

Inferring the ocean subsurface using generative AI

Andre Souza

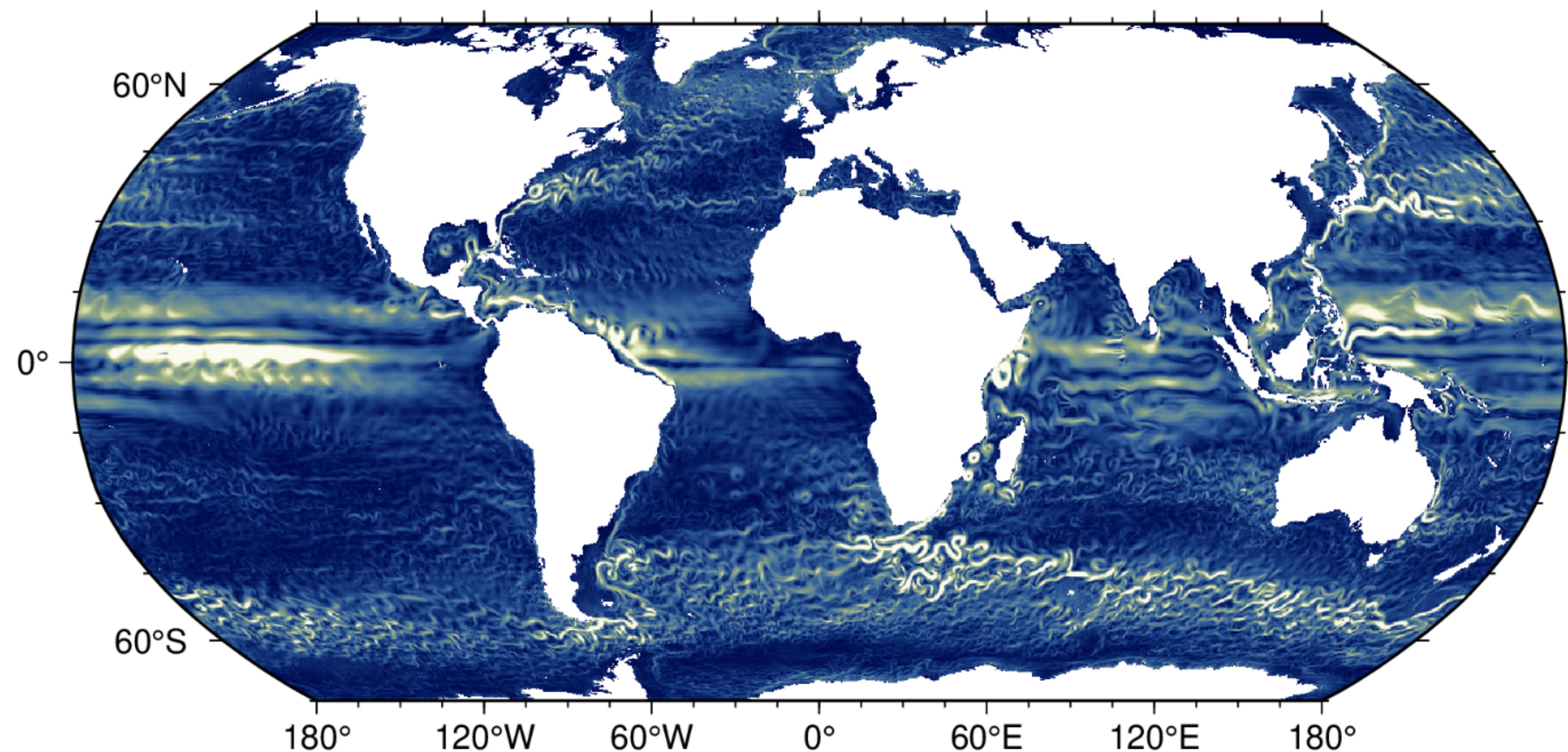


Recap

We've seen Satellites



We've seen Ocean



We've seen Models

$\hat{X} = \sqrt{\frac{m\omega}{n}} X$, $\hat{P} = \frac{1}{\sqrt{m\hbar\omega}} P$ (a) $\begin{bmatrix} 0 & \sqrt{1} & 0 & 0 & \dots & 0 \\ 0 & 0 & \sqrt{2} & 0 & \dots & 0 \\ 0 & 0 & 0 & \sqrt{3} & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 & \sqrt{n} \end{bmatrix}$ $(a^\dagger) = \begin{bmatrix} 0 & 0 & 0 & 0 & \dots & 0 \\ \sqrt{1} & 0 & 0 & 0 & \dots & 0 \\ 0 & \sqrt{2} & 0 & 0 & \dots & 0 \\ 0 & 0 & \sqrt{3} & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \sqrt{n} & \dots & 0 \end{bmatrix}$ $\left(\frac{d\theta}{(0_i - \theta^2)}\right)^{1/2} = \left(\frac{g}{\ell}\right)^{1/2} dt$ $= \frac{d^2 r}{d\phi^2} \left(\frac{\Delta}{\mu r^2}\right) - \frac{\varepsilon}{r^3} \cdot \frac{\Delta}{\mu} \cdot \left(\frac{\partial r}{\partial \phi}\right) \cdot \frac{\Delta}{\mu r^2}$
 $\hat{H} = \frac{1}{2} (\hat{X}^2 + \hat{P}^2)$ $\hat{H} = \hbar\omega \hat{H}$ $\hat{H} = \frac{1}{2} (\hat{X}^2 + \hat{P}^2) + \frac{1}{2} \hbar\omega \hat{H}$ $\left(\frac{d\theta}{(0_i - \theta^2)}\right)^{1/2} = \left(\frac{g}{\ell}\right)^{1/2} dt$ $W(\phi) = \frac{1}{r(\phi)} \frac{dw}{d\phi} - \frac{1}{r^2} \frac{dr}{d\phi} \cdot \frac{dw}{d\phi^2} = -\frac{1}{r^2} \frac{d^2 w}{d\phi^2}$
 $\hat{H}|\psi_n\rangle = E_n|\psi_n\rangle$ $\hat{H}|\psi_n\rangle = E_n|\psi_n\rangle$ $\int_0^\pi \frac{d\theta}{(0_i - \theta^2)} = \left[A_{11} \sin\left(\frac{\theta}{0_i}\right) \right]_0^\pi = A_{11} \sin\left(\frac{\pi}{0_i}\right) - A_{11} \sin\left(\frac{0}{0_i}\right)$ $\frac{d^2 r}{dt^2} = -\frac{1}{r^2} \left(\frac{\Delta}{\mu}\right)^2 \frac{d^2 w}{d\phi^2} = -w^2 \frac{\Delta^2}{\mu^2} \frac{d^2 w}{d\phi^2}$
 $a = \frac{1}{\sqrt{2}} (\hat{X}_+ + i\hat{P})$ $[a, a^\dagger] = \frac{1}{2} [\hat{X}_+, \hat{P}_+, \hat{X}_-, i\hat{P}_-]$ $\varphi_0(x) = \langle x | \varphi_0 \rangle = \left(\frac{m\omega}{\pi\hbar}\right)^{1/4} e^{-\frac{1}{2} \frac{m\omega}{\hbar} x^2}$ $f_0 = \frac{\omega_0}{2\pi} = \frac{(g/\ell)^{1/2}}{2\pi}$ $N_a = (\hat{P}_+ \hat{P}_-) a = (Mg)^{1/2} \sin \theta$
 $a^\dagger a = \frac{1}{2} (\hat{X}^2 + \hat{P}^2 - 1)$ $[a, a^\dagger]^2 = 1$ $\varphi_n(x) = \left[\frac{1}{e^{n+1}} \left(\frac{\hbar}{m\omega}\right)\right]^{1/2} \left(\frac{m\omega}{\pi\hbar}\right)^{1/4} \left[\frac{m\omega x - d}{\hbar} \right] e^{-\frac{1}{2} \frac{m\omega}{\hbar} x^2}$ $\dot{x} = \omega_0 \sin(\omega_0 t + \phi)$ $x^2 + y^2 + z^2 = c^2 t^2$ $\beta = \frac{v}{c}$
 $\hat{H} = a^\dagger a + \frac{1}{2} = \frac{1}{2} (\hat{X}_- - i\hat{P}_-) (\hat{X}_+ + i\hat{P}_+) + \frac{1}{2}$ $\varphi_0(x) = \left(\frac{\hbar}{m\omega}\right)^{1/2} f_0 t$ $\omega_0 = (\hat{P}_+ \hat{P}_-) a = -ML^2 \dot{\theta} = -L M g \sin \theta$
 $\hat{H} = a a^\dagger - \frac{1}{2} = \frac{1}{2} (\hat{X}_- - i\hat{P}_-) (\hat{X}_+ + i\hat{P}_+) + \frac{1}{2}$ $\varphi_n(x) = \left(\frac{\hbar}{m\omega}\right)^{1/2} f_n t$ $\omega_0 = (\hat{P}_+ \hat{P}_-) a = -ML^2 \dot{\theta} = -L M g \sin \theta$
 $\langle P^2 \rangle = -\frac{\hbar^2}{2m} \int_{-\infty}^{+\infty} \varphi_n^*(x) \frac{d^2}{dx^2} \varphi_n(x) dx$ $x = A \sin(\omega_0 t + \phi)$ $\ddot{x} + \frac{\omega_0^2}{2} \sin \theta = 0$ $F_a = -C_a$ $M_a = -C_a$ $\ddot{x} + \frac{C}{m} x = 0$ $x' = \frac{x - vt}{(1 - v/c)^{1/2}}$
 $a^\dagger |\psi_n\rangle = \sqrt{n+1} |\psi_{n+1}\rangle$ $i\hbar \frac{\partial}{\partial t} \psi(\vec{r}; t) = -\frac{\hbar^2}{2m} \Delta \psi(\vec{r}, t) + V(\vec{r}, t) \psi(\vec{r}, t)$ $\ddot{x} = -\omega_0 A \sin(\omega_0 t + \phi)$ $E = Mc^2$
 $a |\psi_n\rangle = \sqrt{n} |\psi_{n-1}\rangle$ $\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$ $\int |\psi(\vec{r}, t)|^2 d^3r = 1$ $K = \frac{1}{2} M \dot{x}^2 = \frac{1}{2} M \left[\omega_0 A \cos(\omega_0 t + \phi) \right]^2$ $\frac{E}{(1 - v/c)^{1/2}} = Mc^2$
 $a^\dagger a |\psi_n\rangle = \frac{1}{2} a a^\dagger |\psi_{n-1}\rangle = \frac{1}{\sqrt{n}} (a^\dagger a + 1) |\psi_{n-1}\rangle$ $\langle K \rangle = \frac{\int_0^T k dt}{t_0} = \frac{1}{2} M \omega_0^2 A^2$ $\sum_{i=1}^n E_i = c^4$
 $= \sqrt{n} |\psi_{n-1}\rangle$ $\lambda_1 |\psi_1\rangle + \lambda_2 |\psi_2\rangle \Rightarrow \lambda_1^* \langle \psi_1 | + \lambda_2^* \langle \psi_2 |$ $L=0$ $\frac{1}{2} M \omega_0^2 A^2$ $\Delta t' = \Delta \tau = \left(1 - \frac{v^2}{c^2}\right)^{1/2} \Delta t$ $\varepsilon = \varepsilon \left(\frac{1 - \beta}{1 + \beta}\right)$
 $\langle \psi_{n-1} | \psi_n \rangle = 1$ $E = \langle U \rangle = \frac{1}{2} M \omega_r^2 A^2$ $\theta = \theta_0$ $\frac{1}{2} M \omega_0^2 A^2$ $E_0 = E + \frac{1}{2} \varepsilon + \frac{1}{2} \varepsilon_0$

**We've seen various ways of
combining models with data**



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combining models with data**

This talk will discuss (yet) another way

Combining Models with Data

- Physical theories let us make inferences using less information (Maxwell's equations)
- For complex systems (atmosphere, ocean, chaotic systems) the best we can do are numerical models (computational irreducibility)
- Using computational models with data-driven approaches allow us to extend the theory + data inferences

Combining Models with Data

- Physical theories let us make inferences using less information (Maxwell's equations)
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What kind of questions do we ask?

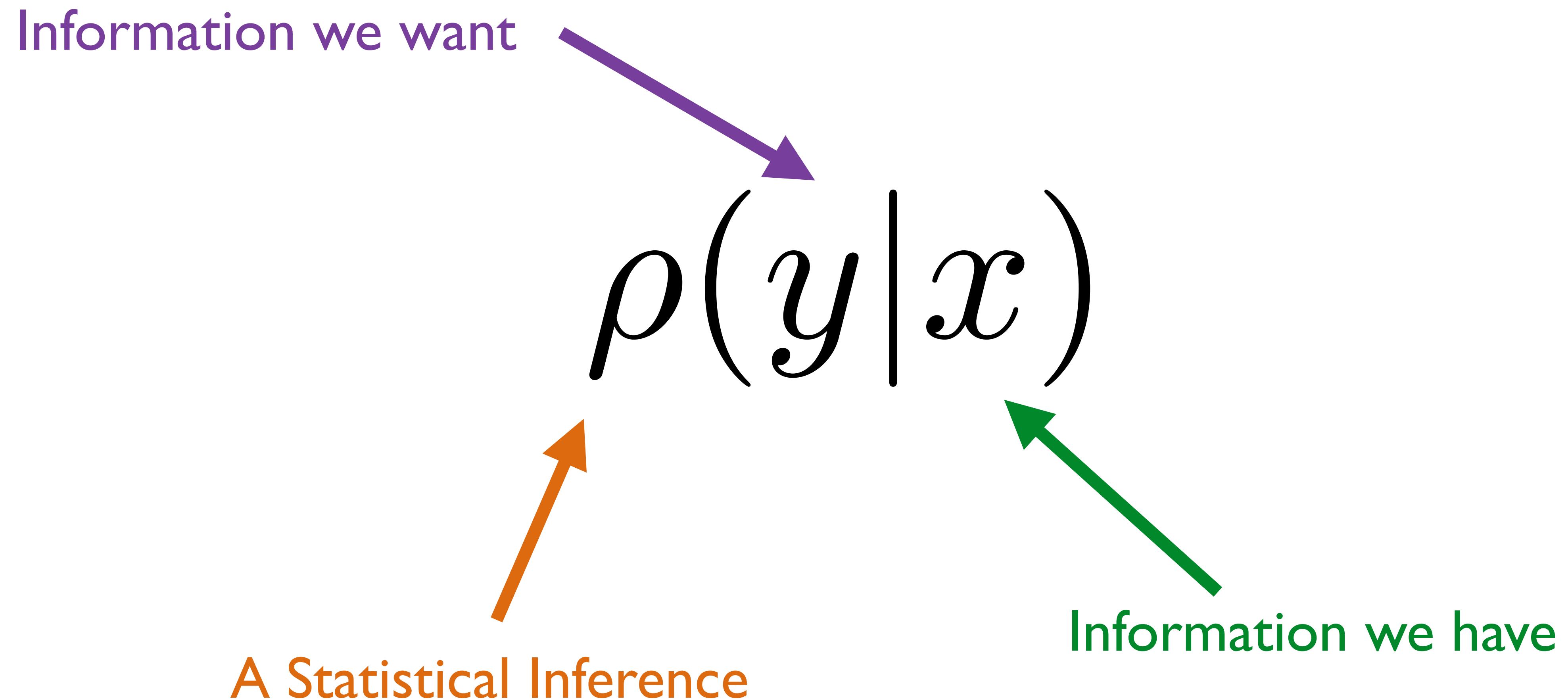
Information we want

$$y = f(x)$$

A mapping

Information we have

What kind of questions do we ask?



What kind of questions do we ask?

$$y = f(x) \qquad \rho(y|x)$$

$$\rho(y|x) = \delta(y - f(x))$$

What kind of questions do we ask?

$$y = x^2 \quad \rho(y|x)$$

$$\rho(y|x) = \delta(y - x^2)$$

What kind of questions do we ask?

$$y = x^2$$

$$\rho(x|y)$$

$$\rho(x|y) = \frac{\delta(x - \sqrt{y}) + \delta(x + \sqrt{y})}{2}$$

What kind of questions do we ask?

Useful Information

$$\rho(y|x) = \delta(y - f(x))$$

“Useless” Information

$$\rho(y|x) = \rho(y)$$

What kind of questions do we ask?

ill-posed

$$y = f(x)$$

well-posed

$$\rho(y|x)$$

What kind of questions do we ask?

ill-posed

$$y = f(x)$$

well-posed

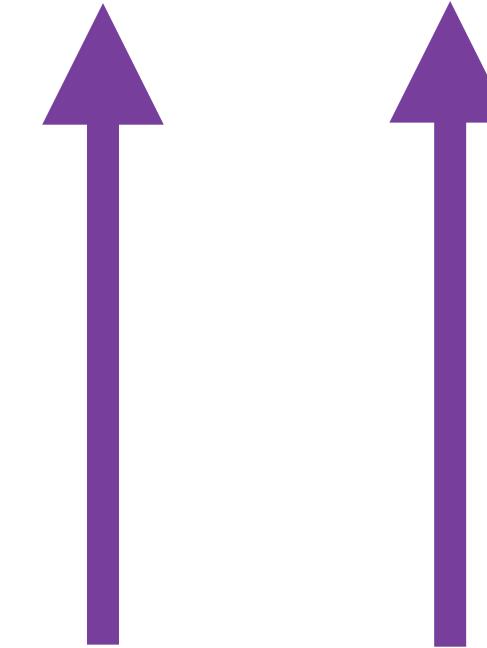
$$\rho(y|x)$$

connection

$$f(x) = \mathbb{E}_y \rho(y|x)$$

What can we do now that we couldn't do before?

$$p(y|x)$$



high-dimensional

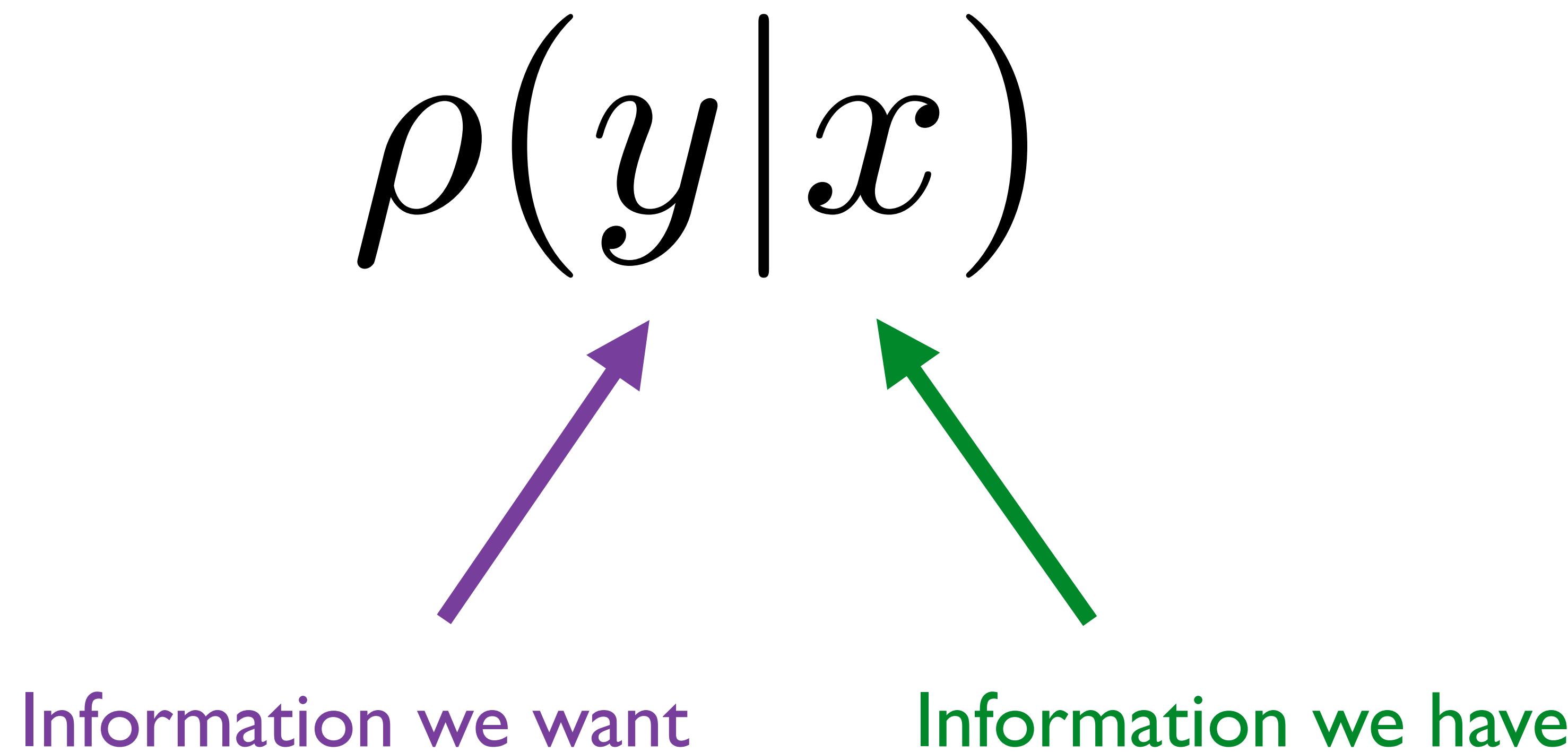
What can we do now that we couldn't do before?

$$p(y|x)$$

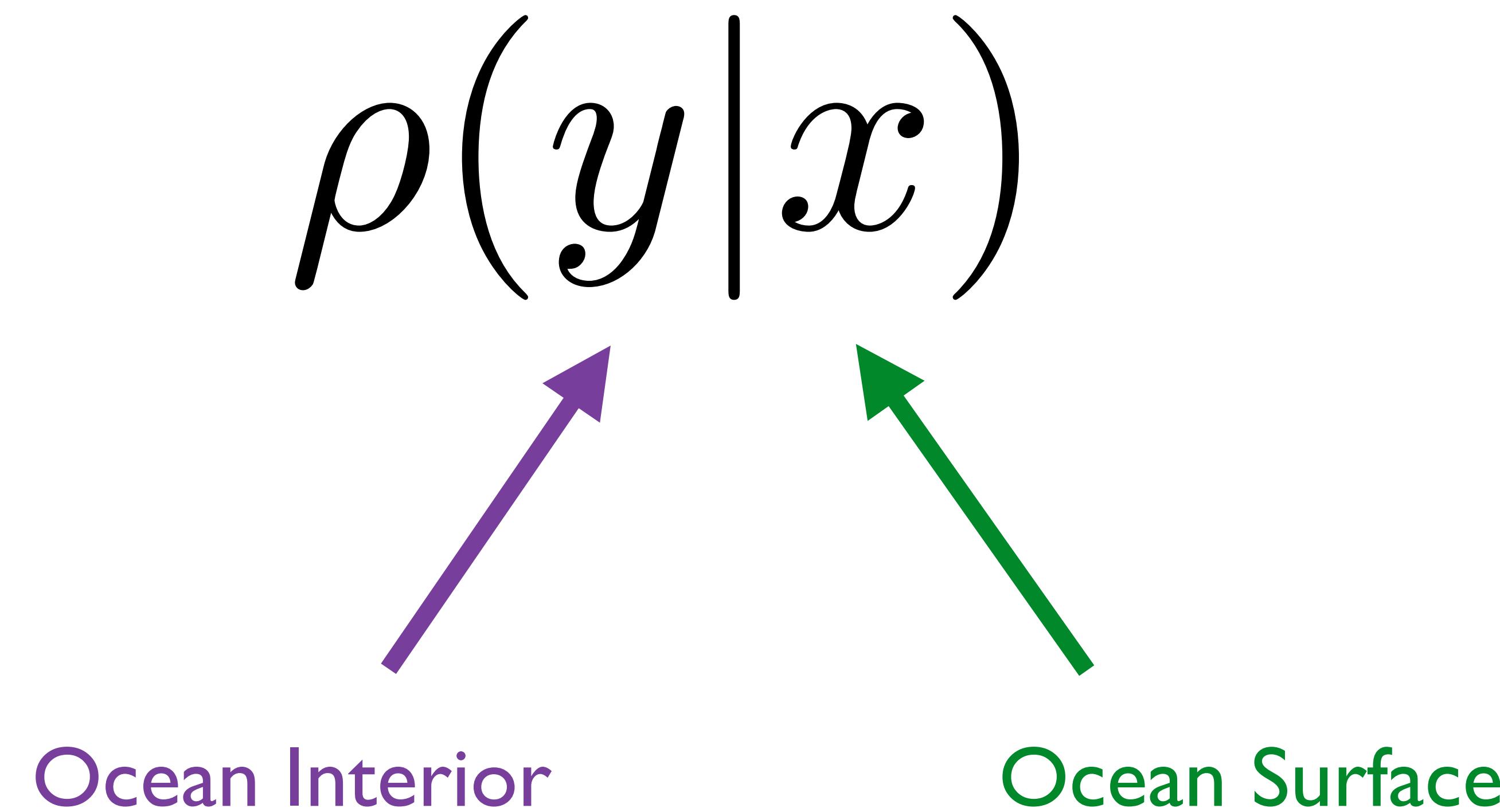
Method: Score-Based Diffusion Models

Architecture: Modified U-Net

Applications



Application: Ocean Inference



What we have



What we want



Application: Ocean Inference

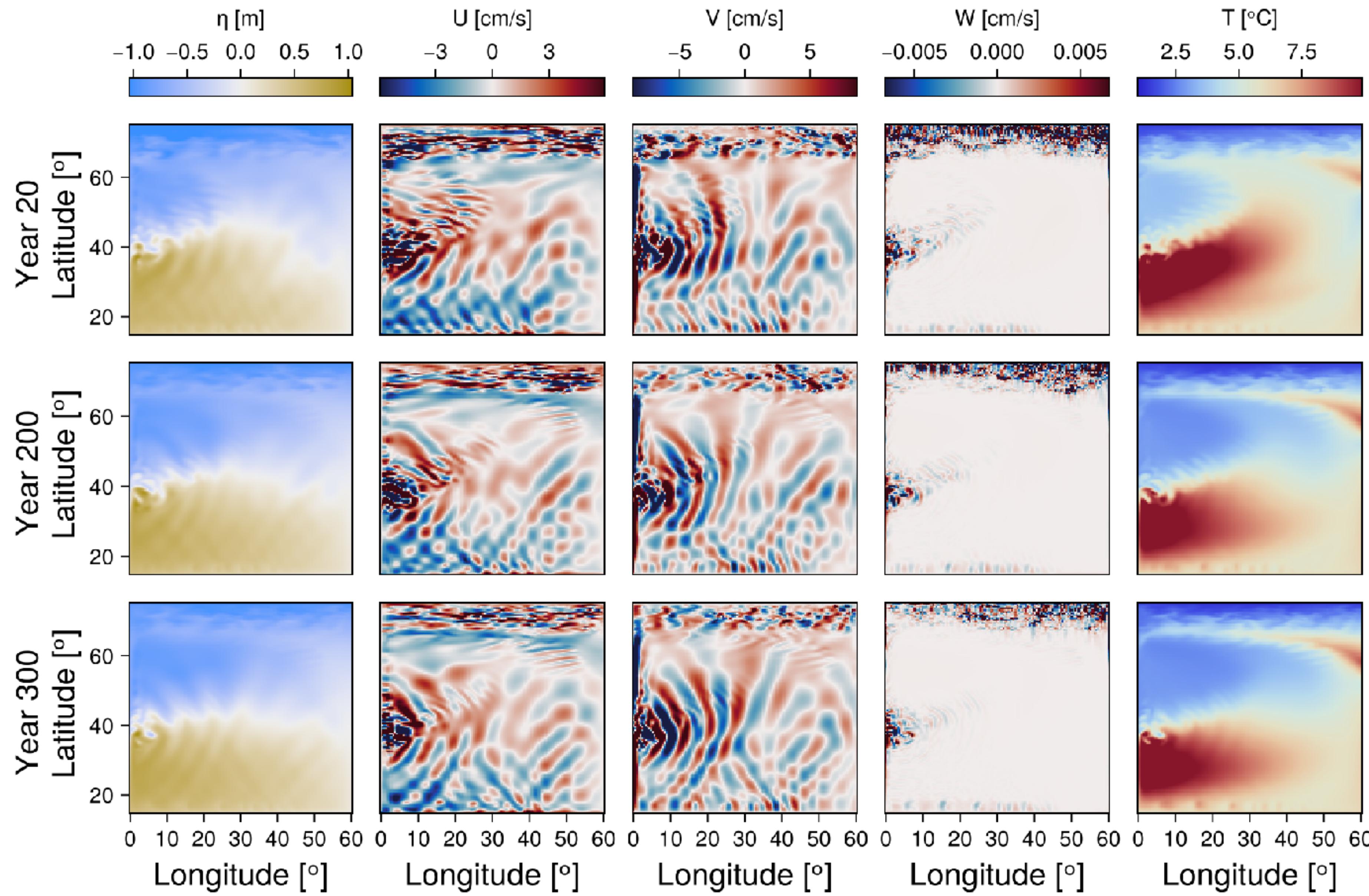
$$\rho(y|x)$$

Model: 3D Navier-Stokes with $256 \times 256 \times 15 \times 3$ degrees of freedom
(non-stationary)

