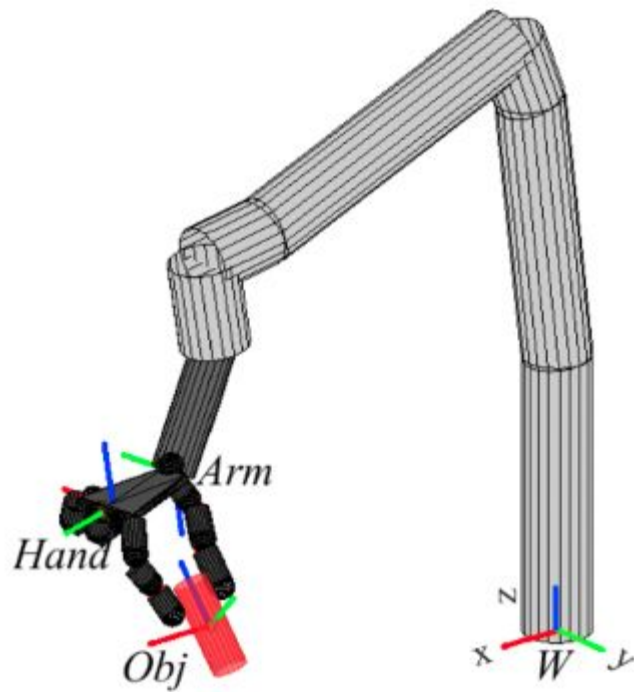


GIANT ROBOTIC ARM OF DEATH

Agent: controller of Giant Death Robotic Arm

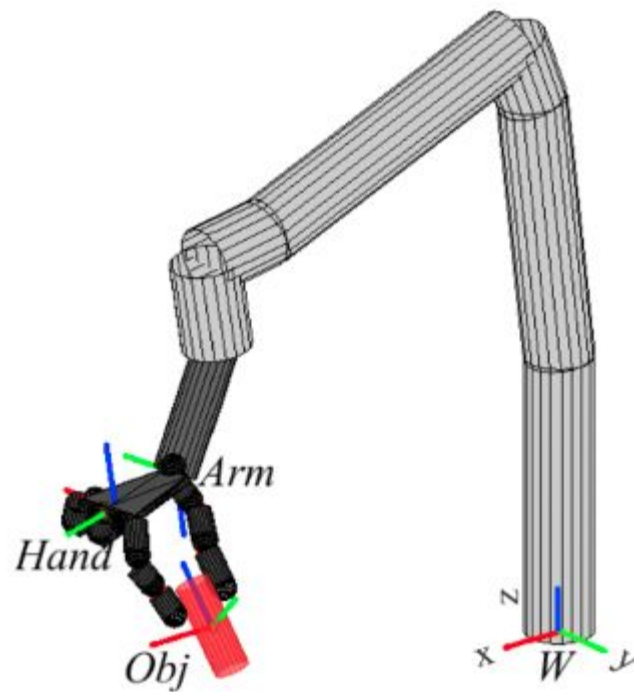
Environment: robotic arm itself + its interaction with blocks



GIANT ROBOTIC ARM OF DEATH

Purpose:

- ~~grab and smash people~~
- take and lift objects



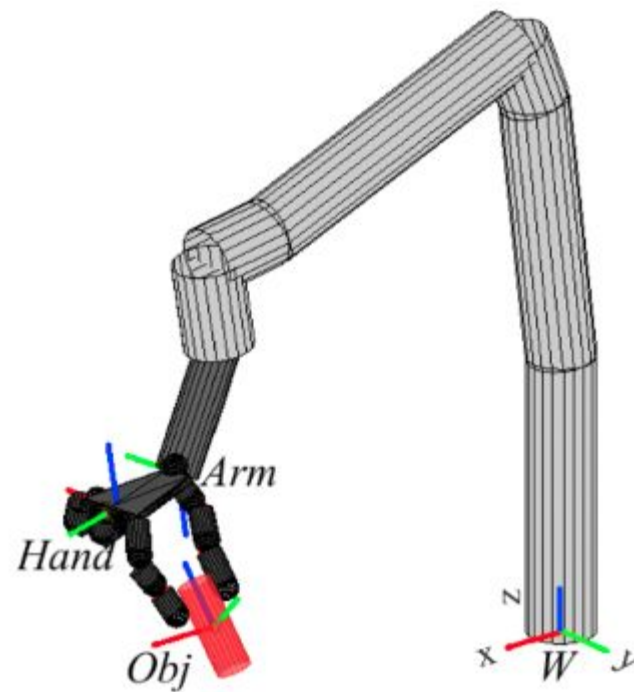
GIANT ROBOTIC ARM OF DEATH

Two ~~(three)~~ stages:

