

**Applied Mathematics 2570, Fall 2011**  
**MWF 3-5:20pm, B&H 166**

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**Textbook**

*Numerical Solution of Partial Differential Equations by the Finite Element Method*, by Claes Johnson.

**Course Content:**

- Finite Element method for second order problems, hyperbolic problems, and parabolic problems
- Type of methods: discontinuous Galerkin Methods, mixed methods, non-conforming methods

**Grading Policy**

- Homework 80%
- Final Project 20%

**Homework Policy**

Homework is due at the beginning of lecture on Monday. In order to get full credit, solutions to the homework must include all steps. Homework must be well organized, neat and stapled. You are allowed to work with classmates. However, everyone needs to turn in their own solution set. Some of the homework problems will involve coding. I require you write code using Matlab.

**Final Project**

The final project will consist of reading a paper related to finite element methods and presenting it to the class at the end of the semester.

- Braute-Hilbert
- inf-sup
- Stokes/elasticity
- Streamline diffusion
- cea's lemma

$$\begin{aligned}
 -\Delta u + \nabla p &= f \\
 \epsilon^2 \Delta p + \nabla \cdot u &= 0
 \end{aligned}$$

## 1D Finite Elements

$$(P) \quad \begin{cases} -u''(x) = f(x) & 0 < x < 1 \\ u(0) = u(1) = 0 \end{cases}$$

Weak form을 찾아볼까!

물리에서 자주 쓰는 weak form?

Multiply (P) by smooth ftn  $V$  and integrate ( $V$  satisfies  $V(0) = V(1) = 0$ ).

$$\int_0^1 -u''(x) V(x) dx = \int_0^1 f(x) V(x) dx$$

Now, integration by parts

$$\int_0^1 u'(x) V'(x) dx - (u'(1)V(1) - u'(0)V(0)) = \int_0^1 f(x) V(x) dx$$

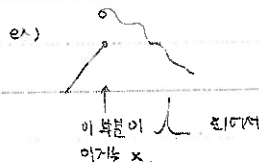
$$\int_0^1 u'(x) V'(x) dx = \int_0^1 f(x) V(x) dx \quad \forall V \in H_0^1([0,1])$$

$$H_0^1([0,1]) := \{m \in H^1([0,1]) : m(0) = 0, m(1) = 0\}$$

$$H^1([0,1]) = \{m \in L^2([0,1]) : m' \in L^2([0,1])\}$$

$$L^2([0,1]) = \{m : \int_0^1 m^2(x) dx < \infty\}$$

m'가 모두 존재할 필요성



Weak form of problem P

$$\text{Find } u \in H_0^1([0,1]) \text{ st } \int_0^1 u'(x) V'(x) dx = \int_0^1 f(x) V(x) dx \quad \forall V \in H_0^1([0,1])$$

Let  $u \in H_0^1([0,1])$ 

$$u = \sum_{i=1}^{\infty} c_i v_i \quad v_i \in H_0^1([0,1]) \quad \text{orthogonal decomposition.}$$

$$\int_0^1 u'(x) V_i'(x) dx = \int_0^1 f(x) V_i(x) dx \quad \text{for every } i=1,2,\dots$$

$$\int_0^1 \sum_{i=1}^{\infty} c_i v_i' V_i' dx = \int_0^1 f(x) V_i(x) dx$$

$$\begin{bmatrix} \int_0^1 v_1' v_1' dx & \int_0^1 v_1' v_2' dx & \dots \\ \int_0^1 v_2' v_1' dx & \int_0^1 v_2' v_2' dx & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} \int_0^1 f v_1 dx \\ \int_0^1 f v_2 dx \\ \vdots \end{bmatrix}$$

← Infinite를 둘 수 있으면

이렇게 할 수 있죠.

## Finite Element Method

- We need a finite dimensional space  $V_h \in H_0^1([0,1])$
- Find  $u_h \in V_h$  st  $\int_0^1 u_h' V' dx = \int_0^1 f V dx \quad \forall V \in V_h$
- We would like that  $u_h$  approximates  $u$  well



Uniqueness of finite element approximation (\*)

pf) Let  $f \equiv 0$ .

$$\int_0^1 u_h' v' dx = 0 \quad \forall v \in V_h$$

Let  $v = u_h$

$$\int_0^1 (u_h')^2 dx = 0 \Leftrightarrow u_h' = 0 \quad (a.e.)$$

$$u_h = \text{const} \in H_0^1([0,1]) \Rightarrow u_h = 0$$

Suppose  $V_h = \text{span}\{v_1, v_2, \dots, v_N\}$

$$u_h = \sum_{i=1}^N c_i v_i$$

$$\begin{bmatrix} \int_0^1 v_1' v_1' dx & \int_0^1 v_1' v_2' dx & \dots & \int_0^1 v_1' v_N' dx \\ \int_0^1 v_2' v_1' dx & \int_0^1 v_2' v_2' dx & \dots & \int_0^1 v_2' v_N' dx \\ \vdots & \vdots & \ddots & \vdots \\ \int_0^1 v_N' v_1' dx & \int_0^1 v_N' v_2' dx & \dots & \int_0^1 v_N' v_N' dx \end{bmatrix} \begin{bmatrix} c_1 \\ \vdots \\ c_N \end{bmatrix} = \begin{bmatrix} \int_0^1 f v_1 dx \\ \vdots \\ \int_0^1 f v_N dx \end{bmatrix}$$

$$A \vec{c} = \vec{f}$$

SPD  $\Rightarrow$  invertible

Uniqueness  $\Leftrightarrow$  (\*)에서 분할에 따른 invertible임을 여쭙 가능

We still have not argued that  $u_h$  will be a good approx of  $u$

Space  $V_h$  should specify:

1) Good approximation

Given any  $u \in H_0^1([0,1])$

$\inf_{v \in V_h} \|u - v\|$  is "small" (norm  $\|\cdot\|$  to be determined)

$\Rightarrow \left( \int_0^1 w' v' dx, \int_0^1 f v dx \right)$  to be "inexpensive" to compute  $\forall w, v \in V_h$

Q) 근사치로?

$\|u - v\|$ 가 작은  $v$ 를  $V_h$ 에서 찾는다

$\forall v \in V_h$ 가  $\|u - v\|$ 를 줄이기 위해

Example of  $V_h$

We first partition  $[0,1]$

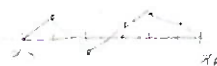
Let  $0 = x_0 < x_1 < \dots < x_{N+1} = 1$

$$\begin{matrix} | \\ x_0 \\ | \end{matrix} \quad \begin{matrix} | \\ x_1 \\ | \end{matrix}$$

$$\begin{matrix} | \\ x_N \\ | \end{matrix} \quad \begin{matrix} | \\ x_{N+1} \\ | \end{matrix}$$

$$I_j = (x_j, x_{j+1}) \quad h_j = x_{j+1} - x_j \quad h = \max h_j$$

$$V_h = \{v \in C_0([0,1]) : v|_{I_j} \in P^1(I_j) \text{ for } j=1, \dots, N\}$$



$\frac{1}{N+1}$   $\rightarrow$  4분할만 하면 되므로

Base for  $V_h = \text{span}\{\phi_1, \phi_2, \dots, \phi_N\}$

For every  $\phi_i \in V_h$ ,  $\phi_i(x_j) = \begin{cases} 0 & j \neq i \\ 1 & j = i \end{cases}$

$\phi_i$



If  $v \in V_h$ ,  $v(x) = v(x_1)\phi_1(x) + v(x_2)\phi_2(x) + \dots + v(x_N)\phi_N(x)$

$$\Rightarrow v(x_j) = v(x_j)\phi_j(x_j) = v(x_j)$$

tent / hat fn.

Good approximation

Given any  $u \in H^2([0,1]) \cap H_0^1([0,1])$

$$\inf_{v \in V_h} \|u - v\|_{H^1([0,1])} \leq Ch \|u''\|_{L^2([0,1])} \quad \checkmark$$

$$\|v\|_{L^2([0,1])} = \sqrt{\int_0^1 u^2(x) dx}$$

$$\|v\|_{H^1([0,1])} = \|v\|_{L^2([0,1])} + \|v'\|_{L^2([0,1])} \quad \checkmark$$

$$\inf_{v \in V_h} \|u - v\|_{H^1([0,1])} \leq \|u - \tilde{u}\|_{H^1([0,1])} \leq Ch \|u''\|_{L^2([0,1])} \quad \checkmark$$

bilinear form

$$a(u, v) := \int_0^1 u(x) v'(x) dx$$

$$(u, v) := \int_0^1 u(x) v(x) dx$$

$$\Rightarrow u_n \in V_h, \quad a(u_n, v) = (f, v) \quad \forall v \in V_h$$

$$\begin{bmatrix} a(\phi_1, \phi_1) & a(\phi_1, \phi_2) \\ \vdots & \vdots \\ a(\phi_N, \phi_1) & a(\phi_N, \phi_N) \end{bmatrix} \begin{bmatrix} u_n(x_1) \\ \vdots \\ u_n(x_N) \end{bmatrix} = \begin{bmatrix} (f, \phi_1) \\ \vdots \\ (f, \phi_N) \end{bmatrix}$$