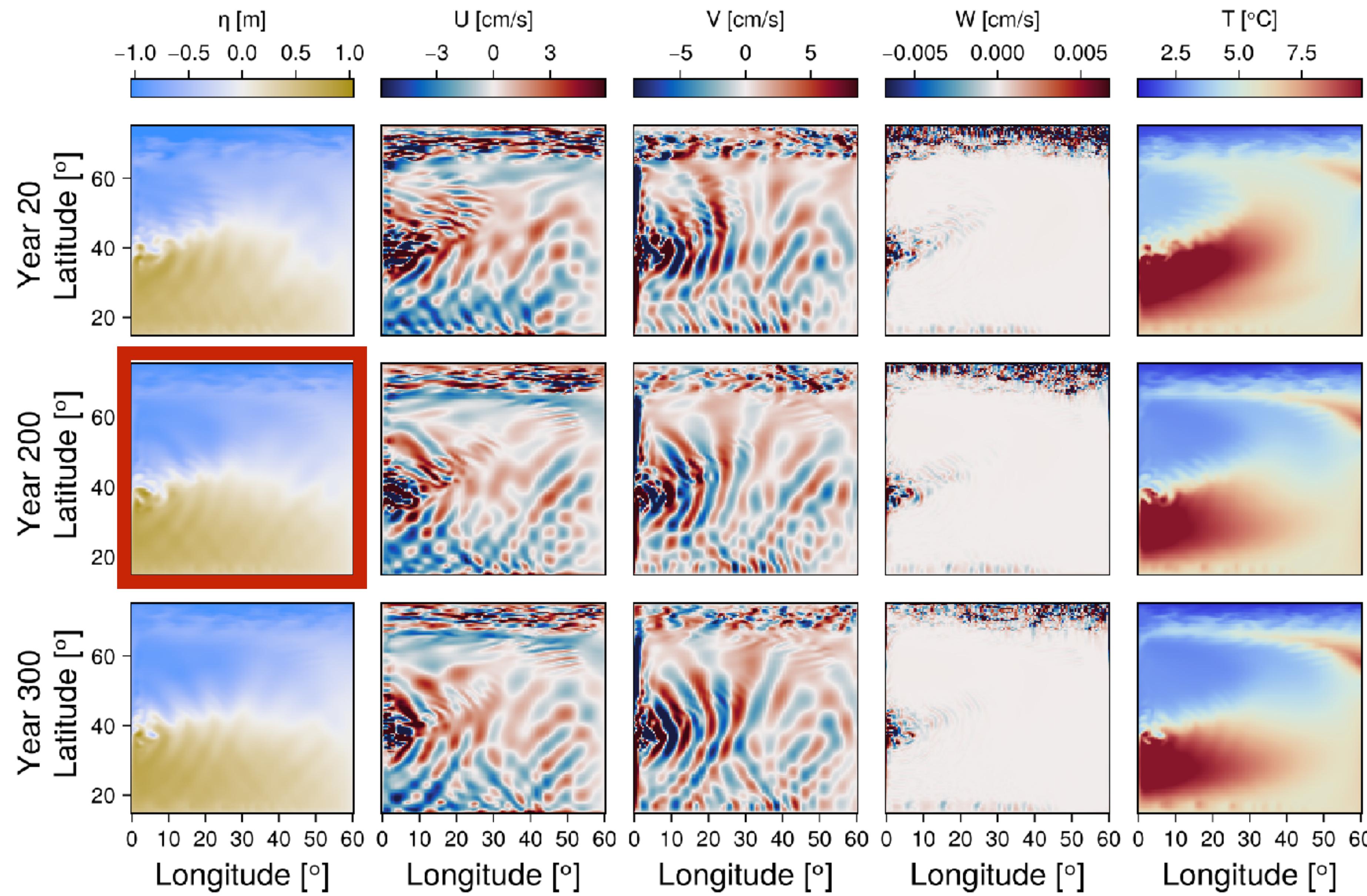
Given information “x”: Free Surface Height (different levels of coarse-graining)

Predicted Information “y”: The 3D Ocean Interior State

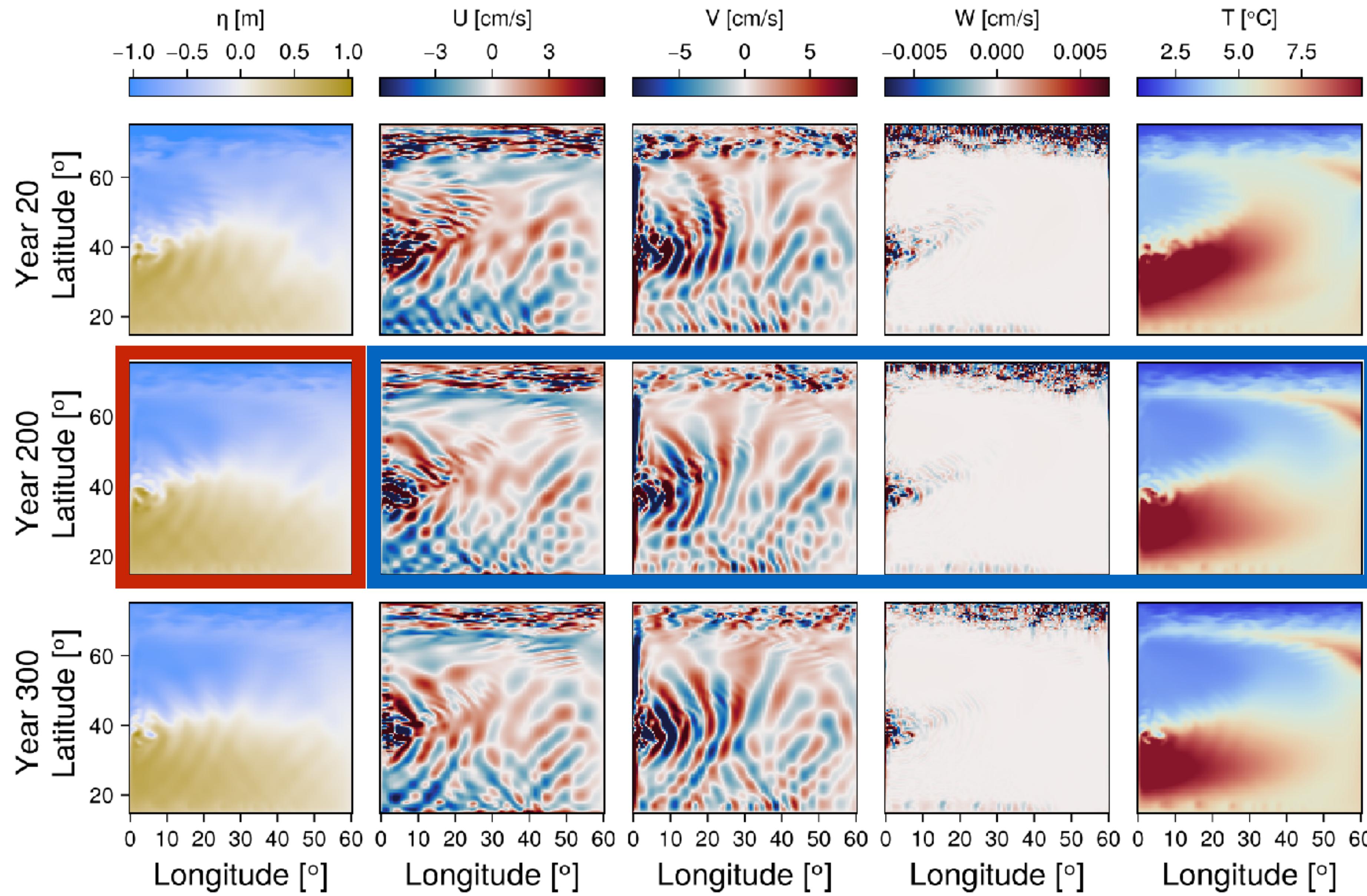
Application: Ocean Inference Task (400m depth)



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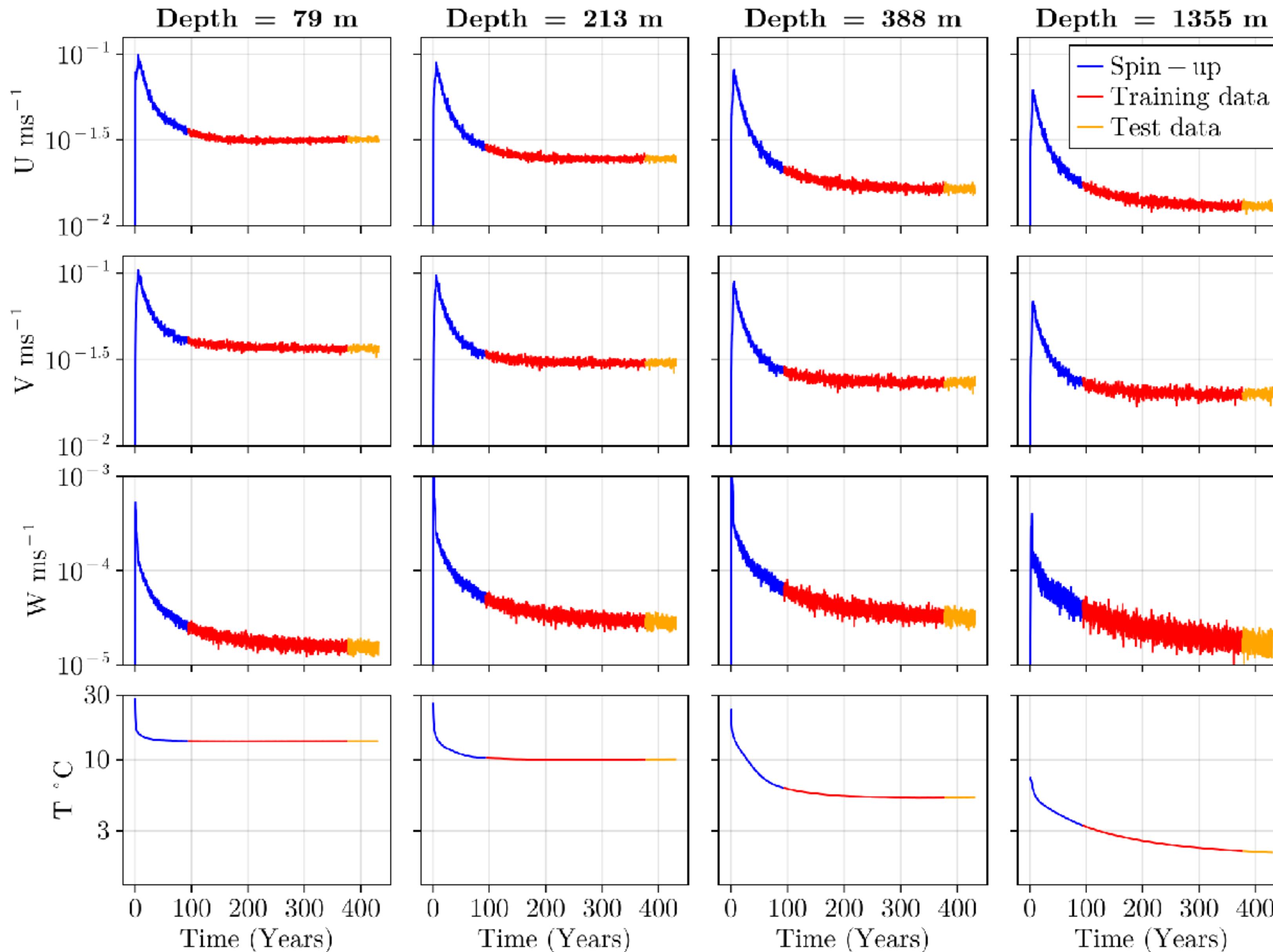


Application: Ocean Inference Task (400m depth)



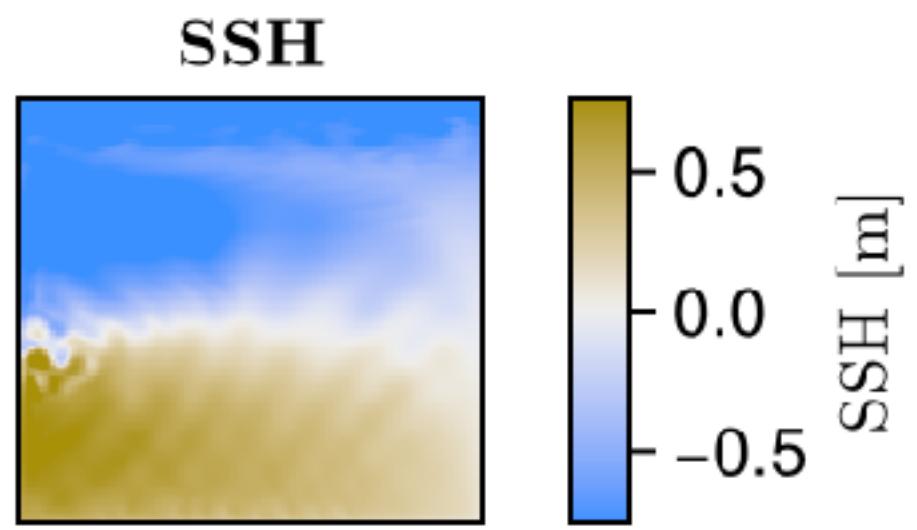
Training and Test Set: Non-stationarity

Application: Ocean Inference

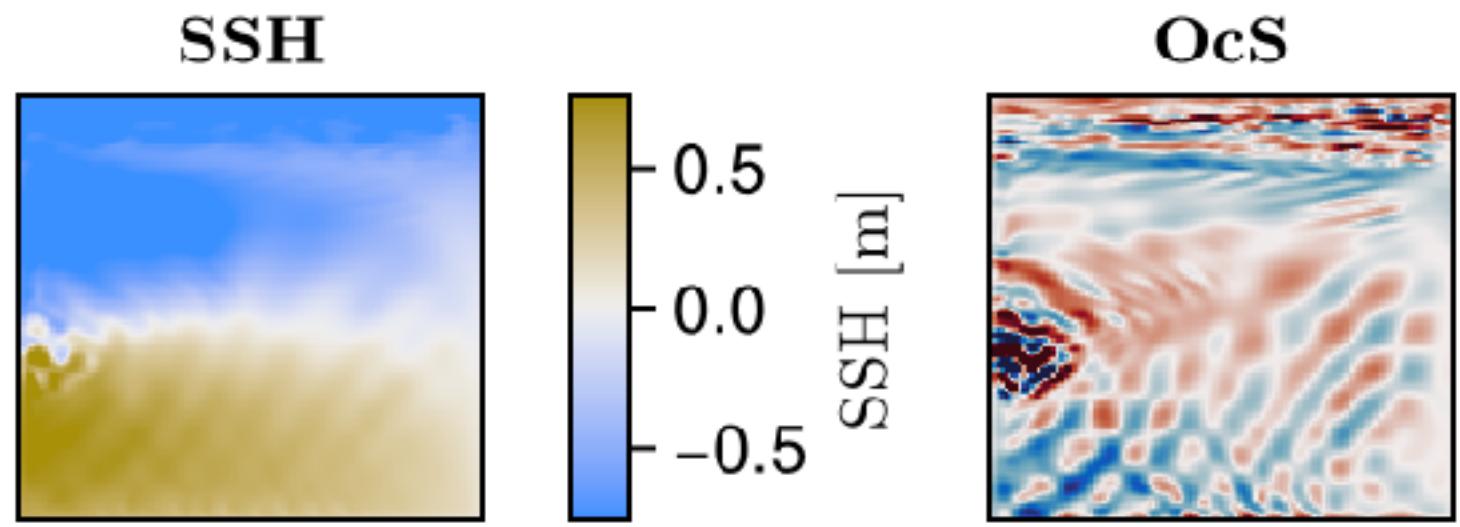


Results

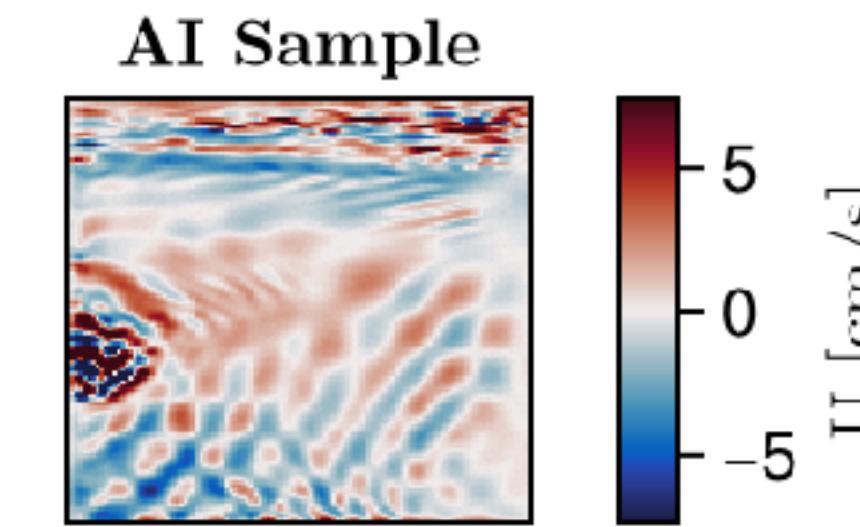
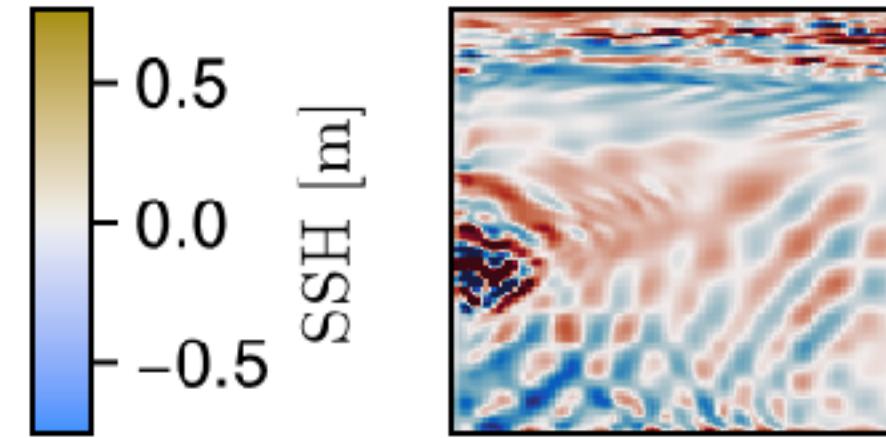
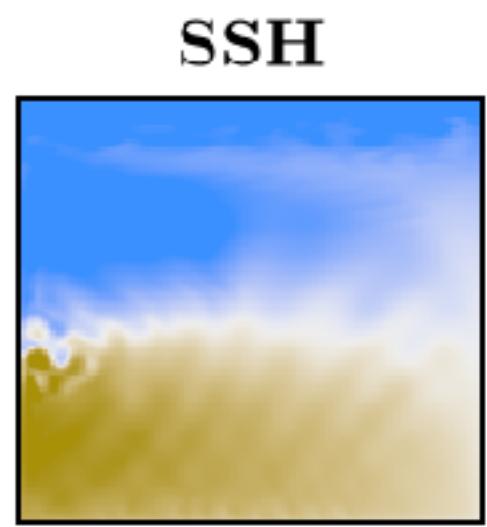
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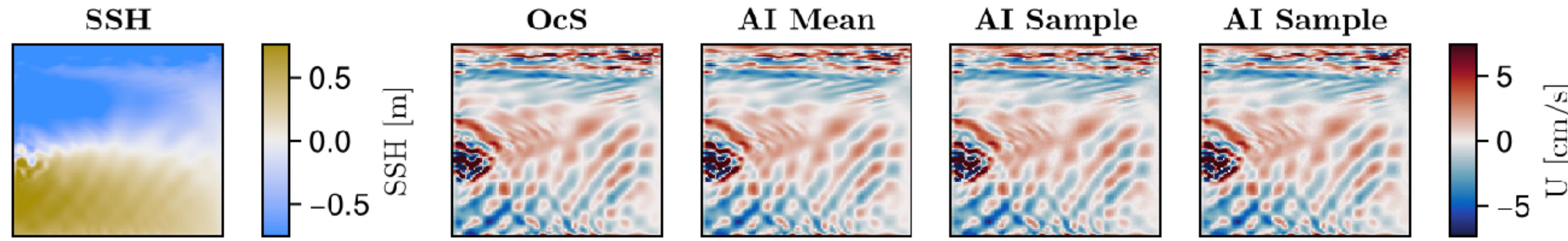
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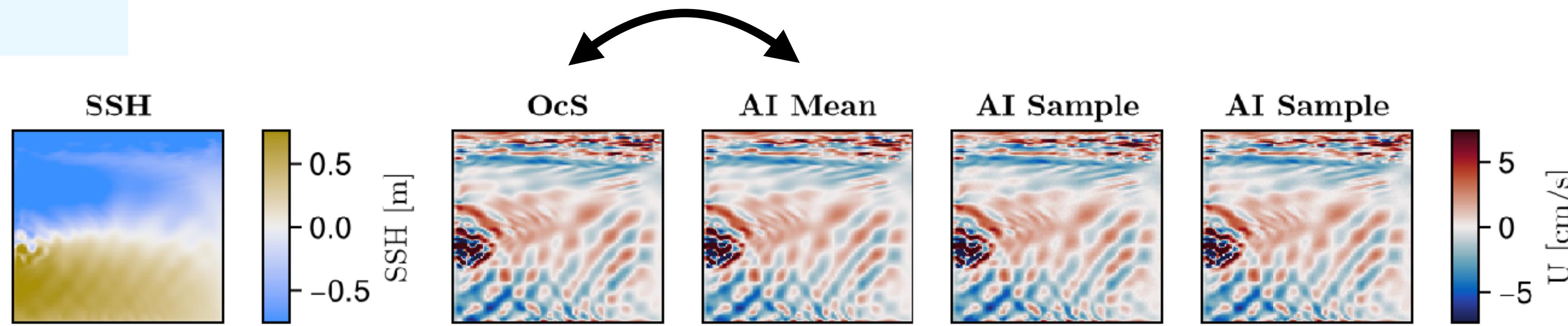
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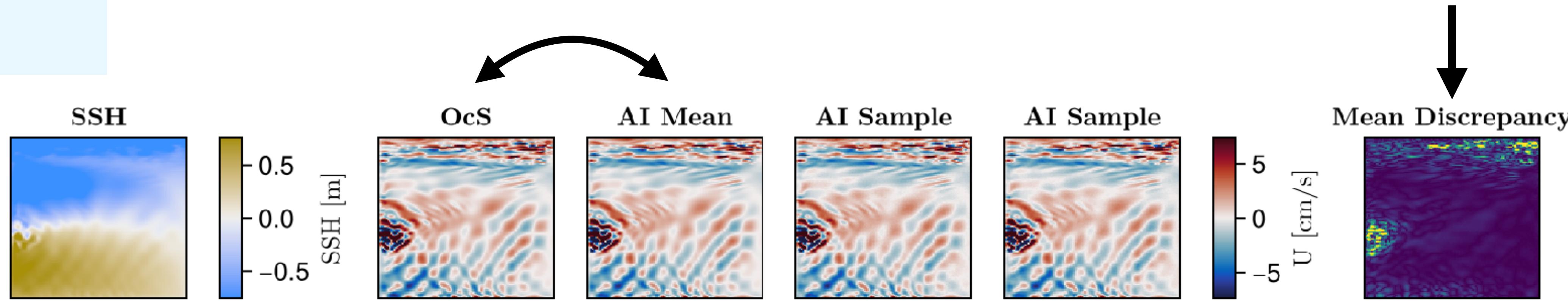
Application: Ocean Inference Result (400m depth)