1. grasp object
2. lift object
- ~~3. smash object~~

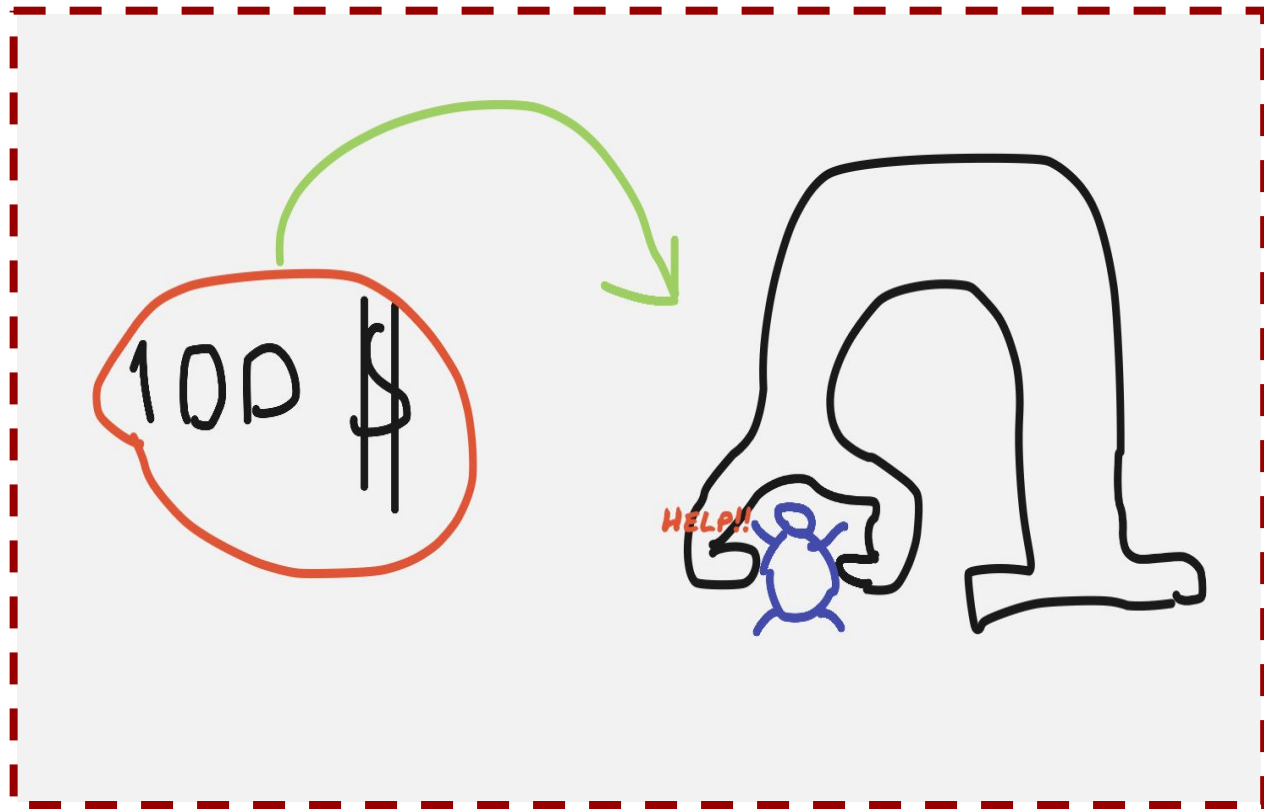


MAKE REWARD STAGED

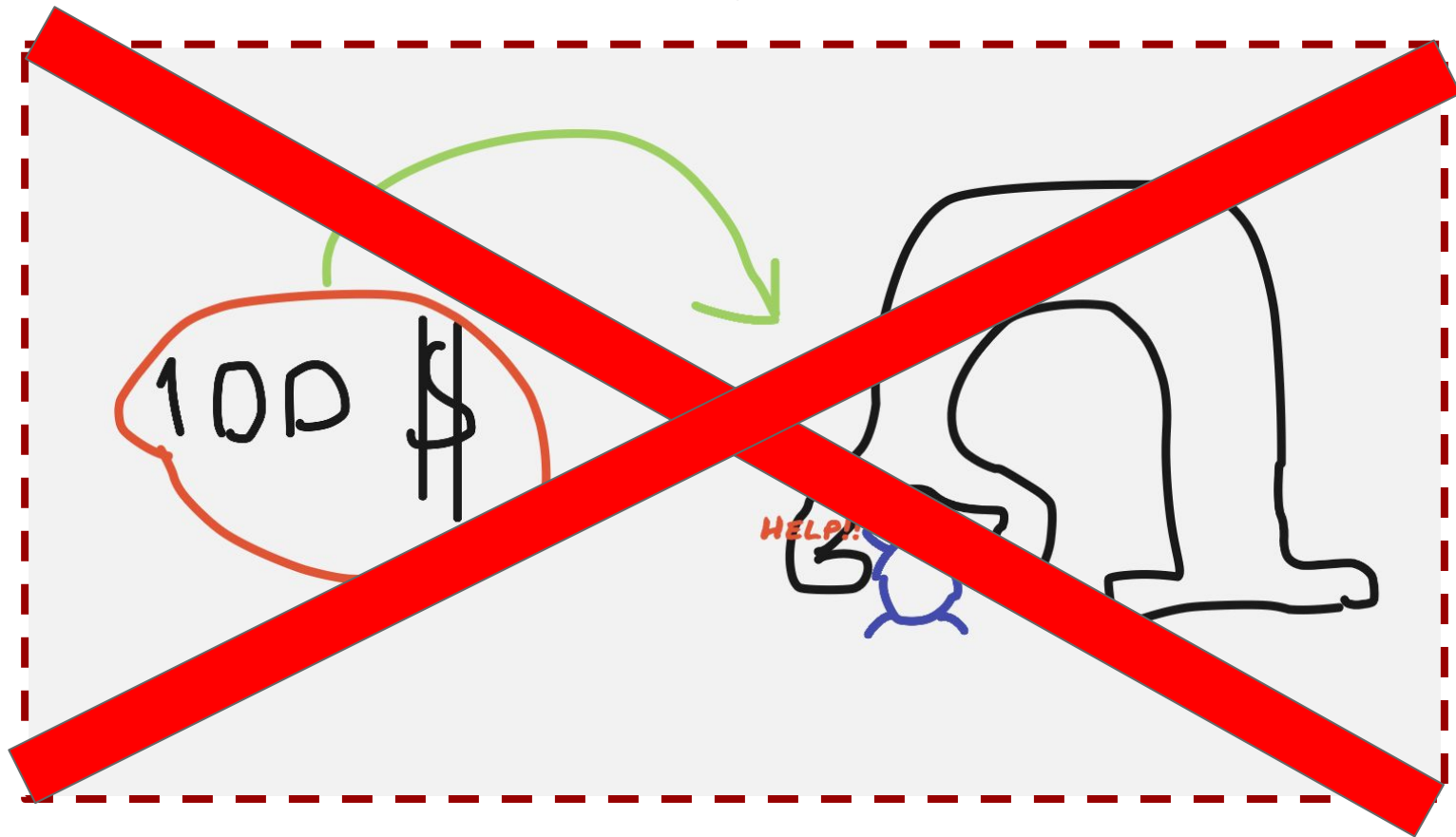


REWARD FOR GIANT ROBOTIC ARM OF DEATH - GRABBING

