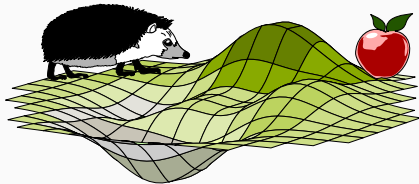


# REINFORCEMENT LEARNING

## CONVERGENCE I

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First of all, convergence of policy gradient algorithms (in the sense of the policy PDF parameters) is the usual convergence of gradient algorithms\* (in general, only to a local extremizer).

This is enabled by the policy gradient theorem which shows that the respective expression of the policy gradient (say, REINFORCE) is indeed a proper gradient of the objective.

Be aware that we are talking about PDF parameters for a definite initial state or a distribution thereof. In the following, we study convergence of tabular methods

\* Provided the value is estimated sufficiently well



Let's consider the following  $\infty$ -horizon undiscounted<sup>\*</sup> optimal control problem:

$$\min_{\mu} \mathbb{E} \left[ \sum_{k=0}^{\infty} \rho(X_k, U_k) \right], \quad \rho(x, u) \geq 0, \forall x, u$$

$$X_+ \sim P_X(x_+ | x, u)$$

$$U \sim P_{\mu(x)}(u | x)$$

This is cost minimization instead of reward maximization, but only chosen so for convenience.

We will use the notation  $X_+^u$  for the next state (as random variable) under the action  $u$ .

<sup>\*</sup> We already tackled the discounted case in the DP Lecture (recall it exploits contraction)



We assume  $\mu: \mathcal{X} \rightarrow \Pi$  where  $\Pi$  is the space of policy PDF parameters. Thus, we consider the parameters state-dependent. Compare this to the policy algorithms we discussed earlier.

Here, we will study convergence of the VI algorithm. Let's recall it: (iterate for  $i$ )

$$\mu_i(x) := \arg\min_{\mu} \left\{ \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}} \left[ \rho(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right] \right\},$$

$$V_{i+1}(x) := \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_i(x)}} \left[ \rho(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right],$$

where  $\mu_i, V_i$  are the successive policy (PDF parameter) and value approximations



In the following, we will abuse the terminology somewhat and refer to functions  $\mathcal{X} \rightarrow \Pi$  simply as policies.

So, let  $\eta: \mathcal{X} \rightarrow \Pi$  be an arbitrary policy. Arbitrary, but not quite...

In general, the cost-to-go

$$J(x|\eta) = \mathbb{E}_{U_k \sim p_U^{\eta}(X_k)} \left[ \sum_{k=0}^{\infty} \rho(X_k, U_k) \mid X_0 = x \right]$$

may fail to converge (i.e., to be finite). We call those policies, for which it is finite, **admissible**. So let  $\eta$  be arbitrary, but admissible



Now, consider some generic iterations

$$\Lambda_{i+1}(x) := \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\eta(x)}} \left[ \rho(x, \mathcal{U}) + \Lambda_i(X_+^{\mathcal{U}}) \right]$$

starting from  $\Lambda_0 \equiv 0$ .

Let's compare them to our VI iteration by iteration.

So, at the first one we have:

$$\sqrt{1}(x) = \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_0(x)}} \left[ \rho(x, \mathcal{U}) \right]$$

where

$$\mu_0(x) = \arg \min_{\mathcal{U}} \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mathcal{U}}} \left[ \rho(x, \mathcal{U}) \right]$$



At the same time,

$$\Lambda_1(x) = \mathbb{E}_{U \sim P_U^{q(x)}} [p(x, U)] .$$

By optimality of  $\mu_0$ ,  $V_1(x) \leq \Lambda_1(x)$  and this holds for all  $x$ .

