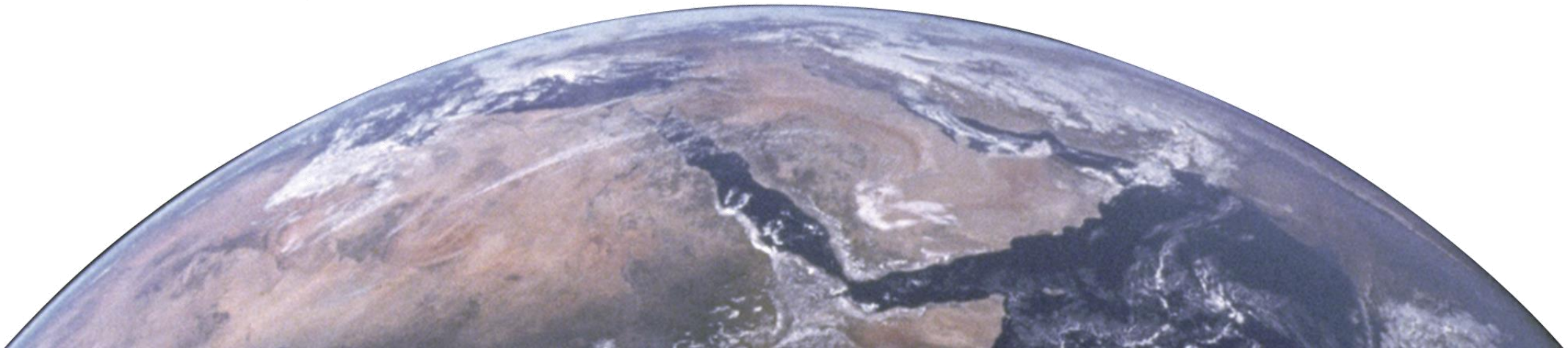


The University of Texas at Austin
**Aerospace Engineering
and Engineering Mechanics**
Cockrell School of Engineering

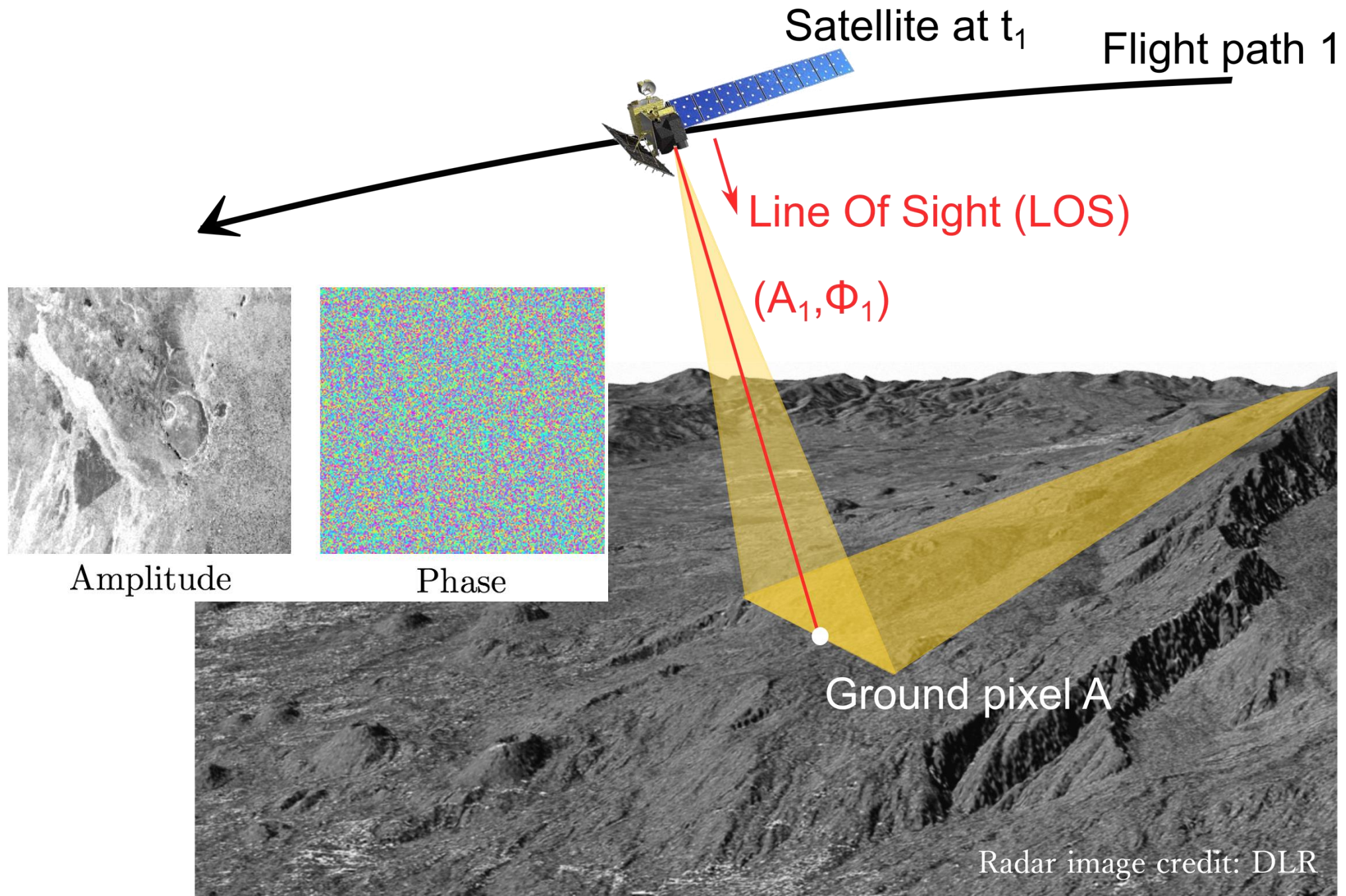
InSAR theory, interferogram processing, and its application to earth science studies

Ann Chen

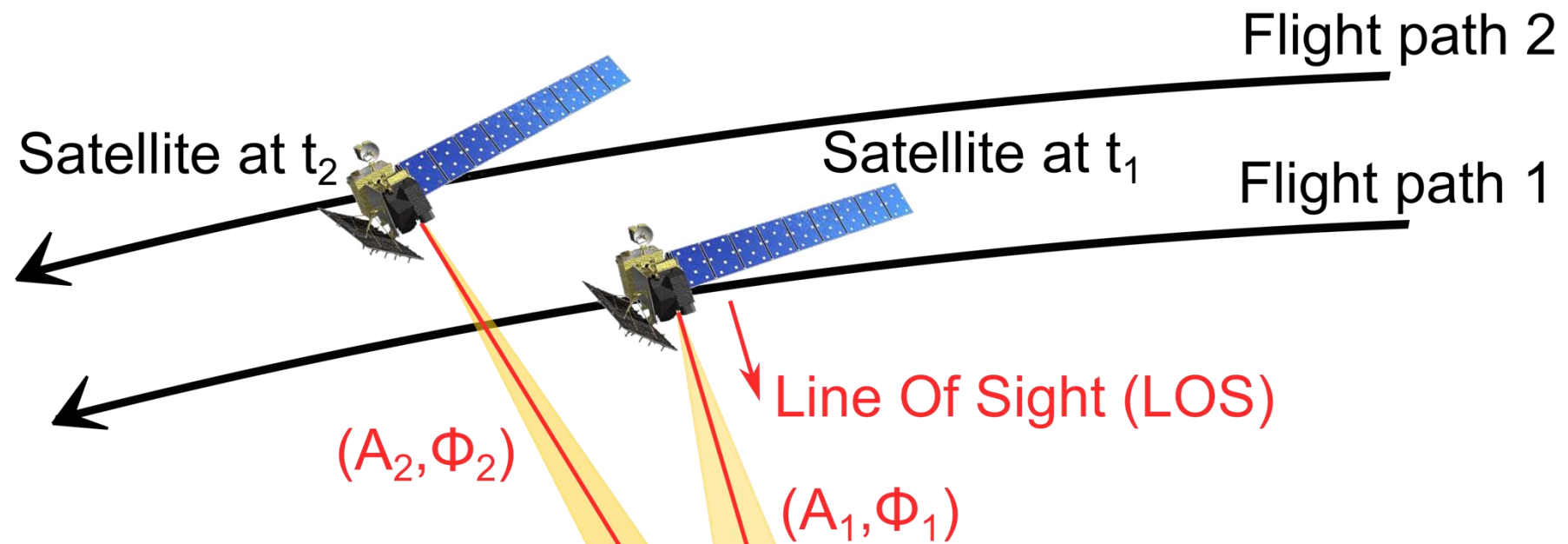
** This lecture was originally developed by Paul Rosen and Scott Hensley from JPL.*



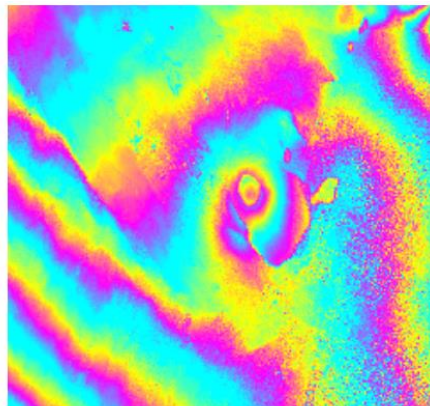
Synthetic Aperture Radar (SAR)



