### Chapter 4

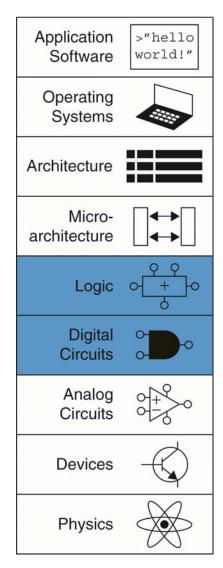
#### Digital Design and Computer Architecture, 2nd Edition

David Money Harris and Sarah L. Harris



# Chapter 4:: Topics

- Introduction
- Combinational Logic
- Structural Modeling
- Sequential Logic
- More Combinational Logic
- Finite State Machines
- Parameterized Modules
- Testbenches





### Introduction

- Hardware description language (HDL):
  - specifies logic function only
  - Computer-aided design (CAD) tool produces or synthesizes the optimized gates
- Most commercial designs built using HDLs
- Two leading HDLs:
  - SystemVerilog
    - developed in 1984 by Gateway Design Automation
    - IEEE standard (1364) in 1995
    - Extended in 2005 (IEEE STD 1800-2009)
  - VHDL 2008
    - Developed in 1981 by the Department of Defense
    - IEEE standard (1076) in 1987
    - Updated in 2008 (IEEE STD 1076-2008)



### **HDL** to Gates

#### Simulation

- Inputs applied to circuit
- Outputs checked for correctness
- Millions of dollars saved by debugging in simulation instead of hardware

### Synthesis

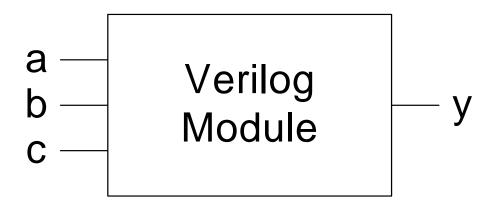
Transforms HDL code into a *netlist* describing the hardware (i.e., a list of gates and the wires connecting them)

#### **IMPORTANT:**

When using an HDL, think of the **hardware** the HDL should produce



# SystemVerilog Modules



### Two types of Modules:

- Behavioral: describe what a module does
- Structural: describe how it is built from simpler modules



# Behavioral SystemVerilog

### **SystemVerilog:**



## Behavioral SystemVerilog

### **SystemVerilog:**

- module/endmodule: required to begin/end module
- example: name of the module
- Operators:

~: NOT

&: AND

: OR



### **HDL Simulation**

### **SystemVerilog:**

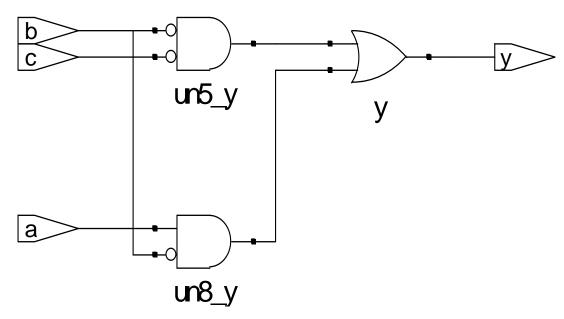
Now: 800 ns		0 ns 160 320 ns 480 640 ns 800
<mark>∛ll</mark> a	0	
<mark>∛</mark> ¶ b	0	
<b>∛</b> 1 c	0	
<mark>∛ll</mark> y	0	



# HDL Synthesis

### **SystemVerilog:**

### **Synthesis:**





## SystemVerilog Syntax

- Case sensitive
  - Example: reset and Reset are not the same signal.
- No names that start with numbers
  - Example: 2mux is an invalid name
- Whitespace ignored
- Comments:



# Structural Modeling - Hierarchy

```
module and3(input logic a, b, c,
            output logic y);
  assign y = a \& b \& c;
endmodule
module inv(input logic a,
           output logic y);
  assign y = \sim a;
endmodule
module nand3(input logic a, b, c
             output logic y);
  logic n1;
                              // internal signal
  and3 andgate(a, b, c, n1); // instance of and3
  inv inverter(n1, y); // instance of inv
endmodule
```



# Bitwise Operators

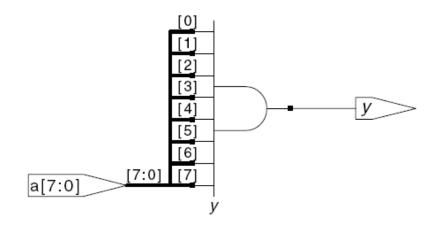
```
module gates(input logic [3:0] a, b,
             output logic [3:0] y1, y2, y3, y4, y5);
   /* Five different two-input logic
      gates acting on 4 bit busses */
   assign y1 = a \& b; // AND
   assign y2 = a \mid bi // OR
   assign y3 = a ^b; // XOR
   assign y4 = \sim (a \& b); // NAND
   assign y5 = \sim(a \mid b); // NOR
endmodule
```

```
y3[3:0]
y1[3:0]
                     y4[3:0]
y2[3:0]
                     y5[3:0]
```

// single line comment /\*...\*/ multiline comment

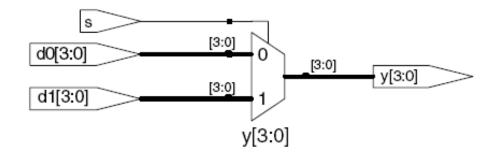


### **Reduction Operators**





# Conditional Assignment



is also called a *ternary operator* because it operates on 3 inputs: s, d1, and d0.



### Internal Variables

```
module fulladder(input logic a, b, cin,
                  output logic s, cout);
  logic p, g; // internal nodes
  assign p = a ^ b;
  assign g = a & b;
  assign s = p ^ cin;
  assign cout = g | (p & cin);
endmodule
                                         S
        cin
                                                 cout
                                        cout
                            un1_cout
```

### Precedence

### **Order of operations**

#### **Highest**

~	NOT		
*, /, %	mult, div, mod		
+, -	add, sub		
<< , >>	shift		
<<< , >>>	arithmetic shift		
< , <= , > , >=	comparison		
== , !=	equal, not equal		
&, ~&	AND, NAND		
^, ~^	XOR, XNOR		
, ~	OR, NOR		
?:	ternary operator		

**Lowest** 



### Numbers

#### Format: N'Bvalue

N = number of bits, B = base

**N'B** is optional but recommended (default is decimal)

Number	# Bits	Base	Decimal Equivalent	Stored
3'b101	3	binary	5	101
'b11	unsized	binary	3	000011
8'b11	8	binary	3	00000011
8'b1010_1011	8	binary	171	10101011
3'd6	3	decimal	6	110
6 <b>'</b> 042	6	octal	34	100010
8'hAB	8	hexadecimal	171	10101011
42	Unsized	decimal	42	000101010



### Bit Manipulations: Example 1

```
assign y = {a[2:1], {3{b[0]}}, a[0], 6'b100_010};

// if y is a 12-bit signal, the above statement produces:
y = a[2] a[1] b[0] b[0] b[0] a[0] 1 0 0 0 1 0

// underscores (_) are used for formatting only to make it easier to read. SystemVerilog ignores them.
```



