

SSA2025 Earthquake Catalog Workshop

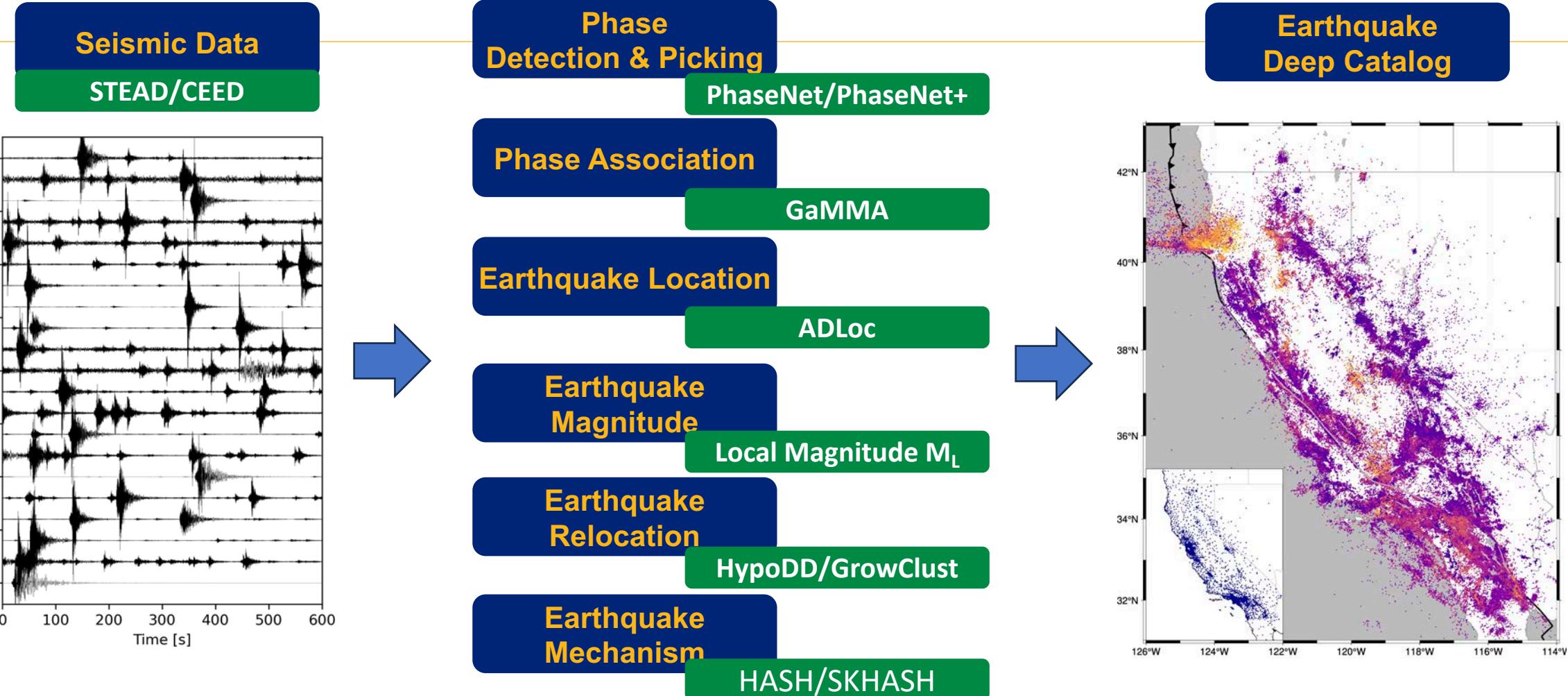
Contributors: Eric Beauch, Gabrielle Tepp, Clara Yoon, Ellen Yu, Weiqiang Zhu

Topic 2: Building Earthquake Catalog using Machine Learning

Main contributors: Clara Yoon, Weiqiang Zhu

Notebook example : https://ai4eps.github.io/Earthquake_Catalog_Workshop/notebooks/quakeflow/

Earthquake Deep Catalog

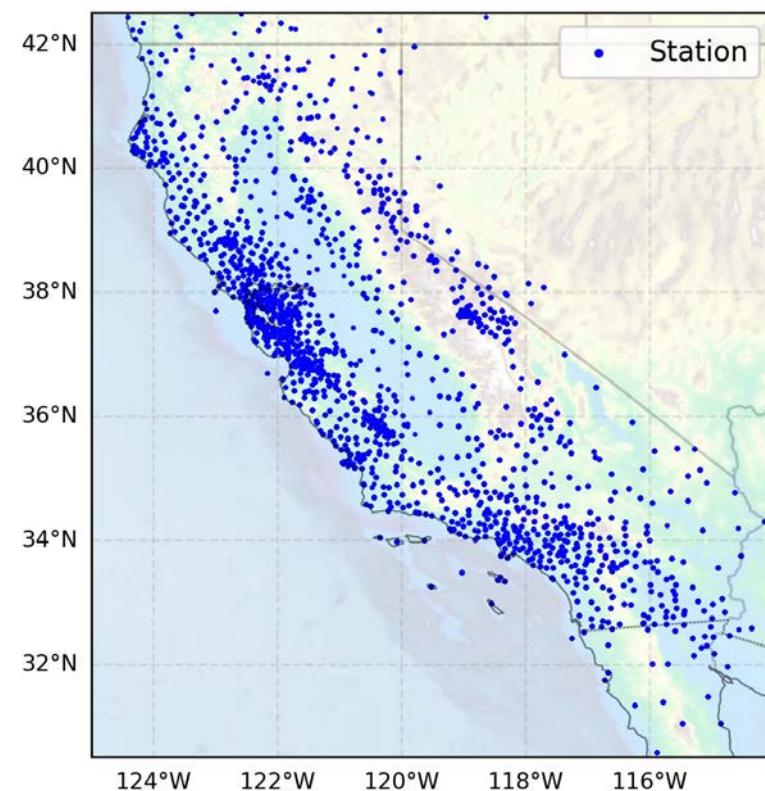


Note: Multiple algorithms exist for each task, with the ones listed here serving as examples.

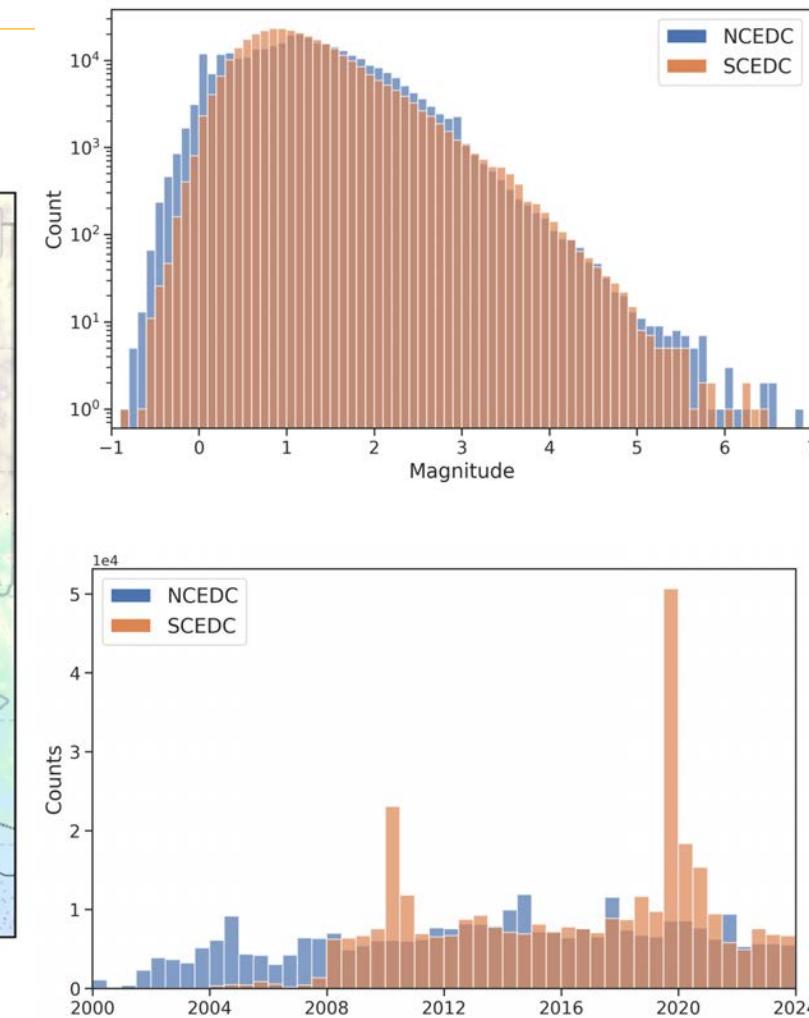
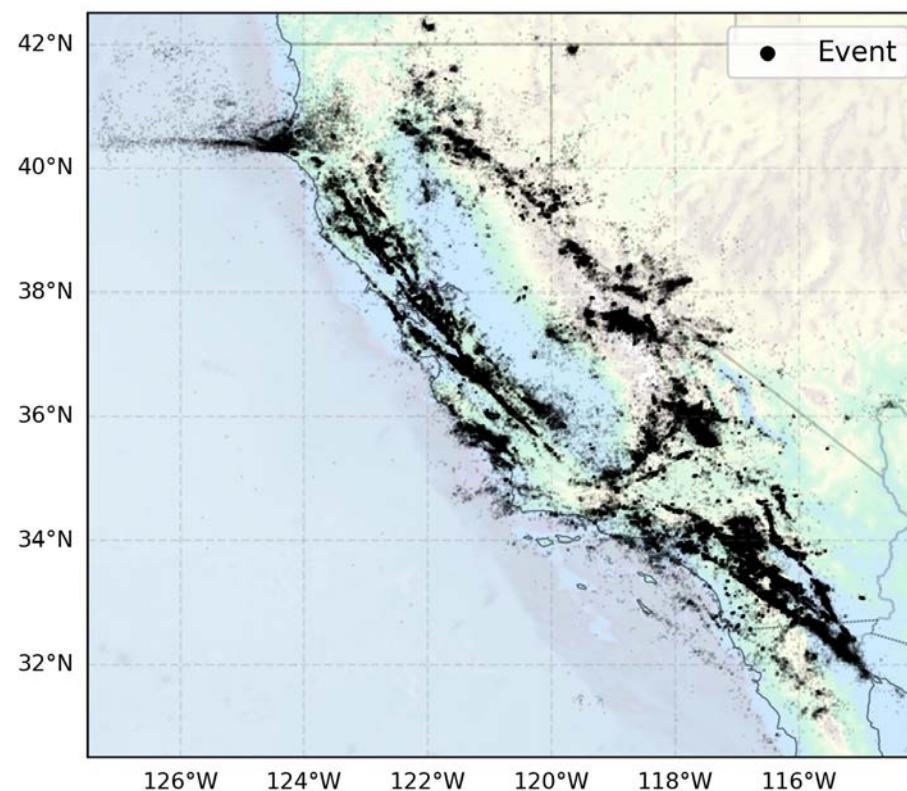
Q0: Seismic datasets for machine learning

CEED: California Earthquake Event Dataset

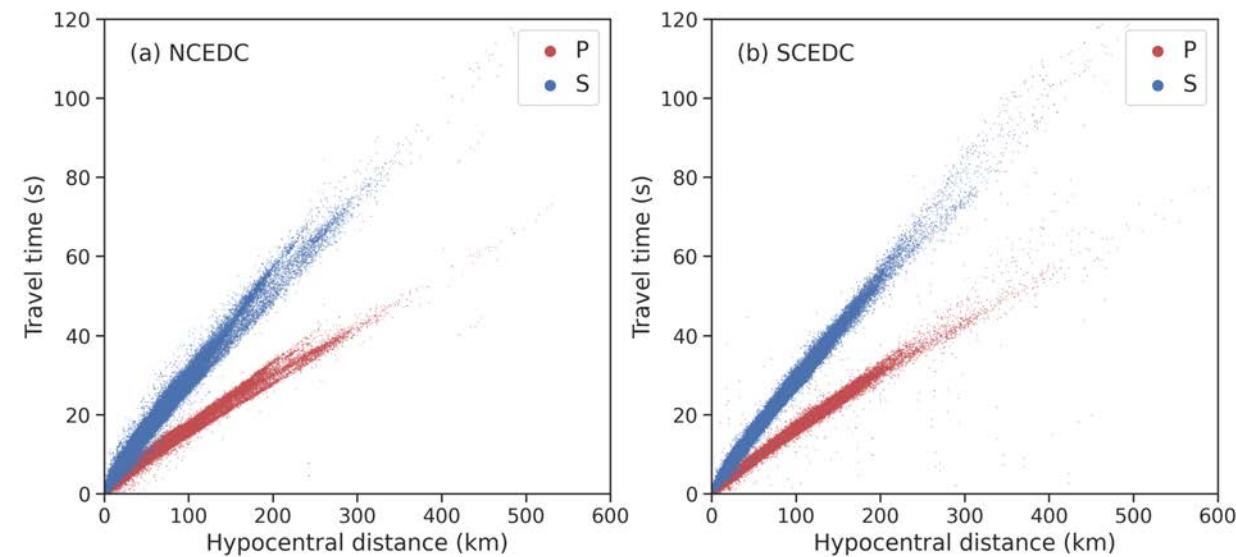
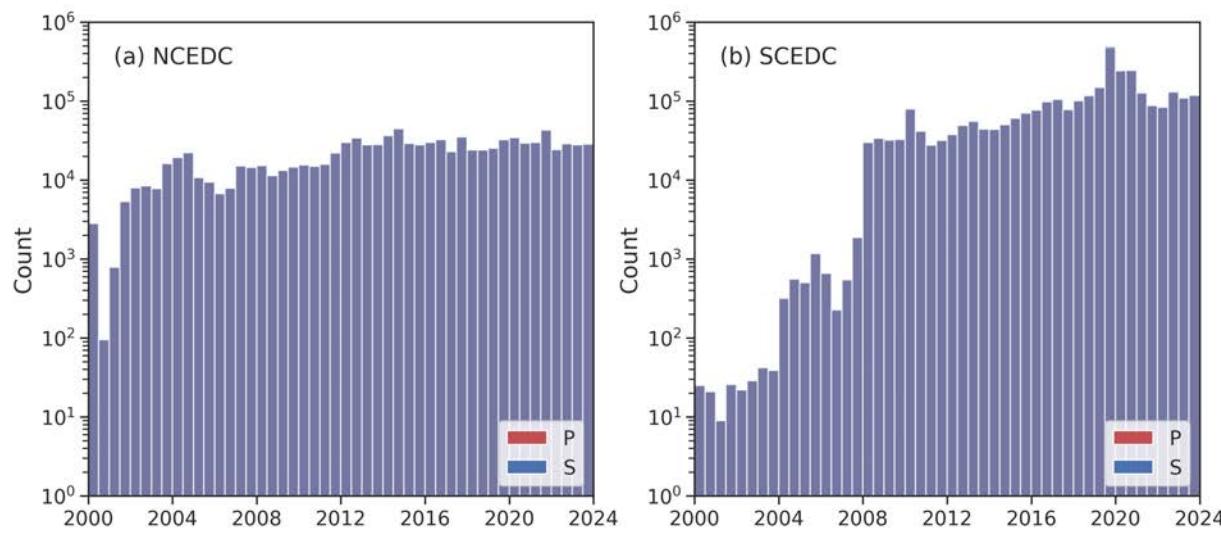
Seismic stations



Earthquake catalog

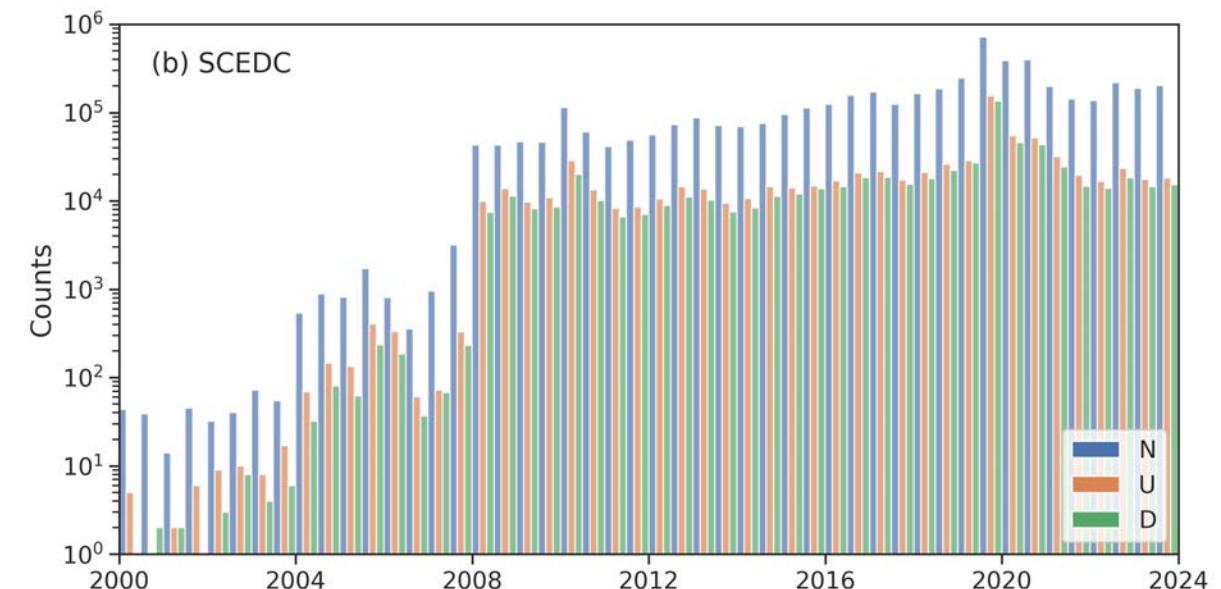
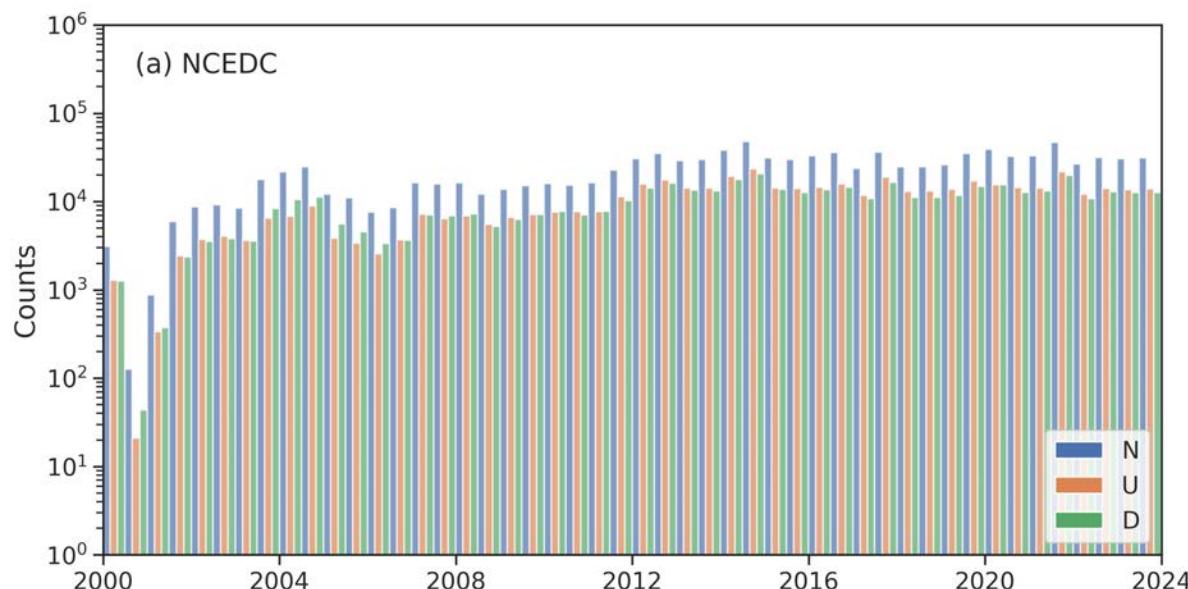


CEED: P&S Phase Picks



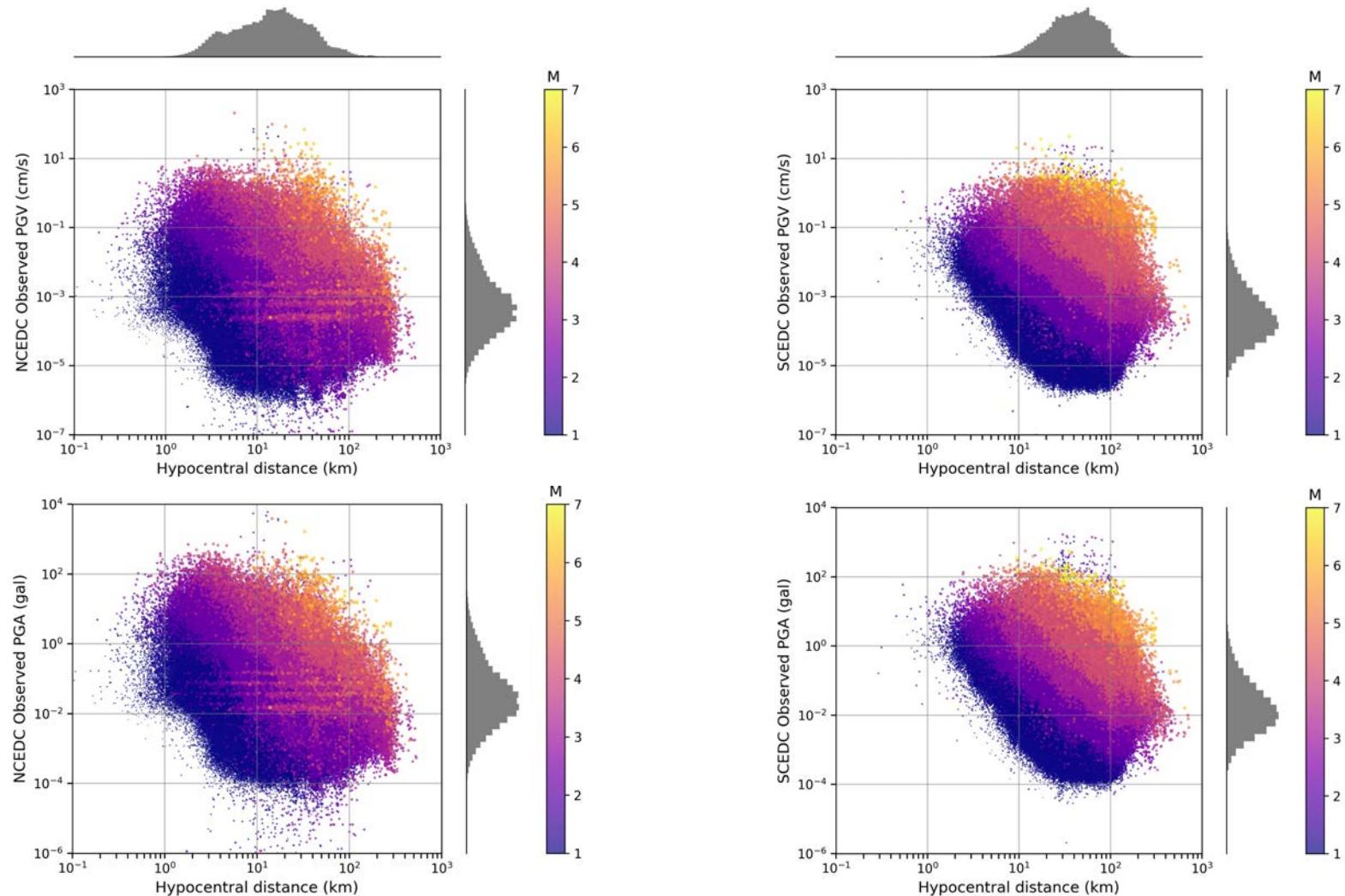
Phase arrival picks: 4.14M (NC: 1.09M + SC: 3.05M)

