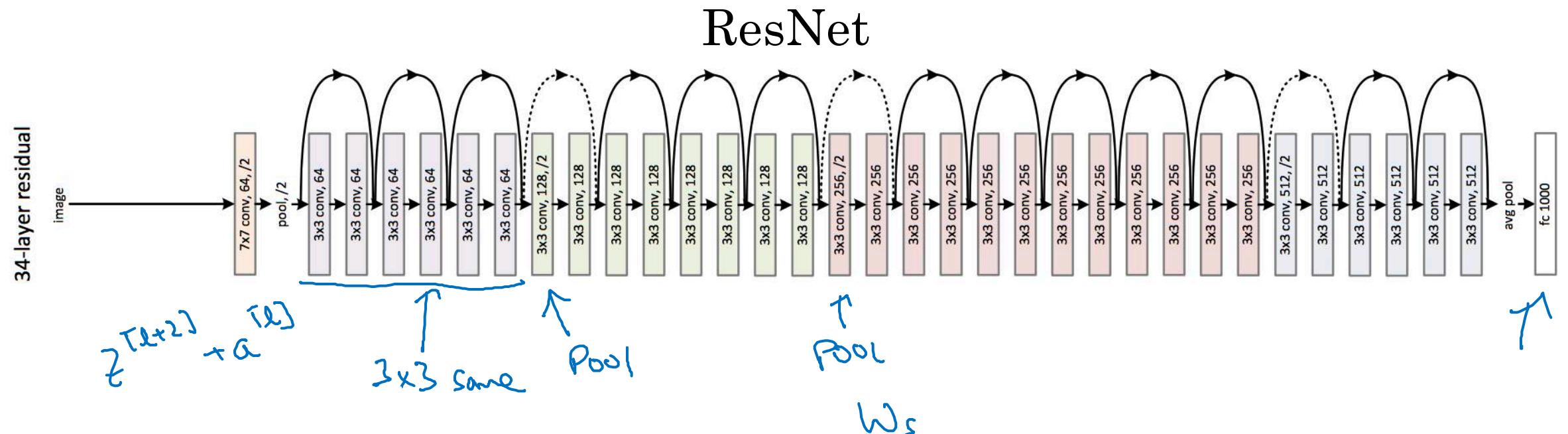
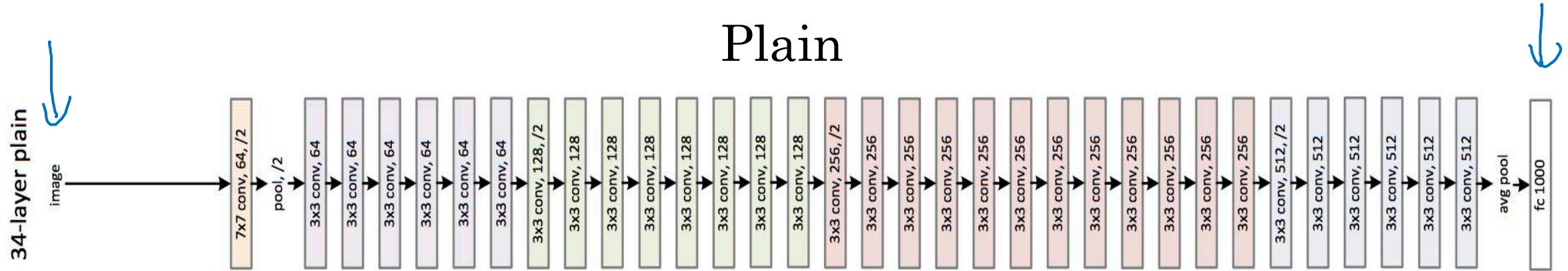
- Similar to LeNet, but much bigger.
- ReLU

- Multiple GPUs.  
- Local Response Normalization (LRN)



~60M Parameters

# ResNet

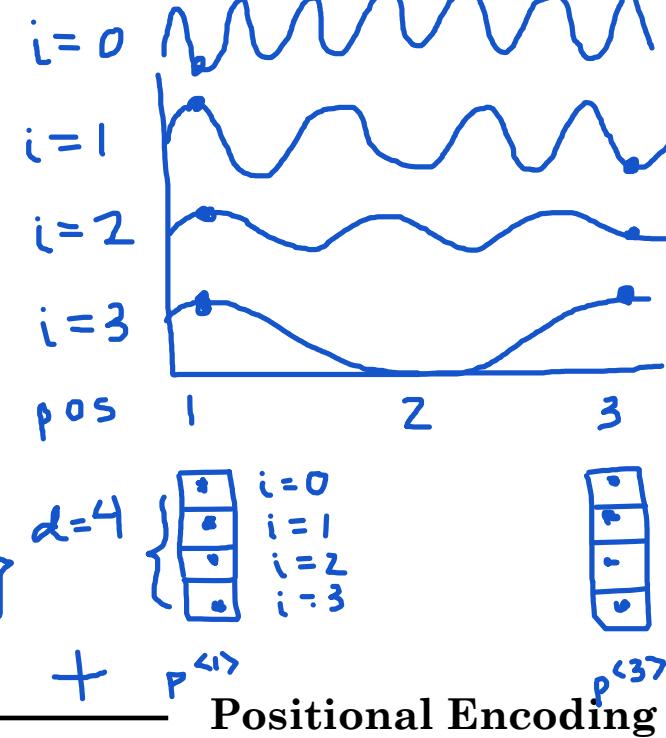
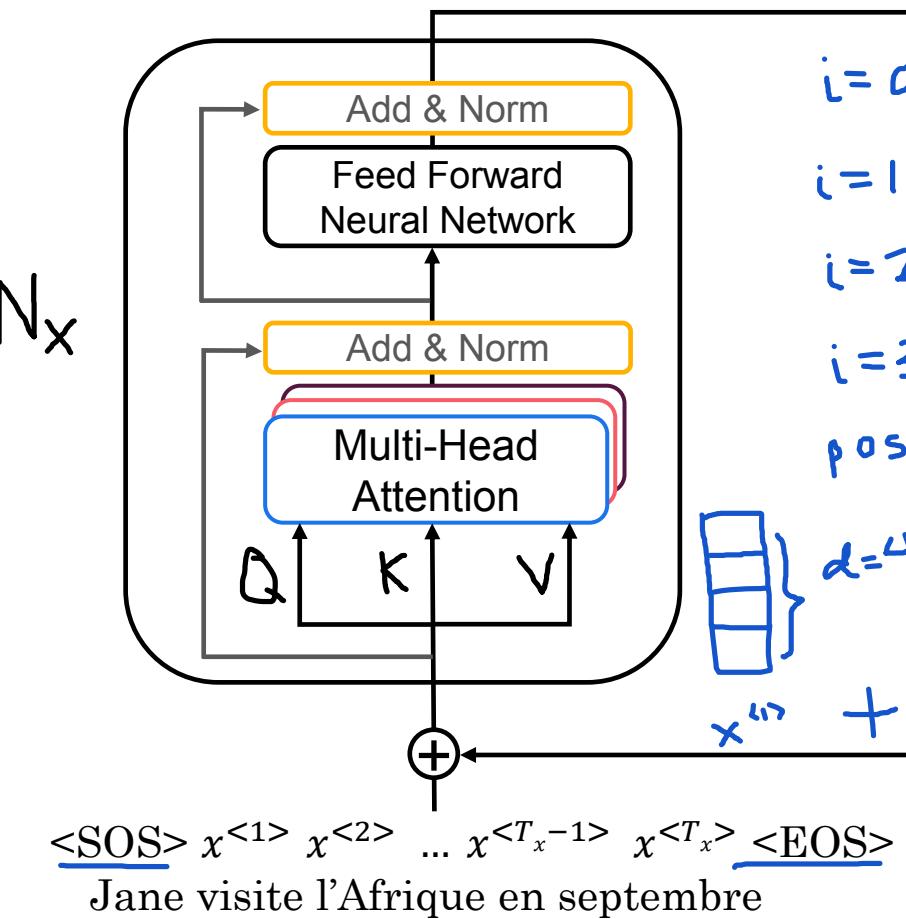