$\overset{\text{"A"}}{\downarrow}$

$$a(\phi_j, \phi_i) = \int_0^1 \phi_j'(x) \phi_i'(x) dx = 0 \quad |i-j| \geq 2$$

$$a(\phi_i, \phi_i) = \int_{x_{i-1}}^{x_{i+1}} \phi_i'(x) \phi_i'(x) dx$$

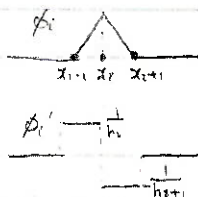
$$a(\phi_{i-1}, \phi_i) = \int_{x_{i-1}}^{x_i} \phi_{i-1}' \phi_i' dx$$

$$a(\phi_{i+1}, \phi_i) = \int_{x_i}^{x_{i+1}} \phi_{i+1}' \phi_i' dx$$

이분할한 계산하면 되는 것이 Fourier와 비교하여 장점

$w, v \in V_h$

$$a(w, v) = \vec{x}^T A \vec{y} \quad \text{where} \quad \vec{x} = \begin{bmatrix} w(x_1) \\ \vdots \\ w(x_N) \end{bmatrix} \quad \vec{y} = \begin{bmatrix} v(x_1) \\ \vdots \\ v(x_N) \end{bmatrix}$$



$$a(\phi_i, \phi_i) = \int_{x_{i-1}}^{x_i} \left(\frac{1}{h_i}\right)^2 dx + \int_{x_i}^{x_{i+1}} \left(-\frac{1}{h_{i+1}}\right)^2 dx = \frac{1}{h_i} + \frac{1}{h_{i+1}}$$

$$a(\phi_{i-1}, \phi_i) = \int_{x_{i-1}}^{x_i} \left(-\frac{1}{h_i}\right) \left(\frac{1}{h_i}\right) dx = -\frac{1}{h_i}$$

$$a(\phi_{i+1}, \phi_i) = -\frac{1}{h_{i+1}}$$

$$A = \begin{bmatrix} \frac{1}{h_1} + \frac{1}{h_2} & -\frac{1}{h_2} & & \\ -\frac{1}{h_2} & \frac{1}{h_2} + \frac{1}{h_3} & -\frac{1}{h_3} & \\ & -\frac{1}{h_3} & \ddots & \\ & & -\frac{1}{h_{N-1}} & \frac{1}{h_{N-1}} + \frac{1}{h_N} \end{bmatrix}$$

Uniform mesh  $h_i = h \quad \forall i$ ,

$$A = \frac{1}{h} \begin{bmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & \ddots & \\ & & -1 & 2 \end{bmatrix}$$

In 1D,  $u_h(x_i) = u(x_i)$   $\Rightarrow$   $\forall$   $u$ 은  $A$ 는 같지만  $u$  성질  $x$

Properties of  $A$ :

- tridiagonal (sparse)
- symmetric
- positive definite  $\vec{y}^T A \vec{y} > 0$  for any  $\vec{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix} \neq 0$

pf) Let  $\vec{y}$  be given

$$\text{Define } v(x) = y_1 \phi_1(x) + y_2 \phi_2(x) + \dots + y_N \phi_N(x)$$

$$\vec{y}^T A \vec{y} = a(v, v) = \int_0^1 v'(x) v'(x) dx > 0$$

Generalize.

$$V_h = \{v \in C_0([0,1]) : v|_{I_j} \in P^k(I_j), j=1, \dots, N\}$$

$P^k(I_j)$  = space of all polynomials of degree  $k$  or less defined on  $I_j$

$k \uparrow \Rightarrow$  better approx. but dimension increases with  $k$

Good approximation

$(k+1)^{\text{th}}$  derivative

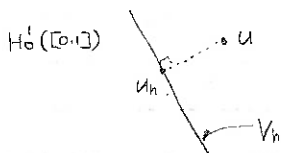
$$\inf \|u - v\|_{H^1([0,1])} \leq Ch^k \|u^{(k+1)}\|_{L^2([0,1])}$$

But if  $u$  is not smooth, the bound  $\uparrow$

Thm Let  $u$  solve (P) and

$u_h$  be the finite element approximation using piecewise polynomial of order  $k$

$$\checkmark \text{ Then, } \|(u - u_h)'\|_{L^2([0,1])} \leq \inf_{v \in V_h} \|(u - v)'\|_{L^2([0,1])} \leq \inf_{v \in V_h} \|u - v\|_{H^1([0,1])} \leq Ch^k \|u^{(k+1)}\|_{L^2([0,1])}$$



my course HW #2

HW #4 Integrate right-hand side exactly (by hand or approximately but very exactly)

HW #4 HW #4

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## FEM for Poisson's problem

We let  $\Omega$  be a bounded polygonal domain

$$(P) \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad \Delta u = \partial_{xx} u + \partial_{yy} u$$

Sobolev spaces.

$$H^1(\Omega) = \{v \in L^2(\Omega) : \nabla v \in L^2(\Omega)\}$$

$$H_0^1(\Omega) = \{v \in H^1(\Omega) : v = 0 \text{ on } \partial\Omega\}$$

$$L^2(\Omega) = \{v : \int_{\Omega} v^2 dx < \infty\}$$

## ★ Derive weak formulation of problem P

First multiply (P) by a fn  $v \in H_0^1(\Omega)$  and integrate

$$\int_{\Omega} -\Delta u(x) v(x) dx = \int_{\Omega} f(x) v(x) dx$$

$$\text{Use IBP, } \int_{\Omega} \nabla u(x) \cdot \nabla v(x) dx = \int_{\Omega} f(x) v(x) dx \quad \text{Green's thm \& Boundary} = 0 \text{ on } \partial\Omega$$

? Integrate by part?

$$u \in H_0^1(\Omega) \text{ solves } a(u, v) = (f, v) \quad \forall v \in H_0^1(\Omega)$$

$$\text{where } a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v(x) dx$$

$$(f, v) := \int_{\Omega} f(x) v(x) dx.$$

FEM: Find  $u_h \in V_h$  st  $a(u_h, v) = (f, v) \quad \forall v \in V_h$   
 where  $V_h \in H_0^1(\Omega)$  is finite dimensional space

Example of  $V_h$ Let  $\mathcal{T}_h$  be the collection of triangles st  $\Omega = \bigcup_{T \in \mathcal{T}_h} T$ 

$$h = \max_{T \in \mathcal{T}_h} \text{diameter}(T)$$

$$V_h = \{v \in C_0(\Omega) : v|_T \in P^1(T) \text{ for all } T \in \mathcal{T}_h\}$$

$P^1(T)$  = all polynomials defined on  $T$  of degree less than or equal to 1

If  $\exists v, w \in V_h$  satisfying  $v = w$  for all nodes.

$$v, w \in V_h \Rightarrow v - w \in V_h$$

$$\Rightarrow v - w = 0 \text{ at all nodes}$$

$$\Rightarrow v - w = 0 \text{ for all } p \in \mathcal{T}_h.$$

M interior nodes:  $\vec{N}_1, \vec{N}_2, \dots, \vec{N}_M$ 

$$\text{Basis fns are } \phi_i \in V_h \quad \phi_i(\vec{N}_j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} \quad (i=1, \dots, M)$$

$$\text{If } v \in V_h, \quad v(\vec{x}) = \sum_{i=1}^M v(\vec{N}_i) \phi_i(\vec{x})$$

$$\uparrow$$

$$v(\vec{N}_j) = \sum_{i=1}^M v(\vec{N}_i) \phi_i(\vec{N}_j) = v(\vec{N}_j)$$

$$U_h \in V_h \quad \text{s.t.} \quad a(U_h, v) = (f, v) \quad \forall v \in V_h$$

$$\Leftrightarrow U_h \in V_h \quad \text{s.t.} \quad a(U_h, \phi_j) = (f, \phi_j) \quad j = 1, 2, \dots, M$$

$$U_h = \sum_{i=1}^M U_h(\vec{N}_i) \phi_i$$

$$\Rightarrow a\left(\sum_{i=1}^M U_h(\vec{N}_i) \phi_i, \phi_j\right) = (f, \phi_j) \quad j = 1, 2, \dots, M$$

$$\sum_{i=1}^M U_h(\vec{N}_i) a(\phi_i, \phi_j) = (f, \phi_j) \quad j = 1, 2, \dots, M$$

↑ unknowns

Recall  $a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \Rightarrow \text{bilinear}$

$$\begin{bmatrix} a(\phi_1, \phi_1) & a(\phi_1, \phi_2) & \dots & a(\phi_1, \phi_M) \\ a(\phi_2, \phi_1) & a(\phi_2, \phi_2) & & \\ \vdots & & \ddots & \\ a(\phi_M, \phi_1) & & & a(\phi_M, \phi_M) \end{bmatrix} \begin{bmatrix} U_h(\vec{N}_1) \\ U_h(\vec{N}_2) \\ \vdots \\ U_h(\vec{N}_M) \end{bmatrix} = \begin{bmatrix} (f, \phi_1) \\ (f, \phi_2) \\ \vdots \\ (f, \phi_M) \end{bmatrix}$$

$$A \vec{U} = \vec{F}$$

Need to compute  $A$  &  $\vec{F}$

### 1) Triangulation

- vertex array

$$Z = \begin{bmatrix} z(i,1) & z(i,2) & z(i,3) \end{bmatrix}$$

$= (M' \times 3)$  matrix where  $M' = \#(\text{total nodes})$  interior + boundary

$$\begin{cases} z(i,1) \text{ is the } x \text{ value of node } \vec{N}_i \\ z(i,2) \text{ is the } y \text{ value of node } \vec{N}_i \\ z(i,3) = \begin{cases} 0 & \text{if } \vec{N}_i \text{ is a boundary node} \\ \text{interior node numbers of node } \vec{N}_i & \text{if } \vec{N}_i \text{ is an interior node} \end{cases} \end{cases}$$



- Connectivity Matrix

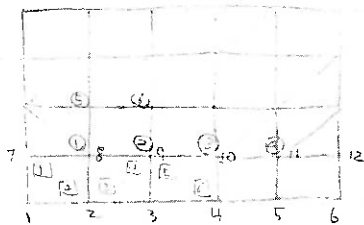
$T = (Q \times 3)$  matrix where  $Q$  is the number of triangles

$$T = \begin{bmatrix} T(j,1) & T(j,2) & T(j,3) \end{bmatrix}$$

$\leftarrow j\text{th triangle}$

$\vec{x}_1 = Z(T(j,1), 1:2)$   
 $\vec{x}_2 = Z(T(j,2), 1:2) - \vec{x}_1$   
 $\vec{x}_3 = Z(T(j,3), 1:2)$

counter clockwise



$$2) A_{ij} = a(\phi_i, \phi_j) = \int_{\Omega} \nabla \phi_i \cdot \nabla \phi_j \, dx = \sum_{n=1}^Q \int_{T_n} \nabla \phi_i \cdot \nabla \phi_j \, dx \quad T_h = \{T_1, T_2, \dots, T_Q\}$$

