MACHINE LEARNING FOR COMPUTATIONAL FINANCE ASSIGNMENT 2

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Problem 1: Calculate prox operator

Recall that

$$\operatorname{prox}_{\alpha f}(z) = \arg\min_{x} \frac{1}{2\alpha} ||x - z||^2 + f(x)$$
 (0.1)

Suppose f is convex and $\alpha > 0$.

(1) Show $\operatorname{prox}_{\alpha f}$ is a single-valued mapping (i.e. there's a unique solution to (0.1)).

Solution: Let $h_z(x) = \frac{1}{2\alpha} ||x - z||^2 + f(x)$. We wish to find $\arg\min_x h_z(x)$. Note that $h_z(x)$ being sum of two convex functions is itself convex, ($||.||^2$ is strongly convex while f is assumed to be convex.) Moreover, the function $\frac{1}{2\alpha} ||x - z||^2$ is strictly convex (essentially because any norm coming from an inner product is strictly convex) and hence h_z is strictly convex. We know that a (non-constant) strictly convex function has atmost one global minimizer. Clearly, h_z is non-constant and convex and hence has at most one global minimizer.

Moreover, h_z is also coercive (and continuous) and hence has at least one global minimizer. (See Definition 1.1 and Theorem 1.3 in [1]). h_z is coercive since it is the sum of a strongly convex function and a covex function. A strongly convex function has a quadratic lower bound. If a convex function has a lower bound, then the sum of a strongly convex function and a convex function must shoot off to ∞ as $||x|| \to \infty$ thereby showing that the sum is coercive. If the convex function does not have a lower bound, then it must shoot off to $-\infty$ but it cannot have a faster than linear growth while doing so. In either case, the strongly convex part will *dominate* and h_z will shoot off to $+\infty$ as $||x|| \to \infty$. Thus h_z has a unique global minimizer thereby proving that $\max_{\alpha f} |x| \to \infty$ as single-valued mapping.

(2) Compute $\operatorname{prox}_{\alpha f}$, for $f(x) = \beta ||x||_1 + (1 - \beta) ||x||_2^2$.

Solution: Let $h_z = \frac{1}{2\alpha} \|x - z\|^2 + \beta \|x\|_1 + (1 - \beta) \|x\|_2^2$. Note that $h_z(x) = \sum_{i=1}^n \frac{1}{2\alpha} \|x_i - z_i\|^2 + \beta \|x_i\|_1 + (1 - \beta) \|x_i\|_2^2$. Since h_z is sum of n one variable 'independent' functions, minimizing h_z is equivalent to minimizing $h_z^i = \frac{1}{2\alpha} \|x_i - z_i\|^2 + \beta \|x_i\|_1 + (1 - \beta) \|x_i\|_2^2$ for each i = 1, 2, ..., n.

Cnsider now the problem of minimizing the one variable function $g_z(x) = \frac{1}{2\alpha} ||x - z||^2 + \beta ||x||_1 + (1 - \beta) ||x||_2^2$.

Case 1: Assume that the minimizer x > 0.

In this case, $g_z(x) = \frac{1}{2\alpha} ||x - z||^2 + \beta x_1 + (1 - \beta) x_2^2$. g is minimized when $x = \frac{z - \alpha \beta}{1 + 2\alpha(1 - \beta)}$. Since x is assumed to be positive, this forces $z > \alpha \beta$.

Case 2: Assume that the minimizer x < 0.

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Similar to case 1, we can show that g is minimized when $x = \frac{z + \alpha \beta}{1 + 2\alpha(1 - \beta)}$. Since x is assumed to be negative, this forces $z < -\alpha \beta$.

Case 3: Assume that the minimizer x = 0. Since prox is a well-defined mapping, this implies that x = 0 for all other values of z i.e when $|z| \le \alpha \beta$.