[He et al., 2015. Deep residual networks for image recognition]

Andrew Ng

# Transformer Details

## Encoder

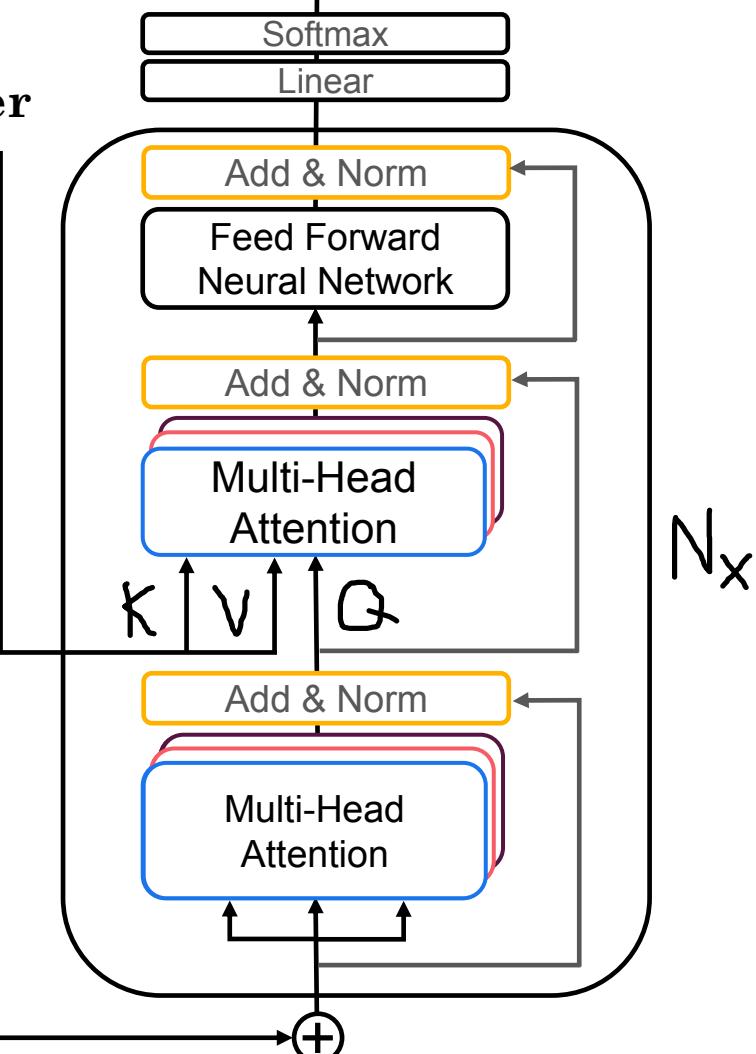


$$PE_{(pos,2i)} = \sin\left(\frac{pos}{1000^{\frac{2i}{d}}}\right)$$

$$PE_{(pos,2i+1)} = \cos\left(\frac{pos}{1000^{\frac{2i+1}{d}}}\right)$$

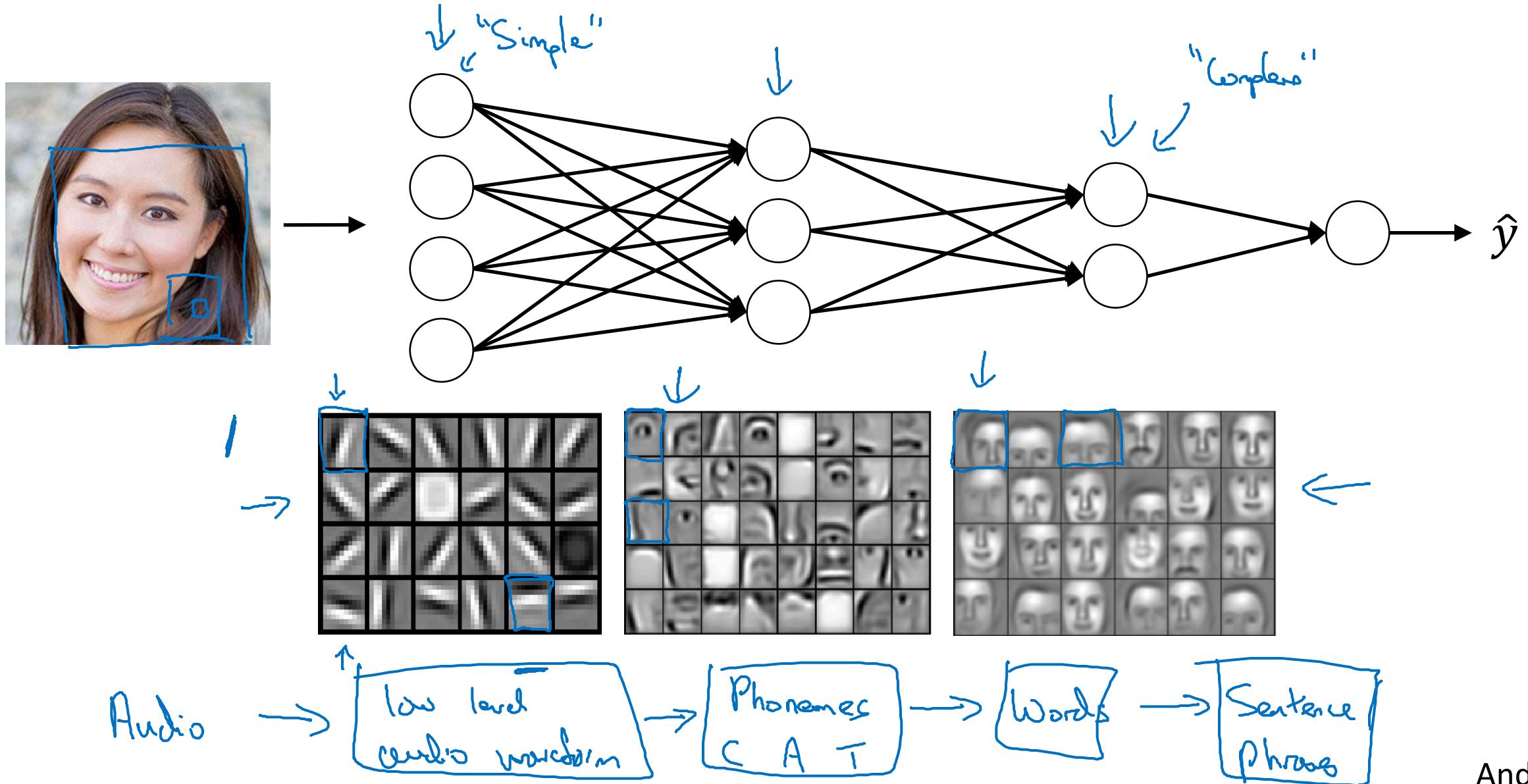
<SOS> Jane visits Africa in September <EOS>