$A$  stiffness matrix

$A^{\text{loc}, n}$  the local stiffness matrix corresponding to triangle  $n$  ( $3 \times 3$ ) matrix

Define  $\psi_{\alpha}(\beta) = \begin{cases} 1 & \text{if } \alpha = \beta \\ 0 & \text{if } \alpha \neq \beta \end{cases} \quad \alpha, \beta = 1, 2, 3$

$$A^{\text{loc}, n}_{\alpha\beta} = \int_{T_n} \nabla \psi_{\alpha} \cdot \nabla \psi_{\beta} \, dx$$



$$dx = \frac{dx}{du} du$$

Initialize A is  $M \times M$

for  $n = 1, 2, \dots, Q$

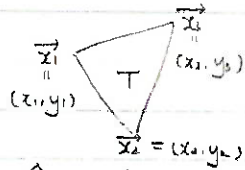
for  $\alpha, \beta = 1, 2, 3$

if  $z(T(n, \alpha), 3) \neq 0$  &  $z(T(n, \beta), 3) \neq 0$

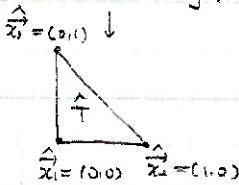
$$A_{z(T(n, \alpha), 3), z(T(n, \beta), 3)} = A_{z(T(n, \alpha), 3), z(T(n, \beta), 3)} + A_{\alpha, \beta}^{h, n}$$

end end end

the subroutine  $\frac{1}{2} \frac{1}{2}$



$$\int_T \nabla \psi_1 \cdot \nabla \psi_2$$



$\hat{T}$  is the reference triangle

$$\begin{cases} \hat{\psi}_1(\hat{x}, \hat{y}) = 1 - \hat{x} - \hat{y} \\ \hat{\psi}_2(\hat{x}, \hat{y}) = \hat{x} \\ \hat{\psi}_3(\hat{x}, \hat{y}) = \hat{y} \end{cases}$$

degree of  $\psi$  in  $T$   
= degree of  $\hat{\psi}$  in  $\hat{T}$

$$F: \hat{T} \rightarrow T$$

or

$$F(\hat{x}) = B\hat{x} + \vec{x}_1$$

where

$$B = \begin{bmatrix} x_2 - x_1 & y_2 - y_1 \\ x_3 - x_1 & y_3 - y_1 \end{bmatrix}$$

Given  $\psi(x, y)$  defined on  $T$   $\hat{\psi}(\hat{x}, \hat{y}) = \psi(x, y)$

$$\Rightarrow \nabla \hat{\psi} = B^T \nabla \psi$$

where

$$\begin{pmatrix} x \\ y \end{pmatrix} = F\left(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}\right)$$

$$\nabla \psi = (B^T)^{-1} \nabla \hat{\psi}$$

$$\int_T \nabla \psi_1 \cdot \nabla \psi_2 dx dy = \int_T (B^{-T} \nabla \hat{\psi}_1(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix})) \cdot (B^{-T} \nabla \hat{\psi}_2(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix})) dx dy$$

$$= \int_T (B^{-T} \nabla \hat{\psi}_1(F^{-1}(\begin{pmatrix} x \\ y \end{pmatrix}))) \cdot (B^{-T} \nabla \hat{\psi}_2(F^{-1}(\begin{pmatrix} x \\ y \end{pmatrix}))) dx dy$$

$$= \int_{\hat{T}} (B^{-T} \nabla \hat{\psi}_1(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix})) \cdot (B^{-T} \nabla \hat{\psi}_2(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix})) |\det B| d\hat{x} d\hat{y}$$

If  $\hat{\psi}_1, \hat{\psi}_2$  are linear,

$$= \frac{|\hat{T}|}{2} |\det B| B^{-T} \cdot \nabla \hat{\psi}_1(0) \cdot B^{-T} \nabla \hat{\psi}_2(0)$$

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$$\text{Example } \begin{cases} -\Delta u = f & \Omega \\ u = g & \partial\Omega \end{cases}$$

: Nonhomogeneous B.C.

Let  $\theta$  be any  $H^1(\Omega)$  st.  $\theta = g$  on  $\partial\Omega$

$$u = \theta + (u - \theta)$$

Let  $w = u - \theta \in H_0^1(\Omega)$

Let  $v \in H_0^1(\Omega)$

$$a(w, v) = a(u - \theta, v) = a(u, v) - a(\theta, v) = (f, v) - a(\theta, v)$$

Find  $w \in H_0^1(\Omega)$  s.t.

$$a(w, v) = L(v) \quad \forall v \in H_0^1(\Omega)$$

where  $L(v) = (f, v) - a(\theta, v)$

Find  $\theta_h \in V_h$  st.  $\theta_h = I_h g$  for some interpolant of  $g$ , and  $\theta_h = 0$  on interior nodes

find  $w_h \in V_h$  st

$$a(w_h, v) = L_h(v) \quad \forall v \in V_h$$

where  $L_h(w) = (f, v) - a(\theta_h, v)$   
note:  $a(\theta_h, v)$

Then  $u_h = \theta_h + w_h$

Neumann Problem:

Note: Neumann problem is not well-posed

boundary value problem is unknown  $\frac{\partial u}{\partial n}$   
 Dirichlet only known

$$\begin{cases} -\Delta u + u = f & \Omega \\ \frac{\partial u}{\partial n} = 0 & \partial\Omega \end{cases}$$

$$\int_{\Omega} (-\Delta u + u) v \, dx = \int_{\Omega} f v \, dx$$

$$\int_{\Omega} (\nabla u \cdot \nabla v + uv) \, dx = \int_{\partial\Omega} \left( \frac{\partial u}{\partial n} v \right) \, ds = \int_{\Omega} f v \, dx \quad \Rightarrow \text{not well-posed} \quad V = \{v \in H^1(\Omega)\}$$

$$\text{or } V_h = \{v \in C(\bar{\Omega}) : v|_T \in P^1(T) \quad \forall T \in \mathcal{T}_h\}$$

Find  $u_h \in V_h$  satisfying

$$a(u_h, v) = (f, v) \quad \forall v \in V_h$$

where  $a(u, v) = \int_{\Omega} (\nabla u \cdot \nabla v + uv) \, dx$

$$\begin{cases} -\Delta u + u = f & \Omega \\ \frac{\partial u}{\partial n} = g & \partial\Omega \end{cases}$$

$$\int_{\Omega} (\nabla u \cdot \nabla v + uv) \, dx = \int_{\partial\Omega} \left( \frac{\partial u}{\partial n} v \right) \, ds = \int_{\Omega} f v \, dx + \int_{\partial\Omega} g v \, ds$$

Check if problem is well-posed: Find  $u \in H^1(\Omega)$  st  $a(u, v) = \int_{\Omega} f v \, dx + \int_{\partial\Omega} g v \, ds$

LEM Find  $u_h \in V_h$  st  $a(u_h, v) = \int_{\Omega} f v \, dx + \int_{\partial\Omega} g v \, ds \quad \forall v \in V_h$

Dirichlet & Neumann  $\Rightarrow$  Mixed B.C.

$$\begin{cases} -\Delta u + u = f & \Omega \\ u = g_1 & \Gamma_1 \\ \frac{\partial u}{\partial n} = g_2 & \Gamma_2 \end{cases} \quad (4) \quad \Gamma_1, \Gamma_2 \subset \partial\Omega, \quad \Gamma_1 \cup \Gamma_2 = \partial\Omega$$

$$V = \{v \in H^1(\Omega) : v = 0 \text{ on } \Gamma_1\}$$

Multiply (4) with  $v \in V$ .

$$\int_{\Omega} (-\Delta u + u) v \, dx = \int_{\Omega} f v \, dx$$

$$\int_{\Omega} (\nabla u \cdot \nabla v + uv) \, dx = \int_{\partial\Omega} \left( \frac{\partial u}{\partial n} v \right) \, ds = \int_{\Omega} f v \, dx + \int_{\Gamma_2} g_2 v \, ds$$

$$\Rightarrow a(u, v) = \int_{\Omega} f v \, dx + \int_{\Gamma_2} g_2 v \, ds \quad \forall v \in V$$

Let  $\theta \in H^1(\Omega)$  with  $\theta = g_1$  on  $\Gamma_1$ , then  $u - \theta \in V$

$$u = \theta + (u - \theta) =: \theta + w \quad w = u - \theta$$

Given  $v \in V$ ,  $a(u, v) = a(u - \theta, v) = a(w, v) = \int_{\Omega} f v \, dx + \int_{\Gamma_2} g_2 v \, ds - a(\theta, v) =: L(v)$

Find  $w \in V$  satisfying  $a(w, v) = L(v) \quad \forall v \in V$

(Neumann problem is well-posed)

Many PDE's are formulated in the following way

$$\begin{cases} \text{Find } u \in V \\ a(u, v) = L(v) \quad \text{for all } v \in V \end{cases}$$

$V$  is a inner-product space

$a$  is a bilinear form  $a: V \times V \rightarrow \mathbb{R}$

$$a(\alpha v_1 + \beta v_2, u) = \alpha a(v_1, u) + \beta a(v_2, u)$$

$$a(u, \alpha v_1 + \beta v_2) = \alpha a(u, v_1) + \beta a(u, v_2)$$

$$L: V \rightarrow \mathbb{R} \quad L(\alpha v_1 + \beta v_2) = \alpha L(v_1) + \beta L(v_2)$$

Example  $V = H_0^1(\Omega)$

$$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \quad L(v) = (f, v) = \int_{\Omega} f v$$

Example

$$\begin{cases} \Delta^2 u = f & \Omega \\ u = 0 & \partial\Omega \\ \frac{\partial u}{\partial n} = 0 & \partial\Omega \end{cases}$$