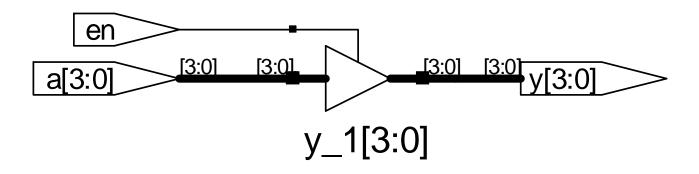
## Bit Manipulations: Example 2

```
SystemVerilog:
module mux2_8(input logic [7:0] d0, d1,
                  input
                           logic
                  output logic [7:0] y);
  \max 2 \ lsbmux(d0[3:0], \ d1[3:0], \ s, \ y[3:0]);
  \max 2 \ \max(d0[7:4], \ d1[7:4], \ s, \ y[7:4]);
endmodule
                                     mux2
                                               [3:0] [7:0] y[7:0]
                                  d0[3:0]
                 d0[7:0]
                                         y[3:0] <del>-</del>
                 d1[7:0]
                                  d1[3:0]
                                    Isbmux
                                     mux2
                                  d0[3:0]
                                         y[3:0] •
                                  d1[3:0]
                                    msbmux
```

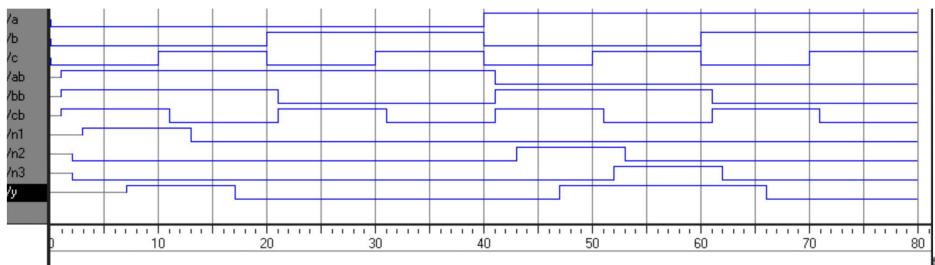


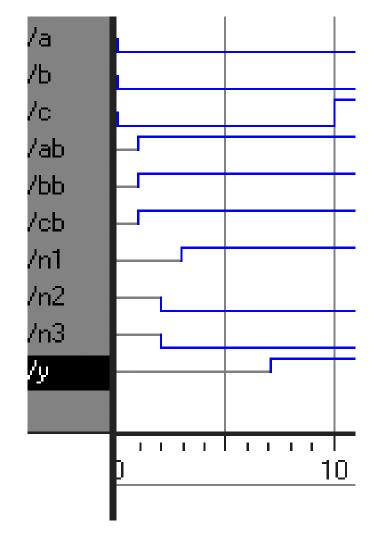
# Z: Floating Output

### **SystemVerilog:**

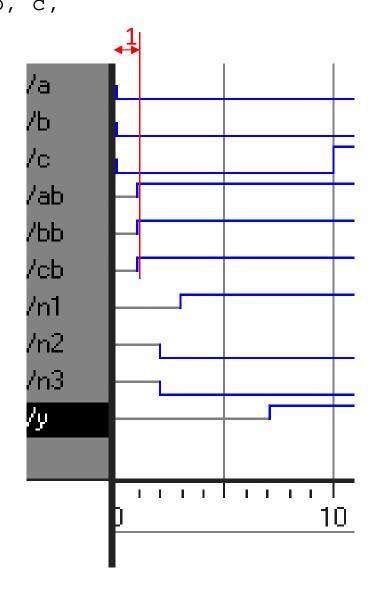