## Decoder

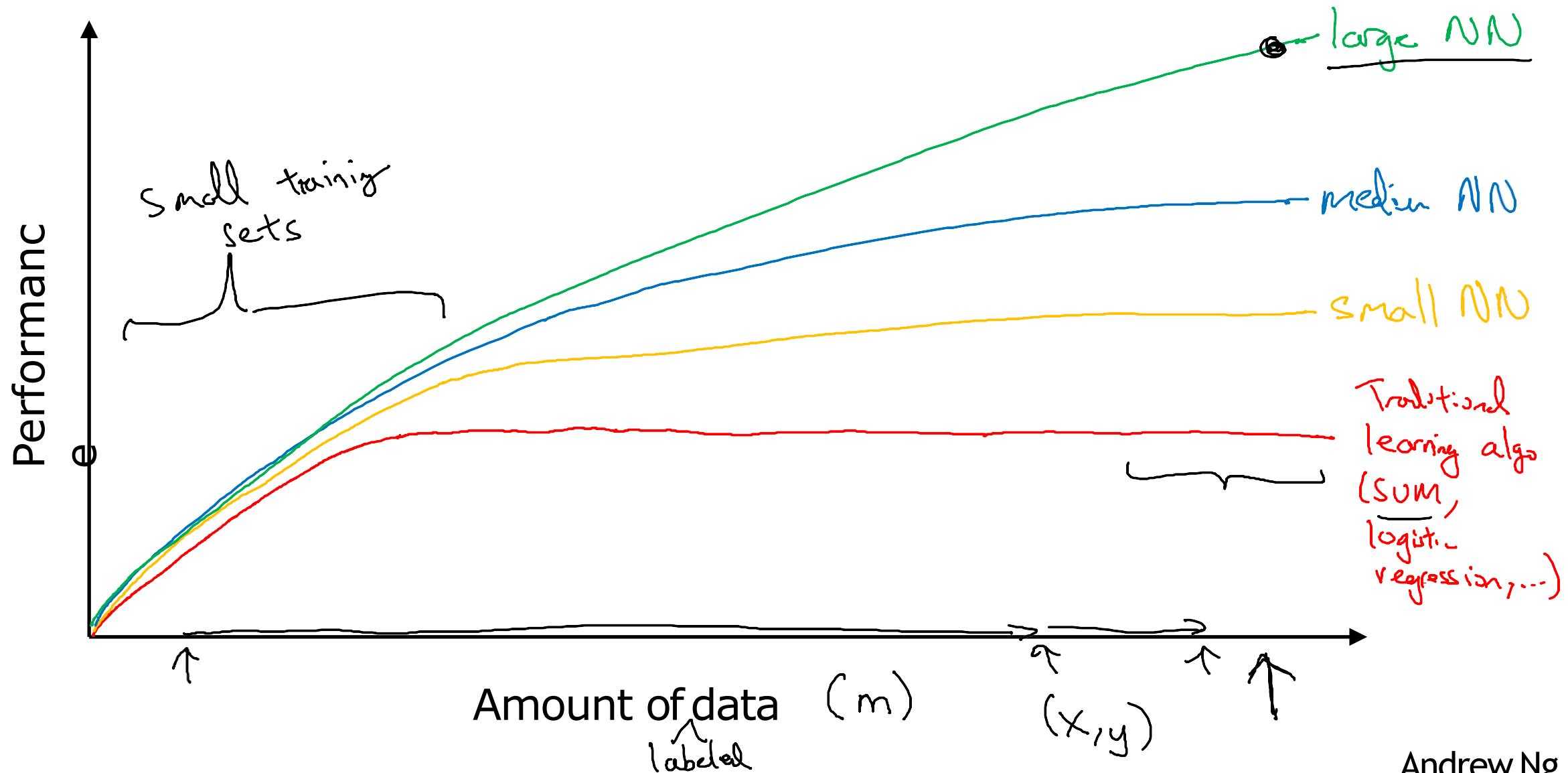


$<\text{SOS}>$  Jane visits Africa in September

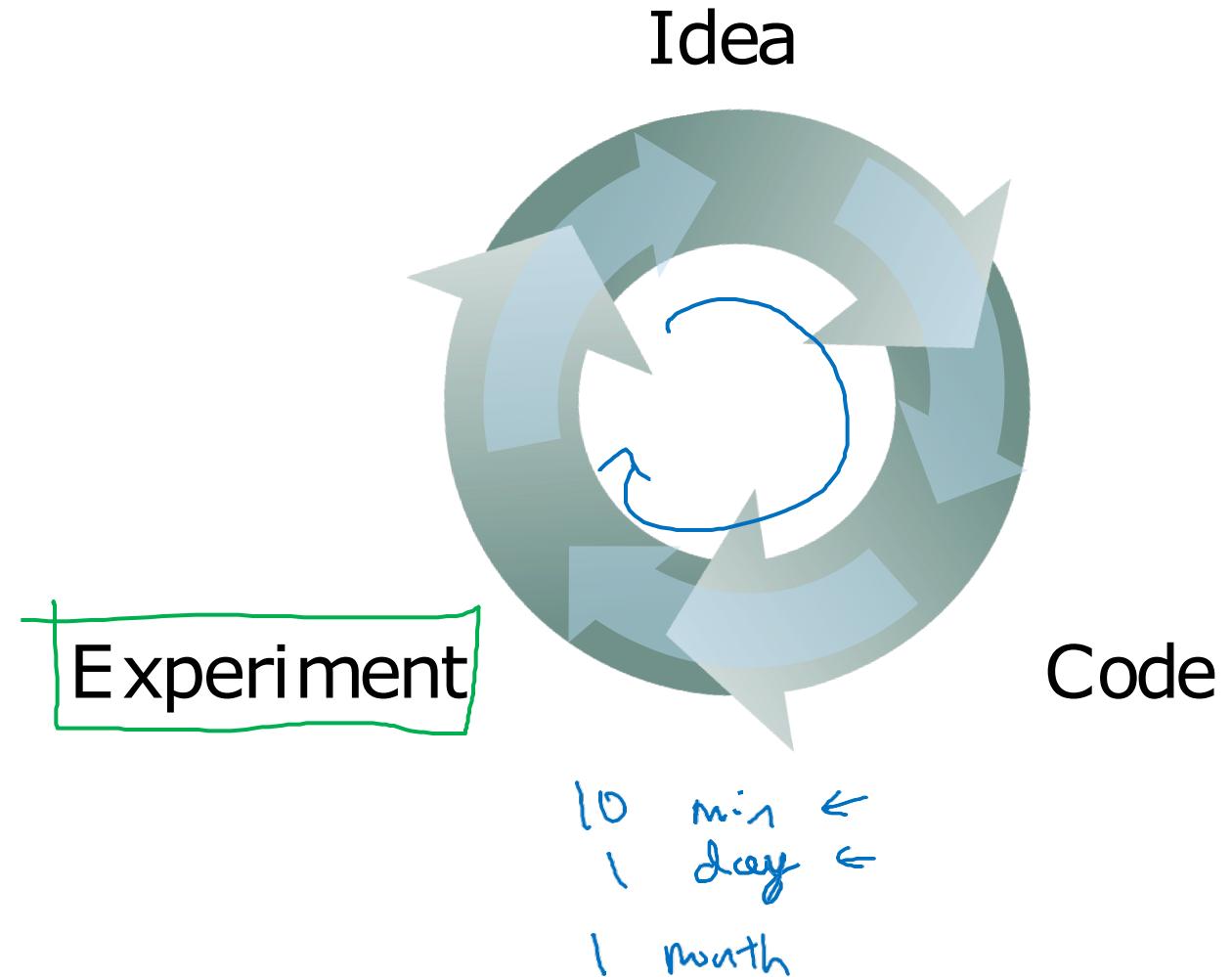
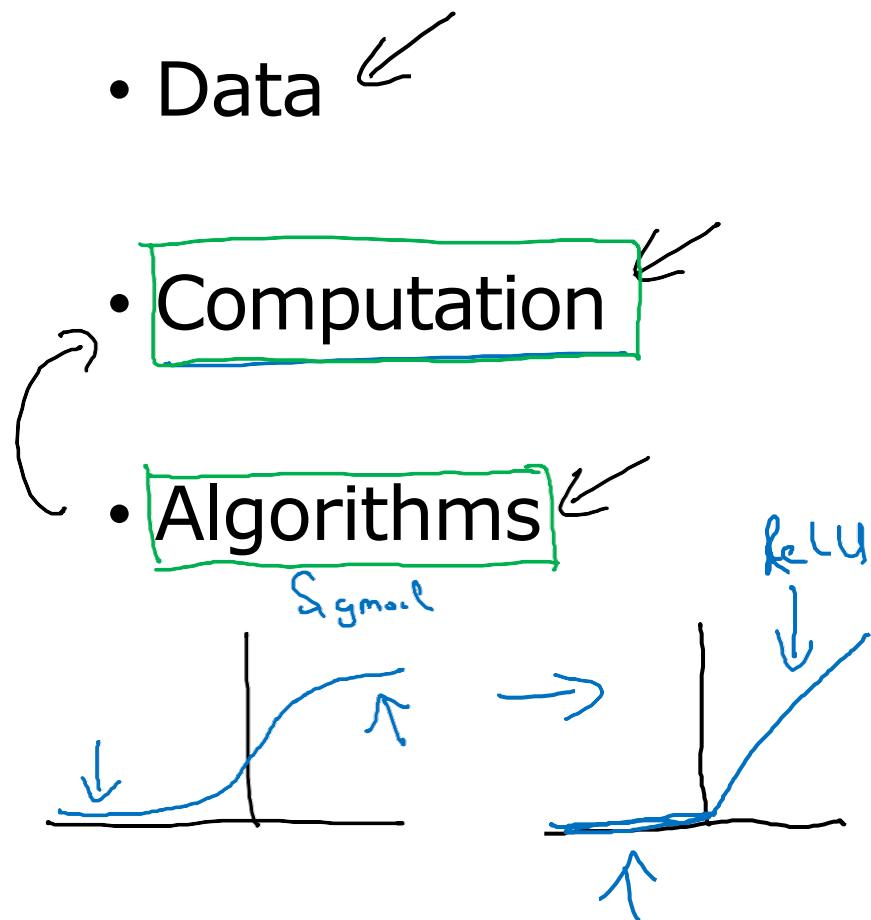
# Intuition about deep representation



