

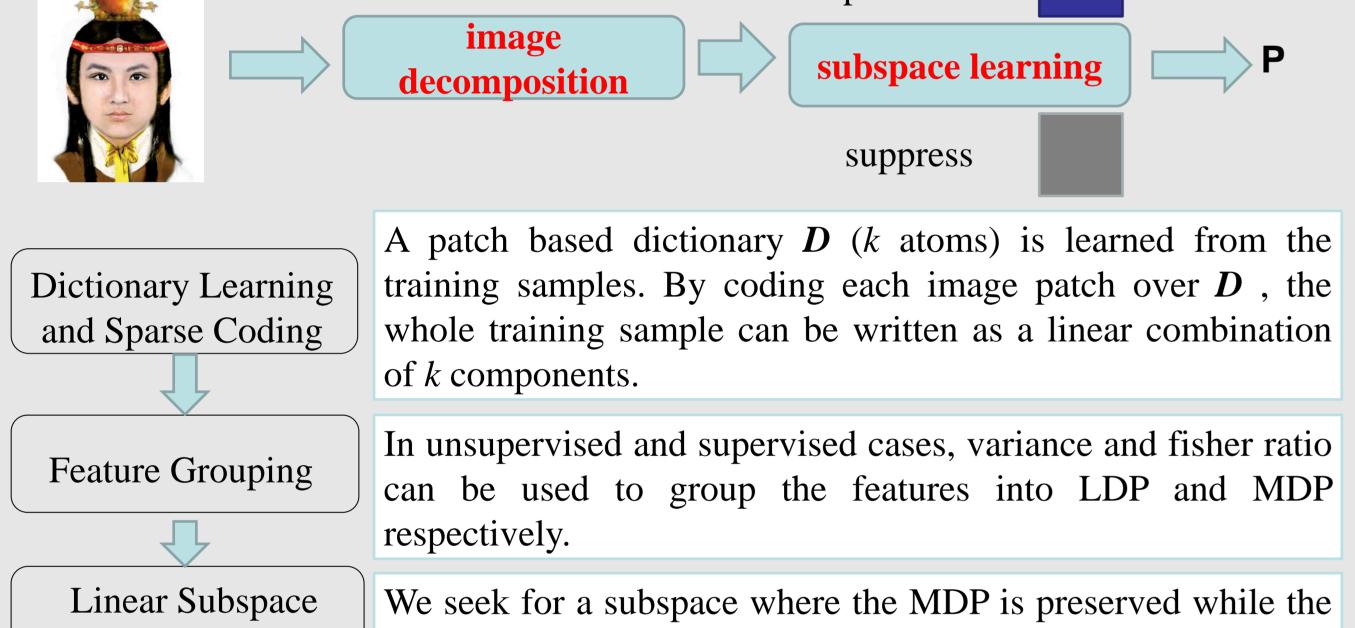
A Linear Subspace Learning Approach via Sparse Coding

Lei Zhang^a, Pengfei Zhu^a, Qinghua Hu^b and David Zhang^a ^aDept. of Computing, The Hong Kong Polytechnic University, Hong Kong, China ^bHarbin Institute of Technology, Harbin, China



cslzhang@comp.polyu.edu.hk

Motivation and flowchart Most of the existing LSL methods estimate sample scatter matrices directly from the original training samples. The subspace learning and image decomposition are accomplished simultaneously. subspace learning image decomposition intrinsic and stable features the noise and trivial structures Different contributions of different components to image recognition cannot be effectively exploited by the present methods. why don't we decompose the image first and then use the different image components to guide the subspace learning? preserve



Dictionary learning and sparse coding

Each training sample x_i is partitioned into q overlapped patches, and totally there are $h=m\times q$ patches. Suppose that the dimension of each patch vector t_i , $j=1,2,\ldots,h$, is l, then an $l \times h$ data matrix $T = [t_1, t_2, ..., t_h]$ is established. From T, we aim to learn a dictionary D $= [d_1, d_2, ..., d_k] \in \Re^{l \times k}$, where $d_z^T d_z = 1, z = 1, 2, ..., k$, such that

$$J_{D,A} = \operatorname{arg\,min}_{D,A} \left\{ \left\| T - DA \right\|_{F}^{2} + \lambda \left\| A \right\|_{1} \right\}$$

where $\Lambda = [\alpha_1, \alpha_2, ..., \alpha_h] \in \mathbb{R}^{k \times h}$ and α_i is the coding vector of t_i over D.

