

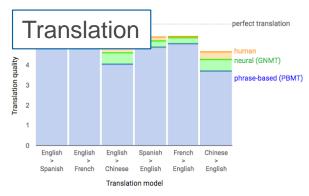
# A MINIMAL INTRODUCTION TO NEURAL NETWORKS

#### **LOGAN WARD**

Asst. Computational Scientists
Data Science and Learning Division



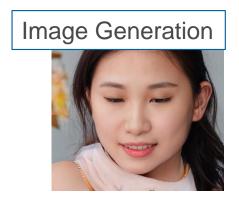
# NEURAL NETWORKS ARE VERY VERSATILE



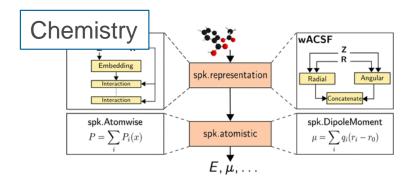
Source: Google Blog



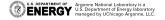
Source: OpenAI



Source: https://thispersondoesnotexist.com/



Source: Schutt et al. JCTC. (2019)





#### **GOALS FOR TODAY**

Get familiar enough to start using neural networks

Goal 1: Describe the three key components of neural networks

Goal 2: Train a neural network with TensorFlow

Goal 3: Understand why CNN are used for images





# CONCEPT OF NEURAL NETWORKS: ARCHITECTURE + LOSS FUNCTION + SOLVER





# AN OLD FRIEND: SIMPLE LINEAR REGRESSION

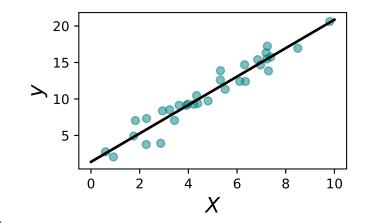
... but let's make it sound modern

**Model Architecture** 

$$f(x; m, b) = mx + b$$

**Training Data:** Inputs  $(x_i)$  and outputs  $(y_i)$ 

**Goal:** Determine m and b that minimize



**Loss Function** 

$$\sum_{i} (f(x_i; m, b) - y_i)^2$$

by computing

$$m = \text{Cov}[x, y] / Var[x]$$
$$b = \overline{y} - m\overline{x}$$

# SIMPLE LOGISTIC REGRESSION

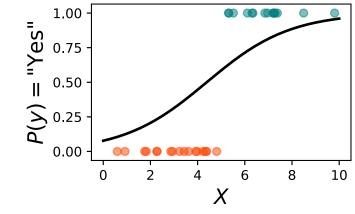
A version of Linear Regression suitable for classification

**Model Architecture** 

$$f(x; m, b) = \frac{1}{1+e^{-(mx+b)}}$$

**Training Data:** Inputs  $(x_i)$  and outputs  $(y_i)$ 

**Goal:** Determine m and b that minimize



**Loss Function** 

$$L(m,b) \sum_{i} y_{i} \ln(f(x_{i})) + (1-y_{i}) \ln(1-f(x_{i}))$$
"log loss"\*

by computing

**Optimizer** 

$$x_0 = (1, 0)$$
  
$$x_{n+1} = x_n + \gamma \nabla L(m, b)$$

Architecture + Loss + Optimizer = ML Algorithm For Regression *and* Classification