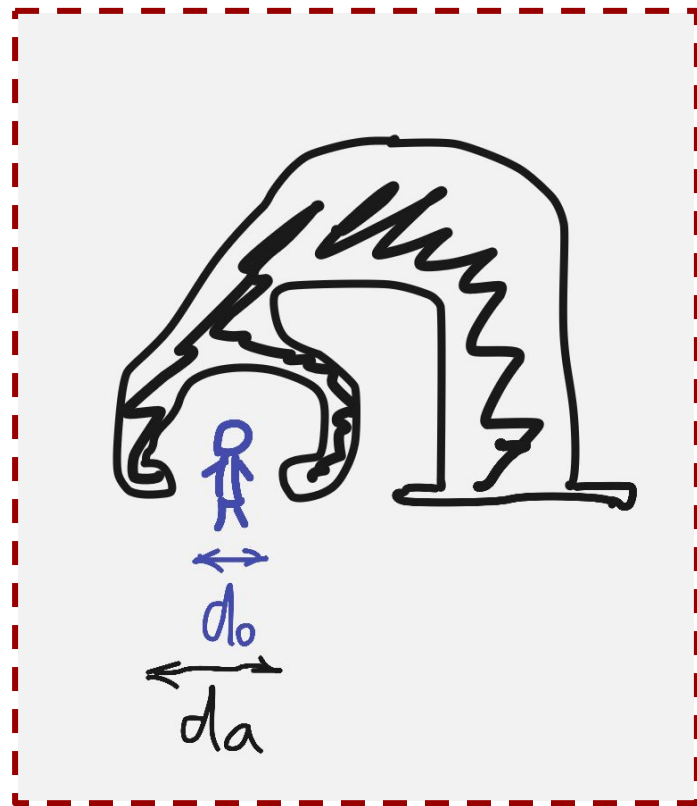
**IS IT A GOOD
REWARD?**



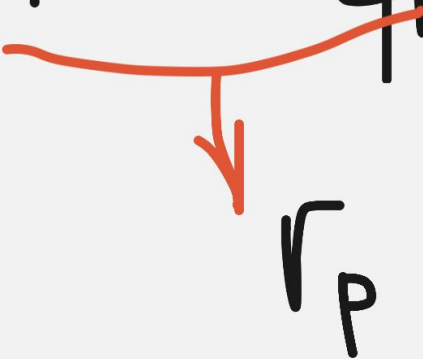
REWARD FOR GIANT ROBOTIC ARM OF DEATH - GRABBING