$\sum_{i,j} \frac{\partial^2 u}{\partial x_i \partial x_j} \frac{\partial^2 v}{\partial x_i \partial x_j} = \text{Hessian} \cdot \text{Hessian}^T$

$$V = H_0^2(\Omega) = \{v \in H^2(\Omega) \mid v = 0, \frac{\partial v}{\partial n} = 0 \text{ on } \partial\Omega\}$$

$$a(u, v) = \int_{\Omega} \Delta u \cdot \Delta v \quad L(v) = \int_{\Omega} f v$$

General Assumptions

induced norm  $\|v\|_V = \sqrt{a(v, v)}$

$V$  is an inner product space with inner product  $(u, v)_V$  for any  $u, v \in V$

There exist positive constants  $\gamma, \alpha, \Lambda$  s.t. the following hold

- (i)  $a(\cdot, \cdot)$  continuous i.e.  $|a(v, w)| \leq \gamma \|v\|_V \|w\|_V$  for all  $v, w \in V$
- (ii)  $a(\cdot, \cdot)$  is  $V$ -elliptic (coercive) i.e.  $a(v, v) \geq \alpha \|v\|_V^2$
- (iii)  $|L(v)| \leq \Lambda \|v\|_V$

Frobenius inner product

Example.  $a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \, dx \quad L(v) = \int_{\Omega} f v \, dx$

$$A: B = \sum_{i,j} A_{ij} B_{ij}$$

For  $V = H_0^1(\Omega)$ ,

$$(u, v)_V = \int_{\Omega} \nabla u \cdot \nabla v + uv \, dx$$

$$D^2 u = \begin{bmatrix} \frac{\partial^2 u}{\partial x_1^2} & \frac{\partial^2 u}{\partial x_1 \partial x_2} \\ \frac{\partial^2 u}{\partial x_1 \partial x_2} & \frac{\partial^2 u}{\partial x_2^2} \end{bmatrix}$$

Check (i) - (iii)

$$(i) \quad a(v, w) = \int_{\Omega} \nabla v \cdot \nabla w \, dx \leq \|\nabla v\|_{L^2(\Omega)} \|\nabla w\|_{L^2(\Omega)} \leq \|v\|_V \|w\|_V$$

$\Rightarrow$  (i) is satisfied with  $\gamma = 1$

$$\|\nabla v\|_{L^2(\Omega)}^2 = \int_{\Omega} (v_{x_1}^2 + 2v_{x_1 x_2} + v_{x_2}^2) \leq 2 \int_{\Omega} (v_{x_1}^2 + v_{x_2}^2)$$

$$\|v\|_V^2 = \int_{\Omega} (v_{x_1}^2 + 2v_{x_1 x_2} + v_{x_2}^2 + v^2) \, dx$$

$$(ii) \quad \int_{\Omega} (\nabla^2 v \cdot \nabla^2 v + \nabla v \cdot \nabla v + v v) \, dx \leq \int_{\Omega} \nabla^2 v \cdot \nabla^2 v \, dx$$

If  $\Omega$  is convex,  $\|v\|_{H^1(\Omega)} \leq C \|\nabla v\|_{L^2} \quad v \in H^1 \cap H_0^1(\Omega)$

$$C = C(\Omega)$$

$$\Rightarrow \alpha = \frac{1}{C}$$

$$(iii) \quad |L(v)| = \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \leq \|f\|_{L^2(\Omega)} \|v\|_V$$

$$\Rightarrow \Lambda = \|f\|_{L^2(\Omega)}$$

$$\int_{\Omega} v_{x_1} v_{x_2} \, dx = - \int_{\Omega} \frac{1}{2} v_{x_1 x_2} \, dx + \dots$$

$\frac{\partial^2 v}{\partial x_1 \partial x_2} = \frac{\partial^2 v}{\partial x_2 \partial x_1} \quad \gamma = 1/2$

elliptic regularity

Finite Element

$$V_h \in V$$

Find  $u_h \in V_h$  satisfying  $a(u_h, v) = L(v) \quad \forall v \in V_h$

Galerkin Orthogonality

Lemma Suppose  $u \in V$  is the solution to

$$a(u, v) = L(v) \quad \text{for all } v \in V$$

Let  $u_h \in V_h$  be its finite element approximation satisfying

$$a(u_h, v) = L(v) \quad \text{for all } v \in V_h$$

Then,  $a(u - u_h, v) = 0 \quad \forall v \in V_h$

p.f) let  $v \in V_h \subset V$

$$a(u, v) = L(v), \quad a(u_h, v) = L(v)$$

$$\Rightarrow a(u, v) - a(u_h, v) = \underbrace{a(u - u_h, v)}_{=0} = 0 \quad \forall v \in V_h$$

"0" orthogonal!

Thm Suppose (i) - (iii) hold, (\*)

(Cea's Lemma)

Then,

$$\|u - u_h\|_V \leq \frac{\gamma}{\alpha} \inf_{v \in V_h} \|u - v\|_V$$

approximation theory. ( $V_h$ 가 얼마나 rich하냐에  $u$ 를 잘 approximate 하느냐...)  
 Error bound  $v$ 가 얼마나  $u$ 에  $u$ 를 regularity를 만족시킨다

p.f)  $u - u_h \in V$

$$\alpha \|u - u_h\|_V^2 \leq a(u - u_h, u - u_h) \quad \text{by (ii)}$$

$$= a(u - u_h, u) - \underbrace{a(u - u_h, u_h)}_{=0 \text{ by (*)}}$$

$$= a(u - u_h, u) - a(u - u_h, v) \quad \forall v \in V_h \quad \text{by Galerkin Orthogonality}$$

$$= a(u - u_h, u - v)$$

$$\leq \gamma \|u - u_h\|_V \|u - v\|_V \quad \text{by (i)}$$

$$\|u - u_h\|_V \leq \frac{\gamma}{\alpha} \|u - v\|_V \quad \forall v \in V_h$$

(finite element  $u_h$  and  $u$ 의 min error bound)

1/3

- 1) Formal Definition of Finite Elements. examples
- 2) Bramble - Hilbert Lemma (Approximation theory)

Def A Finite Element is a triple  $(K, P_K, \Sigma)$

Clarlet or  $P_K$  def.

where  $K$  is a geometric object.



$P_K$  is a finite dimensional space of function defined on  $K$ .

and  $\Sigma$  is a set of degrees of freedom that determine uniquely each function  $v \in P_K$

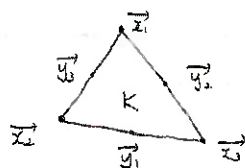
review  
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Example

$K = \text{triangle}$

$P_K = P^2(K) = \text{span} \{1, x, y, x^2, y^2\}$

$\Sigma = \text{value at vertices and values at midpoints of edges.}$



Claim: Given  $v \in P_K$ , we know exactly if we know  $v(\vec{x}_i), v(\vec{y}_i)$   $i=1,2,3$

$\dim(P_K) = \dim(P^2(K)) = 6 = \# \text{ of given points } \vec{x}_i, \vec{y}_i$

We need to show that if  $v \in P_K$  and  $v(\vec{x}_i) = v(\vec{y}_i) = 0$  for  $i=1,2,3$  then  $v=0$ .

p1) quadratic fn that vanishes at 3 points  $\Rightarrow$  zero function.  
restrict to an edge

$v = l \lambda_1$  where  $\lambda_1$  is unique linear function that is one on  $\vec{x}_1$ , and zero on  $\vec{x}_2$  and  $\vec{x}_3$ .  
and  $l$  is a linear function

$0 = v(\vec{y}_3) = l(\vec{y}_3) \lambda_1(\vec{y}_3) = \frac{1}{2} l(\vec{y}_3)$

Similarly,  $l(\vec{x}_1) = 0$  ( $v(\vec{x}_1) = l(\vec{x}_1) \lambda_1(\vec{x}_1) = 0$ )

$v = c \lambda_1 \lambda_3$  where  $\lambda_3 \in P^1(K)$ ,  $\lambda_3(\vec{x}_j) = \begin{cases} 1, & j=3 \\ 0, & j \neq 3 \end{cases}$

$0 = v(\vec{y}_2) = c \lambda_1(\vec{y}_2) \lambda_3(\vec{y}_2) = \frac{1}{4} c$

$\therefore c = 0$

$\therefore v = 0$

• barycentric coordinate of triangle

$\lambda_i \in P^1(K)$ ,

$\lambda_i(\vec{x}_j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$

$$ax^2 + bxy + cy^2 + dx + ey + f$$

Example

$K = \text{triangle}$

$P_K = P^2(K)$

$\Sigma = \text{values at nodes and average on each edge}$

$$\frac{1}{|e|} \int_e v$$

$$\pi \cdot v \rightarrow v_h$$

$$\frac{1}{|K|} \int_K \partial_{x_i}(\pi v) = \frac{1}{|K|} \int_K \partial_{x_i} v$$

Example

$K = [0, 1]$

$P_K = P^5(K)$

$\Sigma = \text{values of function, first and second derivatives on 0 and 1}$

$\Rightarrow C^2 \text{ continuity}$

$$v(0) = v'(0) = v''(0) = v(1) = v'(1) = v''(1) \Rightarrow v=0$$

(2) value on  $\partial K \sim \partial K$  at

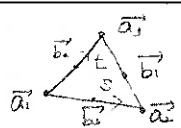
p1) similar to the above p1)

edges? ID example 8/

Example.

$K = \text{triangle}$

$P_K = P^5(K)$



$\Sigma = V(a_i), \nabla V(a_i), \nabla^2 V(a_i), \frac{\partial}{\partial n} V(b_i) \quad i=1,2,3$

: Aggric-element ( $\Rightarrow C^1$  continuity).

3 edges restrict the  $\frac{\partial V}{\partial n}$  on

$\Sigma$  is  $P^5(K) \ni V$  : uniquely determined

$C^1$  continuity가 나오지 않! 이걸 어떻게?