CEED: First-motion Polarity Picks

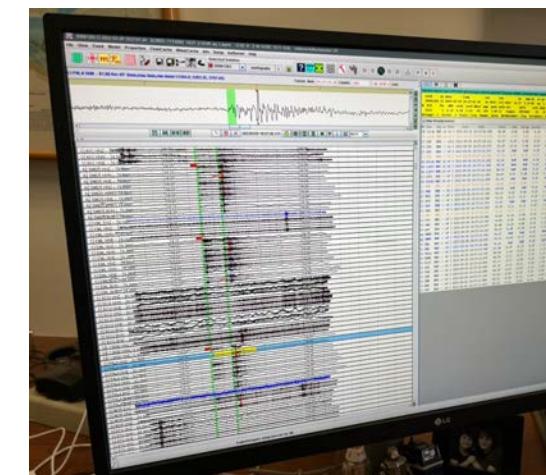
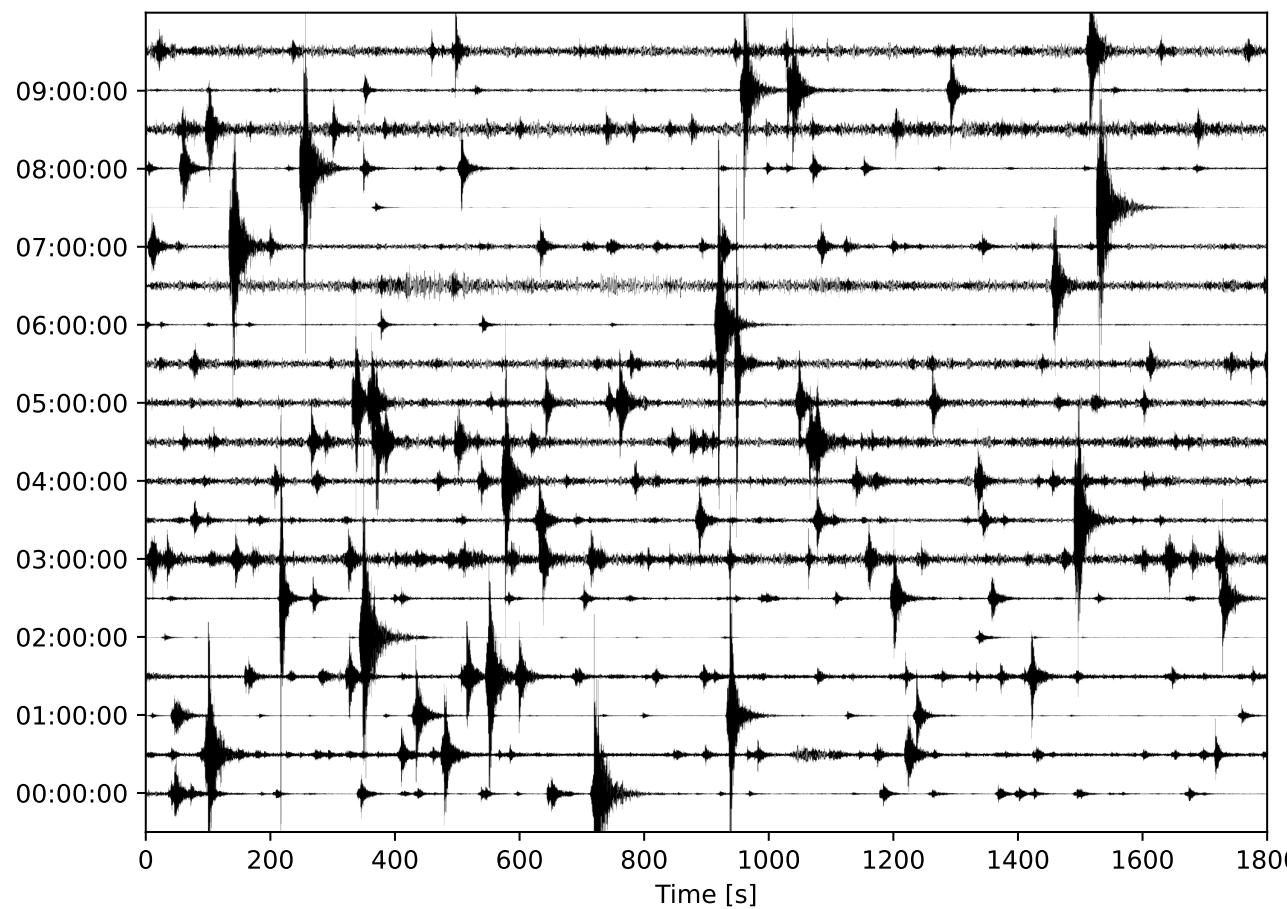


Phase polarity picks: 2.42M (NC: 1.04M + SC: 1.38M)

CEED: Ground Motion Measurements

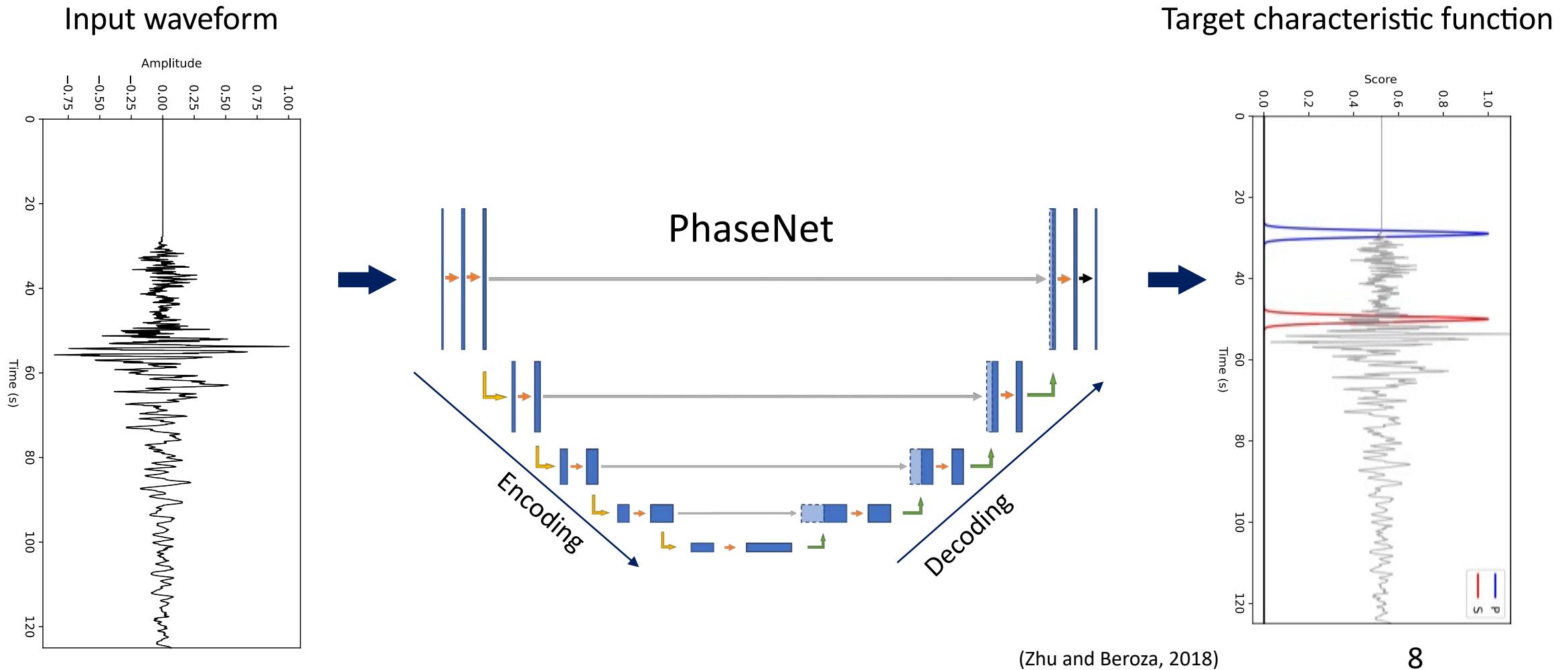


Q1: How to automatically detect earthquakes?



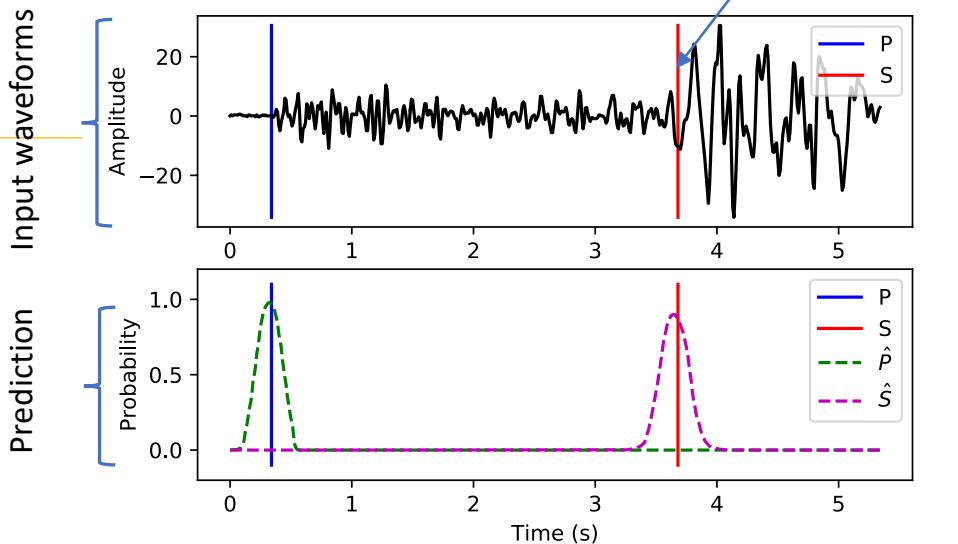
(Photo: Caltech Seismo Lab)

Supervised Learning: Phase Arrival-time Picking

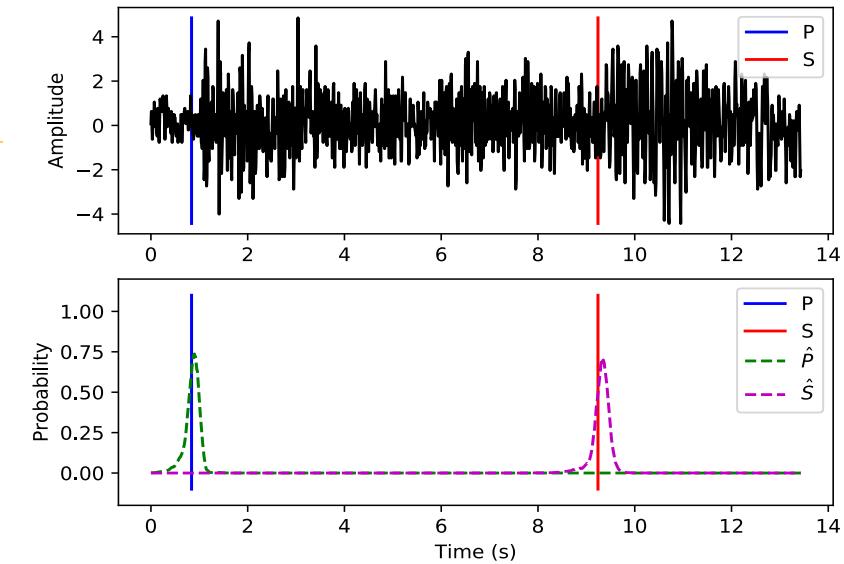


Examples

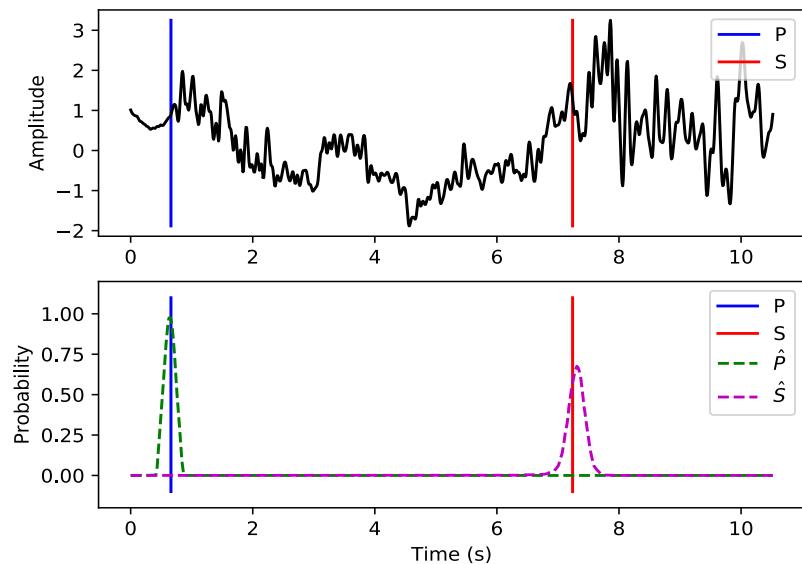
Clear signals



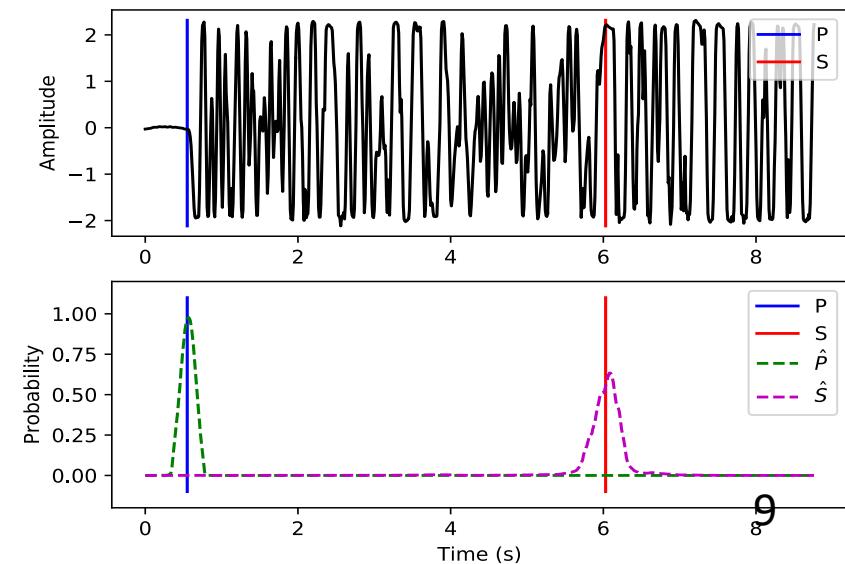
Noisy signals



Noisy signals



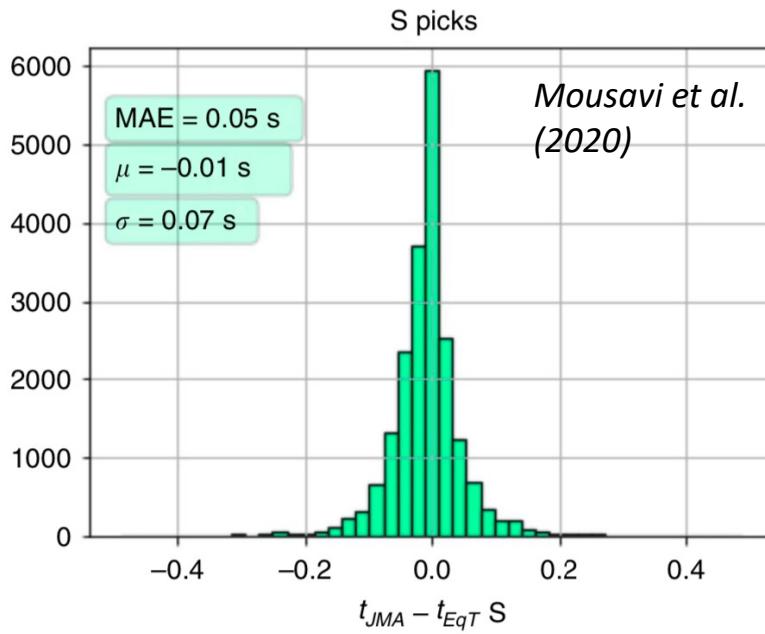
Clipped waveforms



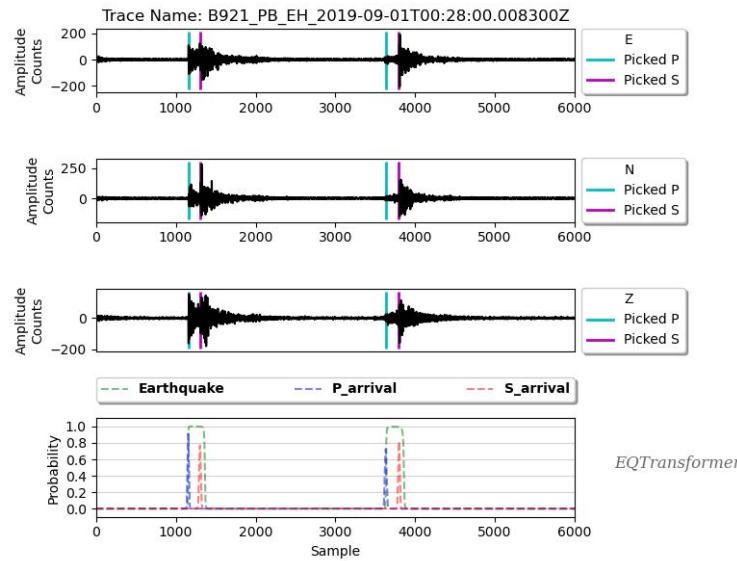
Why use deep learning phase picking methods?

**Automatic processing
with few errors:**

Detect and pick phases
almost as well as humans

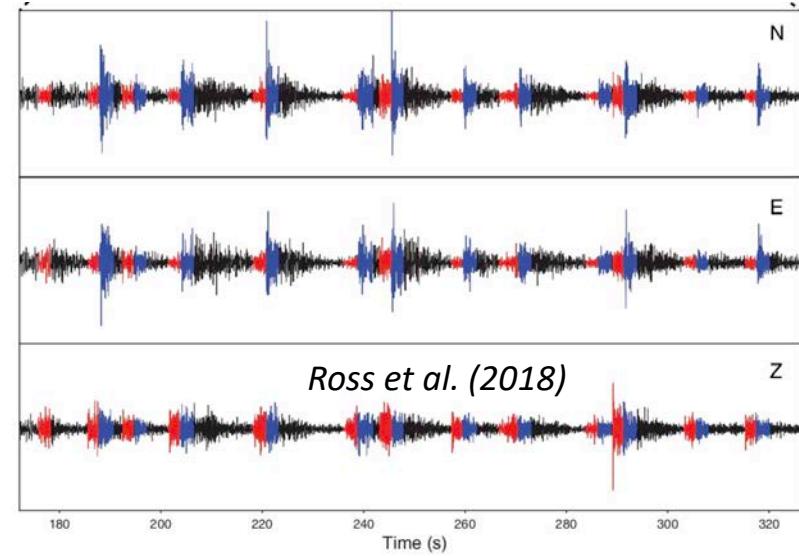


Once trained and tested,
applying deep learning
models is fast and easy



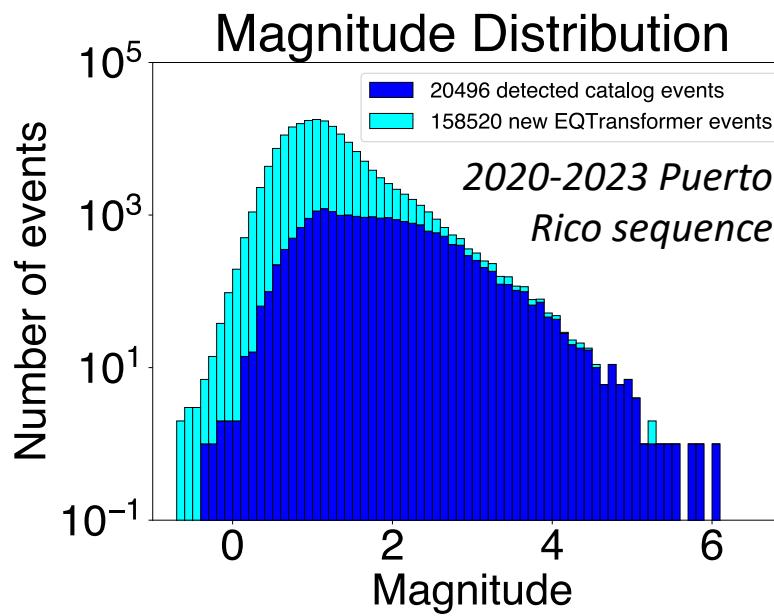
EQTransformer (Mousavi et al., 2020)

**Perform well in active
earthquake sequences:**
when many earthquakes
occur seconds apart

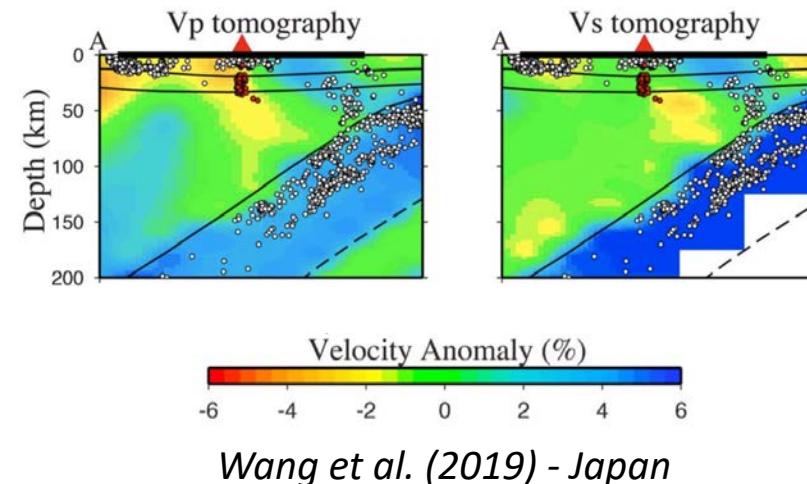


Deep learning phase pickers excel at finding **small** earthquakes, with many scientific benefits