REWARD FOR GIANT ROBOTIC ARM OF DEATH - GRABBING

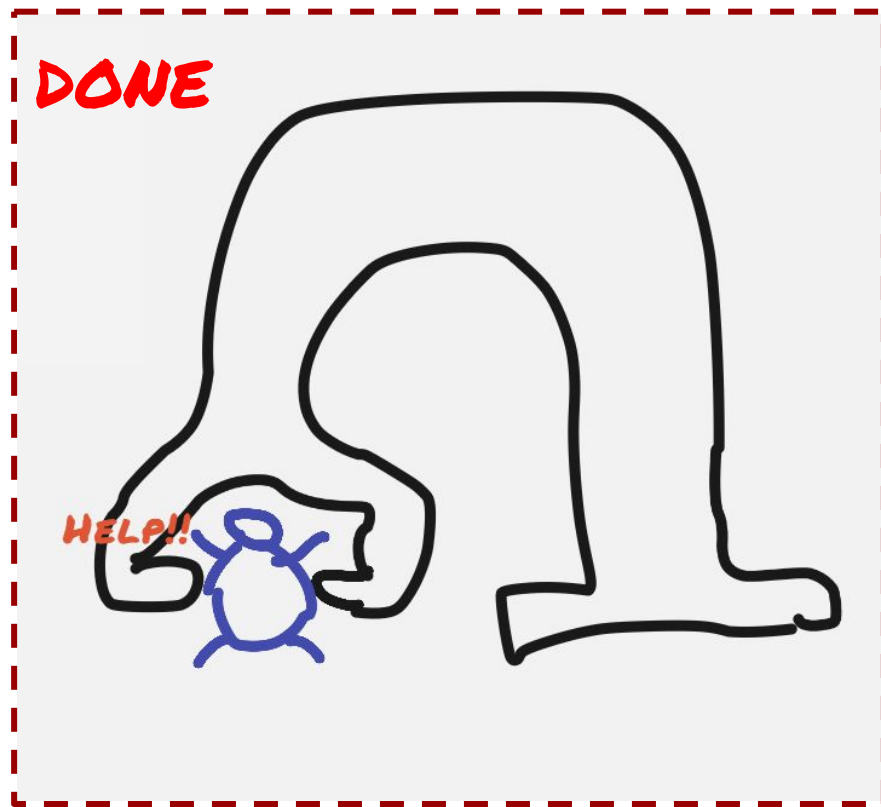


REWARD FOR GIANT ROBOTIC ARM OF DEATH - GRABBING

$$R_1 = 100 \$ \cdot \left| \frac{d_0}{d_a} \right|$$


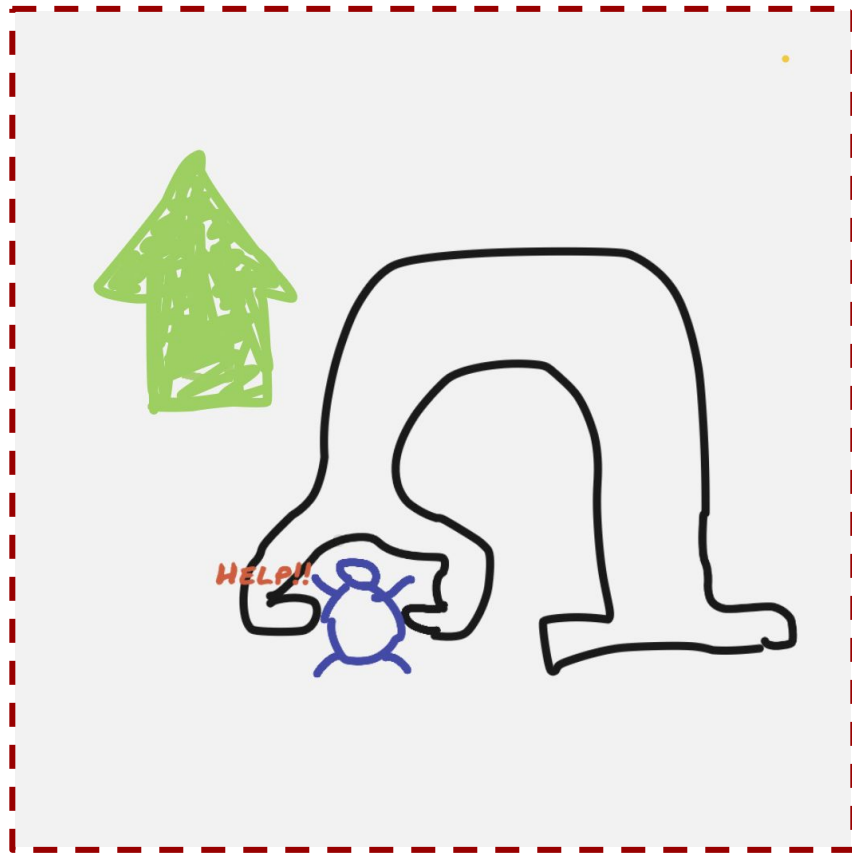
A red bracket is drawn under the term "100 \$". A red arrow points from the center of this bracket down to the symbol r_p .