$\dim(P^p(K)) = \frac{1}{2}(p+1)(p+2) \quad \text{in 2-D.}$

$\Rightarrow \dim(P^5(K)) = 21$

$= 3 + 6 + 9 + 3$

• Suppose  $V \in P^5(K), \quad V(a_i) = \partial_{x_j} V(a_i) = \partial_{x_j} \partial_{x_k} V(a_i) = \frac{\partial V}{\partial n}(b_i) = 0.$

$\Rightarrow V$  vanishes at edges.

$\Rightarrow V = r \lambda_1 \lambda_2 \lambda_3$  where  $r$  is quadratic

First show  $r$  vanishes at vertices.

$\partial_\sigma \partial_\tau V = \partial_\sigma (r \partial_\tau (\lambda_1 \lambda_2 \lambda_3)) + (\partial_\sigma r) \lambda_1 \lambda_2 \lambda_3$

$= r \partial_\sigma \partial_\tau (\lambda_1 \lambda_2 \lambda_3) + (\partial_\sigma r) \underbrace{\partial_\tau (\lambda_1 \lambda_2 \lambda_3)}_0 + (\partial_\sigma \partial_\tau r) \underbrace{\lambda_1 \lambda_2 \lambda_3}_0 + (\partial_\sigma r) \underbrace{\partial_\tau (\lambda_1 \lambda_2 \lambda_3)}_0$

$\partial_\sigma \partial_\tau V(\vec{a}_1) = r(\vec{a}_1) \partial_\sigma \partial_\tau (\lambda_1 \lambda_2 \lambda_3)$

$= r(\vec{a}_1) (\lambda_1 (\underbrace{\partial_\sigma \lambda_2 \partial_\tau \lambda_3}_0 + \underbrace{\partial_\sigma \lambda_3 \partial_\tau \lambda_2}_0) + \lambda_2 (\underbrace{\partial_\sigma \lambda_1 \partial_\tau \lambda_3}_0 + \underbrace{\partial_\sigma \lambda_3 \partial_\tau \lambda_1}_0) + \lambda_3 (\underbrace{\partial_\sigma \lambda_2 \partial_\tau \lambda_1}_0 + \underbrace{\partial_\sigma \lambda_1 \partial_\tau \lambda_2}_0))$

$\Rightarrow r(\vec{a}_1) = 0$

Similarly,  $r(\vec{a}_2) = r(\vec{a}_3) = 0$

$\partial_n V(b_i) = (\partial_n r(b_i)) \underbrace{\lambda_1 \lambda_2 \lambda_3}_0 + r(b_i) \underbrace{\partial_n (\lambda_1 \lambda_2 \lambda_3)}_0$

$\Rightarrow r(b_i) = 0$

$\Rightarrow r \equiv 0$

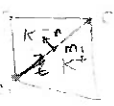
$\Rightarrow V \equiv 0.$

• Global finite element space

$V_h = \{V: V|_K \in P^5(K) \quad \forall K \in \mathcal{T}_h \text{ such that } V, \nabla V, \nabla^2 V, \partial_n V \text{ agree from different triangles}\}.$

$\Rightarrow V_h \subseteq H^1(\Omega) \quad V_h \subseteq C^1(\Omega)$

( $V, \nabla V, \nabla^2 V$  agree at vertices  
 $\partial_n V$  agree at midpoints of triangulation)



$e = \bar{K} - \cap \bar{K}_+$

$V_+ = V|_{K_+}, \quad V_- = V|_{K_-}$

Let  $W = V_+ - V_-$ . We must show  $W \equiv 0, \nabla W \equiv 0$  on  $e$ . ( $\Rightarrow C^1$ )

pf)  $W|_e \in P^5(e)$

$W(a_i) = 0, \nabla W(a_i) = 0, \nabla^2 W(a_i) = 0 \quad i=1,2 \quad \Rightarrow W|_e \equiv 0 \text{ on } e \quad \Rightarrow V_+ = V_- \text{ on } e$

$\nabla W|_e = (\nabla W \cdot \vec{e}) \vec{e}|_e + (\nabla W \cdot \vec{n}) \vec{n}|_e$

0 since  $W \equiv 0$  along the line

Let  $\vec{f} = \nabla W \cdot \vec{n}|_e \in P^4(e)$

$\vec{f}(m_i) = \vec{f}(a_i) = \vec{f}'(a_i) = \vec{f}(a_i) = \vec{f}'(a_i) = 0. \Rightarrow \vec{f} \equiv 0 \Rightarrow \nabla W|_e = 0$

•  $\dim(V_h) = 6 \cdot \text{number of vertices} + 1 \cdot \text{number of edges.}$

$V, \partial_x V, \partial_y V, \partial_{xx} V, \partial_{xy} V, \partial_{yy} V \quad \frac{\partial V}{\partial n}$

Example  $V_n = \{v \in H^1(\Omega) : v|_T \in P^k(T) \quad \forall T \in \mathcal{T}_n\}$

Given  $u \in H^{k+1}(\Omega)$ ,

$$\inf_{v \in V_n} \|u - v\|_{H^1(\Omega)} \leq C h^k |u|_{H^{k+1}(\Omega)}$$

: Good

Bramble-Hilbert Lemma

Lemma Let  $\hat{T}$  be the reference triangle

Let  $u \in H^{k+1}(\hat{T})$

Then, we have

$$\inf_{v \in P^k(\hat{T})} \|u - v\|_{H^m(\hat{T})} \leq C |u|_{H^{k+1}(\hat{T})} \quad \forall m \leq k+1$$

Note  $(u \in H^k \Rightarrow |u|_{H^{k+1}(\hat{T})} = 0 \Rightarrow u \in P^k(\hat{T}))$  what?

$$|u|_{H^m(\hat{T})} = \sum_{|\alpha|+|\beta|=m} \|\partial_x^\alpha \partial_y^\beta u\|_{L^2(\hat{T})}$$

• Poincaré Inequality (for ref triangle)

Let  $u \in H^1(\hat{T})$

$$\left\| u - \frac{1}{|\hat{T}|} \int_{\hat{T}} u \right\|_{L^2(\hat{T})} \leq C |u|_{H^1(\hat{T})}$$

★  
← prelimit proof.

pf of Lemma

There exists  $v \in P^k(T)$  such that

$$\frac{1}{|\hat{T}|} \int_{\hat{T}} (\partial_x^{\alpha_1} \partial_y^{\alpha_2} v_k) = \frac{1}{|\hat{T}|} \int_{\hat{T}} (\partial_x^{\alpha_1} \partial_y^{\alpha_2} u)$$

i.e. find  $\alpha_i$  it always holds

pf

$$(v) \quad v_k = a_k x^k y^0 + a_{k-1} x^{k-1} y + a_{k-2} x^{k-2} y^2 + \dots + a_0 x^0 y^k$$

$$\partial_x^{\alpha_1} \partial_y^{\alpha_2} v_k = a_{\alpha_1} (\alpha_1)! (\alpha_2)!$$

$$(v) \Rightarrow \frac{1}{|\hat{T}|} \int_{\hat{T}} a_{\alpha_1} (\alpha_1)! (\alpha_2)! = \frac{1}{|\hat{T}|} \int_{\hat{T}} \partial_x^{\alpha_1} \partial_y^{\alpha_2} u$$

②

$$a_{\alpha_1} = \frac{1}{(\alpha_1)! (\alpha_2)! |\hat{T}|} \int_{\hat{T}} \partial_x^{\alpha_1} \partial_y^{\alpha_2} u$$

이제 같이  $\alpha_i$ 들을 계산하면 모든  $u \in H^{k+1}$ 에 대해 성립

$$|u - v_k|_{H^k(\hat{T})} = \left( \sum_{|\alpha|+|\beta|=k} \|\partial_x^\alpha \partial_y^\beta (u - v_k)\|_{L^2(\hat{T})}^2 \right)^{1/2} \leq C |u|_{H^{k+1}(\hat{T})}$$

Poincaré

Find  $v_{k-1} \in P^{k-1}(\hat{T})$  s.t.

$$\text{avg}(\partial_x^{\alpha_1} \partial_y^{\alpha_2} (u - v_{k-1})) = \text{avg}(\partial_x^{\alpha_1} \partial_y^{\alpha_2} v_{k-1}) \quad \text{for } |\alpha_1| + |\alpha_2| = k-1$$

$v_0 \in P^0(\hat{T})$

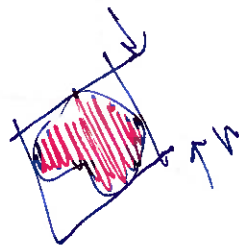
$$|u - (v_k + v_{k-1} + \dots + v_0)|_{H^m} = |u - (v_k + \dots + v_m)|_{H^m}$$

$$= |u - v_k - v_{k-1} - \dots - v_{m+1} - v_m|_{H^m}$$

$$\leq C |u - (v_k + v_{k-1} + \dots + v_{m+1})|_{H^{m+1}}$$

$$\leq C |u|_{H^{k+1}(\hat{T})}$$

$m \leq k+1$



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## Approximation properties.

last time we proved Bramble - Hilbert

- ① BH on  $\hat{T}$   
 ② BH on  $T$

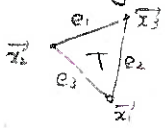
$$V_h^k = \{v \in C_0(\Omega) : v|_T \in P^k(T), \forall T \in \mathcal{T}_h\}$$

