

Last time

Lax-Milgram - abstract stability analysis

① Find $u \in V_h$ s.t. $V_h \subseteq V$
 $a(u, v) = L(v) \quad \forall v \in V_h$

- April 30th Last Day
- May 5-13 finals
- Plan projects now

ex Poisson
 $-\nabla^2 u = f$
 $u|_{\partial\Omega} = 0$

$$a(u, v) = \int \nabla u \cdot \nabla v \, dx, \quad L(v) = \int f v \, dx$$

Biharmonic Egn (Acoustics, phase field, Beam theory)

$$\rightarrow \nabla^2 \nabla^2 u = f$$

$$u|_{\partial\Omega} = \partial_n u|_{\partial\Omega} = 0$$

$$V = H^2(\Omega) = \left\{ \int (\nabla^2 u)^2 < \infty \right\}$$

$$a(u, v) = \int \nabla^2 u \cdot \nabla^2 v \, dx \quad L(v) = \int f v \, dx$$

Lax-Milgram

a is cont ① $|a(v, w)| \leq \gamma \|v\|_V \|w\|_V$

elliptic ② $a(v, v) \geq \alpha \|v\|_V^2$

\Rightarrow stability

L is cont ③ $|L(v)| \leq \Lambda \|v\|_V$

Cesàr Lemma

Suppose ① - ③. Then

$$\|u - u_n\|_V \leq \frac{\delta}{\alpha} \inf_{v \in V_h} \|u - v\|_V$$

Pf $u - u_n \in V$

$$a(u - u_n, v) = 0 \quad \forall v \in V_h$$

$$\begin{aligned} \alpha \|u - u_n\|_V^2 &\leq a(u - u_n, u - u_n) \\ &= a(u - u_n, u) - a(u - u_n, u_n) \\ &= a(u - u_n, u) - a(u - u_n, v) \quad \text{for any } v \\ &= a(u - u_n, u - v) \\ &\leq \delta \|u - u_n\|_V \|u - v\|_V \end{aligned}$$

$$\|u - u_n\|_V \leq \frac{\delta}{\alpha} \|u - v\|_V \quad \forall v \in V_h$$

Today we'll get some practice working through this abstract theory

We are free to choose the

- PDE
- FEM subspace
- Norm

Remember

$$L^2 \rightarrow \|f\|_{L^2}^2 = \int f^2 dx$$

H^1 -seminorm

$$|f|_{H^1} = \int |\nabla f|^2 dx$$

H^1 -norm

$$\|f\|_{H^1}^2 = \|f\|_{L^2}^2 + |f|_{H^1}^2$$

ex

$$a(u, v) = \int \nabla u \cdot \nabla v \, dx$$

$$L(v) = \int f v \, dx$$

Let $V = H_0^2(\Omega)$

← ~~twice differentiable~~ integrable 2nd derivs

$$(u, v)_V = \int \nabla^2 u : \nabla^2 v + \nabla u \cdot \nabla v + uv$$

where $A : B = \sum_{i,j} A_{ij} B_{ij}$ Frobenius inner prod.

Check conditions

① $|a(v, w)| = \left| \int \nabla v \cdot \nabla w \, dx \right|$
 $\leq \|\nabla v\|_* \|\nabla w\|_* \quad \text{C-S}$

$$\|f\| = \sqrt{\int f^2 dx}$$

$$\|v\|_V^2 = \int \nabla^2 v : \nabla^2 v + |\nabla v|^2 + v^2 \, dx$$

$$\geq \int |\nabla v|^2 \, dx = \|\nabla v\|_*^2$$

so $|a(v, w)| \leq \|v\|_V \|w\|_V$

②

$$a(u, v) = \|\nabla v\| \geq \alpha \int \nabla^2 v + |\nabla v|^2 + v^2 dx$$

~~Challeng.~~ Non-Trivial \rightarrow need a result from PDEs
called elliptic regularity

$$\text{For convex } \Omega, \|v\|_{H^2(\Omega)} \leq C \|\Delta v\|_{L^2(\Omega)} \\ \text{for } v \in H^2 \cap H_0^1$$

$$③ |L(v)| \leq \|f\|_{L^2} \|v\|_{L^2}$$

$$\leq \|f\|_{L^2} \|v\|_V \Rightarrow L = \|f\|_{L^2}$$

Reaction Diffusion eqn

$$-\nabla \cdot A \nabla u + \Gamma u = f$$

w/assumptions (A) A is pos def, $x^T A x > 0$

(B) $\Gamma \geq 0$

(C) $|A_{ij}| < \infty, |\Gamma| < \infty$ bounded

weak form

$$a(u, v) = L(v) \quad v \in H_0^1$$

$$a(u, v) = \int_{\Omega} \nabla u \cdot A \cdot \nabla v + \Gamma u v \, dx$$

$$L(v) = \int_{\Omega} f v \, dx$$

(1) show $|a(v, w)| \leq \delta \|v\|_{H_1} \|w\|_{H_1}$

$$\left| \int \nabla v \cdot A \cdot \nabla w \, dx \right| \leq \max_{i,j} |A_{ij}| \left| \int \nabla v \cdot \nabla w \, dx \right|$$