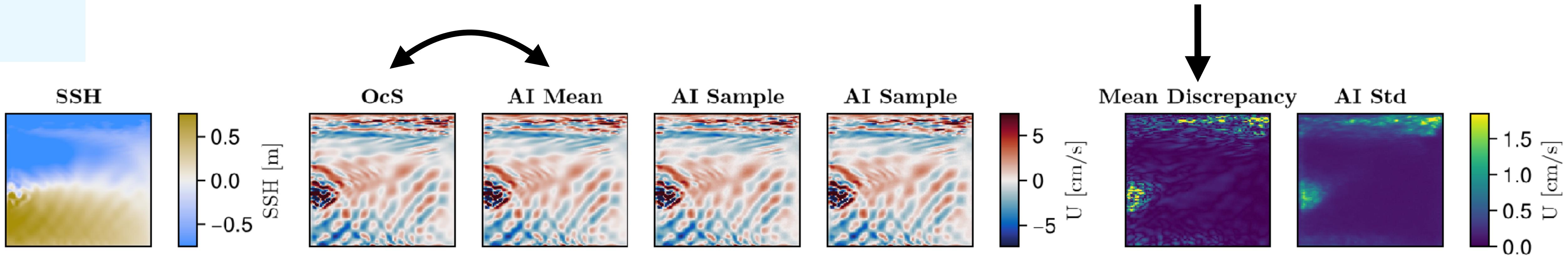
Application: Ocean Inference Result (400m depth)



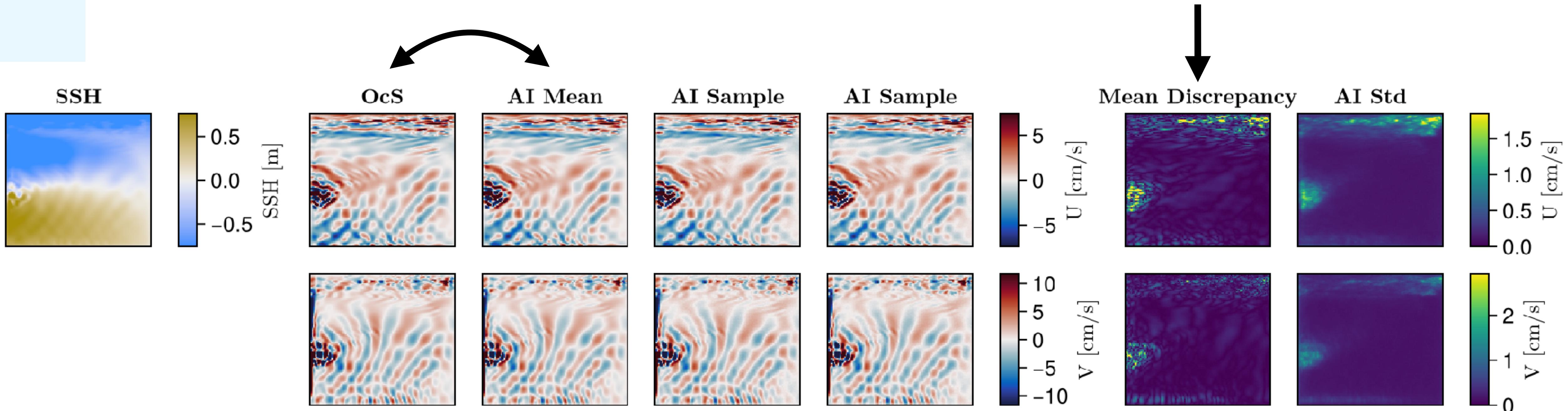
Application: Ocean Inference Result (400m depth)



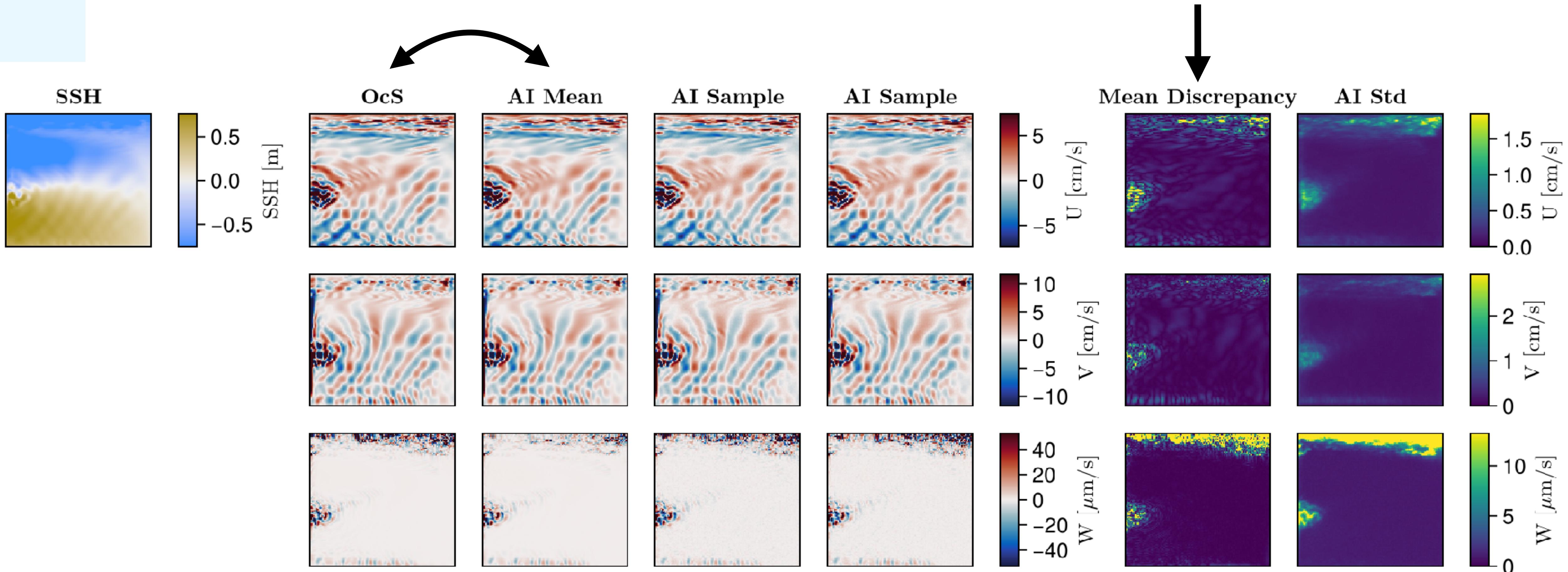
Application: Ocean Inference Result (400m depth)



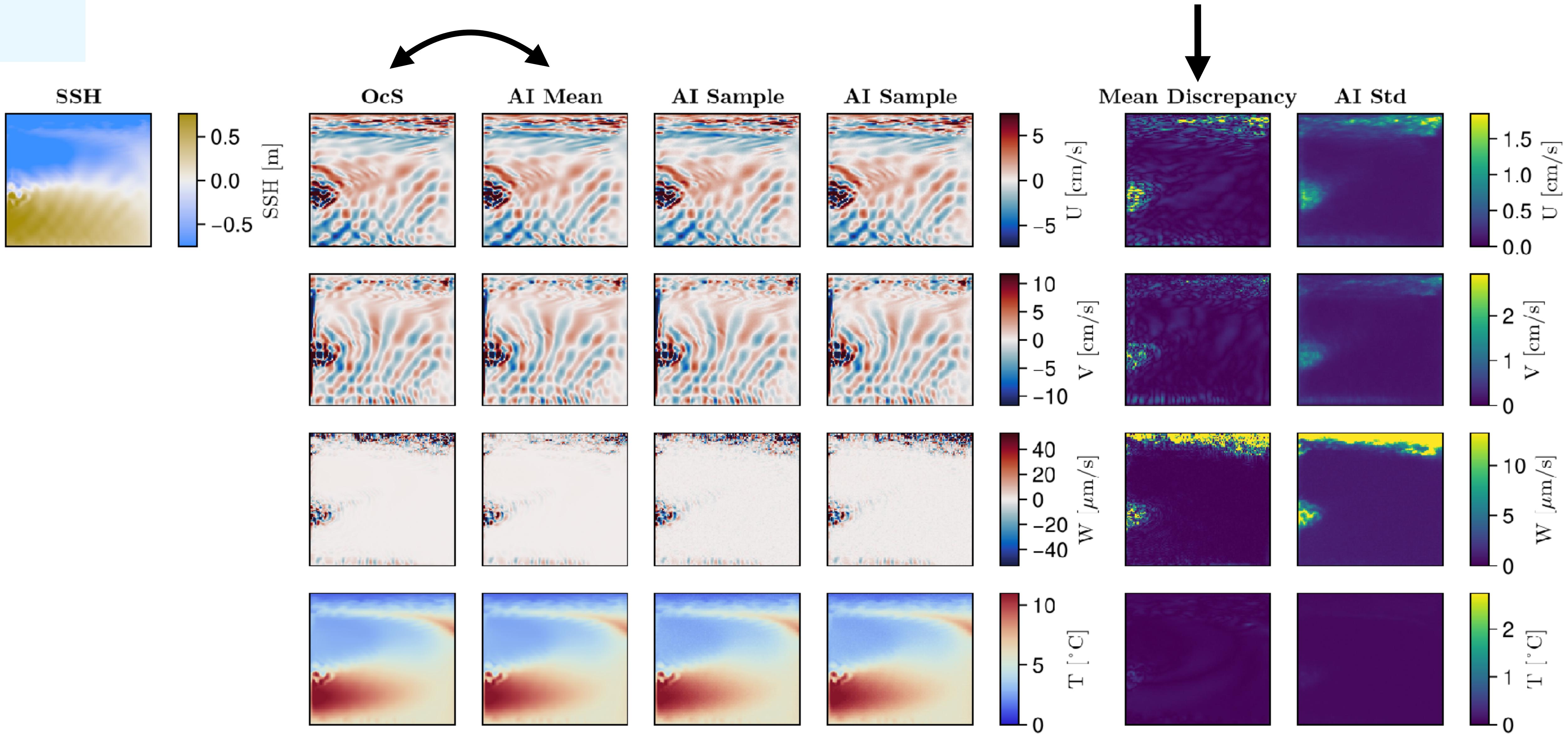
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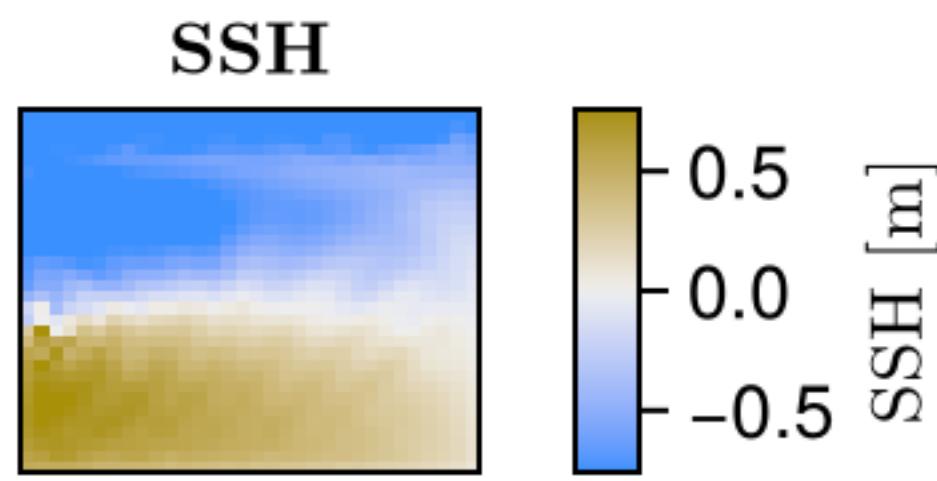
Application: Ocean Inference Result (400m depth)



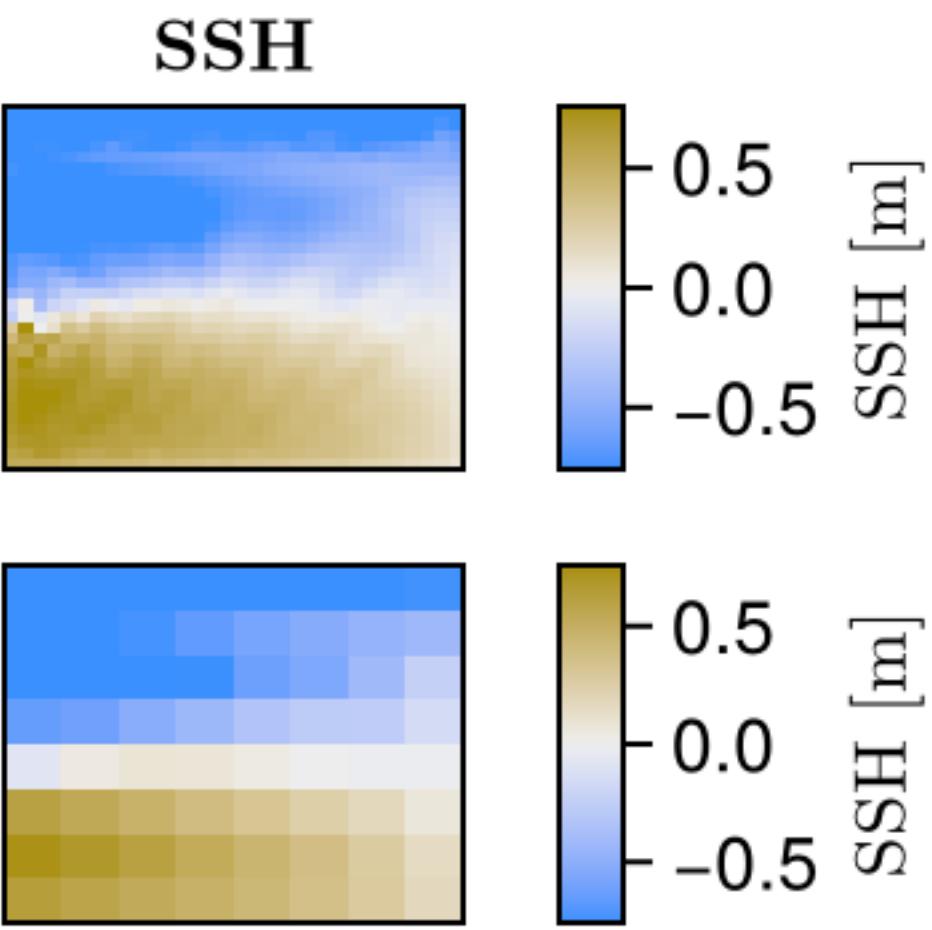
Application: Ocean Inference Result (400m depth)

(with Coarse-Graining)

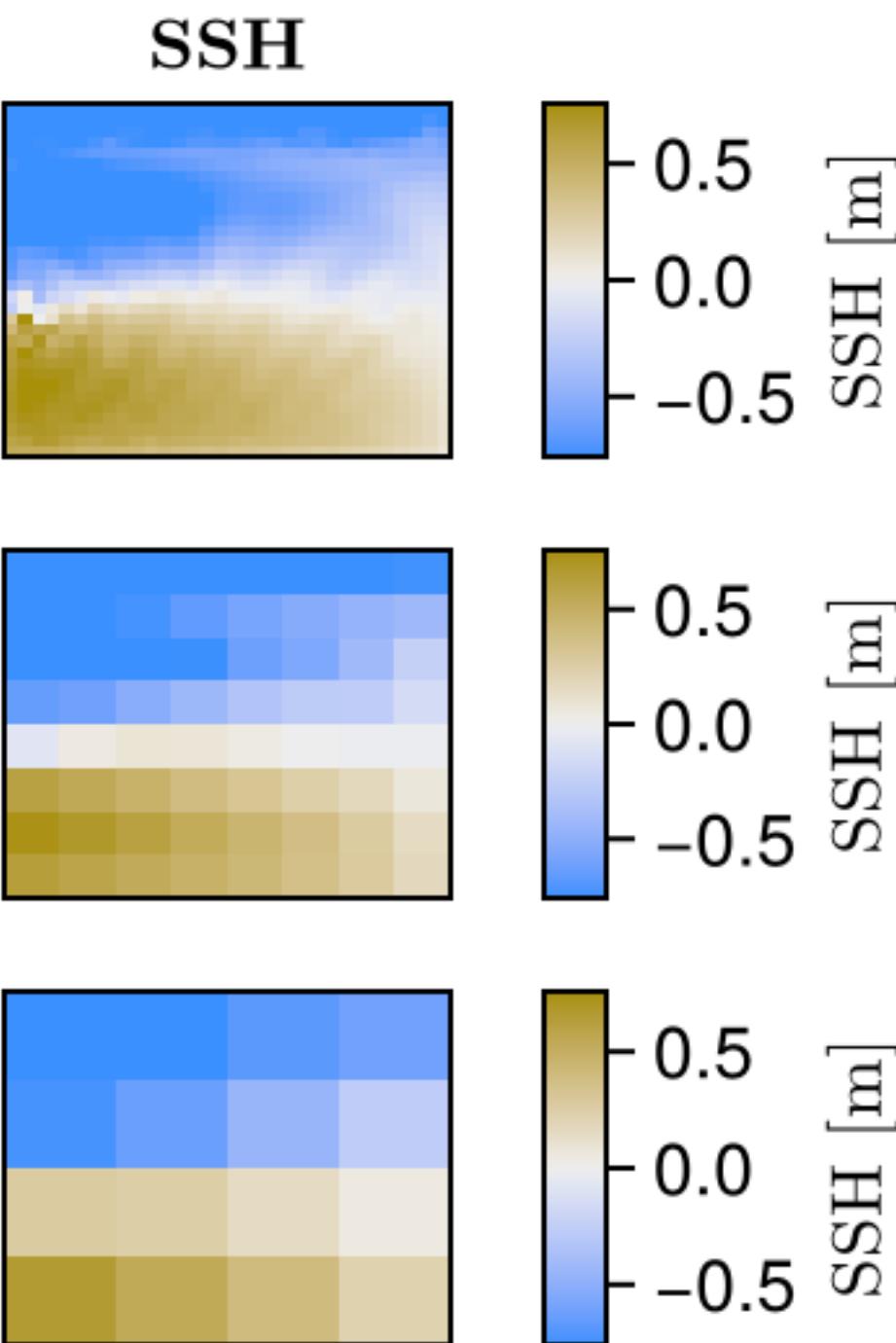
Application: Ocean Inference Result (400m depth)



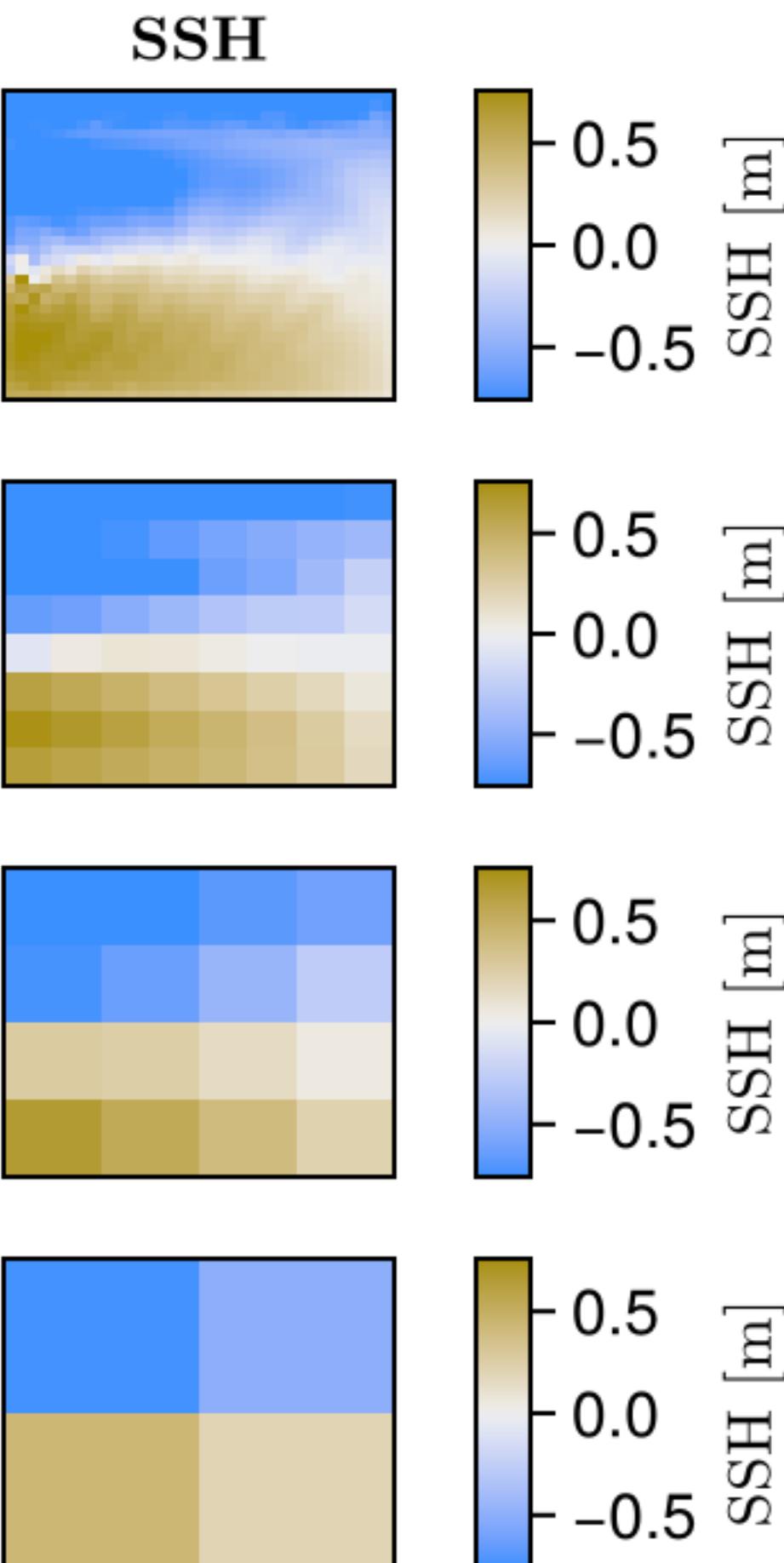
Application: Ocean Inference Result (400m depth)