Now, at the second iteration,

$$\begin{aligned} V_2(x) &= \mathbb{E}_{U \sim P_U^{\mu_1(x)}} [p(x, U) + V_1(X_+^U)] \\ &= \mathbb{E}_{U \sim P_U^{\mu_1(x)}} [p(x, U) + \mathbb{E}_{U \sim P_U^{\mu_0(X_+^U)}} [p(X_+^U, U) | X = x]] \\ &= \mathbb{E}_{\substack{U \sim P_U^{\mu_1(x)} \\ U_+ \sim P_U^{\mu_0(X_+^U)}}} [p(x, U) + p(X_+^U, U_+)] \end{aligned}$$



The policy reads :

$$\mu_1(x) = \arg \min_{\sigma} \mathbb{E}_{\substack{U \sim P_U^{\sigma} \\ U_+ \sim P_{U_+}^{\mu_0(x^U)}}} \left[ \rho(x, U) + \rho(x_+^U, U_+) \right].$$

Observe that, again, by optimality of  $\mu_1$ ,

$$\mathbb{E}_{\substack{U \sim P_U^{\mu_1(x)} \\ U_+ \sim P_{U_+}^{\mu_0(x^U)}}} \left[ \rho(x, U) + \rho(x_+^U, U_+) \right] \leq$$

$$\mathbb{E}_{\substack{U \sim P_U^{\mu_2(x)} \\ U_+ \sim P_{U_+}^{\mu_0(x^U)}}} \left[ \rho(x, U) + \rho(x_+^U, U_+) \right]$$





Due to optimality of  $\mu_0$ ,

$$\mathbb{E}_{U \sim P_U^{\mu_0(x)}} [\rho(x, U)] \leq \mathbb{E}_{U \sim P_U^{\eta(x)}} [\rho(x, U)], \quad \forall x,$$

which implies, in particular,

$$\mathbb{E}_{U_+ \sim P_{U_+}^{\mu_0(x_+^U)}} [\rho(x_+^U, U_+)] \leq \mathbb{E}_{U_+ \sim P_{U_+}^{\eta(x_+^U)}} [\rho(x_+^U, U_+)] \text{ a.s.}$$

no matter what  $U$  was.

Therefore,

$$\mathbb{E}_{\substack{U \sim P_U^{\eta(x)} \\ U_+ \sim P_{U_+}^{\mu_0(x_+^U)}}} [\rho(x, U) + \rho(x_+^U, U_+)] \leq$$

$$\mathbb{E}_{\substack{U \sim P_U^{\eta(x)} \\ U_+ \sim P_{U_+}^{\eta(x_+^U)}}} [\rho(x, U) + \rho(x_+^U, U_+)]$$



Combining all facts, conclude:

$$\mathbb{E}_{\substack{U \sim P_U^{\mu_2(x)} \\ U_+ \sim P_{U_+}^{\mu_0(x_+^U)}}} \left[ \rho(x, U) + \rho(x_+^U, U_+) \right] \leq$$

$$\mathbb{E}_{\substack{U \sim P_U^{\mu(x)} \\ U_+ \sim P_{U_+}^{\mu(x_+^U)}}} \left[ \rho(x, U) + \rho(x_+^U, U_+) \right]$$

which means  $V_2(x) \leq \Lambda_2(x)$ ,  $\forall x$



Now, suppose  $\sqrt{J}_i(x) \leq \Lambda_i(x)$ ,  $\forall x$ .

Consider:

$$\mu_i(x) = \arg \min_{\mu} \left\{ \mathbb{E}_{\sigma \sim P_{\sigma}^{\mu}} \left[ \rho(x, \sigma) + \sqrt{J}_i(X_+^{\sigma}) \right] \right\},$$

$$\sqrt{J}_{i+1}(x) = \mathbb{E}_{\sigma \sim P_{\sigma}^{\mu_i(x)}} \left[ \rho(x, \sigma) + \sqrt{J}_i(X_+^{\sigma}) \right],$$

$$\Lambda_{i+1}(x) = \mathbb{E}_{\sigma \sim P_{\sigma}^{\eta(x)}} \left[ \rho(x, \sigma) + \Lambda_i(X_+^{\sigma}) \right]$$

By optimality of  $\mu_i$ ,

$$\mathbb{E}_{\sigma \sim P_{\sigma}^{\mu_i(x)}} \left[ \rho(x, \sigma) + \sqrt{J}_i(X_+^{\sigma}) \right] \leq$$

$$\mathbb{E}_{\sigma \sim P_{\sigma}^{\eta(x)}} \left[ \rho(x, \sigma) + \sqrt{J}_i(X_+^{\sigma}) \right]$$



(cont.)

