Course Notes for EE227C (Spring 2018): Convex Optimization and Approximation

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7 Lecture 7: Nesterov's accelerated gradient descent

In this lecture, we present Nesterov's accelerated gradient descent for smooth convex functions. We will derive an algorithm that obtains a runtime of $\mathcal{O}\left(\frac{\beta}{t^2}\right)$ for β-smooth functions. For functions which are α-strongly convex, we will achieve a rate of $\mathcal{O}\left(\exp\left(-\sqrt{\frac{\beta}{\alpha}}t\right)\right)$. The algorithm proceeds iteratively as follows.

$$x_0 = y_0 = z_0,$$
$$y_k = x_k - \frac{1}{\beta}\nabla f(x_k),$$
$$z_k = z_{k-1} - \eta\|\nabla f(x_k)\|,$$
$$x_{k+1} = \tau z_k + (1-\tau)y_k.$$

The definitions are constructed so that we can apply bounds related to smooth and convex functions. We will simplify our proof of the runtime of the algorithm by "restarting" the procedure in the lemma several times; namely, after the error is reduced from d to $\frac{d}{2}$, we run our algorithm again with a new $x_0 = x_T$

Lemma 7.1. *Suppose $\|x_0 - x^*\| \leqslant R$, f attains its minimum at x^* and is β-smooth. Also assume $f(x_0) - f(x^*) \leqslant d$. Put $\eta = \frac{R}{\sqrt{d\beta}}$, and τ s.t. $\frac{1-\tau}{\tau} = \eta\beta$.*

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Then after $T = 4R\sqrt{\frac{\beta}{d}}$ steps, we have

$$f(\bar{x}) - f(x^*) \leqslant \frac{d}{2},$$

where $\bar{x} = \frac{1}{T}\sum_{k=0}^{T-1} x_k$.

Proof. By smoothness and convexity, we have

$$f(y_k) - f(x_k) \leqslant -\frac{1}{2\beta}\|\nabla f(x_k)\|^2. \tag{1}$$

By convexity, we have

$$\forall u: \ \eta\langle\nabla f(x_{k+1}), z_k - u\rangle \leqslant \frac{\eta^2}{2}\|\nabla f(x_{k+1})\|^2 + \|z_k - u\|^2 - \|z_{k+1} - u\|^2.$$

Substituting the first equation yields

$$\eta\langle\nabla f(x_{k+1}, z_k - u\rangle \leqslant \eta^2\beta(f(x_{k+1}) - f(y_{k+1})) + \|z_k - u\|^2 - \|z_{k+1} - u\|^2 \tag{2}$$

Besides,

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\begin{aligned}
&\eta\langle\nabla f(x_{k+1}), x_{k+1} - u\rangle - \eta\langle\nabla f(x_{k+1}), z_k - u\rangle \\
&= \eta\langle\nabla f(x_{k+1}), x_{k+1} - z_k\rangle \\
&= \frac{1-\tau}{\tau}\eta\langle\nabla f(x_{k+1}), y_k - x_{k+1}\rangle \\
&\leqslant \frac{1-\tau}{\tau}\eta(f(y_k) - f(x_{k+1})) \text{ (by convexity).}
\end{aligned} \tag{3}
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Combining (2) and (3), and setting $\frac{1-\tau}{\tau} = \eta\beta$ yield

$$\forall u, \ \eta\langle\nabla f(x_{k+1}), x_{k+1} - u\rangle \leqslant \eta^2\beta(f(y_k) - f(y_{k+1})) + \|z_k - u\|^2 - \|z_{k+1} - u\|^2.$$

This implies

$$\eta T(f(\bar{x}) - f(x^*)) \leqslant \sum_{k=0}^{T}\eta\langle\nabla f(x_{k+1}), x_{k+1} - x^*\rangle \leqslant \eta^2\beta d + R^2,$$

which can be rewritten as

$$f(\bar{x}) - f(x^*) \leqslant \frac{\eta\beta d}{T} + \frac{R^2}{\eta T}.$$

Setting $\eta = \frac{R}{\sqrt{\beta d}}$, this gives us

$$f(\bar{x}) - f(x) \leqslant \frac{2\sqrt{\beta d}}{T}R.$$

Therefore, for $T \geqslant 4\sqrt{\frac{\beta}{d}}R$, we have

$$f(\bar{x}) - f(x) \leqslant \frac{d}{2}.$$

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This lemma was initially proven by Allen-Zhu and Orecchia in 2014 in their article *Linear Coupling: An Ultimate Unification of Gradient and Mirror Descent*. From the lemma, our analysis of the runtime of the algorithm naturally follows.