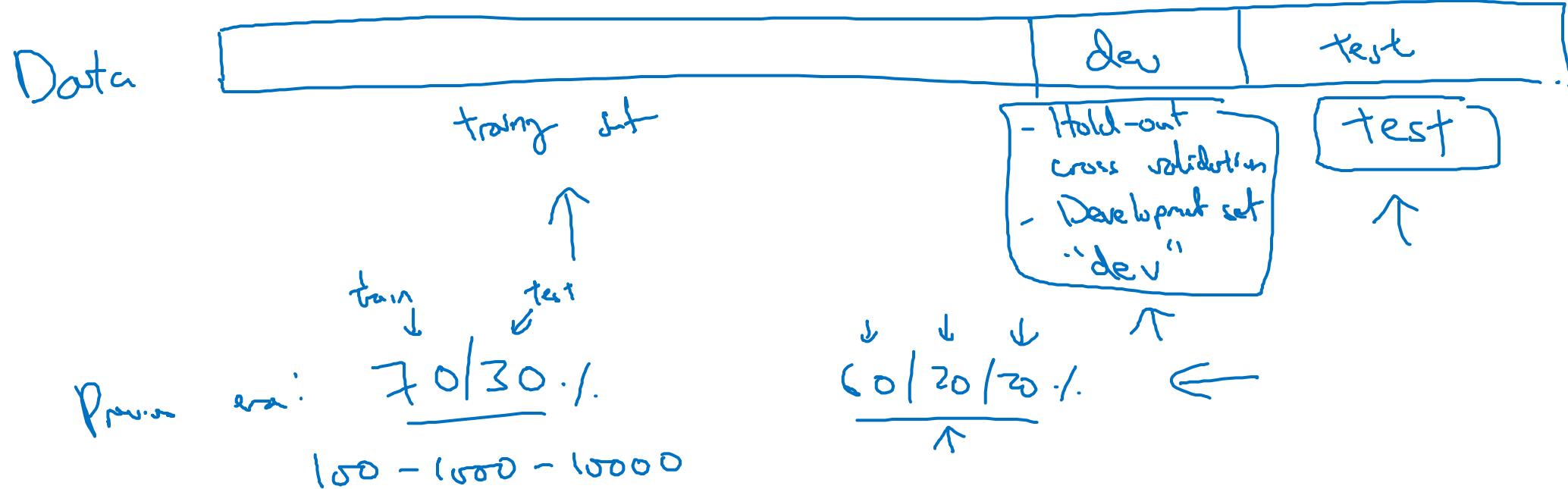
# Scale drives deep learning progress



# Scale drives deep learning progress



# Train/dev/test sets



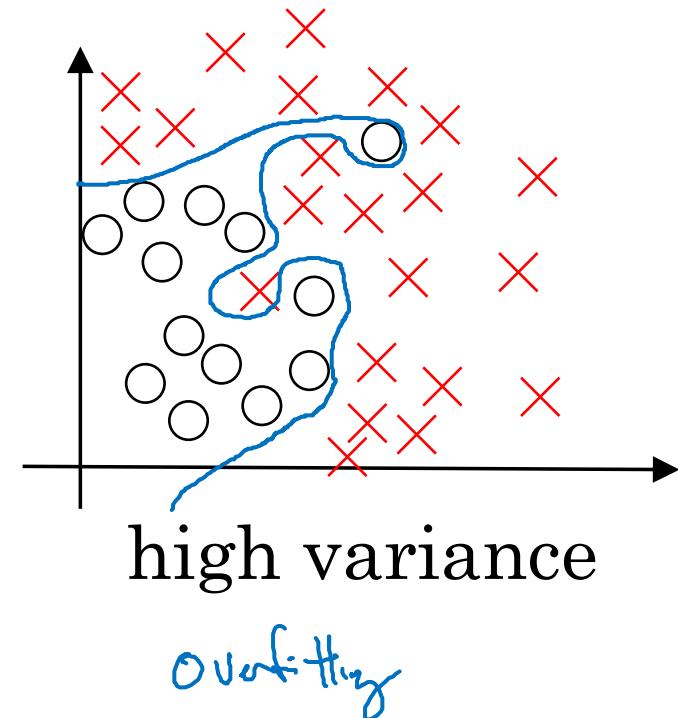
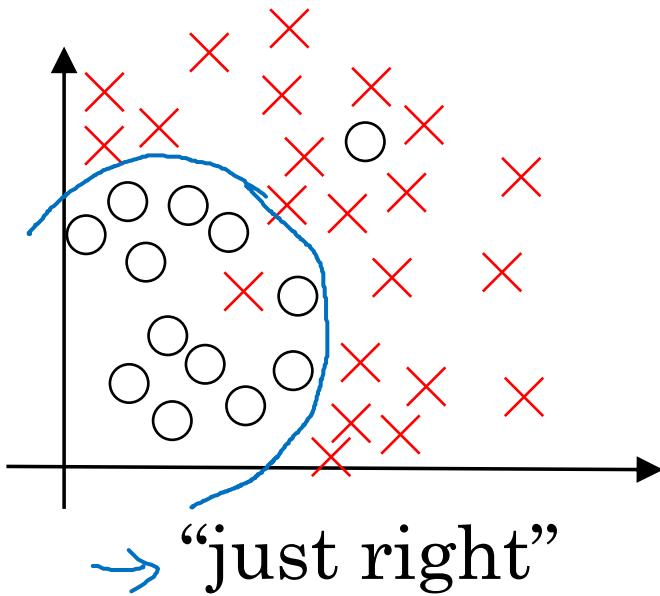
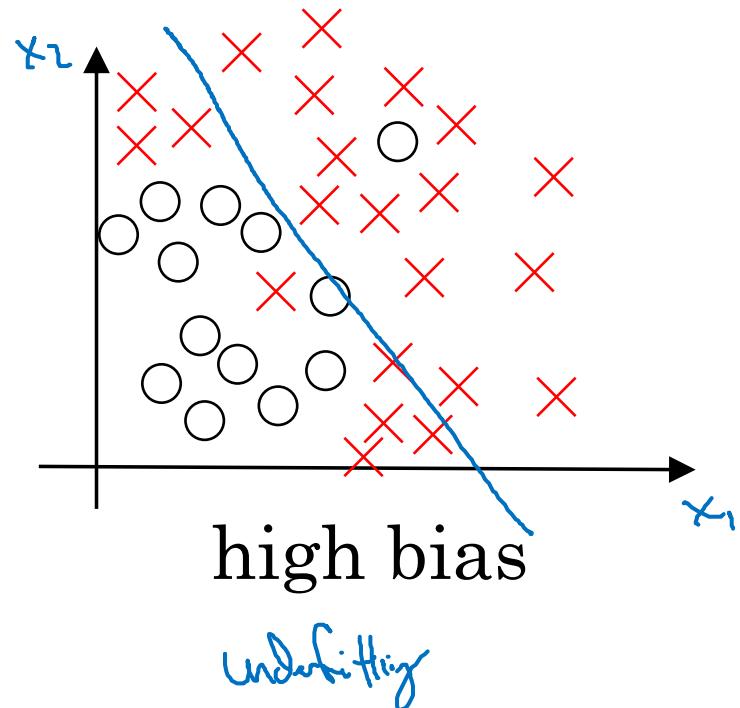
Big data! 1,000,000

10,000 10,000

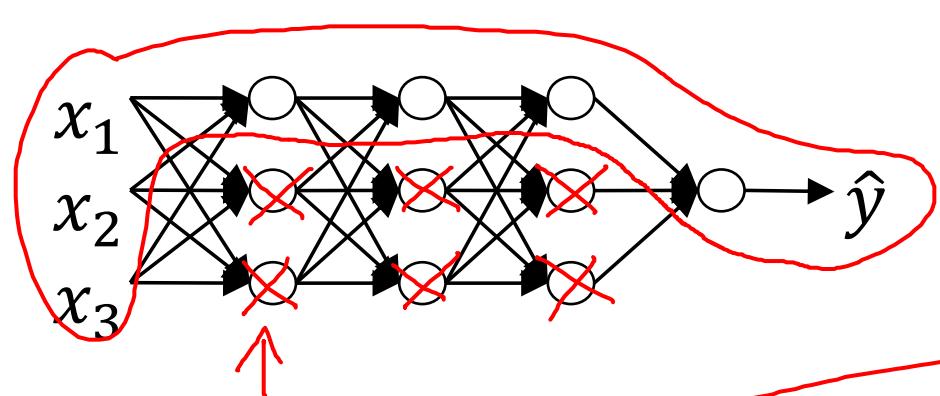
98 / 1 / 1 . .

99.5 { 25 / 25  
        : 4 { - 1 . 1 .