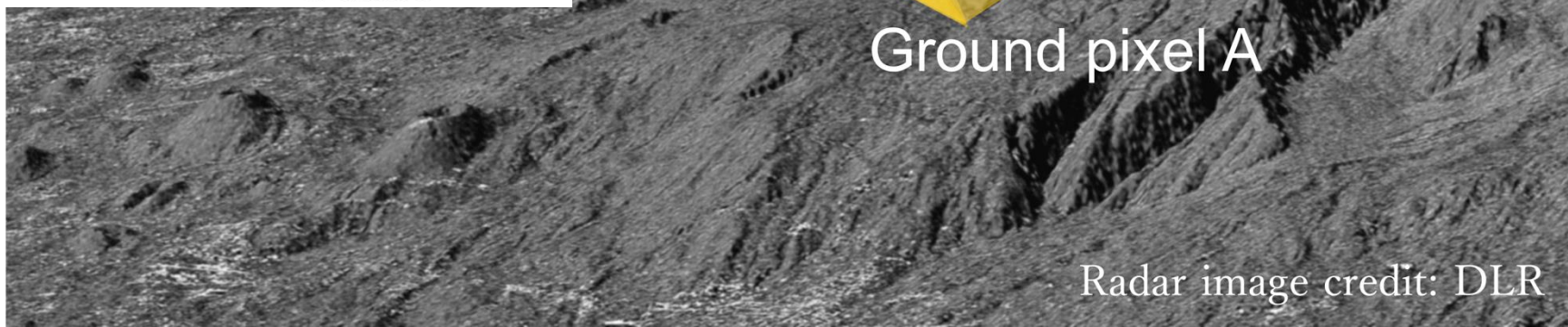
Interferometric Synthetic Aperture Radar (InSAR)



Amplitude



Phase

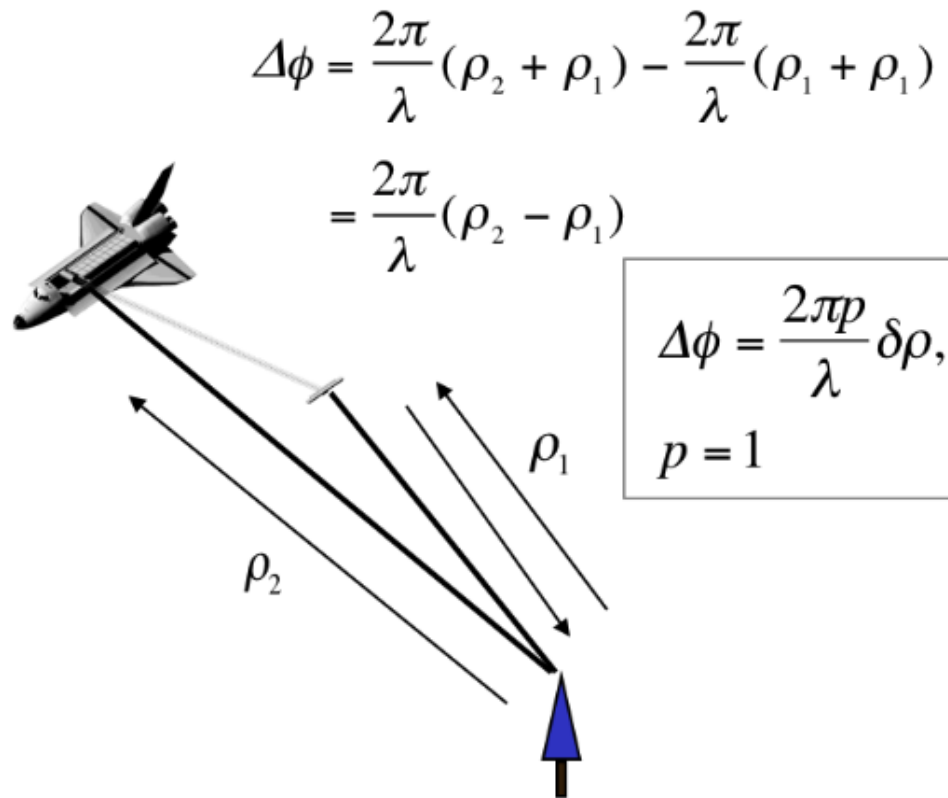


Ground pixel A

Radar image credit: DLR

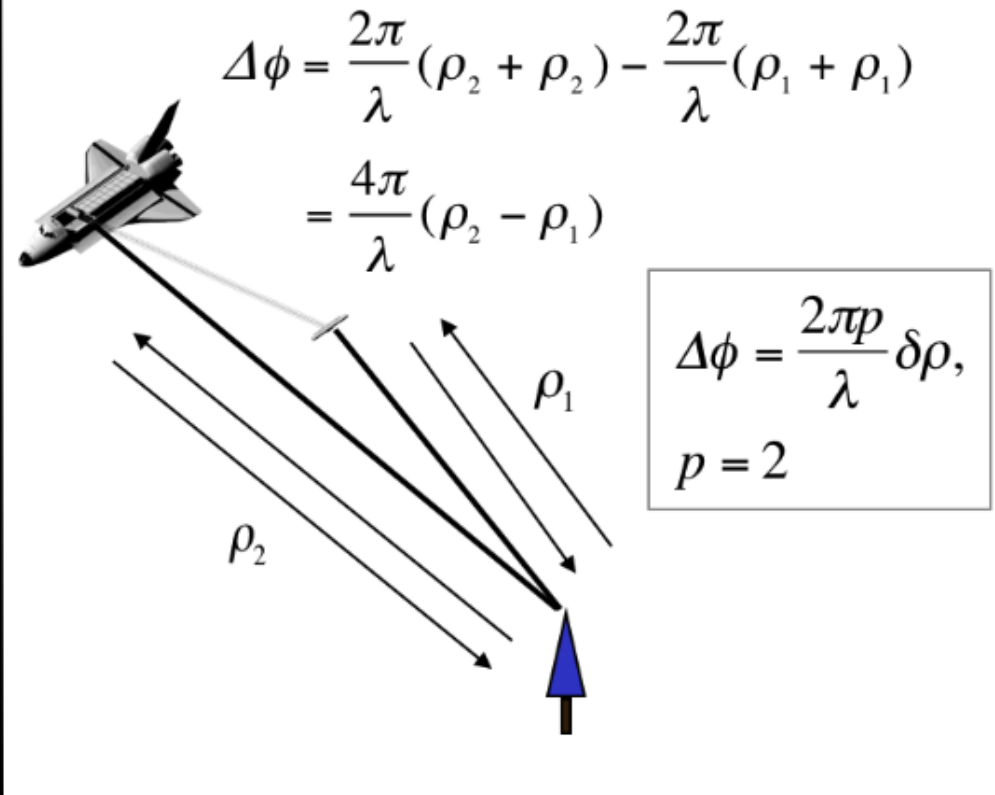
The relationship of phase to propagation distance

Classic



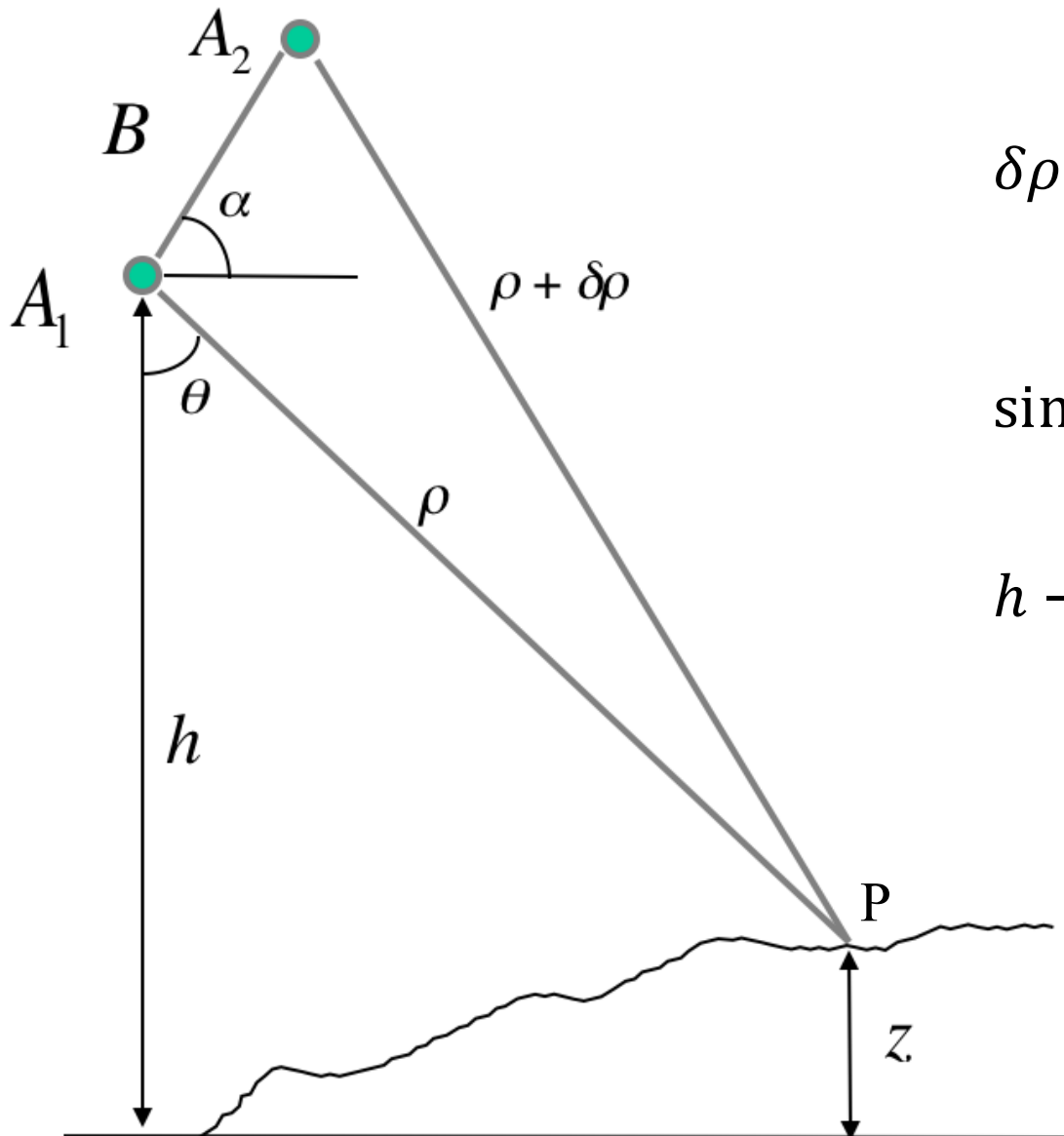
Classic: one antenna transmits, and both receives.

Ping-Pong



Ping pong: each antenna transmits and receives its own echo.