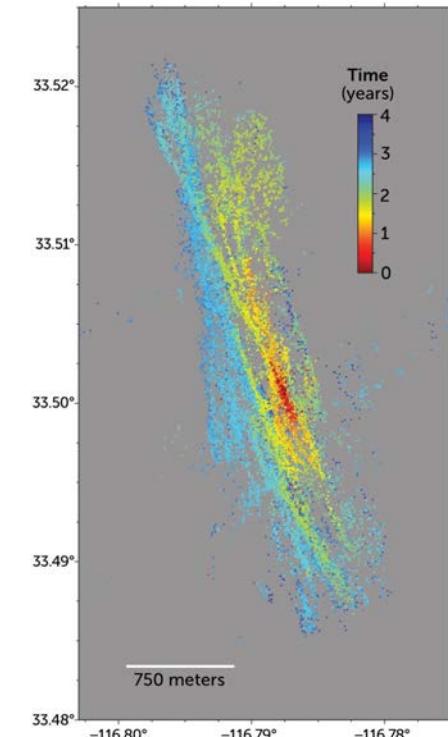
More complete earthquake catalogs:
fault structure, monitoring



More input to infer subsurface conditions:
tomography, velocity models

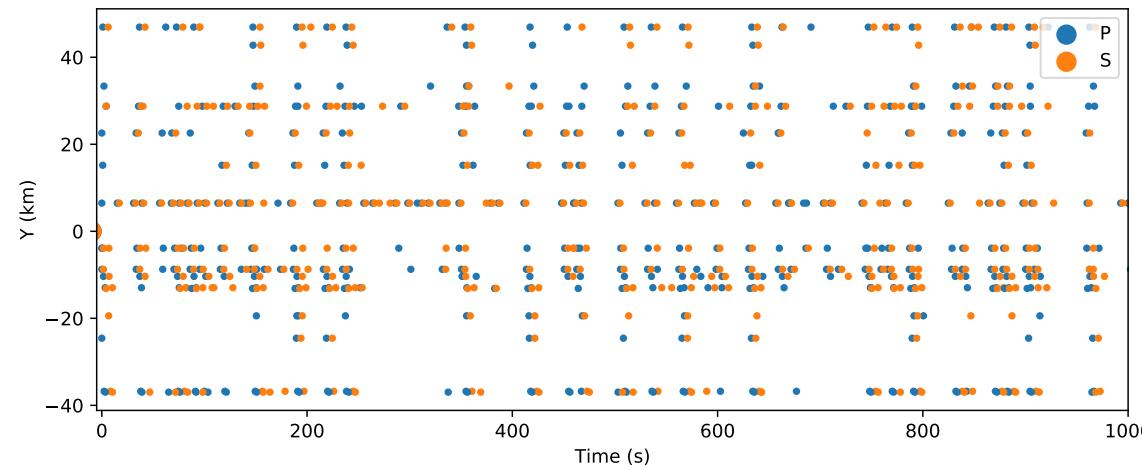


More detail about earthquake processes:
space-time evolution, fluid migration, stress transfer

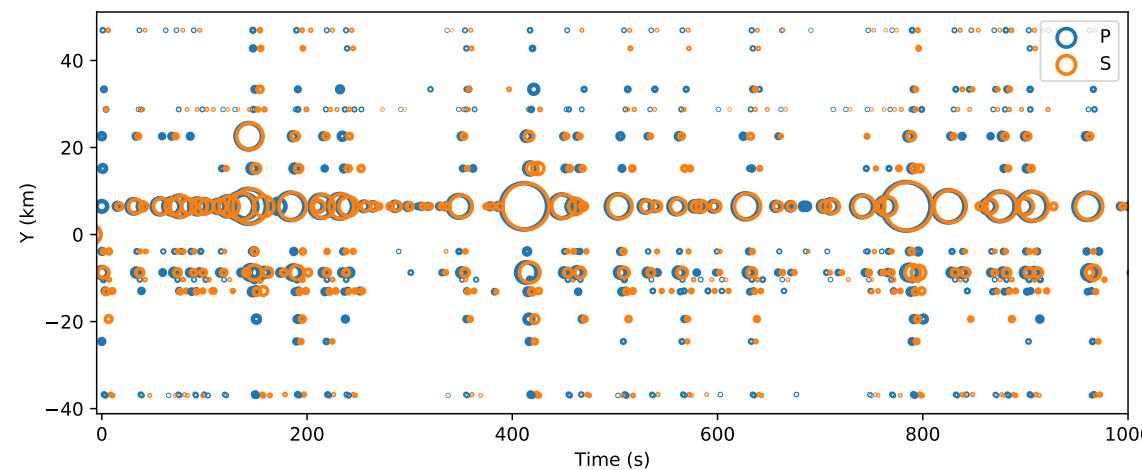


Ross et al. (2020) - California

Q2: How to identify underlying events?



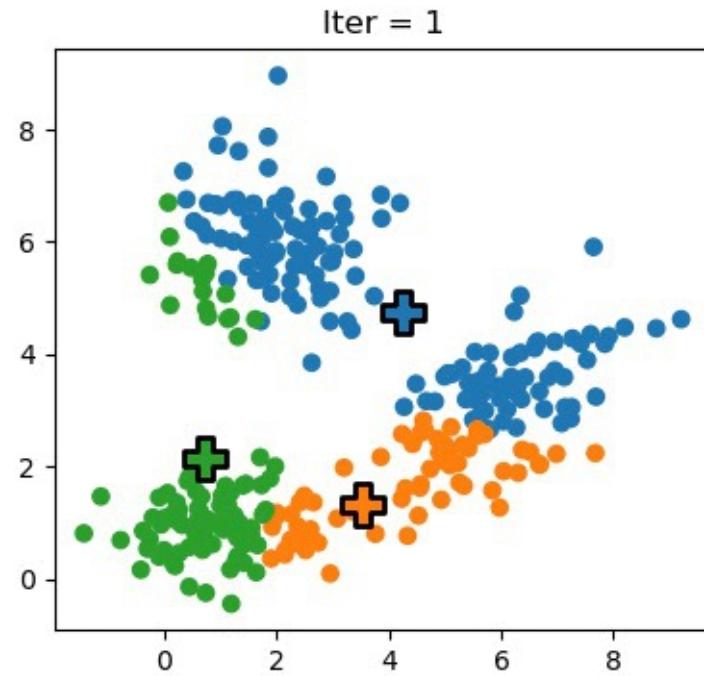
Phase arrival time only



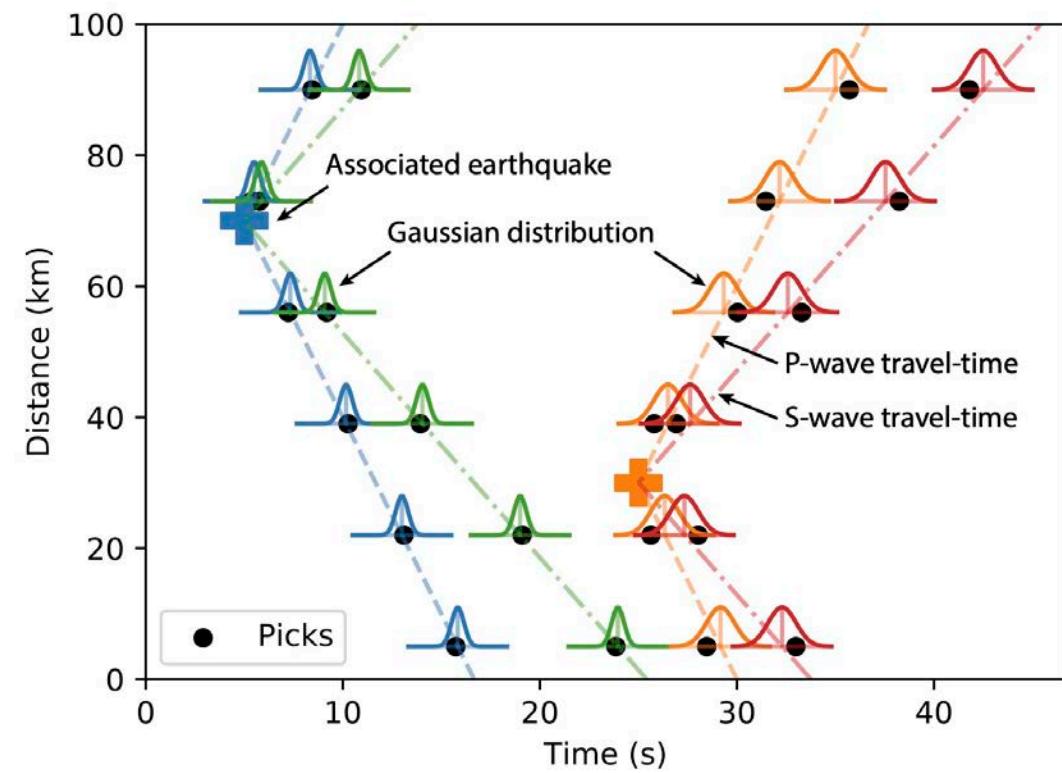
Phase arrival time + amplitude

Unsupervised Learning: Phase Association

K-means clustering

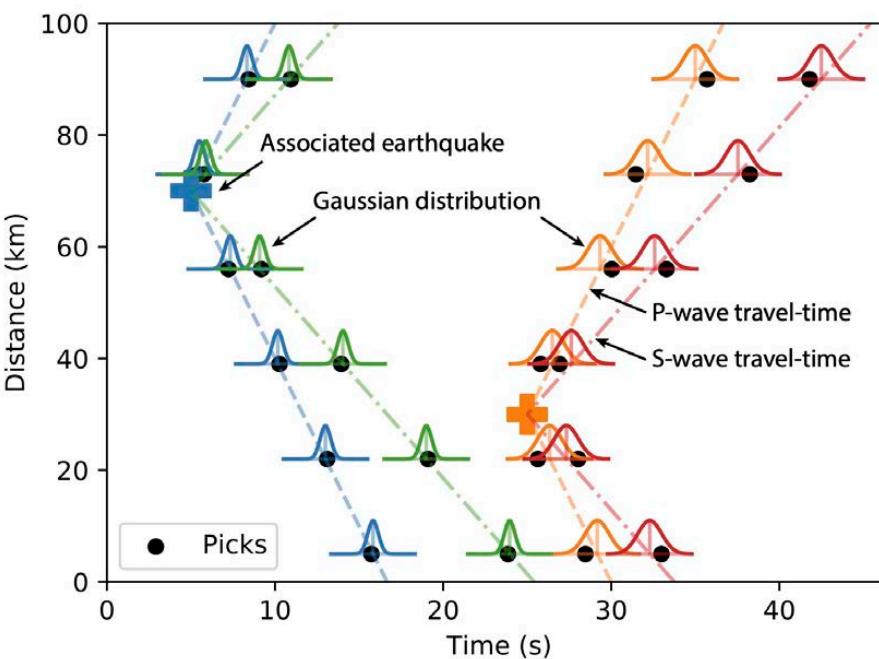


Phase association



GaMMA: Gaussian Mixture Model Association

- Modeling Gaussian distributions based on theoretical travel-time and amplitude
- Solving clustering using the Expectation-Maximization algorithm



- E-step (phase space): Assign picks to each earthquake

$$\gamma_{ik} = \frac{\phi_k \mathcal{N}(\mathbf{x}_i | \mu_k, \Sigma_k)}{\sum_{k=1}^K \phi_k \mathcal{N}(\mathbf{x}_i | \mu_k, \Sigma_k)}$$

- M-step (earthquake space): Update earthquake parameters

$$\phi_k = \sum_{i=1}^N \frac{\gamma_{ik}}{N}$$

$$\underset{(x_k, y_k, z_k, t_k)}{\text{minimize}} \quad l(x_k, y_k, z_k, t_k) = \sum_{i=1}^N \frac{\gamma_{ik}}{2} \mathcal{L}(t_i, \hat{t}_{ik}(x_k, y_k, z_k, t_k))$$

$$m_k = \frac{\sum_{i=1}^N \gamma_{ik} \mathcal{F}'_a(a_i, d_{ik})}{\sum_{i=1}^N \gamma_{ik}}$$

$$\mu_k = \begin{bmatrix} \hat{t}_{ik} \\ \hat{a}_{ik} \end{bmatrix} = \begin{bmatrix} \mathcal{F}_t(x_k, y_k, z_k, t_k) \\ \mathcal{F}_a(m_k, d_{ik}) \end{bmatrix}$$

$$\Sigma_k = \frac{\sum_{i=1}^N \gamma_{ik} (\mathbf{x}_i - \mu_k)(\mathbf{x}_i - \mu_k)^T}{\sum_{i=1}^N \gamma_{ik}}$$

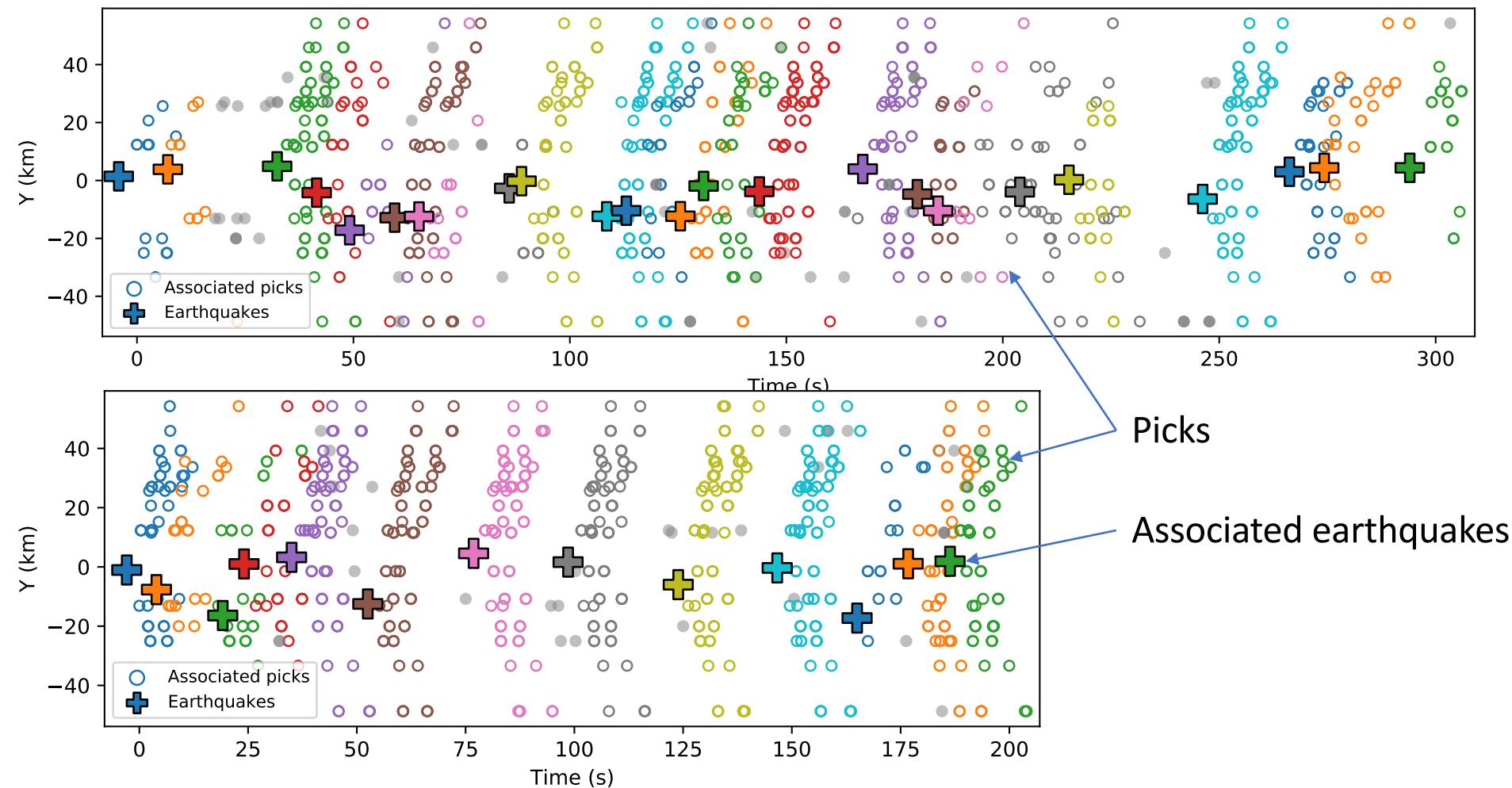
Estimate origin time
and location

Estimate magnitude

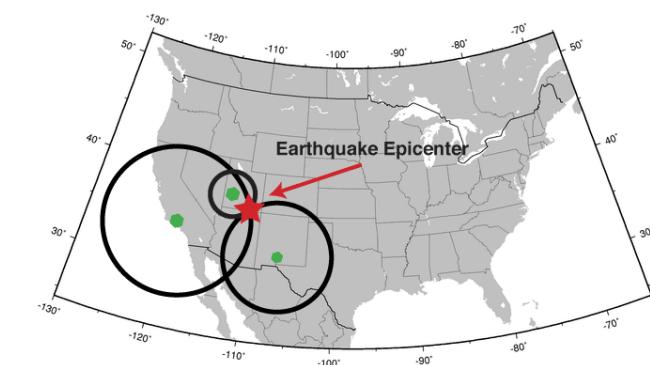
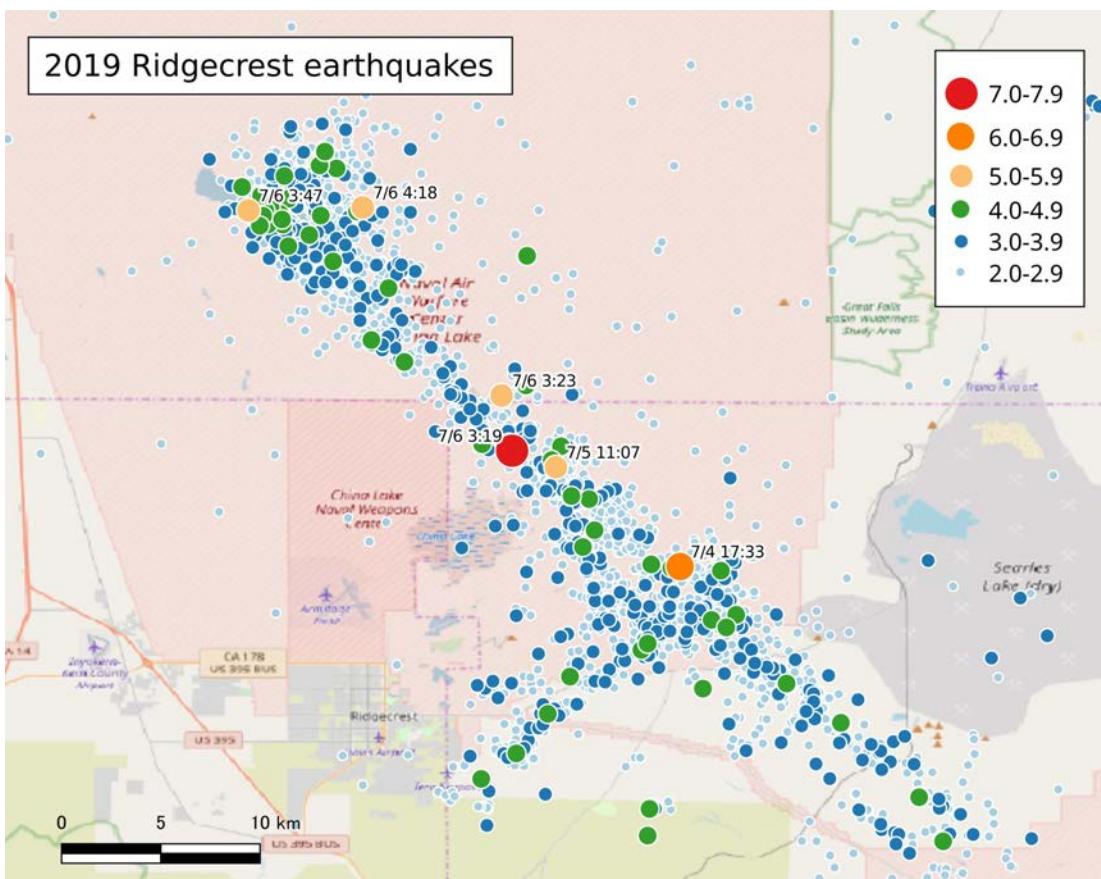
Update theoretical values

Update covariance matrix

Applications



Q3: How determine earthquake locations?