Generalize

The aim of this lecture is to prove

$$\inf_{v \in V_h^k} \|u - v\|_{H^1(\Omega)} \leq Ch^k \|u\|_{H^{k+1}(\Omega)}$$

$$h = \max_{T \in \mathcal{T}_h} \text{diam } T$$

Define the global interpolant of  $u$  which we denote by  $Iu \in V_h^k$ Locally  $Iu|_T \in P^k(T)$  defined via the degree of freedom  $\mathcal{I}$  of our finite element  $(T, P^k(T), \mathcal{I})$ Essentially the degrees of  $Iu$  match those of  $u$ 

$$Iu|_T \in P^k(T)$$

$$1) Iu(\vec{x}_i) = u(\vec{x}_i) \quad \text{for } i=1,2,3.$$

&lt;0 or 2 more

$$2) \int_{e_i} (Iu) g \, ds = \int_{e_i} u g \, ds \quad \text{for } g \in P^{k-1}(e_i) \quad i=1,2,3$$

normal at  $\vec{x}_1, \vec{x}_2, \vec{x}_3$ 

$$3) \int_T (Iu) w \, dx = \int_T u w \, dx \quad \forall w \in P^{k-1}(T)$$



$$l = [(Iu)|_{T^+} - (Iu)|_{T^-}]|_e \quad l \in P^k(e)$$

$$l(\vec{x}_1) = 0, \quad l(\vec{x}_2) = 0.$$

$$\int_e l g \, ds = 0 \quad \forall g \in P^{k-1}(e) \Rightarrow l \equiv 0 \Rightarrow \text{continuous through } e$$

pf) Let  $l \in P^k([0,1])$ 

$$l(0) = l(1) = 0$$

$$\int_0^1 l g \, dx = 0 \quad \forall g \in P^{k-1}([0,1]) \quad (*)$$

Since  $l \in P^k([0,1])$ ,  $l = x(1-x)m$  where  $m \in P^{k-2}([0,1])$ 

$$(*) \Rightarrow \int_0^1 l(x) m(x) \, dx = 0$$

$$\int_0^1 x(1-x) m^2(x) \, dx = 0$$

zero at 0, 1 only

$$m \equiv 0 \quad \therefore l \equiv 0.$$

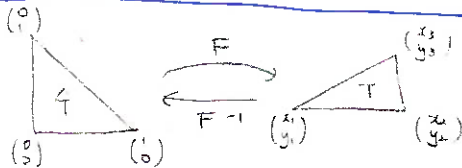
$$\inf_{v \in V_h^k} \|u - v\|_{H^1(\Omega)} \leq \|u - Iu\|_{H^1(\Omega)} = \left( \sum_{T \in \mathcal{T}_h} \|u - Iu\|_{H^1(T)}^2 \right)^{1/2} \leq Ch^k \left( \sum_{T \in \mathcal{T}_h} \|u\|_{H^{k+1}(T)}^2 \right)^{1/2} = Ch^k \|u\|_{H^{k+1}(\Omega)}$$

if the claim is true

Claim: For any  $T \in \mathcal{T}_h$ ,

$$\|u - Iu\|_{H^1(T)} \leq Ch^k \|u\|_{H^{k+1}(T)}$$

depends on reference triangle &amp; degree of polynomial

h = 101st Bramble-Hilbert, 2.9 in H1, h1/2 on the  $\hat{T}$ .

$$\begin{pmatrix} x \\ y \end{pmatrix} = F\left(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}\right) = B\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix} + \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} \quad \text{where} \quad B = \begin{bmatrix} x_2 - x_1 & x_3 - x_1 \\ y_2 - y_1 & y_3 - y_1 \end{bmatrix}$$



For any function  $\hat{w}$  defined on  $\hat{T}$ , we have a corresponding function defined on  $T$

$$w\left(F\left(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}\right)\right) = \hat{w}\left(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}\right) \quad w\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \hat{w}\left(F^{-1}\left(\begin{pmatrix} x \\ y \end{pmatrix}\right)\right)$$

Know (Lemma

$$\begin{aligned} |\hat{w}|_{H^m(\hat{T})} &\leq C \|B\|^m |\det B|^{-\frac{1}{2}} |w|_{H^m(T)} \\ |w|_{H^m(T)} &\leq C \|B^{-1}\|^m |\det B^{-1}|^{-\frac{1}{2}} |\hat{w}|_{H^m(\hat{T})} \end{aligned}$$

$$\|B\| = \sup_{\vec{z} \neq 0} \frac{\|B\vec{z}\|}{\|\vec{z}\|} \quad \text{where } \|\vec{z}\| = \sqrt{z_1^2 + z_2^2}$$

p.f)  $|\hat{w}|_{H^m(\hat{T})} = \left( \sum_{|\alpha|+|\beta|=m} \|\partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} \hat{w}(\hat{x}, \hat{y})\|_{L^2(\hat{T})} \right)^{1/2}$

$$\begin{aligned} \partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} \hat{w}(\hat{x}, \hat{y}) &= \partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} w\left(F\left(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}\right)\right) = \partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} w(b_{11}\hat{x} + b_{12}\hat{y} + x_1, b_{21}\hat{x} + b_{22}\hat{y} + y_1) \\ &= \sum_{\alpha=0}^{\alpha} \sum_{\beta=0}^{\beta} b_{11}^{\alpha} b_{12}^{\beta} b_{21}^{\alpha-\beta} b_{22}^{\beta-\alpha} \partial_{y_1}^{\alpha+\beta-(\alpha+\beta)} \partial_{x_1}^{\alpha+\beta} w\left(F\left(\begin{pmatrix} \hat{x} \\ \hat{y} \end{pmatrix}\right)\right) \end{aligned}$$

multiple chainrules

$$\begin{aligned} \|\partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} \hat{w}\|_{L^2(\hat{T})}^2 &= \int_{\hat{T}} (\partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} \hat{w})^2 d\hat{x} d\hat{y} \\ &= \int_T \left( \sum_{\alpha=0}^{\alpha} \sum_{\beta=0}^{\beta} b_{11}^{\alpha} b_{12}^{\beta} b_{21}^{\alpha-\beta} b_{22}^{\beta-\alpha} \partial_{y_1}^{\alpha+\beta-(\alpha+\beta)} \partial_{x_1}^{\alpha+\beta} w\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) \right)^2 |\det B|^{-1} dx dy \\ &\leq C (\max |b_{ij}|)^{2m} |\det B|^{-1} |w|_{H^m(T)}^2 \\ \|\partial_{\hat{y}}^{\alpha} \partial_{\hat{x}}^{\beta} \hat{w}\|_{L^2(\hat{T})} &\leq C (\max |b_{ij}|)^m |\det B|^{-\frac{1}{2}} |w|_{H^m(T)} \end{aligned}$$

depends on m

$$\|B \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}\| = \left\| \begin{pmatrix} b_{11} \\ b_{21} \end{pmatrix} \right\| \leq \sqrt{b_{11}^2 + b_{21}^2}$$

"In finite dimensions all norms are equivalent."

why

WTS  $\|u - Iu\|_{H_1(T)} \leq h^k \|u\|_{H^{k+1}}$

$$\leq C \|B\|^m |\det B|^{-\frac{1}{2}} |w|_{H^m(T)}$$

Back to the claim)

by lemma

$$\|u - Iu\|_{H_1(T)} \leq C \|B^{-1}\| |\det B^{-1}|^{-\frac{1}{2}} \|\hat{u} - I\hat{u}\|_{H_1(\hat{T})} = C \|B^{-1}\| |\det B^{-1}|^{-\frac{1}{2}} \|\hat{u} - \hat{I}\hat{u}\|_{H_1(\hat{T})}$$

$$\hat{u} - I\hat{u} = \hat{u} - \hat{I}\hat{u}$$

$$\hat{I}\hat{u} = \hat{I}\hat{u} \quad \leftarrow \text{can prove}$$

$$\hat{I}: C(\hat{T}) \rightarrow P^k(\hat{T})$$

ex:

$$\begin{cases} \hat{I}\hat{u}(\vec{x}_i) = \hat{u}(\vec{x}_i) \\ \int_{\hat{e}_i} \hat{I}\hat{u} \hat{g} = \int_{\hat{e}_i} \hat{u} \hat{g} & \forall \hat{g} \in P^{k-2}(\hat{e}_i) \\ \int_{\hat{T}} (\hat{I}\hat{u}) w = \int_{\hat{T}} \hat{u} w & \forall w \in P^{k-3}(\hat{T}) \end{cases}$$

$$|\hat{I}| = \sup_v \frac{\|\hat{I}v\|}{\|v\|}$$

For any  $\hat{v} \in P^k(\hat{T})$

$$|\hat{u} - \hat{I}\hat{u}|_{H_1(\hat{T})} \leq |\hat{u} - \hat{v}|_{H_1(\hat{T})} + |\hat{v} - \hat{I}\hat{u}|_{H_1(\hat{T})} \quad \hat{v} = \hat{I}\hat{v} \quad \text{by def of } \hat{I}$$

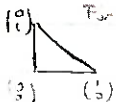
$$\leq |\hat{u} - \hat{v}|_{H_1(\hat{T})} + |\hat{I}(\hat{v} - \hat{u})|_{H_1(\hat{T})} \quad (*)$$

$$|\hat{I}(\hat{v} - \hat{u})|_{H_1(\hat{T})} \leq |\hat{I}| |\hat{v} - \hat{u}|_{H_1(\hat{T})}$$

operator norm

$$\text{note: } |\hat{I}\hat{w}|_{C(\hat{T})} \leq C |\hat{w}|_{C(\hat{T})}$$

$\hat{I}\hat{w}$  is  $\hat{w}$  at values of set of average of  $\hat{w}$  is bound. prove in HW



$$|\hat{I}\hat{w}| \leq \max_{i=1,2,3} |\hat{I}\hat{w}(\vec{x}_i)| = \max_{i=1,2,3} |\hat{w}(\vec{x}_i)| \leq \max_{\vec{x} \in T} |\hat{w}(\vec{x})| = |\hat{w}|_{C(\hat{T})}$$

$$|\hat{I}(\hat{v} - \hat{u})|_{H_1(\hat{T})} \leq C |\hat{I}(\hat{v} - \hat{u})|_{C(\hat{T})} \leq C |\hat{v} - \hat{u}|_{C(\hat{T})}$$

