where

$$J_b = \frac{1}{L} \sum_{i=1}^{L} \sum_{j=1, j \neq l(x_i)}^{M} (x_i - x_{ij}^b)(x_i - x_{ij}^b)^T$$

and

$$J_w = \frac{1}{L} \sum_{i=1}^{L} (x_i - x_i^w)(x_i - x_i^w)^T$$

Afterwards, the objective function can be expressed as

$$\underset{P}{\operatorname{arg\,max}} \frac{P^T J_b P}{P^T J_w P}$$
s.t.
$$P^T P = I$$

(20)eral vision recognition databases.

$$\underset{P}{\operatorname{arg\,max}} \frac{P^{T}J_{b}P}{P^{T}J_{w}P}$$

term εI is increased without affecting the subspace. Thus, LFW-a database (Zhu et al. 2012) is used in this exthe objective function can be rewritten as

$$\underset{P}{\operatorname{arg\,max}} \frac{P^{T} J_{b} P}{P^{T} (J_{w} + \varepsilon I) P}$$

$$s.t. \quad P^{T} P = I$$

where ε is a small number and I is an identity matrix. \mathbf{SVM} By using Lagrange multiplier, the projection matrix P $[p_1,...,p_k,...,p_d]$ that maximizes the objective function, RCR which can be gained by solving the eigen decomposition (Saeidi, Astudillo, and Kolossa 2016), problem of $\frac{J_b}{J_w + \varepsilon I}$ as

$$J_b p_k = \lambda_k (J_w + \varepsilon I) p_k \quad , k = 1, 2, ..., d$$
 (2)

their corresponding eigenvectors, $p_1, ..., p_k, ..., p_d$ of $\frac{J_b}{J_{av}}$. ItDPRC has more than 3% improvement.. is noted that $P = [p_1, ..., p_k, ..., p_d]$ is a $q \times d$ projection matrix, which can project the original q-element data vector to the new d-element data vector as $w_i = P^T x_i$ for i =

Classification

1, 2...L.

In the above Section, DPRC obtains the effective discriminant space $W = \{w_i \in R^{d \times 1}, i = 1, 2, \dots, L\}$. Using the

discriminant space W and Algorithm I the approximation Table 1: The recognition rate (RR) of several classifiers on projection of the last subspace The distance of the last subspace of the last subs e computed as

DPRC selects the class with the minimum distance

$$\min_{c^*} d_c(w), c = 1, 2, \cdots, M.$$

where $w = P^T x$.

DPRC vs ULDA

method: Uncertain LDA based Saeidi, Astudillo, and Kolossa 2016). To better explain it, LC-KSVD their similarity and difference are given as follows.

(Haeb-Umbach and Ney 1992).

where S_b , S_w are the within-class and between-class scatters in LDA. ULDA proposes the uncertain within-class and between-class scatters U_b, U_w . In DPRC, the J_b, J_w can be treated as new projection-based within-class and between-class scatters, which has significantly difference to S_b, S_w and U_b, U_w . (19)

• Difference: In ULDA, $J_b = S_b + U_b, J_w = S_w + U_w$,

Experimental Results

This section evaluate the proposed PRC and DPRC on sev-

In order to address the typical small sample size problem, the Face recognition

periment. Following (Zhang et al. 2015), we apply 158 subjects that have no less than ten samples for eval-(21) uation. The experiment set: 5 samples are randomly selected to form the training set, while other 2 samples are exploited for testing. The SRC (Wright et al. 2009), (Schüldt, Laptev, and Caputo 2004), **FDDL** =(Yang et al. 2014), MCT (Zhang et al. 2015), (Yang et al. 2012), ULDA **ProCRC** (Cai et al. 2016) and CRC (Zhang, Yang, and Feng 2011)

(22) algorithms are chosen for comparison. Table 1 illustrates the comparison results of all methods. DPRC obtains better where $\lambda_1 \geq ... \geq \lambda_k \geq ... \geq \lambda_d$ is d largest eigenvalues and performance than PRC. Compared to the exsiting methods,

Classifier	Accuracy	Classifier	Accuracy (%)
SRC	44.10	CRC	44.30
SVM	43.30	ULDA	44.30
FDDL	42.00	ProCRC	44.90
MCT	44.90	PRC	46.84
RCR	36.70	DPRC	47.90

23 Scene classification

The well-known 15 scene database contains 4,485 images of (24)15 scene categories (Lazebnik, Schmid, and Ponce 2006). Each image is transformed to spatial pyramid feature provided by (Jiang, Lin, and Davis 2013). The following experimental protocol is used (Liu and Liu 2015): 100 images per class are randomly chosen for train-This section compares DPRC with a discriminant-ing and the rest images are used for testing. The D-(ULDA)KSVD (Zhang and Li 2010), LLC (Wang et al. 2010), (Jiang, Lin, and Davis 2013), ULDA (Saeidi, Astudillo, and Kolossa 2016), LLNMC • Similarity: They both maximize the following objective function $\max_{P} J(P) = \max_{P} \frac{J_b}{J_w}$, where J_b, J_w (Liu and Liu 2015), SRC (Wright et al. 2009), are the within-class and between-class scatters. This ProCRC (Cai et al. 2016), DADL (Guo et al. 2016) methods objective function is the same to that in LDA are chosen for comparison. The average classification rate of 10 runs is used to evaluate all methods. From the results