Earthquake Location: Single-Event

Linearized Inversion

Examples:

- Geiger's method (1912)
- HYPOINVERSE
 - o Klein et al. (2002)
 - o Used in regional network monitoring
- VELEST
 - o Kissling et al. (1994)
 - o Can also solve for 1D velocity model, station corrections



Efficient, runs fast



Location might be incorrect, if stuck in local minimum

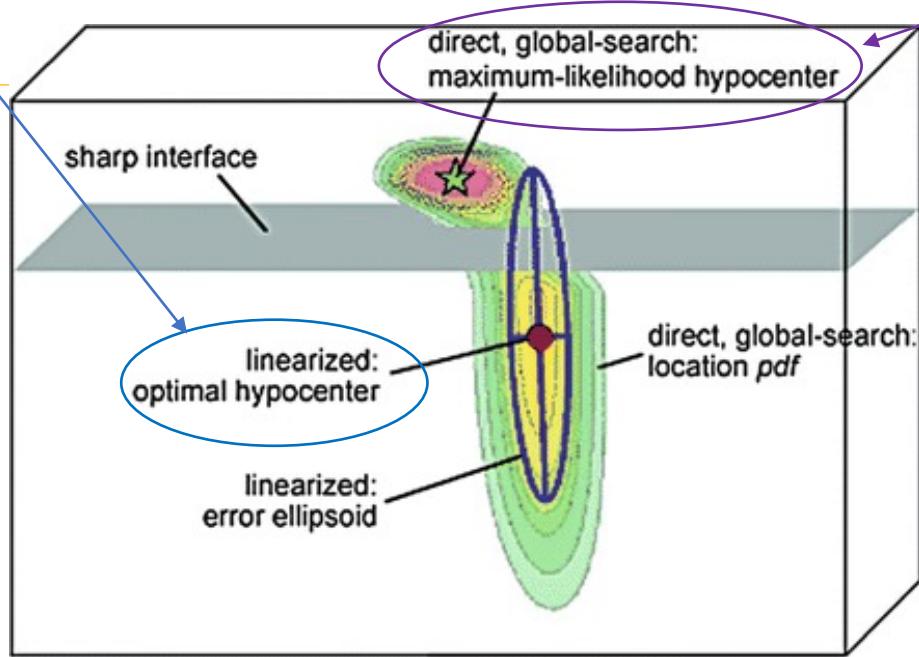


Figure: Lomax et al. (2009)

Earthquake location is a nonlinear inversion problem:
want *minimum* residual
(best fit to arrival-time data)

Direct (Global) Search

Examples:

- 3D Grid Search
- NonLinLoc
 - o Lomax et al. (2000, 2009)
- HypoSVI
 - o Smith et al. (2021)
 - o Stochastic direct search



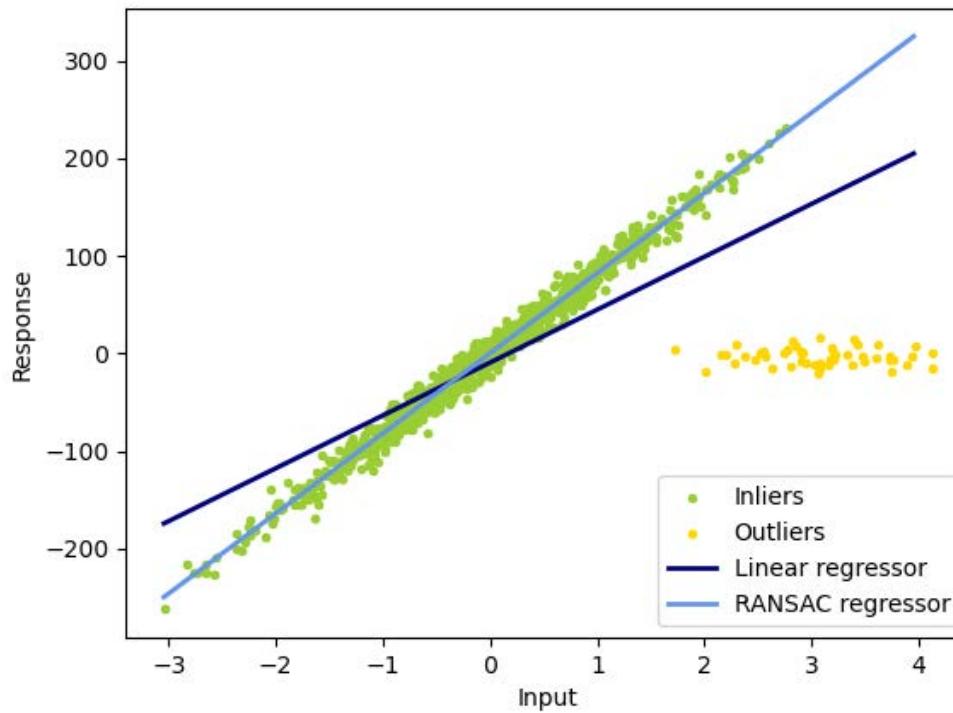
Compute intensive, slow runtime



Location can find global minimum & uncertainty distribution

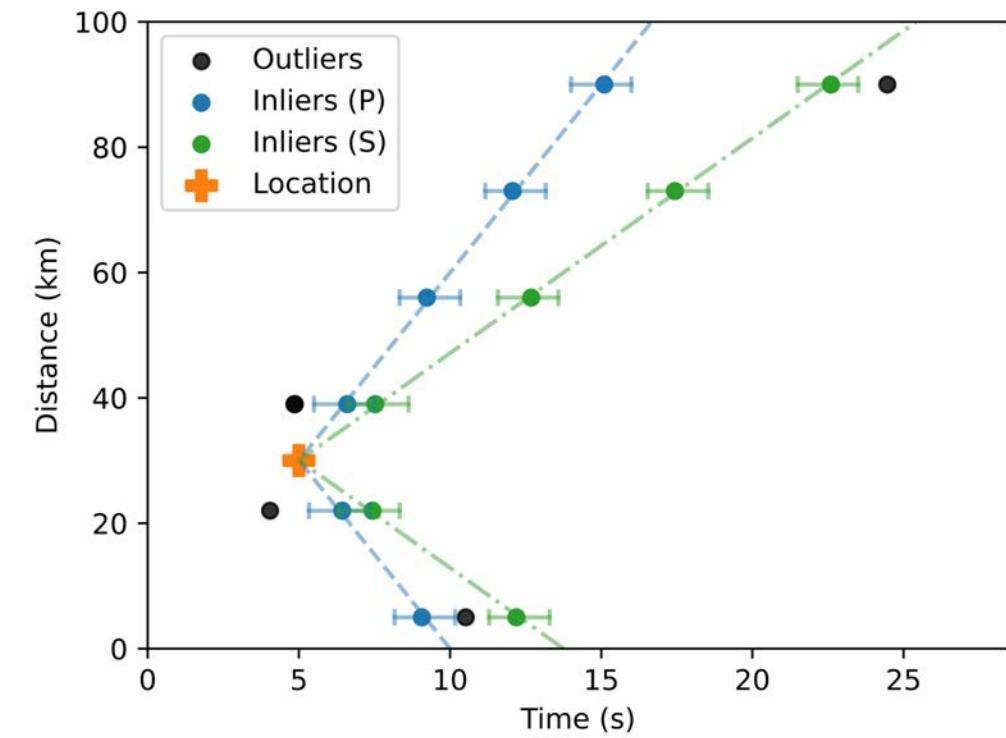
RANSAC: Robust Earthquake Location to Outliers

Robust linear regression



(<https://scikit-learn.org>)

Robust earthquake location



(Zhu et al. 2025)

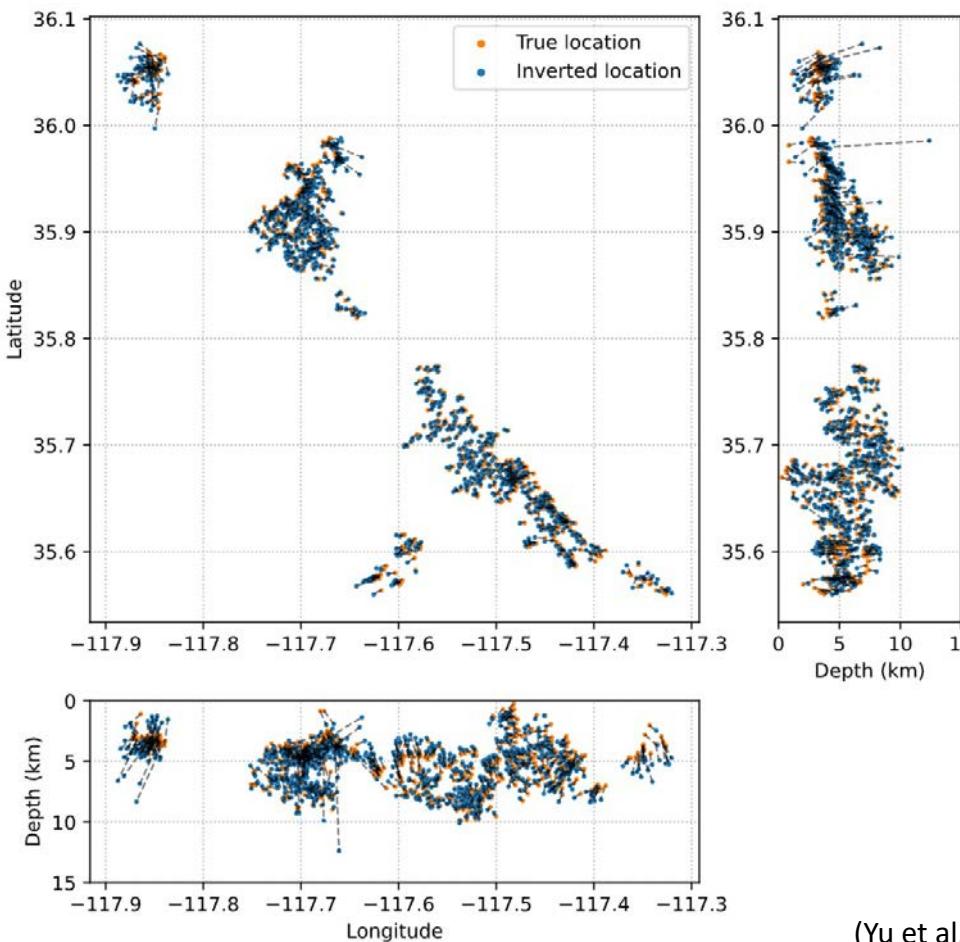
RANSAC (RANdom SAmple Consensus) fits a model from random subsets of inliers from the complete data set.

Earthquake Location + RANSAC

1. Randomly sample a subset of phase picks S
2. Evaluate subset quality (e.g., P&S pick counts)
3. Locate earthquake using the subset S
4. Apply the model to the full dataset G ; Compute evaluation metrics (e.g., inliers and residuals)
5. Evaluate model quality; Update the best model if improved;
6. Repeat for K iterations, or until stopping criteria met.
7. Use the best inlier subset to determine the final earthquake location

Benchmarking on synthetic datasets

Stanford Earthquake Location Benchmarks



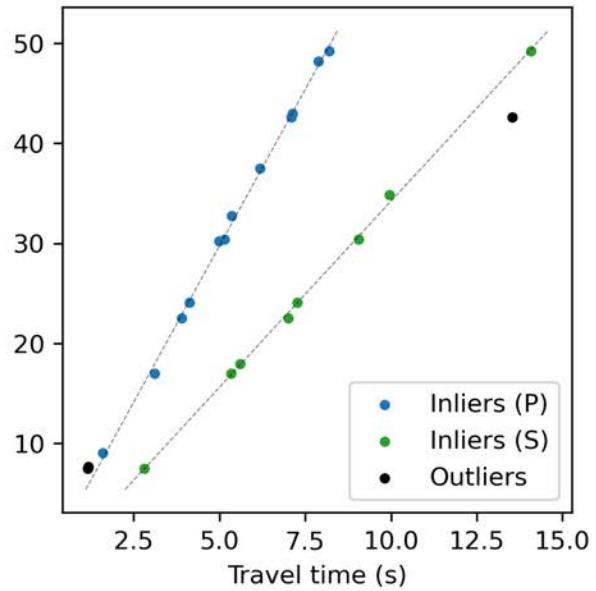
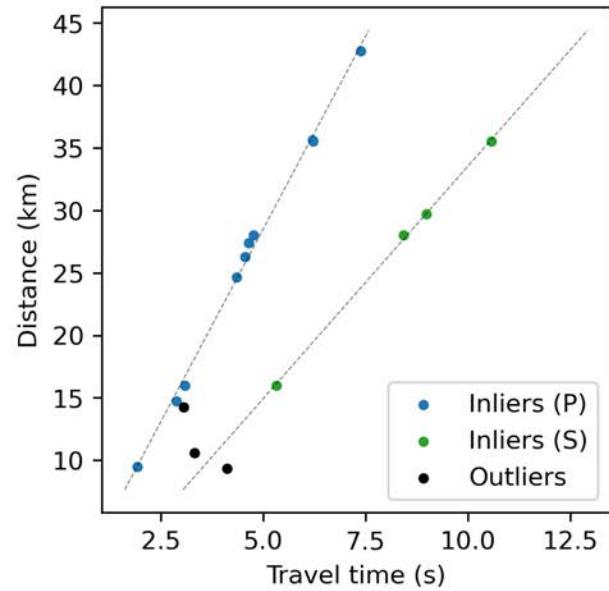
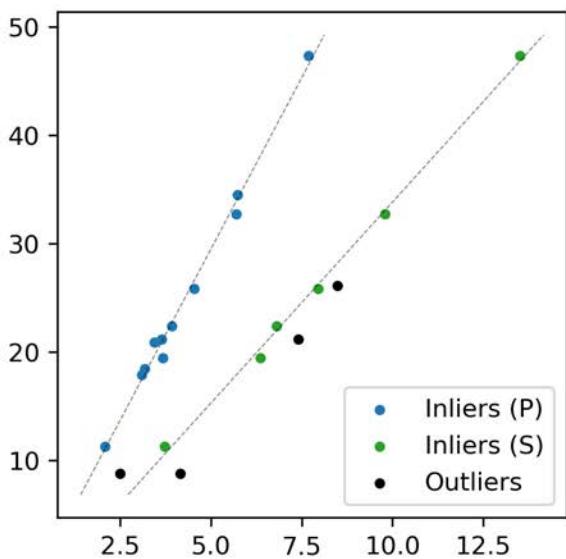
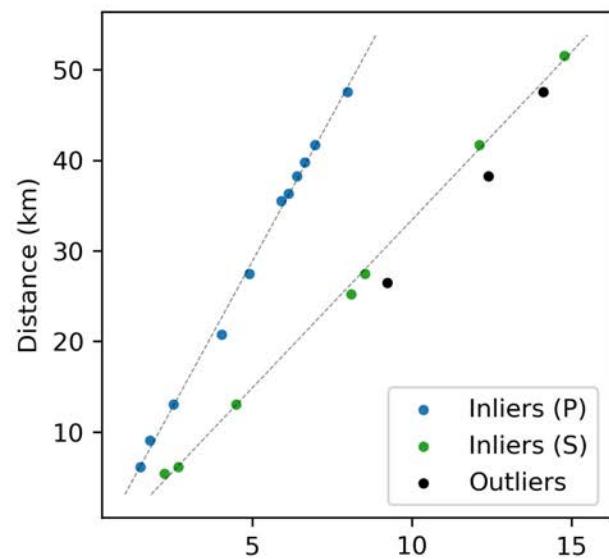
(Yu et al. 2024)

Method	Mean Accuracy Error (km)		Chamfer Distance
	Horizontal	Depth	
HypoInverse	0.824	1.118	1.617
VELEST	0.696	0.559	1.170
NonLinLoc	0.953	0.969	1.626
ADLoc	1.132	1.257	1.802
ADLoc+SST	0.680	0.539	1.080
ADLoc+SST+RANSAC (1.0s)	0.630	0.498	1.035
ADLoc+SST+RANSAC (0.2s)	0.456	0.450	0.915

The dataset, comprising 19,994 phase picks, includes:
1% P-phase; 4% S-phase outliers.

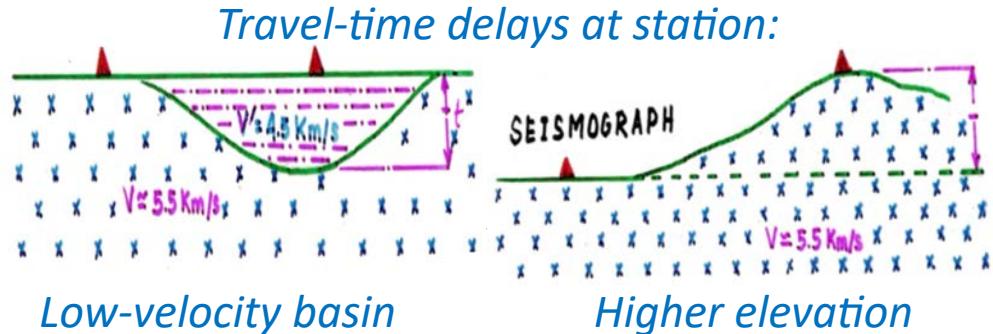
ADLoc, using a 0.2 s threshold, identified:
0.9% (184) P-phase; 2.7% (539) S-phase outliers.

Examples of outliers



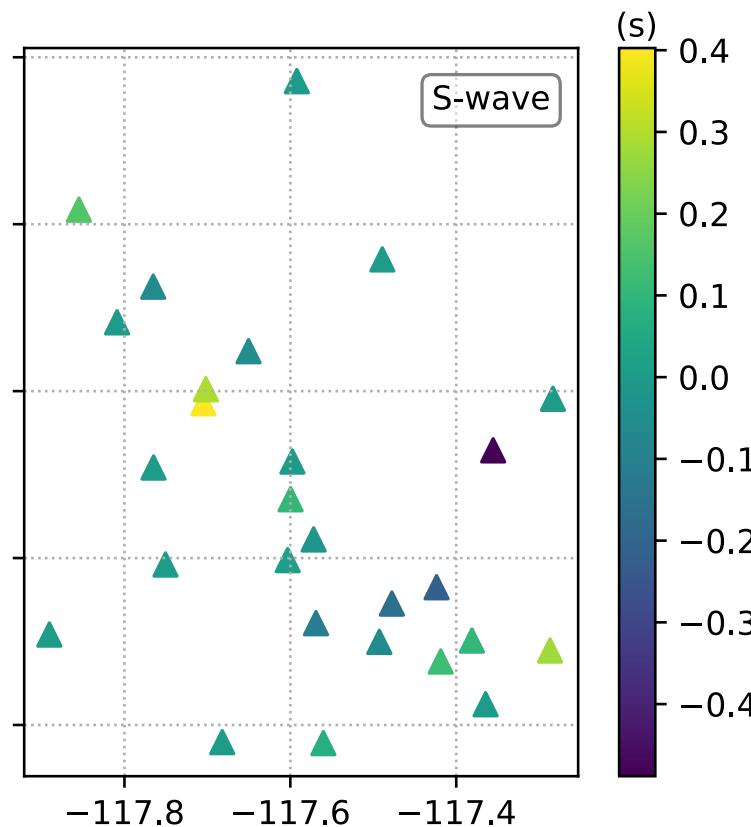
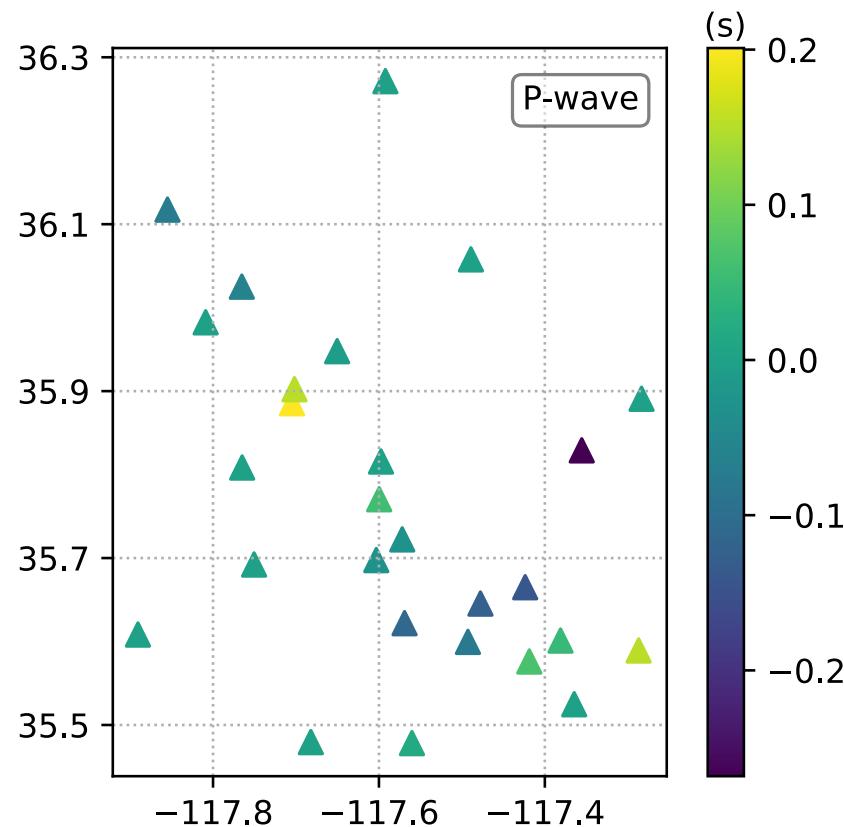
Station correction terms

Station corrections:



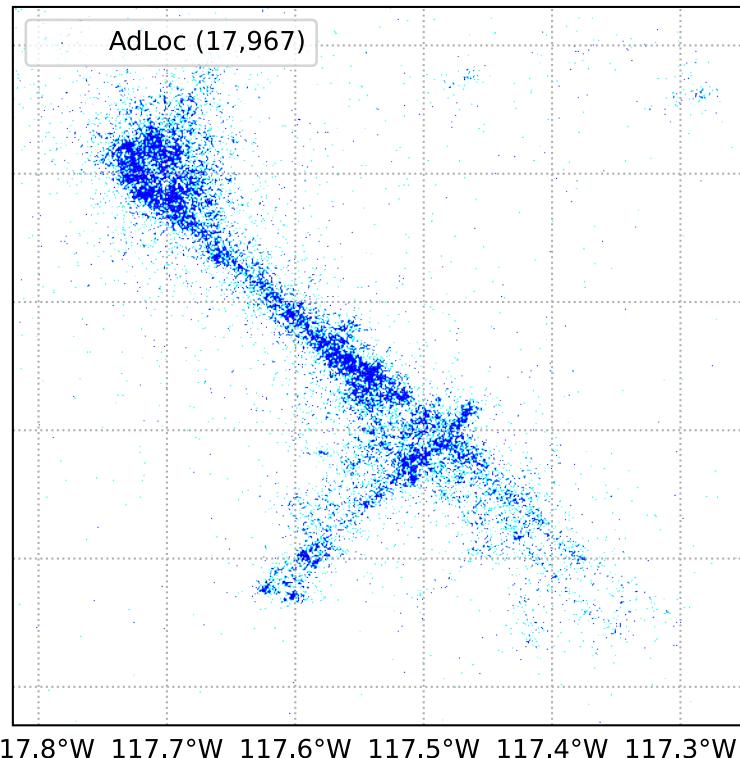
Low-velocity basin

Higher elevation

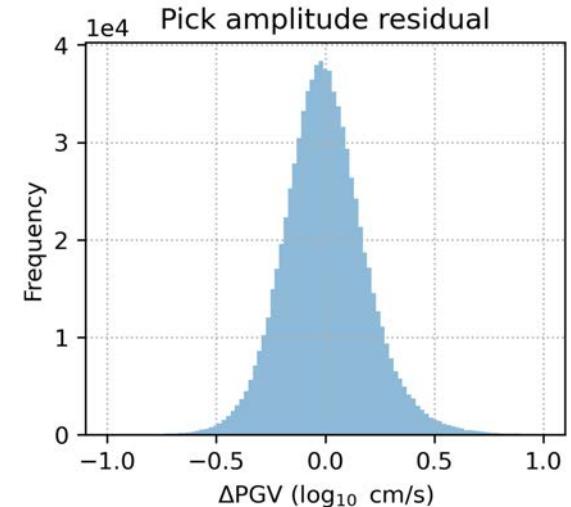
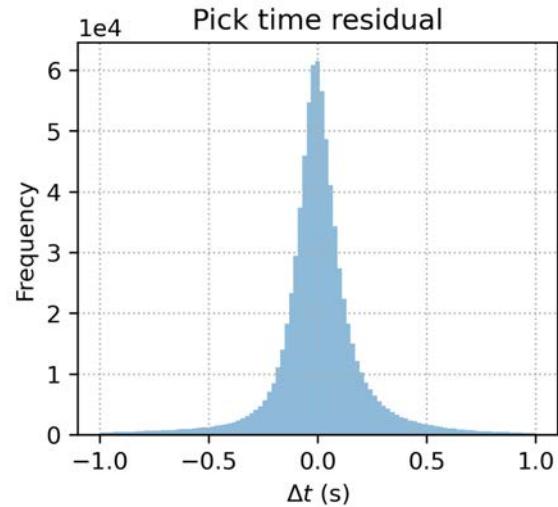


