

# IEC 61499: primer course

**Module 0: Motivations and Origins**

Valeriy Vyatkin

Luleå University of Technology and Aalto University



# What is IEC 61499?

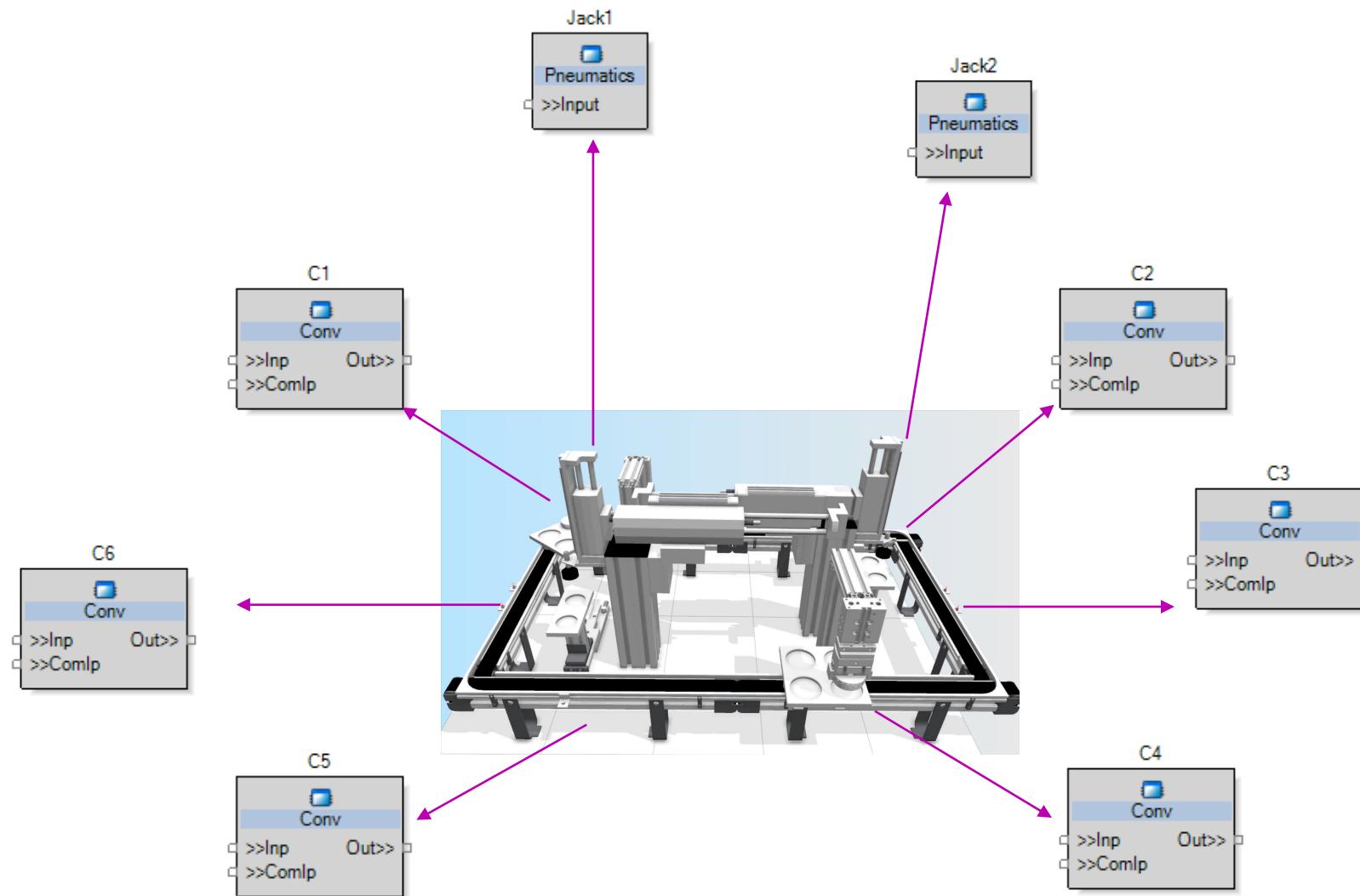
# Example: Assembly system model

- Mechatronic modularity
- Layout changes during the production process to flexibly accommodate new order
- Wireless communication
- Totally distributed hardware control architecture



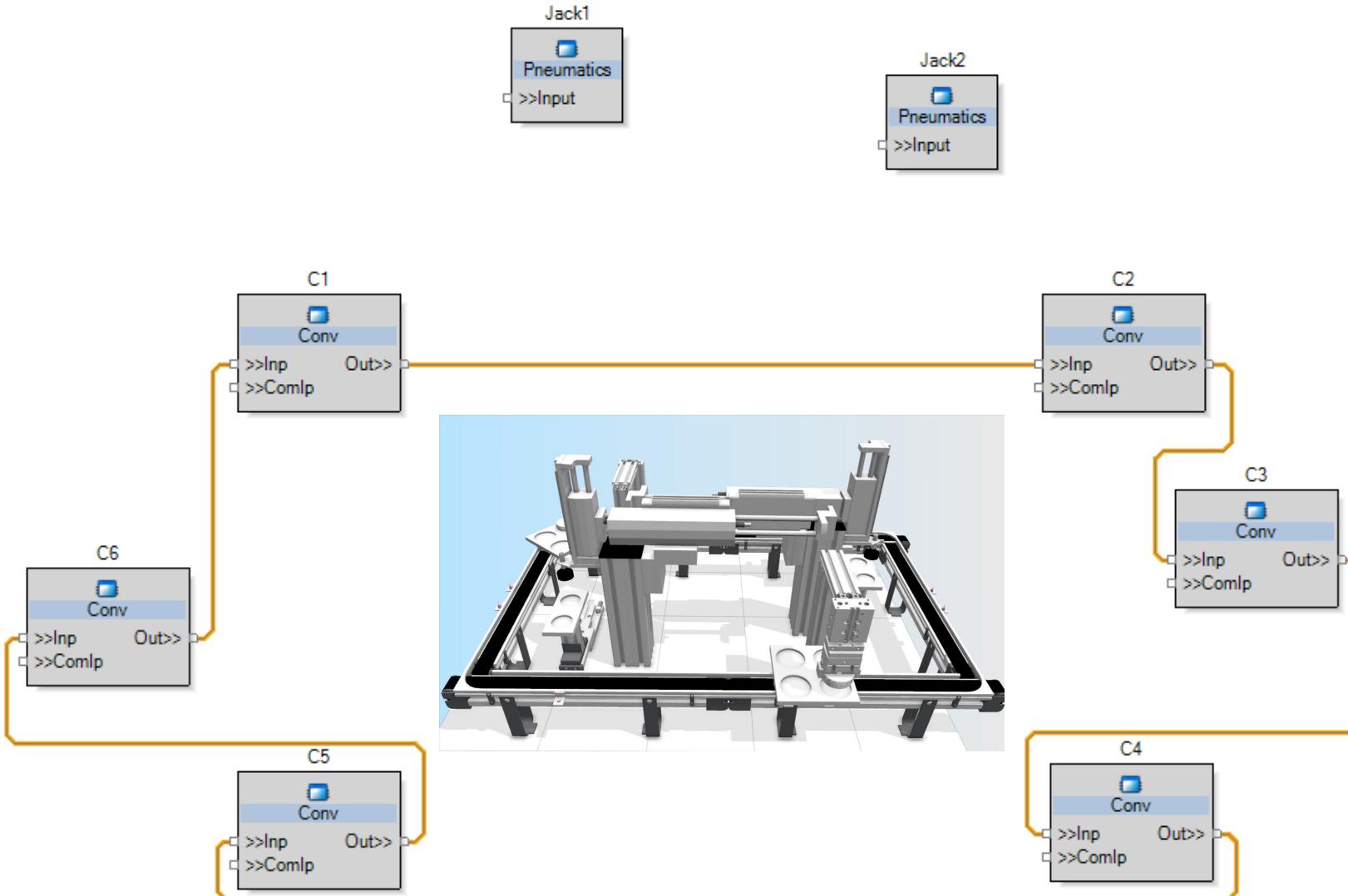
# Object-based design

Each function block type corresponds to a mechatronic component type.

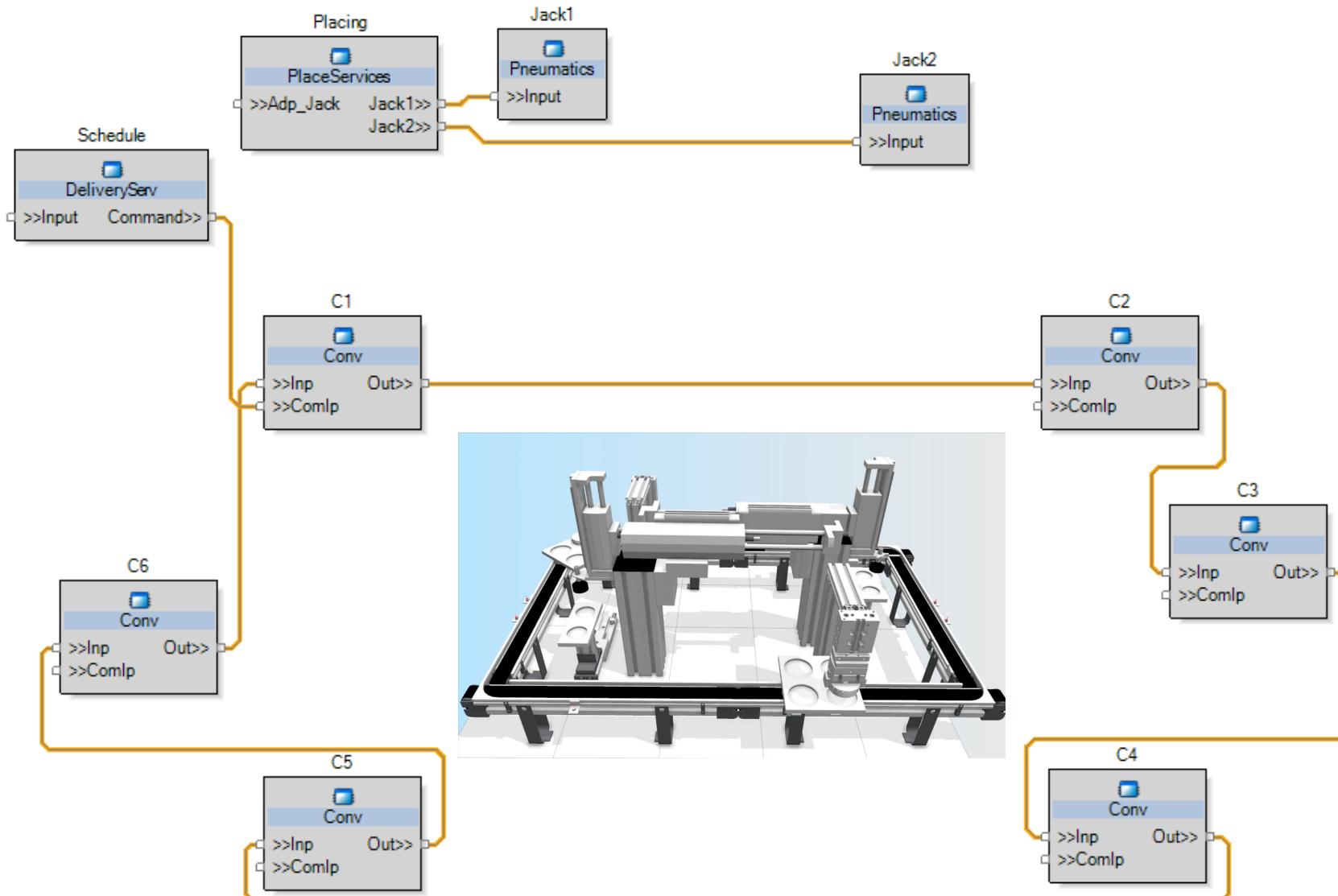


Each function block type implements basic control services for the mechatronic component.