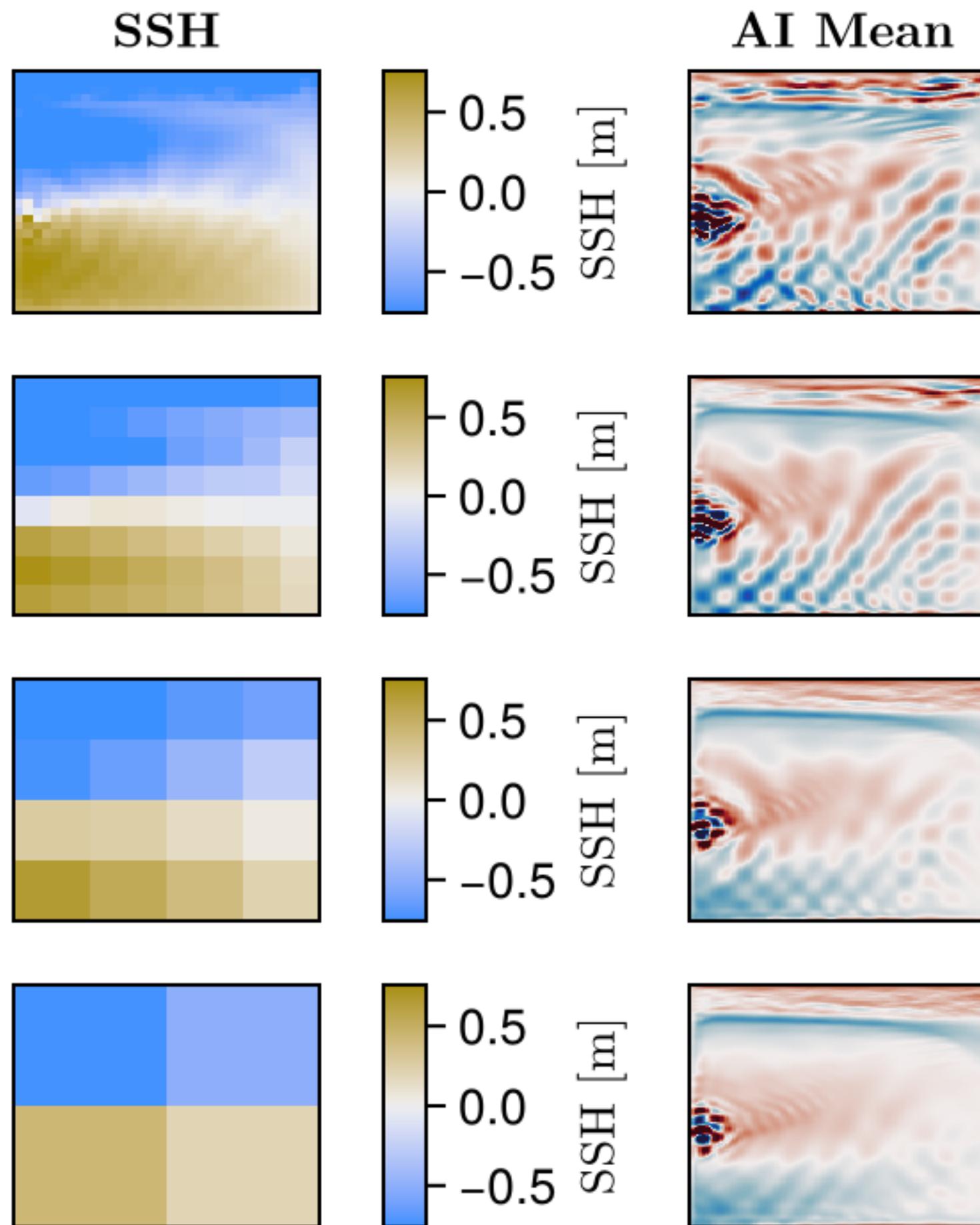
Application: Ocean Inference Result (400m depth)



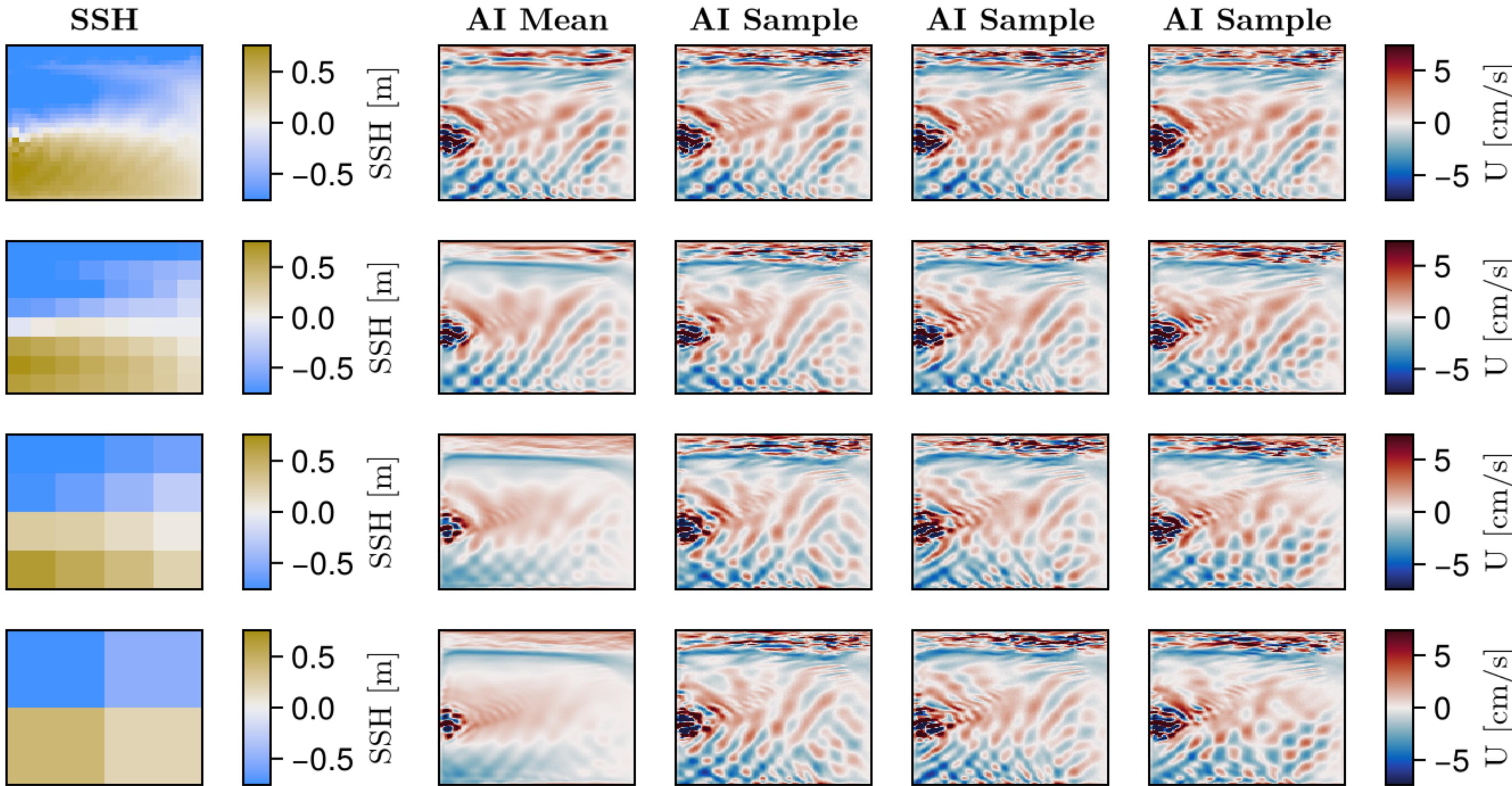
Application: Ocean Inference Result (400m depth)



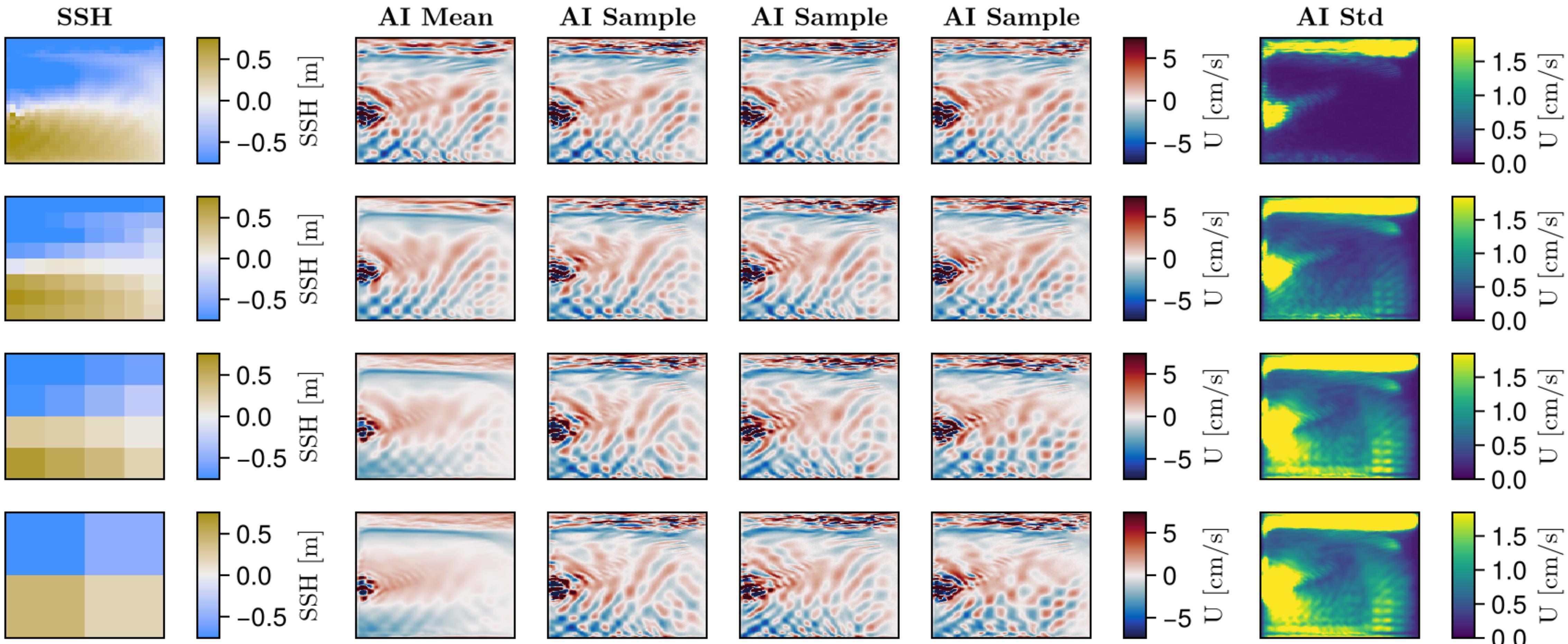
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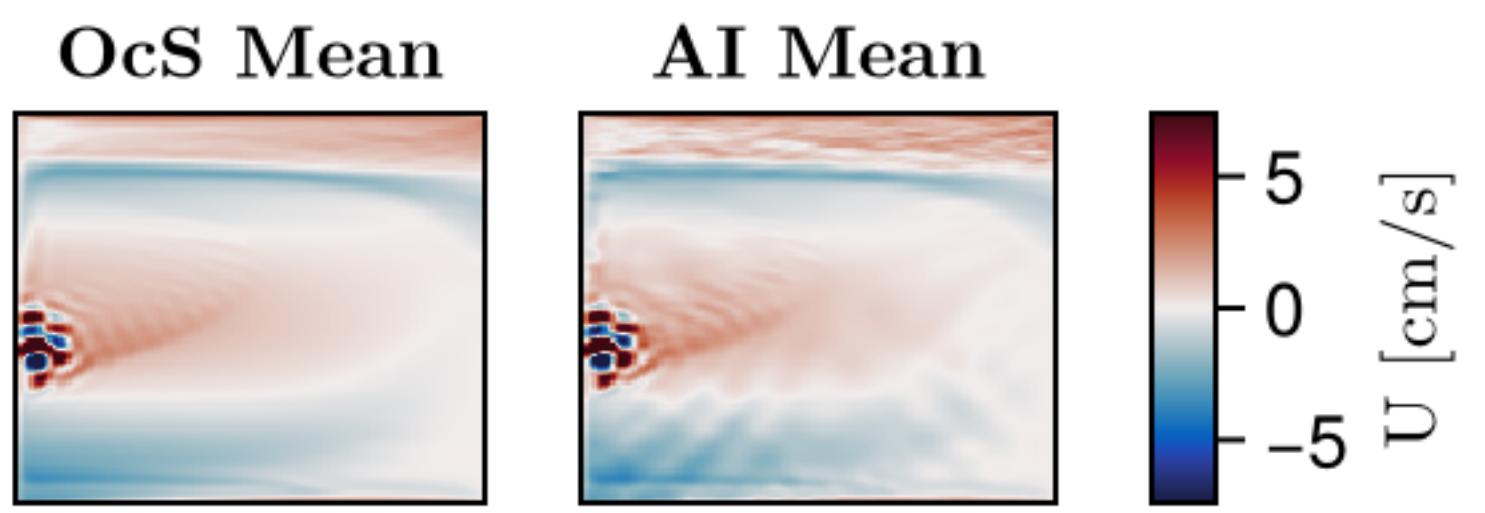
Application: Ocean Inference Result (400m depth)



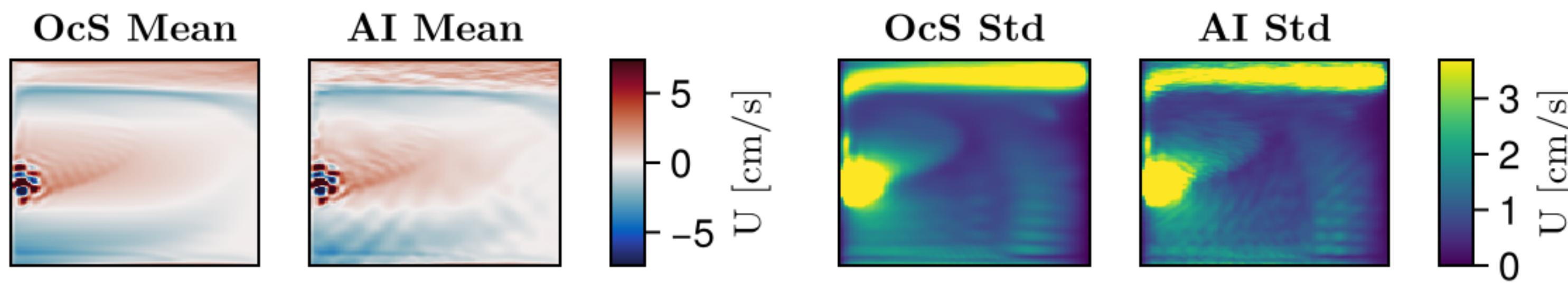
Application: Ocean Inference Result (400m depth)

(with Extreme Coarse-Graining)

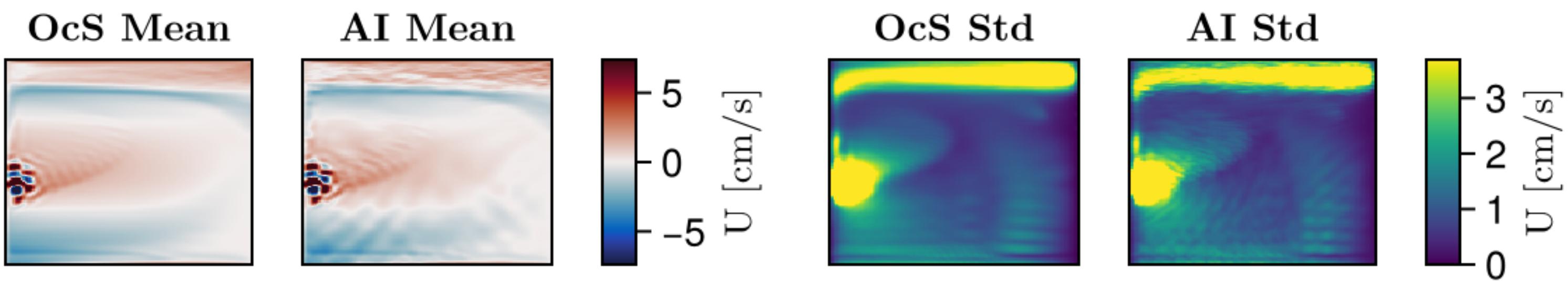
Application: Regression to Ensemble Mean



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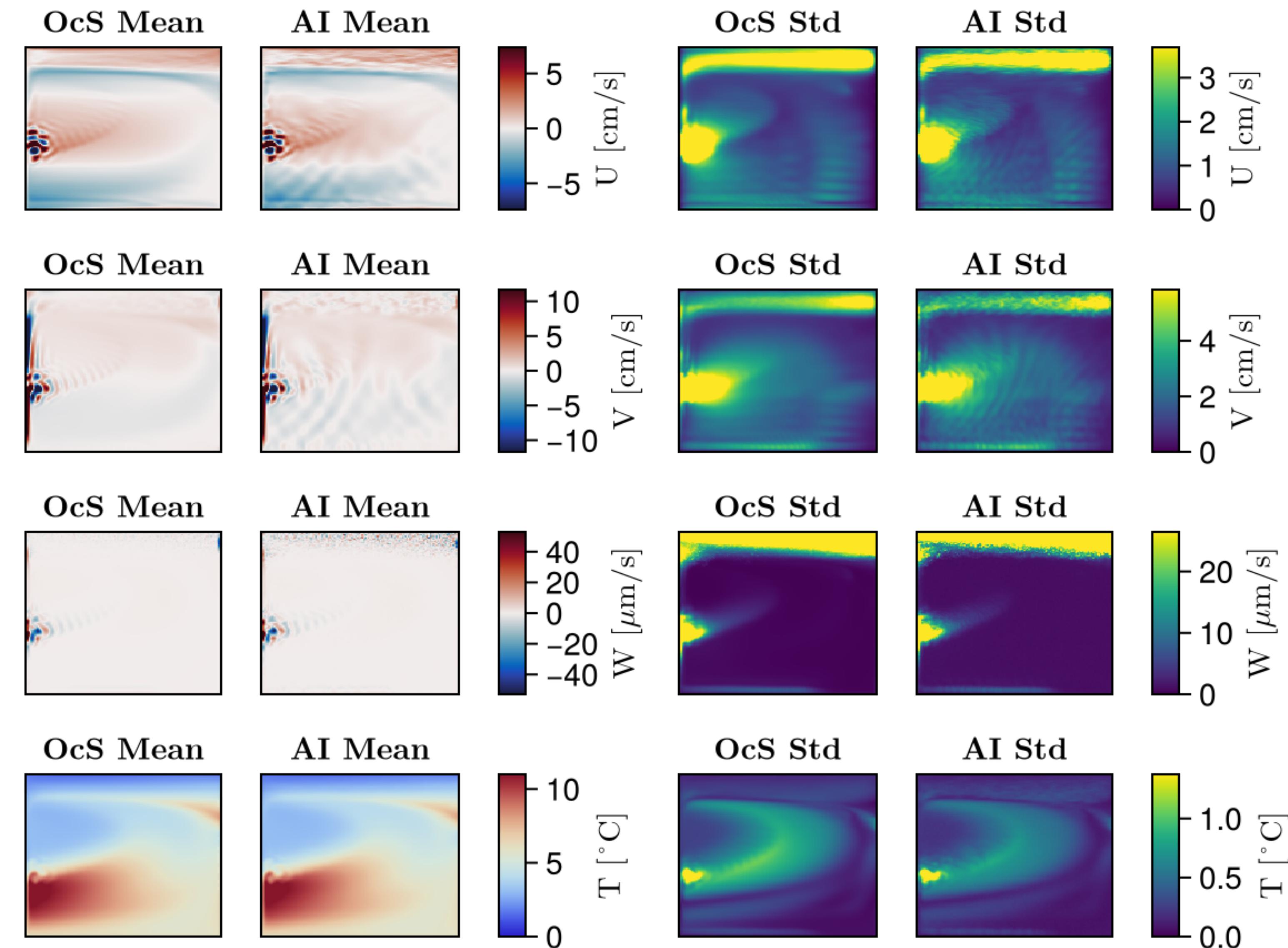


Application: Regression to Ensemble Mean



$$\rho(y|x) = \rho(y)$$

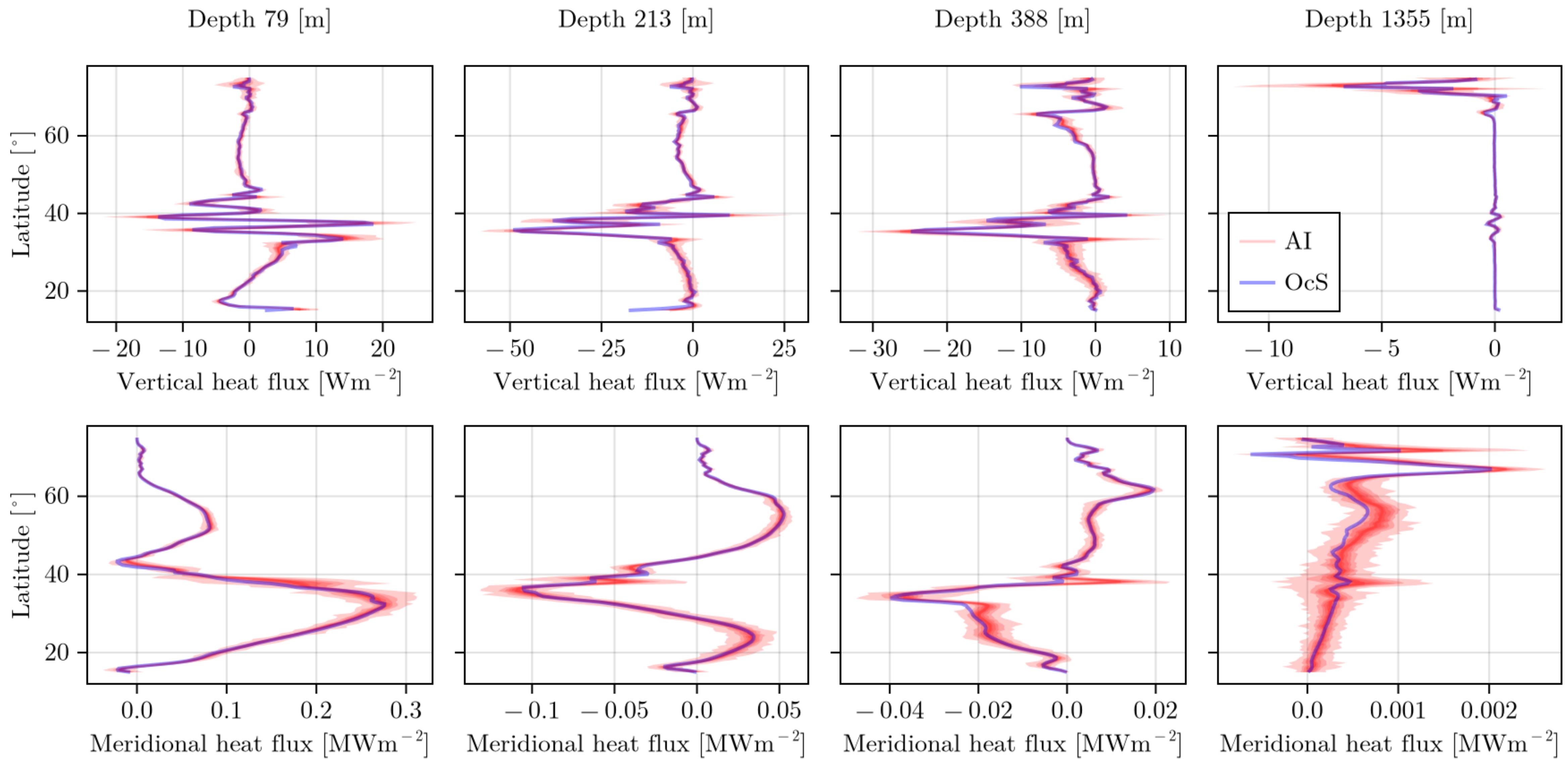
Application: Regression to Ensemble Mean



