

Figure 4: Accuracy curve using a large-size training set. For Random and PUIS, the bottom x-axis (number of selected samples) is used. For PUIW, the top x-axis is used (the value of α).

Task	KLD	ALL	PUIS	PUIW
Video \rightarrow Apparel	166.69	0.7440	0.7704	0.7995
Video \rightarrow Baby	160.50	0.7494	0.7759	0.7932
Video \rightarrow Books	85.61	0.7328	0.7952	0.7893
Video \rightarrow Camera	146.61	0.7747	0.8164	0.8278
Video \rightarrow DVD	66.71	0.7877	0.8169	0.8180
Video \rightarrow Electronics	143.87	0.7213	0.7603	0.7712
Video \rightarrow Health	159.73	0.7331	0.7576	0.7826
Video \rightarrow Kitchen	155.72	0.7424	0.7736	0.7980
Video \rightarrow Magazines	122.53	0.8030	0.8344	0.8484
Video \rightarrow Music	99.49	0.7562	0.7581	0.7734
Video \rightarrow Software	136.48	0.7411	0.8078	0.7830
Video \rightarrow Toys	134.84	0.7679	0.7858	0.8066
Average	—	0.7545	0.7877	0.7993

Table 2: Accuracy comparison using a large-size training set.

4.3 Further Discussion

We finally investigate the relation between K-L divergence (KLD) and the accuracy improvements of our approach. It is known that KLD measures the difference of two distributions. In our tasks, KLD represents the distributional change from the training set to test set. Hence, when KLD is small, the space of improvements in domain adaptation is limited; when

KLD increases, the space of improvements also becomes larger.

In Figure 5, we draw the relation of KLD and the accuracy increase gained by PUIW. It can be observed that, KLD and accuracy increase are in a linear relation generally, except for few aberrant points. It indicates that our approach has a good property: the larger the KLD of the training and test data is, the more effective our approach will be.

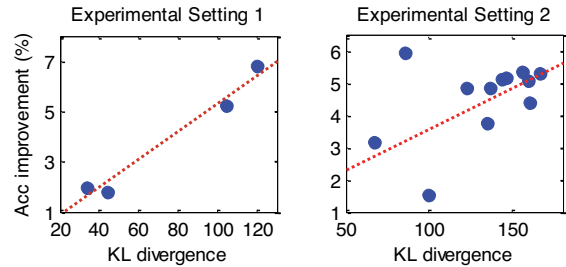


Figure 5: The relation between KLD and Accuracy Increase across all of the tasks (Each point represents one task).

5 Conclusions

In this paper, we propose a novel approach for cross-domain sentiment classification, based on instance selection and instance weighting via PU learning. PU learning is first used to learn an in-target-domain selector, and assign an in-target-domain probability to each sample in the training set. Based on the in-target-domain probabilities, two models namely PUIS and PUIW, are developed. The experimental results prove the necessity and effectiveness of the approach, especially when the size of training data is large. The results also indicate another good property of our approach: the larger the K-L divergence between the training and test data is, the more effective our approach will be.

Shortcomings of this work contain two aspects: 1) Explicit model selection, such as the determination of the number of selected samples and the value of the calibration parameter α , are not involved; 2) It lacks the consideration for labeling adaptation (we simply assume $p_s(y|\mathbf{x}) \approx p_t(y|\mathbf{x})$ in Section 3.3) in instance adaptation. Both of them are very important issues, and we will perform some related investigation in our future work.

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