Need to pick  $\hat{I}$  carefully w/ a good norm  $\|\cdot\|_{H^1}$  s.t.  $\|\hat{I}u\|_{H^1} = \|u\|_{H^1} \leq \|u\|_{H^{k+1}}$

$$|\cdot|_{C(\hat{T})} = |\cdot|_{L^\infty}$$

\* Sobolev inequality

In two dimensions,

$$|\hat{w}|_{C(\hat{T})} \leq C \|\hat{w}\|_{H^1(\hat{T})}$$

finite element continuous mapping

pt5

$$(*) \Rightarrow |\hat{u} - \hat{I}\hat{u}|_{H^1(\hat{T})} \leq |\hat{u} - \hat{v}|_{H^1(\hat{T})} + C \|\hat{u} - \hat{v}\|_{H^2(\hat{T})}$$

$$|u - Iu|_{H^1(T)} \leq C \|B^{-1}\| |\det B^{-1}|^{-\frac{1}{2}} \inf_{\hat{v} \in P^k(\hat{T})} \|\hat{u} - \hat{v}\|_{H^2(\hat{T})}$$

Wise's lemma

$$\leq C \|B^{-1}\| |\det B^{-1}|^{-\frac{1}{2}} |\hat{u}|_{H^{k+1}(\hat{T})}$$

$$\leq C \|B^{-1}\| |\det B^{-1}|^{-\frac{1}{2}} \|B^{k+1}\| |\det B|^{-\frac{1}{2}} |u|_{H^{k+1}(T)}$$

$$|u - Iu|_{H^1(T)} \leq C \|B\| \|B^{-1}\| \|B\|^k |u|_{H^{k+1}(T)} \quad (**)$$

h and h-hat triangle inequality



Let  $P(T) = \sup \{ \text{diam}(S) : S \subseteq T, S \text{ is a circle} \}$

$$\hat{h} = \text{diam}(\hat{T}) = \sqrt{2} \quad h = \text{diam}(T) (= h_T)$$

$$\|B^{-1}\| \leq \frac{\hat{h}}{P(T)}$$

$$\|B\| \leq \frac{h}{P(\hat{T})}$$

See figure at p14



$$(\because) \|B^{-1}\| = \sup_{\|\vec{z}\|=1} \frac{\|B^{-1}\vec{z}\|}{\|\vec{z}\|} = \frac{1}{P(T)} \sup_{\|\vec{z}\|=P(T)} \|B^{-1}\vec{z}\| \leq \frac{\hat{h}}{P(T)}$$

Let  $\vec{z} \in \mathbb{R}^2, \|\vec{z}\| = P(T)$

There exist points  $\vec{m}, \vec{g} \in T$  s.t.  $\vec{m} - \vec{g} = \vec{z}$

$$F^{-1}(\vec{z}) = F^{-1}(\vec{m} - \vec{g}) = F^{-1}(\vec{m}) - F^{-1}(\vec{g}) = (B^{-1}\vec{m} + c) - (B^{-1}\vec{g} + c) = B^{-1}(\vec{m} - \vec{g})$$

$$\|F^{-1}(\vec{z})\| \leq \hat{h} \quad (\because \vec{m}, \vec{g} \in T)$$

$$\|F^{-1}(\vec{z})\| = \|B^{-1}(\vec{z})\|$$

$$(**) \Rightarrow |u - Iu|_{H^1(T)} \leq C \frac{h}{P(\hat{T})} \frac{\hat{h}}{P(T)} \left( \frac{h}{P(\hat{T})} \right)^k |u|_{H^{k+1}(T)} = C \left( \frac{h}{P(T)} \right) h^k |u|_{H^{k+1}(T)}$$

shape regularity:  $\frac{h}{P(T)} \leq c \quad \forall T \in \mathcal{T}_h$

$$\text{shape regularity: } \frac{h}{P(T)} \leq c \quad \forall T \in \mathcal{T}_h$$

skinny triangle:



10/24 Last time

$$V_h = \{ v \in C_0(\Omega) : v|_T \in P^k(T), \forall T \in \mathcal{T}_h \}$$

Let  $u \in H^{k+1}(\Omega)$

interpolation error

$$\inf_{v \in V_h} \|u - v\|_{H^1(\Omega)} \leq C h^{\frac{k+1}{2}} |u|_{H^{k+1}(\Omega)}$$

C is independent of u.

as long as we have  $\frac{\text{diam}(T)}{h} \leq M$

for every  $T \in \mathcal{T}_h$



independent of T.

shape regularity of  $\mathcal{T}_h$

같은 방법으로  $L^2(\Omega)$  norm에 대해서도 증명가능.

$$\Rightarrow \inf_{v \in V_h} \|u - v\|_{L^2(\Omega)} \leq Ch^{k+1} |u|_{H^{k+1}(\Omega)}$$

Generalize  $\Rightarrow \inf_{v \in V_h} \|u - v\|_{H^m(\Omega)} \leq Ch^{(k+1)-m} |u|_{H^{k+1}(\Omega)}$

$m=0,1$   
 $\sim$  m이 더 크면  $v$ 가  $H^m$ 에 속할거 알 수 x  $|u-v|_{H^0}$   
 But locally 3 triangle로 나눠 계산 가능

Ask Seonmin

- Today: 1) a few applications of  $\uparrow$   
 2) Elasticity  
 3) STOKES problem

$$\|u-v\|_{H_1}^2 = \|u-v\|_{L^2}^2 + |u-v|_{H_1}^2 \leq C(h^{k+1} + h^k) |u-v|_{H_1}^2$$

$$\otimes \begin{cases} -\nabla \cdot (A \nabla u) + ru = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

- Assumption 1)  $v^T A(x) v > \alpha |v|^2 \quad \forall x$  pos def  
 2)  $r(x) \geq 0 \quad \forall x$   
 3)  $|r(x)| < c, |A(x)| < c$  ( $\Rightarrow$  entry  $\neq$  bounded)

Weak form of  $\otimes$ :  $a(u, v) = L(v) \quad \forall v \in H_0^1(\Omega)$   
 where  $a(u, v) = \int_{\Omega} (A \nabla u \cdot \nabla v + ruv) dx$   
 $L(v) = \int_{\Omega} f \cdot v dx$

- $$\begin{cases} i) \|u\|_{H^1(\Omega)} \leq \beta a(u, u) \quad \forall u \in H^1(\Omega) \\ ii) a(u, v) \leq \gamma \|u\|_{H^1} \|v\|_{H^1} \quad \forall u, v \in H^1 \\ iii) L(v) \leq C \|v\|_{H^1} \quad \forall v \in H^1 \end{cases}$$

이 세 조건을 만족하면,  $\downarrow$  weak form prove

Let  $V_h = \{v \in C(\Omega), v|_T \in P^k(T), \forall T \in \mathcal{T}_h\}$

Let  $u_h \in V_h$  satisfy  $a(u_h, v) = L(v)$  for all  $v \in V_h$

$$\|u - u_h\|_{H^1(\Omega)} \leq C \inf_{v \in V_h} \|u - v\|_{H^1(\Omega)} \quad \text{Cea's}$$

$\leq Ch^k |u|_{H^{k+1}(\Omega)}$  as long as  $\{\mathcal{T}_h\}$  are shape regular

But,  $L^2$  norm을 이용하면

$$\|u - u_h\|_{L^2(\Omega)} \leq C \inf_{v \in V_h} \|u - v\|_{L^2(\Omega)} \leq Ch^{k+1} |u|_{H^{k+1}(\Omega)}$$

$\uparrow$  not true       $\uparrow$  true

but 비슷한 것 같음!  $\rightarrow$  유사한데 어떤 것 같음 1D case

General BH result  
 $|u-v|_{H^m} \leq C^{k-m+1} |u|_{H^k}$

Aubin - Nitsche Lemma

$$\|u - u_h\|_{L^2(\Omega)} \leq Ch \|u - u_h\|_{H^1(\Omega)}$$

pf) FIRST solve a dual problem

Let  $\psi \in H^1(\Omega)$  solve

$$\begin{cases} -\nabla \cdot (A \nabla \psi) + r\psi = u - u_h & \text{in } \Omega \\ \psi = 0 & \text{on } \partial\Omega \end{cases}$$

with assumption that  $\Omega$  is convex

dual  $a(u, v) = (f, v) \rightarrow a^*(u, v) = a(u, v)$

이제 dual 문제 solve  
 dual solution  $\psi$ 의 regularity 문제  
 dual의 interior estimate  $|u - u_h|_{H^2(\Omega)}$

Elliptic regularity:

$$\|\psi\|_{H^2(\Omega)} \leq C \|u - u_h\|_{L^2(\Omega)}$$

이제  $\psi$ 는  $\psi = u - u_h$ 로 바꿔서,  $u - u_h$ 의  $H^2$  norm을 구해보자!

$$\begin{aligned} \|u - u_h\|_{L^2(\Omega)}^2 &= \int_{\Omega} (u - u_h) [-v \cdot (A \nabla \psi) + r \psi] dx = a(u - u_h, \psi) \\ &= a(u - u_h, \psi - v) \quad \text{for any } v \in V_h \\ &\leq C \|u - u_h\|_{H^1(\Omega)} \|\psi - v\|_{H^1(\Omega)} \end{aligned}$$

$$\Rightarrow \|u - u_h\|_{L^2(\Omega)}^2 \leq C \|u - u_h\|_{H^1(\Omega)} \inf_{v \in V_h} \|\psi - v\|_{H^1(\Omega)}$$

B-4 Lemma

$$\leq C \|u - u_h\|_{H^1(\Omega)} h \|\psi\|_{H^2(\Omega)} \quad \text{Elliptic regularity}$$

$$\leq Ch \|u - u_h\|_{H^1(\Omega)} \|u - u_h\|_{L^2(\Omega)}$$

$$\Rightarrow \|u - u_h\|_{L^2(\Omega)} \leq Ch \|u - u_h\|_{H^1(\Omega)}$$

$$\Rightarrow L^2 \text{ norm도 비슷한 결과를 얻을 수 있다!} \quad \square$$

### Plane Elasticity

$\vec{u}$ : displacement

$\sigma$ : stresses

$$\varepsilon(\vec{u}) = \frac{\nabla \vec{u} + (\nabla \vec{u})^T}{2} \quad \text{strain tensor}$$

$$\text{where } \vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, \quad \nabla \vec{u} = \begin{bmatrix} \partial_x u_1 & \partial_x u_2 \\ \partial_y u_1 & \partial_y u_2 \end{bmatrix}$$