By the induction hypothesis,

$$\mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\pi(x)}} \left[ \rho(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right] \leq \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\pi(x)}} \left[ \rho(x, \mathcal{U}) + \Lambda_i(X_+^{\mathcal{U}}) \right].$$

Therefore,  $V_{i+1}(x) \leq \Lambda_{i+1}(x)$ ,  $\forall x$ . Proof by induction is complete.

Notice that  $\eta$  was arbitrary. Let's try the optimal policy  $\mu^*$  in place of it



Recall the generic iteration:

$$\Lambda_{i+1}(x) := \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu^*(x)}} \left[ \rho(x, \mathcal{U}) + \Lambda_i(X_{+1}^{\mathcal{U}}) \right].$$

Unwrapping the recursion gives:

$$\Lambda_i(x) = \mathbb{E}_{\mathcal{U}_{+k} \sim P_{\mathcal{U}}^{\mu^*(X_{+k})}} \left[ \sum_{k=0}^{i-1} \rho(X_{+k}, \mathcal{U}_{+k}) \mid X = x \right]$$

which, by non-negativeness of  $\rho$ , is not greater than

$$\mathbb{E}_{\mathcal{U}_{+k} \sim P_{\mathcal{U}}^{\mu^*(X_{+k})}} \left[ \sum_{k=0}^{\infty} \rho(X_{+k}, \mathcal{U}_{+k}) \mid X = x \right].$$

But this is just the optimum of the cost-to-go,  
or the value function  $V(x)$



Thus, we may conclude that

$$\forall x, i \quad \bar{V}_i(x) \leq V(x).$$

The next step is to compare  $\bar{V}_{i+1}$  and  $\bar{V}_i$ .

For this sake, recall:

$$\bar{V}_{i+1}(x) = \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_i(x)}} \left[ \rho(x, \mathcal{U}) + \bar{V}_i(X_+^{\mathcal{U}}) \right]$$

$$\bar{V}_i(x) = \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_{i-1}(x)}} \left[ \rho(x, \mathcal{U}) + \bar{V}_{i-1}(X_+^{\mathcal{U}}) \right]$$



By the virtue of  $\mu_{i-1}$ , namely,

$$\mu_{i-1}(x) = \arg\min_{\nu} \left\{ \mathbb{E}_{\nu \sim P_{\nu}^{\nu}} \left[ p(x, \nu) + \sqrt{\nu_{i-1}}(X_+^{\nu}) \right] \right\}$$

leads to the fact that

$$\begin{aligned} \mathbb{E}_{\nu \sim P_{\nu}^{\mu_{i-1}(x)}} \left[ p(x, \nu) + \sqrt{\nu_{i-1}}(X_+^{\nu}) \right] \\ \leq \mathbb{E}_{\nu \sim P_{\nu}^{\mu(x)}} \left[ p(x, \nu) + \sqrt{\nu_{i-1}}(X_+^{\nu}) \right] \end{aligned}$$

for any  $\mu$ , in particular,  $\mu_i$  even, whence

$$\begin{aligned} \mathbb{E}_{\nu \sim P_{\nu}^{\mu_{i-1}(x)}} \left[ p(x, \nu) + \sqrt{\nu_{i-1}}(X_+^{\nu}) \right] \\ \leq \mathbb{E}_{\nu \sim P_{\nu}^{\mu_i(x)}} \left[ p(x, \nu) + \sqrt{\nu_{i-1}}(X_+^{\nu}) \right] \end{aligned}$$



So far, we have thus:

$$V_i(x) \leq \mathbb{E}_{U \sim P_U^{\mu_i(x)}} \left[ \rho(x, U) + V_{i-1}(X_{+}^U) \right].$$

Now, let's do some unwrapping:

$$V_i(x) = \mathbb{E}_{U_{+k} \sim P_U^{\mu_{i-1-k}(X_{+k})}} \left[ \sum_{k=0}^{i-1} \rho(X_{+k}, U_{+k}) \mid X = x \right],$$

$$V_{i+1}(x) = \mathbb{E}_{U_{+k} \sim P_U^{\mu_{i-2-k}(X_{+k})}} \left[ \sum_{k=0}^i \rho(X_{+k}, U_{+k}) \mid X = x \right]$$

(verify this!)





