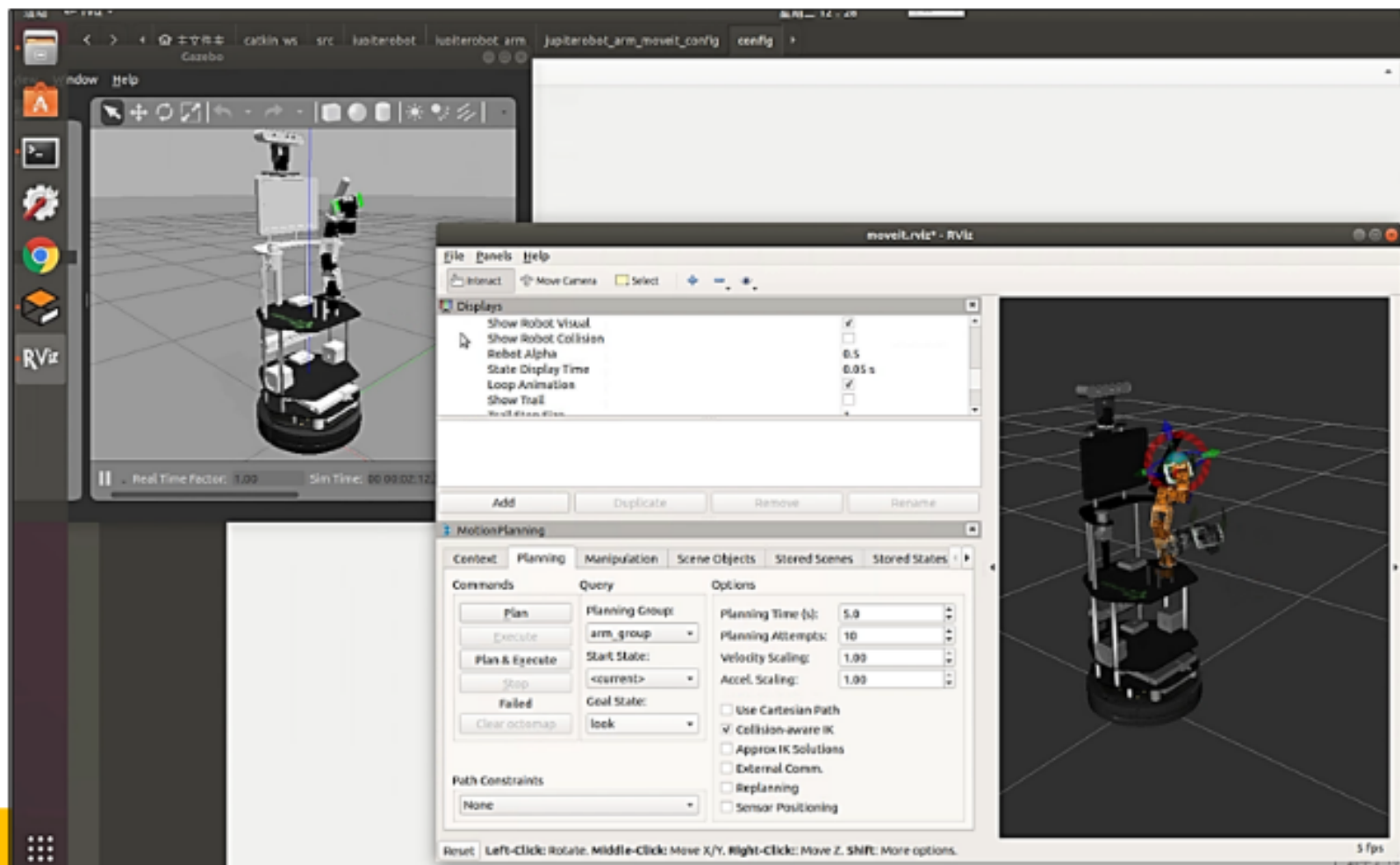


ROBOT ARM WITH MOVEIT

Robot Arm with MoveIt

- `$ roslaunch jupiterobot_arm_moveit_config demo_gazebo.launch`



Exercise: Waving Arm

1. Develop a waving arm movement
 - Refer to the `dance_arm` sample code