

MACHINE LEARNING FOR COMPUTATIONAL FINANCE

ASSIGNMENT 3

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Problem 1: Matrix Norms

Consider any full rank matrix $A \in \mathbb{R}^{m \times n}$ (assume $m > n$), with SVD,

$$A = U\Sigma V^T,$$

where $U \in \mathbb{R}^{m \times n}$, $V \in \mathbb{R}^{n \times n}$ and $\Sigma \in \mathbb{R}^{n \times n}$ is a diagonal matrix with positive entries. $\text{diag}(\Sigma) = [\sigma_1, \dots, \sigma_n]^T \triangleq \sigma(A)$, and $\sigma_1 \geq \dots \geq \sigma_n \geq 0$. Here are some useful properties,

- $\|A\|_F^2 = \text{trace}(A^T A)$.
- $\text{trace}(AB) = \text{trace}(BA)$.
- $\|A\|_2 = \sup_{\|x\|_2 \leq 1} \|Ax\|_2 = \sup_{\|x\|_2=1} \|Ax\|_2$.

Show the following result:

$$(1) \|A\|_F^2 = \|\sigma(A)\|_2^2 = \sum_{i=1}^n \sigma_i^2.$$

Solution: By the first property listed above, $\|A\|_F^2 = \text{trace}(A^T A)$. Since $A = U\Sigma V^T$, $\text{trace}(A^T A) = \text{trace}(V\Sigma^2 V^T)$. By the second property listed above, $\text{trace}(V\Sigma^2 V^T) = \text{trace}(V V^T \Sigma^2) = \text{trace}(\Sigma^2)$.

Note that $\text{trace}(\Sigma^2) = \sum_{i=1}^n \sigma_i^2$. And since $\|\sigma(A)\|_2^2 = \sum_{i=1}^n \sigma_i^2$, it follows that

$$\|A\|_F^2 = \|\sigma(A)\|_2^2 = \sum_{i=1}^n \sigma_i^2. \quad \blacksquare$$

$$(2) \|A\|_2 = \|\sigma(A)\|_\infty = \sigma_1.$$

Solution: We first note that for any vector $y \in \mathbb{R}^n$, if $U \in \mathbb{R}^{m \times n}$ is such that U has orthonormal columns, then $\|Uy\|_2 = \|y\|_2$. Hence for any vector $x \in \mathbb{R}^n$, if the SVD of $A = U\Sigma V^T$, then $\|Ax\|_2 = \|U\Sigma V^T x\|_2 = \|\Sigma V^T x\|_2$. (The assumption that U has orthonormal columns is indeed justified since $m > n$ and we are looking at the reduced SVD.)

Next, note that $\|x\|_2 = 1$ iff $\|V^T x\|_2 = 1$. Hence,

$$\|A\|_2 = \sup_{\|x\|_2=1} \|Ax\|_2 = \sup_{\|x\|_2=1} \|\Sigma V^T x\|_2 = \sup_{\|V^T x\|_2=1} \|\Sigma V^T x\|_2 = \sup_{\|y\|_2=1} \|\Sigma y\|_2.$$

Since Σ is a diagonal matrix with positive entries, $\|\Sigma\|_2 = \sigma_1$ (the largest singular value of A). Moreover, it is clear that $\sigma_1 = \|\sigma(A)\|_\infty$ and hence $\|A\|_2 = \|\sigma(A)\|_\infty = \sigma_1$. \blacksquare

$$(3) \|A\|_* = \text{trace}(\sqrt{A^T A}) = \|\sigma(A)\|_1 = \sum_{i=1}^n \sigma_i, \text{ where } \sqrt{A^T A} \text{ denotes any symmetric positive semidefinite matrix } B \text{ such that } B^2 = A^T A.$$

Solution: Since $A = U\Sigma V^T$, $A^T A = V\Sigma^2 V^T$. If we define $B = V\Sigma V^T$, then $B^2 = A^T A$. (Since the choice of such a V in the singular value decomposition is not unique, the

choice of B is also not unique.) $\|A\|_* = \text{trace}(\sqrt{A^T A}) = \text{trace}(B) = \text{trace}(V\Sigma V^T) = \text{trace}(V V^T \Sigma) = \text{trace}(\Sigma)$. (The second to last equality follows since $\text{trace}(XY) = \text{trace}(YX)$.)

Clearly, $\text{trace}(\Sigma) = \sum_{i=1}^n \sigma_i = \|\sigma(A)\|_1$. ■

Problem 2: Low Rank Matrix Factorization (Convex)

Consider optimization problem,

$$\min_X \frac{1}{2} \|R - X\|_F^2 + \lambda \|X\|_*$$

Denote $f(X) = \frac{1}{2} \|R - X\|_F^2$ and $g(X) = \lambda \|X\|_*$.

- (1) Calculate $\nabla f(X)$. Is f a β -smooth function? If it is what is the β ?

Solution: By Question 1 above, $\frac{1}{2} \|R - X\|_F^2 = \text{trace}((R - X^T)(R - X))$.

Before we proceed, let us collect two facts without proof.

