

Research Progress Report

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February 25, 2019

1 Reading and Research Activities

1.1 Reading Summary

The existing networks structure and traffic control mechanisms are not adequate to cope with exponential increase in volume and complexity of the network traffic. [1] proposed a reward based deep learning structure which jointly performs traffic load prediction and value based final action decision to control the network traffic in an intelligent manner to address the issues.

For the supervised deep learning, some researchers proposed to train the network for packets forwarding based on labeled traffic data. However, the labeled traffic data are difficult to collect. In the non-supervised learning, the paths combinations are considered as the action space of the training process to choose the better action based on the action reward of each iteration. Such kind of path selection and action space design is reasonable only when the number of paths combination is finite. In order to solve the above issue, [1] employs the set of next candidate forwarding destinations as the action space, and migrate the action decision process from the centralized controller to each distributed node. In addition, the reward are constructed as a vector to fit for the upcoming time sequences, which is able to more accurately measure the temporal connections between the selected action and get better computational cost performance than contemporary deep learning approaches.

- System model and action space format

The topology of the considered network is a fully connected graph $G = (CR \cup AP, E)$, where CR denotes the set of core routers in the network, $CR = \{cr_1, cr_2, \dots, cr_{|CR|}\}$. AP denotes the set of access points, $AP = (ap_1, ap_2, \dots, ap_{|AP|})$, $N = |CR| + |AP|$, the total number of nodes, E denotes the set of connection edges between all nodes.

The action spaces is modeled and calculated as an algorithm complexity problem. Assuming the complexity of a single neural network is $O(1)$,

1.2 Course Summary

1.2.1 Network Performance Analysis

They compared the proposed deep learning method with OSPF by the network signaling overhead, throughput and average delay.

2 Objectives for the Next 2 Weeks

2.1 Reading

Reading papers focused on ML-based or DL-based routing.

2.2 Course

Studying chapter 1 and chapter 2 of Neural Networks and Deep Learning, **Coursera**. <https://www.coursera.org/learn/neural-networks-deep-learning>

2.3 Code

Designing the following WSN model, the packets of N1 are forwarded to the next node, N3 or N4, via N2 which has a ML model. So, in this model, the routing problem can be simply simulated as a two-class problem.

Simulation goal:

1. Learn how to build WSN by NS3
2. Explore how to add ML model in network nodes.
3. Learn how to extract network features as input layer.
4. Learn how to model routing search as problems of machine learning.

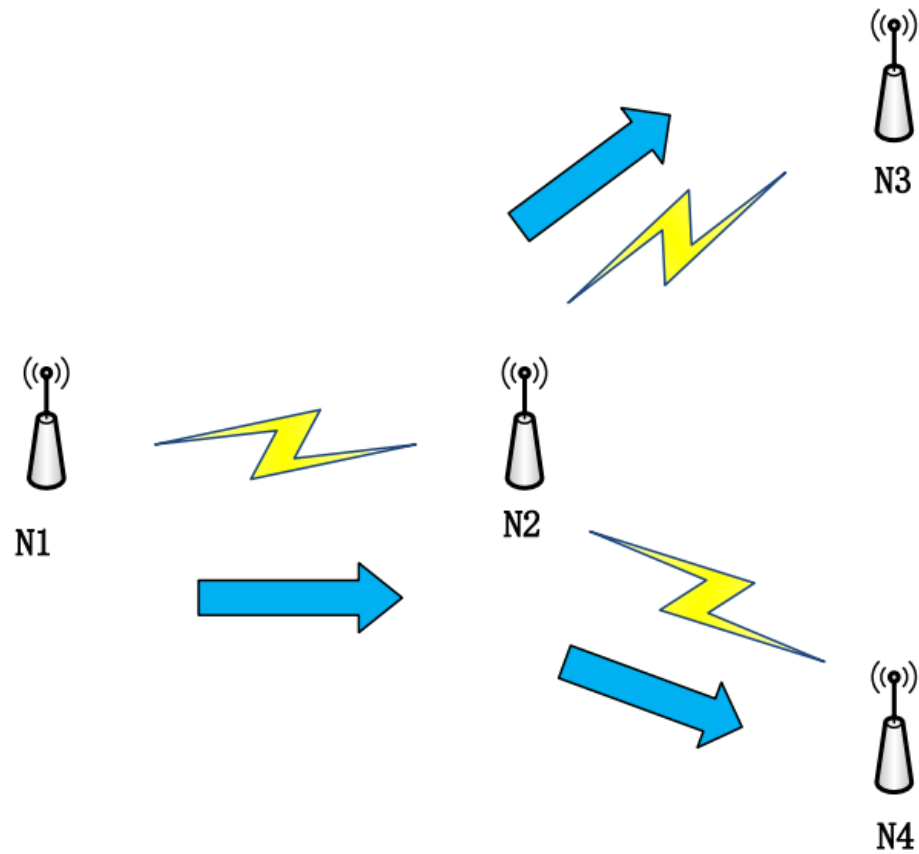


Figure 1: ML-based WSN model

3 Advisor's Comments

Bibliography

- [1] Z. Md. Fadlullah, F. Tang, B. Mao, J. Liu, and N. Kato, “On intelligent traffic control for large-scale heterogeneous networks: A value matrix-based deep learning approach,” *IEEE Communications Letters*, vol. 22, no. 12, pp. 2479–2482, Dec 2018.