$$\leq \delta_A \|v\|_{H_1} \|w\|_{H_1}$$

$$\left| \int \Gamma v w \, dx \right| \leq \delta_{\Gamma} \|v\|_{H_1} \|w\|_{H_1}$$

$$\leq \max |\Gamma| \int v w \, dx$$

$$\leq \delta_{\Gamma} \|v\|_{L^2} \|w\|_{L^2}$$

$$a(v, w) \leq \delta_A \|v\|_{H_1} \|w\|_{H_1} + \delta_{\Gamma} \|v\|_{L^2} \|w\|_{L^2}$$

$$\leq 2 \max(\delta_A, \delta_{\Gamma}) \|v\|_{H_1} \|w\|_{H_1}$$

$$\textcircled{2} \quad a(u, u) \geq \alpha \|u\|_V^2$$

$$a(u, u) = \int \nabla u \cdot A \cdot \nabla u + \gamma u^2 \, dx$$

$$\geq \int \nabla u \cdot \nabla u + u^2 \, dx$$

by $\textcircled{A} + \textcircled{B}$

$$= \|u\|_{H_1}^2$$

Elasticity

- First example of how analysis predicts breakdown of stability

def $u \in \mathbb{R}^d$ - displacement
 $\varepsilon(u) \in \mathbb{R}^{d \times d}$ - strain

$$\varepsilon(u) = \frac{1}{2} (\nabla u + \nabla u^T)$$

$\sigma(\varepsilon)$ - stress

$$\sigma_{ij} = C_{ijkl} \varepsilon_{kl}$$

To enforce rotational invariance for isotropic materials

$$C_{ijkl} = \lambda \delta_{ij} \delta_{kl} + \mu (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk})$$

so the stress reduces to

$$\sigma_{ij} = \lambda \delta_{ij} \varepsilon_{kk} + 2\mu \varepsilon_{ij}$$

Aside For elasticity, we have the Lagrangian density

$$\mathcal{L} = -\frac{1}{2} \varepsilon^T C \varepsilon + \frac{\rho}{2} \partial_t u^2$$

Governing Eqs

$$\left\{ \begin{array}{l} -\operatorname{div} \sigma = f \\ \sigma = 2\mu \varepsilon + \lambda \operatorname{tr}(\varepsilon) I \\ u|_{\partial\Omega} = 0 \end{array} \right.$$

Note that $\text{tr}(\varepsilon) = \nabla \cdot u$

$$\begin{cases} -\nabla \cdot (2\mu \varepsilon(u) + \lambda \nabla \cdot u \mathbf{I}) = f \\ u|_{\partial\Omega} = 0 \end{cases}$$

To define variational problem, we'll work w/ displacements

$$\vec{u} \in \vec{H}_0^1(\Omega) = [H_0^1(\Omega)]^d \quad \text{aka } H_0^1 \text{ in each component} \quad (\text{lots of other choices})$$

$$\textcircled{V} \Rightarrow a(u, v) = (f, v)$$

$$a(u, v) = \int \mu \varepsilon(u) : \varepsilon(v) + \lambda (\nabla \cdot u)(\nabla \cdot v) dx$$

Again, we'll check continuity and ellipticity of a ,
but write

$$\lambda = \frac{2\mu \delta}{1 - 4\delta} \quad \text{where } \delta \text{ is the Poisson ratio}$$
$$\delta = - \frac{\varepsilon_{transverse}}{\varepsilon_{axial}}$$

For near-incompressible materials, as $\delta \rightarrow \frac{1}{2}$, $\lambda \rightarrow \infty$

So we'd like to understand the $\lambda \rightarrow \infty$ limiting stability

To do this we need Korn's inequality

$$\int \varepsilon(u) : \varepsilon(u) dx \geq \|u\|_{H^1}^2$$

ex near-incomp

Rubbers

Hydrogels

Bio material (cartilage, keratin)