\*You will be seeing these again

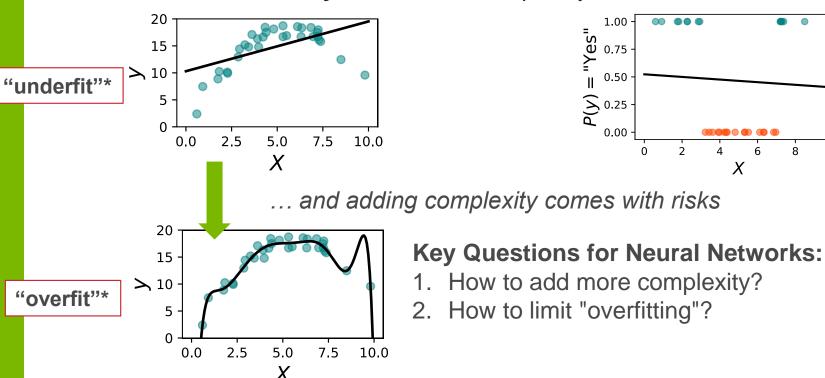


"gradient decent"\*

#### LINEAR MODELS ARE NOT SUFFICIENT

Otherwise, this would be a very short lecture

Why Not? Model complexity is limited



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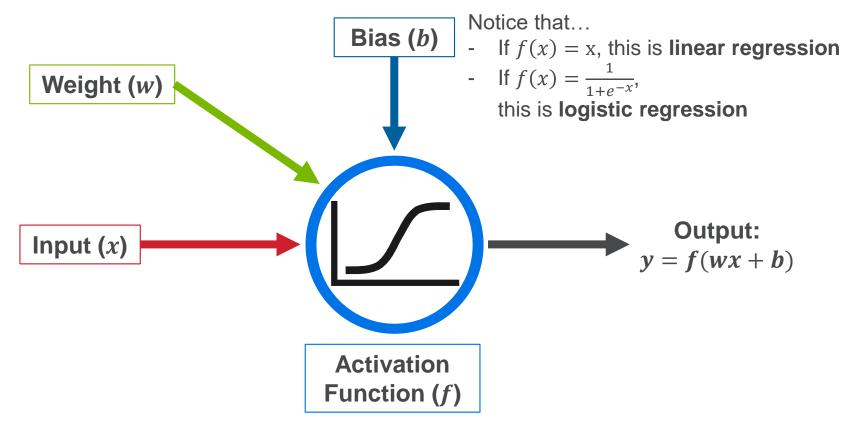
# NEURAL NETWORKS ARE COMPOSABLE, NON-LINEAR MODELS





#### **TODAY'S FOCUS: NEURAL NETWORKS**

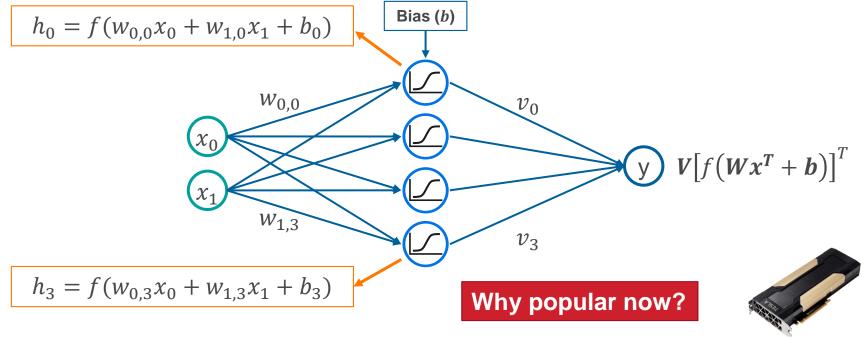
Build on a small building block: "The Perceptron"





#### MANY PERCEPTRONS = NEURAL NETWORK

Stack enough, and you get \*very\* complex functions



Many small operations
performed on many data

Massive Parallelism







#### **HOW DO I TRAIN A NEURAL NETWORK?**

Remember when I said "gradient decent"

#### **Key Terminology:**

Architecture: How inputs/outputs are linked, adjustable weights

Loss Function: Generates error between "current" and "desired" outputs

Optimizer: Algorithm for finding parameters that minimize a function

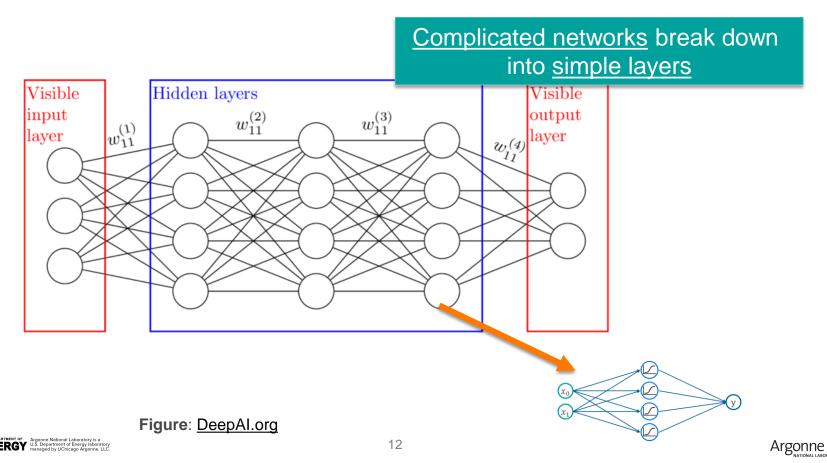
These are the three ingredients forming all\* neural networks