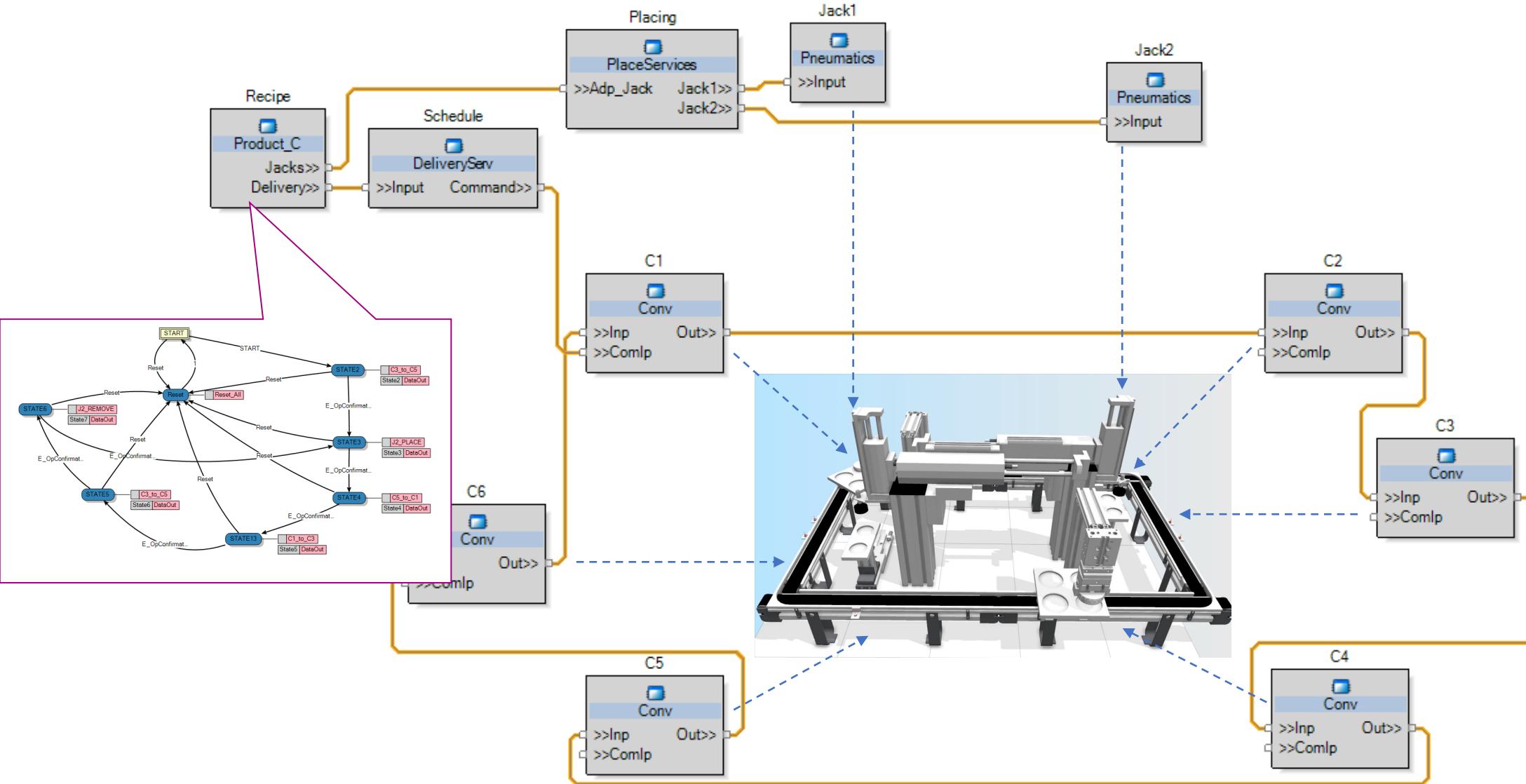
# Programming with Function Blocks



# Programming with Function Blocks



# Programming with Function Blocks

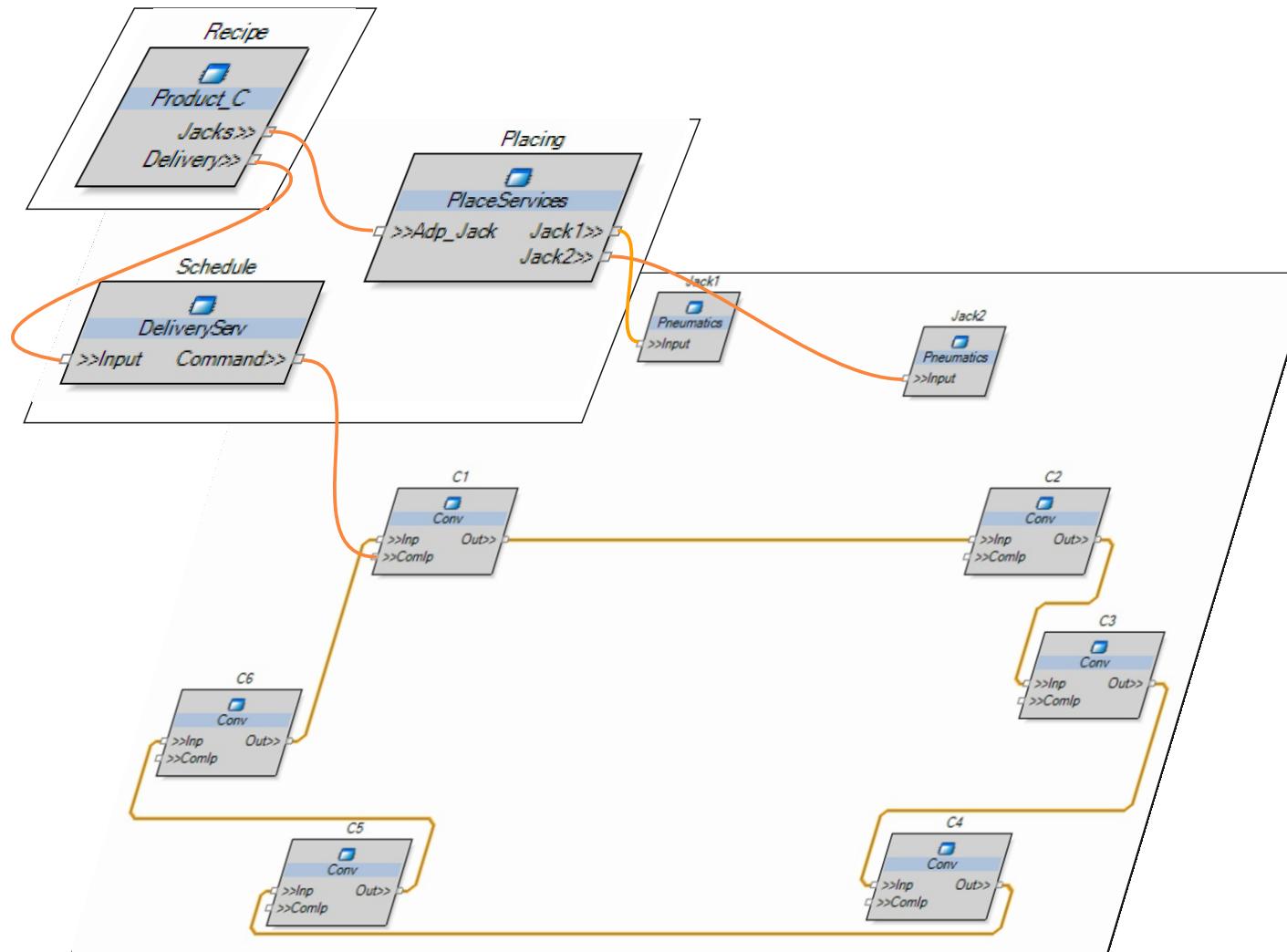


# Layered services architecture

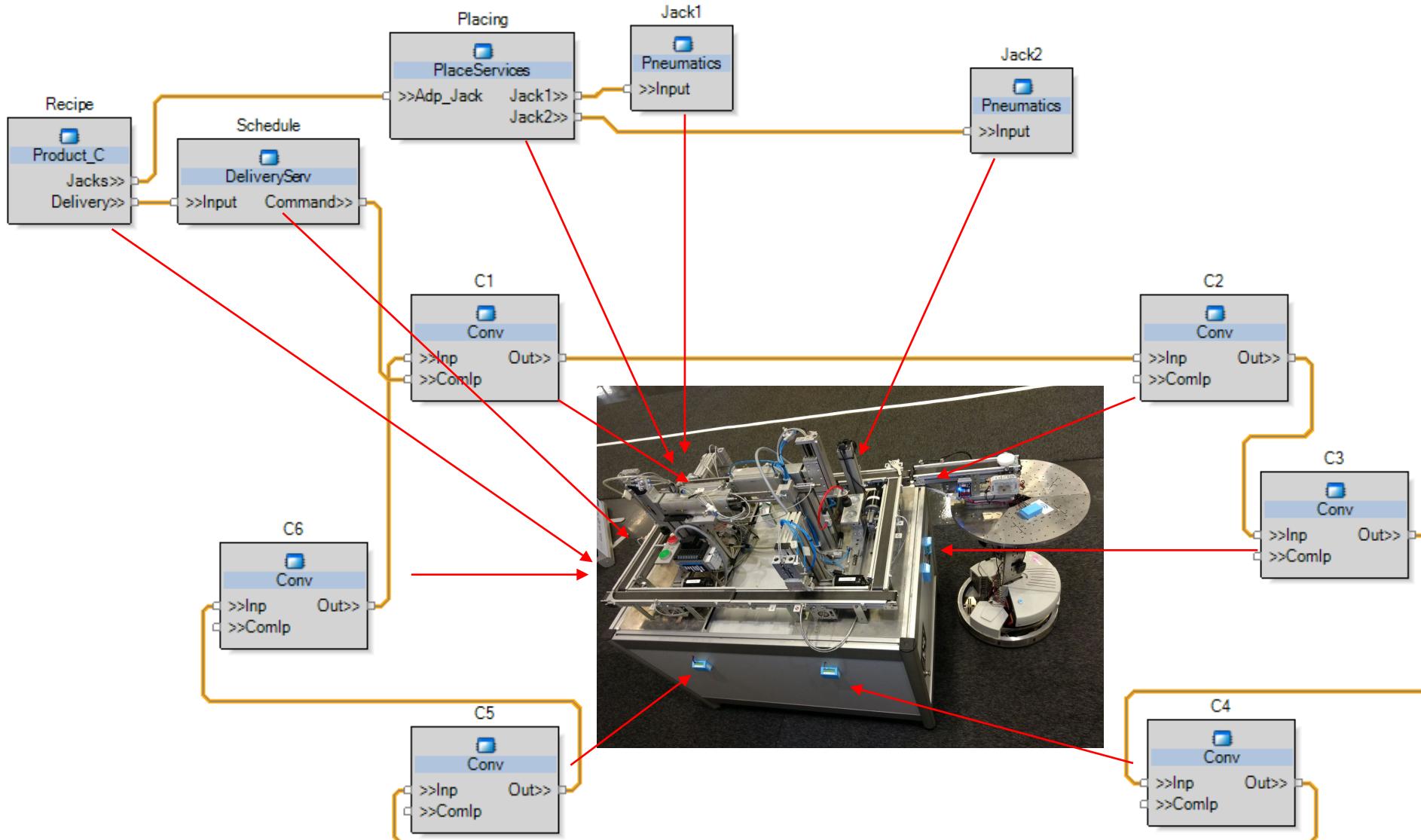
Product  
description  
layer

Planning  
services layer

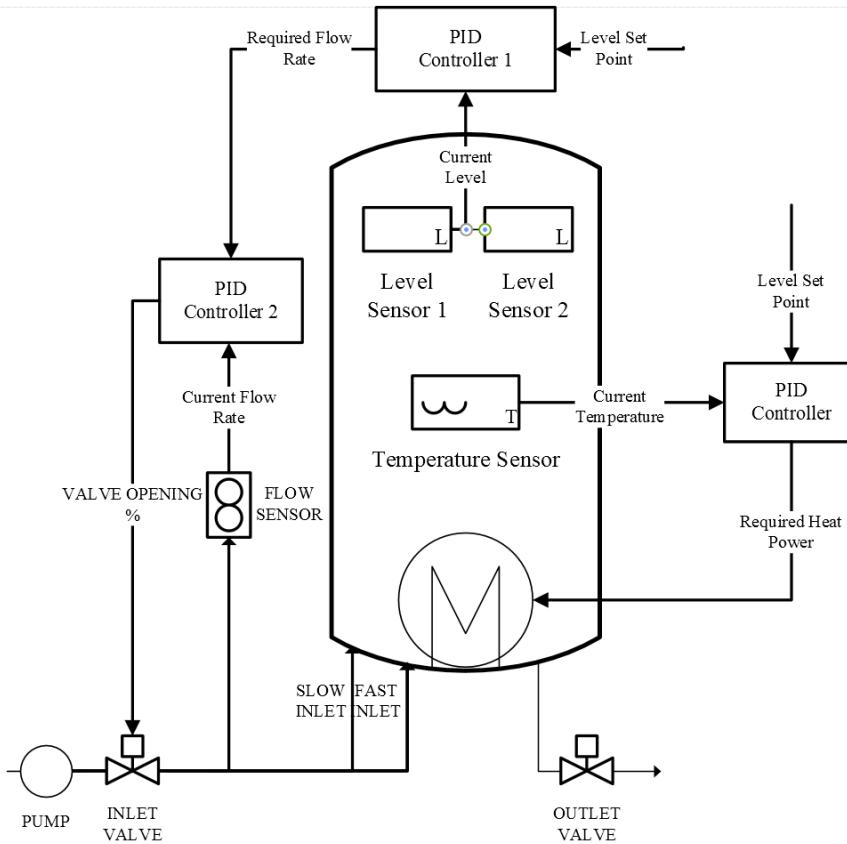
Execution  
services layer



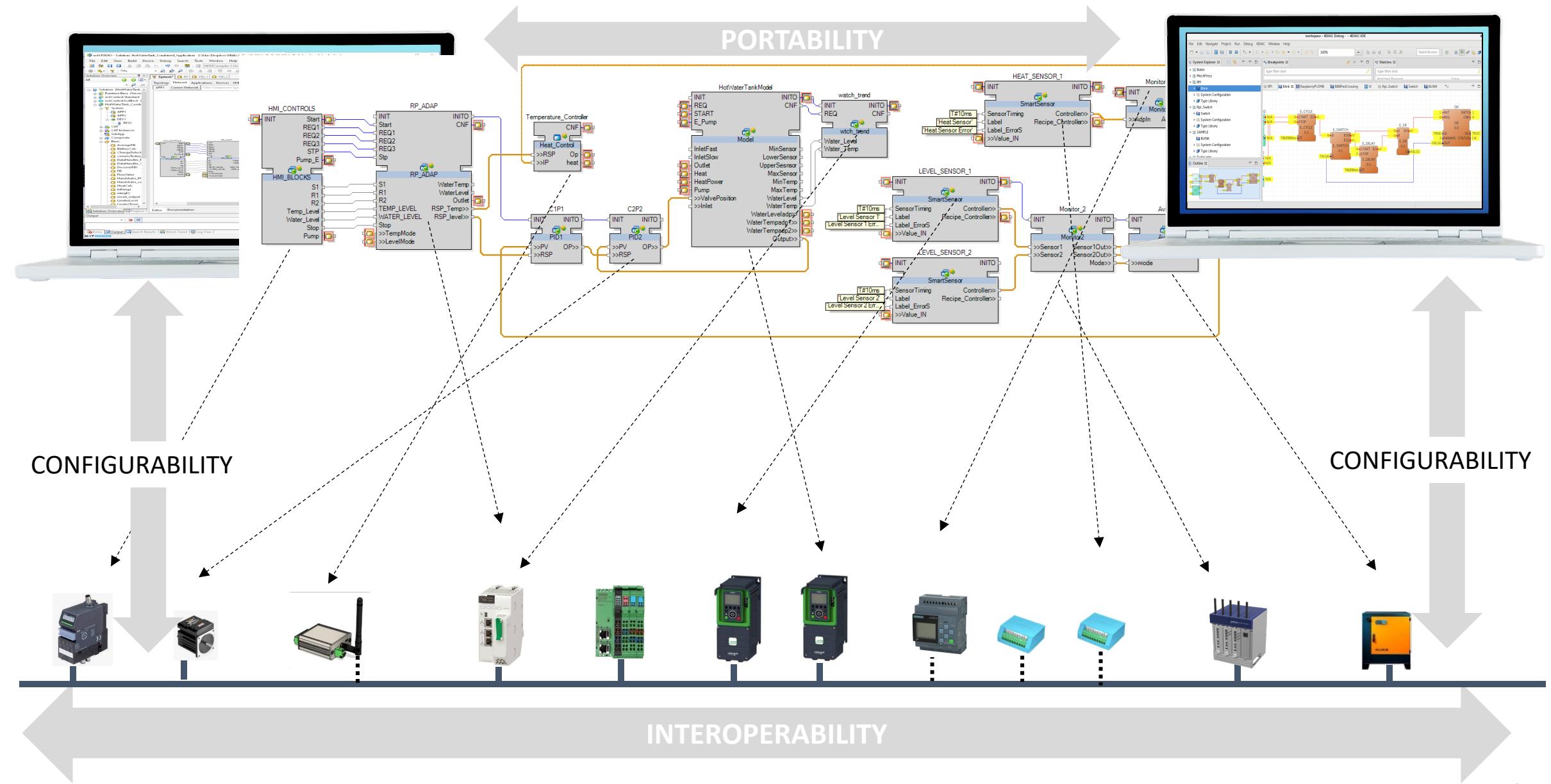
# Distributed deployment



# What is IEC 61499?



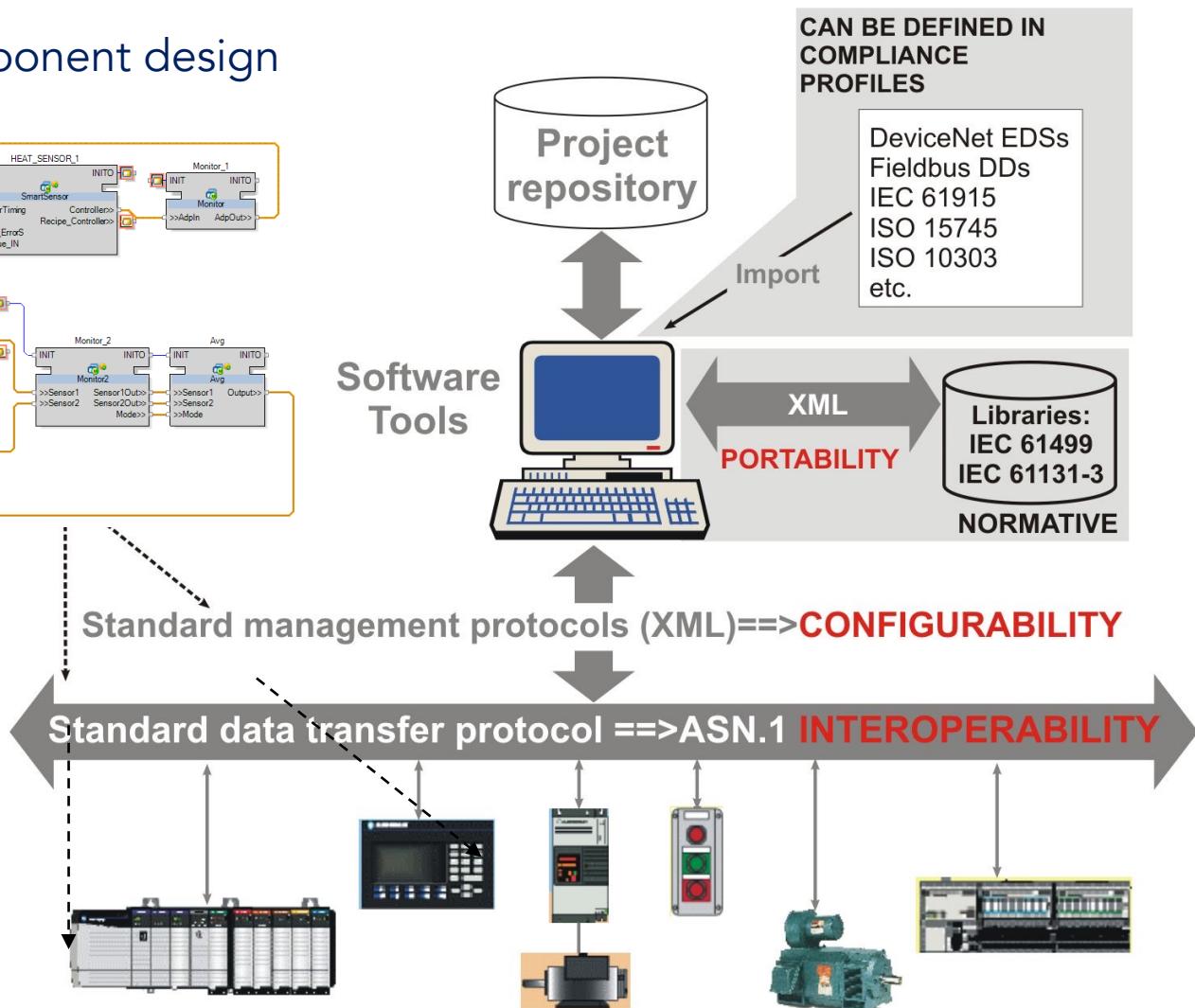
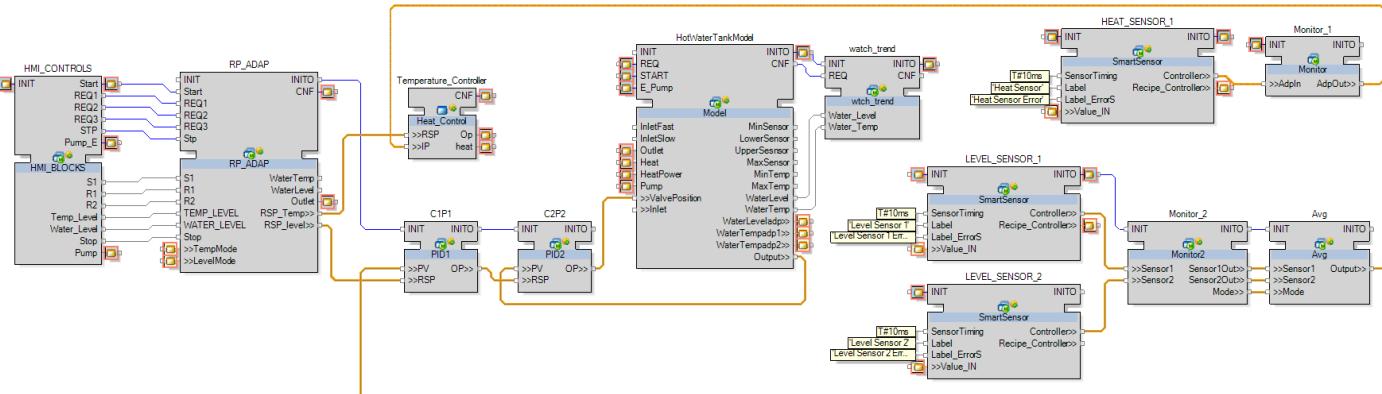
# What is IEC 61499?



# How does IEC61499 address the needs?

## Open Distributed Automation Architecture

Extends IEC 61131 PLC programming with a component design language for distributed automation systems



Distributed Intelligent Devices and Controllers

# IEC 61499 International Standard

International Electrotechnical Commission IEC TC 65B/ WG7/ MT15

A component-based, open reference architecture for

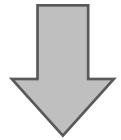
**Distributed Industrial - Process Measurement & Control Systems (IPMCS)**

which can meet both current and future requirements for intelligent automation

1992 – project started