For the starting state  $X_+^U$ , these read:

$$V_i(X_+^U) = \mathbb{E}_{U_{+k} \sim P_U^{\mu_{i-k}}(X_{+k})} \left[ \sum_{k=1}^i p(X_{+k}, U_{+k}) | X_+^U \right],$$

$$V_{i-1}(X_+^U) = \mathbb{E}_{U_{+k} \sim P_U^{\mu_{i-1-k}}(X_{+k})} \left[ \sum_{k=1}^{i-1} p(X_{+k}, U_{+k}) | X_+^U \right].$$

Let's add the  $i$ th stage cost under the policy  $\mu_{i-1}$  to the last displayed expected sum



(cont.)

$$\mathbb{E}_{\mathcal{U}_{+k} \sim \mathcal{P}_{\mathcal{U}}^{\mu_{i-1-k}}(X_{+k})} \left[ \sum_{k=1}^{i-1} \rho(X_{+k}, \mathcal{U}_{+k}) \mid X_+^{\mathcal{U}} \right] \leq$$

$$\mathbb{E}_{\substack{\mathcal{U}_{+k} \sim \mathcal{P}_{\mathcal{U}}^{\mu_{i-1-k}}(X_{+k}) \\ \mathcal{U}_{+i} \sim \mathcal{P}_{\mathcal{U}}^{\mu_{i-1}}(X_{+i})}} \left[ \sum_{k=1}^{i-1} \rho(X_{+k}, \mathcal{U}_{+k}) + \rho(X_{+i}, \mathcal{U}_{+i}) \mid X_+^{\mathcal{U}} \right] =$$

$$\mathbb{E}_{\mathcal{U}_{+k} \sim \mathcal{P}_{\mathcal{U}}^{\mu_{i-k}}(X_{+k})} \left[ \sum_{k=1}^i \rho(X_{+k}, \mathcal{U}_{+k}) \mid X_+^{\mathcal{U}} \right] =$$

$$\mathcal{V}_i(X_+^{\mathcal{U}})$$



Therefore,

$$\begin{aligned} V_i(x) &\leq \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_i(x)}} \left[ p(x, \mathcal{U}) + V_{i+1}(X_+^{\mathcal{U}}) \right] \\ &\leq \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_i(x)}} \left[ p(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right] \\ &= V_{i+1}(x). \end{aligned}$$

Thus, we have :

$$\begin{aligned} \forall i, x \quad V_i(x) &\leq V_{i+1}(x) \\ V_i(x) &\leq V(x) < \infty \end{aligned}$$



So,  $V_i$  is point-wise increasing and bounded above whence, by the monotone convergence theorem, it point-wise convergent.

Let's denote the limit  $V_\infty$ .

By the virtue of the value function,  
 $V(x) \leq V_\infty(x)$ .

On the other hand,  $\forall i, x \quad V_i(x) \leq V(x)$ , whence  
 $V_\infty(x) \leq V(x)$ .

So,  $V_\infty(x) = V(x)$ ,  $\forall x$



We have:

$$v_{\infty}(x) = \mathbb{E}_{\nu \sim P_{\nu}^{\mu_{\infty}(x)}} \left[ \rho(x, \nu) + v_{\infty}(X_{+}^{\nu}) \right] =$$

$$v(x) = \mathbb{E}_{\nu \sim P_{\nu}^{\mu(x)}} \left[ \rho(x, \nu) + v(X_{+}^{\nu}) \right],$$

$$\mu^{*}(x) = \arg \min_{\mu} \mathbb{E}_{\nu \sim P_{\nu}^{\mu}} \left[ \rho(x, \nu) + v(X_{+}^{\nu}) \right],$$

$$\mu_{\infty}(x) = \arg \min_{\mu} \mathbb{E}_{\nu \sim P_{\nu}^{\mu}} \left[ \rho(x, \nu) + v_{\infty}(X_{+}^{\nu}) \right].$$