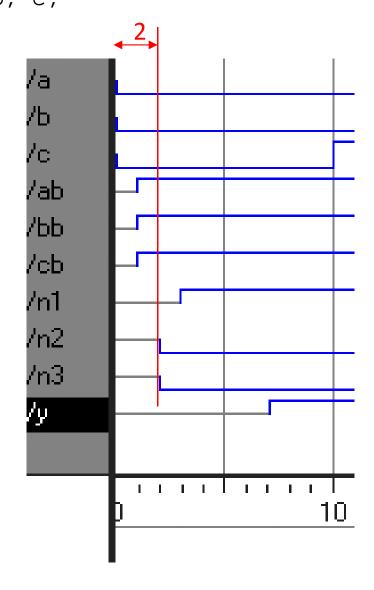




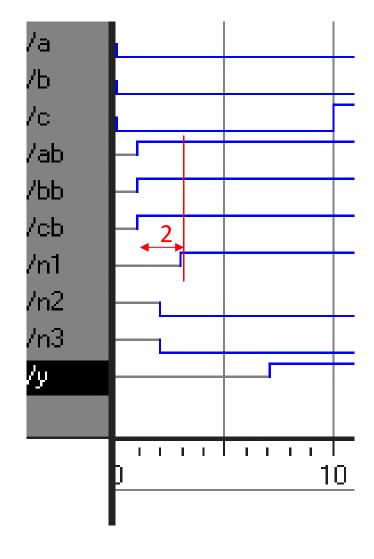




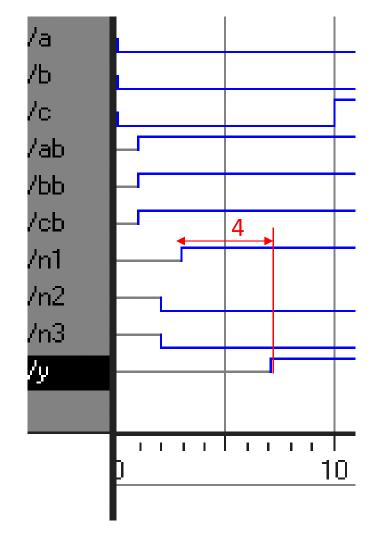














## Sequential Logic

- System Verilog uses **idioms** to describe latches, flip-flops and FSMs
- Other coding styles may simulate correctly but produce incorrect hardware



# Always Statement

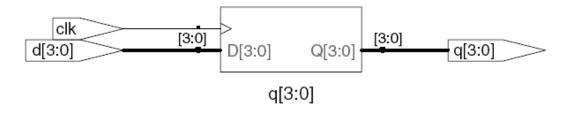
### **General Structure:**

```
always @(sensitivity list)
statement;
```

Whenever the event in sensitivity list occurs, statement is executed



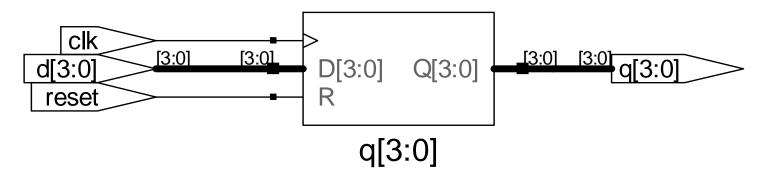
### D Flip-Flop





### Resettable D Flip-Flop

endmodule

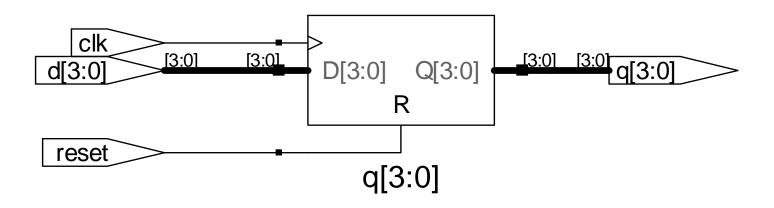




# Resettable D Flip-Flop

```
module flopr(input
                  logic
                              clk,
                 logic
            input
                              reset,
            input logic [3:0] d,
            output logic [3:0] q);
  // asynchronous reset
 always_ff @(posedge clk, posedge reset)
   if (reset) q \ll 4'b0;
   else
         a <= d;
```