Including amplitudes for outlier detection

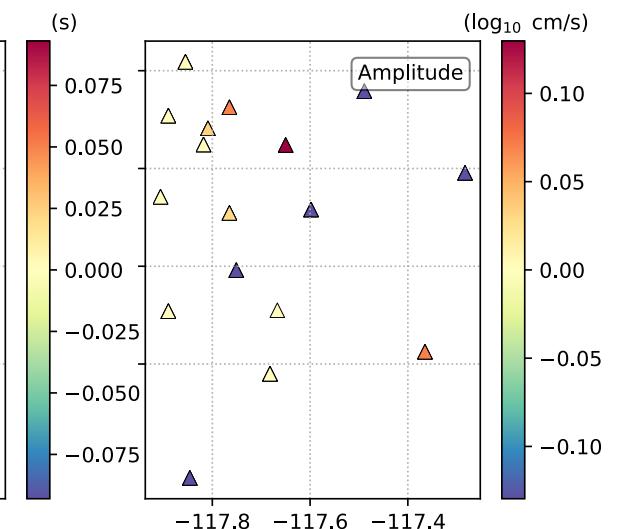
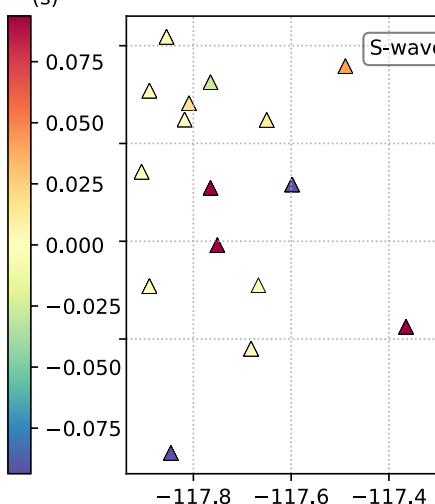
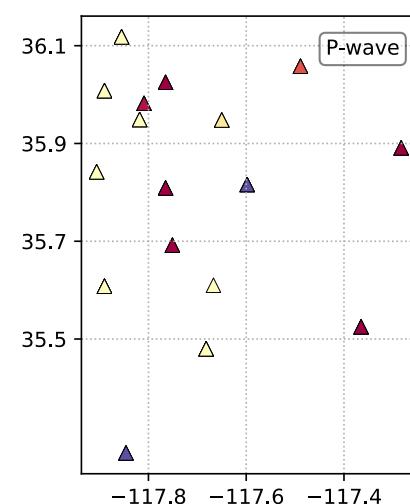
Application to the 2019 Ridgecrest earthquake



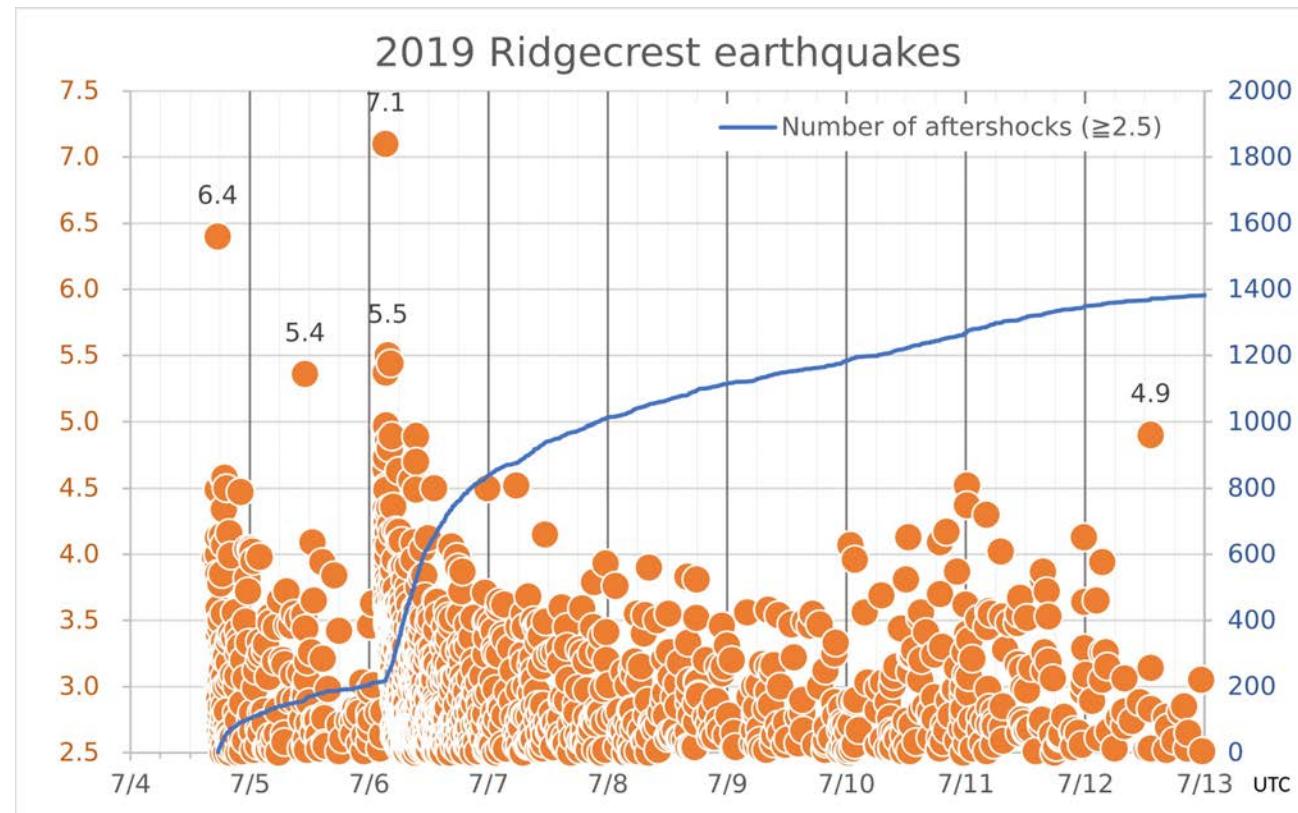
Residuals:



Station correction terms:



Q4: How to determine earthquake magnitudes?



Local Magnitude (M_L)

Adapted from Richter (1958): Elementary Seismology

$$M_L = \log(A) - \log A_0(r) + dM_L,$$

A: peak amplitude (mm)
on (horizontal) Wood-
Anderson seismogram

**Attenuation
correction:** depend on
event-station distance
 r ; varies by region

dM_L : station correction
(different for each
station; default value 0)

Bulletin of the Seismological Society of America

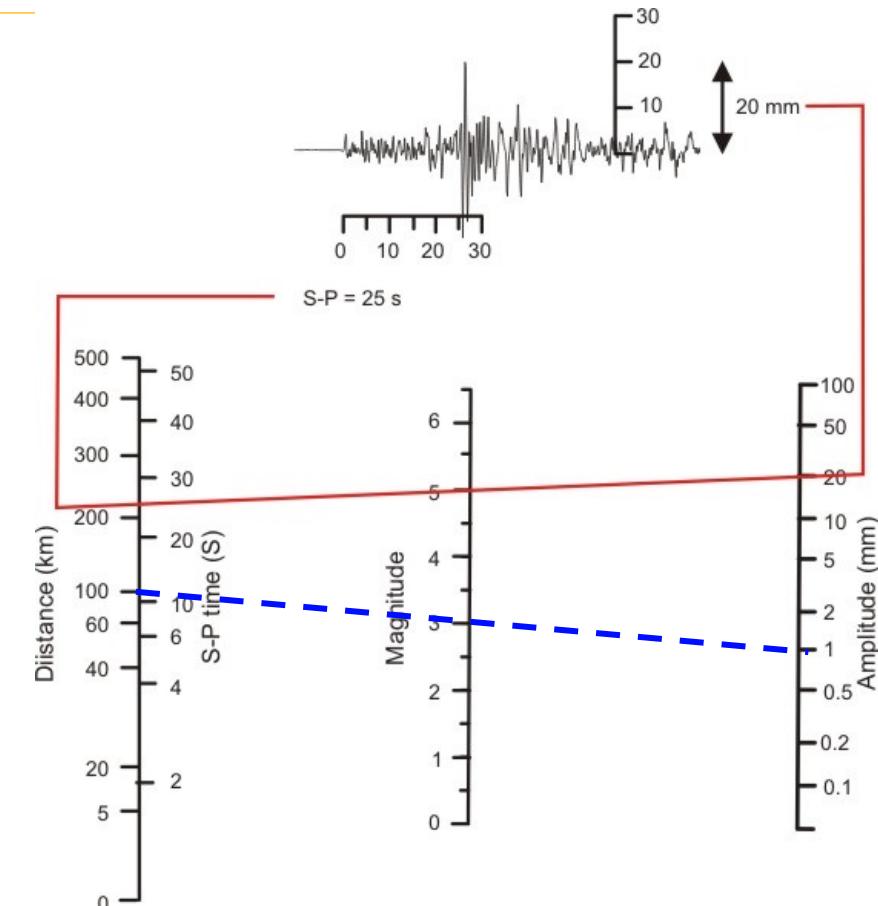
VOL. 25

JANUARY, 1935

No. 1

AN INSTRUMENTAL EARTHQUAKE MAGNITUDE SCALE*

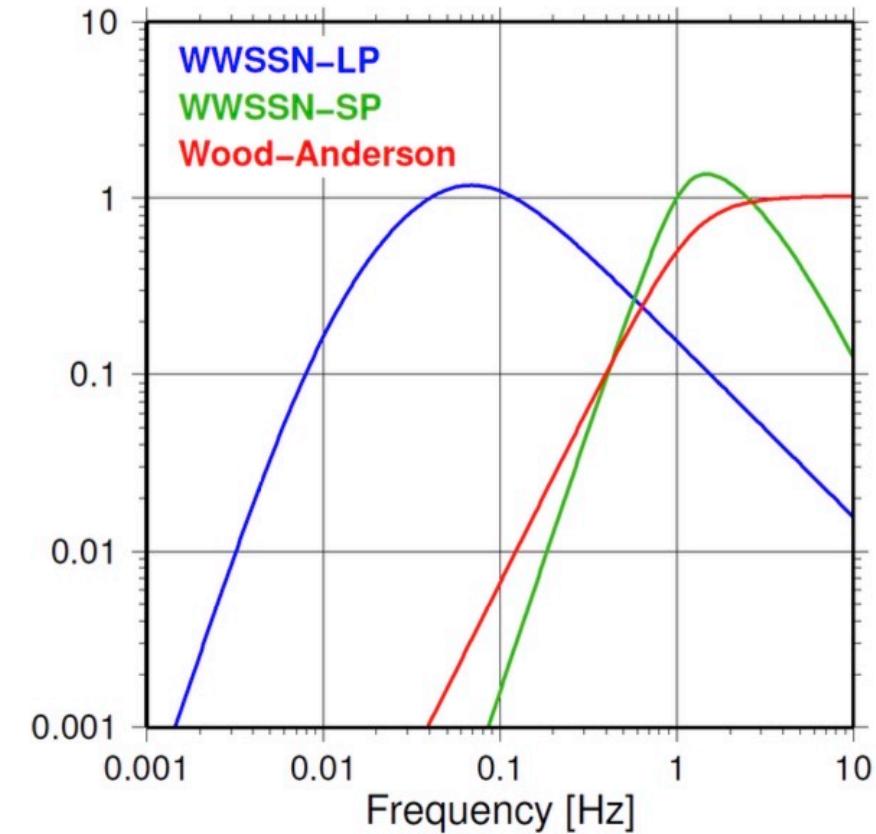
By CHARLES F. RICHTER



Richter (1935): Southern California local earthquake with amplitude=1 mm at station $r=100$ km away defined as $M_L=3$

Why Local Magnitude (M_L) for deep-learning enhanced earthquake catalogs?

- Appropriate for small earthquakes at local distances (Wood-Anderson: freq >1 Hz), newly detected in enhanced catalog
- Quick & easy to compute automatically: get peak amplitude at each station



https://doi.org/10.2312/gfz.nmsop-2_is_3.3

$$M_L = \underbrace{\log(A)}_{\text{peak amplitude}} - \underbrace{\log A_0(r)}_{\text{attenuation (distance) correction}} + \underbrace{dM_L}_{\text{station correction}},$$

$$\begin{aligned} -\log A_0(r) &= 1.11 \log(r) + 0.00189r \\ &\quad + 0.591 + \text{TP}(n) \times T(n, z), \quad (4) \end{aligned}$$

where n is summed from 1 to 6. The $\text{TP}(n)$ coefficients are

$$\begin{aligned} \text{TP}(1) &= +0.056, & \text{TP}(2) &= -0.031, \\ \text{TP}(3) &= -0.053, & \text{TP}(4) &= -0.080, \\ \text{TP}(5) &= -0.028, & \text{TP}(6) &= +0.015, \end{aligned}$$

and z is the scale transformation of r ,

$$z(r) = 1.11366 \times \log(r) - 2.00574, \quad (5)$$

$$T(n, z) = \cos[n \times a \cos(z)]. \quad (6)$$



Uhrhammer et al. (2011), BSSA

$$-\log A_0 = \begin{cases} 2.07 \times \log(R_{hyp}) + 0.0002 \times (R_{hyp} - 100) - 0.72 & R_{hyp} \leq 16 \text{ km} \\ 1.54 \times \log(R_{hyp}) + 0.0002 \times (R_{hyp} - 100) - 0.08 & 16 \text{ km} < R_{hyp} \leq 105 \text{ km}, \\ 0.29 \times \log(R_{hyp}) + 0.0002 \times (R_{hyp} - 100) + 2.45 & R_{hyp} > 105 \text{ km} \end{cases}$$



Kavoura et al. (2020), SRL

r, R_{hyp} : hypocentral distance to station (km)

- M_L equation (distance & station correction) varies with region; often determined empirically with regression or inversion

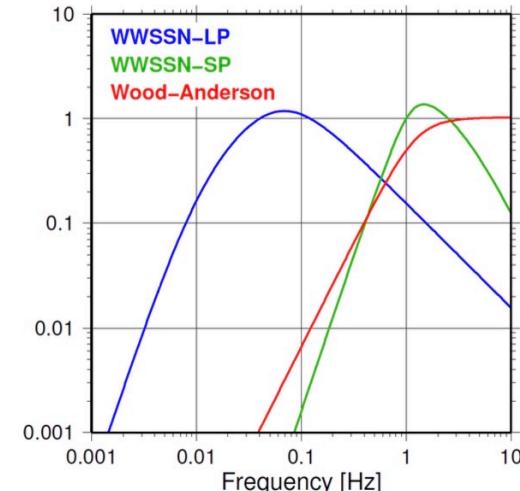
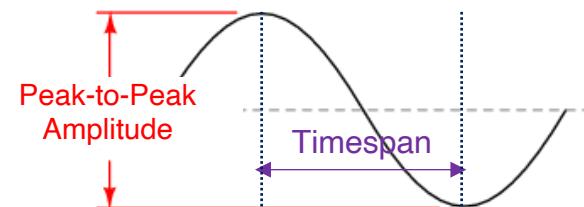
- Preferred: use existing M_L equation from literature for your region; dM_L usually in a supplement table, or text file from seismic network (e.g. SCSN)
- Otherwise: calibrate M_L yourself with observed peak amplitudes (A) and event-station distances (r) by setting up an inversion (e.g. Yoon et al., 2023, BSSA for southwest Puerto Rico)

See talk: Tue 4/15 @ 2:30 PM, Hartog et al.
Local Magnitude Practices in the United States of America
(Network Seismology)

M_L : How to get Wood-Anderson seismogram?

$$M_L = \log(A) - \log A_0(r) + dM_L,$$

A: peak amplitude (mm) on (horizontal)
Wood-Anderson seismogram



- Get StationXML file for each station
 - ObsPy (inside loop over stations):

```
inv = client.get_stations(network=net, station=sta, starttime=start_time,
                           endtime=end_time, level='response', filename=out_stationxml_file, format='xml')
```

 - https://docs.obspy.org/packages/autogen/obspy.clients.fdsn.Client.get_stations.html
- Cut event time window, get **peak-to-peak amplitude** & **timespan**, then correct for Wood-Anderson instrument response.
 - ObsPy (inside loop over stations):

```
A_sta_WA = estimate_wood_anderson_amplitude_using_response(inv, A_sta_pkpk, timesp_sta_pkpk)
```

 - https://docs.obspy.org/packages/autogen/obspy.signal.invsim.estimate_wood_anderson_amplitude_using_response.html

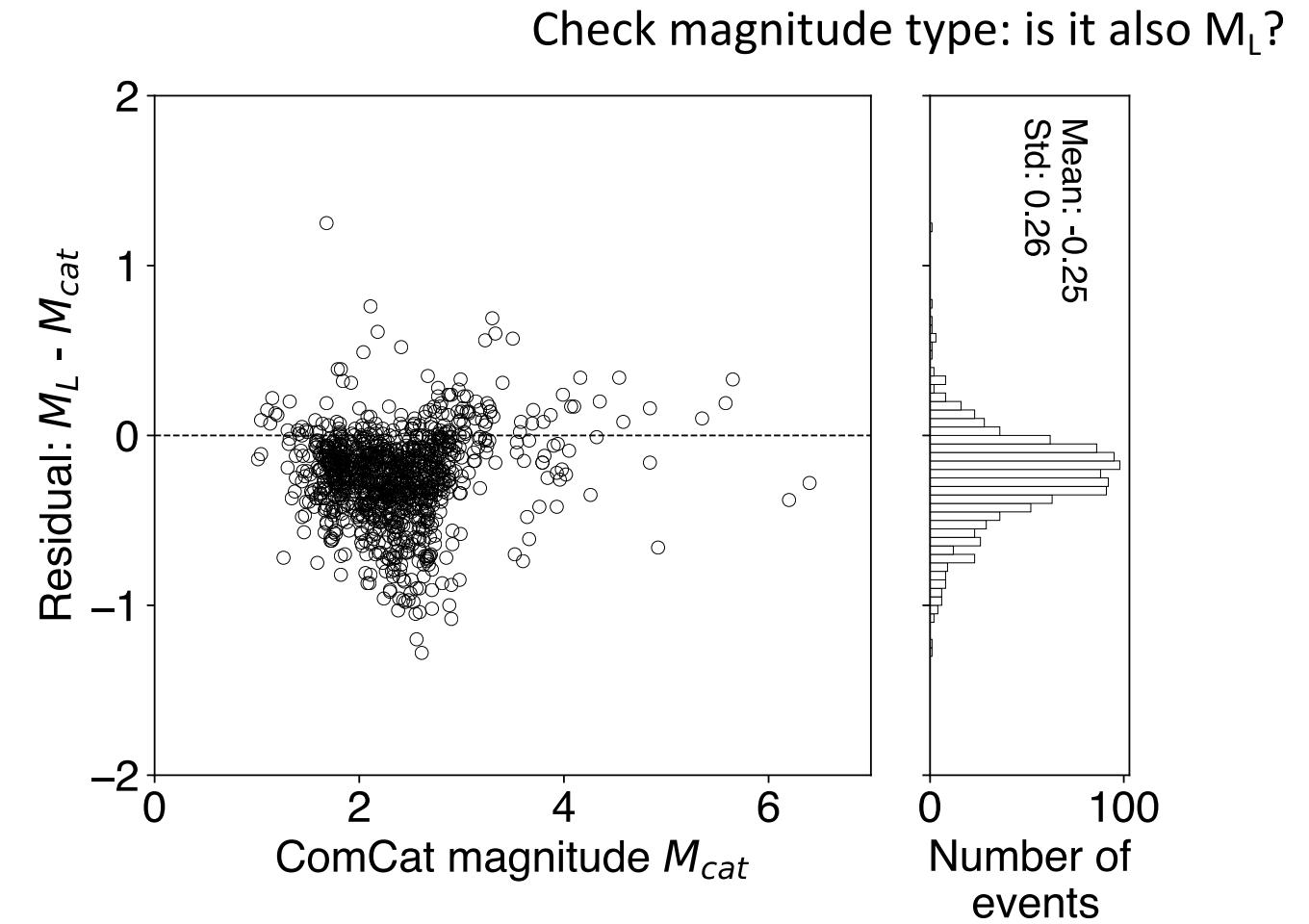
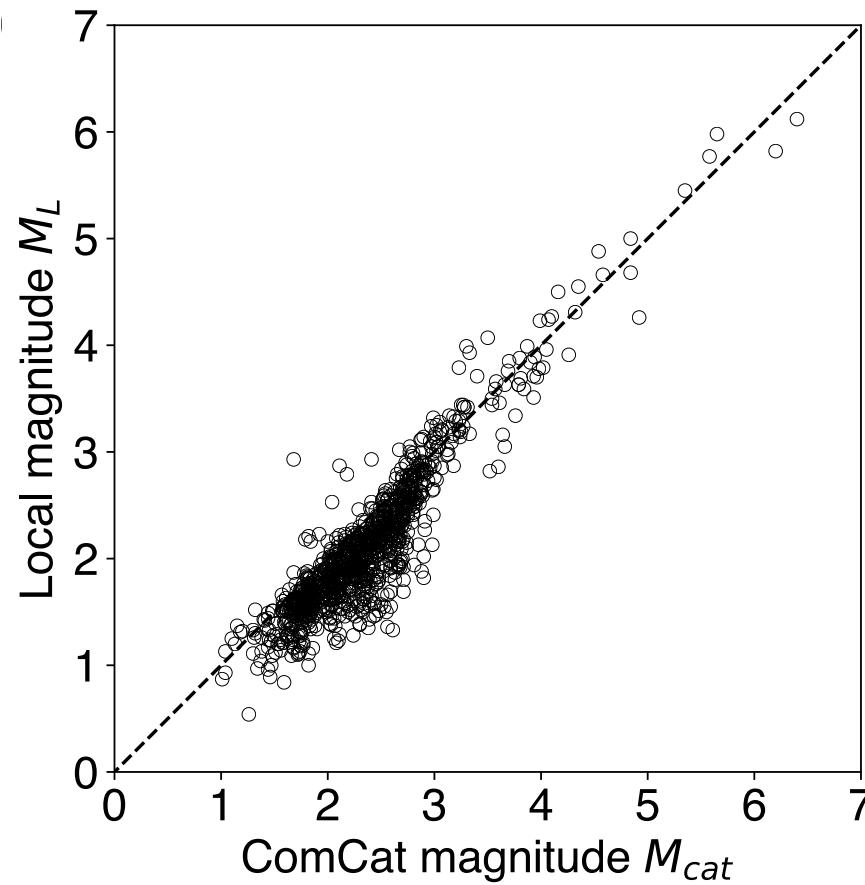
M_L : Calculation steps