LDP is suppressed.

In learning the dictionary D, the sparse coding matrix Λ is computed simultaneously. For each patch t_i , we have

$$t_i \approx D\alpha_i = \alpha_i(1) \cdot d_1 + \alpha_i(2) \cdot d_2 + \dots + \alpha_i(k) \cdot d_k$$

That is, each patch can be written as the summation of *k* components

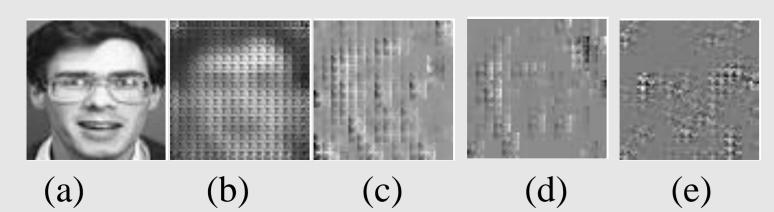
$$t_{j} \approx t_{j,1} + t_{j,2} + \ldots + t_{j,k}$$

where $\boldsymbol{t}_{i,z} = \boldsymbol{\alpha}_i(z) \cdot \boldsymbol{d}_z$.

Learning

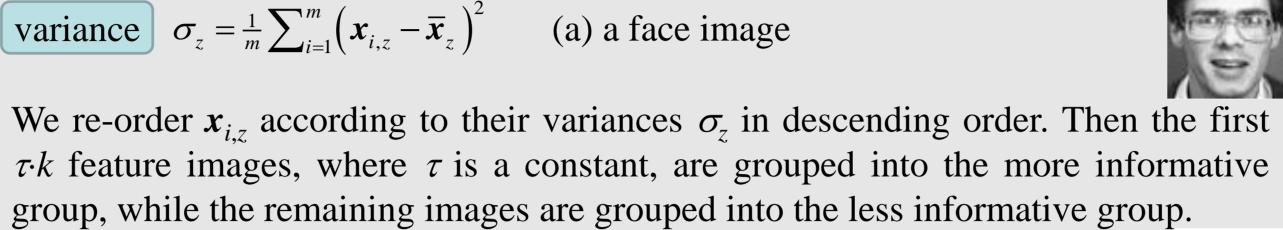
By combining all the patches, each image x_i can be written as the summation of k components:

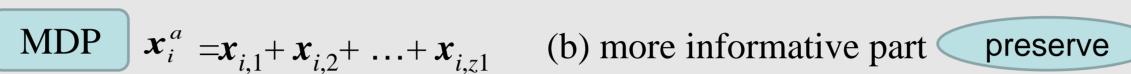
$$\boldsymbol{x}_i \approx \boldsymbol{x}_{i,1} + \boldsymbol{x}_{i,2} + \ldots + \boldsymbol{x}_{i,k}$$



(a) is the original face image; (b) \sim (e) show the decomposed components $x_{i,z}$ corresponding to the 1st, 11th, 21th, and 41th atoms.

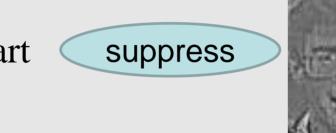
Unsupervisded subspace learning











 $E_a = \frac{1}{m} \sum_{i=1}^{m} \left\| \mathbf{P} \overline{\mathbf{x}}_i^a \right\|_2^2 = tr \left\{ \mathbf{P} \mathbf{S}_a \mathbf{P}^T \right\}$ average energy of $P\bar{x}_{i}^{a}$ $E_b = \frac{1}{m} \sum_{i=1}^{m} \left\| \mathbf{P} \overline{\mathbf{x}}_i^b \right\|_2^2 = tr \left\{ \mathbf{P} \mathbf{S}_b \mathbf{P}^T \right\}$ average energy of $P\bar{x}_{i}^{b}$ $J_{P} = \arg \max_{P} \frac{E_{a}}{E_{b}} = \arg \max_{P} \frac{tr(PS_{a}P^{T})}{tr(PS_{b}P^{T})}$ optimization objective $J_{P} = \arg \max_{P} tr(PS_{a}P^{T}) \text{ s.t. } PS_{b}P^{T} = I$ equivalent form