Combining everything together, we obtain

$$(\operatorname{prox}_{\alpha f}(z))_{i} = \begin{cases} \frac{z_{i} - \alpha \beta}{1 + 2\alpha(1 - \beta)}, & \text{when } z_{i} > \alpha \beta \\ \frac{z_{i} + \alpha \beta}{1 + 2\alpha(1 - \beta)}, & \text{when } z_{i} < -\alpha \beta \\ 0 & \text{when } |z_{i}| \leq \alpha \beta \end{cases}$$

(3) Compute $\operatorname{prox}_{\alpha f}$, for $f(x) = ||x||_2$. (no square)

Solution: Let $h_z(x) = \frac{1}{2\alpha} \|x - z\|^2 + \|x\|$. Assume that the minimizer x is such that $\|x\| > 0$. In this case, h_z becomes a differentiable function of x. Setting the gradient of h_z to 0 gives us $x = z \frac{\|x\|}{\alpha + \|x\|}$. This implies that $\|z\| = \|x\| + \alpha$. Since we have assumed that $\|x\| > 0$, this forces $\|z\| > \alpha$.

And for the other possibility (viz $||z|| \le \alpha$, we obtain ||x|| = 0 i.e x = 0.) Hence

$$\operatorname{prox}_{\alpha f}(z) = \begin{cases} z \left(1 - \frac{\alpha}{\|z\|} \right) \text{ when } \|z\| > \alpha \\ 0 \text{ when } \|z\| \le \alpha \end{cases}$$

(4) Compute $\operatorname{prox}_{\alpha f}$, for $f(x) = ||x||_2^2 + \delta_{\mathbb{R}_+^n}(x)$, where

$$\delta_{\mathbb{R}^n_+}(x) = \sum_{i=1}^n \begin{cases} 0, & x_i \ge 0 \\ \infty, & x_i < 0 \end{cases}.$$

Proof. Solution: Let $h_z(x) = \frac{1}{2\alpha} \|x - z\|^2 + \|x\|_2^2 + \delta_{\mathbb{R}^n_+}(x)$. The minimizer for this function, first of all exists (by part (1)) and cannot possibly be outside the first octant since outside the first octant, h_z is ∞ . We can thus recast the minimization problem as $\arg\min_{x \in \delta_{\mathbb{R}^n_+}} \frac{1}{2\alpha} \|x - z\|^2 + \|x\|_2^2$.

By the seperability of $\frac{1}{2\alpha}\|x-z\|^2 + \|x\|_2^2$ and $\delta_{\mathbb{R}^n_+}$, the minimization can be thought of as n separate independent minimizations of the form $\arg\min_{x\in\delta_{\mathbb{R}_+}}\frac{1}{2\alpha}|x-z|^2 + |x|_2^2$. Let us now concentrate on the one variable minimization $\arg\min_{x\in\delta_{\mathbb{R}_+}}\frac{1}{2\alpha}|x-z|^2 + |x|_2^2$.

If $z \le 0$, then we can think of the minimization problem as finding the point $x \in \mathbb{R}_+$ for which the distance of z from \mathbb{R}_+ is minimum and also that |x| is minimum. Clearly, 0 is the desired candidate.

Now, assume that z > 0. In this case, there are two possible choices for the minimizer x. Either x > 0 or x = 0. (Since \mathbb{R}_+ is a closed set, we separate in to 2 cases to ensure that we can differentiate without worry.)

If x > 0, then the first derivative test implies that $x_{min} = \frac{z}{1+2\alpha}$ and this is our candidate for the minimizer. (x = 0 cannot be a minimizer since the value of $\frac{1}{2\alpha}|x-z|^2 + |x|_2^2$ at 0 is bigger than the value at x_{min} .)

Combining everything together, we obtain

$$(\operatorname{prox}_{\alpha f}(z))_i = \begin{cases} \frac{z_i}{1+2\alpha}, & \text{when } z_i > 0\\ 0 & \text{when } z_i \le 0 \end{cases}$$

Problem 2: Bias-Variance Decomposition

We know that generalized error could be decomposed into irreducible error, error from bias, and error from variance, using linear regression as a specific example. Consider more general setting:

- $\{y_i, a_i\}_{i=1}^m$ is the training data
- · the model is

$$y_i = f(a_i) + \epsilon_i, \quad i = 1, ..., m$$

where ϵ_i are i.i.d. random variables with mean 0 and variance σ_ϵ^2 .

