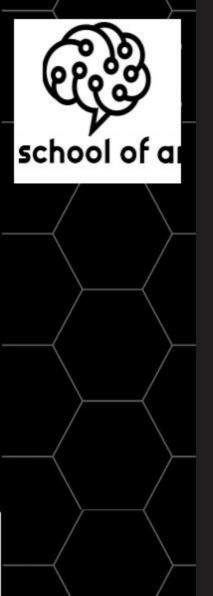


### **Unsupervised Learning: Dimensionality reduction**

**AAA-Python Edition** 



### Plan

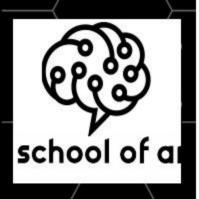
- 1- Dimensionality reduction
- 2- Some Math
- 3- PCA
- 4- PCA in scikit-learn
- 5- Manifold Learning
- 6- Manifold Examples



### 1- Dimensionality reduction

### Objective

- Dimensionality reduction in machine learning is reducing the number of features of the training dataset.
- This reduction is necessary to:
  - Fliminate the **noise** from the data
  - Visualize the data in 2 or 3 dimensions
  - Speed up the learning process
  - > Enhance the learning results by eliminating correlated features.
  - Eliminate unnecessary features.
  - Compress the data size.
- Two main approaches to dimensionality redcution are:
  - Projection: project the data into a lower dimensional space.
  - Manifold: suppose that the data in the higher dimension is just a manifold of a representation of the data in the lower dimension.



### 1- Dimensionality reduction

### Projection

- Sometimes the degree of the variation of the data is different from one dimension to an other. So, for some features, the values can be very diverse, an for others, they can barely change.
- So we project the data into a lower dimension in order to keep only the most influential **information** ==> we define a mapping between the original data from the higher dimension to new data in a lower dimension.

- The most used technique to define this mapping, is PCA (Principal Component Analysis) and its variations:
  - Incremental PCA
  - Randomized PCA
  - Kernel PCA



### 1- Dimensionality reduction

### Manifold

• Like we said earlier, we make the hypothesis that our data is created from a **manifold** of a data in a **lower dimension**. So, reducing it to this low dimension is like **straightening up** this manifold (or **unrolling it**).

- The different techniques used, are:
  - MDS: Multidimensional Scaling. Tries to preserve the distances between instances.
  - LLE: Locally Linear Embedding. Tries to preserve the relationship between a sample and its closets points.
  - Isomap: the samples will represent nodes of a graph. These nodes are connected to their closets neighbors. The algorithm tries to preserve the number of nodes in the shortest path connecting two nodes.

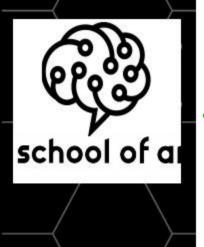


## 2- Some Math

### Singular value decomposition

• It is the the decomposition of a matrix  $\mathbf{M}_{(m,n)}$  into  $\mathbf{3}$  matrices:  $\mathbf{U}_{(m,m)}$ ,  $\mathbf{S}_{(m,n)}$ , and  $\mathbf{V}_{(n,n)}$ . Considering only **real** values, we have the following characteristics:

- M = U .S . V<sup>T</sup> ( V<sup>T</sup> is the transpose matrix of V : value at i,j becomes at j,i )
- $\rightarrow$  U . U<sup>T</sup> = U<sup>T</sup> . U = I<sub>(m,m)</sub> (the identity matrix)
- $\rightarrow$  V . V<sup>T</sup> = V<sup>T</sup> . V<sup>T</sup> = I<sub>(n,n)</sub>
- The diagonal (values with the same row and column indices) of S are the Singular values of M
  - → Singular values are the square roots of **eigenvalues**
  - The other values of S are zeros.
- The columns of U are the eigenvectors of M . M<sup>T</sup>.
- > The columns of **V** are the **eigenvectors** of **M<sup>T</sup>. M**.