REWARD FOR GIANT ROBOTIC ARM OF DEATH - GRABBING

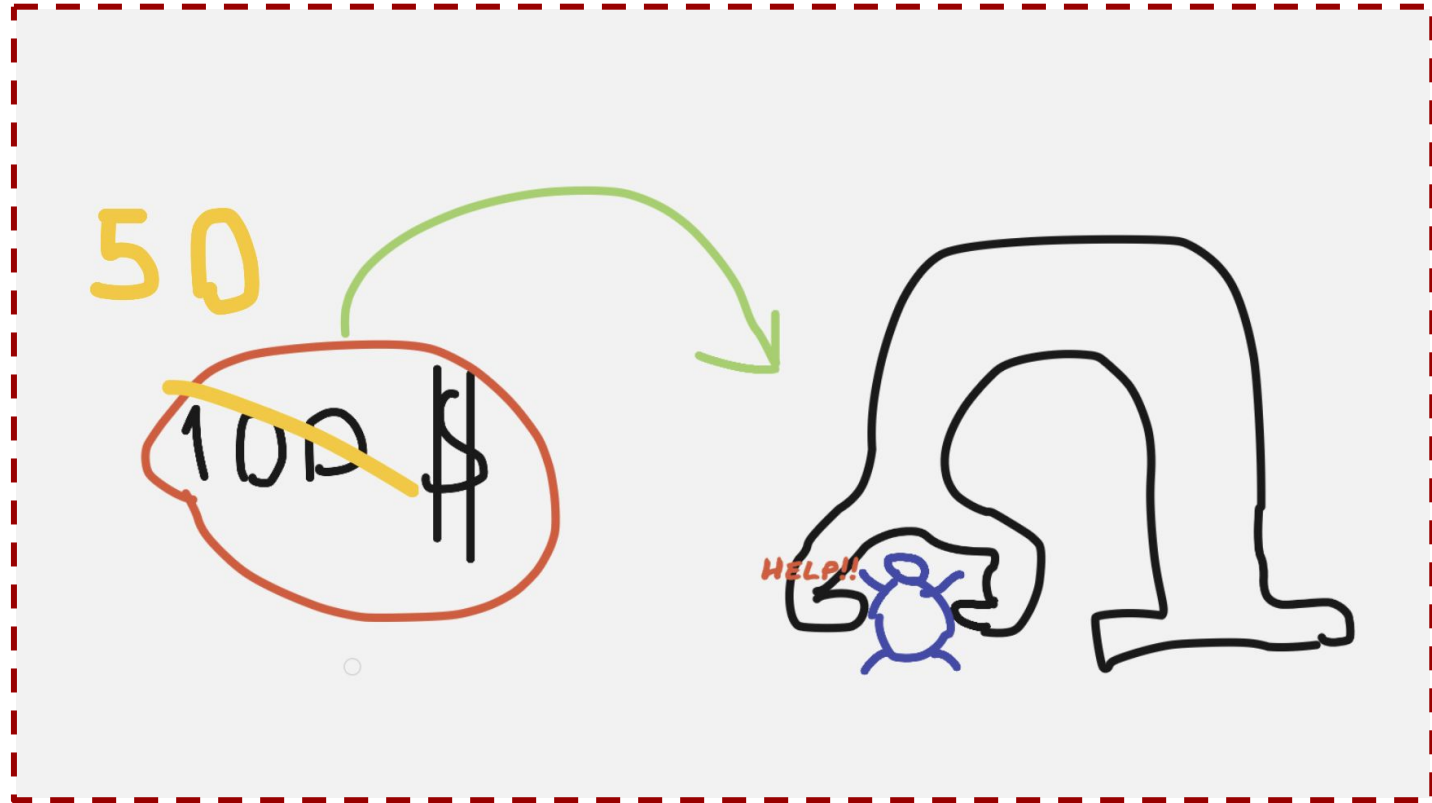


REWARD FOR GIANT ROBOTIC