- f is the true data generating mechanism, and \hat{f} is the estimated model.
- $\{y_0, a_0\}$ is a test data point, which also satisfies

$$y_0 = f(a_0) + \epsilon_0.$$

Based on this information show that,

$$\operatorname{Err}_{a_0} = \mathbb{E}\left[\left(y_0 - \hat{f}(a_0)\right)^2\right]$$
$$= \sigma_{\epsilon}^2 + \left(\mathbb{E}\left[\hat{f}(a_0)\right] - f(a_0)\right)^2 + \mathbb{E}\left[\hat{f}(a_0) - \mathbb{E}\left[\hat{f}(a_0)\right]\right]^2$$

Proof. Let us denote $\mathbb{E}\left[\hat{f}(a_0)\right] = c$. Then

$$\left(\mathbb{E}\left[\hat{f}(a_{0})\right] - f(a_{0})\right)^{2} + \mathbb{E}\left[\hat{f}(a_{0}) - \mathbb{E}\left[\hat{f}(a_{0})\right]\right]^{2} = (c - f(a_{0}))^{2} + \mathbb{E}\left[\hat{f}(a_{0}) - c\right]^{2} \\
= c^{2} + f^{2}(a_{0}) - 2cf(a_{0}) + \mathbb{E}\left[\hat{f}(a_{0})^{2}\right] + c^{2} - 2c\mathbb{E}\left[\hat{f}(a_{0})\right] \\
= f^{2}(a_{0}) - 2\mathbb{E}\left[\hat{f}(a_{0})\right]f(a_{0}) + \mathbb{E}\left[\hat{f}(a_{0})^{2}\right]\left(\text{since }\mathbb{E}\left[\hat{f}(a_{0})\right] = c\right) \\
= \mathbb{E}\left[\left(f(a_{0}) - \hat{f}(a_{0})\right)^{2}\right] \tag{0.2}$$

Hence,

$$\operatorname{Err}_{a_{0}} = \mathbb{E}\left[\left(y_{0} - \hat{f}(a_{0})\right)^{2}\right] = \mathbb{E}\left[\left(y_{0} - f(a_{0}) + f(a_{0}) - \hat{f}(a_{0})\right)^{2}\right]$$

$$= \mathbb{E}\left[\left(y_{0} - f(a_{0})\right)^{2} + \left(f(a_{0}) - \hat{f}(a_{0})\right)^{2} - 2\sigma_{\epsilon}\left(f(a_{0}) - \hat{f}(a_{0})\right)\right]$$

$$= \mathbb{E}\left[\epsilon_{0}^{2} + \left(f(a_{0}) - \hat{f}(a_{0})\right)^{2} - 2\epsilon_{0}\left(f(a_{0}) - \hat{f}(a_{0})\right)\right]$$

$$(0.3)$$

Using (0.2), (0.3), $\mathbb{E}(\epsilon_0^2) = Var(\epsilon_0) = \sigma_{\epsilon}^2$ and the fact that $\mathbb{E}(\epsilon_0) = 0$ and that ϵ_0 and $\hat{f}(a_0)$ are independent random variables (there cannot be any dependence between the model error and the measurement error), we obtain the desired equality.

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Thus the prediction error is composed of the irreducible error (the first term), the bias error (the second term) and the variance error (the third term).

Problem 3: Newton's Method Consider logistic regression problem,

$$\min_{x} f(x) := \sum_{i=1}^{m} \left\{ \log(1 + \exp(\langle a_i, x \rangle)) - b_i \langle a_i, x \rangle \right\} + \frac{\lambda}{2} \|x\|_2^2$$

(1) What is the Hessian of this objective, $\nabla^2 f(x)$?

Proof. Let $A = [a_{ij}]_{m \times n}$. Note that, $\frac{\partial f}{\partial x_j} = \sum_{i=1}^m \left[\frac{a_{ij}}{1 + e^{-\langle a_i, x \rangle}} - b_i a_{ij} \right] + \lambda x_j$. Let $p_i = \frac{1}{1 + e^{-\langle a_i, x \rangle}}$, the probability vector. We can thus rewrite $\nabla f(x) = A^T(p-b) + \lambda x$.

Note that $\frac{\partial p_i}{\partial x_j} = a_{ij}p_i(1-p_i)$. This combined with the form of $\nabla f(x)$ implies that $\nabla f^2(x) = A^TDA + \lambda I_{n\times n}$ where D is the $m\times m$ diagonal matrix with the jth entry $= p_i(1-p_i)$.