## 2- Some Math

### Eigenvectors, Eigenvalues

- Given **A** (n,n) a square matrix:
  - → If A .  $V_{(n)} = \lambda$  .  $V_{(n)}$  then: V is an **eigenvector** and  $\lambda$  is its corresponding **eigenvalue**.
  - → The above equation can be rewritten as follow: (A-  $\lambda$ I). V= 0
  - ightharpoonup Several ho can solve the equation. For each ho lambda value, an eigenvector is computed.
- Example:

$$|A| = \begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix}$$

- Its eigenvalues will be: 1, 3
- And their corresponding eigenvectors will be:  $\begin{vmatrix} 1 \\ -1 \end{vmatrix}$  and  $\begin{vmatrix} 1 \\ 1 \end{vmatrix}$



## 2- Some Math

### Standard Deviation

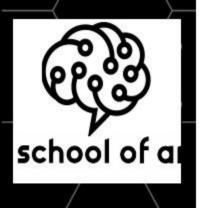
- The standard deviation  $\sigma$  measures how data is spread (or distant from the mean) . It is the **square root** of the **variance.**
- The variance is computed as follow:

variance = 
$$\frac{\sum_{i=1}^{N} (x_i - \mu)^2}{N}$$

And the standard deviation:

$$\sigma = \sqrt{variance}$$

 To project data on new axis, we select the axis that preserve the maximum possible variance of the data. This way, most of the information is preserved.

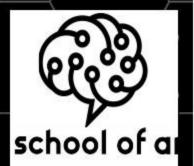


# 3- PCA in scikit-learn

### Definition

- It is a linear dimensionality reduction technique that project data using orthogonal axes (components) that preserve the maximum variance possible. One of the method used is singular value decomposition of the mean centered training data.
- As stated before the decomposition leads to 3 matrices. The vectors of the matrix V<sup>⊤</sup> will be used to project the data. They are the "principal components".
- Each component will conserve a certain amount of variance. The variance obtained after projection is the accumulation of the variances obtained by each component
- To project, we select a sufficient number of component to preserve the maximum of variance, then we apply the transformation (the projection), using only this number of vectors.
- The number of vectors will determine the dimension of the projection.

**IBv** Amina Delal



# 3- PCA in scikit-learn

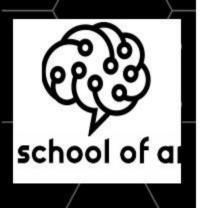
### Example

```
# import necessary libraries
 import numpy as np
 from sklearn.datasets import load iris
 import sklearn.preprocessing as preprocess
  1 # loading the data ( 4 feautres ==> 4 dimensions)
  2 myIris = load iris()
  3 X= myIris.data
  4 v=mvIris.target
from numpy import mean
# centring the data
X centred = preprocess.scale(X,with std=False, axis=0)
X centred = X - X.mean(axis=0)
# extracting the principal component
U, s, V = np.linalg.svd(X centred)
# extracting the 3 first principal commponets
cl = V.T[:,0]# V.T is the transopose of V
c2 = V.T[:,1]
c3 = V.T[:,2]
  # compute the projection in a 3D dimension
  C3 = V.T[:::3]
  X3d = X centred.dot(C3)
```

Center the data to the mean, before applying the decomposition

The decomposition

To project, we multiply the centered data by the first selected component==> we will have a 3 dimensions projection

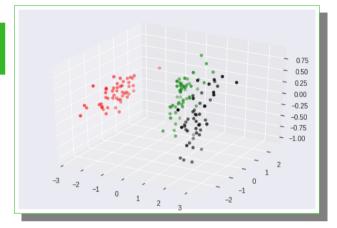


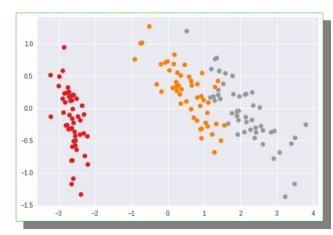
PCA in scikit-learn

M

### Results

3D projection





2D projection

Since our data was originally labeled (we don't use those label for decomposition), we used them for colorizing the data.

And what is obvious, is that the data is clustered according to its classes. Which proofs:

- that the clustering can in certain cases classify data.
- the decomposition preserved the most important amount of information.