# Bias and Variance

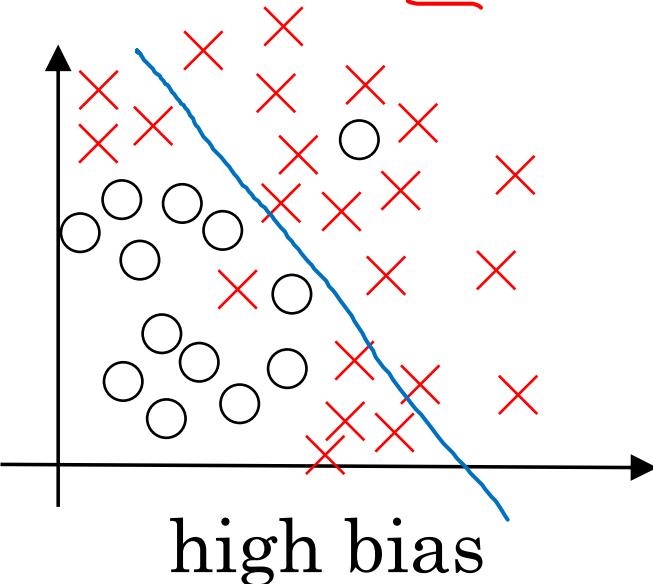


# How does regularization prevent overfitting?

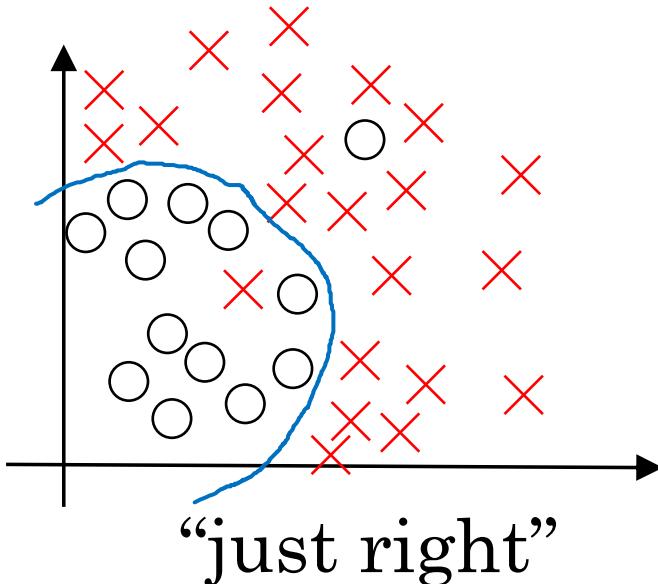


$$J(\boldsymbol{\theta}^{(m)}, \boldsymbol{b}^{(m)}) = \frac{1}{m} \sum_{i=1}^m \ell(y^{(i)}, \hat{y}^{(i)}) + \frac{\lambda}{2m} \sum_{l=1}^L \|\boldsymbol{w}^{(l)}\|_F^2$$

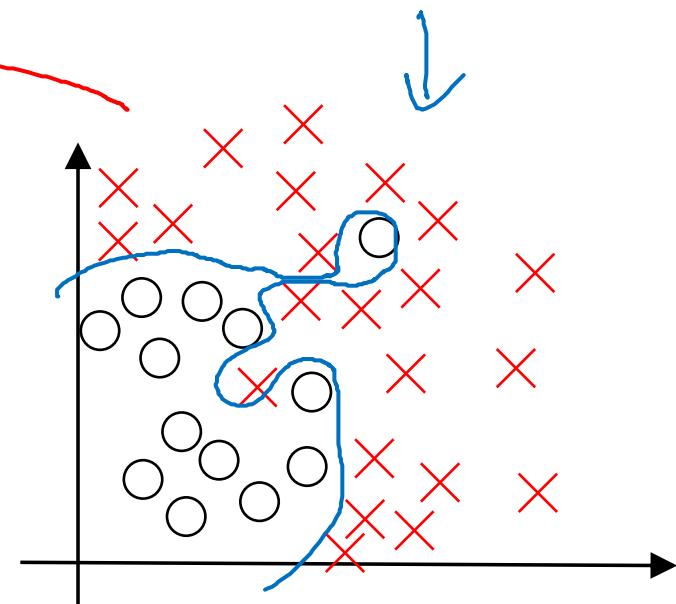
$\boldsymbol{w}^{(l)} \approx 0$



high bias

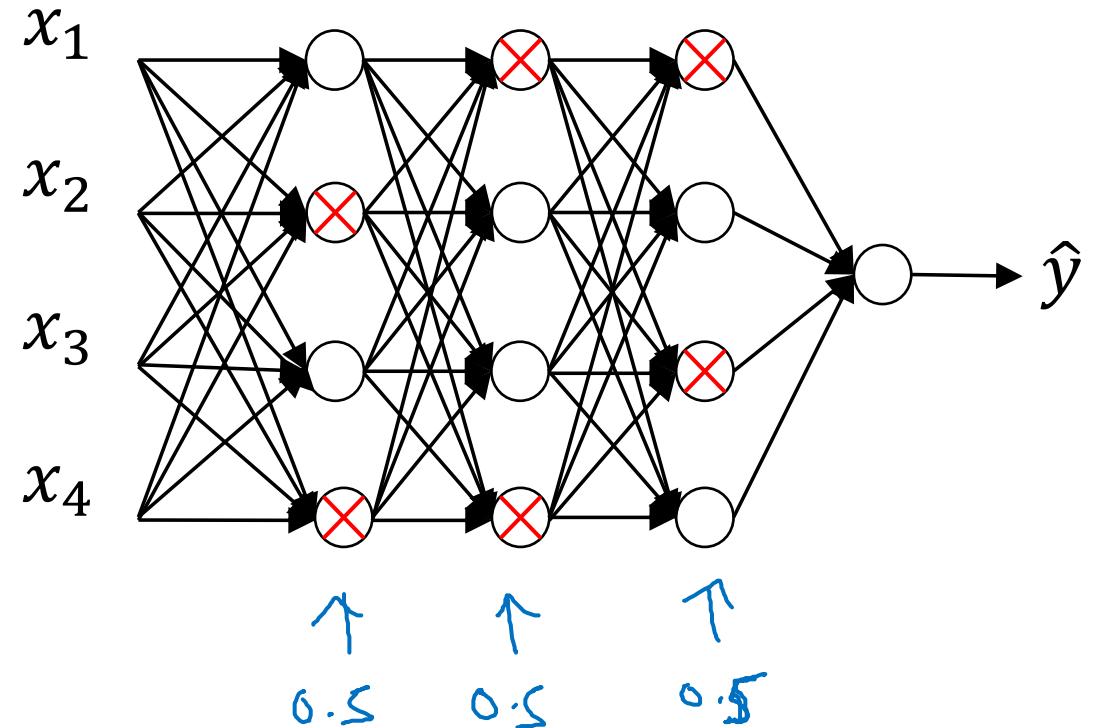
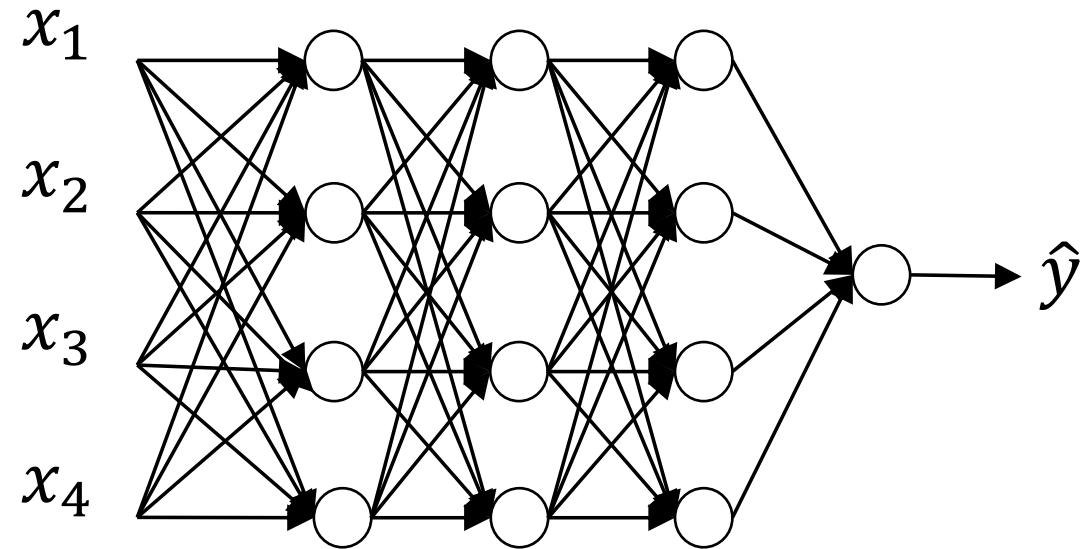