ARM OF DEATH - LIFTING

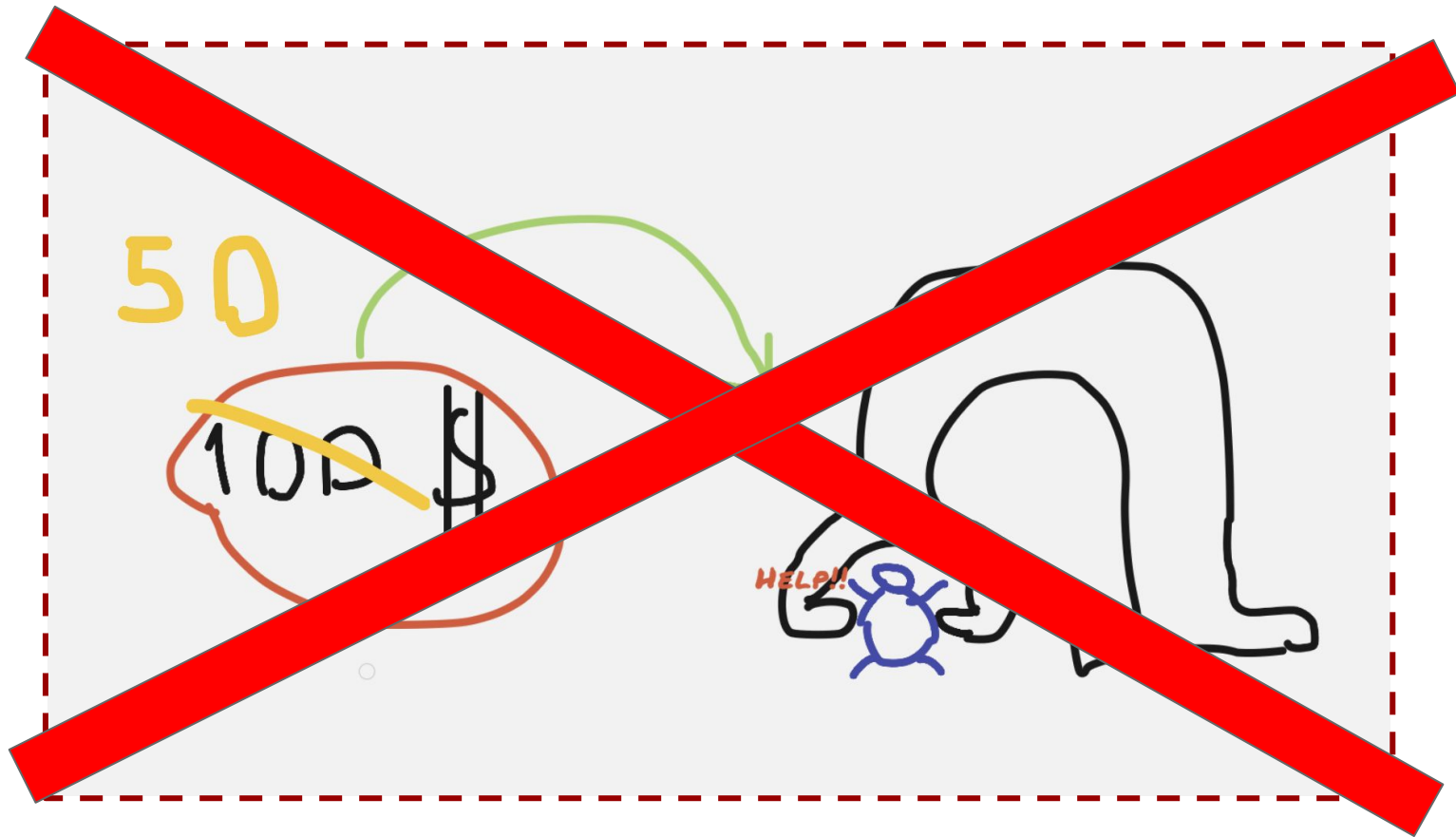
**WHAT PROPERTY
OF THE REWARD
SHOULD HOLD?**