2005 – first edition

2011 – second edition



Based on and  
extends the  
standards



PLC Function Blocks (IEC 61131-3)

DCS Function Blocks (IEC 61804 project)

# IEC61499 ingredients

- Extends PLC programming languages of IEC 61131-3 to distributed systems design
- Uses visual block-diagram representation for component-based design
- Uses state-machines for defining components' logic
- Components communicate via message passing
- All these features are common in engineering of automation and embedded systems, in IEC 61499 they are brought making powerful engineering framework for modern automation needs

# Origins

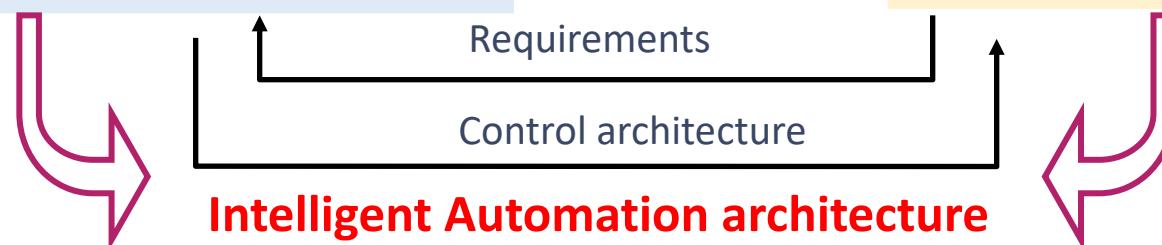
# Architectural Co-Evolution

## IEC 61499

- Parent organization: IEC
- Working group: TC65/WG6
- Goal: Standard model (function blocks) for control encapsulation & distribution
- Started: 10/90
- Active development: 3/92
- Trial period: 2001-03
- Completion: 2005

## Holonic Manufacturing Systems (HMS)

- Parent organization: IMS
- Working group: HMS Consortium
- Goal: Intelligent manufacturing through holonic (autonomous, cooperative) modules
- Feasibility study: 3/93-6/94
- First phase: 2/96 - 6/00
- Second phase: 6/00-6/03