"just right"



high variance

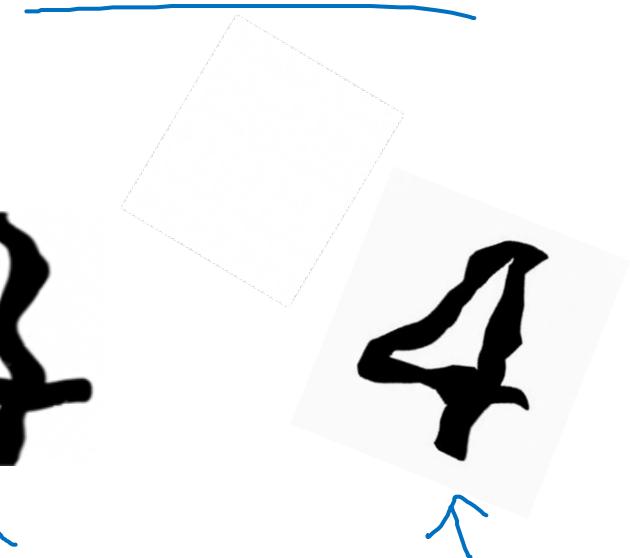
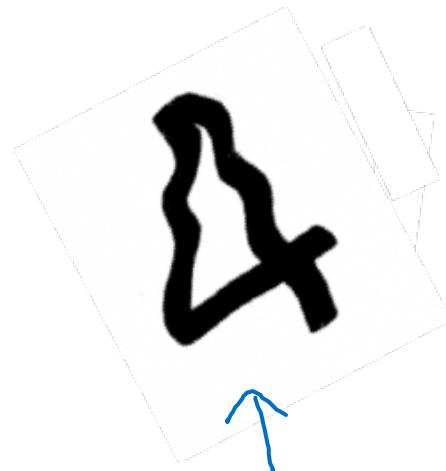
# Dropout regularization