Fact 1:

$$\nabla_X \text{trace}(AXB) = A^T B^T$$

Fact 2:

$$\nabla_X \text{trace}(AX^T B) = BA$$

Hence,

$$\begin{aligned} \nabla f(X) &= \frac{1}{2} \nabla_X (\text{trace}(RR^T) - \text{trace}(RX^T) - \text{trace}(XR^T) - \text{trace}(XX^T)) \\ &= X - R \text{ (Using Fact 1 and Fact 2)} \end{aligned}$$

Clearly, $\nabla^2 f(X) = I$ and thus F is a β -smooth function with $\beta = \|\nabla^2 f\|_2 = \|I\|_2 = 1$. ■

- (2) What is $\text{prox}_{\alpha g}(Z)$?

Proof. $\text{prox}_{\alpha g}(Z) = \text{argmin}_U (\lambda \|U\|_* + \frac{1}{2\alpha} \|U - Z\|_F^2) = \text{argmin}_U (\|U\|_* + \frac{1}{2\alpha\lambda} \|U - Z\|_F^2)$.

To solve this, take the singular value decomposition, $Z = U\sigma(Z)V^T$ and apply soft-thresholding to the singular values (Theorem 2.1 in [1]) to get $\text{prox}_{\alpha g}(Z) = U\hat{\Sigma}V^T$, where $\hat{\Sigma}$ is a $n \times n$ diagonal matrix with i th diagonal entry equal to $\hat{\sigma}_i$ where

$$\hat{\sigma}_i = \begin{cases} \sigma_i - \lambda\alpha, & \text{when } \sigma_i > \alpha\lambda \\ 0 & \text{otherwise} \end{cases}$$

Here σ_i denotes the i th singular value of A . ■

- (3) Implement proximal gradient descent in **Jupyter Notebook** to solve the problem. For given λ report the rank k of optimal solution X_* .

Solution: See the accompanying Jupyter notebook for the code. For the given value of $\lambda = 30$, we obtain the rank of the optimal solution to be 29. ■

(4) Based on the rank we find above, what is the solution of the following problem,

$$\min_X \frac{1}{2} \|R - X\|_F^2, \quad \text{s.t. rank}(X) = k,$$

which we denote as X_k .

Proof. Let u_i denote the i th column of U and let v_i denote the i th column of V where U and V are such that $A = U\Sigma V^T$ (SVD of A .) It is well known that we can write A as a sum of rank 1 matrices of the form $A = \sum_{i=1}^n \sigma_i u_i v_i^T$.

Let us define $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$. It is clear that A_k has rank k . We claim that among all matrices B of rank at most k ,

$$\|A - A_k\|_F \leq \|A - B\|_F.$$

Let us prove this claim. Assume B minimizes $\|A - B\|_F^2$ among all matrices of rank at most k . Let V be the vector space spanned by the rows of B . The dimension of V is at most k . Since B minimizes $\|A - B\|_F^2$, it must be that each row of B is the projection of corresponding row of A onto V . If not, replace each row of B with the projection of the corresponding row of A onto V . This will not change V and thus the rank of B but it reduces $\|A - B\|_F^2$. Since each row of B is the projection of the corresponding row of A , it follows that $\|A - B\|_F^2$ is the sum of squared distances of rows of A to V . Since A_k minimizes the sum of squared distance of rows of A to any k -dimensional subspace, it follows that $\|A - A_k\|_F \leq \|A - B\|_F$ and our claim is justified.

Hence $X_k = \sum_{i=1}^k \sigma_i u_i v_i^T$, where $R = U\Sigma V^T$. Moreover, $\frac{1}{2} \|X_k - R\|_F^2 = \sum_{i=k+1}^n \sigma_i^2$. ■

Problem 3: Low Rank Matrix Factorization (Nonconvex)

Consider the low rank variation of the low rank matrix factorization,

$$\min_{B,F} \frac{1}{2} \|R - BF\|_F^2, \quad \text{s.t. } B \in \mathbb{R}^{m \times k}, F \in \mathbb{R}^{k \times n}.$$

where k is the rank you obtain from **Problem 2** (3).

Denote $f(B, F) = \frac{1}{2} \|R - BF\|_F^2$.

(1) Calculate $\nabla_B f(B, F)$ and $\nabla_F f(B, F)$.

Solution: Using the facts we mentioned in Problem 2 and the characterization of the Frobenius norm in terms of trace,

$\|R - BF\|_F^2 = \text{trace}(RR^T) - \text{trace}(RF^T B^T) - \text{trace}(BFR^T) + \text{trace}(BFF^T B^T)$. Using the facts mentioned in **Problem 2**, we can conclude that

$$\nabla_B f(B, F) = (BF - R)F^T.$$

Notice that $\|\nabla_B^2 f(B, F)\|_2 = \|F^T F\|_2$. Appealing again to the facts mentioned in Problem 2 and characterization of the Frobenius norm in terms of trace,

$$\nabla_F f(B, F) = B^T (BF - R).$$

Notice that $\|\nabla_F^2 f(B, F)\|_2 = \|B^T B\|_2$. ■

(2) Implement PALM algorithm in **Jupyter Notebook** solve the problem.