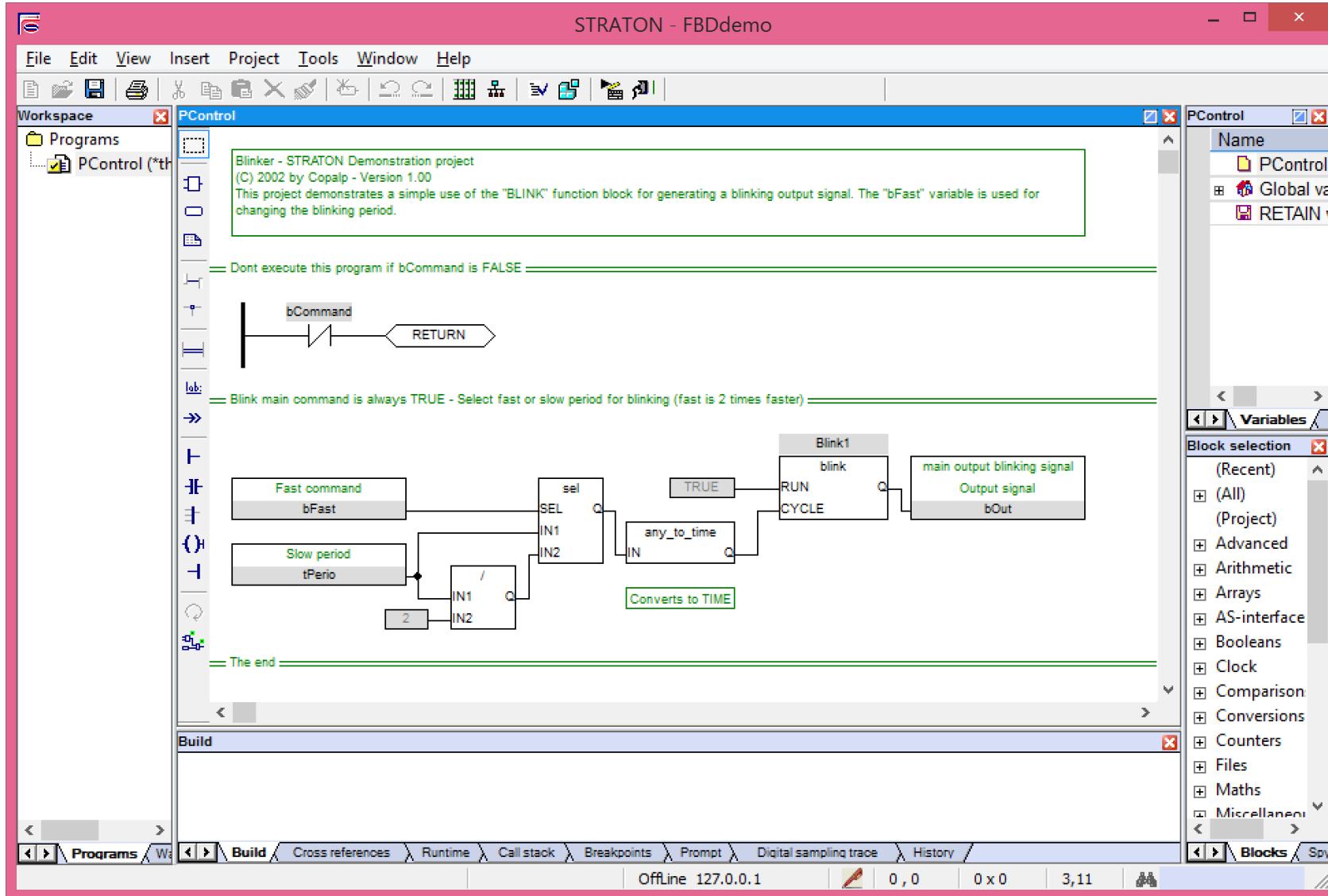


# **Origins/block diagram programming**

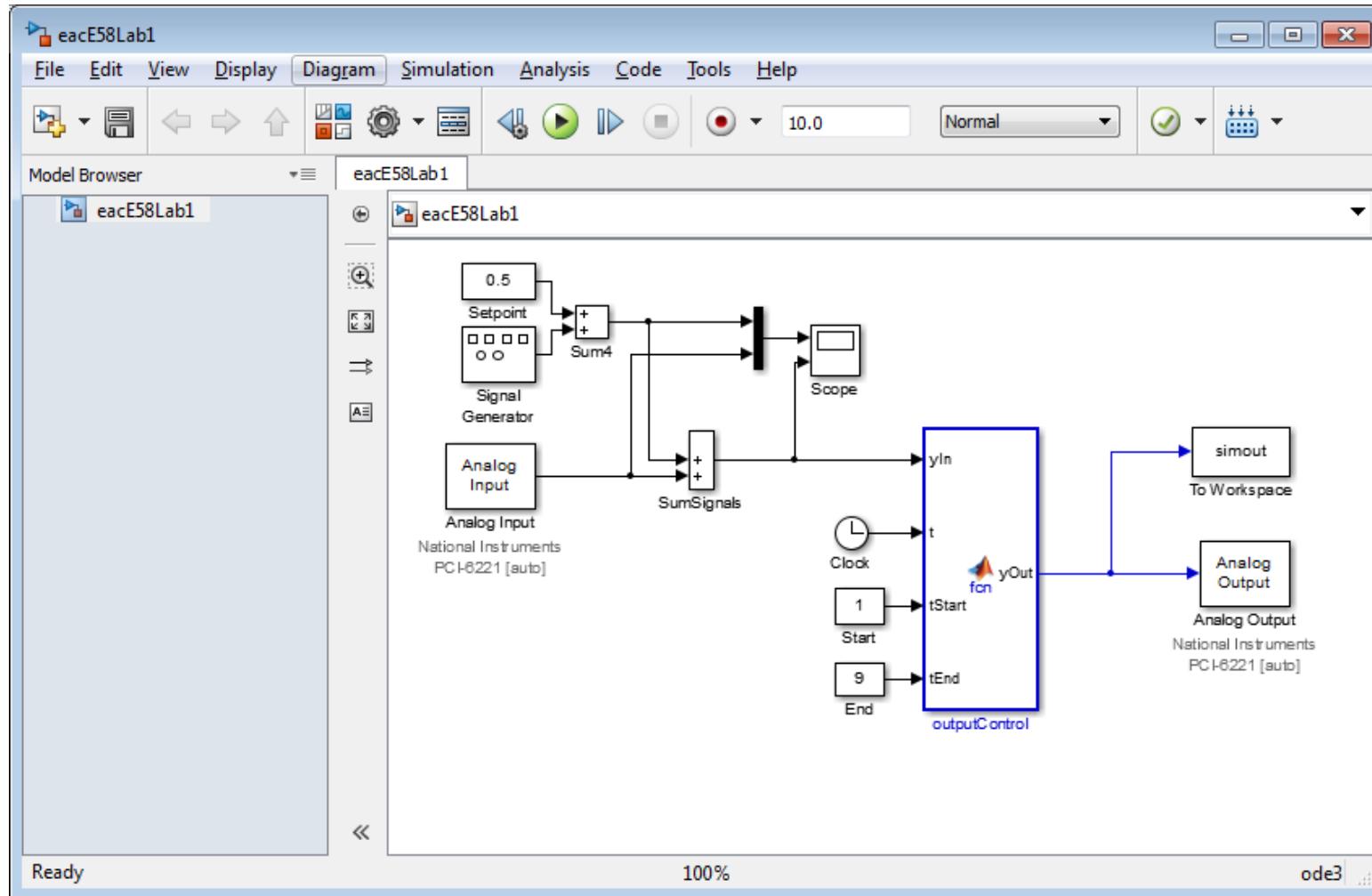
# Block diagrams as a programming language

- Block diagrams is a convenient abstraction for representing component-based engineering
- It is used widely in Industrial Automation, Embedded systems, Cyber-Physical Systems, including automotive and aerospace

