

Speed X3



## ONLINE API AND CHATBOT APPLICATION

# Online API and Chatbot Application

- Xunfei - <https://www.xfyun.cn/>
- TTS Speech Synthesis [online]
  - `$ roscore`
  - `$ rosrun xfei_asr tts_subscribe_speak`
  - `$ rostopic pub xfwords std_msgs/String "hello world"`
- Speech Recognition [online]
  - `$ roscore`
  - `$ rosrun xfei_asr iat_record`
- Simple Chatbot Development
  - TalkBack: `rchomeedu_speech/scripts/talkback.py`
  - PartyBot: `rchomeedu_apps/rchomeedu_partybot/scripts/partybot.py`

# Google Text-to-Speech [online]

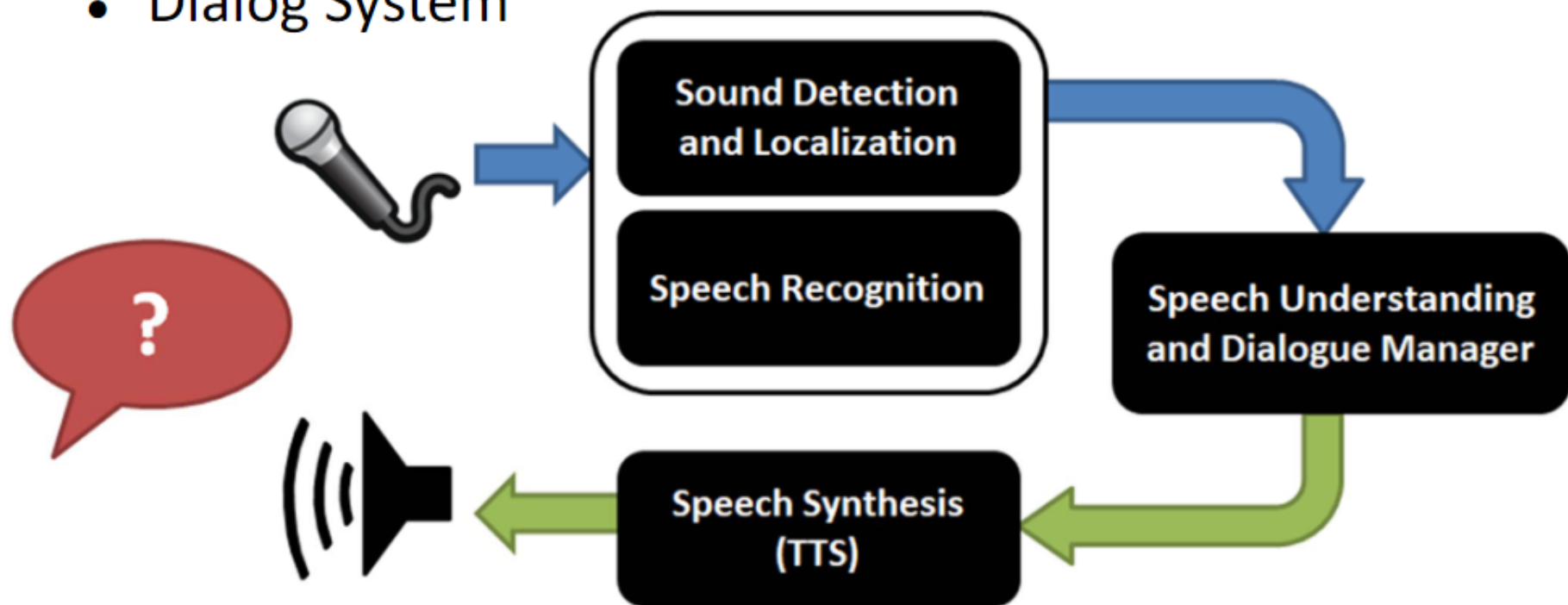
- gTTS – <https://pypi.org/project/gTTS/>
- Documentation – <http://gtts.readthedocs.org/>
- Setup
  - \$ pip install gTTS
  - \$ sudo apt-get install mpg321
- Sample code and execution
  - \$ roscore
  - \$ rosrun rchomeedu\_speech **google\_tts.py**
  - \$ rostopic pub -1 /input std\_msgs/String "hello world"

# Google Speech Recognition [online]

- SpeechRecognition –  
<https://pypi.org/project/SpeechRecognition/>
- Setup
  - \$ pip install SpeechRecognition
- Sample code and execution
  - \$ roscore
  - \$ rosrun rchomeedu\_speech **google\_sr.py**
  - \$ rostopic echo /result

# More Speech Interaction

- Other Language Support
- Sound Detection and Localization
- Speech Understanding and Dialogue Manager
- Dialog System



# Exercise: Location Commands

1. Create a new vocabulary for location commands using lm mode (language model mode).
  - Location examples: Kitchen, living room, bedroom, dining room.
2. Create a new node to subscribe to the lm\_data topic and display the data in the terminal.