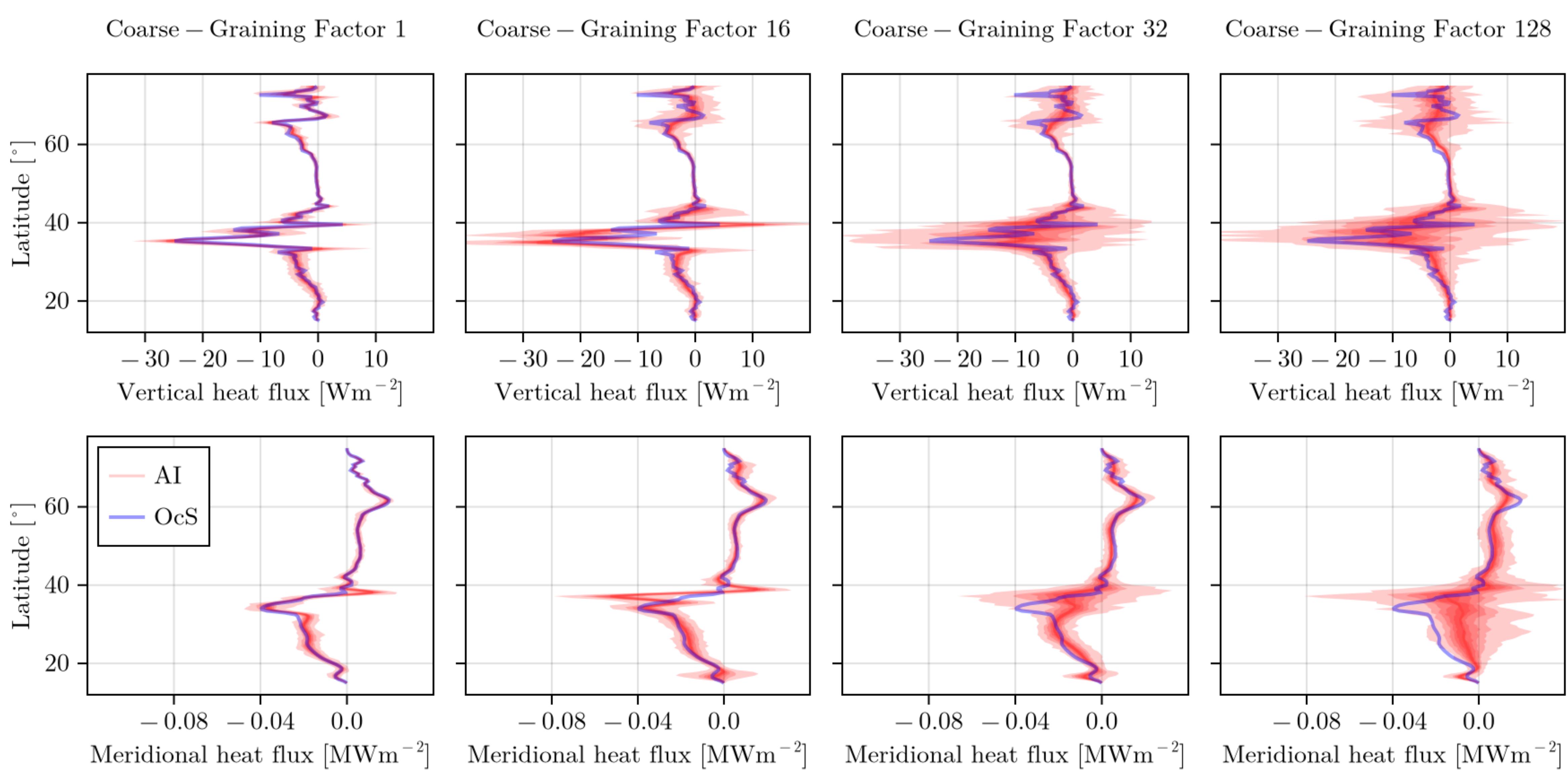
$$\rho(y|x) = \rho(y)$$

Results: Covariances

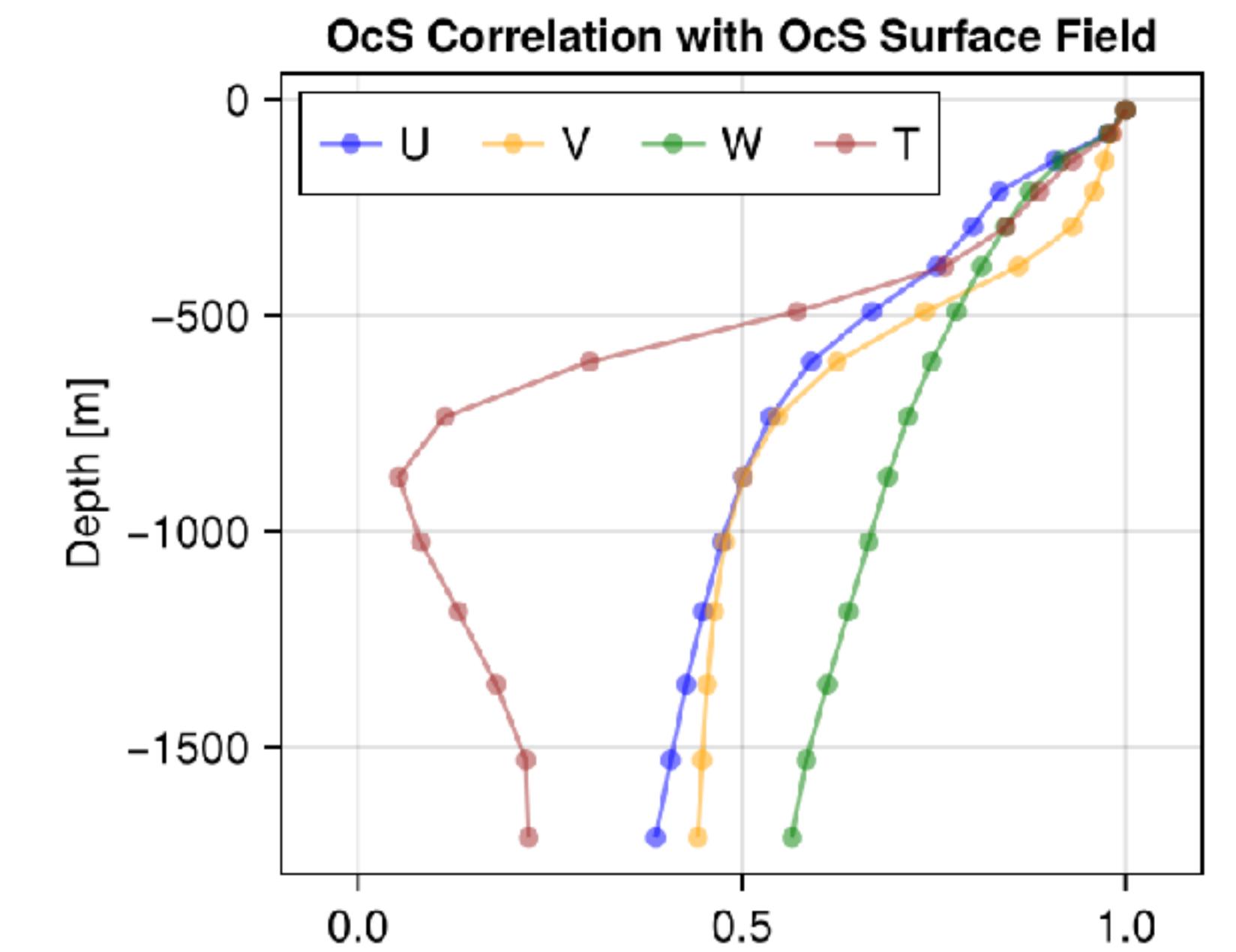
Application: Ocean Inference Covariances

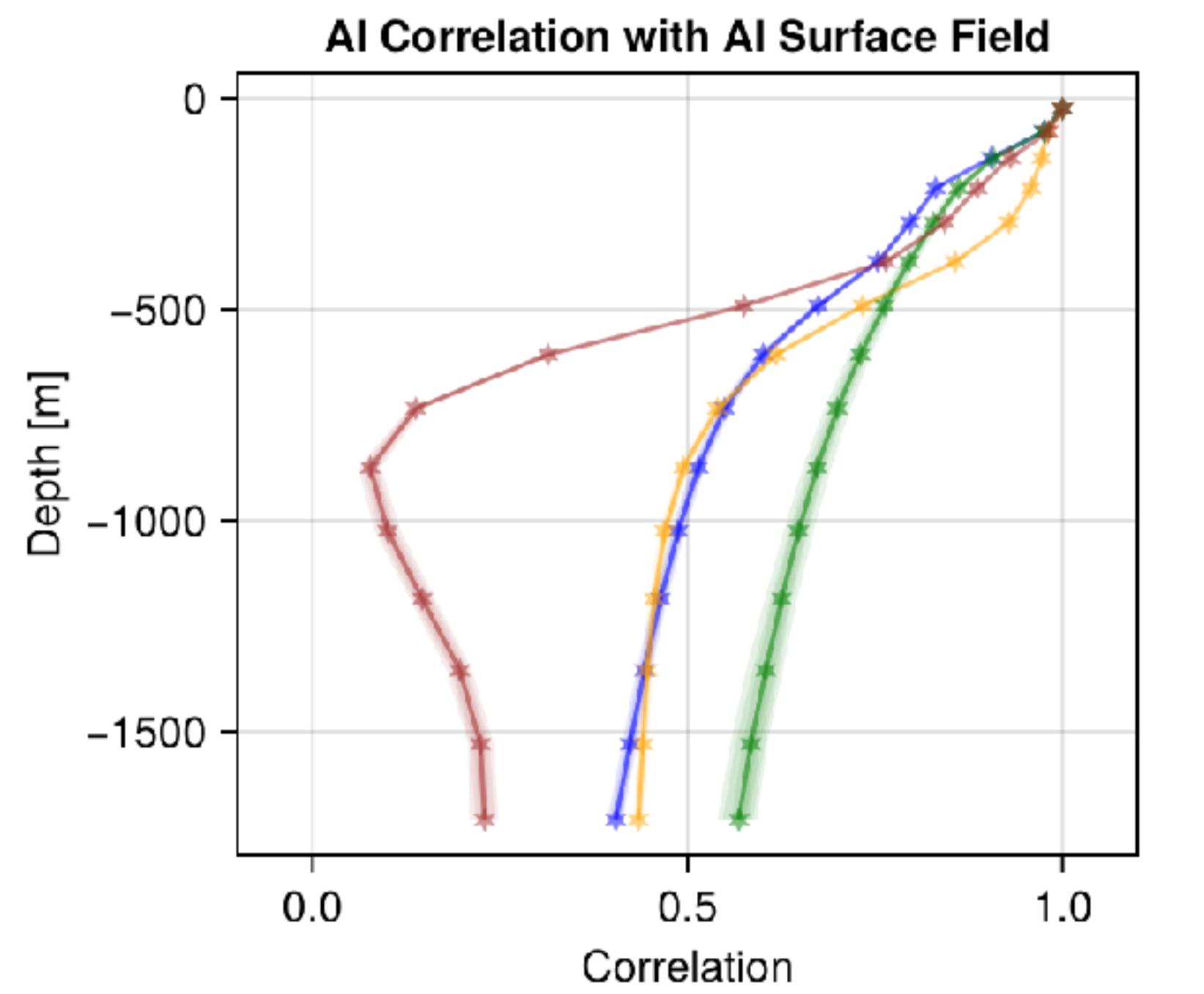
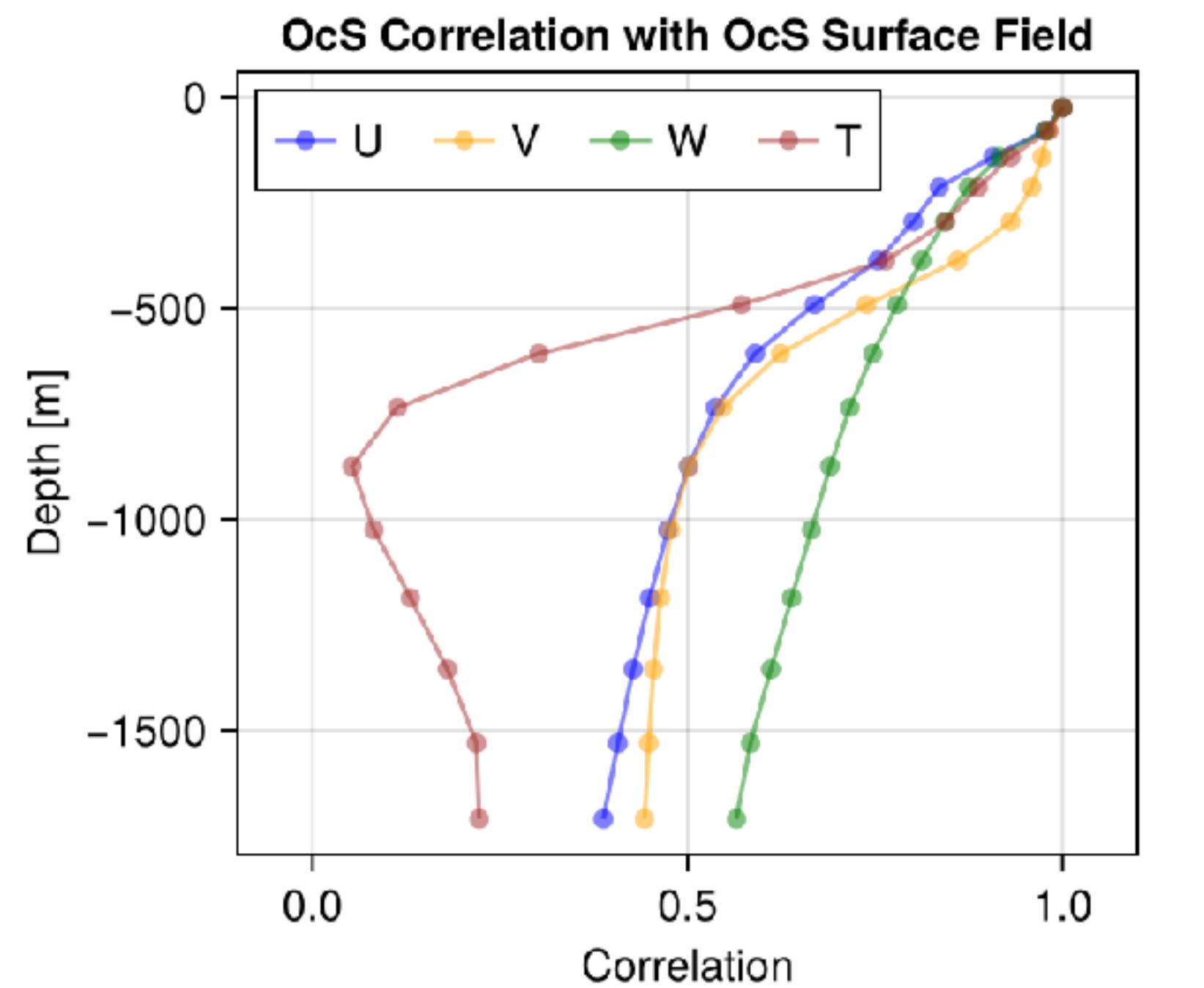


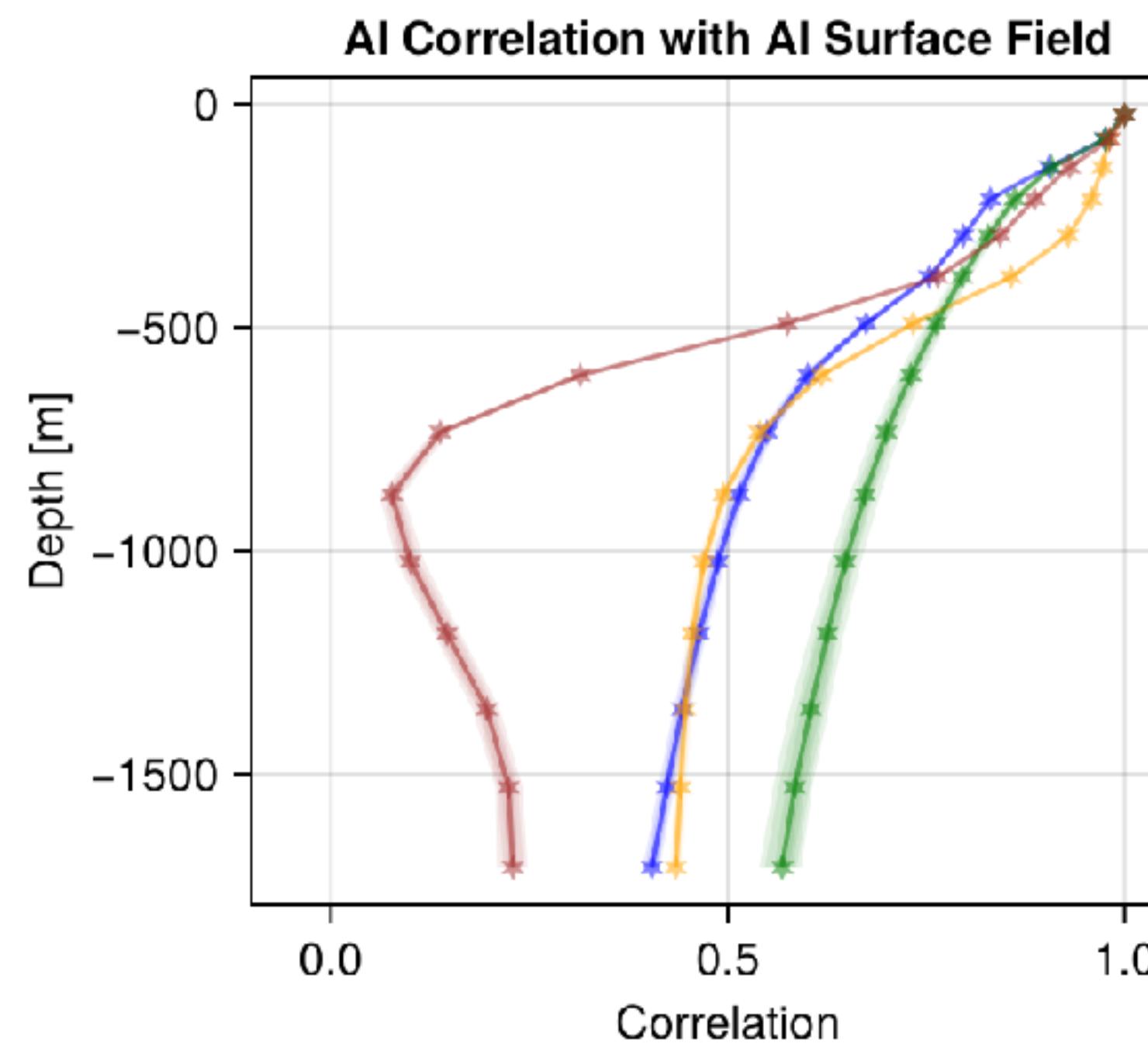
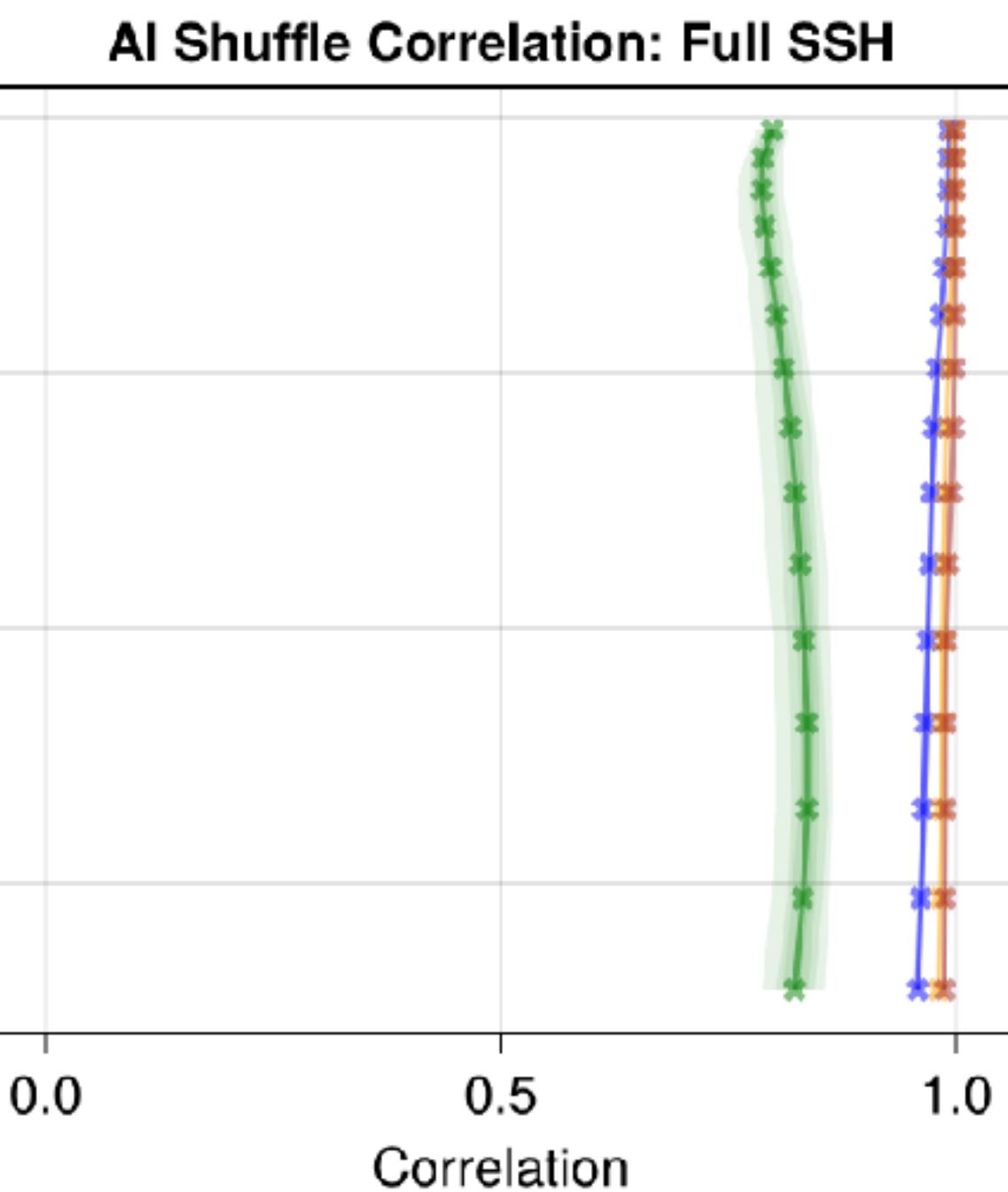
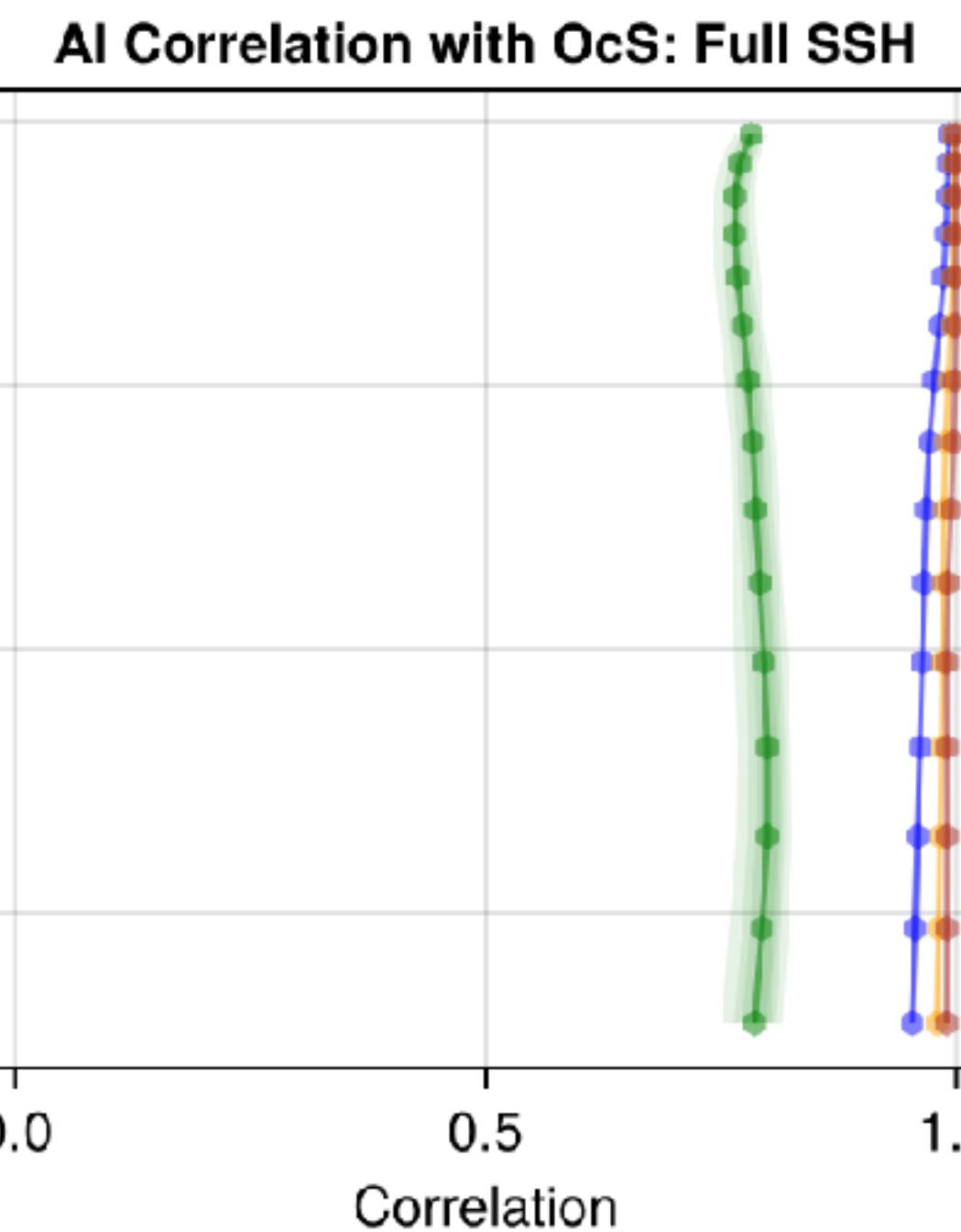
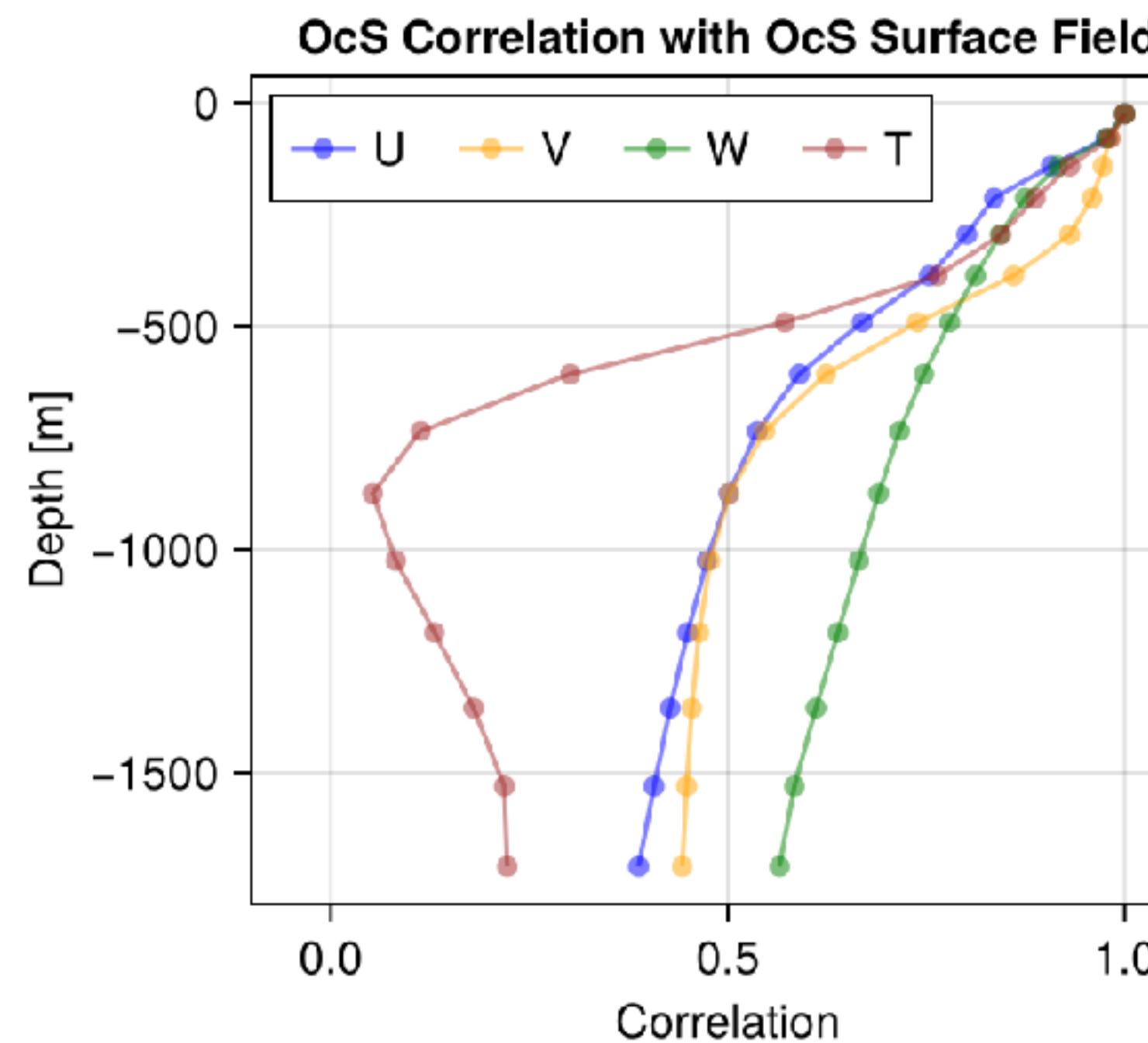
Application: Ocean Inference Covariances