# Block Diagram Programming in Automation

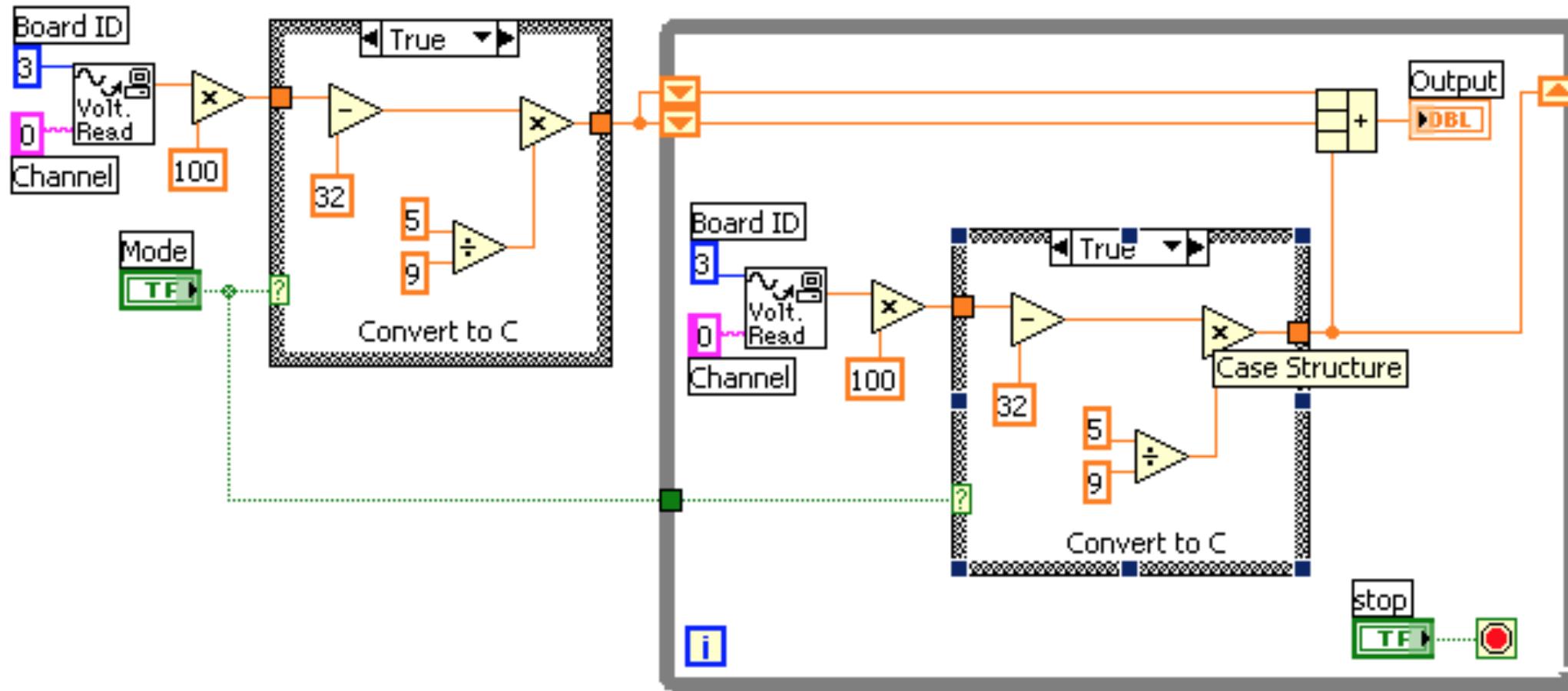


# Matlab / Simulink

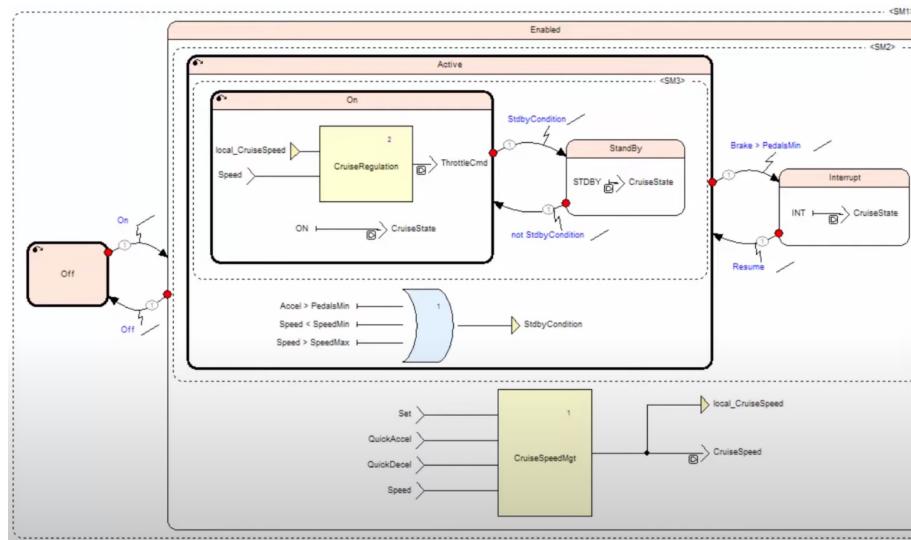
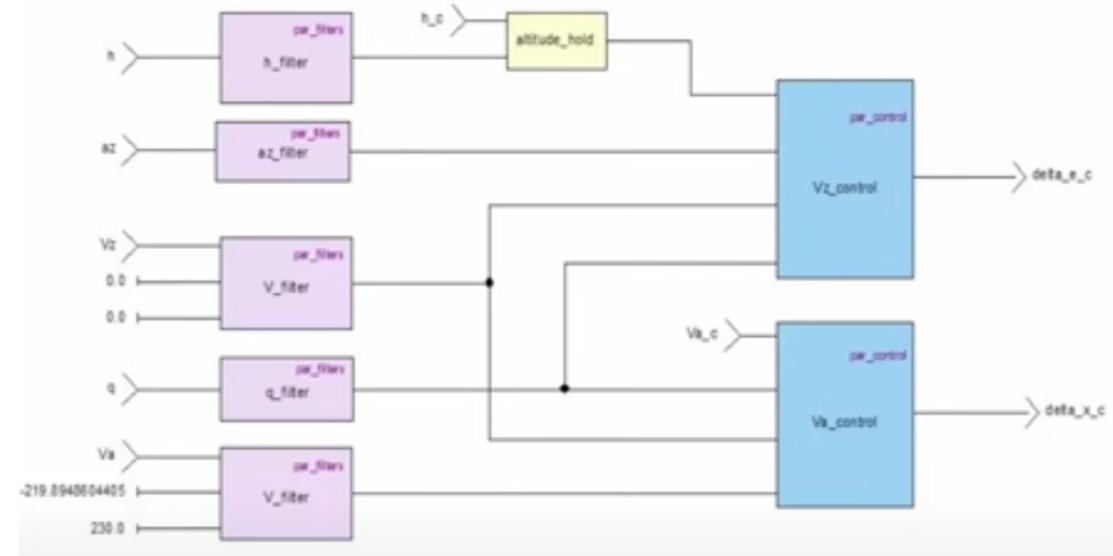
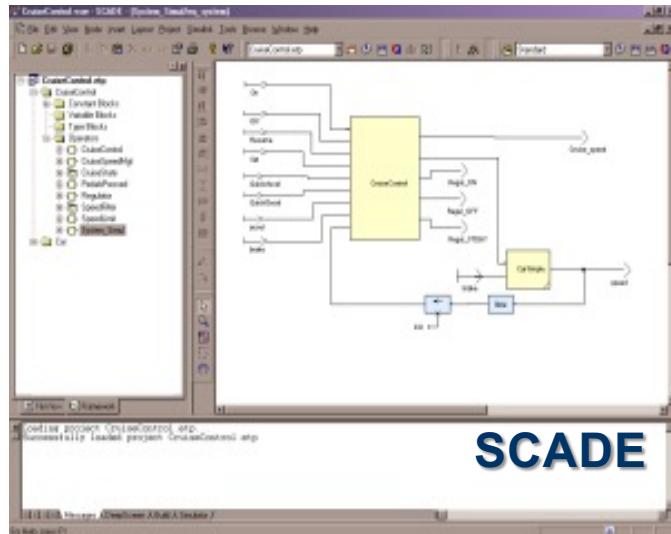


- Block diagrams is a convenient way of defining systems' functionality.
- It is quite standard in control systems engineering and in modelling.