Interferometry for topography



$$\delta\rho = \frac{\lambda}{2\pi p} (\phi_1 - \phi_2) = \frac{\lambda}{2\pi p} \Delta\phi$$

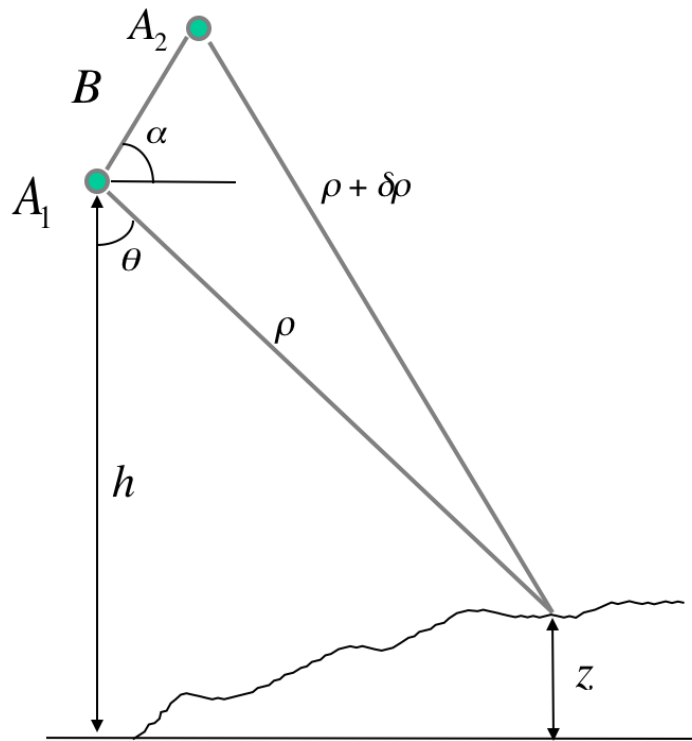
$$\sin(\theta - \alpha) = \frac{\rho^2 + B^2 - (\rho + \delta\rho)^2}{2\rho B}$$

$$h - z = \rho \cos \theta$$

We can measure $\Delta\phi$ (unwrapped) from radar. Given h, B, α and ρ , we can solve for θ , which gives us z at every pixel location.

Solution for topography from interferometric phase

- After subtracting a flat earth fringe:



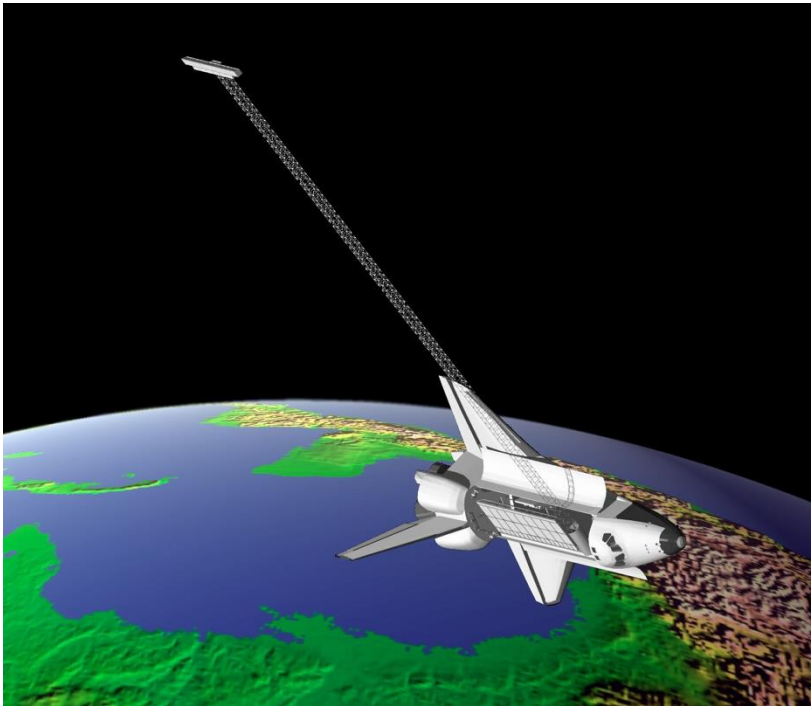
$$\phi_{topo} = -\frac{2\pi p B}{\lambda \rho} \left(\frac{1}{\tan \theta_0} \cos \alpha + \sin \alpha \right) dz$$

Known!

The constant-phase contours will appear at the constant height on the imaged topography. The phase will repeat every 2π radians, so therefore each “fringe” (one phase cycle) corresponds to a constant height difference (the ambiguity height).

Implementation options

- A single spacecraft with two displaced antennas
- Two spacecraft, each with a synthetic aperture radar, flying in formation to form the interferometer baseline.



The Shuttle Radar
Topography Mission

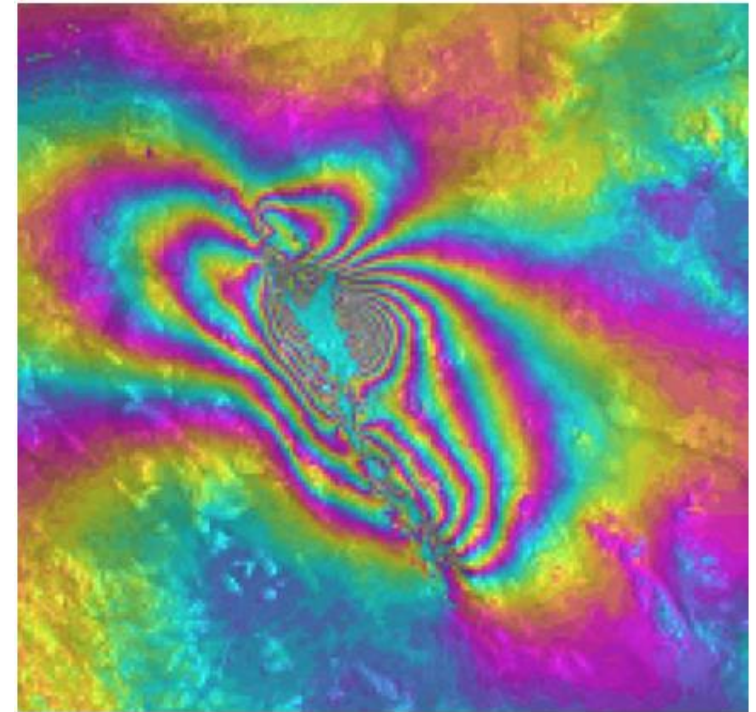
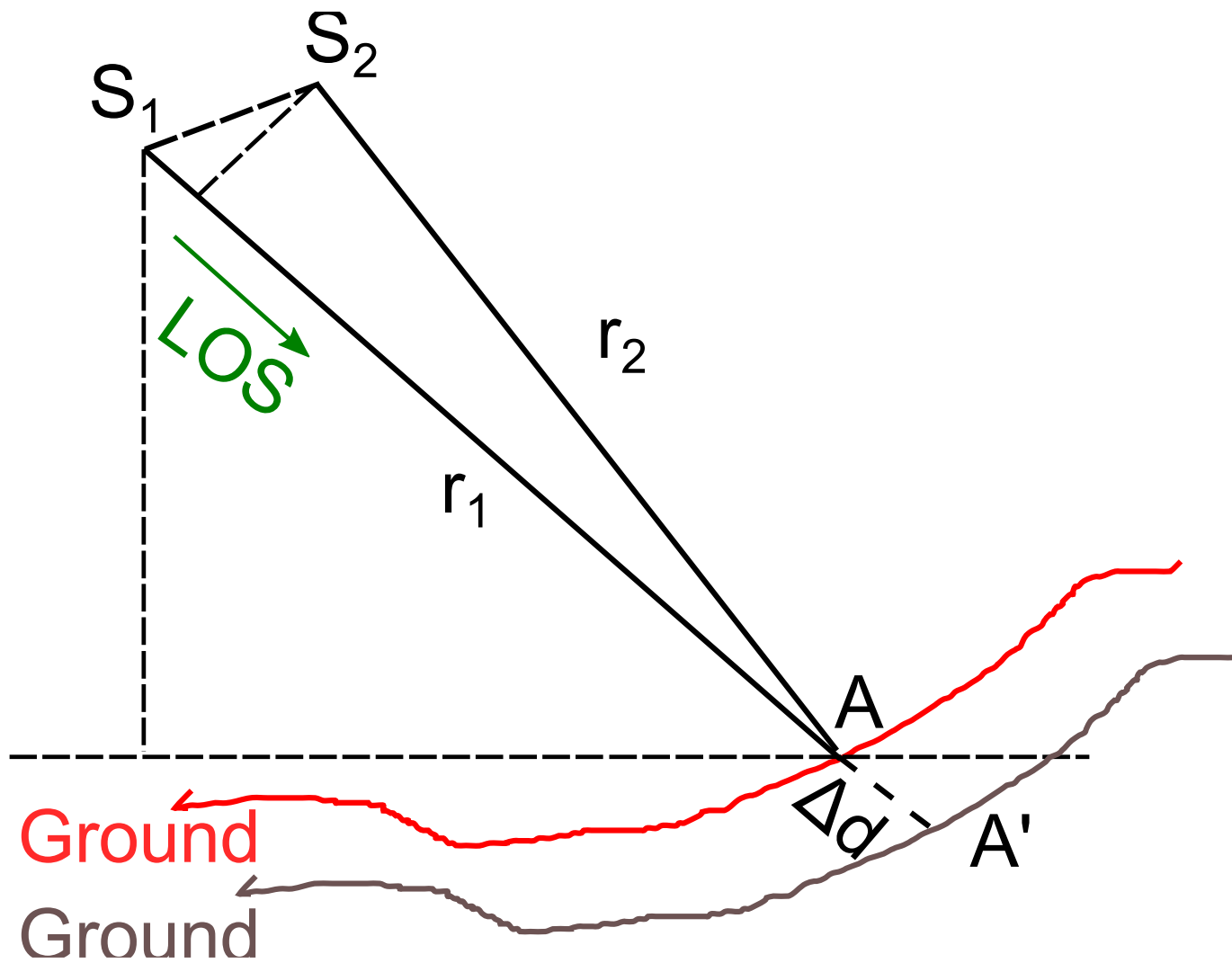