Assuming  $\mu^{*}(x)$  is unique, we conclude  $\mu_{\infty} = \mu^{*}$



## Discussion

We saw that the convergence result worked thanks to the policy being state-dependent. The argument collapses if it's made fixed over states. Next, the VI „algorithm“ is only a real algorithm when the state space is finite. Otherwise, a compact and a finite mesh over it must be taken. This necessarily introduces approximation errors. The convergence result considered herein is not inherently robust to such errors



(cont.)

Works are known in this direction, e.g.,

Heydari, A. (2016). Theoretical and numerical analysis of approximate dynamic programming with approximation errors.  
Journal of Guidance, Control, and Dynamics, 39(2), 301-311.

But they assume the errors to tend to zero sufficiently fast along iterations, for otherwise their accumulation effect destroys convergence.

There are other sources of errors, such as non-exact optimization in finding  $\mu_i$ s.

In general, we cannot expect any kind of errors to vanish. What makes things worse is that no rate of convergence was provided above



Convergence of PI

$$V_i(x) := \mathbb{E}_{\mathcal{U} \sim \mu_i^{\mathcal{U}}(x)} \left[ r(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right], \quad \forall x$$

$$\mu_{i+1}(x) := \operatorname{argmin}_{\mu^{\mathcal{U}}} \left\{ \mathbb{E}_{\mathcal{U} \sim \mu^{\mathcal{U}}} \left[ r(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right] \right\}, \quad \forall x$$

is somewhat similar.

First of all, let's look at the value update.

It resembles the HJB, but with a policy  $\mu_i$ .

A particular way to calculate it is to pretend it's a fixed-point equation and iterate over  $j$  as per:

$$\forall x \quad V_i^{j+1}(x) := \mathbb{E}_{\mathcal{U} \sim \mu_i^{\mathcal{U}}(x)} \left[ r(x, \mathcal{U}) + V_i^j(X_+^{\mathcal{U}}) \right]$$





Let's say  $V_i^0 \equiv 0$ .

Then,  $V_i^\infty$  is just the cost-to-go under  $\mu_i$   
(show it).

For the value update thus to be meaningful,  
 $\mu_i$  needs to be admissible.

In fact, the very first candidate  $\mu_0$   
also needs to be admissible and it makes  
a lot of difference to VI. In other words,  
PI is an order of magnitude stricter on the  
requirements than VI



But, PI has some serious advantage compared to VI.

We know that

$$V_i(x) = \mathbb{E}_{U_{+k} \sim P_U^{\mu_i(X_{+k})}} \left[ \sum_{k=0}^{\infty} \rho(X_{+k}, U_{+k}) \mid X=x \right] < \infty \quad \forall i, x.$$

If  $\rho$  is positive-definite, deduce that

$$\lim_{k \rightarrow \infty} \mathbb{E}_{U_{+k} \sim P_U^{\mu_i(X_{+k})}} \left[ \rho(X_{+k}, U_{+k}) \right] = 0 \quad \text{a.s.}$$

Let's assume, furthermore, that  $\rho$  is convex in  $\|x\|, \|u\|$ . For instance,

$$\exists c > 0 \quad \forall x, u \quad \rho(x, u) \geq c(\|x\|^2 + \|u\|^2)$$



Then,  $\rho(\mathbb{E}[\|X\|], \mathbb{E}[\|U\|]) \leq \mathbb{E}[\rho(X, U)]$  by the Jensen's inequality.