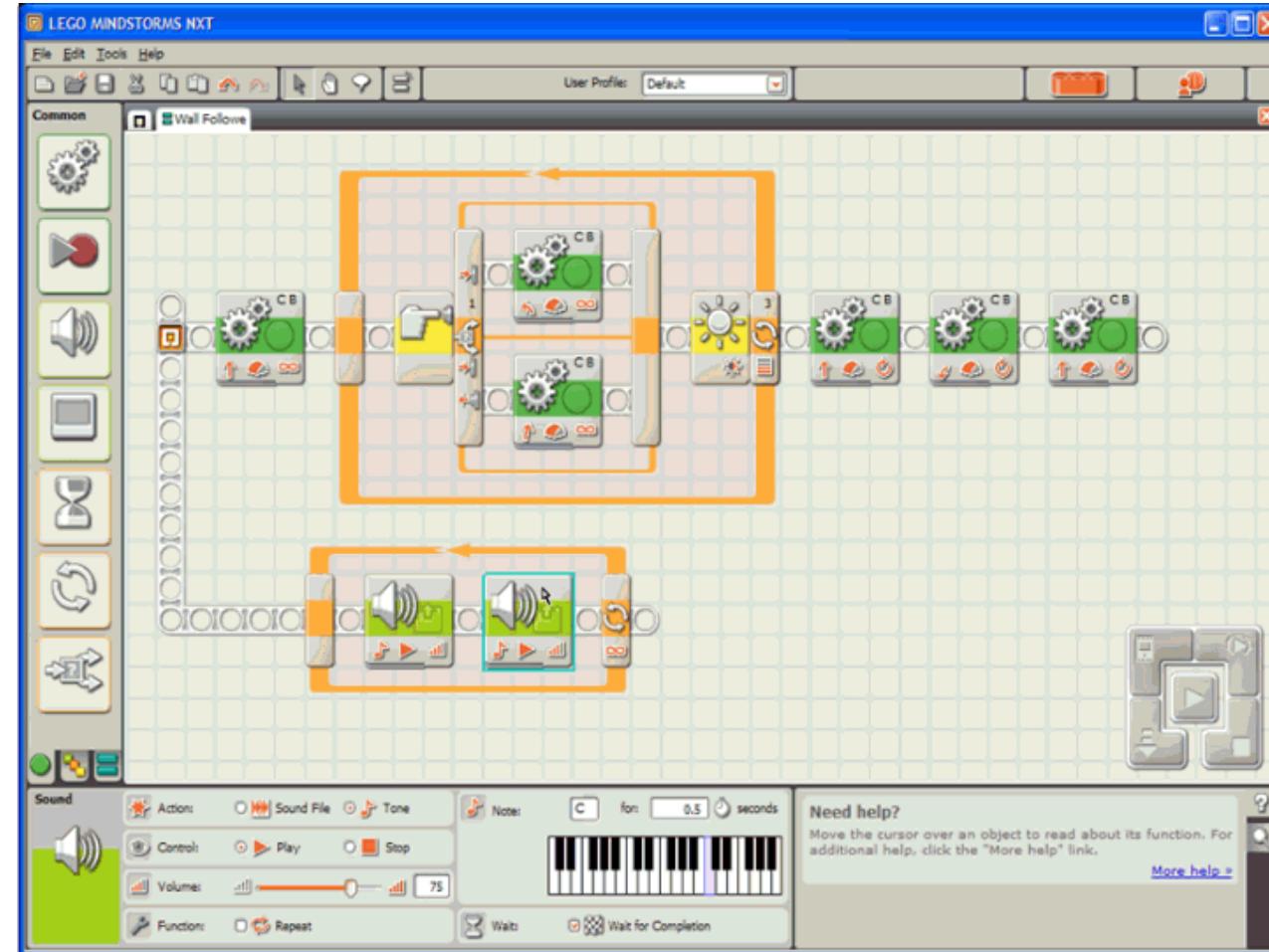
# LabView



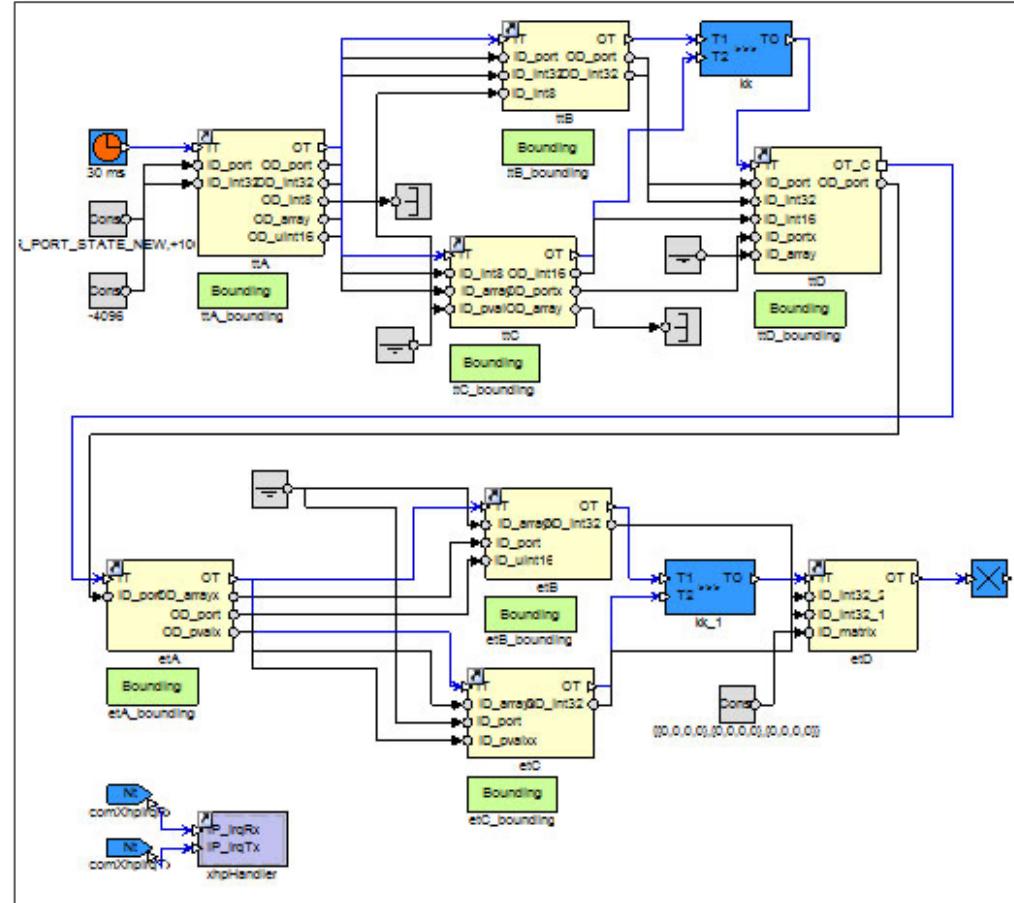
# Ansys SCADE



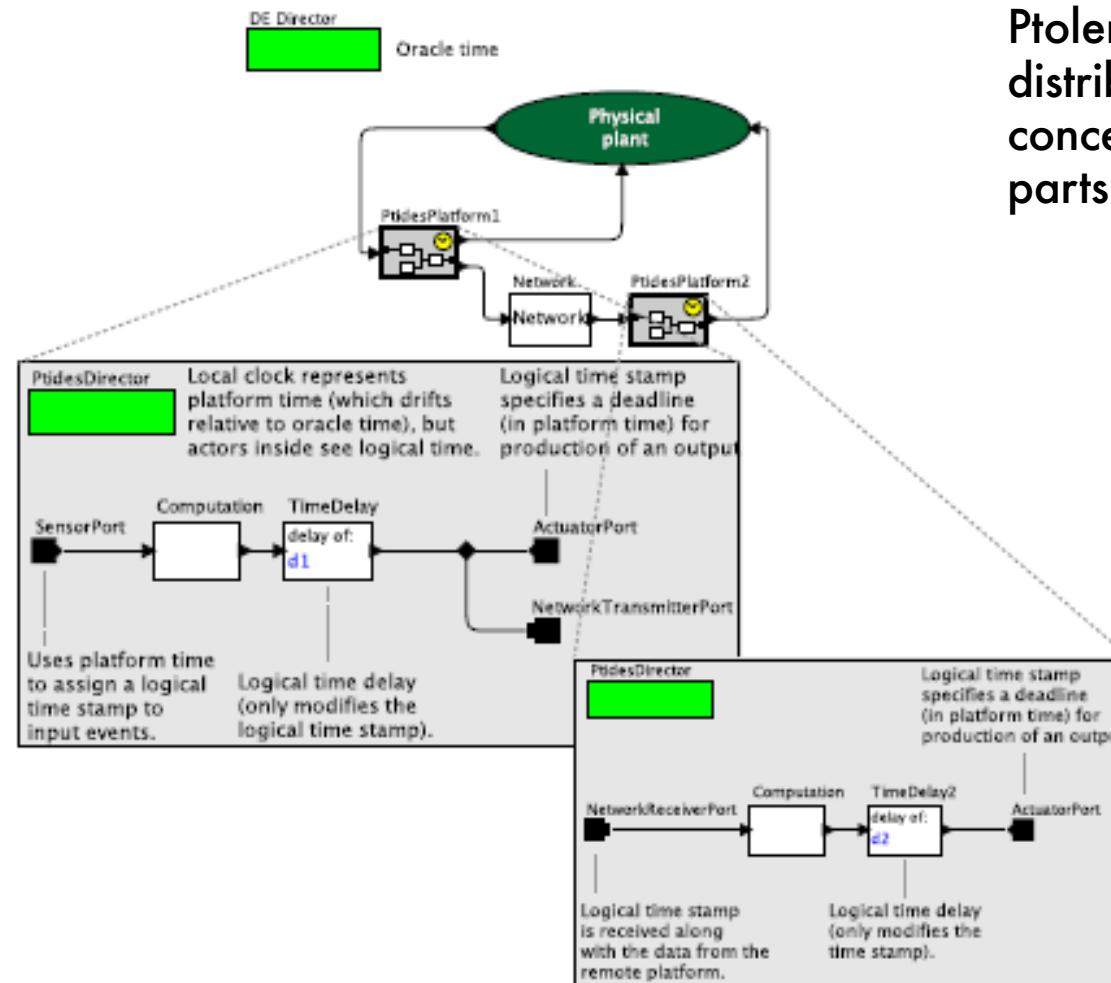
# Lego MindStorm



# Rubus: embedded systems programming

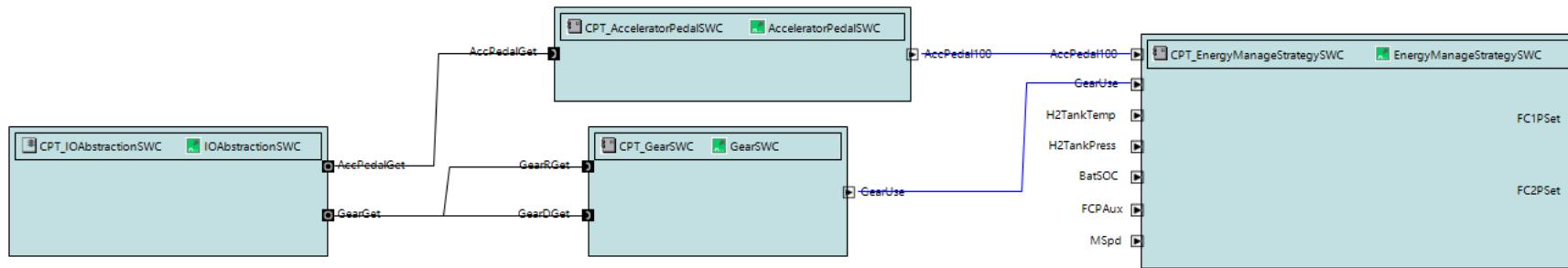