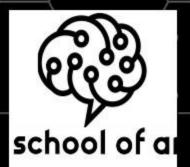


## - Processing Data

[By Amina Delali]

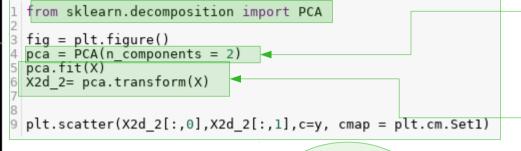
### With matplotlib

```
are using matplotlib version 2.1.2
                                                                     It tells to only
        l be removed in version 3.1
     matplotlib.mlab import PCA as PCA2
                                                                     center the
my2PCA = PCA2(X, standardize=False)
results = my2PCA.project(X, minfrac=0.02)
                                                                     data, and to
fig = plt.figure()
plt.scatter(results[:,0],results[:,1],c=y, cmap = plt.cm.Set1)
                                                                     not
                                                                     standardize
  It will drop all the axis with
  variance ratio < minfrac.
                                                 10
  In this case, it will only
  keep 2 axis.
                                                 -0.5
Same results as in our
previous implementation
                                                 -1.0
                                                -1.5
```



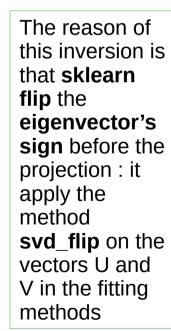
4- Processing Data

### With sklearn

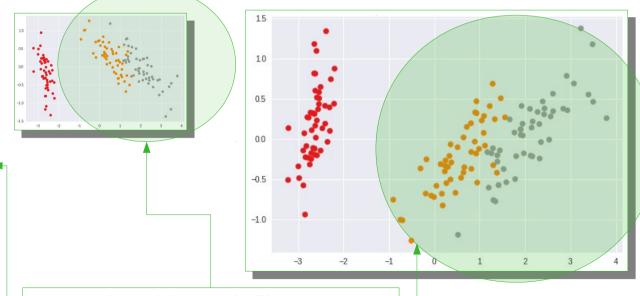


We have to select the number of components before transforming the data

As in matplotlib, we don't have to center the data



[By Amina Delali]



Comparing with matplotlib we see that the directions are inverted

13



## 4- Processing Data

### Explained variance ratio

- The correct number of components can be defined by the explained variance ratio of each component.
- It is computed by the value of explained variance divided by the sum of all variances.
- The ratio of each component are **summed up** until a certain percentage is obtained.
- The variances can be computed from the square of the singular values in S

```
# the explained variance ratio (our implementation, 2D)

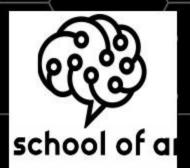
explained_ratio_2FirstC = (np.square(s[0])+ np.square(s[1]))/np.sum(np.square(s))

# explained variance ratio (with matplotlib, 2D)

EVR2= my2PCA.fracs[0] + my2PCA.fracs[1]

# explained variance_ratio (with sklearn, 2D)

EVR2= np.sum(pca.explained_variance_ratio_)
```



### 5- Manifold Learning: LLE

### Algorithm

- LLE for Locally Linear Embeeding. The algorithm consist of 3 major steps:
- Step 1 identifying the neighbors for each sample x<sub>i</sub> from the data X<sub>(N,D)</sub> (for N samples and D features):
  - Compute the distances of the other samples from x<sub>i</sub>
  - > Select the **k** smallest distances.
- Step 2 for each sample x<sub>i</sub> compute its neighbors weights:
  - > Create the matrix  $Z_{(k,D)}$  with the k samples rows from  $X_{(N,D)}$  corresponding to the neighbors of  $x_i$
  - > Subtract  $x_i$  values from each row of  $Z_{(k,D)}$
  - > Compute  $C_{(k,k)} = Z_{(k,D)}$ .  $Z_{(D,k)}^T$  in the original page it is inverted because of X and Z are transposed)
  - > Compute the row **i** of the matrix  $\mathbf{W}_{(\mathbf{N},\mathbf{N})}$  with:
    - → Compute the weights in the one column vector  $\mathbf{w}_{(\mathbf{k},\mathbf{1})}$  that solve the equation  $C_{(\mathbf{k},\mathbf{k})}$ .  $\mathbf{w}_{(\mathbf{k},\mathbf{1})} = 1_{(\mathbf{k},\mathbf{1})}$  (1 is a column vector with only 1 as

values)