TanDEM-X (TerraSAR-X add-on for
Digital Elevation Measurement)

Technology for generation of DEM

- Optical-stereo instrumentation
- Laser profiling instruments
- Radar interferometry

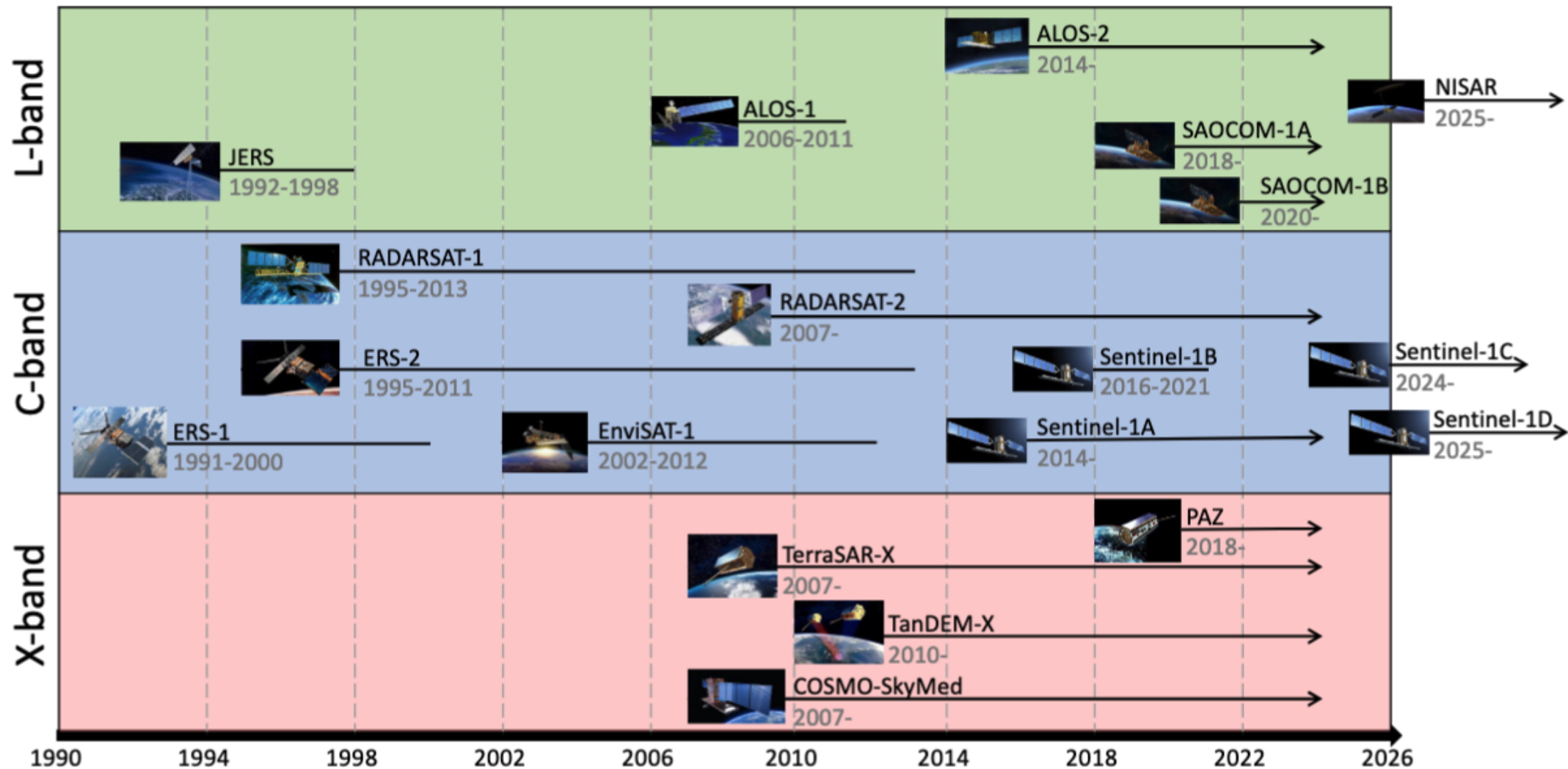
Interferometry for surface deformation



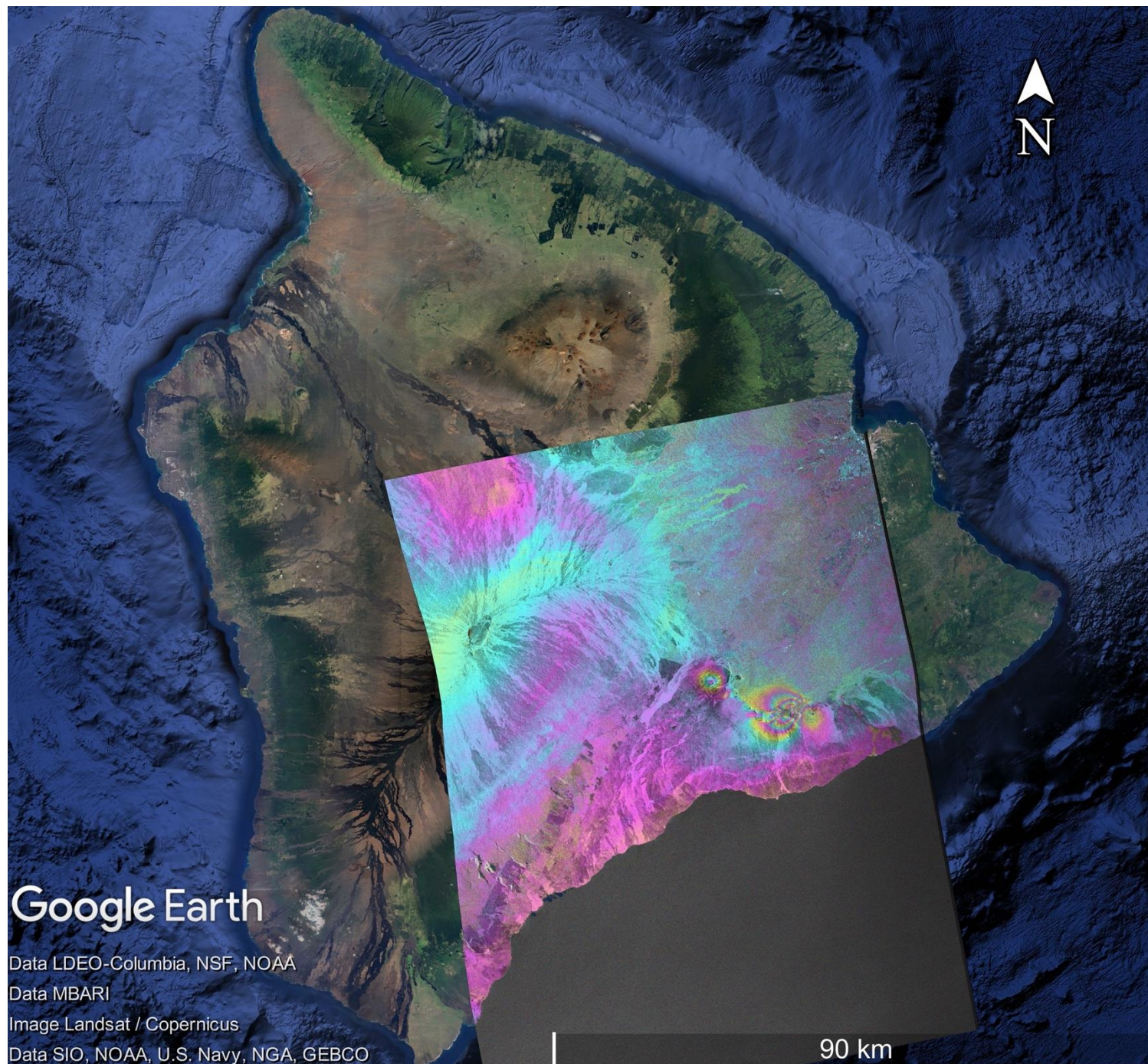
$$\phi_2 - \phi_1 = \phi_{topo} + \frac{4\pi}{\lambda} \Delta d$$