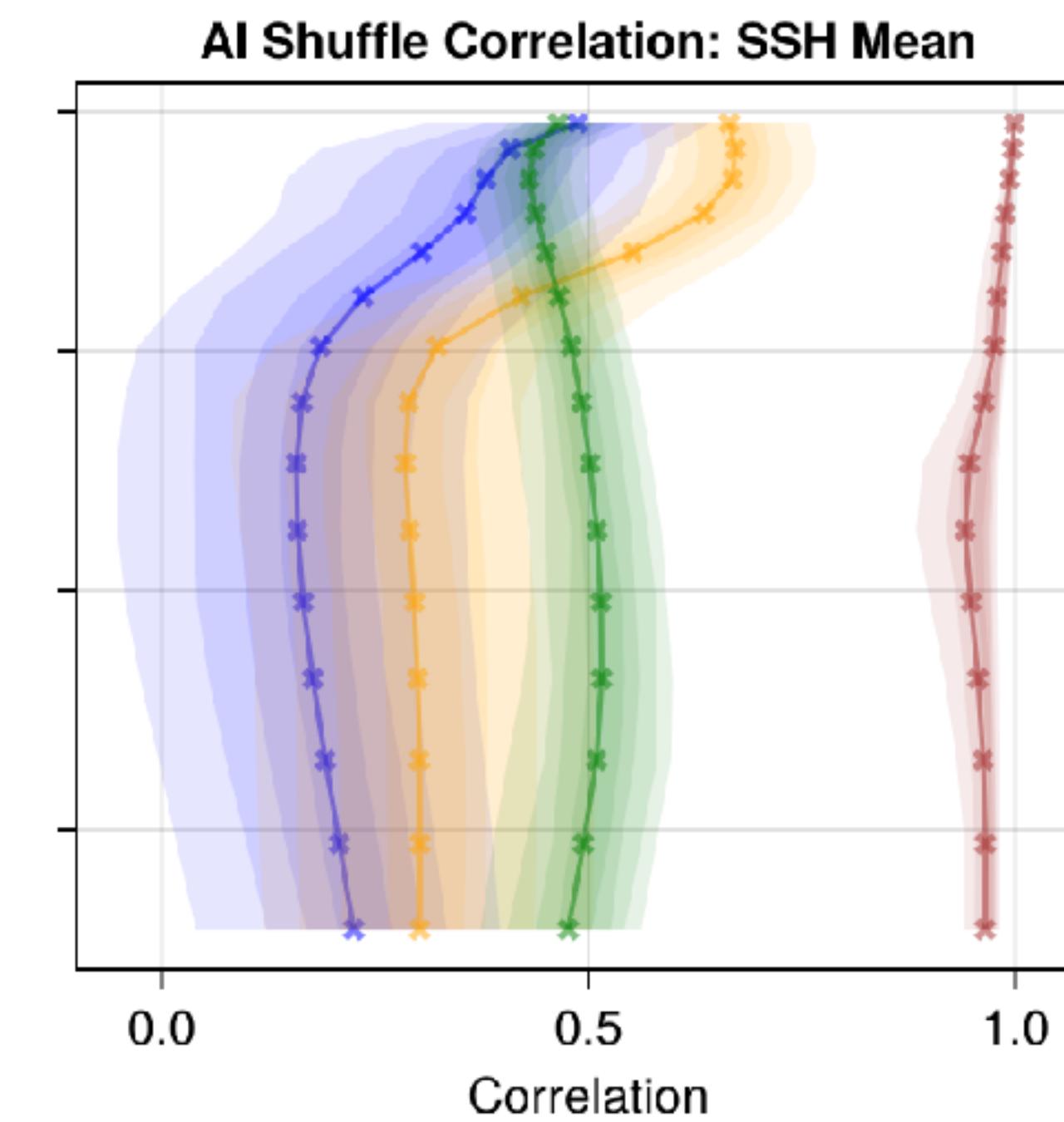
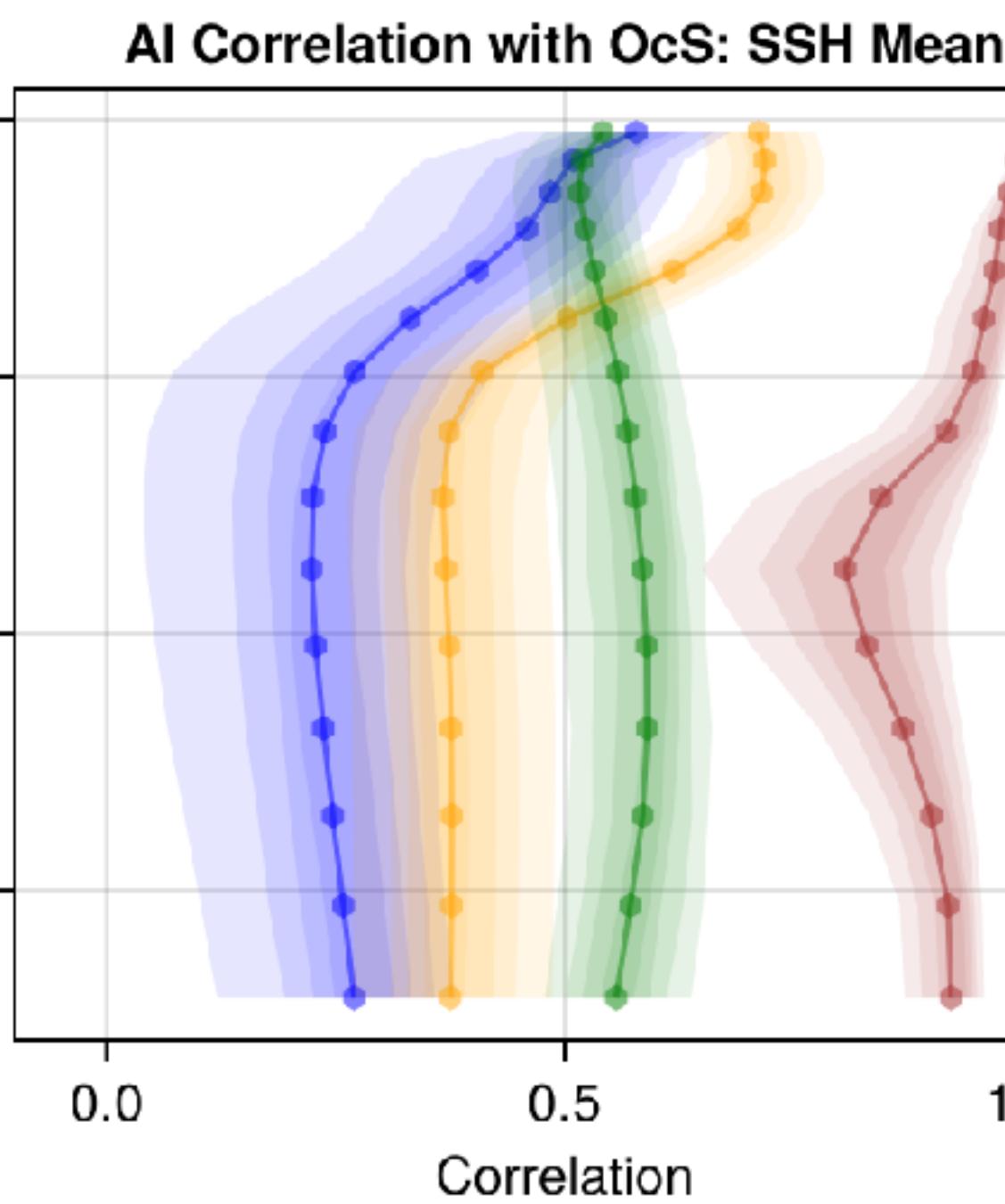
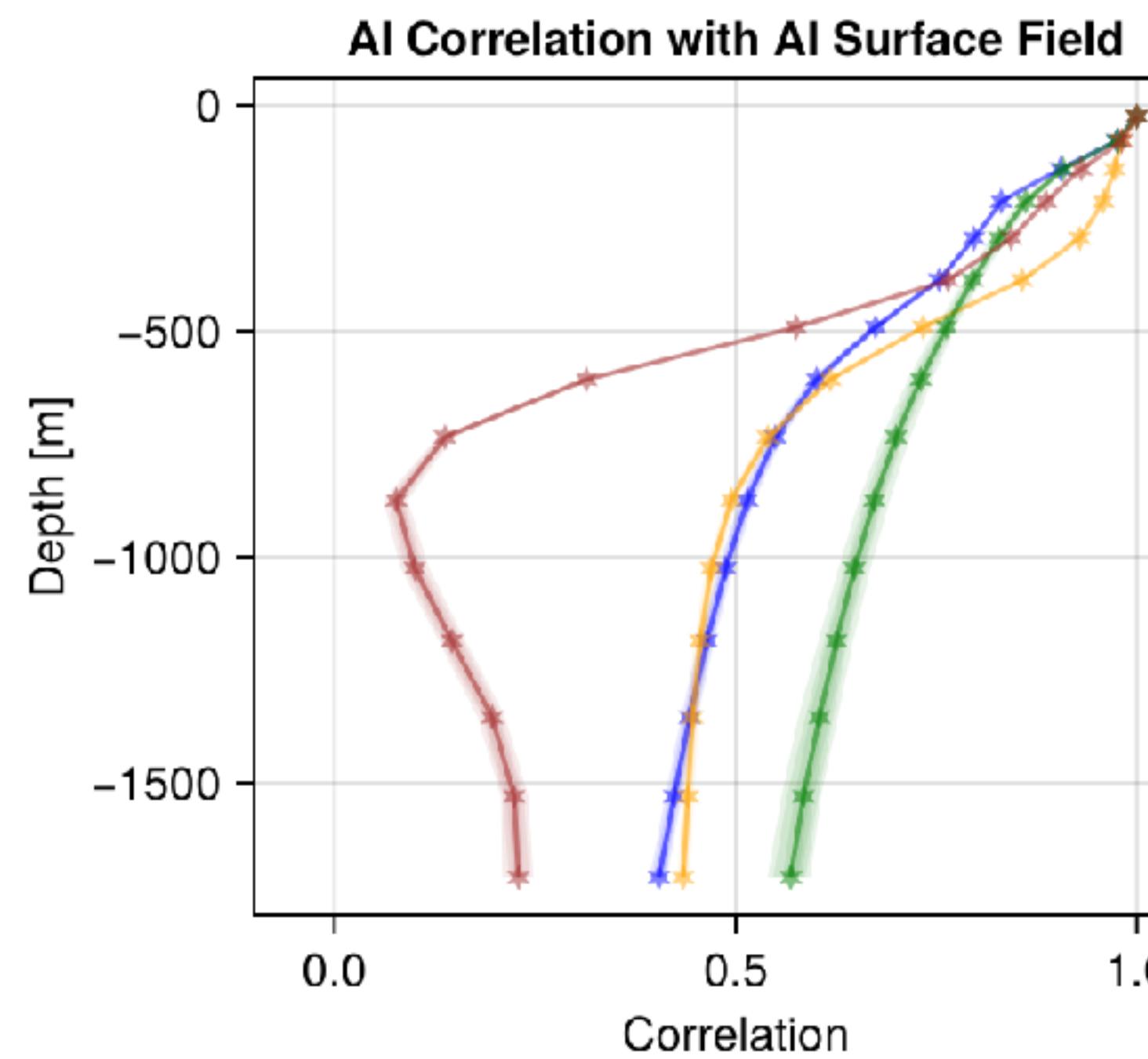
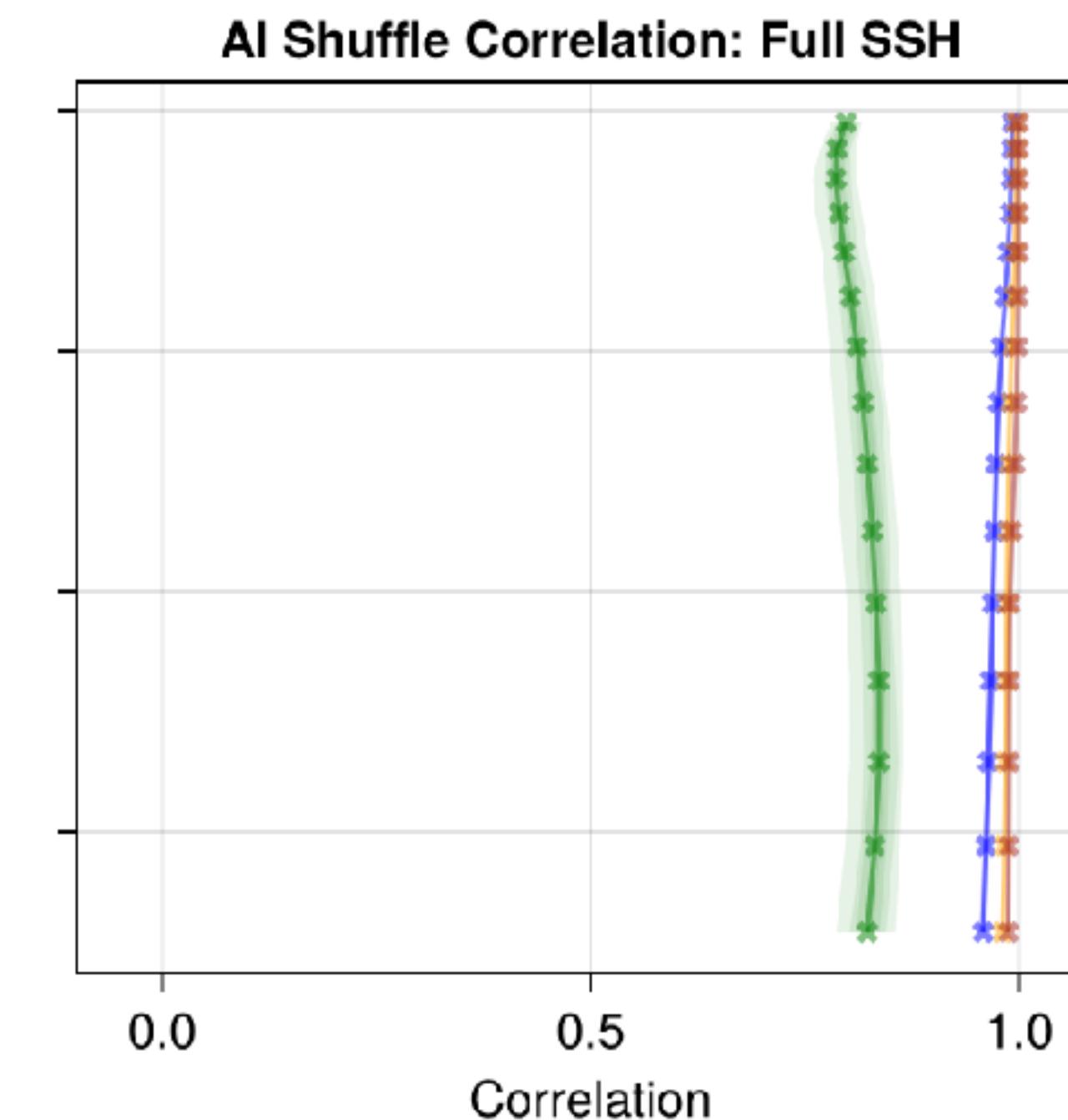
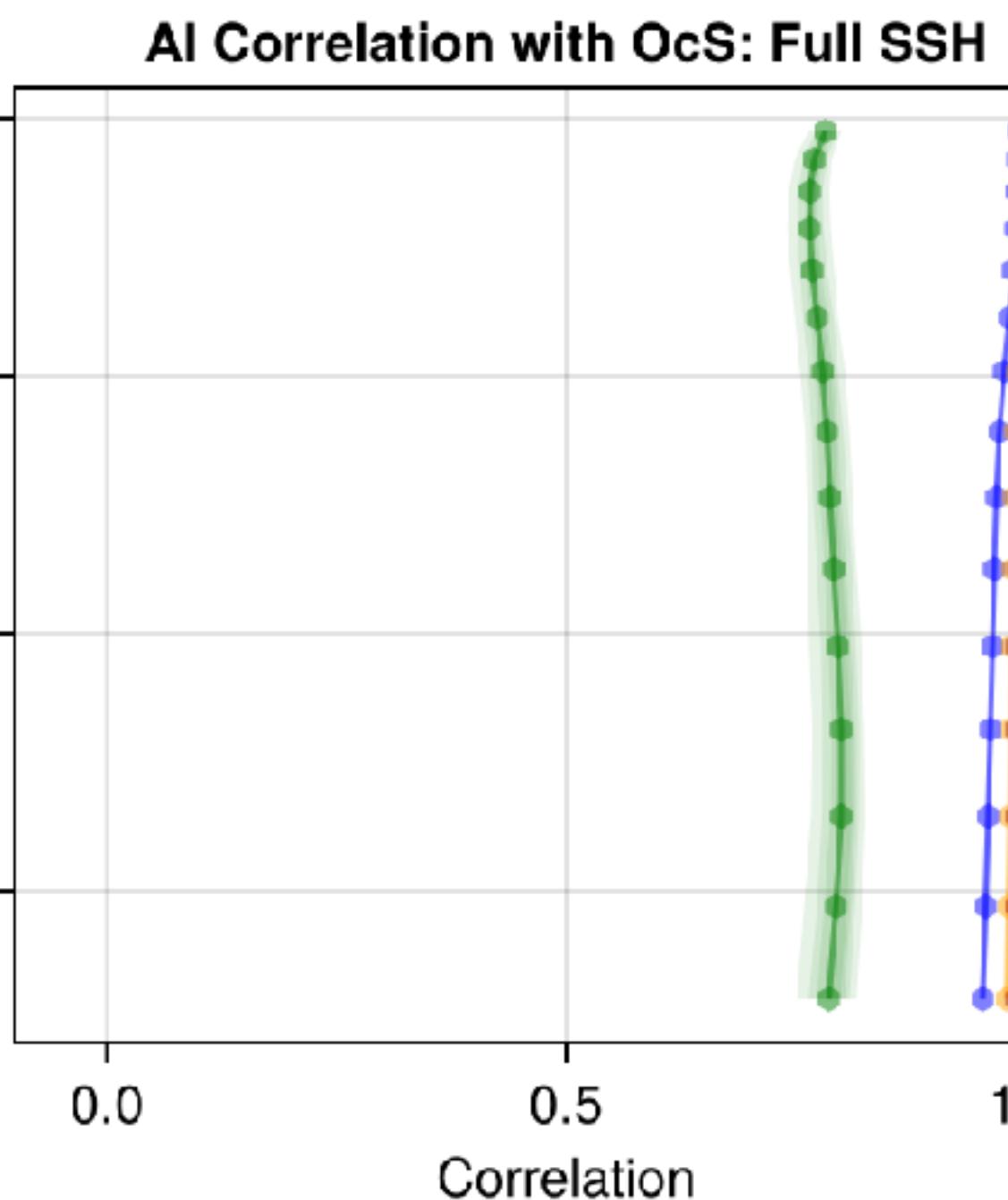
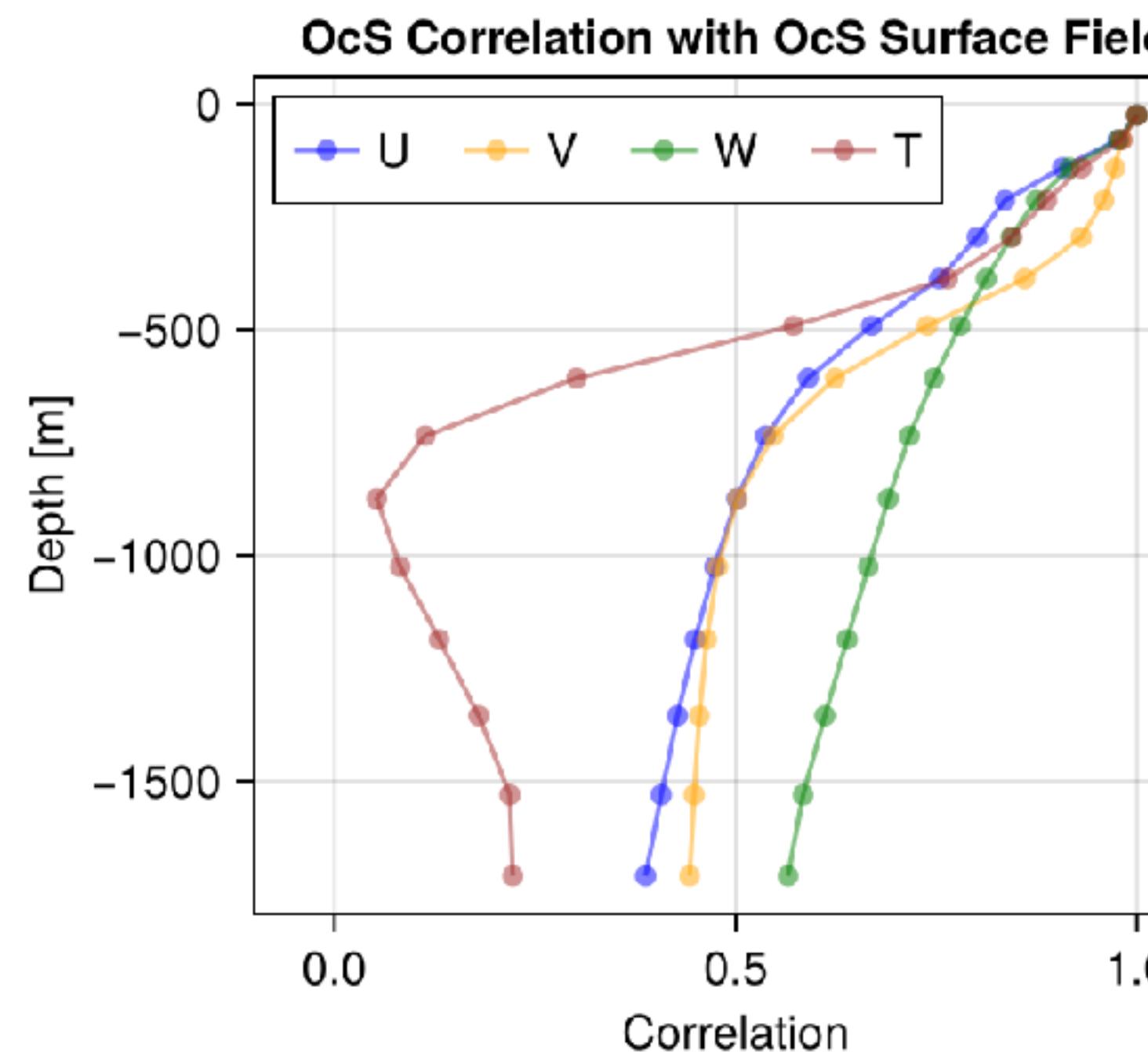