### **NETWORKS ARE COMPOSED OF LAYERS**

**Tensors in, different tensors out** 



#### **NETWORKS ARE COMPOSED OF LAYERS**

Tensors in, different tensors out

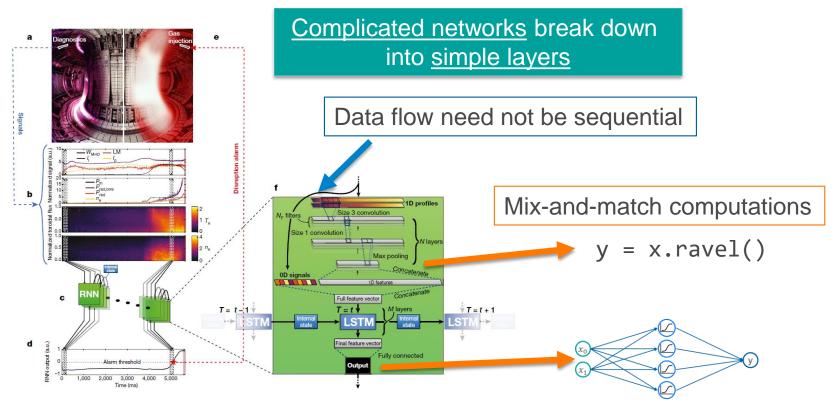


Figure: Keats-Harbeck et al. Nature. 2019





### LOSS FUNCTIONS: NOT JUST "LOG LOSS"

#### Express how "wrong" your network is as a differentiable function

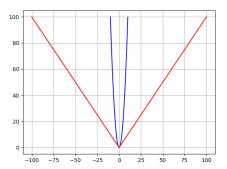


Figure: Towards Data Science

#### Regression:

Mean Absolute Error:  $L = \sum_i |\hat{y}_i - y_i|$ Mean Squared Error:  $L = \sum_i (\hat{y}_i - y_i)^2$ 

#### **Classification:**

**Accuracy:** Not differentiable!

Log Loss:  $L = \sum_{i} \sum_{c} (y_i = c) \log P(y_i = c)$ 

Only counts for the correct class

Bigger penalty if more wrong





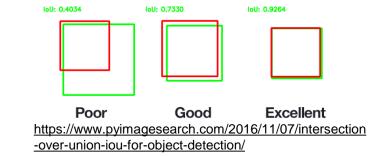
#### LOSS FUNCTIONS: NOT JUST "LOG LOSS"

Express how "wrong" your network is as a differentiable function

Mean Squared Error: Standard for regression problems

Huber Loss: Less outlier-sensitive than MSE

Jaccard Loss: Used for image bounding boxes



"KL" Divergence: Ensure outputs follow a desired distribution

Loss gives another tool to control training



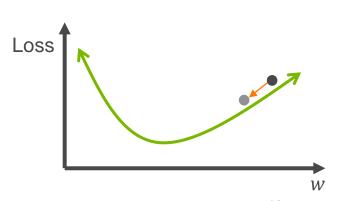


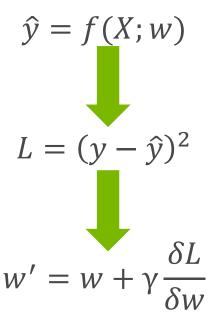
#### **HOW DO I TRAIN A NETWORK?**

#### **Short Answer: Gradually make the weights better**

#### Simple procedure:

- 1. Compute output
- 2. Compute "loss"
- 3. Compute how each weight affects loss (Uses "back propagation")
- 4. Adjust weights to lower loss (More complicated than you might think)
- 5. Repeat with new weights









#### THERE IS A RICH VARIETY IN NEURAL NETWORKS

#### **Optimizers, layers, and loss functions**



**Activation:** Applies function to an input

Batch Normalization: Make batch mean 0, std. 1

**Convolution:** Apply spatial/temporal filters

... Dense, Dropout, Embedding, ....

#### Loss Functions



**Log-loss:** Classification, same loss function as logistic regression

**Mean Absolute Error:** Regression, small penalty for outliers

**Mean Squared Error:** Regression, large penalty for outliers

... KL divergence, accuracy ...

# **Optimizers**



#### Many different techniques:

Momentum: Keep moving in direction of last step

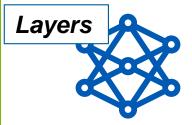
Decay: Gradually lower step size

Clipping: Prevent too large of gradient changes



#### THERE IS A RICH VARIETY IN NEURAL NETWORKS

**Optimizers, layers, and loss functions** 

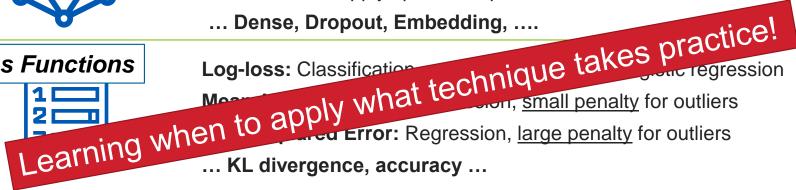


**Activation:** Applies function to an input

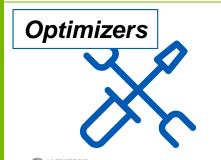
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#### Many different techniques:

Momentum: Keep moving in direction of last step

Decay: Gradually lower step size

Clipping: Prevent too large of gradient changes



#### **DNN EXERCISE: KEY SKILLS**

Learning how to make and train a model effectively with Keras

Open the <u>first exercise!</u>





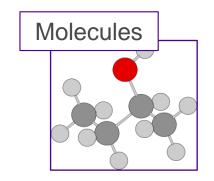




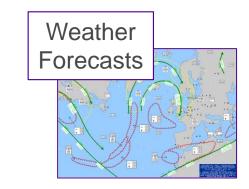


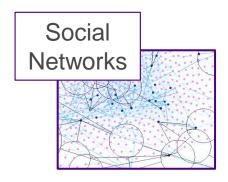
# **NOT ALL DATA ARE VECTORS**

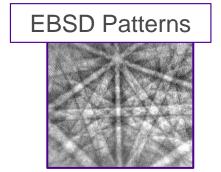
#### And that's OK!

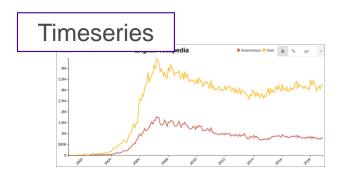










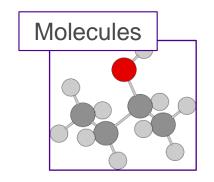






# **NOT ALL DATA ARE VECTORS**

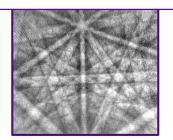
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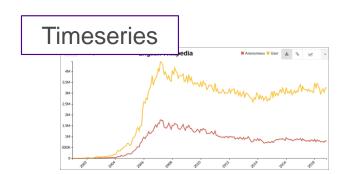






**Networks** 







# IMAGE CLASSIFICATION AND CONVOLUTIONS

Better classification by translation symmetry

**Example:** Classify Horizontal vs Vertical lines







**Initial Approach:** Just flatten the images. They are now vectors.







How do we know which are which? Adjacent blue blocks

Problem! Fully connected NNs don't care about order

Solution: Make new features that deal with order



# **CONVOLUTIONS, PADDING, AND POOLING**

Borrow from computer vision, graphics

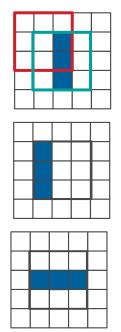
1. Pad Image

2. Convolve Filter

3. Maximum of Image ("Pooling")

Vertical Edge Filter:













Classification is easy



with filters!

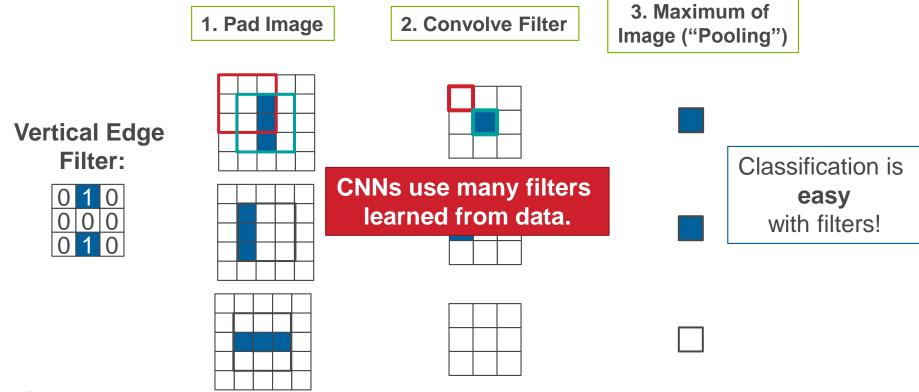






# **CONVOLUTIONS, PADDING, AND POOLING**

Borrow from computer vision, graphics







# **EXERCISE: DIGIT CLASSIFICATION**

It's a great tutorial example!

■ Let's do example #2





#### TAKE-HOME MESSAGES

#### 1. Neural Networks have three main components

- 1. Architecture: How the "perceptrons" are arranged
- 2. Loss Function: Measures difference between "actual" and "expected"
- 3. Optimizer: How network weights are adjusted to lower loss

#### 2. TensorFlow+Keras makes deep learning easy

- Compose layers to form network architectures
- Use callbacks to prevent overfitting
- Control batch size to improve efficiency

#### 3. Special data requires special networks

- General concept: Exploit symmetries / domain knowledge
- Special Example: Convolutions exploit translation symmetry and that "nearby" pixels/inputs are related





# EMAIL ME AT <u>LWARD@ANL.GOV</u> IF YOU HAVE QUESTIONS!