endmodule





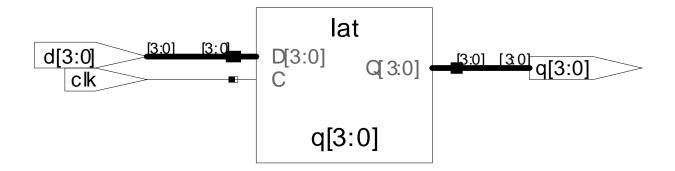
### D Flip-Flop with Enable

```
module flopren(input
                        logic
                                       clk,
                 input
                        logic
                                       reset,
                 input logic
                                       en,
                 input logic [3:0] d,
                 output logic [3:0] q);
  // asynchronous reset and enable
  always_ff @(posedge clk, posedge reset)
              (reset) q <= 4'b0;
    else if (en) q <= d;
endmodule
               clk
                      [3:0]
                             [3:0]
                                              [<u>3</u>:0] [3:0]
                                  D[3:0]
                                                      q[3:0]
              d[3:0]
                                        Q[3:0]
                en
                                      R
              reset
```

q[3:0]

### Latch

endmodule



**Warning**: We don't use latches in this text. But you might write code that inadvertently implies a latch. Check synthesized hardware – if it has latches in it, there's an error.

### Other Behavioral Statements

- Statements that must be inside always statements:
  - if / else
  - case, casez



# Combinational Logic using always

```
// combinational logic using an always statement
module gates(input logic [3:0] a, b,
            output logic [3:0] y1, y2, y3, y4, y5);
 always_comb // need begin/end because there is
           // more than one statement in always
   begin
     y1 = a \& b; // AND
     y2 = a \mid bi // OR
     y3 = a ^b; // XOR
     y4 = \sim (a \& b); // NAND
     y5 = ~(a | b); // NOR
   end
endmodule
```

This hardware could be described with assign statements using fewer lines of code, so it's better to use assign statements in this case.

# Combinational Logic using case

```
module sevenseq(input logic [3:0] data,
                output logic [6:0] segments);
  always_comb
    case (data)
                              abc_defg
      //
                           7'b111 1110;
      0: segments =
      1: segments =
                           7'b011 0000;
      2: segments =
                           7'b110 1101;
      3: segments =
                           7'b111 1001;
      4: segments =
                           7'b011_0011;
      5: segments =
                           7'b101 1011;
      6: segments =
                           7'b101 1111;
      7: segments =
                           7'b111_0000;
                          7'b111_1111;
      8: segments =
      9: segments =
                          7'b111 0011;
      default: segments = 7'b000 0000; // required
    endcase
endmodule
```



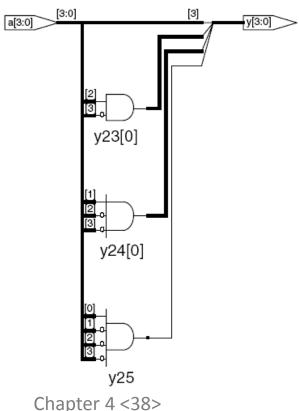
## Combinational Logic using case

- case statement implies combinational logic only if all possible input combinations described
- Remember to use **default** statement



# Combinational Logic using casez

```
module priority_casez(input logic [3:0] a,
                      output logic [3:0] y);
  always_comb
    casez(a)
      4'b1???: y = 4'b1000; // ? = don't care
      4'b01??: y = 4'b0100;
      4'b001?: y = 4'b0010;
      4'b0001: y = 4'b0001;
      default: y = 4'b0000;
   endcase
endmodule
```

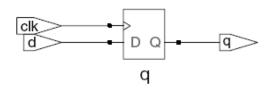




#### Blocking vs. Nonblocking Assignment

- <= is nonblocking assignment</p>
  - Occurs simultaneously with others
- = is blocking assignment
  - Occurs in order it appears in file

```
// Bad synchronizer using
// blocking assignments
c clk, module syncbad(input logic clk,
c d, input logic d,
c q); output logic q);
logic n1;
always_ff @(posedge clk)
begin
sing n1 = d; // blocking
q = n1; // blocking
end
endmodule
```