Let's abuse the notation a bit and write:

$$\mathbb{E}_{U_{+\infty} \sim P_U^{\mu_i(X_{+\infty})}} \left[ \rho(X_{+\infty}, U_{+\infty}) \right] = 0 \quad \text{a.s.}$$

Then, also

$$\rho \left( \mathbb{E}[\|X_{+\infty}\|], \mathbb{E}_{U_{+\infty} \sim P_U^{\mu_i(X_{+\infty})}} [\|U_{+\infty}\|] \right) = 0 \quad \text{a.s.}$$

whence  $\mathbb{E}[\|X_{+\infty}\|] = 0 \quad \text{a.s.}$

$$\mathbb{E}_{U_{+\infty} \sim P_U^{\mu_i(X_{+\infty})}} [\|U_{+\infty}\|] = 0 \quad \text{a.s.}$$



Therefore, to be admissible,  $U$  must be zero-mean if the current state is zero.

Furthermore, it must asymptotically stabilize the state in mean.

Evidently,

$$\mathbb{E}_{U_{+k} \sim P_U^{\mu_i(X_{+k})}} \left[ \rho(X_{+k}, U_{+k}) \right] < \infty, \forall k,$$

whence, by the same token, the state has to be mean-stable. This is a **strong conclusion**: the environment under PI is (stochastically) stable, at every iteration.

Under VI, it is only guaranteed at the limit  $i \rightarrow \infty$



Let's study the PI further. Recall:

$$V_i(x) = \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu_i(x)}} \left[ \rho(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right], \quad \forall x$$

$$\mu_{i+1}(x) = \operatorname{argmin}_{\mu} \left\{ \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\mu}} \left[ \rho(x, \mathcal{U}) + V_i(X_+^{\mathcal{U}}) \right] \right\}, \quad \forall x$$

So far, we know how the value update works.  
 Let's study convergence iteration-to-iteration.  
 First of all, by the virtue of the value function,

$$\forall i, x \quad V(x) \leq V_{\infty}(x)$$



Let's compare  $i$ th and  $i+1$ st iterations:

$$v_i(x) = \mathbb{E}_{\mathcal{U} \sim p_{\mathcal{U}}^{\mu_i(x)}} \left[ r(x, \mathcal{U}) + v_i(X_+^{\mathcal{U}}) \right],$$

$$v_{i+1}(x) = \mathbb{E}_{\mathcal{U} \sim p_{\mathcal{U}}^{\mu_{i+1}(x)}} \left[ r(x, \mathcal{U}) + v_{i+1}(X_+^{\mathcal{U}}) \right]$$



(cont.)

By optimality of

$$\mu_{i+1}(x) = \arg \min_{\nu} \left\{ \mathbb{E}_{\mathcal{U} \sim P_{\mathcal{U}}^{\nu}} \left[ \rho(x, \mathcal{U}) + \sqrt{V_i}(X_{+}^{\mathcal{U}}) \right] \right\},$$

and the fact that each  $\sqrt{V_i}$  is a cost-to-go, deduce

$$\sqrt{V_{i+1}}(x) = \mathbb{E}_{\mathcal{U}_{+k} \sim P_{\mathcal{U}}^{\mu_{i+1}(X_{+k})}} \left[ \sum_{k=0}^{\infty} \rho(X_{+k}, \mathcal{U}_{+k}) \mid X = x \right] \leq$$

$$\mathbb{E}_{\mathcal{U}_{+k} \sim P_{\mathcal{U}}^{\mu_i(X_{+k})}} \left[ \sum_{k=0}^{\infty} \rho(X_{+k}, \mathcal{U}_{+k}) \mid X = x \right] =$$

$$\sqrt{V_i}(x)$$



We have :

$$\forall i, x \quad \begin{aligned} \sqrt{v_{i+1}}(x) &\leq \sqrt{v_i}(x) \\ \sqrt{v}(x) &\leq \sqrt{v_i}(x). \end{aligned}$$

Therefore , again, by the monotone convergence theorem and optimality of  $\sqrt{v}$ ,

$$\forall x \quad \begin{aligned} \lim_{i \rightarrow \infty} \sqrt{v_i}(x) &= \sqrt{v}(x) \\ \lim_{i \rightarrow \infty} \mu_i(x) &= \mu^*(x). \end{aligned}$$