REWARD FOR GIANT ROBOTIC ARM OF DEATH - LIFTING



REWARD FOR GIANT ROBOTIC ARM OF DEATH - LIFTING



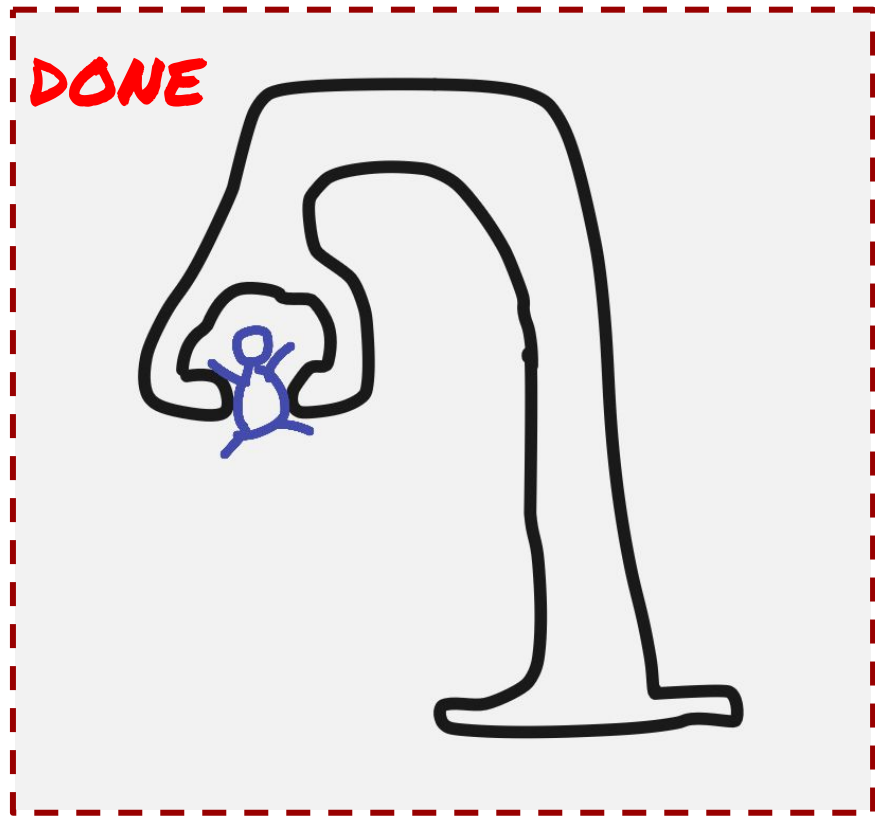
REWARD FOR DEATH ROBOTIC ARM - LIFTING

$$R = r_p + r_e * \left(\frac{h_o}{h_t} \right)$$

REWARD FOR GIANT ROBOTIC ARM OF DEATH - LIFTING