# Ptolemy II



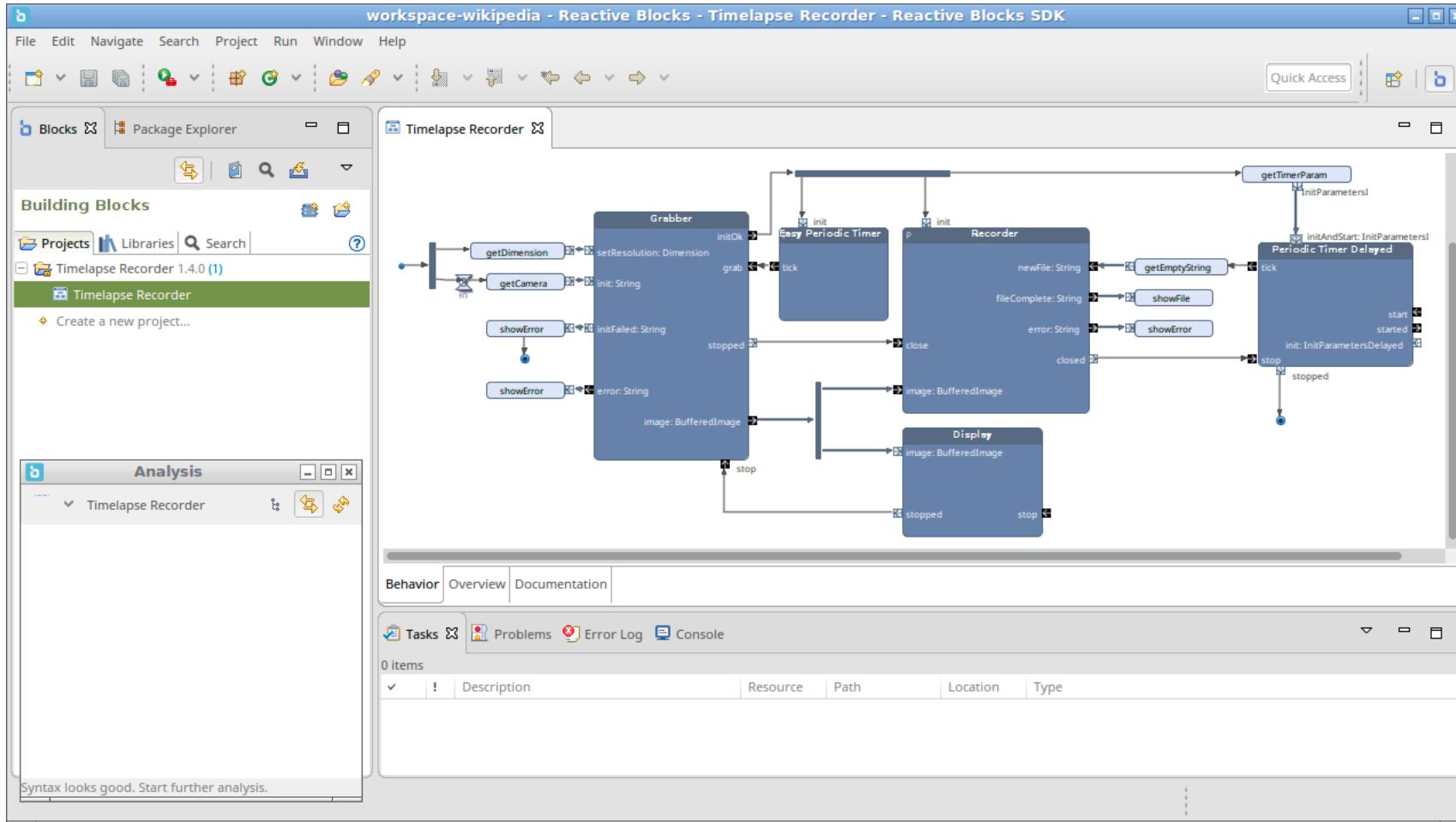
Ptolemy and pTides is a semantic framework for distributed CPS that uses a uniform time concept for both physical and computational parts developed at UCLA Berkeley.