(2) Implement Newton's method in **Jupyter Notebook**. Use the validation dataset to select λ . Report your best test error.

Proof. See the accompanying Jupyter notebook. We get the best test log loss as 0.69642675615051364 for $\lambda = 0.037$.

Problem 4: FISTA Using the data set from **Problem 3**, pick your favorite penalty g(x) (not limited by the ones we saw on class) and solve logistic regression problem,

(1) What is your g? Calculate $\operatorname{prox}_{\alpha g}$ based the g you provide. Implement the FISTA algorithm in **Jupyter Notebook**, and use validation to select the best λ .

Proof. We choose 3 different g and compare their performace.

(1)
$$g(x) = t||x||_1 + (1-t)||x||^2; 0 \le t \le 1.$$

For this g, we ran FISTA over a grid of values of t and λ and obtained the following best test log loss.

(i) $t \in [0, 1]$ (30 values, equally spaced) and $\lambda \in [0.01, 0.001]$ (21 values equally spaced).

The best test log loss is 0.69572123490420545 for t = 0.13793103448275862 and $\lambda = 0.00235$.

- (ii) $t \in [0, 1]$ (30 values, equally spaced) and $\lambda \in [0.1, 0.001]$ (100 values equally spaced). This is very expensive computationally. I timed this in Python and this takes about 722 seconds. The best test log loss is still 0.69572123490420545 and occurs for t = 0.27586206896551724 and $\lambda = 0.03$.
- (2) $g(x) = ||x||_2$.

For this g, we ran FISTA over a grid of values of λ ; $\lambda \in [0.01, 0.001]$ (100 equally spaced values) and obtained a best test log loss of 0.71515597021017085. This is not promising. Let us look for 'smoother and more robust' penalities.

(3) $g(x) = \rho_c(x)$, where ρ_c is the Huber function with parameter c.

Computing the prox for Huber penalty is simple as it is decomposes in to n one variable optimizations where n is such that $x \in \mathbb{R}^n$.

Assume for the time being that n = 1. We split up in to 3 mutually exclusive and exhaustive cases. Either $x_0 = \arg\min_x \frac{1}{2\alpha} \|x - z\|^2 + \rho_c(x)$ is such that $|x_0| \le c$ or $x_0 > c$ or $x_0 < -c$. In each of these cases, we can differentiate with respect to x and compute the following expression for x_0 :

$$x_0 = \begin{cases} \frac{z}{1+\alpha}, & \text{when } |z| < c(1+\alpha) \\ z - c\alpha, & \text{when } z > c(1+\alpha) \\ z + c\alpha & \text{when } z < -c(1+\alpha) \end{cases}$$

We can combine everything together and obtain the following expression for prox for ρ_c .

$$(\operatorname{prox}_{\alpha \rho_c}(z))_i = \begin{cases} \frac{z_i}{1+\alpha}, & \text{when } |z_i| < c(1+\alpha) \\ z_i - c\alpha, & \text{when } z_i > c(1+\alpha) \\ z_i + c\alpha & \text{when } z_i < -c(1+\alpha) \end{cases}$$

We choose a large value of c (c = 40). (Choosing a small value of c implies we are essentially computing the prox for 1 norm, which we saw earlier leads to a large log loss. A large value of c implies that we are essentially computing the prox for 2 norm square.) We choose a grid of λ values ($\lambda \in [0.01, 0.001]$, 21 equally spaces points) and compute the test log loss for Huber penalty with c = 40 to obtain the best test log loss as 0.69642737105302122. (This is almost the same as that for 2 norm penalty, which is to be expected since c is large, implying that we mostly compute the prox for 2 norm square.)

Note that we are not actually achieving a good log loss by using logistic regression for this particular data set. For instance, instead of doing the minimization, if we just set the x to be always 0, then the log loss for this x will be $\log(2)$ which is slightly better than the best log loss we obtained using Huber, elastic net, and $||x||_2$ penalty.

REFERENCES

[1] https://sites.math.washington.edu/ burke/crs/408/notes/nlp/unoc.pdf