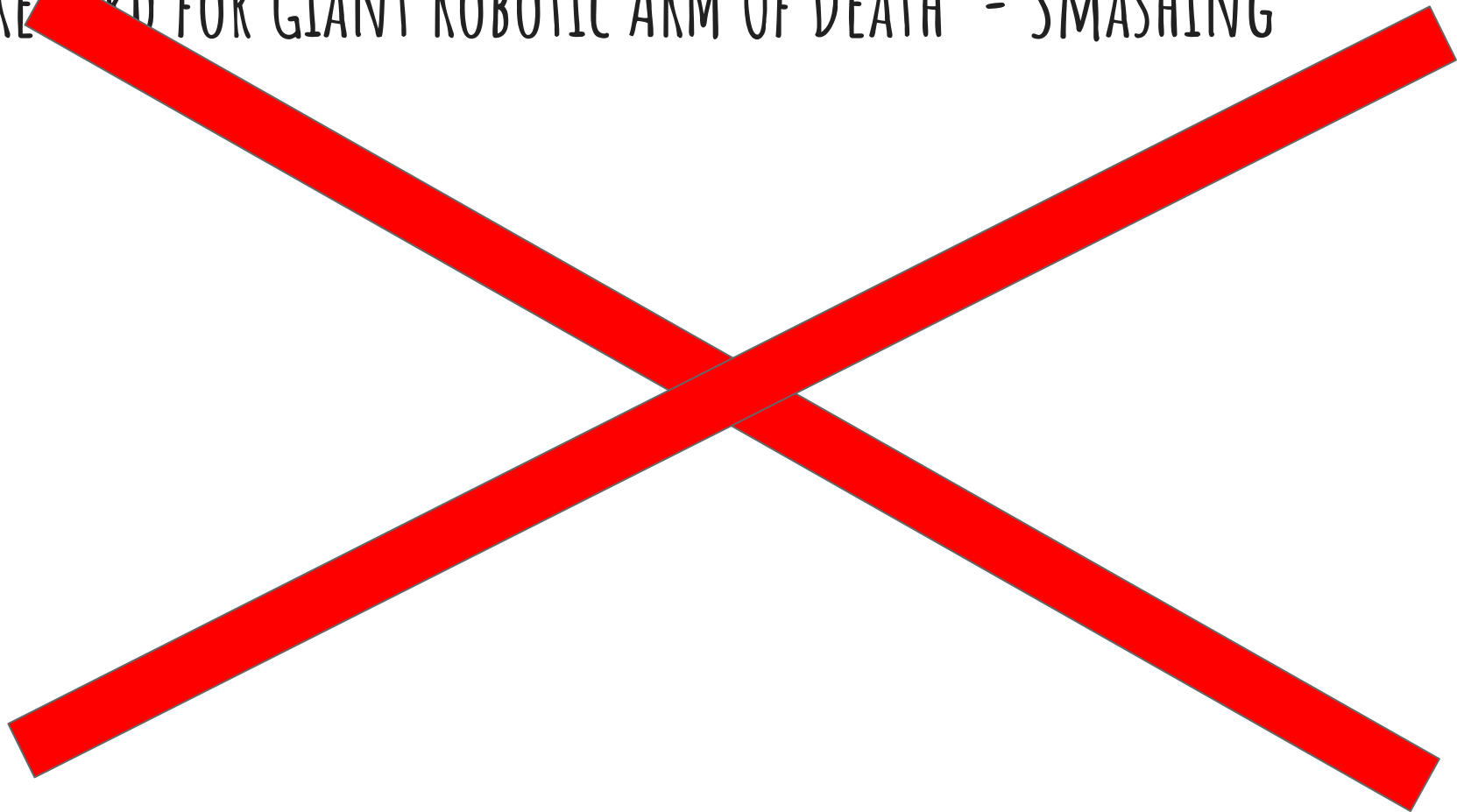
$$R = r_p + r_e * \left(\frac{h_o}{h_t} \right)^2$$

REWARD FOR GIANT ROBOTIC ARM OF DEATH - LIFTING



REWARD FOR GIANT ROBOTIC ARM OF DEATH - SMASHING

REWARD FOR GIANT ROBOTIC ARM OF DEATH - SMASHING



CONCLUSION

WE CAN SHAPE THE REWARD IN TIME AND SPACE