Wet clays (saturated pores)

$$\textcircled{1} \quad |a(w, v)| \leq \mu \|w\|_{H_1} \|v\|_{H_1}$$

$$\begin{aligned} \left| \int \mu \varepsilon(w) : \varepsilon(v) \, dx \right| &= \left| \frac{\mu}{4} \sum_{i,j} \int (\partial_{x_i} w_j + \partial_{x_j} w_i) \cdot (\partial_{x_i} v_j + \partial_{x_j} v_i) \, dx \right| \\ &= \left| \mu \sum_{i,j} \int \partial_{x_i} w_j \, \partial_{x_i} v_j \, dx \right| \\ &= \mu \|w\|_{H_1} \|v\|_{H_1} \end{aligned}$$

$$\leq \mu \|w\|_{H_1} \|v\|_{H_1}$$

$$\left| \int \lambda (\nabla \cdot w) \nabla \cdot v \, dx \right|$$

$$\leq \lambda \int |\nabla \cdot w| \int |\nabla \cdot v| \, dx$$

$$\leq \lambda \|w\|_{H_1} \|v\|_{H_1}$$

$$|a(w, v)| \leq (\mu + \lambda) \|w\|_{H_1} \|v\|_{H_1}$$

$$\textcircled{2} \quad a(u, u) = \int \mu \varepsilon(u) : \varepsilon(u) + \lambda (\nabla \cdot u)^2 \, dx \stackrel{?}{\geq} \alpha \|u\|_{H_1}^2$$

$$\geq \int \mu \varepsilon(u) : \varepsilon(u) \, dx$$

$$\geq \mu \|u\|_{H_1}^2 \quad \text{By Korn}$$

What goes wrong?

$$\textcircled{1} \quad \|u\|_{H_1} \leq \frac{\lambda}{\mu} \Rightarrow \text{get a stable solution} \quad \leftarrow \text{loss of control!}$$

$$\textcircled{2} \quad \text{By Cauchy's lemma} \quad \|u - u_h\|_{H_1} \leq \frac{\mu + \lambda}{\mu} \|u - v\|_{H_1}$$

One solution, and our first example of mixed FEM
take

$$\mu \int \varepsilon(u) : \varepsilon(v) + \lambda \int \operatorname{div} u \operatorname{div} v = \int f v$$

Let $p = \lambda \operatorname{div} u$, and introduce second FEM ^{space}
 $q \in M_h$

$$\mu \int \varepsilon(u) : \varepsilon(v) dx + \int p \nabla \cdot v dx = \int f v dx$$

$$\int \nabla \cdot u q dx + \frac{1}{\lambda} \int p q dx = 0$$

This gives a new galerkin eqn but how to
design M_h ?

Note in limit $\mu=1$, $\lambda \rightarrow \infty$ this reduces to
the stationary Stokes problem

$$\textcircled{S} \quad \begin{cases} -\Delta u - \nabla p = f \\ \nabla \cdot u = 0 \end{cases}$$

$u \in H_0^1$ for Laplacian to make sense, $M_h \subseteq L^2$
 \downarrow

$$(\nabla p, v) \xrightarrow{\text{IBP}} -(p, \nabla \cdot v) < \|p\|_{L^2} \|v\|_{H_1}$$

Galerkin form

$$\begin{aligned} (\nabla u, \nabla v) + (p, \nabla \cdot v) &= (f, v) \\ (\nabla \cdot u, q) &= 0 \end{aligned}$$

~~Stability Take $q=p, v=u$~~

~~$$\|u\|_{H_1}^2 + (p, \nabla \cdot u) = (f, u)$$~~

This gives our first variational saddle-pt problem

We'll need some lemmas to tackle it, but let's prove uniqueness quickly now ($f=0 \Rightarrow p, u=0$)

Take $v=u$

$$\|u\|_{H_1}^2 + (p, \nabla \cdot u) = 0$$

Taking $q=p$ in 2nd eqn, $(p, \nabla \cdot u) = 0 \Rightarrow \|u\|_{H_1}^2 = 0$
 $\Rightarrow u = 0$

Finally, we'd like to show

$u=0 \Rightarrow p=0$. But we can't. Nothing in eqn gives us that

IDEA Design relationship between V_h, M_h so $u=0 \Rightarrow p=0$

Inf-sup condition

V_h and M_h are inf-sup compatible if
for any $g \in M_h$, there exists a $v \in V_h$

$$\text{s.t.} \quad \beta \|g\|_{L^2} \leq \frac{(g, \nabla \cdot v)}{\|v\|_{H_1}}$$

Returning to Stokes momentum eqn

$$(\cancel{\nabla u}, \nabla v) + (p, \nabla \cdot v) = 0$$

Already shown

Take $g = p$

$$\|p\|_{L^2} \leq \frac{(p, \nabla \cdot v)}{\beta \|v\|_{H_1}} = 0$$

$$\Rightarrow p = 0$$

Next time

- How to build inf-sup stable spaces
- How to learn physics in this mixed FEM setting