λ : radar wavelength
 Δd : LOS deformation

Available spaceborne InSAR missions



An interferogram example



Interferometry Sensitivities

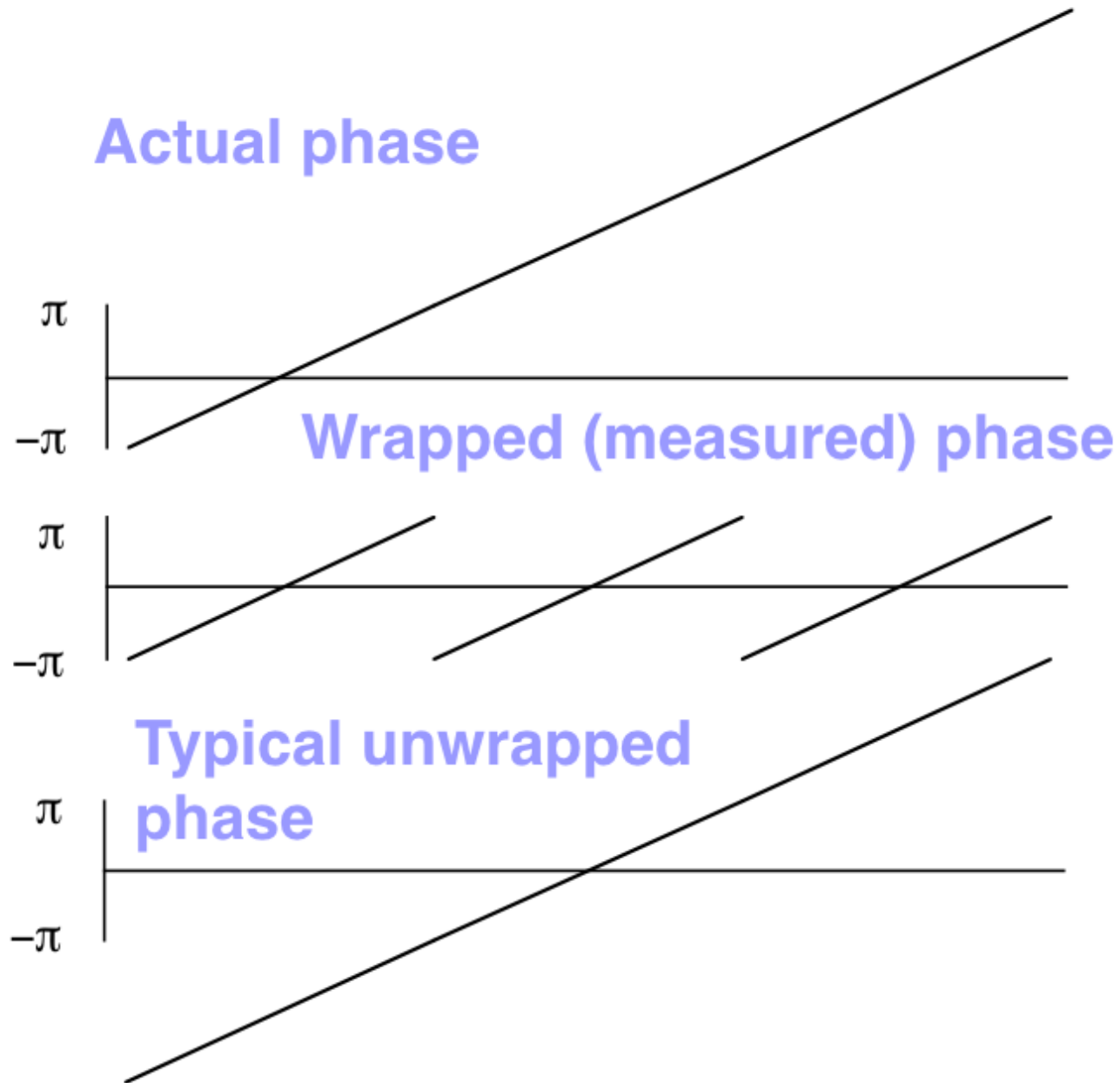
- Topographic Sensitivity (meter level topography)

$$\frac{\partial \Delta \phi}{\partial h} = \frac{2\pi p b \cos(\theta - \alpha)}{\lambda \rho \sin \theta}$$

- Displacement Sensitivity (cm-mm level deformation)

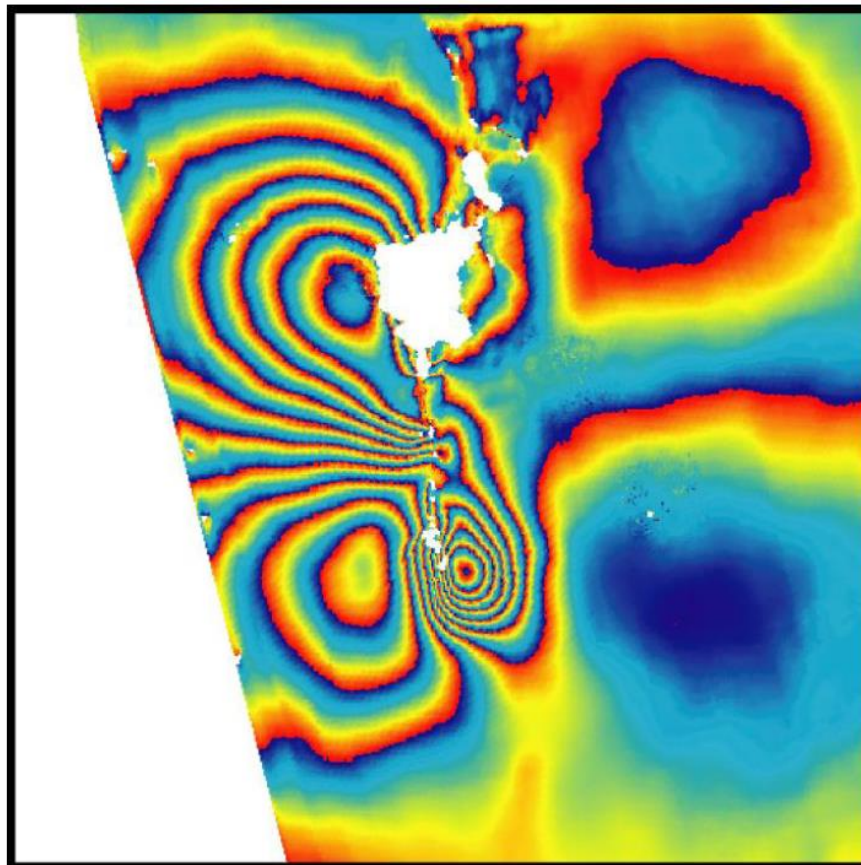
$$\frac{\partial \Delta \phi}{\partial \Delta \rho} = \frac{4\pi}{\lambda}$$