- M_L for each station:
 - Get event-station distance R [km]; should I use current station to compute magnitude?
 - e.g. use only stations within a maximum distance ($R = 100$ km?)
 - e.g. use only stations with deep-learning automatic picks?
 - Get event waveform at station within short time window
 - e.g. start time: 5 seconds before P arrival, end time: 4*(S-P time) seconds after S arrival
 - Get peak-peak amplitude & timespan in windowed event waveform
 - 3-component (preferred): average of peak_amp[North] and peak_amp[East]
 - 1-component: peak_amp[Z]
 - Correct for Wood-Anderson instrument response
 - Can use ObsPy `estimate_wood_anderson_amplitude_using_response()`
 - Compute station M_L with region-specific equation
- M_L for event: median over all M_L station values
- If possible, compare calculated M_L with reference catalog M_L values for common events

vertical axis

horizontal axis

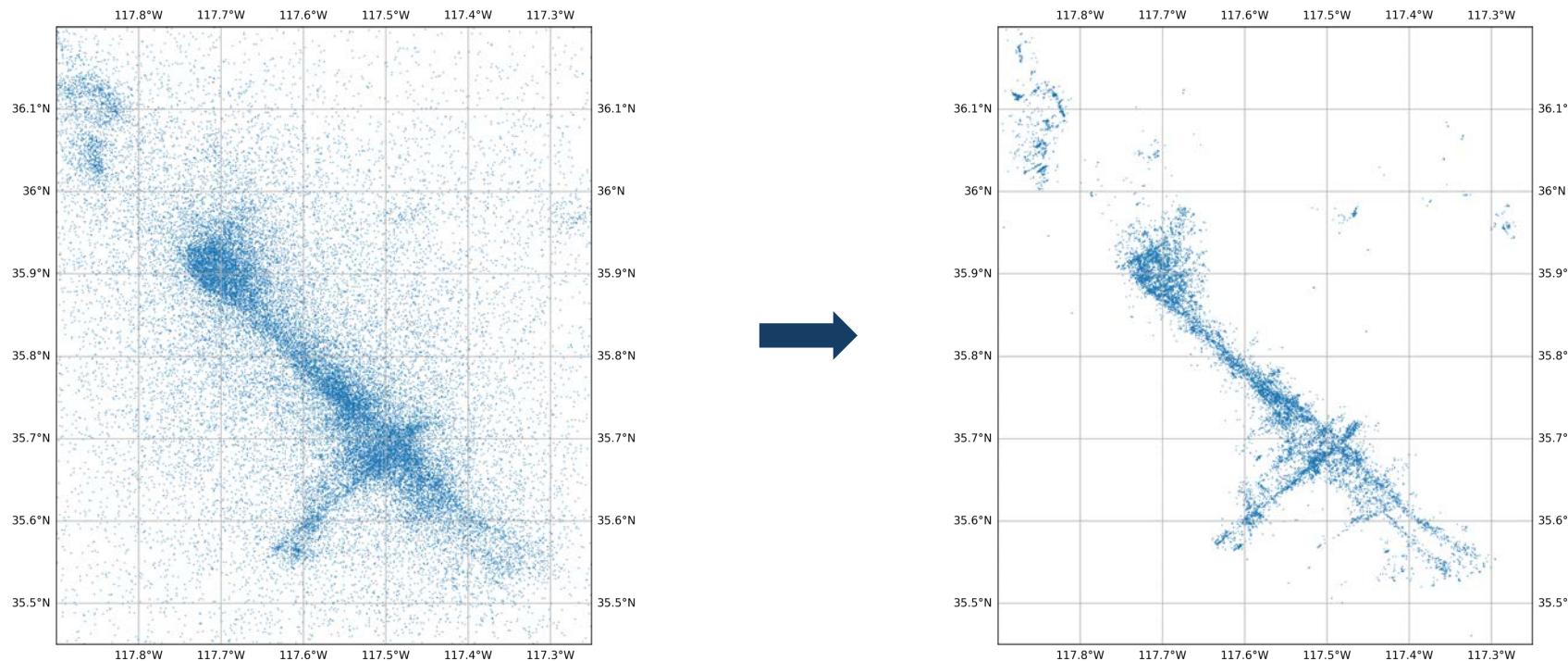
Calculated M_L vs. reference catalog (ComCat) M_{cat}



Alternatives to M_L (for small local earthquakes)

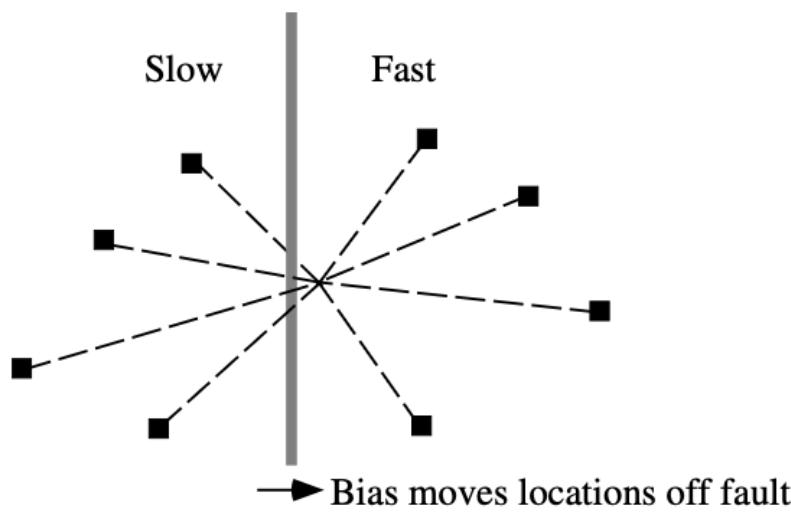
- Moment magnitude M_w from coda waves
 - Source code: <https://github.com/LLNL/coda-calibration-tool>
 - Docs: <https://software.llnl.gov/coda-calibration-tool/>
 - Examples: Holt et al. (2021) SRL; Shelly et al. (2021) BSSA; Patton et al. (2025) BSSA
 - Requires more computation and calibration – I have not tried it myself
- Relative magnitude based on event-pair cross-correlation or amplitude-ratios: good choice for template-matching (Eric's talk)
 - Calibrate against known magnitudes from reference (template) events
 - Examples: Cleveland and Ammon (2015) BSSA; Shelly et al. (2016) JGR; Gable and Huang (2024) BSSA

Q5: How to constrain earthquake relative locations?

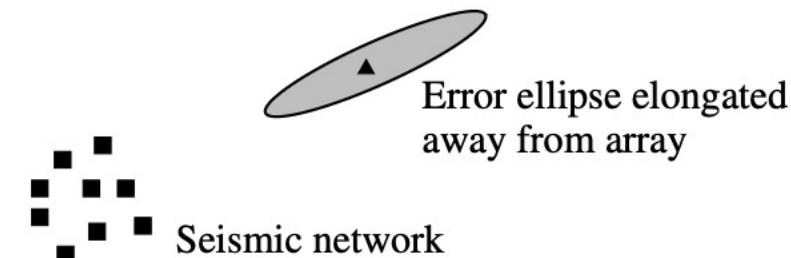


Challenges in absolute locations

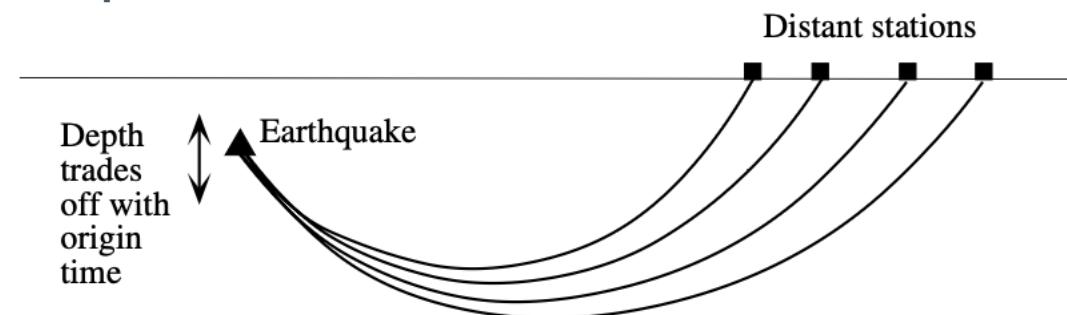
- Unmodeled velocity heterogeneity



- Station coverage



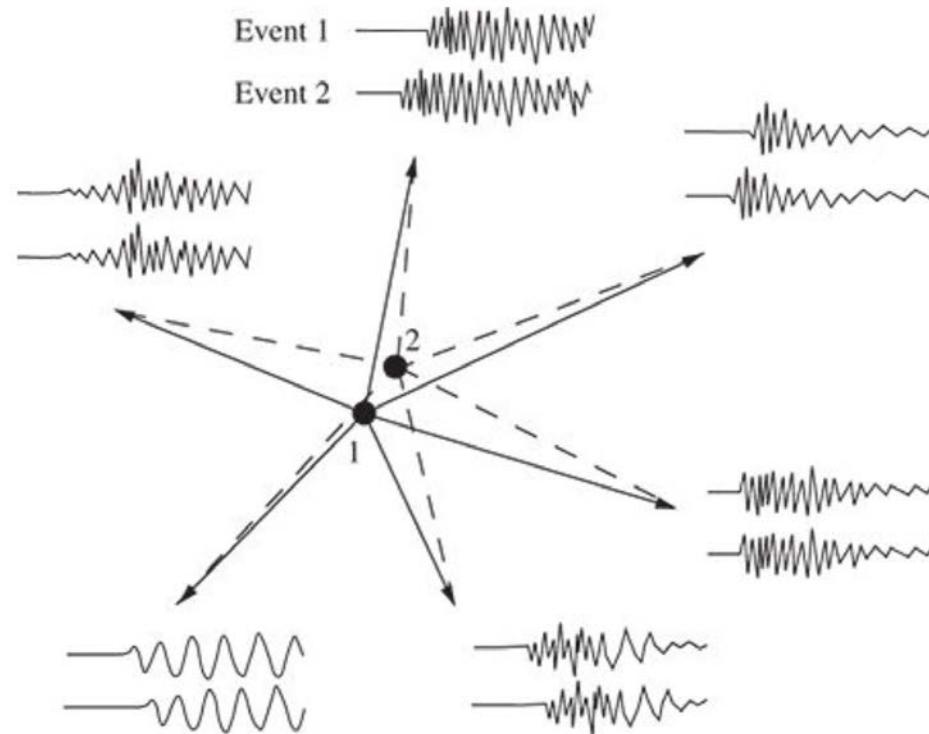
- Depth tradeoff



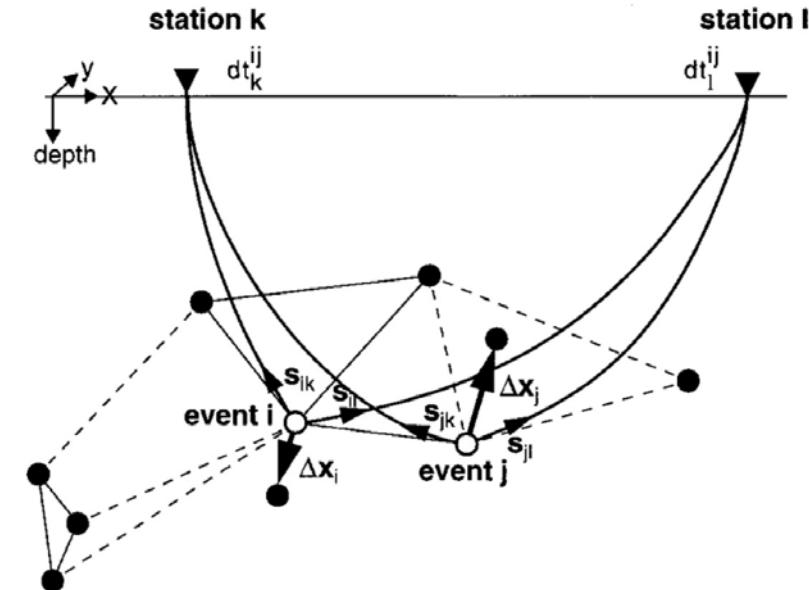
(Credit: Peter Shearer)

Double-difference earthquake location

(Credit: Peter Shearer)



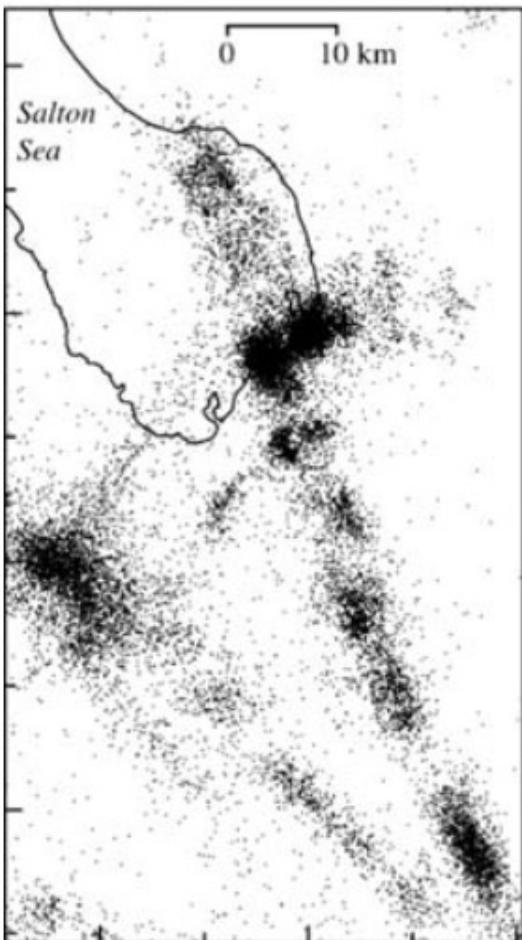
$$\Delta r_k^{ij} = (t_k^i - t_k^j) - (\hat{t}_k^i - \hat{t}_k^j)$$



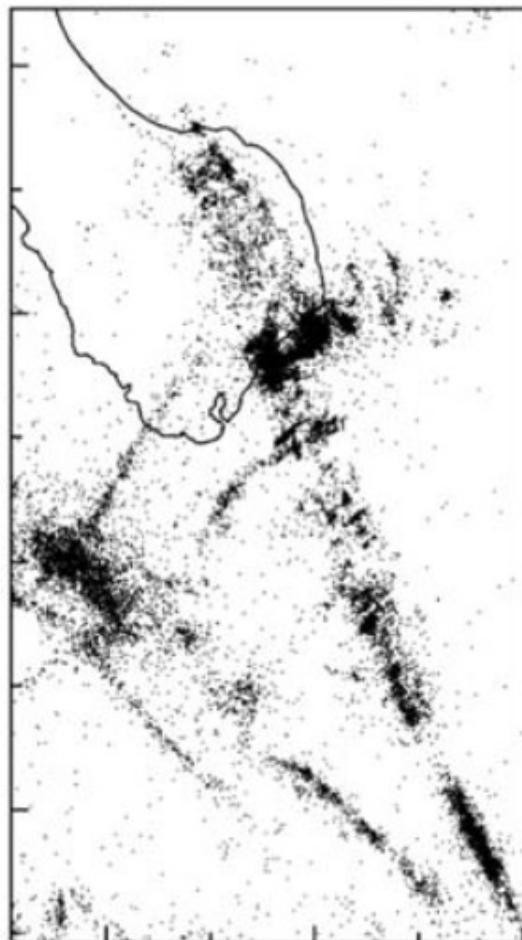
(Waldhauser and Ellsworth, 2000)

Comparison

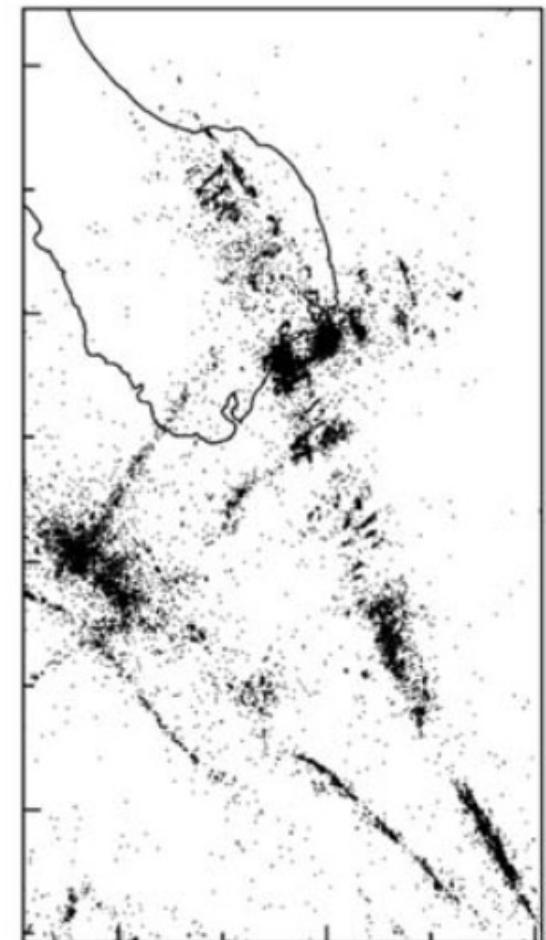
single event location



source-specific station
term location (SSST)

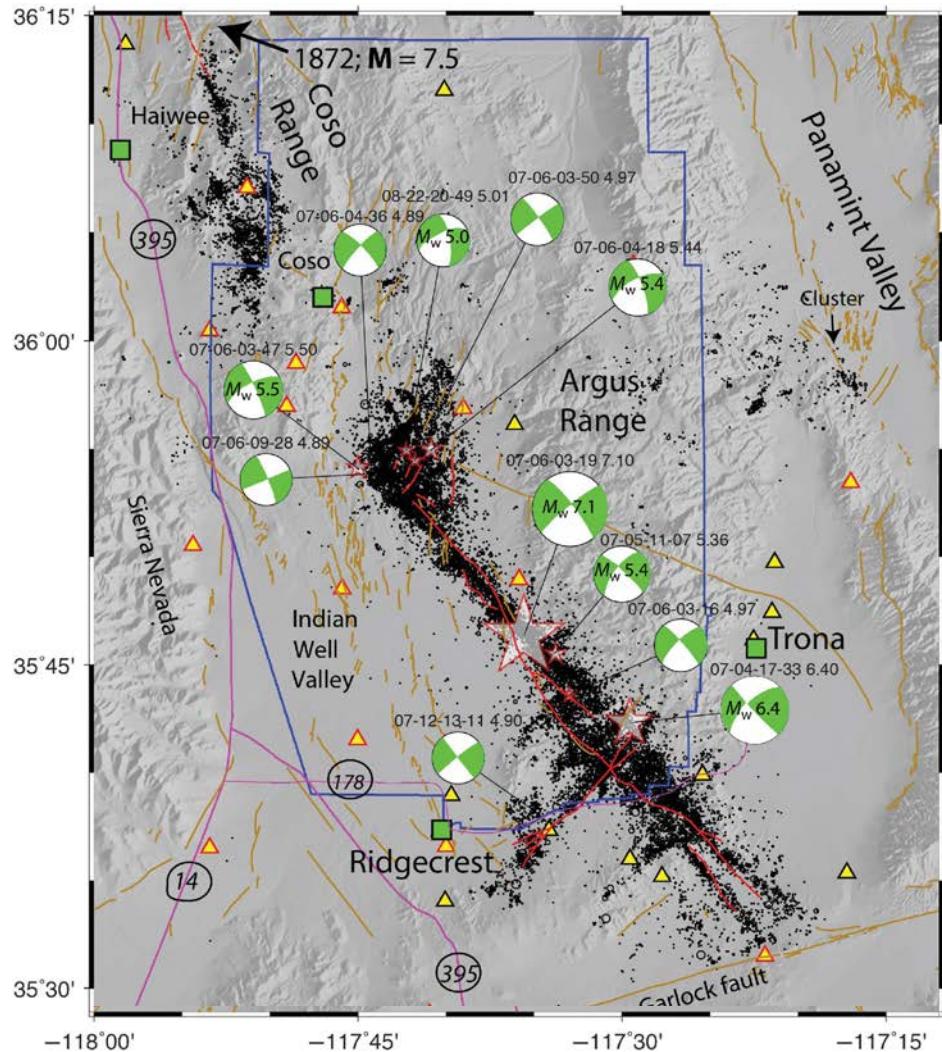


waveform cross-correlation
location



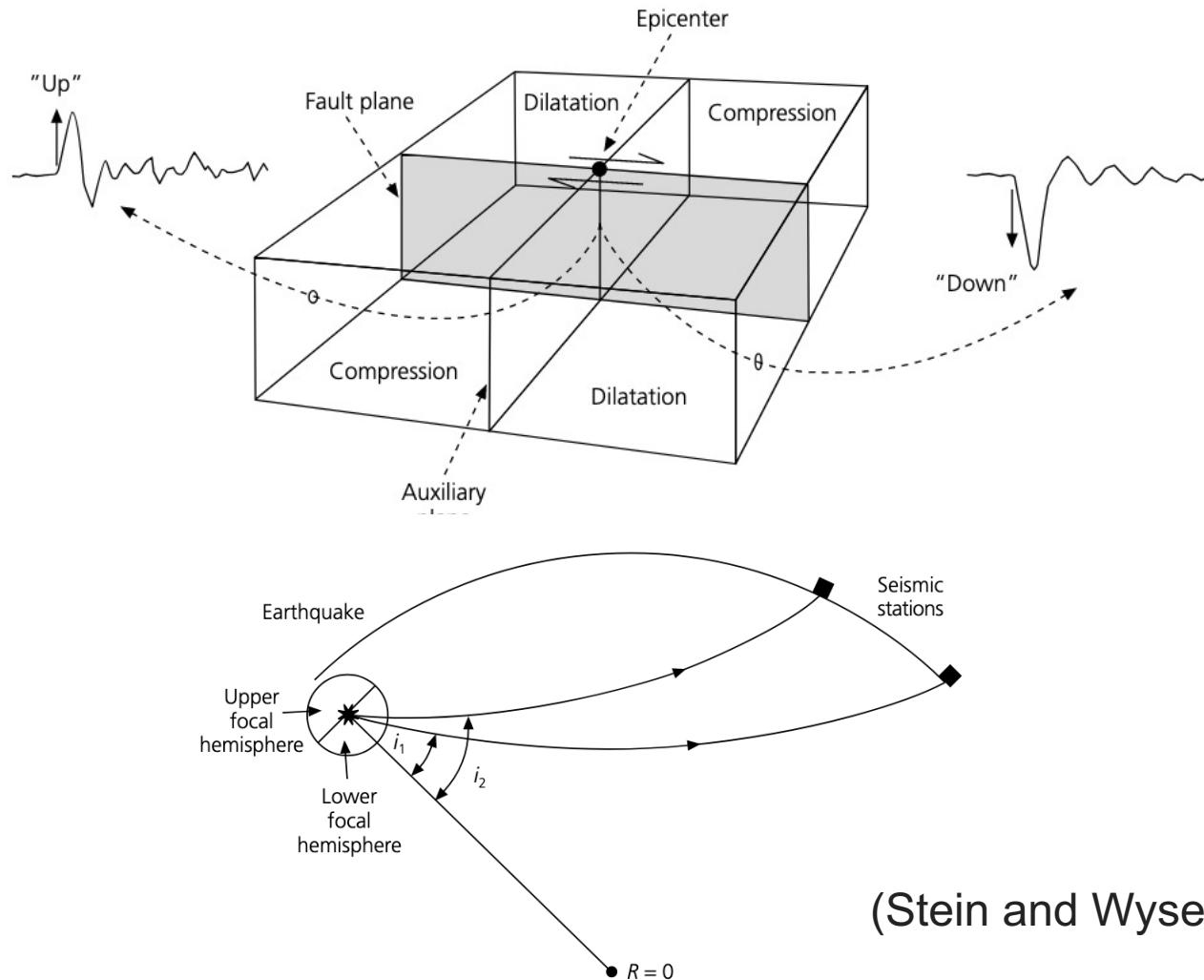
Lin et al. (2007)

Q6: How determine earthquake mechanism?