## Rules for Signal Assignment

Synchronous sequential logic: use always\_ff
 @(posedge clk) and nonblocking assignments
 (<=)</li>
 always\_ff @ (posedge clk)
 q <= d; // nonblocking</li>

• Simple combinational logic: use continuous assignments (assign...)

```
assign y = a \& b;
```

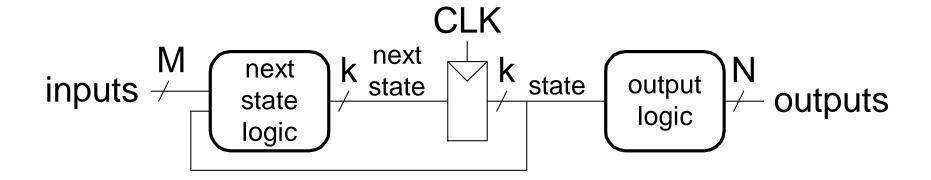
- More complicated combinational logic: use always\_comb and blocking assignments (=)
- Assign a signal in **only one** always statement or continuous assignment statement.



## Finite State Machines (FSMs)

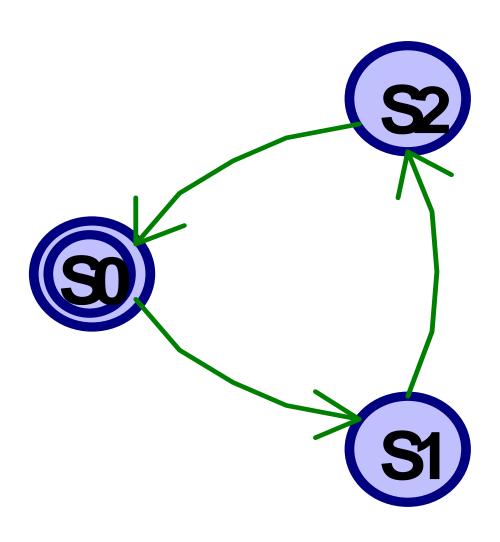
#### • Three blocks:

- next state logic
- state register
- output logic





# FSM Example: Divide by 3



The double circle indicates the reset state



# FSM in SystemVerilog

```
module divideby3FSM (input logic clk,
                     input logic reset,
                     output logic q);
   typedef enum logic [1:0] {S0, S1, S2} statetype;
   statetype [1:0] state, nextstate;
   // state register
   always_ff @ (posedge clk, posedge reset)
      if (reset) state <= S0;
      else
                 state <= nextstate;
   // next state logic
   always_comb
      case (state)
                  nextstate = S1;
         S0:
         S1:
                  nextstate = S2;
         S2:
                  nextstate = S0;
         default: nextstate = S0;
      endcase
  // output logic
   assign q = (state == S0);
endmodule
```



#### Parameterized Modules

#### 2:1 mux:

#### Instance with 8-bit bus width (uses default):

```
mux2 myMux(d0, d1, s, out);
```

#### Instance with 12-bit bus width:

```
mux2 #(12) lowmux(d0, d1, s, out);
```



#### Testbenches

- HDL that tests another module: device under test (dut)
- Not synthesizeable
- Types:
  - Simple
  - Self-checking
  - Self-checking with testvectors



## Testbench Example

 Write SystemVerilog code to implement the following function in hardware:

$$y = \overline{b}\overline{c} + a\overline{b}$$

Name the module sillyfunction



## Testbench Example

 Write SystemVerilog code to implement the following function in hardware:

$$y = \overline{b}\overline{c} + a\overline{b}$$



## Simple Testbench

```
module testbench1();
  logic a, b, c;
  logic y;
  // instantiate device under test
  sillyfunction dut(a, b, c, y);
  // apply inputs one at a time
  initial begin
    a = 0; b = 0; c = 0; #10;
    c = 1; #10;
    b = 1; c = 0; #10;
    c = 1; #10;
    a = 1; b = 0; c = 0; #10;
    c = 1; #10;
    b = 1; c = 0; #10;
    c = 1; #10;
  end
endmodule
```