# AUTOSAR



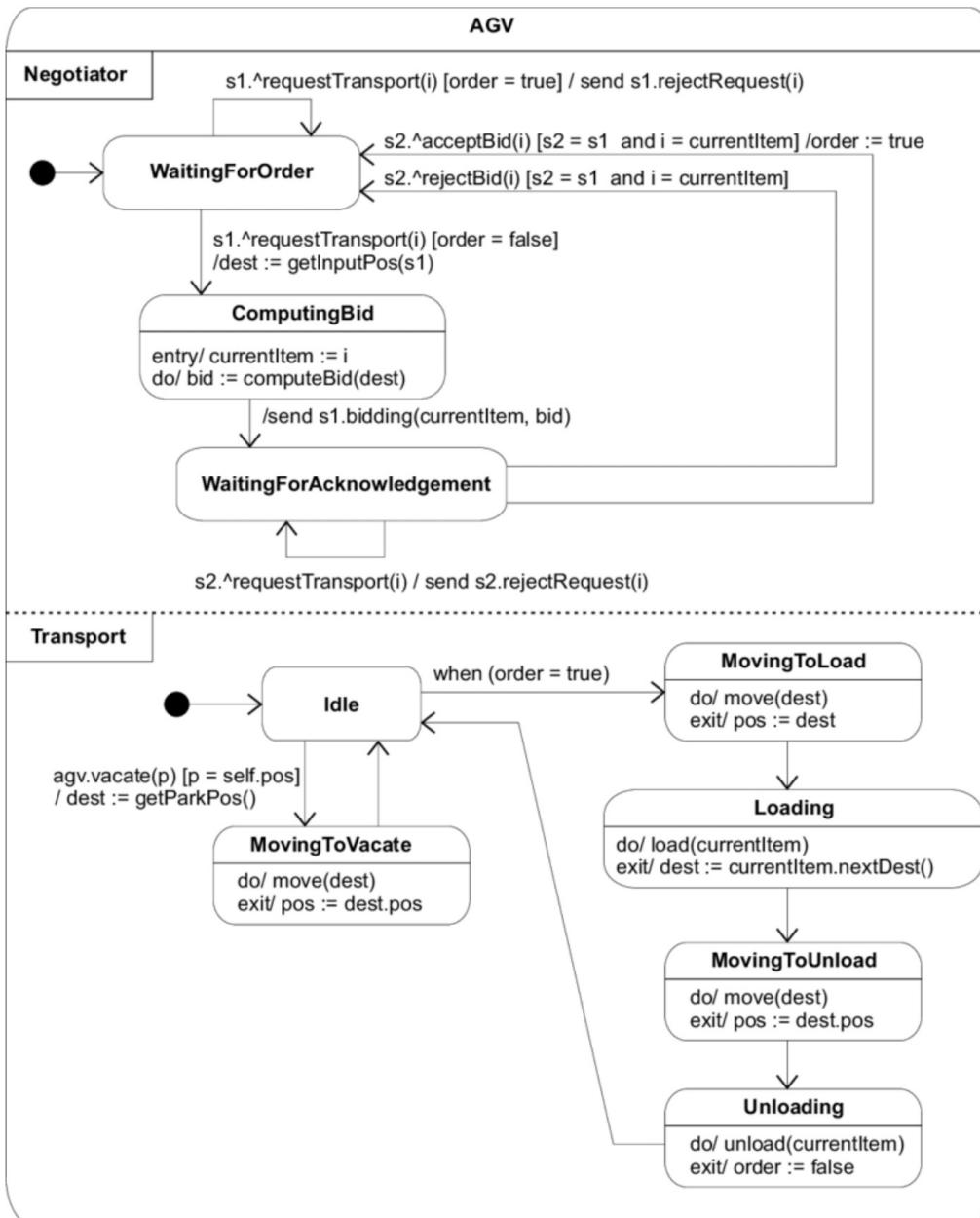
# ReactiveBlocks

## Compiled to Java



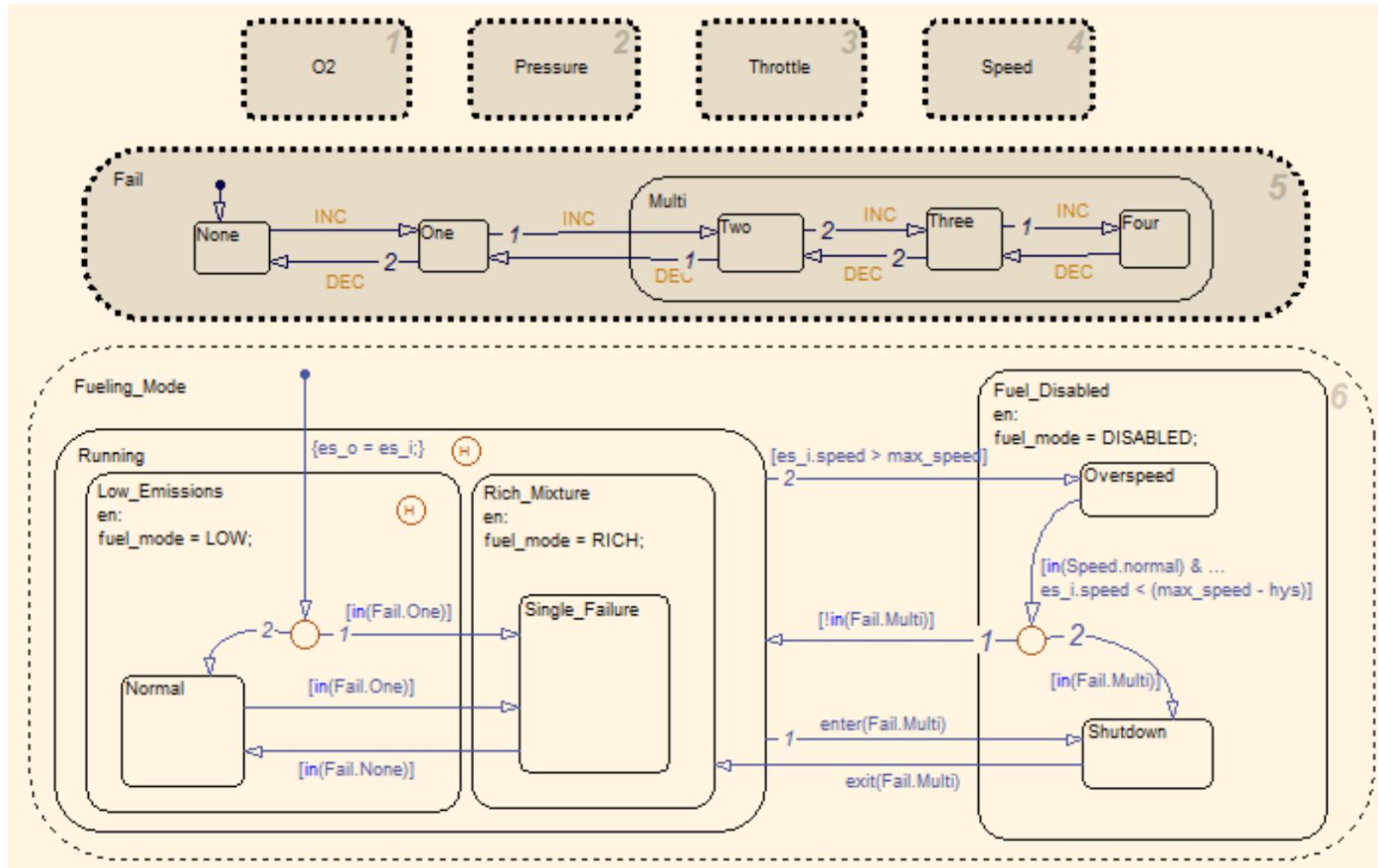
# State machines

# UML State Charts

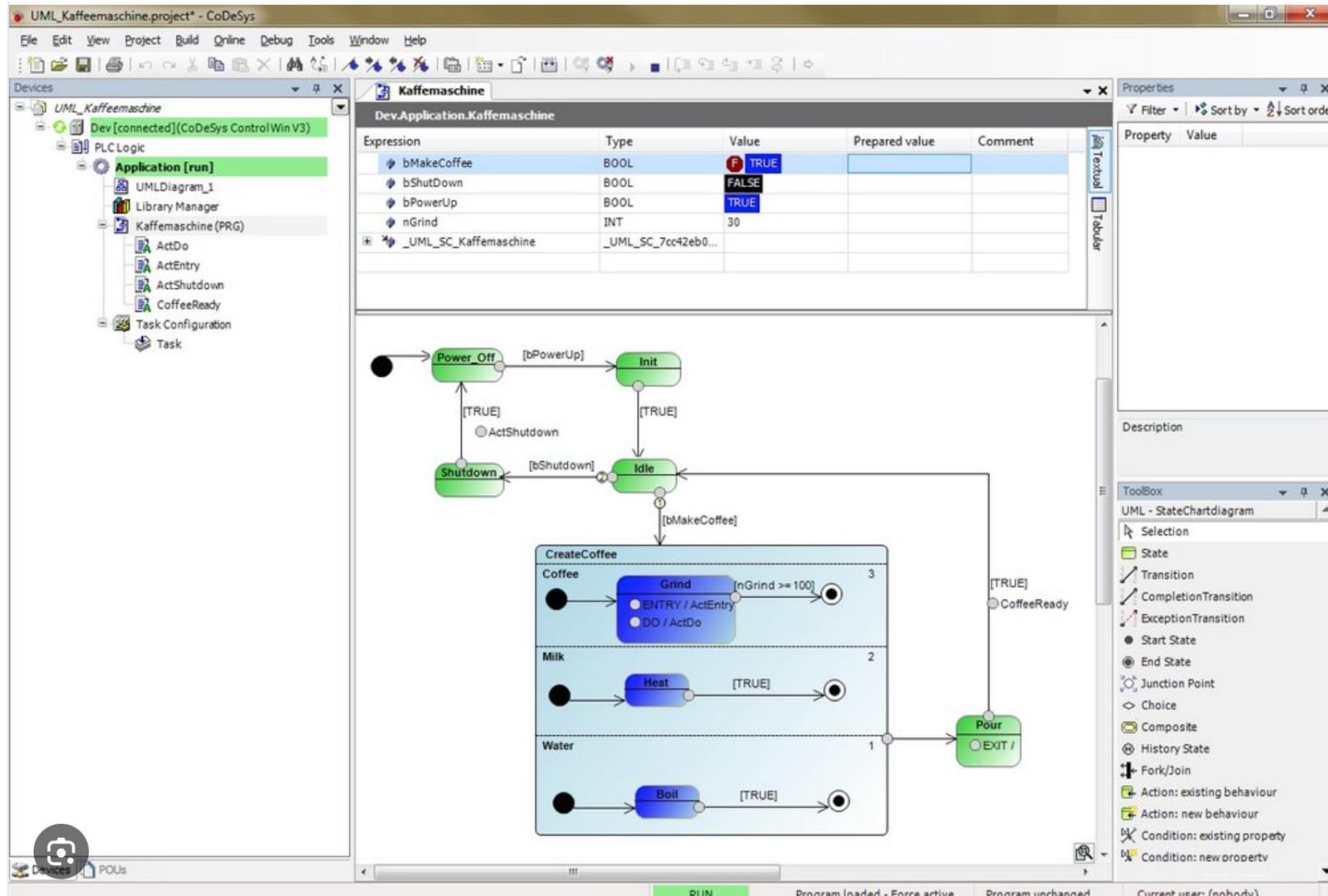


- An important supporting tool for Model-Based Engineering in software and embedded systems engineering.

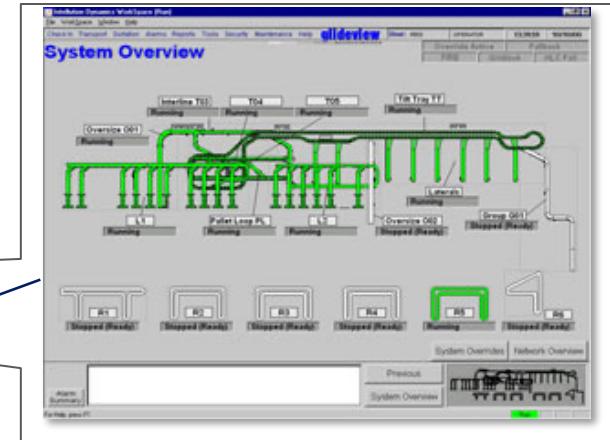
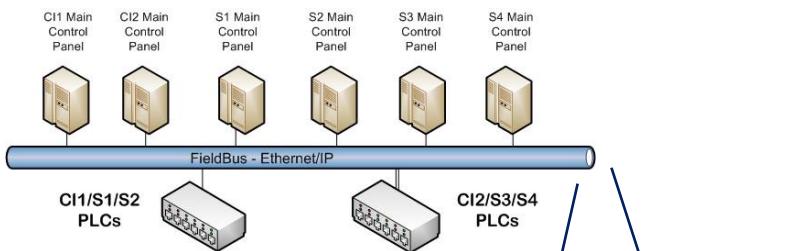
# Matlab/Simulink StateFlow



# CoDeSys State Charts



# Structure of the course



Evolution of Automation

IEC 61499 standard

State based control

System -level design

Design Rules and Patterns

HMI and SCADA

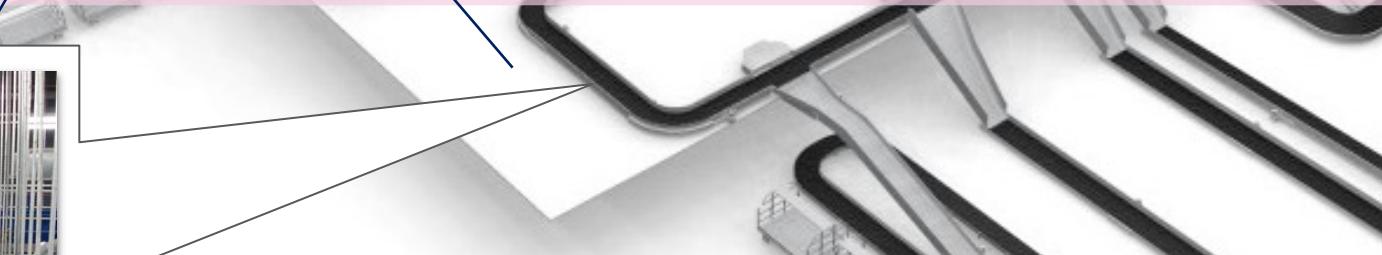
Communication

Alarms and Events Handling

Continuous control

Deployment on hardware

Project



**UNIVERSAL  
AUTOMATION.ORG**