Proof. The PALM algorithm is implemented in the accompanying Jupyter notebook. ■

- (3) Denote B_* and F_* the optimal solution you obtain from the algorithm, compare X_k with B_*F_* . Report $\|X_k - B_*F_*\|_F$.

Proof. It makes more sense to look at the percent change. We therefore compute the quantity $\frac{\|X_k - B_*F_*\|}{\|X_k\|}$ and it turns out that there is only about 6% change in the answers for the two algorithms. ■

Problem 4: Robust Risk Decomposition

Consider R as our return matrix. Sometimes due to accidental activity R will contain outliers. In order to eliminate this random effect when we do the risk decomposition, we need to use robust formulation,

$$\min_{B,F} \rho_\kappa(\bar{R} - BF), \quad \text{s.t. } B^\top B = I$$

where ρ_κ is the Huber penalty and \bar{R} is the centered return matrix.

Denote $f(B, F) = \rho_\kappa(\bar{R} - BF)$ and

$$g(B) = \delta(B \mid B^\top B = I) = \begin{cases} 0, & B^\top B = I \\ \infty, & B^\top B \neq I \end{cases}$$

- (1) What is $\nabla_B f(B, F)$ and $\nabla_F f(B, F)$?

Solution:

$$\begin{aligned} \nabla_B \rho_\kappa(\bar{R} - BF) &= \nabla_B \rho_\kappa(\bar{R} - IBF) \\ &= -I^\top \nabla \rho_\kappa(\bar{R} - IBF) F^\top \\ &= -\nabla \rho_\kappa(\bar{R} - BF) F^\top. \end{aligned}$$

Similarly,

$$\begin{aligned} \nabla_F \rho_\kappa(\bar{R} - BF) &= \nabla_F \rho_\kappa(\bar{R} - BFI) \\ &= -B^\top \nabla \rho_\kappa(\bar{R} - BFI) I^\top \\ &= -B^\top \nabla \rho_\kappa(\bar{R} - BF). \end{aligned}$$

- (2) What is $\text{prox}_{\alpha g}(Z)$? Hint: there is a closed form solution that uses the SVD. ■

Proof. Note that $\text{prox}_{\alpha g}(Z) = \arg\min_U \left(g(U) + \frac{1}{2\alpha} \|U - Z\|_F^2 \right) = \arg\min_{U: U^\top U = I} \left(\frac{1}{2\alpha} \|U - Z\|_F^2 \right)$. Consider the SVD of Z of the form $Z = U\Sigma V^\top$ where $U^\top U = VV^\top = I$. Finding the prox is now equivalent to finding the closest (in Frobenius norm) orthogonal matrix to Z .

Since the Frobenius norm, like the 2-norm) is unitary equivalent,

$$\|Z - Q\|_F = \|U\Sigma V^\top - Q\|_F = \|\Sigma - U^\top QV\|_F.$$

This is the same as saying that we want to minimize

$$\|\Sigma - Q\|_F.$$

over all orthogonal matrices Q . We have,

$$\begin{aligned}
 \|\Sigma - Q\|_F^2 &= \sum_k (\Sigma_{kk} - Q_{kk})^2 + \sum_{j \neq k} Q_{kj}^2 \\
 &= \sum_k (\Sigma_{kk}^2 + Q_{kk}^2 - 2\Sigma_{kk}Q_{kk}) + \sum_{j \neq k} Q_{kj}^2 \\
 &= \sum_k (\Sigma_{kk}^2 - 2\Sigma_{kk}Q_{kk}) + \sum_{j,k} Q_{kj}^2 \\
 &= \text{Tr}(\Sigma^2) + \text{Tr}(Q^T Q) - 2 \sum_k \Sigma_{kk}Q_{kk} \\
 &= \text{Tr}(\Sigma^2) + n - 2 \sum_k \Sigma_{kk}Q_{kk}
 \end{aligned}$$

To minimize this quantity over Q , since the entries of Σ are non-negative and $Q_{kk} \in [-1, 1]$, we need to choose $Q_{kk} = 1$ for all k , which makes $Q = I$ (Note that columns of Q are orthonormal and hence are unit Euclidean vectors. If any one component of a unit Euclidean vector is 1, then all other components are forced to be 0.) Hence the minimum is

$$\|\Sigma - I\|_F = \|U\Sigma V^T - UV^T\|_F = \|Z - UV^T\|_F.$$

(I learnt this argument from [2].) ■

- (3) Implement PALM algorithm in **Jupyter Notebook** over S&P 500 data.

See the accompanying Jupyter notebook for the code.

- (4) After obtaining the optimal solution B_* , F_* , calculate the SVD of $B_*F_* = U\Sigma V$ and report the first column of U which corresponding to the most risky portfolio.

REFERENCES

- [1] <https://arxiv.org/pdf/0810.3286.pdf>
 [2] <https://math.stackexchange.com/questions/2215359/showing-that-matrix-q-uv^t-is-the-nearest-orthogonal-matrix-to-a>