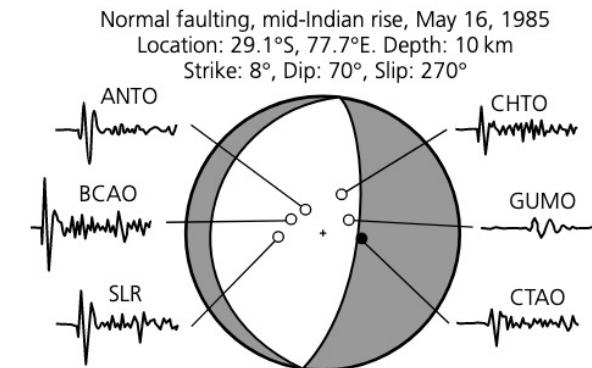
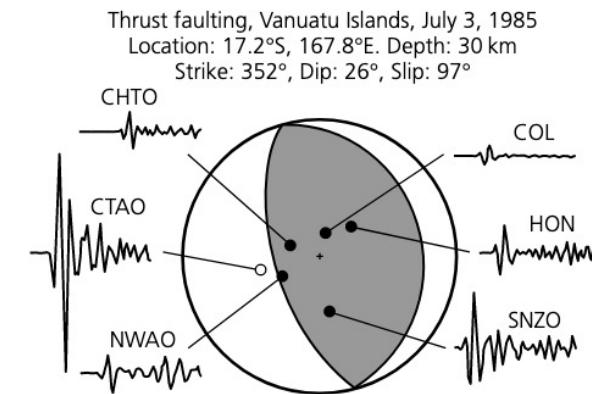
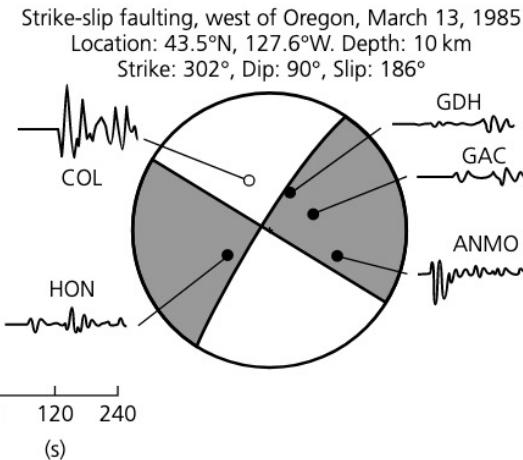


(Hauksson et al. 2020)

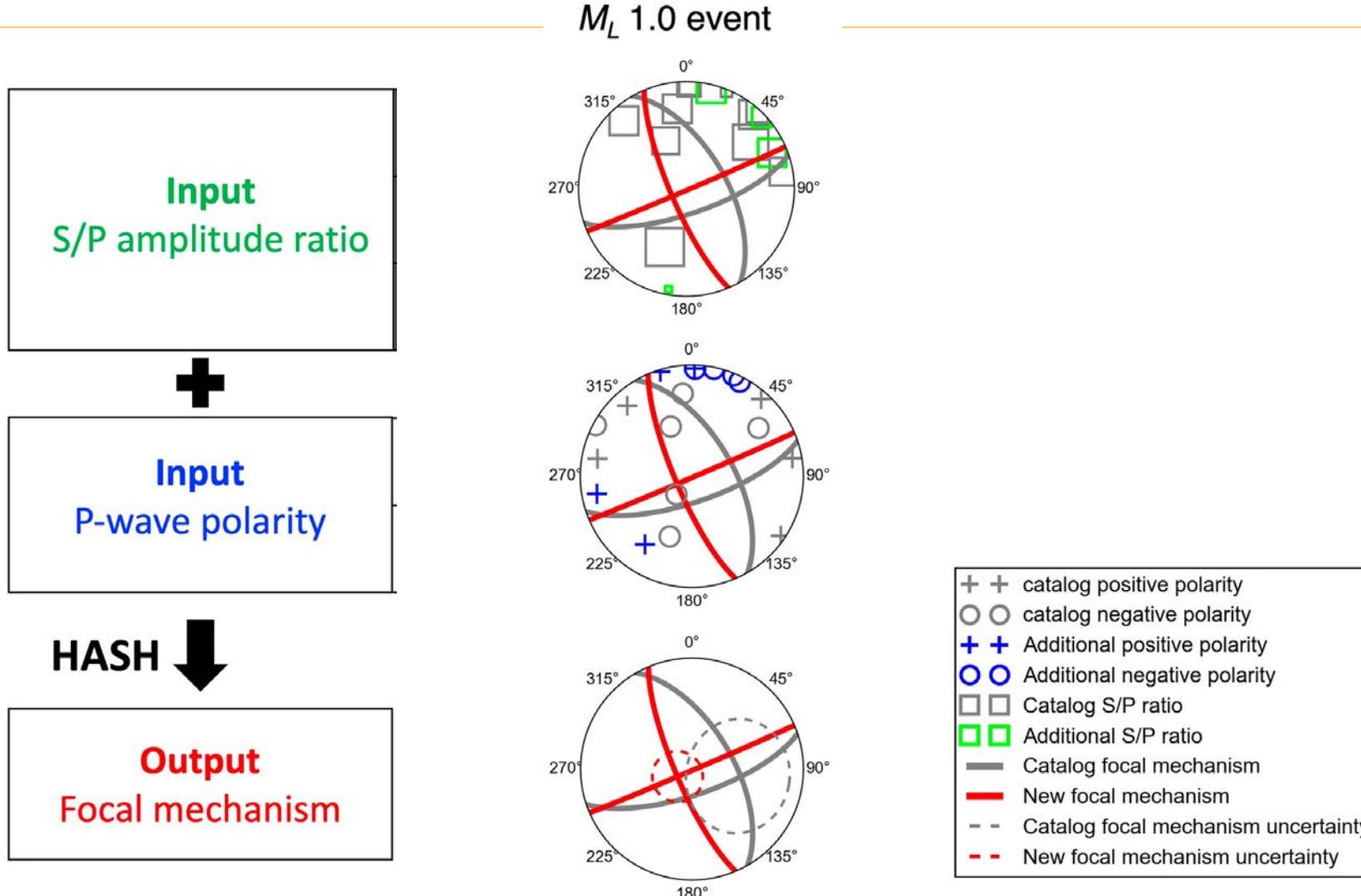
First-motion polarity



(Stein and Wysession 2009)

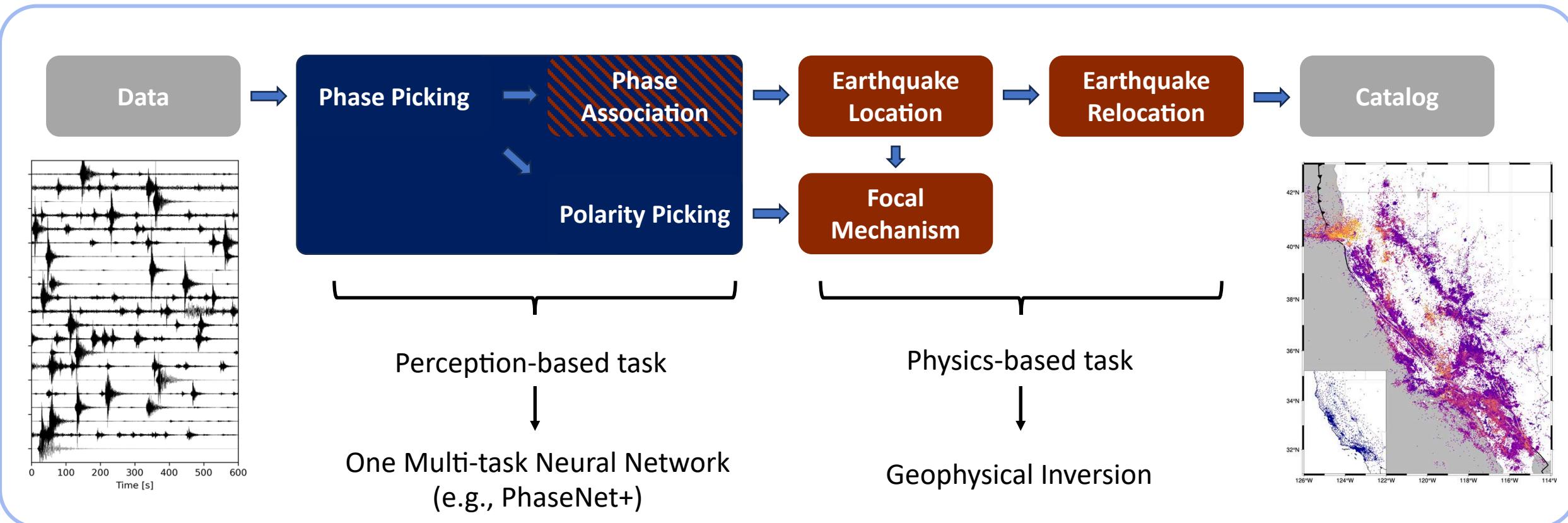


Constrain focal mechanisms



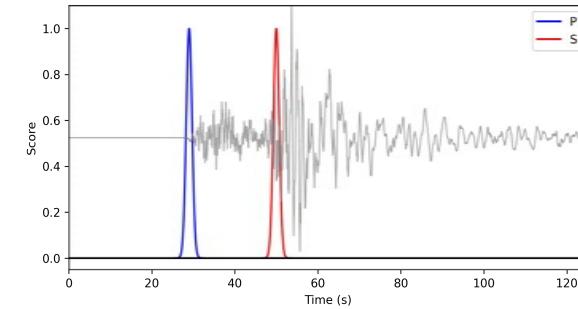
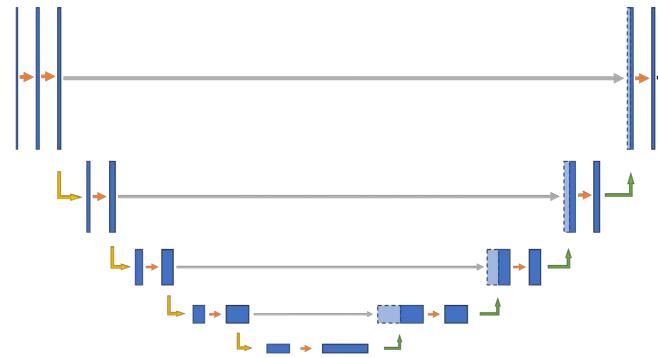
(Hardebeck and Shearer 2002)
(Cheng et al. 2023)
(Skoumal et al. 2024)

Multitask Learning: Arrival-time, Polarity, and Association

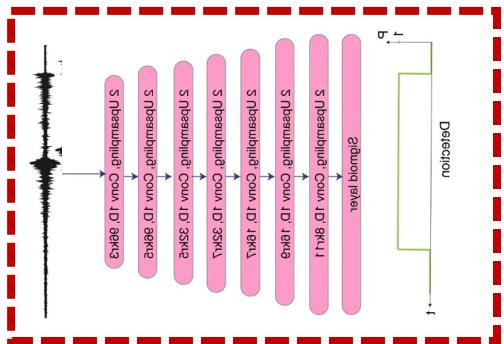


Neural Network Modules

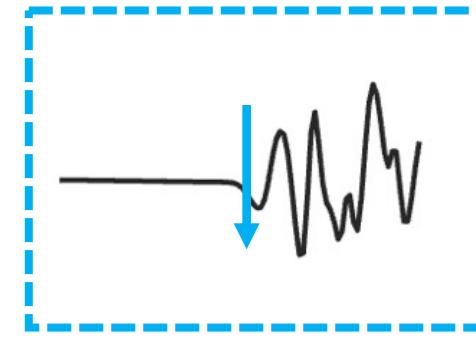
Phase Picking



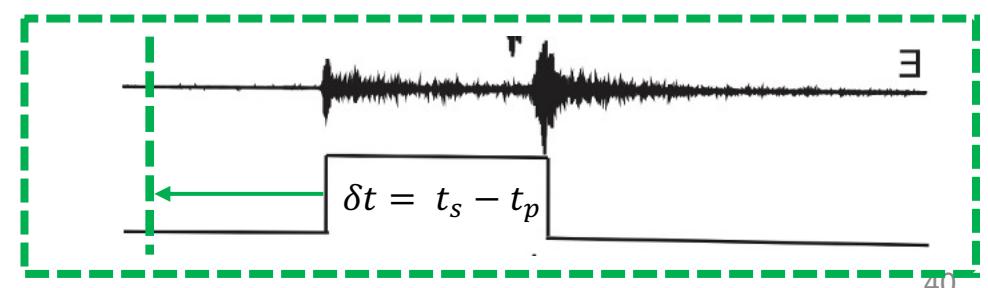
+ Event Detection



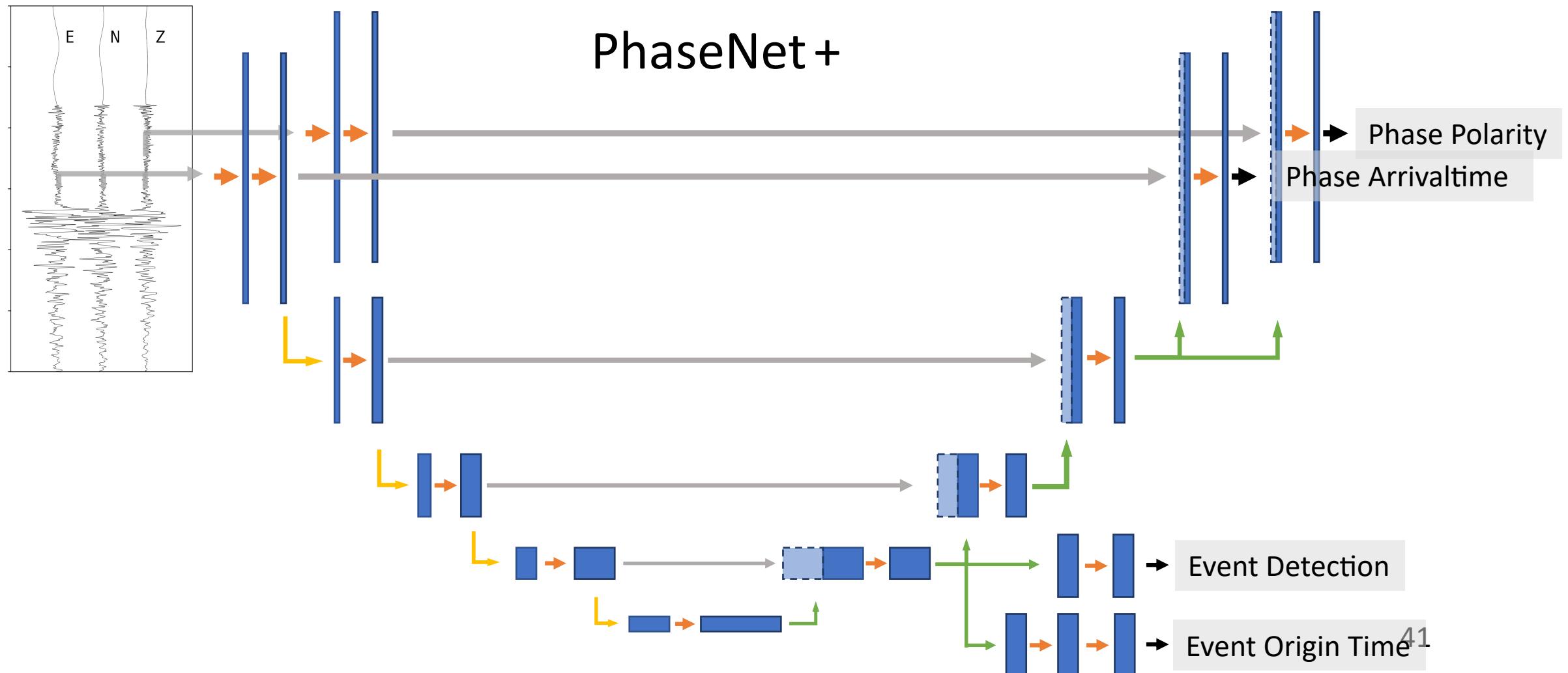
+ Polarity Picking



+ Phase Association based on origin time



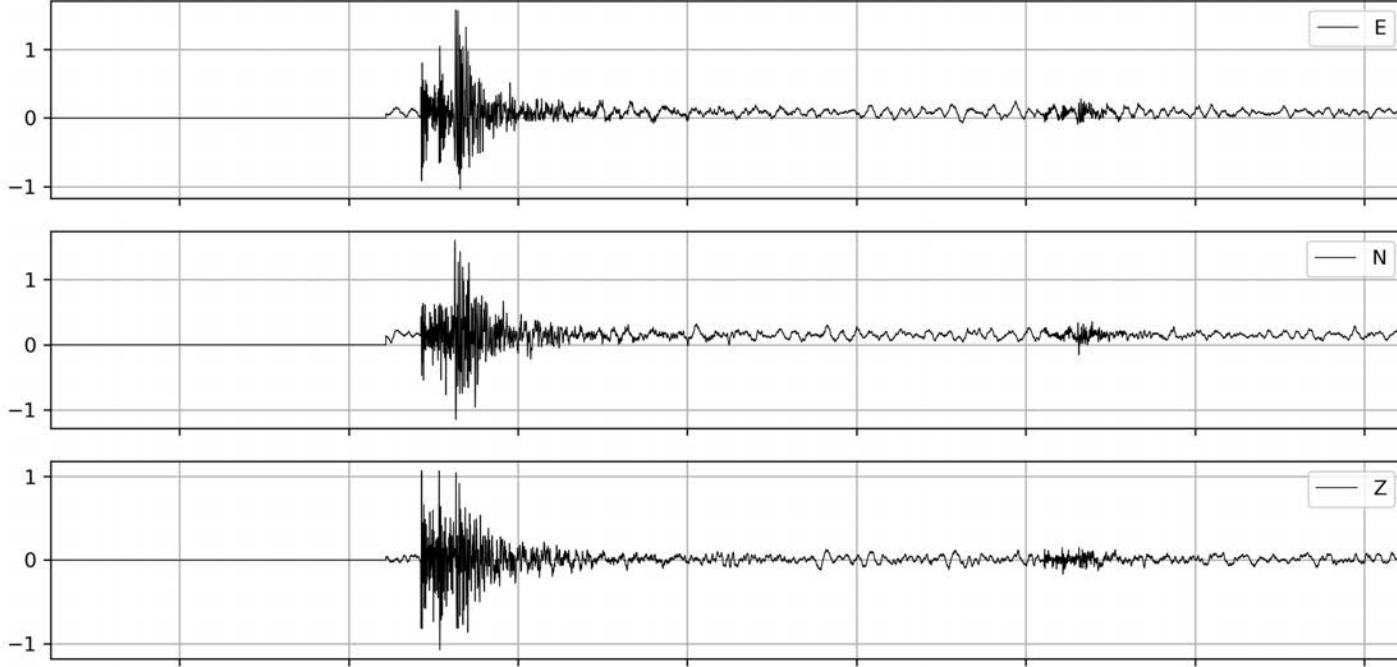
Multi-task Learning



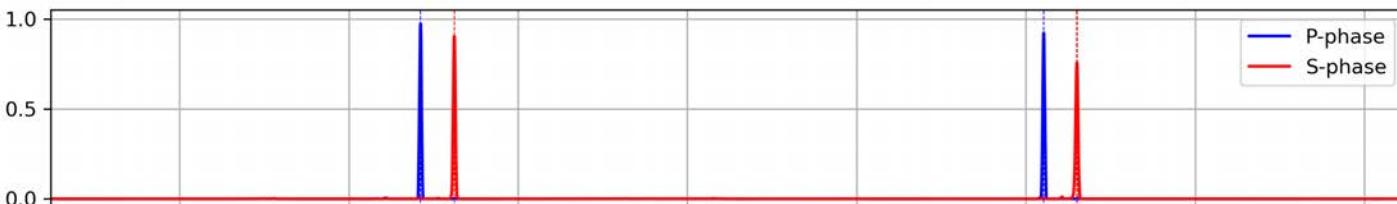
Examples:

PhaseNet+

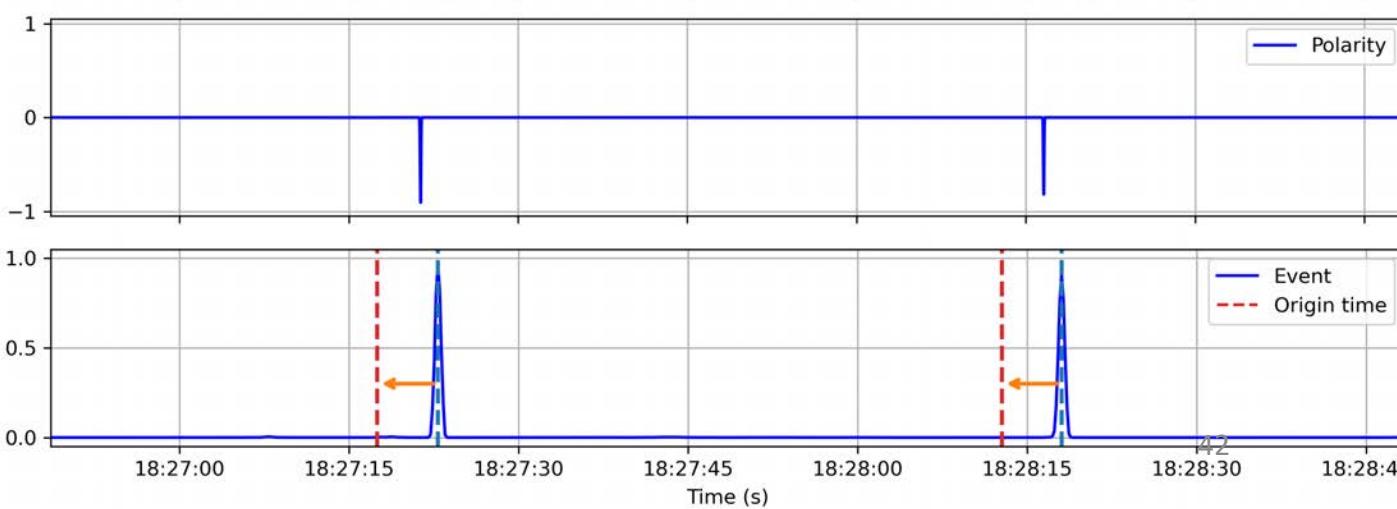
Phase Arrival-time:



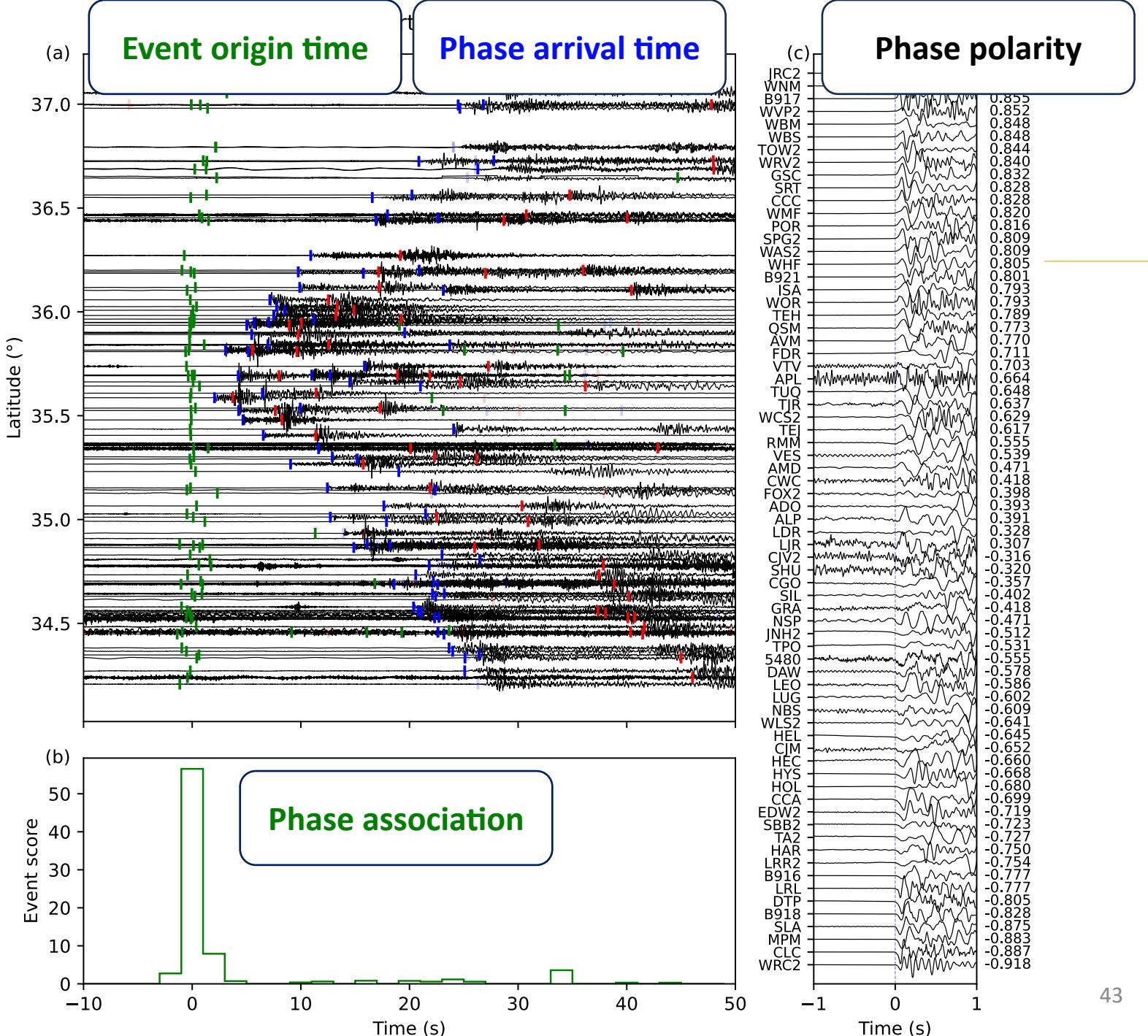
Phase Polarity:



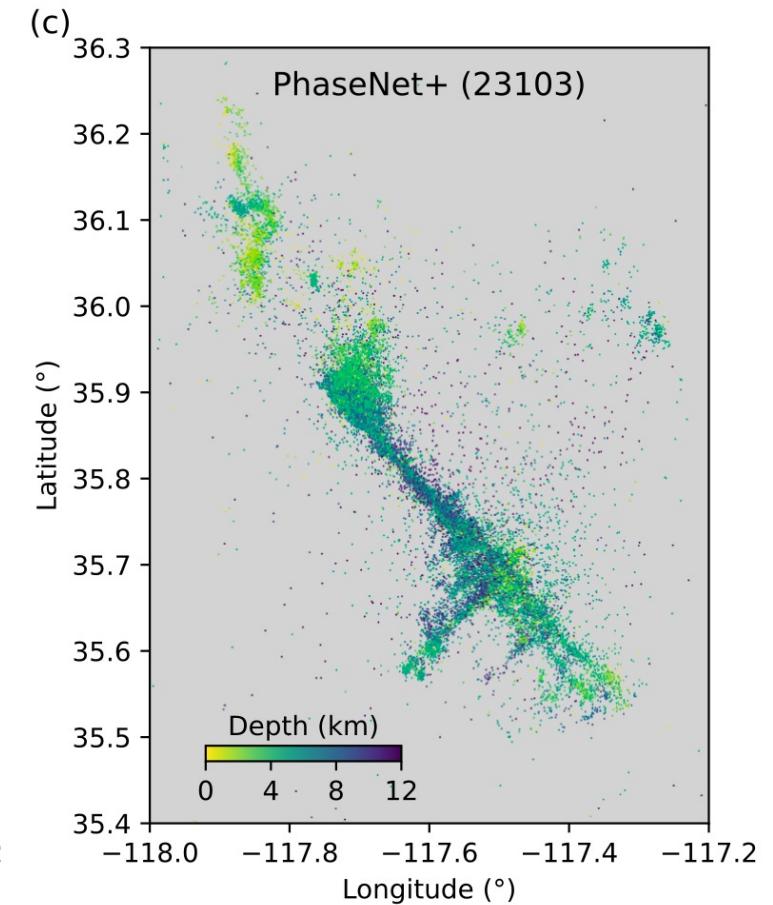
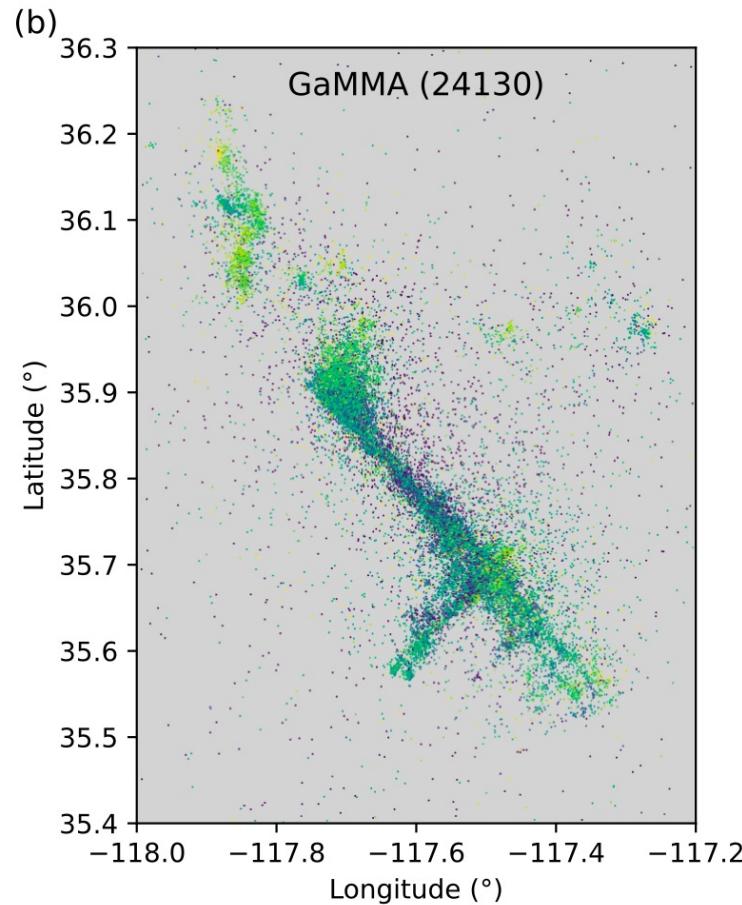
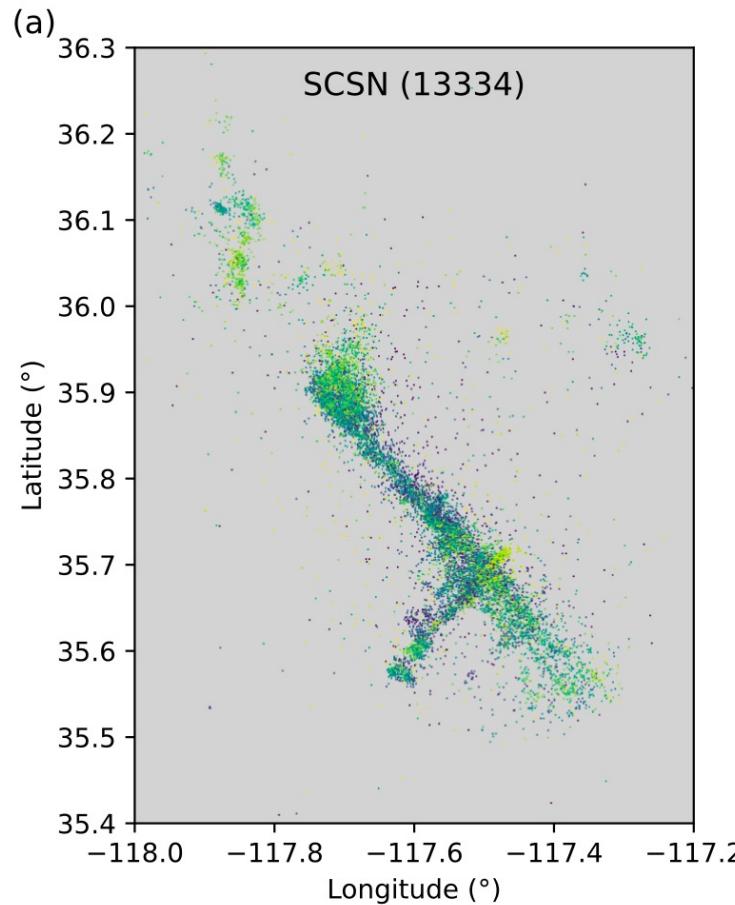
Event Detection:
Origin-time Prediction:



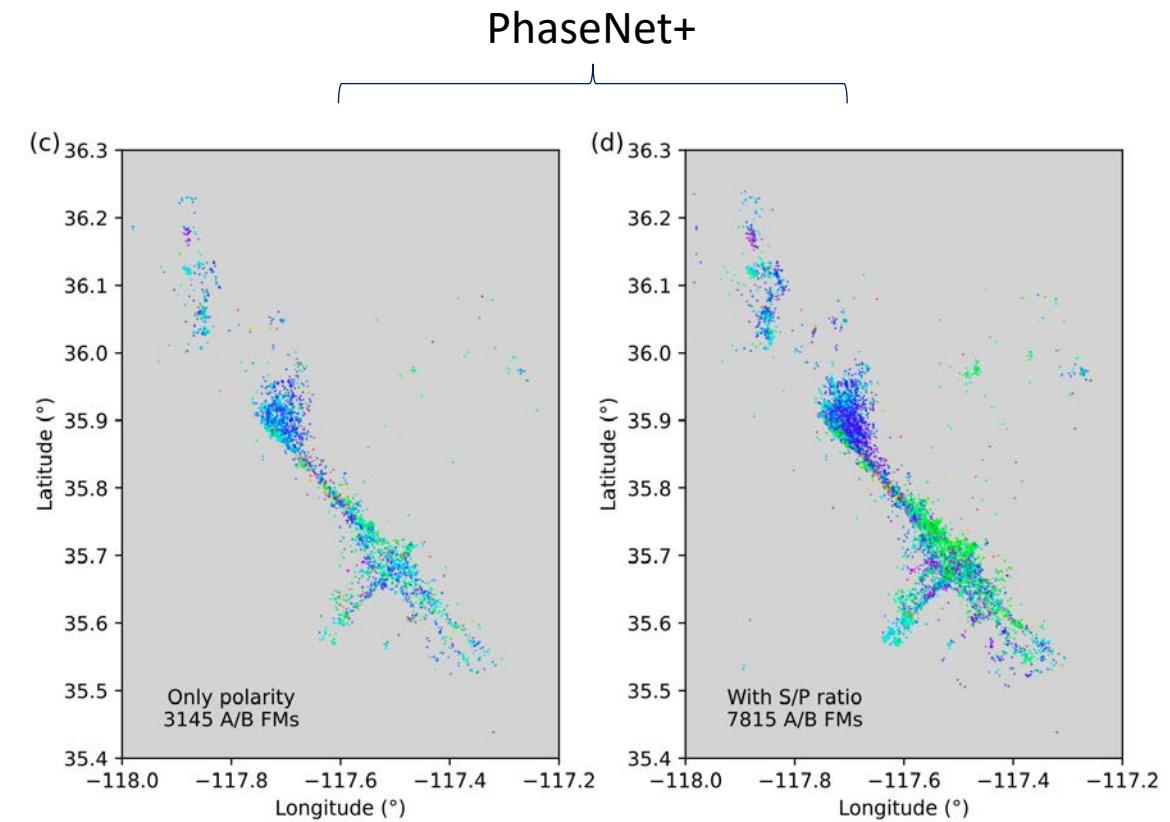
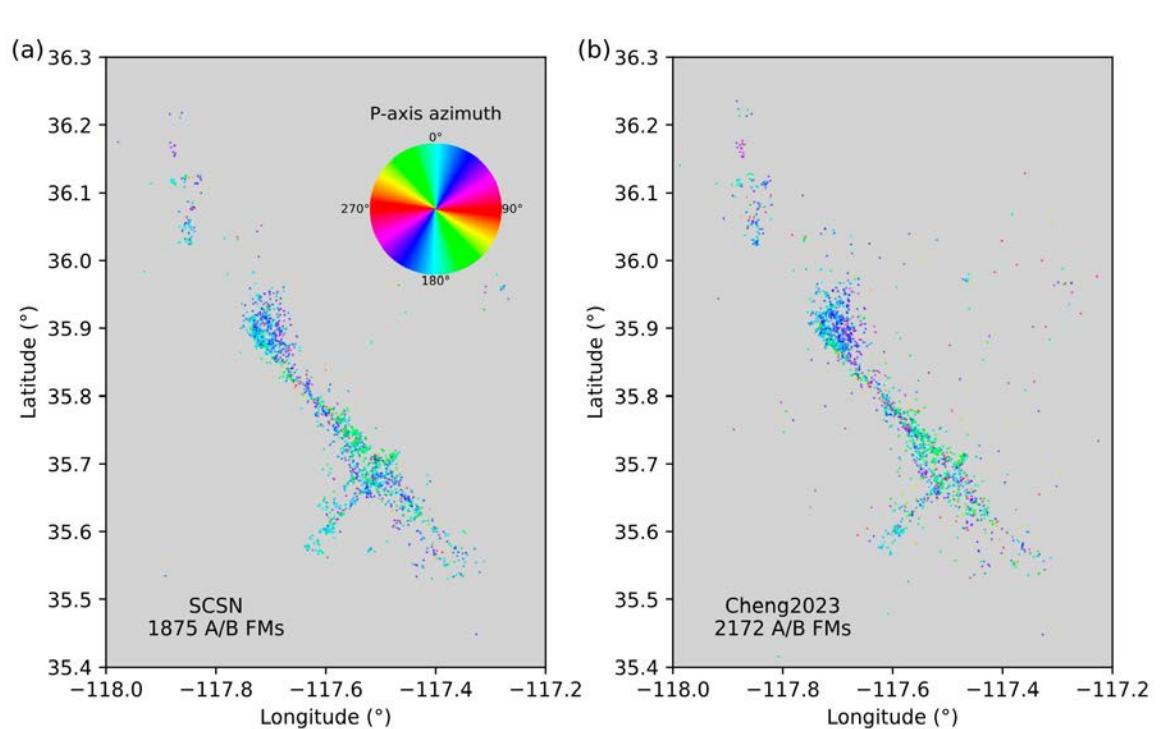
Examples:



Comparisons

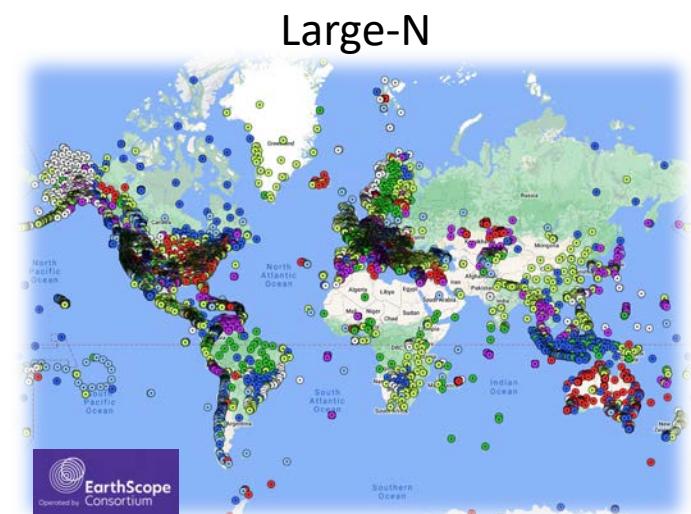
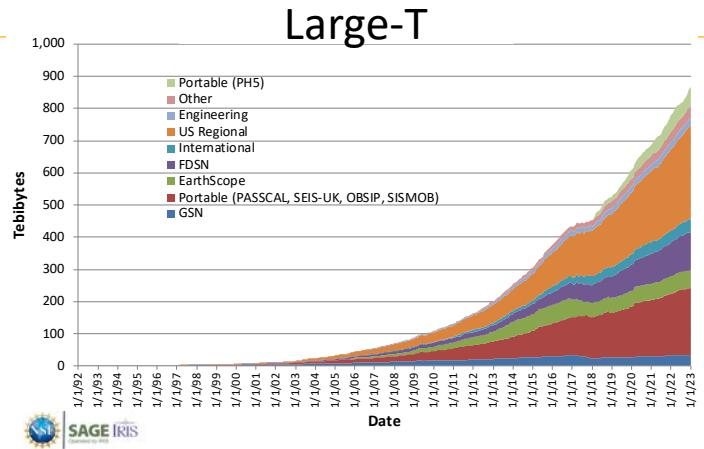


Comparisons

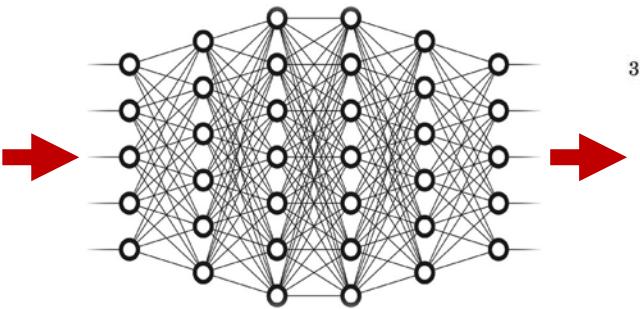


Applications of Earthquake Deep Catalogs

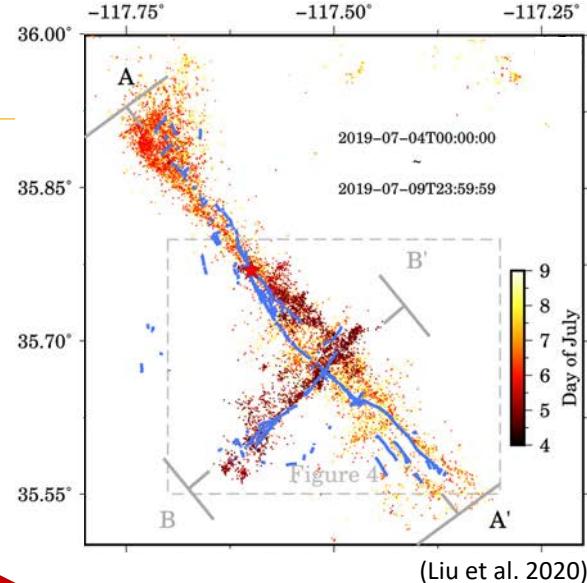
Seismic Datasets



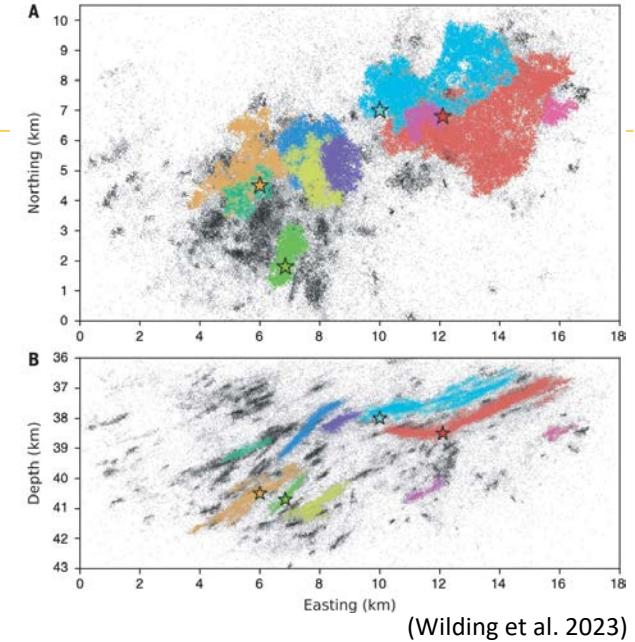
Deep Neural Networks



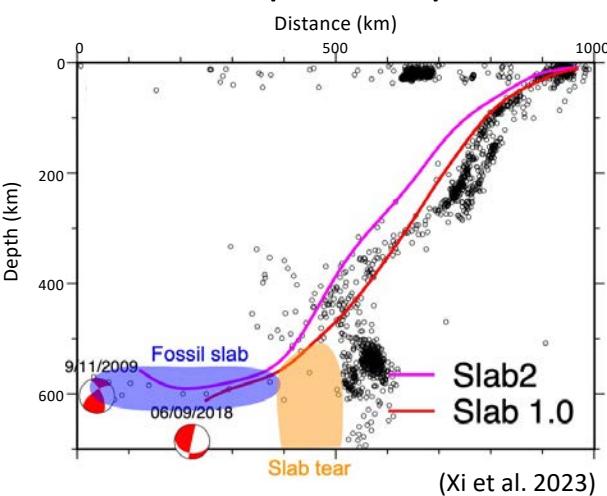
Tectonic earthquake



Volcanic earthquake



Deep earthquake



Induced earthquake

