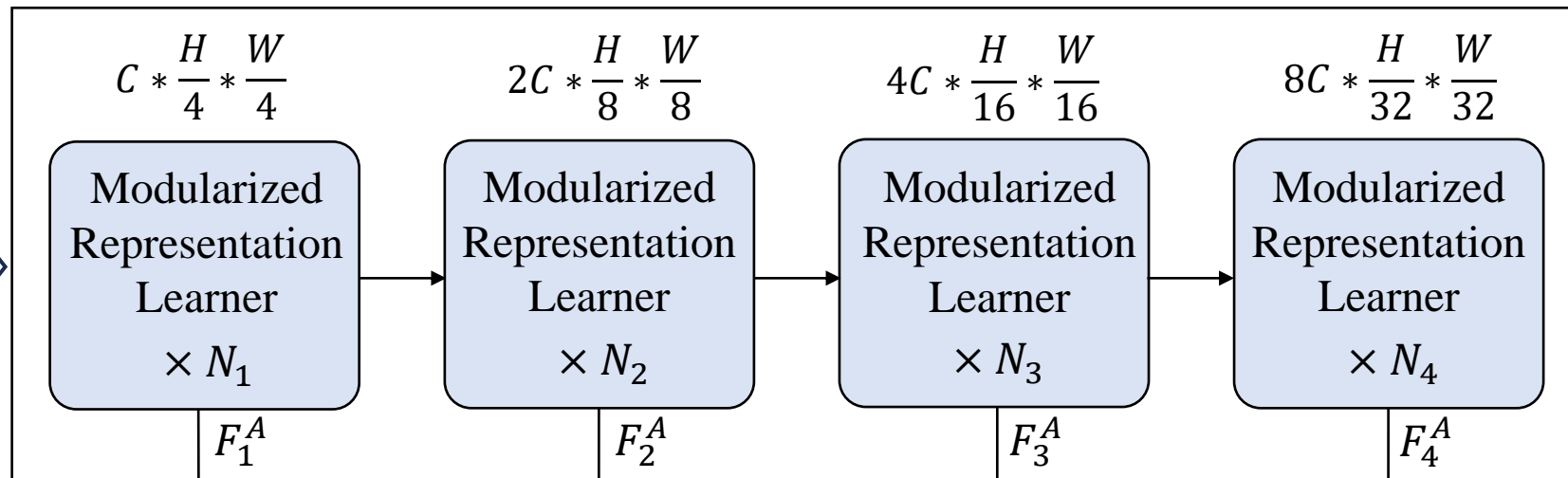


Modularized Siamese Encoder

Pre-change



I^A



$$\ominus \Rightarrow \bullet F_1$$

$$\ominus \Rightarrow \bullet F_2$$

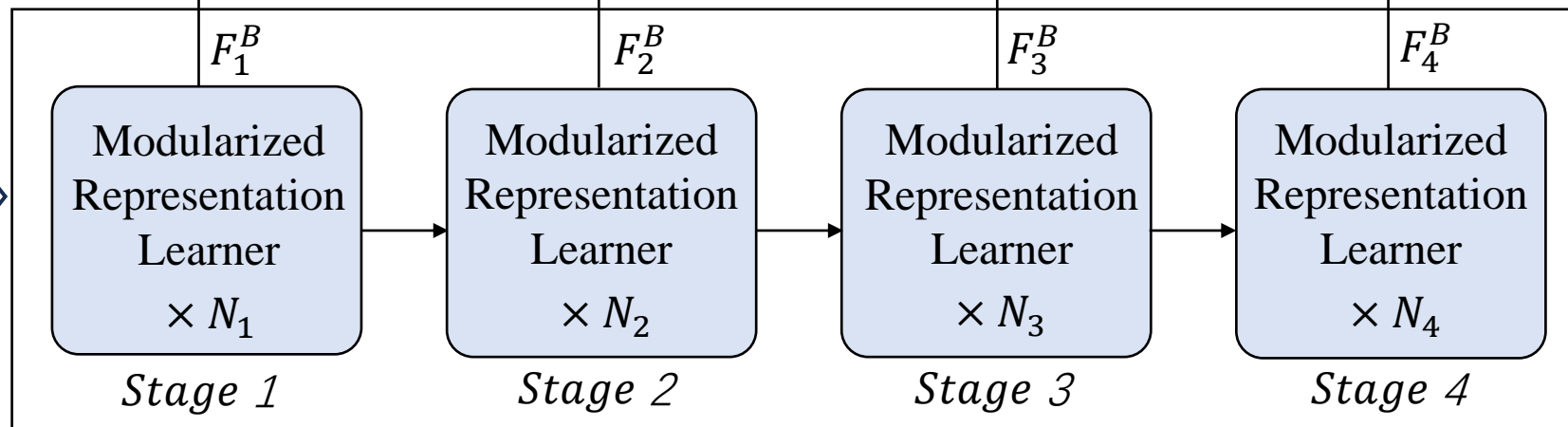
$$\ominus \Rightarrow \bullet F_3$$

$$\ominus \Rightarrow \bullet F_4$$

Weight Shared



I^B



Post-change