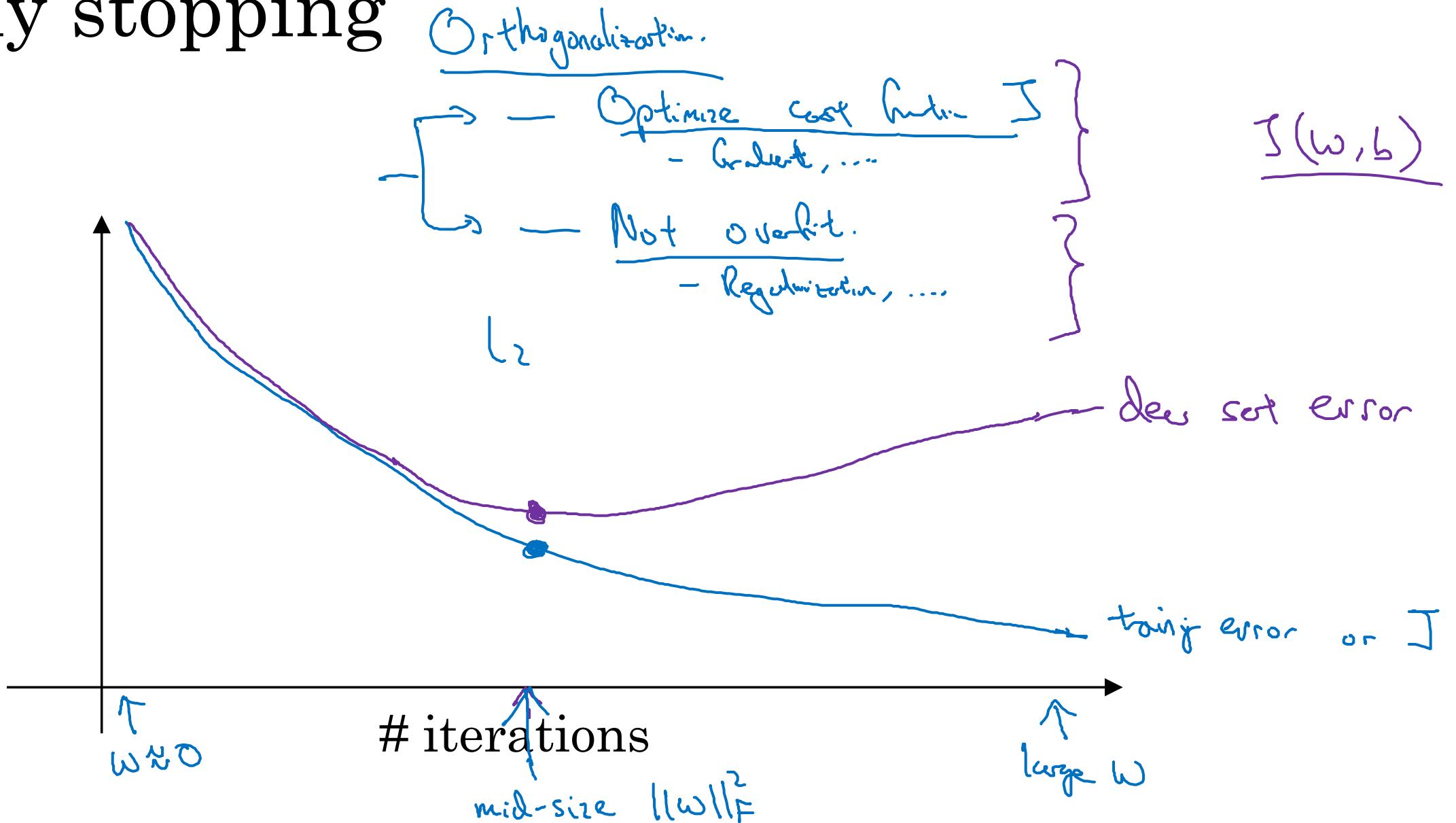
# Data augmentation



4



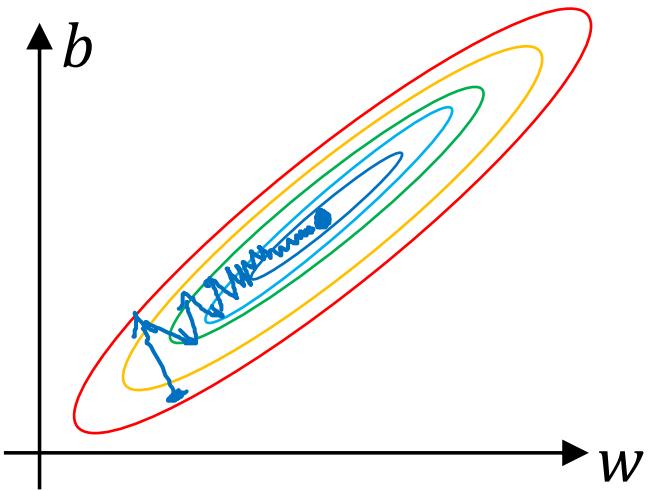
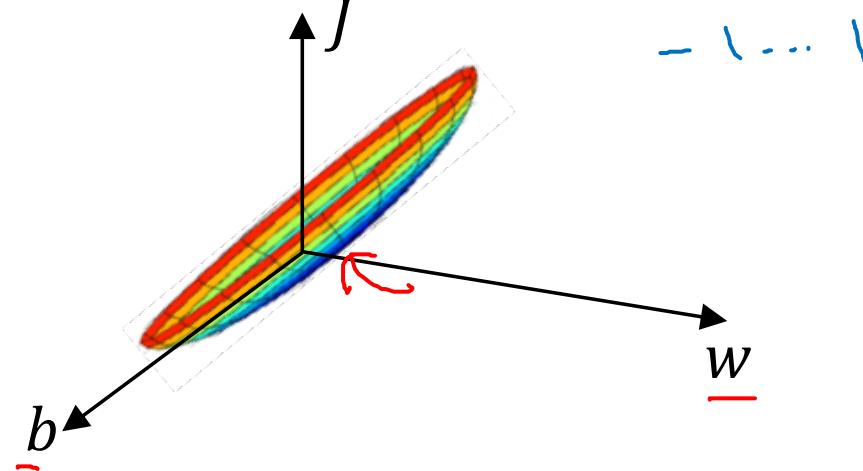
# Early stopping



# Why normalize inputs?

$\omega_1 \quad x_1: \frac{1 \dots 1000}{0 \dots 1} \leftarrow$   
 $\omega_2 \quad x_2: \frac{0 \dots 1}{-1 \dots 1} \leftarrow$

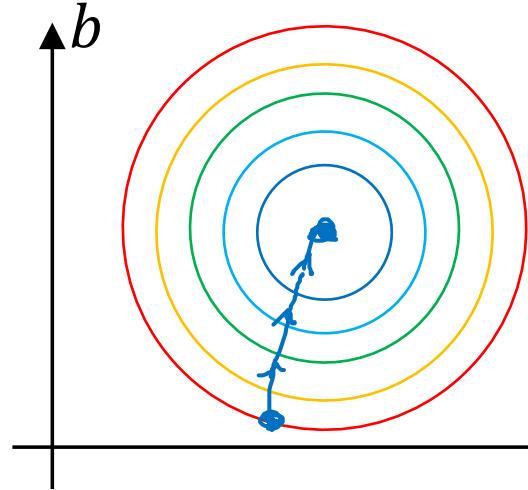