# Self-checking Testbench

```
module testbench2();
  logic a, b, c;
  logic y;
  sillyfunction dut(a, b, c, y); // instantiate dut
  initial begin // apply inputs, check results one at a time
    a = 0; b = 0; c = 0; #10;
    if (y !== 1) $display("000 failed.");
    c = 1; #10;
    if (y !== 0) $display("001 failed.");
    b = 1; c = 0; #10;
    if (y !== 0) $display("010 failed.");
    c = 1; #10;
    if (y !== 0) $display("011 failed.");
    a = 1; b = 0; c = 0; #10;
    if (y !== 1) $display("100 failed.");
    c = 1; #10;
    if (y !== 1) $display("101 failed.");
    b = 1; c = 0; #10;
    if (y !== 0) $display("110 failed.");
    c = 1; #10;
    if (y !== 0) $display("111 failed.");
  end
endmodule
```



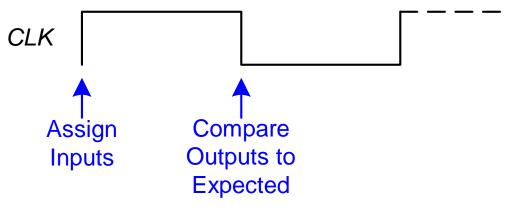
#### Testbench with Testvectors

- Testvector file: inputs and expected outputs
- Testbench:
  - 1. Generate clock for assigning inputs, reading outputs
  - 2. Read testvectors file into array
  - 3. Assign inputs, expected outputs
  - 4. Compare outputs with expected outputs and report errors



#### Testbench with Testvectors

- Testbench clock:
  - assign inputs (on rising edge)
  - compare outputs with expected outputs (on falling edge).



 Testbench clock also used as clock for synchronous sequential circuits



#### Testvectors File

- File: example.tv
- contains vectors of abc\_yexpected

```
000_1
001_0
010_0
011_0
```

101\_1

100\_1

110\_0

111\_0



#### 1. Generate Clock

```
module testbench3();
 logic
        clk, reset;
 logic
        a, b, c, yexpected;
 logic
              y;
 logic [31:0] vectornum, errors; // bookkeeping variables
 logic [3:0] testvectors[10000:0]; // array of testvectors
  // instantiate device under test
  sillyfunction dut(a, b, c, y);
  // generate clock
 always
            // no sensitivity list, so it always executes
   begin
     clk = 1; #5; clk = 0; #5;
   end
```



### 2. Read Testvectors into Array

```
// at start of test, load vectors and pulse reset
initial
   begin
      $readmemb("example.tv", testvectors);
      vectornum = 0; errors = 0;
      reset = 1; #27; reset = 0;
    end
// Note: Sreadmemh reads testvector files written in
// hexadecimal
```



#### 3. Assign Inputs & Expected Outputs

```
// apply test vectors on rising edge of clk
always @(posedge clk)
  begin
  #1; {a, b, c, yexpected} = testvectors[vectornum];
  end
```



#### 4. Compare with Expected Outputs

```
// check results on falling edge of clk
  always @(negedge clk)
  if (~reset) begin // skip during reset
    if (y !== yexpected) begin
        $display("Error: inputs = %b", {a, b, c});
        $display(" outputs = %b (%b expected)",y,yexpected);
        errors = errors + 1;
    end

// Note: to print in hexadecimal, use %h. For example,
        $display("Error: inputs = %h", {a, b, c});
```



### 4. Compare with Expected Outputs

```
// increment array index and read next testvector
      vectornum = vectornum + 1;
      if (testvectors[vectornum] === 4'bx) begin
          $display("%d tests completed with %d errors",
                vectornum, errors);
        $finish;
      end
    end
endmodule
// ===  and !==  can compare values that are 1, 0, x, or z.
```