Proof. 1) If a function f is β-smooth and convex (not strongly convex), the Lemma gives that after $T(d) = 4R\sqrt{\frac{\beta}{d}}$ steps,

$$f(\bar{x}) - f(x^*) \leqslant \frac{d}{2} \qquad \text{, where } \bar{x} = \frac{1}{T}\sum_{\tau=0}^{T-1} x_k.$$

This means after $T(d)$ steps, Nesterov's accelerated gradient descent method reduces the function value error by half. For the complete Nesterov's method, after every $T(d)$ steps, let $\bar{x}$ be the new initial state and restart the updating algorithm from the beginning.

By applying the Lemma n times, we have the total iterations before $f(\bar{x}_{(n)}) - f(x^*) \leqslant \frac{d}{2^n} \leqslant \epsilon$,

$$t(\epsilon) = \mathcal{O}\left(4R\sqrt{\frac{\beta}{d/2^{n-1}}} + 4R\sqrt{\frac{\beta}{d/2}} + 4R\sqrt{\frac{\beta}{d}}\right)$$

$$= \mathcal{O}\left(4R\sqrt{\frac{\beta}{d/2^{n-1}}}\right)$$

$$= \mathcal{O}\left(\sqrt{\frac{\beta}{\epsilon}}\right).$$

This can also be written as:
$$\epsilon(t) = \mathcal{O}\left(\frac{\beta}{t^2}\right)$$

2) If function f is β-smooth and α-strongly convex, the Lemma gives that after constant $T = 4\sqrt{\frac{2\beta}{\alpha}}$ steps,

$$\|\bar{x} - x^*\|^2 \leqslant \frac{1}{2}\|x_0 - x^*\|^2 \qquad \text{, where } \bar{x} = \frac{1}{T}\sum_{\tau=0}^{T-1} x_k.$$

Using the same trick in 1), we apply the Lemma n times before $\|\bar{x}_{(n)} - x^*\|^2 \leqslant \frac{1}{2^n}\|x_0 - x^*\|^2 \leqslant \epsilon$. Then the total iterations are:

$$t(\epsilon) = \mathcal{O}(nT)$$

$$= \mathcal{O}\left(4\sqrt{\frac{2\beta}{\alpha}}\log_2\left(\frac{\|x_0 - x^*\|^2}{\epsilon}\right)\right)$$

$$= \mathcal{O}\left(-\sqrt{\frac{\beta}{\alpha}}\log_2 \epsilon\right).$$

In this case, Nesterov's accelerated gradient descent method yields linear convergence:

$$\epsilon(t) = \mathcal{O}\left(2^{-t\sqrt{\frac{\alpha}{\beta}}}\right).$$

Table 1 compares the bounds on error $\epsilon(t)$ while applying Nesterov's method and ordinary gradient descent method to different functions. Nesterov's accelerated gradient descent method has a faster convergence rate than the ordinary gradient descent method.

	Nesterov's Method	Ordinary GD Method
β-smooth, convex	$\mathcal{O}\left(\frac{\beta}{t^2}\right)$	$\mathcal{O}\left(\frac{\beta}{t}\right)$
β-smooth, α-strongly convex	$\mathcal{O}\left(2^{-t\sqrt{\frac{\alpha}{\beta}}}\right)$	$\mathcal{O}\left(2^{-t\frac{\alpha}{\beta}}\right)$

Table 1: Bounds on error ϵ as a function of number of iterations t for different methods.

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References