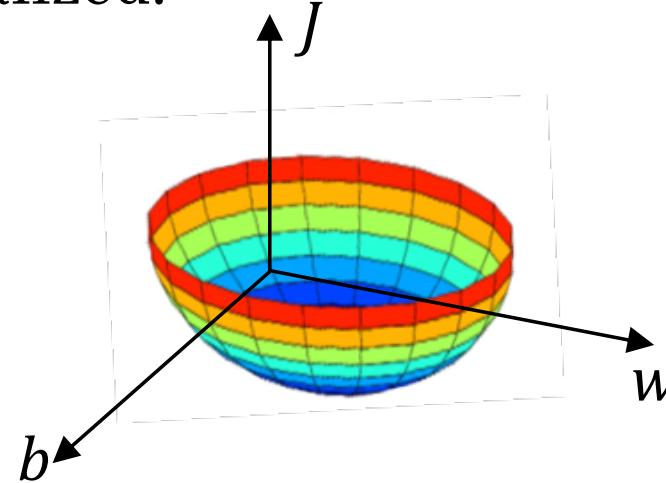
Unnormalized:



$x_1: 0 \dots 1$   
 $x_2: -1 \dots 1$   
 $x_3: 1 \dots 2$

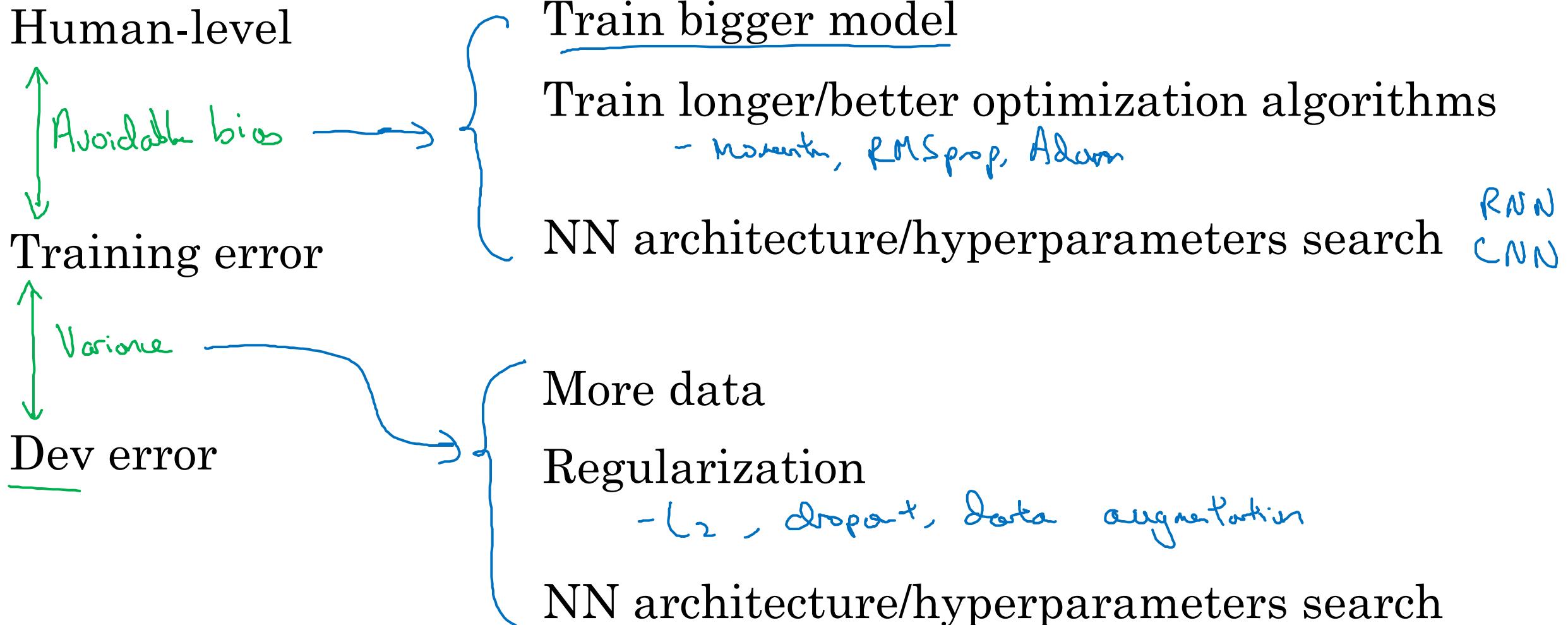
$$J(w, b) = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}^{(i)}, y^{(i)})$$

Normalized:



$w$  Andrew Ng

# Reducing (avoidable) bias and variance



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