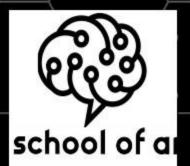
15



### 5- Manifold Learning LLE

### Algorithm (Suite)

- $\rightarrow$  For the samples **j** that do not belong to each  $x_{i,}$  neighbors, set the weights to **0**.
- → For each neighbor b of x<sub>i</sub> set the weight to: w(p) /sum(w<sub>(k,1)</sub>). Where p is the indices in w corresponding to the b neighbor of x<sub>i</sub>
- Step 3 reduce the dimensionality to d < D in a new matrix</li>
   Y<sub>(N,d)</sub>:
  - > Compute the matrix  $\mathbf{M}_{(\mathbf{N},\mathbf{N})} = (\mathbf{I}_{(\mathbf{N},\mathbf{N})} \mathbf{W}_{(\mathbf{N},\mathbf{N})})^{\mathsf{T}} \cdot (\mathbf{I}_{(\mathbf{N},\mathbf{N})} \mathbf{W}_{(\mathbf{N},\mathbf{N})})$
  - Select the d+1 eigenvectors of M<sub>(N,N)</sub> corresponding to the d+1 smallest eigenvalues. Order these eigenvectors according to the corresponding eigenvalues sorted in a decreasing order.
  - For each column q in Y set the values equal to the values of the q+1 smallest eigenvector counting from the bottom (to discard the last eigenvector corresponding to the eigenvalue 0)



# 5- Manifold Learning:

### Example

from sklearn.datasets import make\_swiss\_roll
#from sklearn.datasets.samples\_generator import make\_swiss\_roll
X\_swiss, color = make\_swiss\_roll(n\_samples=1500) N== 1500, D == 3 0.100 0.075 0.050 0.025 0.000 -0.025-0.050 -0.075 -0.06from sklearn import manifold
X\_r, err = manifold.locally\_linear\_embedding(X\_swiss, n\_neighbors=12,

[By Amina Delali]

LLE: k == 12, d == 2

n\_components= 2)



# -Polyno

### Algorithm

- There are two types of Multidimensional Scaling: classical (or metric) that tries to reproduce the original distances. The second one is non-metric (NMDS) that tries to reproduces only the rank of the distances.
- We will describe the algorithm of the classical method using the euclidean distance:
  - Compute the distances between all points, and form a matrix of those distances in a matrix **D**.
  - > Compute the matrix **A** as follow:  $A(i,j) = -1/2 * D(i,j)^2$
  - Compute the matrix **B** as follow: B(i,j)= A(i,j)- A(i,.) A(.,j) +A(.,.) where: A(i,.) is the average of all A(i,j) for a selected i A(.,j) is the average of all A(.,j) for a selected j A(.,.) is the average of all values of A
  - Find the **p** (the **new dimension, lesser** than the original dimension ) largest eigenvalues of B:  $\lambda_1 > \lambda_2 > ... > \lambda_p$  and their corresponding normalized eigenvectors  $L_1^p, L_2^p, ..., L_p$  so that  $L_1^T$ .  $L_1 = \lambda_1$



## egression 6-Polyno

### Algorithm (suite)

- Form the matrix **L** as follow:  $L = (L_1, L_2, ..., L_p)$ . The new values (coordinates) are the **rows** of L.
- This method minimizes the value of the Stress
- The **stress** is a measure that can be used to find the optimal lower dimension. It is computed as follow:

• stress = 
$$\sqrt{\frac{\sum\limits_{i < j} (D(i,j) - \Delta(i,j))^2}{\sum\limits_{i < j} D(i,j)^2}}$$

- where:  $\Delta$  is the matrix of the distances of the new matrix L
- A stress with a value < 0.05 is acceptable, below 0.01 is considered to be good.

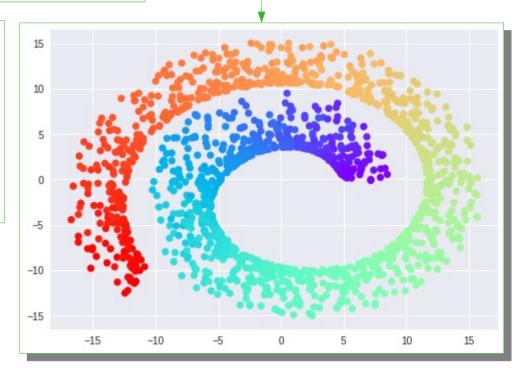


## Regression 6-Polyno

### Example in Scikit-learn

```
from sklearn.manifold import MDS
embedding = MDS(n_components=2)
X_transformed_mds = embedding.fit_transform(X_swiss)
```

The results are completely different from the previous manifold technique. We see here, the goal is to keep the same original distances values as much as possible.





### References

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## Thank you!

FOR ALL YOUR TIME