Phase unwrapping

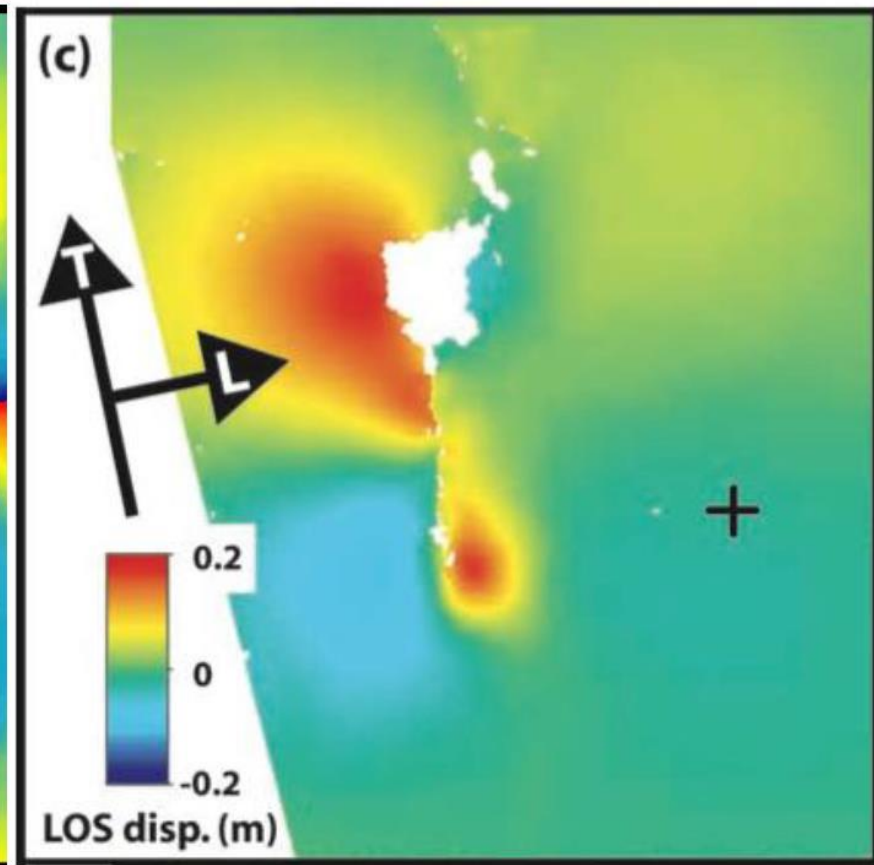


Phase unwrapping

Wrapped



Unwrapped

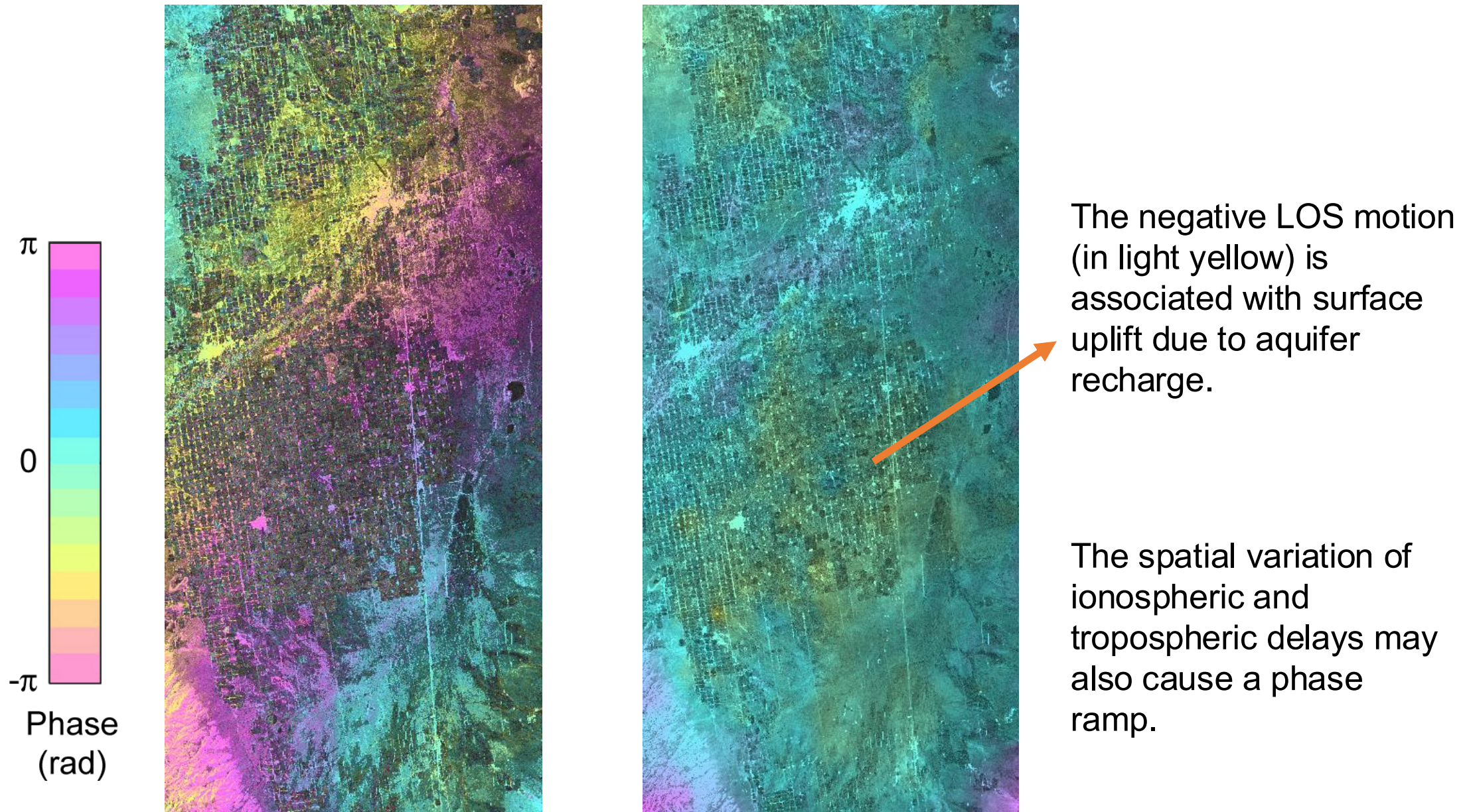


Error Sources in LOS measurements

$$\Delta\varphi = \frac{4\pi}{\lambda}\Delta d_{\text{LOS}} + \Delta\varphi_{dem} + \Delta\varphi_{atm} + \Delta\varphi_{iono} + \Delta\varphi_{orb} + \Delta\varphi_{decor} + \Delta\varphi_{unwrp} + \Delta\varphi_n$$

- Orbital errors
- DEM errors
- Ionospheric and tropospheric errors
- Decorrelation and phase unwrapping errors

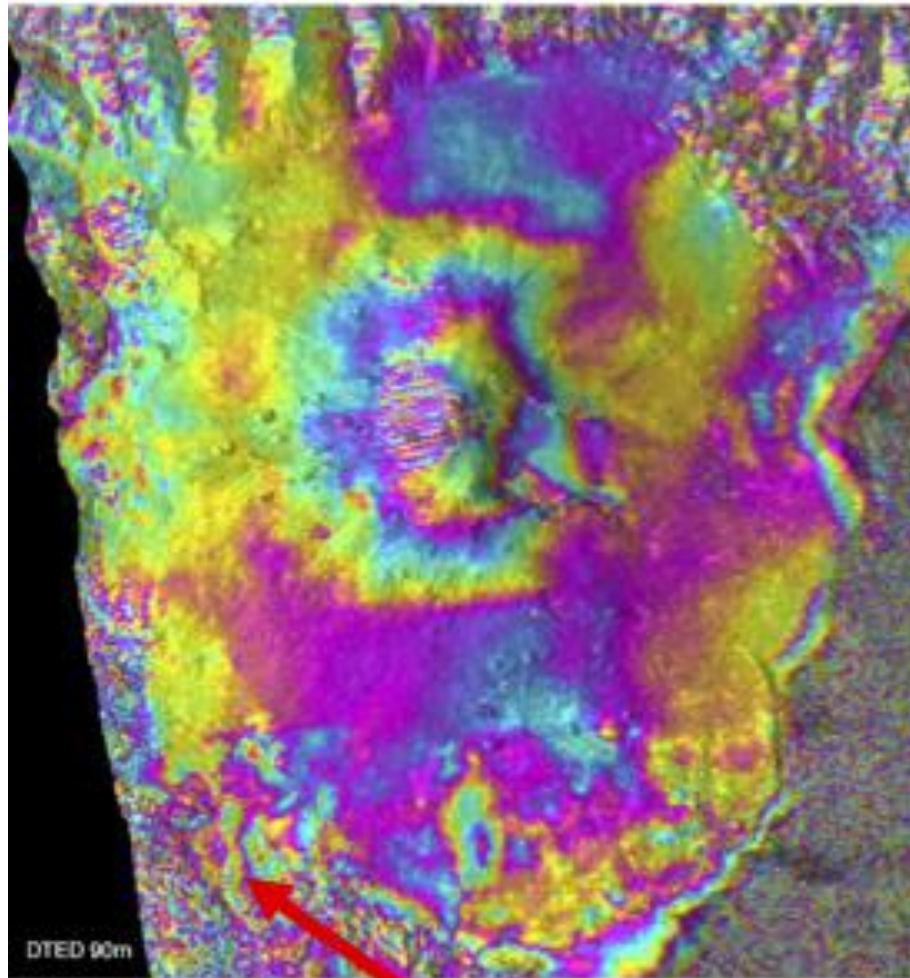
Orbital errors



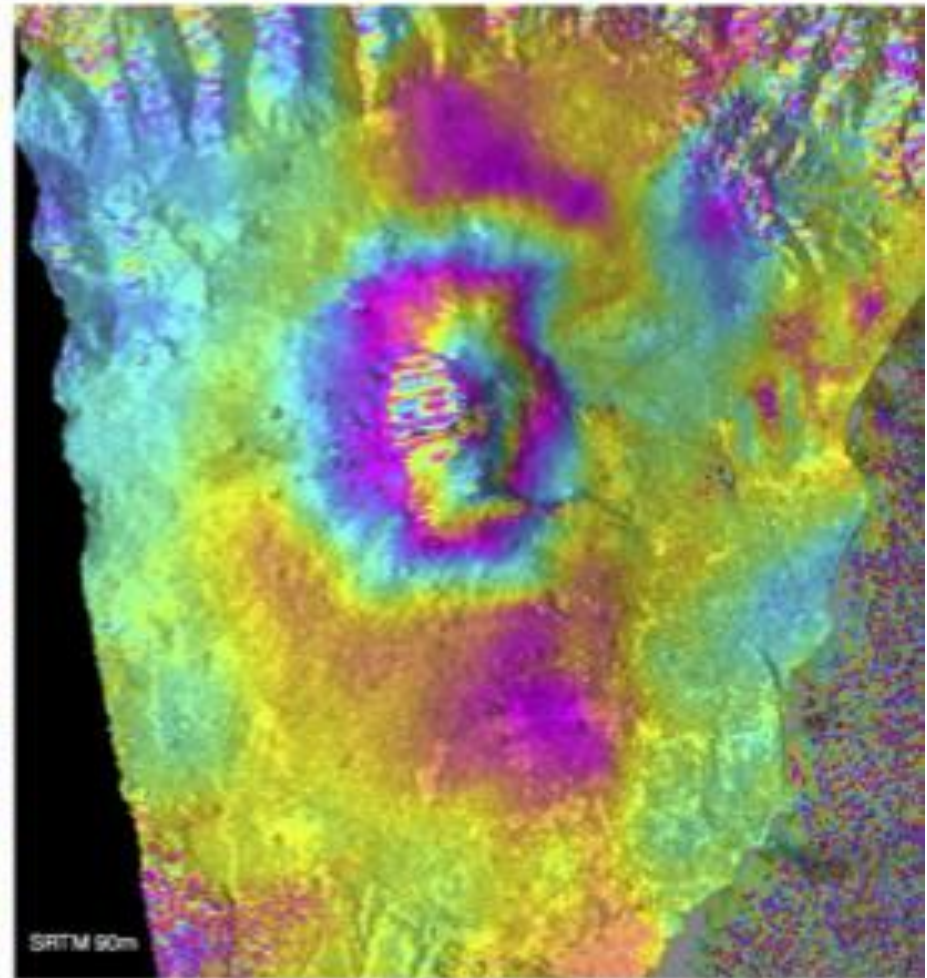
An L-band interferogram before (left) and after (right) the orbital ramp removal.