 $J_{P} = \arg \max_{P} tr(PSP^{T})$ s.t. $PSP^{T} = I$ PCA

The row vector of desired P can be chosen as the p generalized Solution eigenvectors $S_a w = \lambda S_b w$ corresponding to the first p largest eigenvalues

Supervised subspace learning

In supervised learning, the Fisher ratio can be utilized to evaluate features. If the feature $x_{i,\tau}$ has a bigger Fisher ratio, this feature is more discriminative to separate the samples.

Fisher ratio $f_z = \frac{\sigma_b}{\sigma_w} = \frac{\sum_{c=1}^C (\overline{x}_z - \overline{x}_{z,c})^2}{\sum_{c=1}^C \frac{1}{m_c} \sum_{x_i \in X_c} (x_{i,z} - \overline{x}_{z,c})^2}$





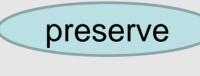
MDP within-class scatter matrices

 $S_W^a = \frac{1}{m} \sum_{c=1}^C \sum_{\boldsymbol{x}_i \in \boldsymbol{X}_c} (\boldsymbol{x}_i - \overline{\boldsymbol{x}}_c^a) (\boldsymbol{x}_i - \overline{\boldsymbol{x}}_c^a)^T$



MDP between-class scatter matrices

 $S_B^a = \frac{1}{m} \sum_{c=1}^C m_c \left(\overline{\boldsymbol{x}}_c^a - \overline{\boldsymbol{x}}^a \right) \left(\overline{\boldsymbol{x}}_c^a - \overline{\boldsymbol{x}}^a \right)^T$



LDP scatter matrix

 $S^{b} = \frac{1}{m} \sum_{c=1}^{C} \sum_{\boldsymbol{x}_{i} \in X_{c}} (\boldsymbol{x}_{i} - \overline{\boldsymbol{x}}^{b}) (\boldsymbol{x}_{i} - \overline{\boldsymbol{x}}^{b})^{T}$



optimization objective $J_{P} = \arg \max_{P} \frac{tr\{PS_{B}^{a}P^{T}\}}{tr\{P(\alpha S_{W}^{a} + (1-\alpha)S_{b})P^{T}\}}$

Equivalent form

 $J_{P} = \arg \max_{P} \frac{tr\{PS_{B}^{a}P^{T}\}}{\alpha \cdot tr\{PS_{W}^{a}P^{T}\} + (1-\alpha)tr\{PS_{B}P^{T}\}}$