Results: Depth Correlations



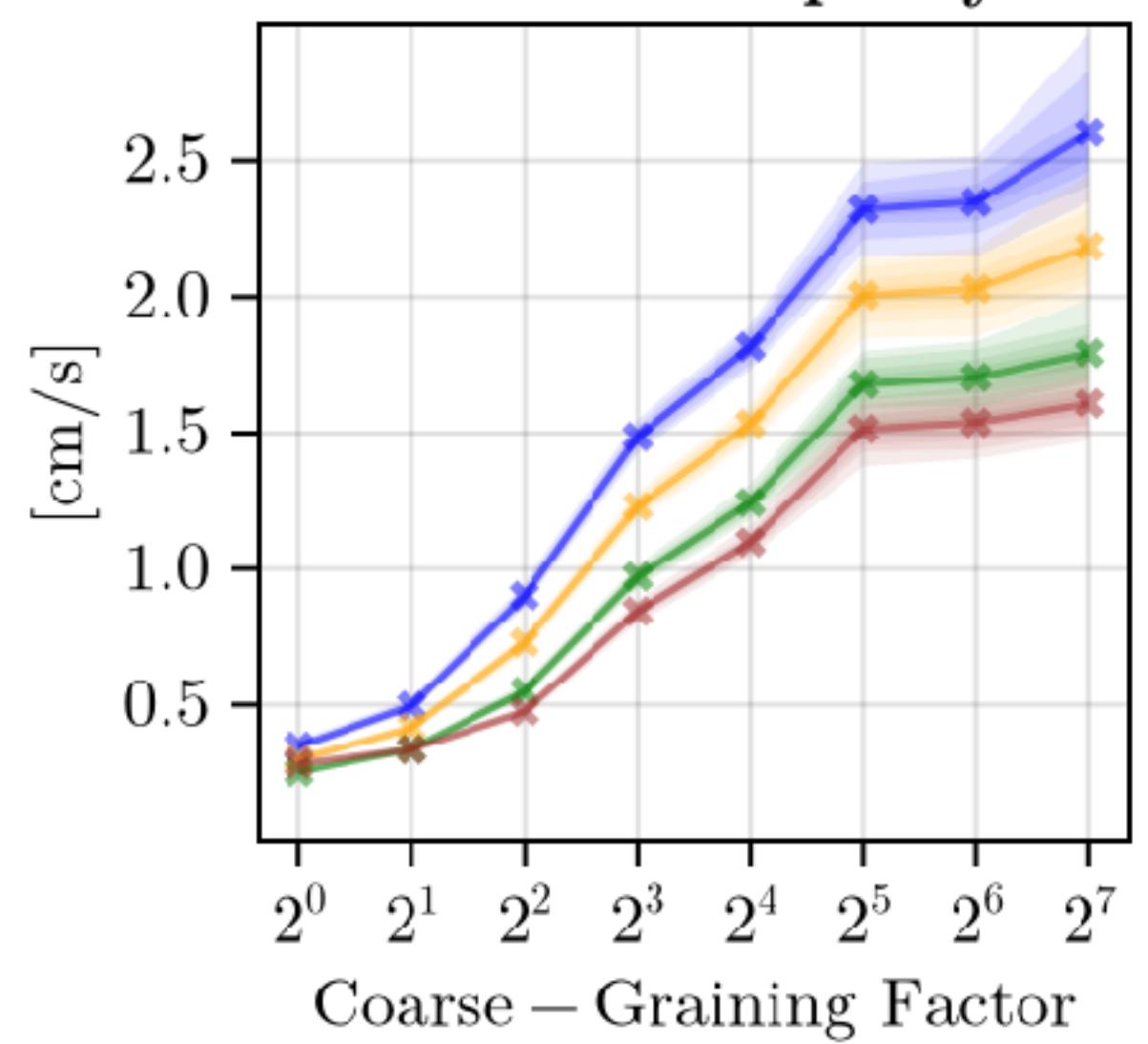




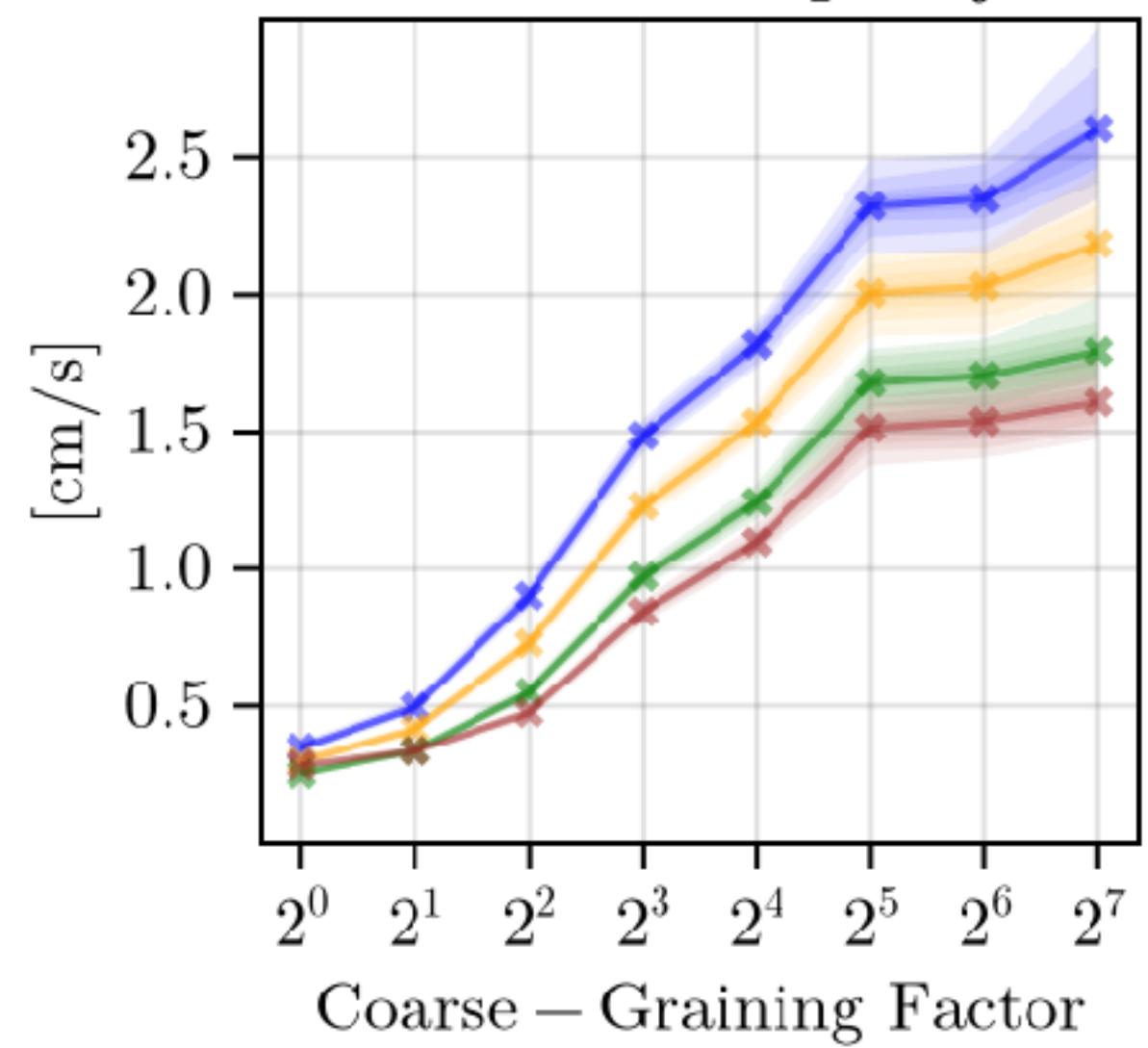


Results: Discrepancies

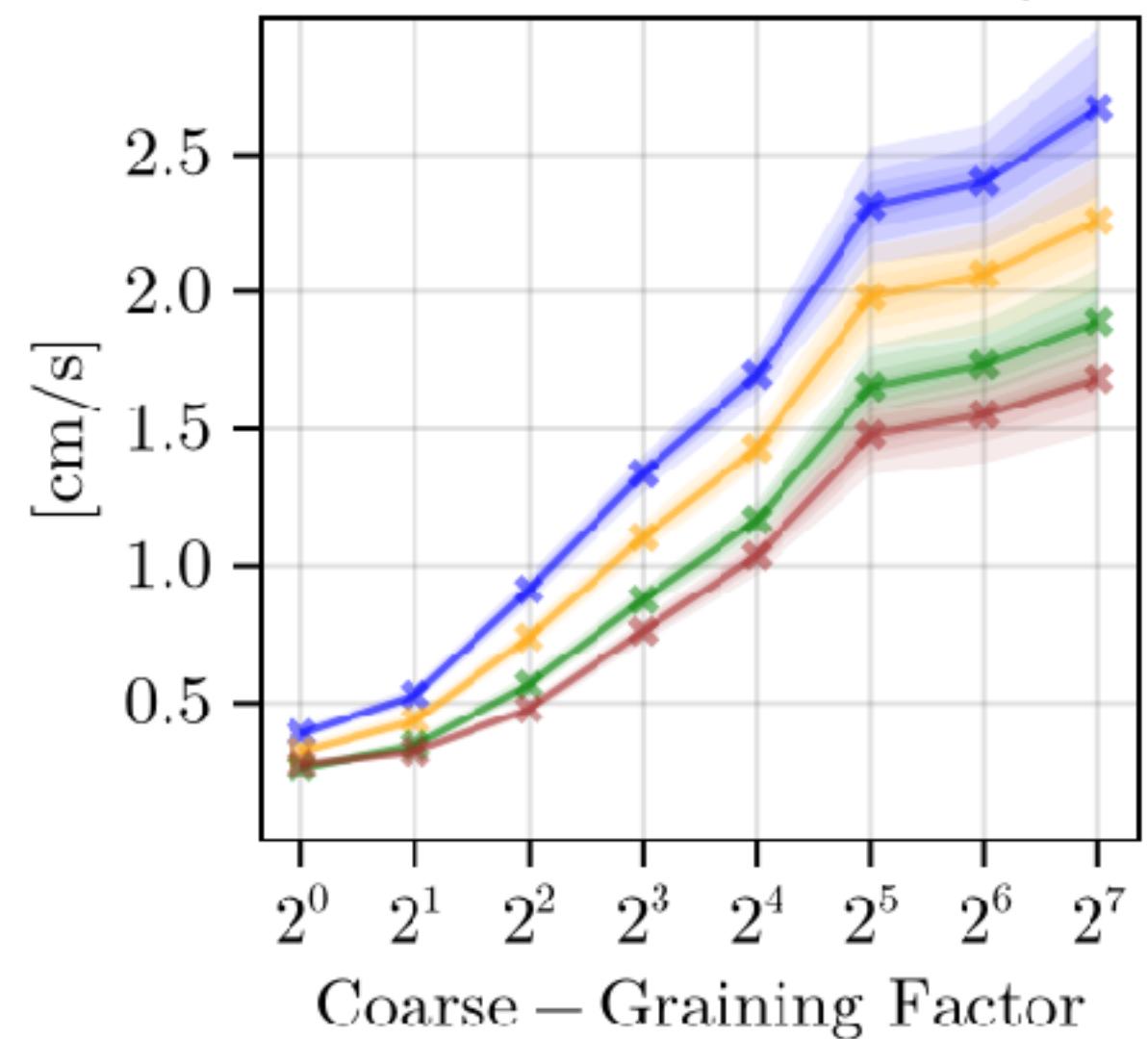
OsC AI Discrepancy \mathbf{U}

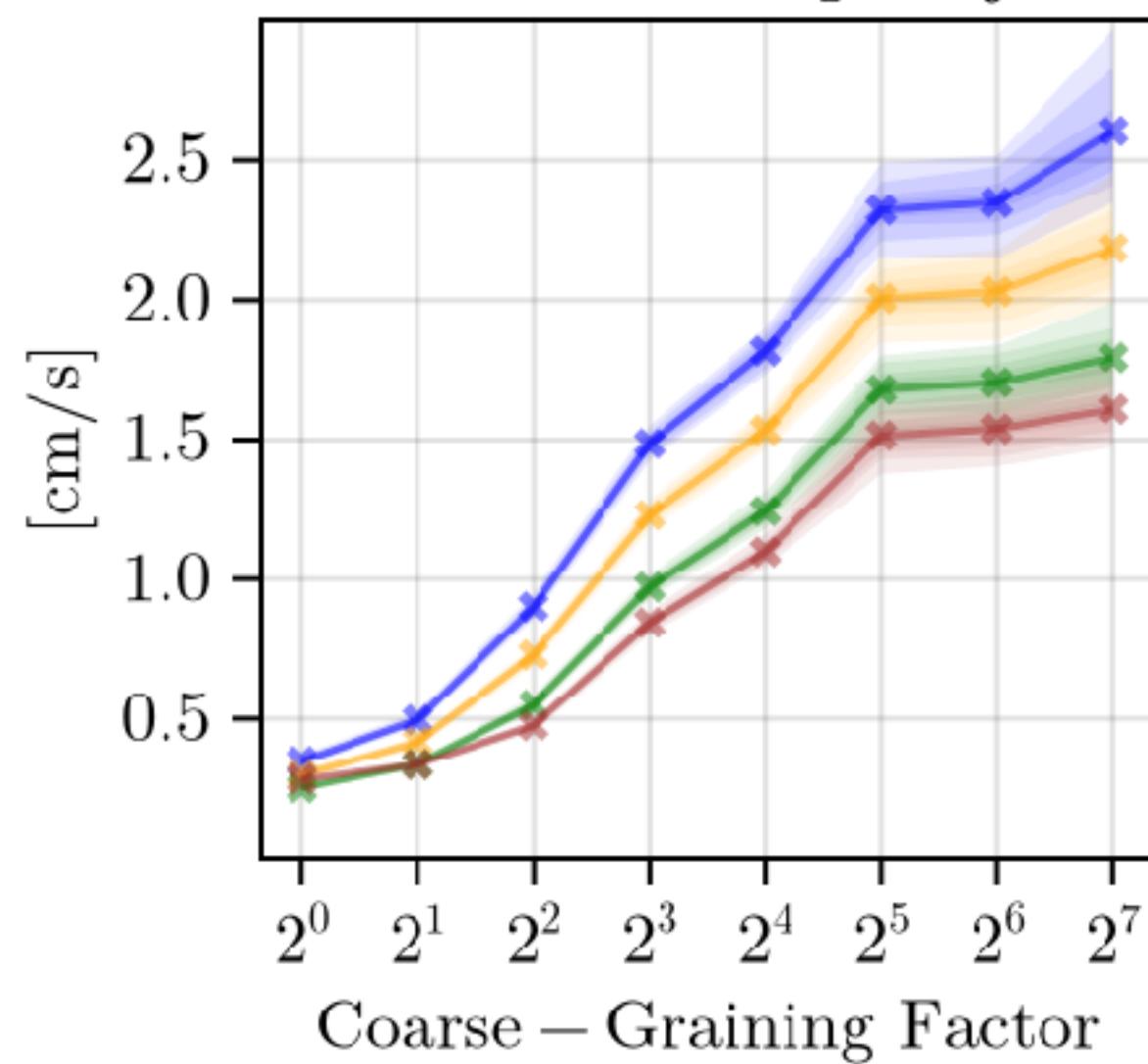
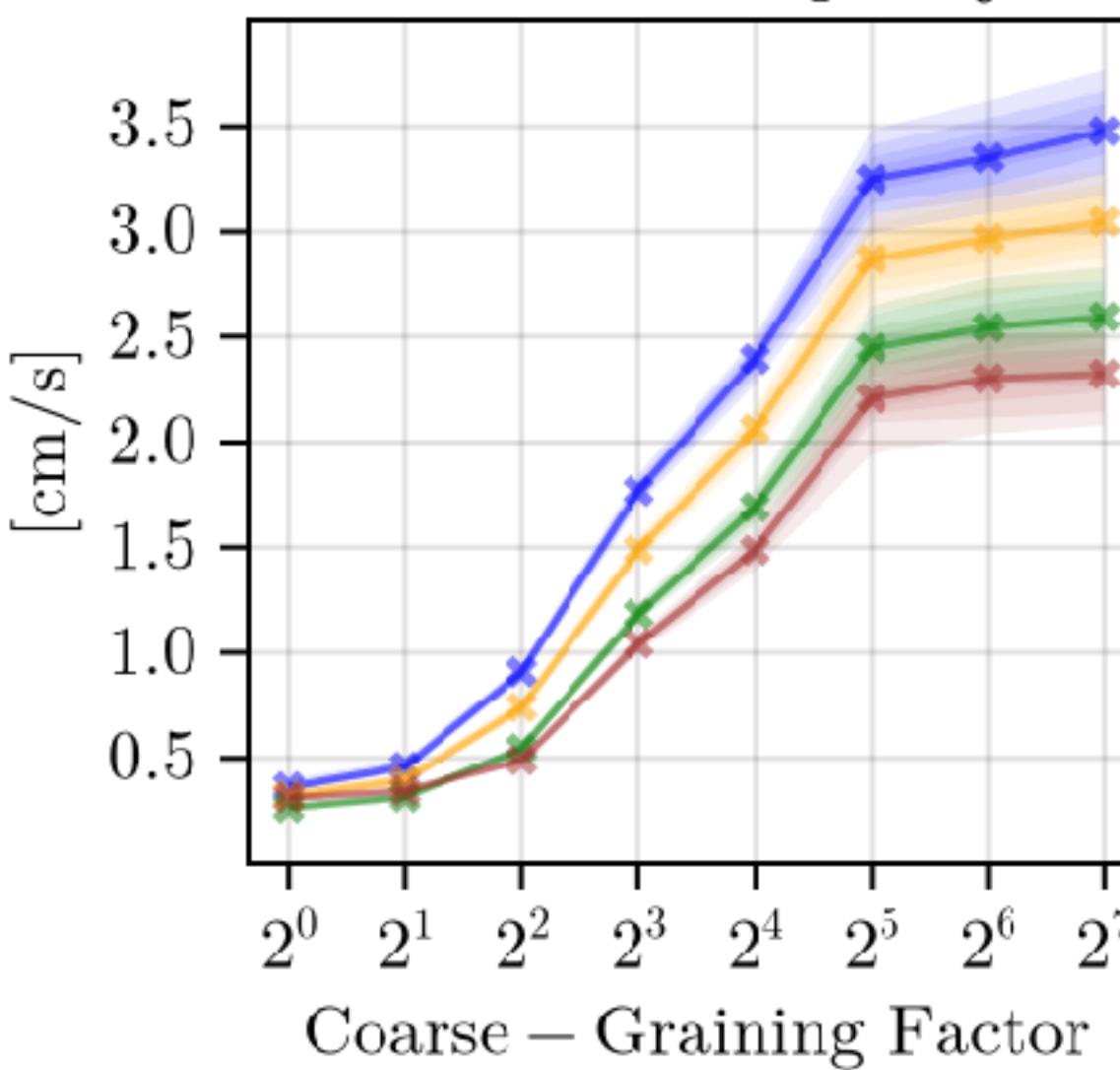
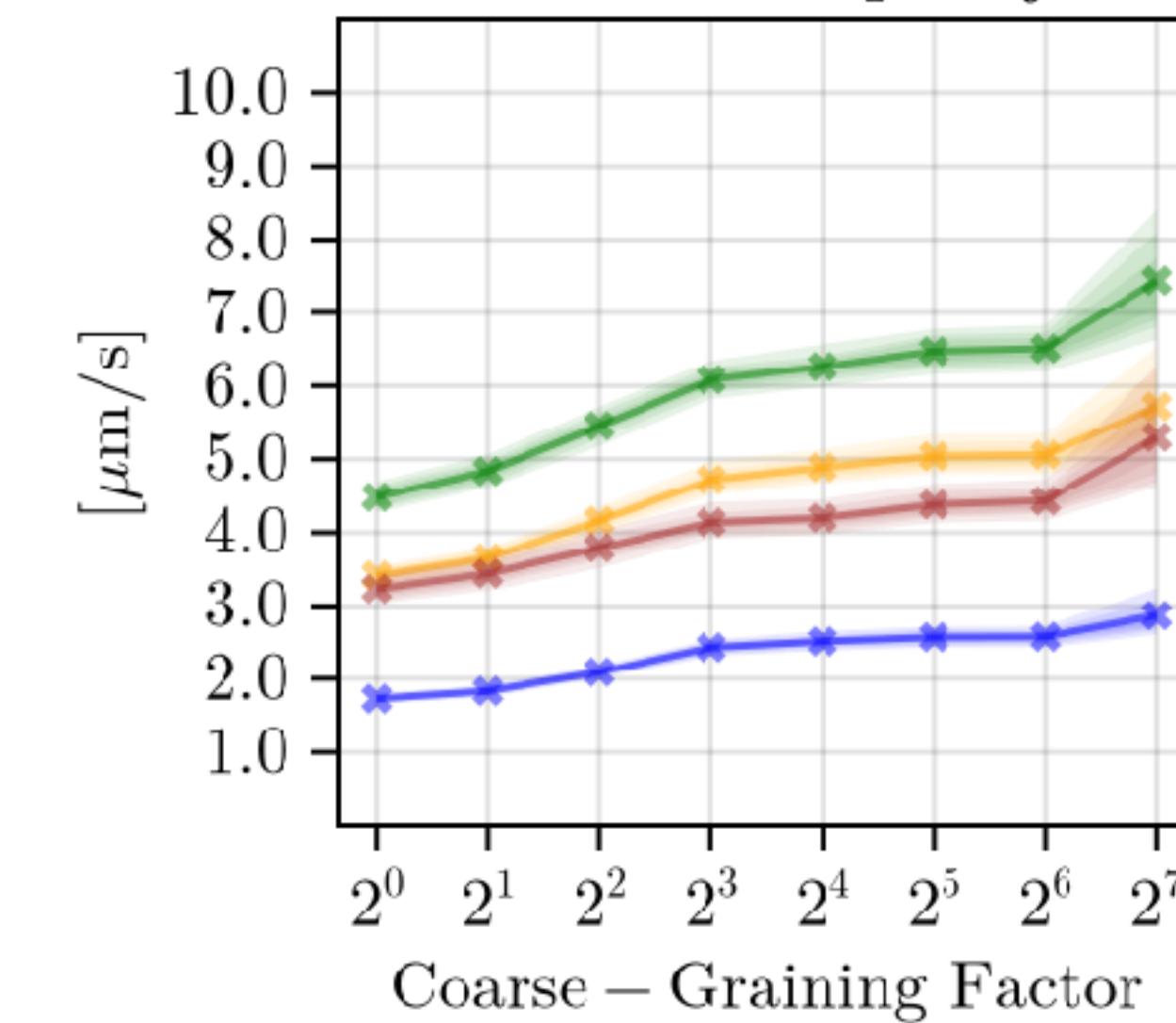
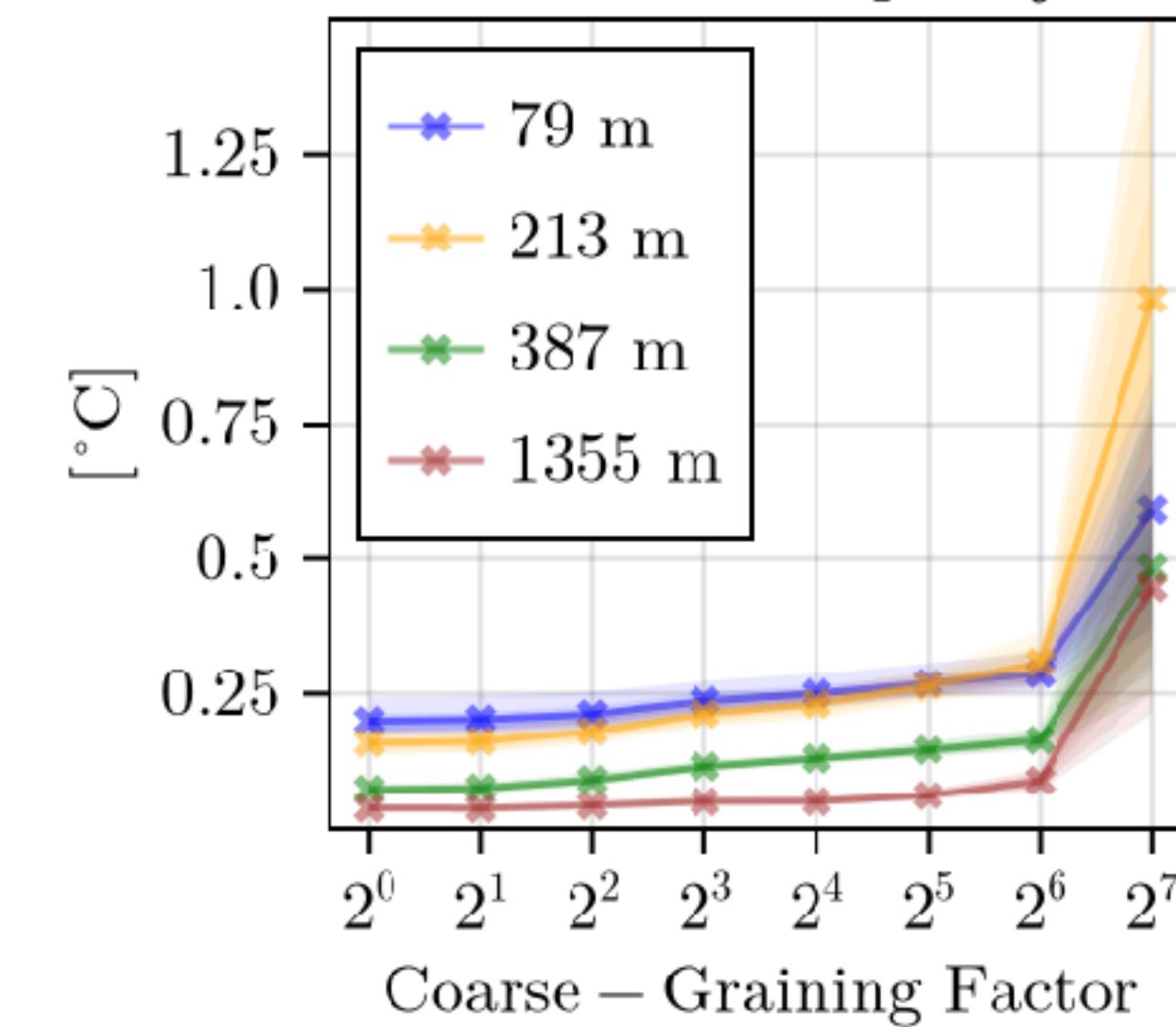
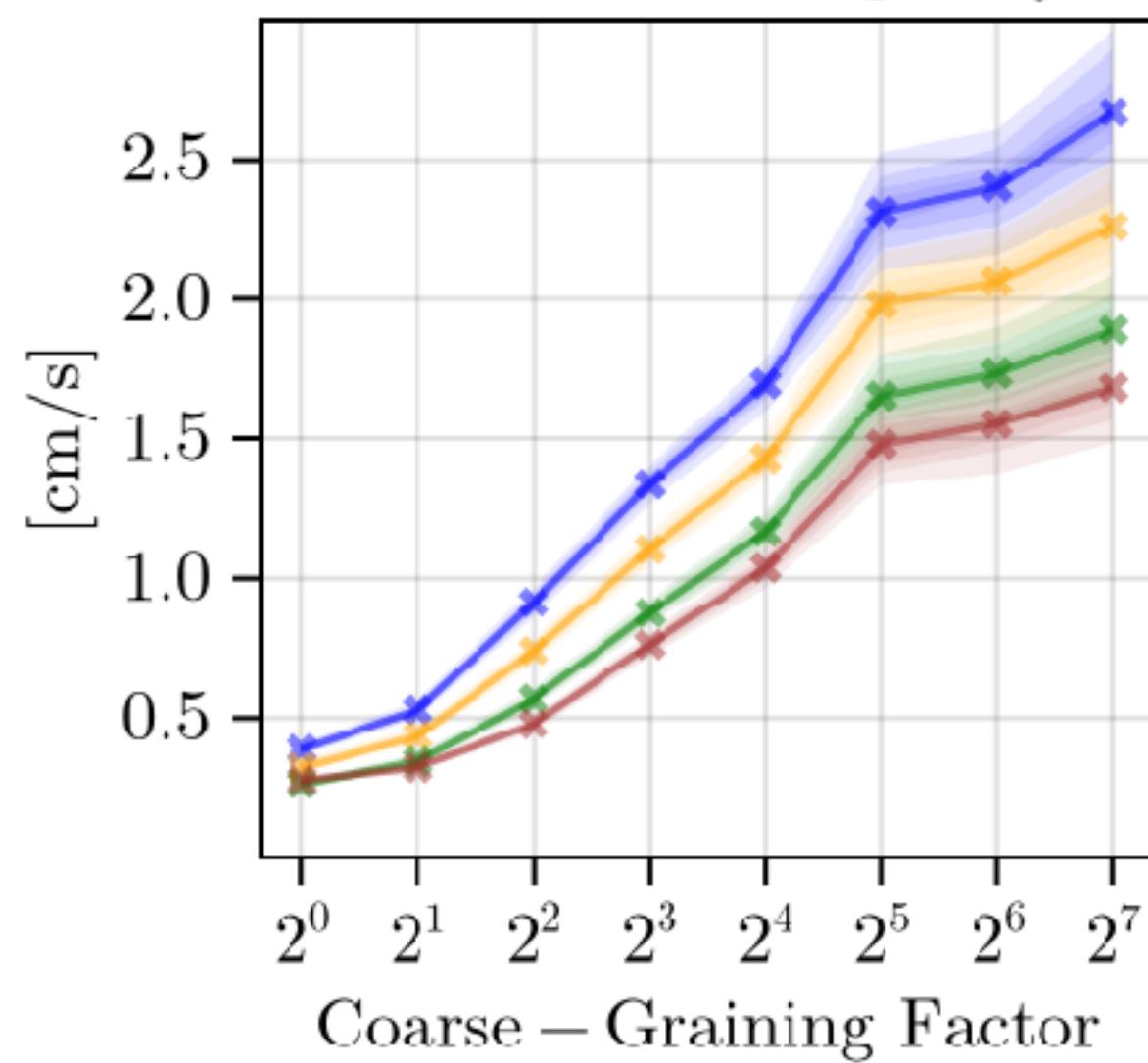
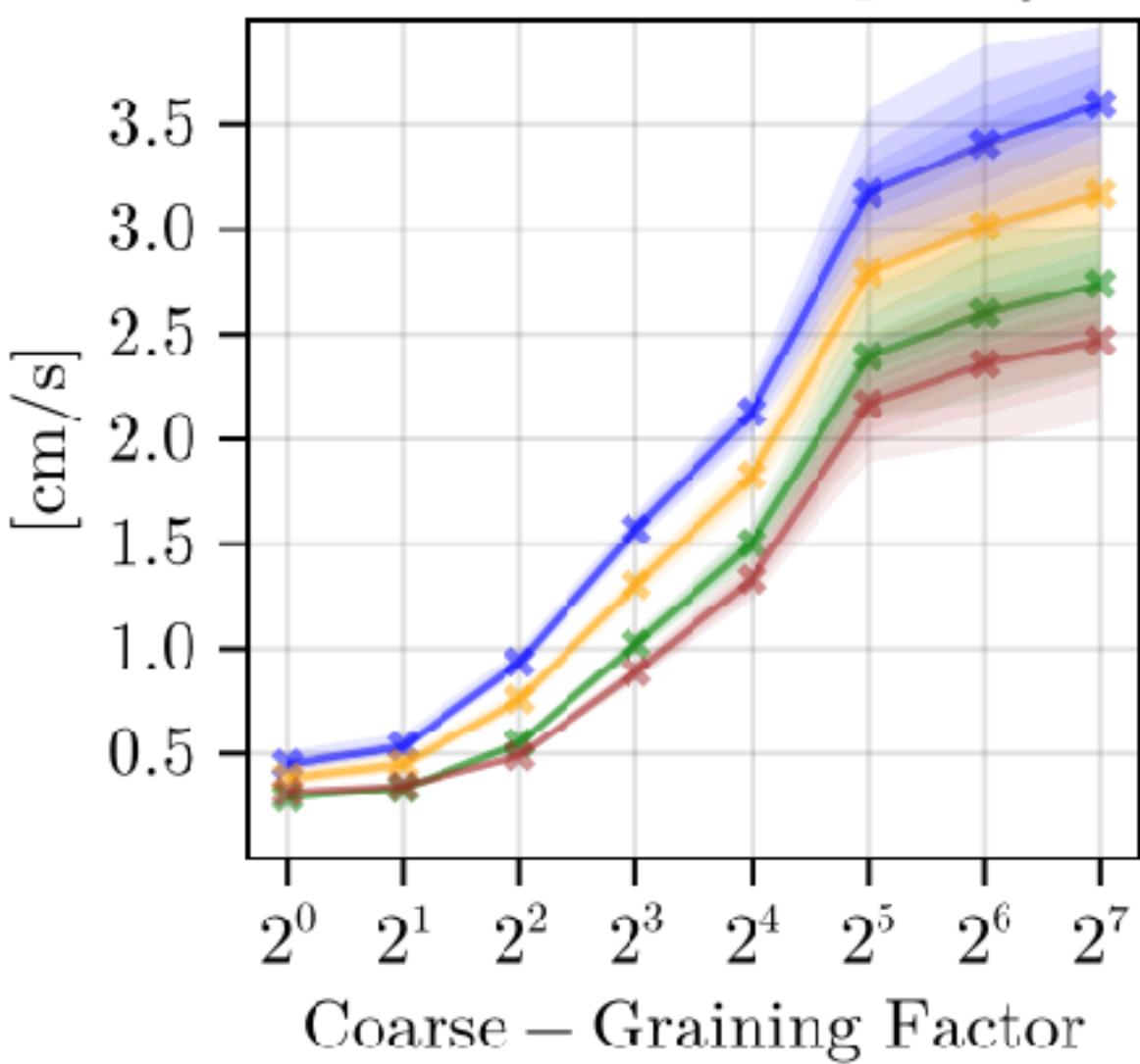
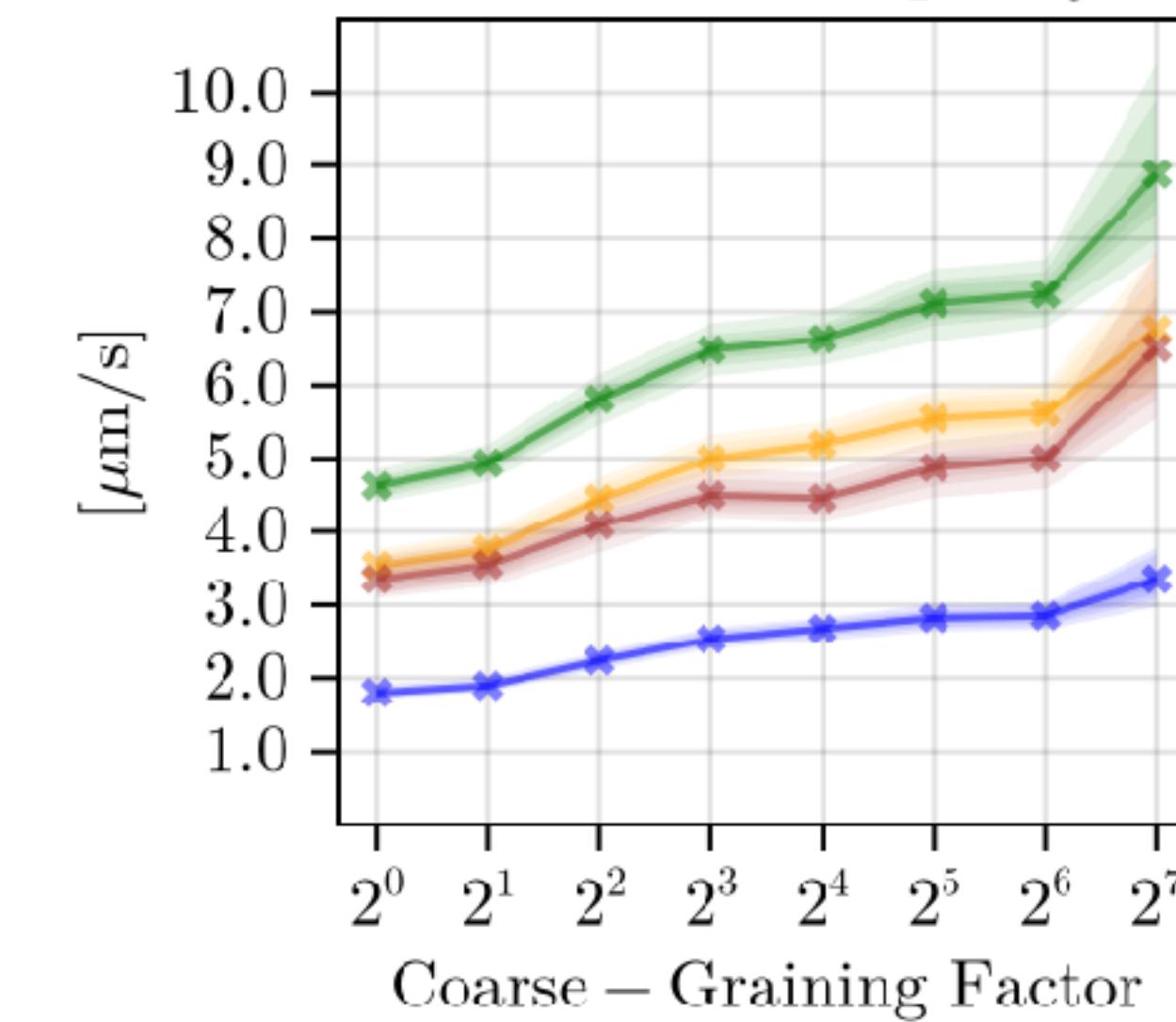
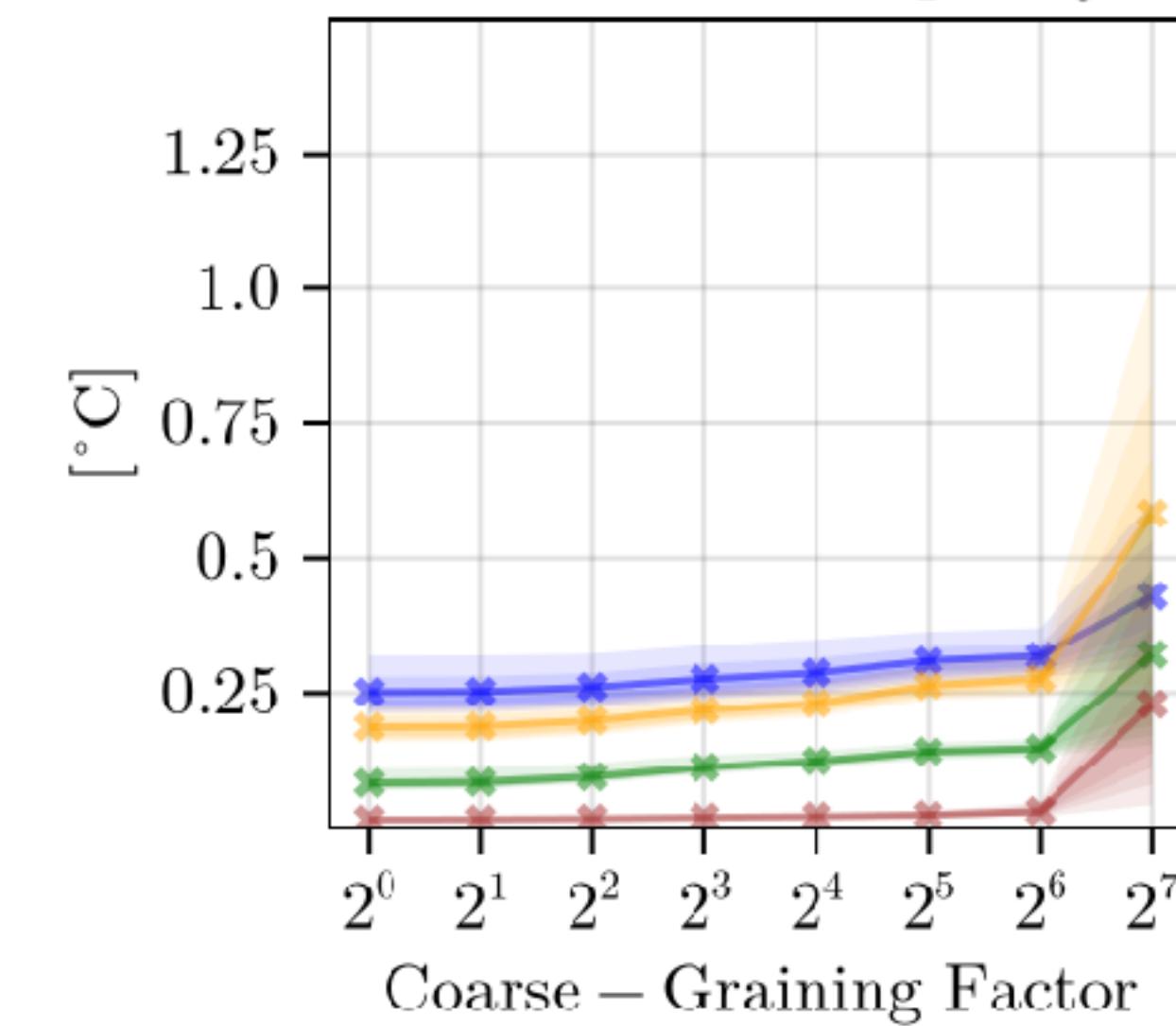