DEM errors

Poor DEM

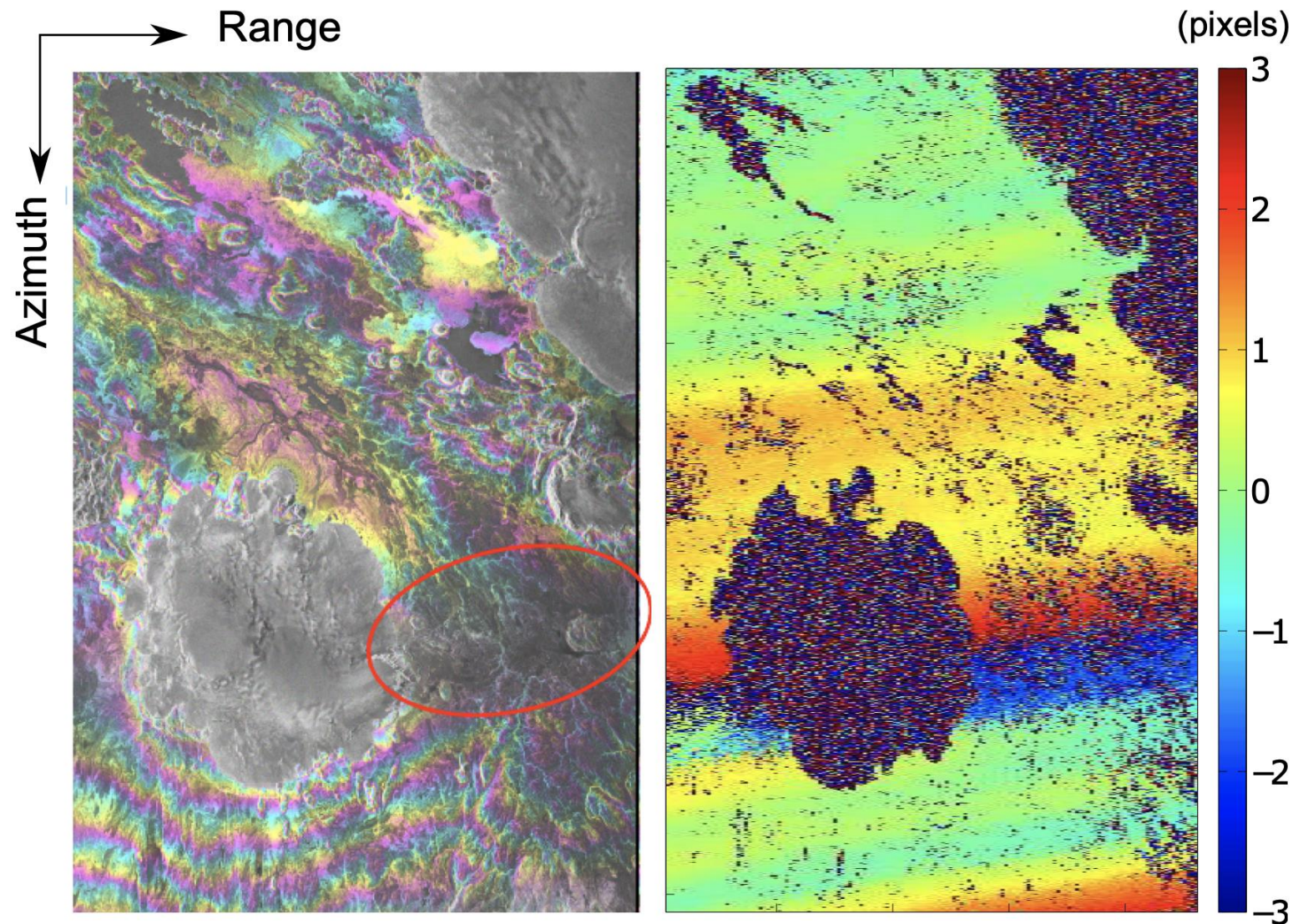


SRTM DEM



Result of DEM Error

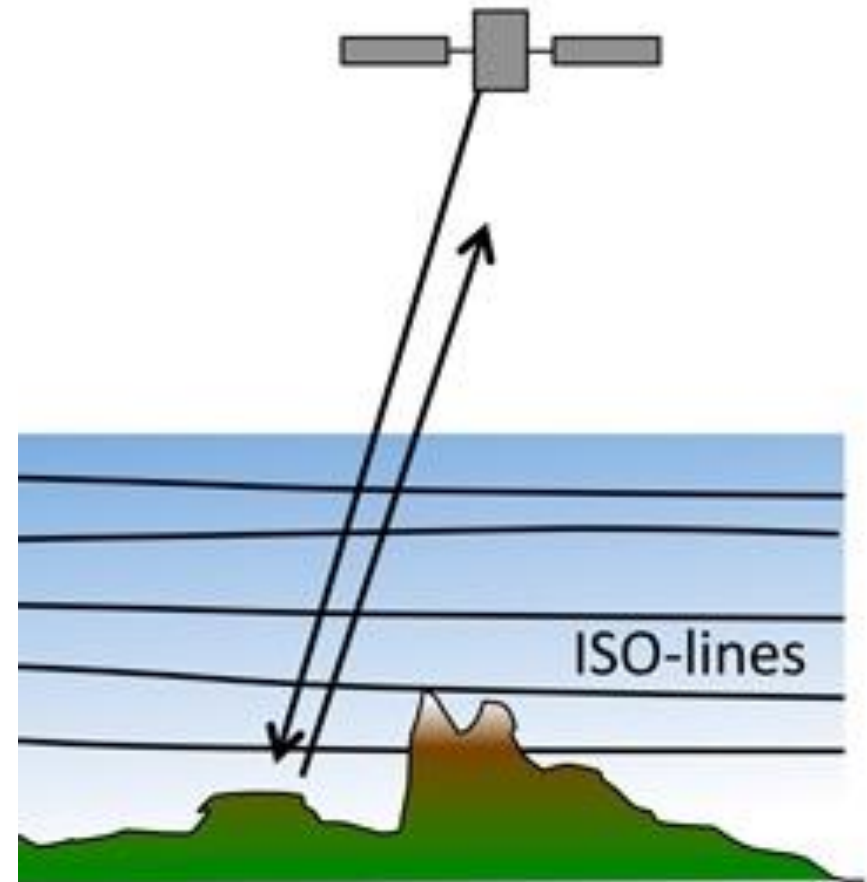
Ionospheric artifacts



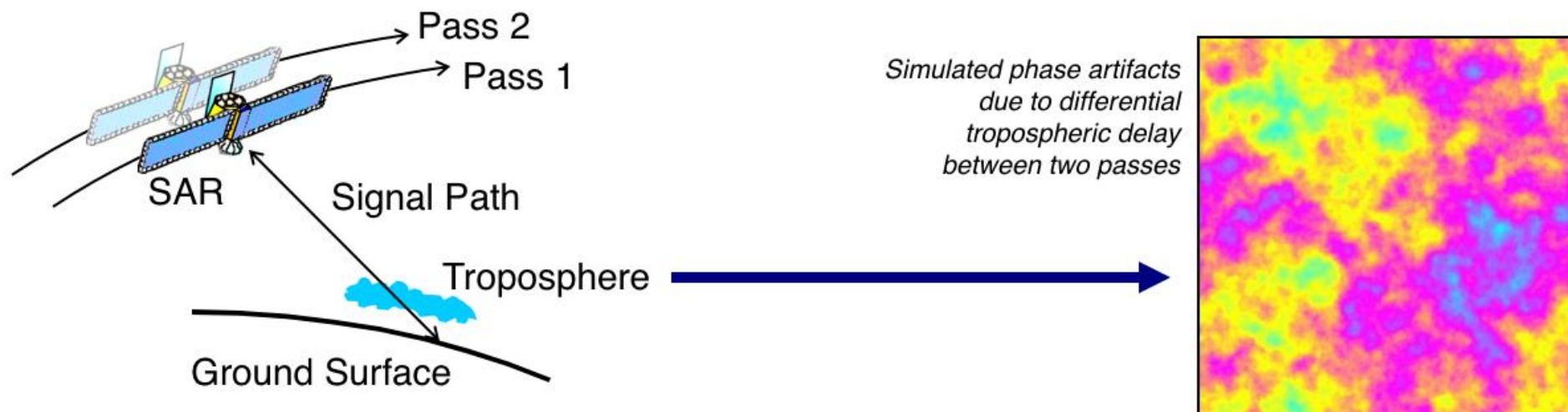
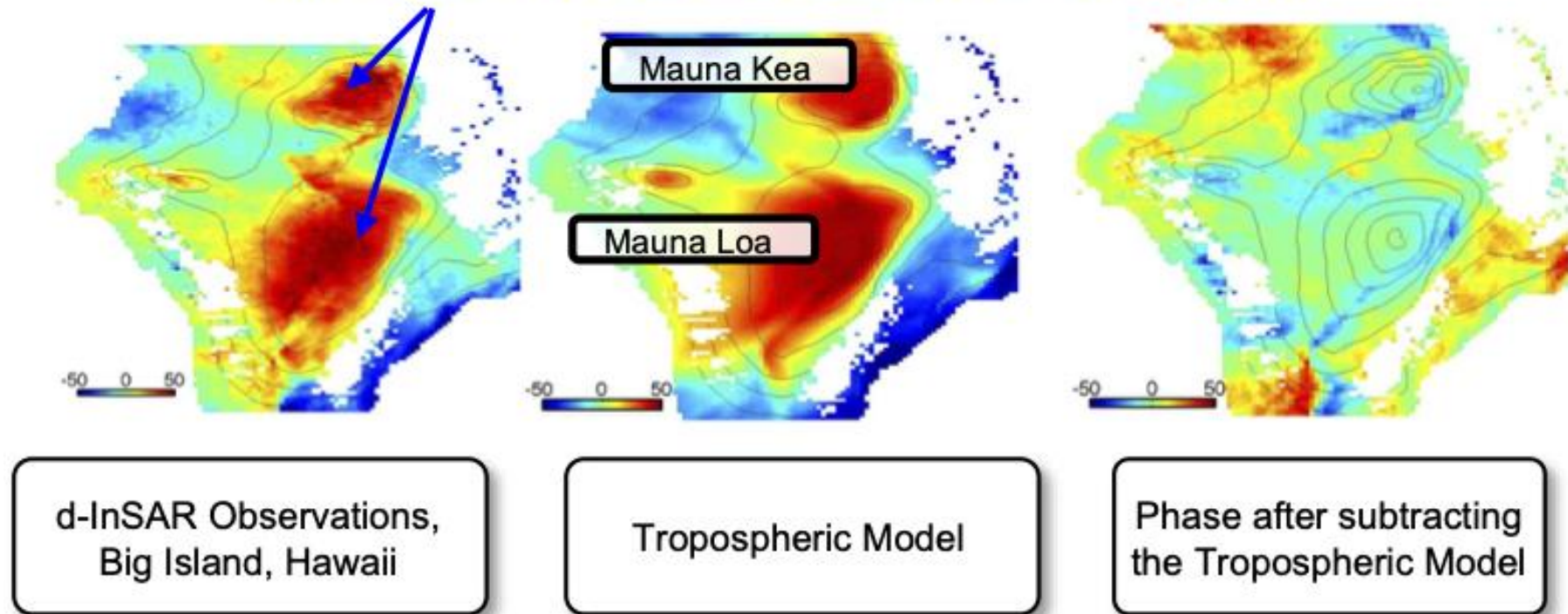
An L-band Iceland interferogram (Left) and the azimuth misregistration measured in pixels due to a local ionospheric TEC gradient.

Tropospheric noise

- Introduced by variation in pressure, temperature, and water vapor in troposphere.
- Affect all radar wavelengths in the same way
- Can be as large as 15 cm or more
- May contain a component that is correlated with topography
- Often contain a component that is random in time.