Solution

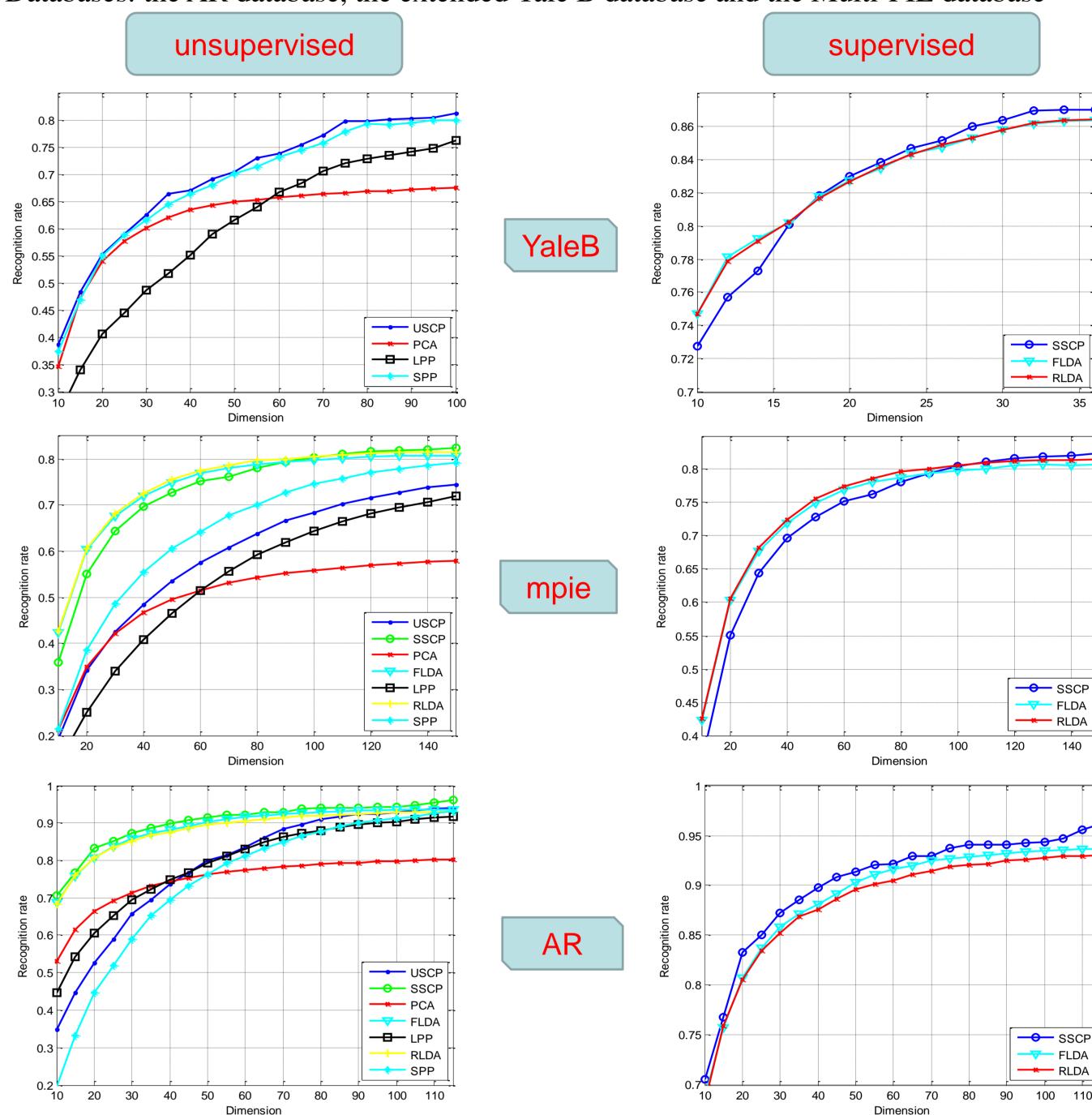
The row vector of desired P can be chosen as the p generalized eigenvectors $S_B^a w = \lambda [\alpha S_W^a + (1-\alpha)S_b] w$ corresponding to the first p largest eigenvalues.

FLDA

 $J_P = \arg\max_{P} \frac{tr\{PS_BP^T\}}{tr\{PS_bP^T\}}$ without applying sparse coding and feature grouping to the training images and let $\alpha=0$

Experimental result

Databases: the AR database, the extended Yale B database and the Multi-PIE database



method	Yale B	MPIE	AR
PCA	67.5 ± 17.2	57.9 ± 10.1	80.2 ± 13.6
	100	150	115
LLP	76.2 ± 16.6	71.9 ± 7.3	91.8 ± 3.5
	100	150	115
SSP	79.9 ± 17.7	79.2 ± 7.3	93.2 ± 2.8
	95	150	115
USCP	81.2 ± 16.8	74.5 ± 8.8	94.0 ± 4.4
	100	150	115
FLDA	86.3 ± 12.8	80.7 ± 8.8	93.7 ± 8.6
	36	130	115
RLDA	86.4 ± 12.9	81.5 ± 9.5	93.1 ± 9.2
	36	150	115
SSCP	87.0 ± 13.5	82.4±11.6	96.2±3.2
	36	150	115

Conclusion

In this paper, we proposed a novel linear subspace learning (LSL) method via sparse coding and feature grouping. Each training image can be decomposed as a linear combination of k components. These components were grouped into two parts: a more discriminative part (MDP) and a less discriminative part (LDP). Finally, a desired linear subspace was sought by preserving the MDP component while weakening the LDP component. The experimental results on benchmark face databases showed that the proposed sparse coding induced LSL methods outperform many representative and state-of-the-art LSI methods.