OsC AI Discrepancy U



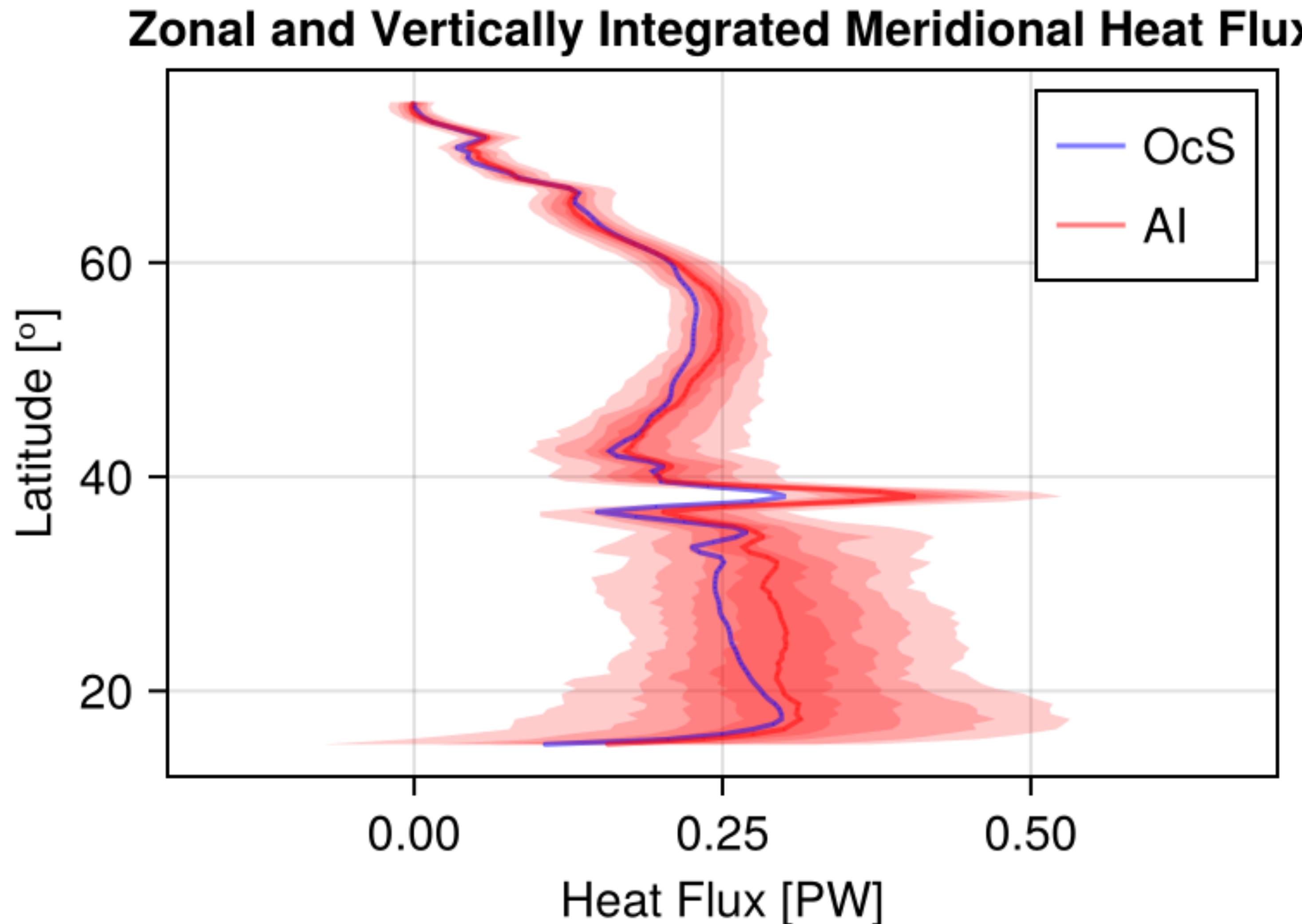
AI Shuffle Discrepancy U



OsC AI Discrepancy U**OsC AI Discrepancy V****OsC AI Discrepancy W****OsC AI Discrepancy T****AI Shuffle Discrepancy U****AI Shuffle Discrepancy V****AI Shuffle Discrepancy W****AI Shuffle Discrepancy T**

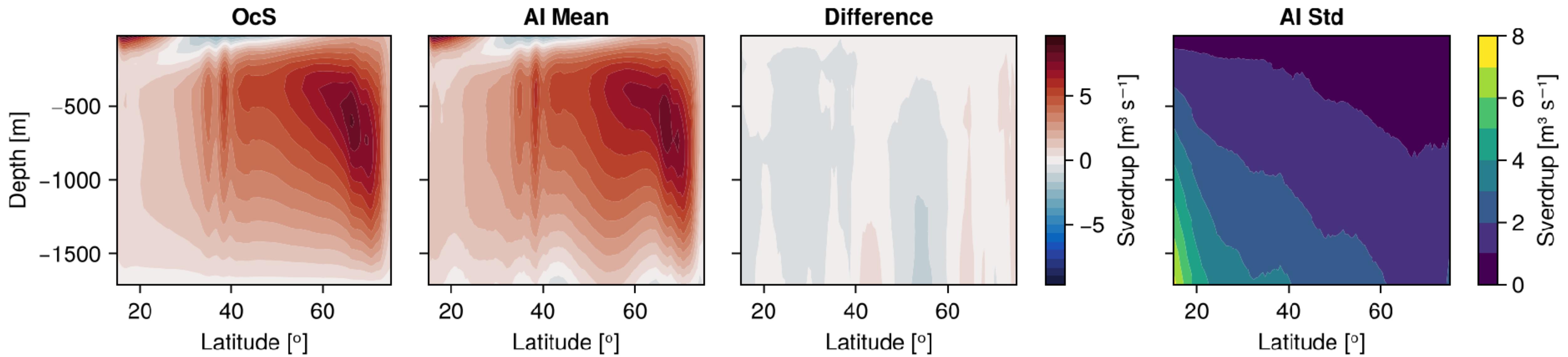
Results: Heat Transport

Application: Ocean Inference Combining Depths



Results: Overturning

Application: Ocean Inference Combining Depths



Take aways

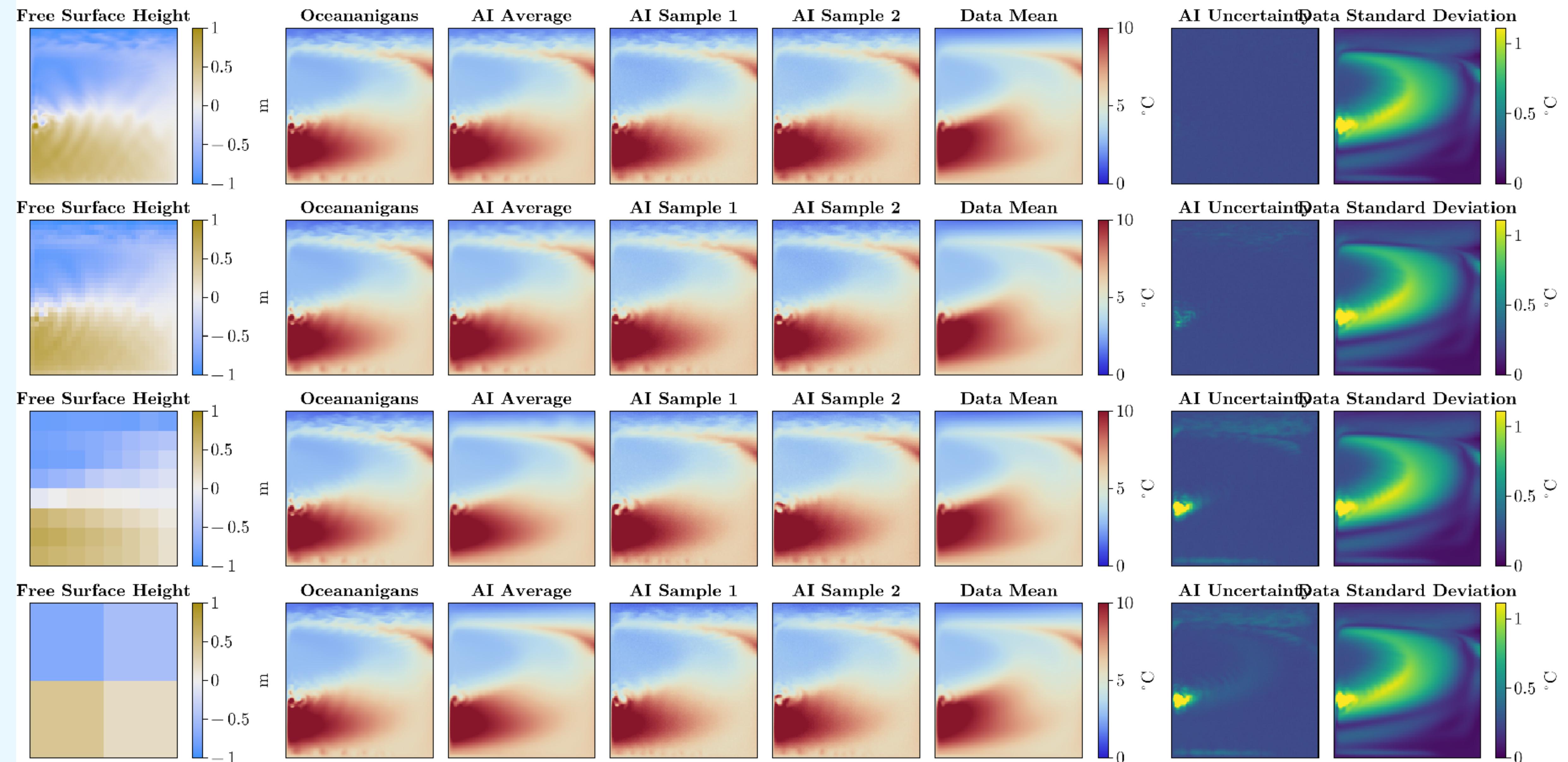
- Questions in Geophysics should be reformulated as probabilistic inference questions
- Gen AI Provides Meaningful Uncertainty Estimates

Questions?

Drawbacks

- Expensive to Evaluate
- Expensive to Train
- Harder to understand the theory of why it works
- Harder for interpretability
- Harder to evaluate
- Requires modifying old / designing new architectures

Application: Ocean Inference Result (400m depth)



Brief Overview of Score-Matching

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**Empirical
Distribution**

$$\rho(x) = \frac{1}{N} \sum_{n=1}^N \delta(x - x^n)$$

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**Neural-Network
implicit
regularization**

$$\mathbb{E} |\nabla \ln \rho_\sigma(x) - N_\theta(x)|^2$$

Brief Overview of Score-Matching

Instead of minimizing

$$\mathbb{E}|\nabla \ln \rho_\sigma(x) - N_\theta(x)|^2$$

We minimize

$$\mathbb{E}_x \mathbb{E}_Z |Z/\sigma + N_\theta(x + \sigma Z)|^2$$

Brief Overview of Score-Matching