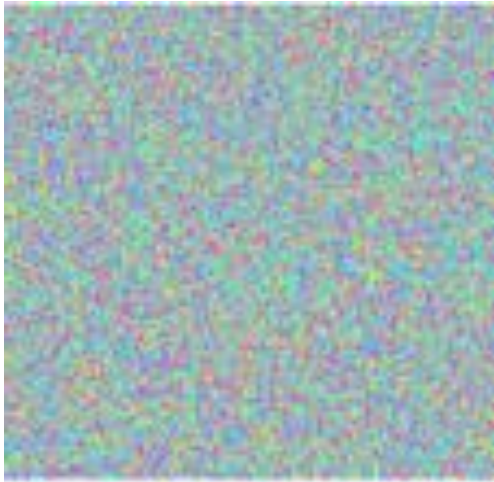


Atmospheric phase correlated with Topography

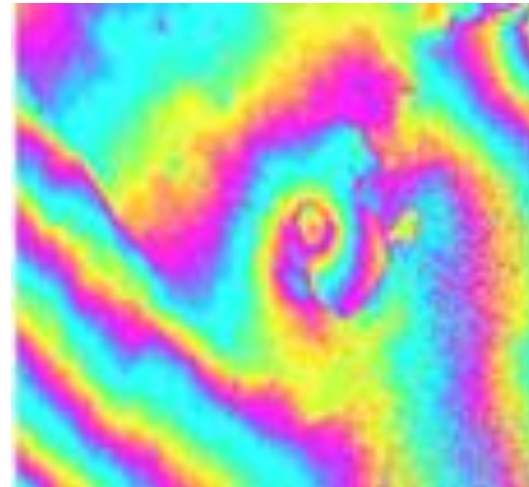


Correlation

- An important measure of interferogram quality is the correlation of the two SAR images. This quantity varies from 0 to 1.



Correlation equals 0 (decorrelated), phase measurements are completely random.



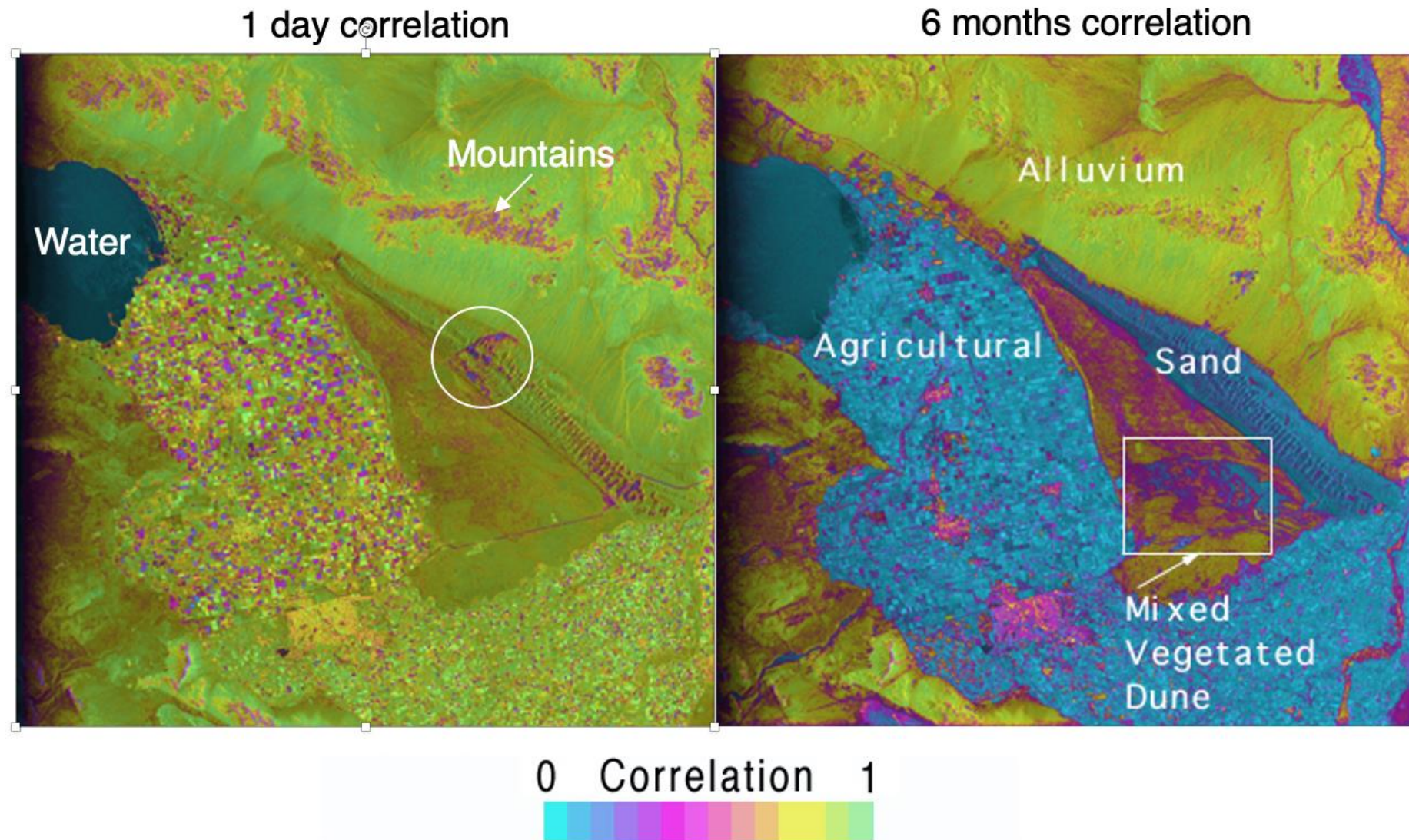
High correlation, phase measurements contains high quality topographic and deformation information

Correlation

- We can calculate the correlation when we generate the multi-looked interferogram, according to the following definition:

$$\hat{\gamma} = \frac{|\langle s_1 s_2^* \rangle|}{\sqrt{\langle s_1 s_1^* \rangle \langle s_2 s_2^* \rangle}}$$
$$\rightarrow \frac{|\sum_{mn} s_1(\rho_{mn}, x_{mn}) s_2^*(\rho_{mn}, x_{mn})|}{\sqrt{\sum_{mn} s_1(\rho_{mn}, x_{mn}) s_1^*(\rho_{mn}, x_{mn}) \sum_{mn} s_2(\rho_{mn}, x_{mn}) s_2^*(\rho_{mn}, x_{mn})}}$$

An example



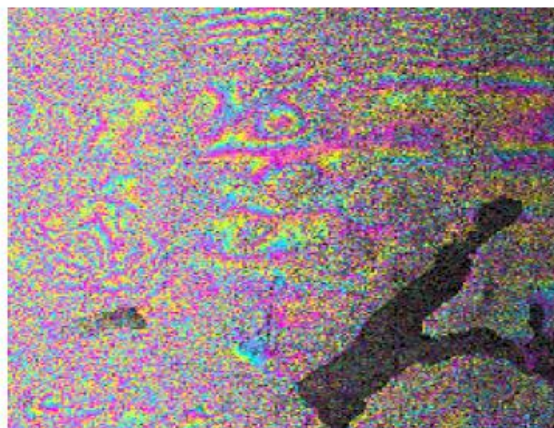
Total correlation

- The total correlation is the product of the individual correlation components:

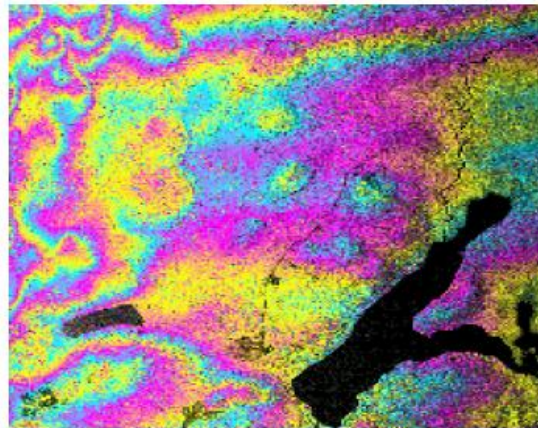
$$\rho_{total} = \rho_{thermal} \cdot \rho_{spatial} \cdot \rho_{temporal}$$

where $\rho_{thermal}$ represents electronic changes inside the radar system, $\rho_{spatial}$ referred to a change in sensor location (including rotation), $\rho_{temporal}$ represents decorrelation from a change in the surface between observations.

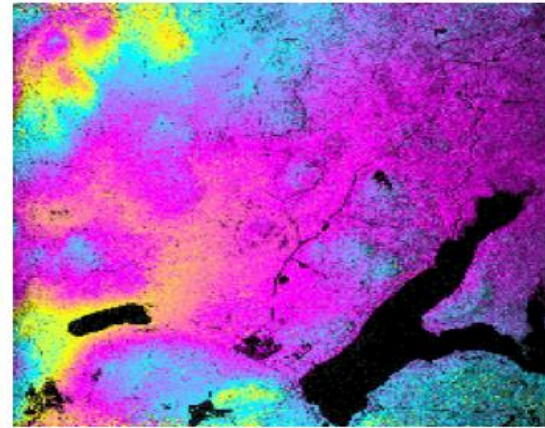
Interferograms



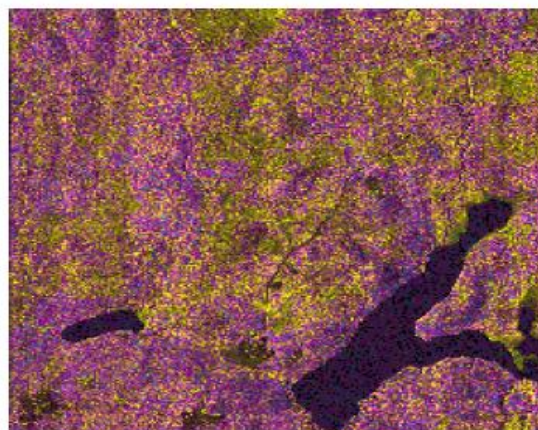
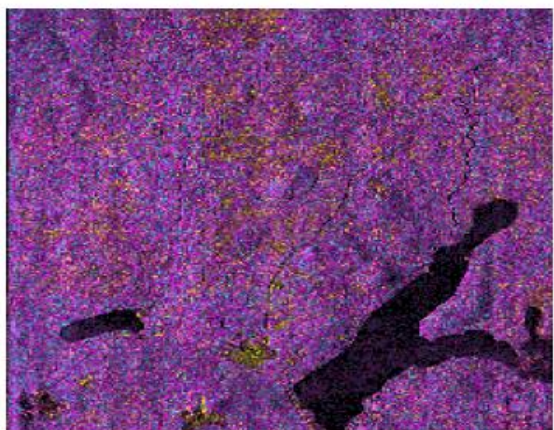
C-band



L-band



P-band



Correlation