Elasticity equations

$$\begin{cases} \sigma = \mu \varepsilon(\vec{u}) + \mu \frac{\nu}{1-2\nu} \operatorname{div} u \mathbf{I} & \Omega \\ -\operatorname{div} \sigma = \vec{f} & \Omega \\ \vec{u} = 0 & \partial\Omega \end{cases} \quad \mu, \nu \text{ constant}, \quad \mathbf{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$\partial_i \sigma_{ij}$

$$\operatorname{div} \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{bmatrix} = \begin{bmatrix} \partial_x \sigma_{11} + \partial_y \sigma_{12} \\ \partial_x \sigma_{21} + \partial_y \sigma_{22} \end{bmatrix}$$

Eliminate  $\sigma$ ,

$$\begin{cases} -\operatorname{div} \left( \mu \varepsilon(\vec{u}) + \mu \frac{\nu}{1-2\nu} \operatorname{div} u \mathbf{I} \right) = \vec{f} & \Omega \\ \vec{u} = 0 & \partial\Omega \end{cases}$$

$$\vec{H}_0^1(\Omega) \equiv [H_0^1(\Omega)]^2 \quad (\text{7th element of } H_0^1(\Omega) \text{ is } \vec{u})$$

$\vec{u} \in \vec{H}_0^1(\Omega)$  solves

$$a(\vec{u}, \vec{v}) = \int_{\Omega} \vec{f} \cdot \vec{v} \quad \forall \vec{v} \in \vec{H}_0^1(\Omega)$$

$$\text{where } a(\vec{u}, \vec{v}) = \int_{\Omega} (\mu \varepsilon(\vec{u}) : \varepsilon(\vec{v}) + \mu \frac{\nu}{1-2\nu} \operatorname{div} \vec{u} \operatorname{div} \vec{v}) dx$$

$$\mathbf{M} : \mathbf{E} \equiv M_{11} E_{11} + M_{12} E_{12} + M_{21} E_{21} + M_{22} E_{22}$$

Natural finite element approximation

$$\vec{V}_h = \{ \vec{v} \in [C_0(\Omega)]^2 : \vec{v}|_T \in [P^1(T)]^2 \quad \forall T \in \mathcal{T}_h \}$$

Find  $\vec{u}_h \in \vec{V}_h$  s.t.

$$a(\vec{u}_h, \vec{v}) = \int_{\Omega} \vec{f} \cdot \vec{v} \quad \forall \vec{v} \in \vec{V}_h$$

(1)-(4) 2.3.5 5.2.10 4.1.5 3.1.2

$$1) \quad \alpha \|\vec{u}\|_{H^1(\Omega)}^2 \leq \mu \|\varepsilon(\vec{u})\|_{L^2(\Omega)}^2 \leq a(\vec{u}, \vec{u}) \quad (\text{coercivity})$$

Korn's inequality

$$2) a(\vec{u}, \vec{v}) \leq \mu \|\vec{u}\|_{H^1(\Omega)} \|\vec{v}\|_{H^1(\Omega)} + \mu \frac{\nu}{1-2\nu} \|\vec{u}\|_{H^1(\Omega)} \|\vec{v}\|_{H^1(\Omega)} \\ = \mu \left(1 + \frac{\nu}{1-2\nu}\right) \|\vec{u}\|_{H^1(\Omega)} \|\vec{v}\|_{H^1(\Omega)}$$

3) right-hand-side is bounded

$$\Rightarrow \|\vec{u} - \vec{u}_h\|_{H^1(\Omega)} \leq \underbrace{C h^k}_{\text{depends on } \mu, \nu} \|\vec{f}\|_{H^1(\Omega)}$$

depends on  $\mu, \nu$

$\mu \rightarrow 0, 1-2\nu \rightarrow 0$  되면 안됨

$$\bullet \nu \nearrow \frac{1}{2} \Rightarrow C \nearrow \infty$$

$\Rightarrow$  standard method does not do well when  $\nu \nearrow \frac{1}{2}$

그러나 이런 문제가 있을 때 사용하는 새로운 방법들이 많이 나왔어요

- 1) Mixed methods
- 2) Non-conforming methods
- 3) Projection methods
- 4) Red interpolation methods
- 5) Discontinuous Galerkin

$$\mu \int_{\Omega} \varepsilon(\vec{u}) : \varepsilon(\vec{v}) + \frac{\mu\nu}{1-2\nu} \int_{\Omega} \operatorname{div} \vec{u} \operatorname{div} \vec{v} = \int_{\Omega} \vec{F} \cdot \vec{v}$$

Define  $p = \frac{\mu\nu}{1-2\nu} \operatorname{div} \vec{u}$

$$\Rightarrow \begin{cases} \mu \int_{\Omega} \varepsilon(\vec{u}) : \varepsilon(\vec{v}) + \int_{\Omega} p \operatorname{div} \vec{v} = \int_{\Omega} \vec{F} \cdot \vec{v} & \forall \vec{v} \in \vec{H}_0^1(\Omega) \\ \int_{\Omega} (\operatorname{div} \vec{u}) \varphi - \frac{1-2\nu}{\mu\nu} \int_{\Omega} p \varphi = 0 & \forall \varphi \in L^2(\Omega) \end{cases}$$

Limiting case  $\nu \rightarrow \frac{1}{2}$ ,

$$\begin{cases} -\Delta \vec{u} - \nabla p = \vec{F} \\ \operatorname{div}(\vec{u}) = 0 \end{cases}$$

integrals of unit mass

: STOKES problem

Simplify  $\rightarrow \begin{cases} -\Delta \vec{u} - \nabla p = \vec{F} \\ \operatorname{div} \vec{u} = 0 \end{cases}$

: saddle-point problem. (variational form is this form)

$$\int_{\Omega} \nabla \vec{u} : \nabla \vec{v} + \int_{\Omega} p \operatorname{div} \vec{v} = \int_{\Omega} \vec{F} \cdot \vec{v} \quad \forall \vec{v} \in \vec{H}_0^1(\Omega)$$

$$\int_{\Omega} \operatorname{div} \vec{u} \varphi = 0 \quad \vec{F} \in L^2(\Omega) = \{ \vec{F} \in L^2(\Omega) \mid \int_{\Omega} \vec{F} \cdot \vec{x} \, dx = 0 \}$$

uniqueness:  $\vec{u} \mapsto \vec{u} + \vec{c}$

→ 변하지 않음!  
→ define  $\vec{u}$ 의  
가장 작은  
( $\vec{u} = \vec{c}$  일 때는 0)  
( $\vec{u} = 0$  일 때는 0)

Stability result

Let  $\vec{v} = \vec{u}$

$$\|\nabla \vec{u}\|_{L^2(\Omega)}^2 + \int_{\Omega} p \operatorname{div} \vec{u} = \int_{\Omega} \vec{F} \cdot \vec{u} \leq \|\vec{F}\|_{L^2(\Omega)} \|\vec{u}\|_{L^2(\Omega)}$$

Gauß-Schwarz

$$\leq \|\vec{F}\|_{L^2(\Omega)} \|\vec{u}\|_{L^2(\Omega)} \leq \|\vec{F}\|_{L^2(\Omega)} C \|\nabla \vec{u}\|_{L^2(\Omega)}$$

→ Poincaré inequality

$$\Rightarrow \|\nabla \vec{u}\|_{L^2(\Omega)} \leq \|\vec{F}\|_{L^2(\Omega)}$$

finite element  $u$ 의 bound  $\Rightarrow$  stable

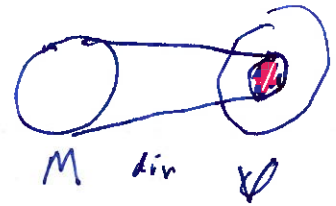
Lemma Let  $p \in L^2(\Omega)$

There exists  $\vec{v} \in H_0^1(\Omega)$  such that

$$\text{div } \vec{v} = p \text{ and } \|\vec{v}\|_{H^1(\Omega)} \leq C \|p\|_{L^2(\Omega)} \text{ where } C \text{ is independent of } p$$

$$\begin{aligned} \int_{\Omega} p^2 dx &= \int_{\Omega} \text{div } \vec{v} \cdot p = \int_{\Omega} \vec{F} \cdot \vec{v} - \int_{\Omega} \nabla \vec{u} : \nabla \vec{v} \\ &\leq \|\vec{F}\|_{L^2(\Omega)} \|\vec{v}\|_{L^2(\Omega)} + \|\nabla \vec{u}\|_{L^2(\Omega)} \|\nabla \vec{v}\|_{L^2(\Omega)} \\ &\leq C \|\vec{F}\|_{L^2(\Omega)} (\|\vec{v}\|_{L^2(\Omega)} + \|\nabla \vec{v}\|_{L^2(\Omega)}) \\ &\leq C \|\vec{F}\|_{L^2(\Omega)} \|\vec{v}\|_{H^1(\Omega)} \\ &\leq C \|\vec{F}\|_{L^2(\Omega)} \|p\|_{L^2(\Omega)} \quad \text{Lemma} \\ \Rightarrow \|p\|_{L^2(\Omega)} &\leq C \|\vec{F}\|_{L^2(\Omega)} \end{aligned}$$

$$\Rightarrow \|\nabla \vec{u}\|_{L^2(\Omega)} + \|p\|_{L^2(\Omega)} \leq C \|\vec{F}\|_{L^2(\Omega)}$$



Note  $\star H_0^1(\Omega) \xrightarrow{\text{div map}} L^2(\Omega)$

div. map onto  $L^2$  mapping  $\vec{v} \mapsto \text{div } \vec{v}$

roughly speaking,  $\vec{v}_h \xrightarrow{\text{div}} M_h$  이걸 보면 하긴 쉽지만, 마치 continuous case에서 했듯이

velocity space  $\uparrow$  pressure space

Let  $\vec{v}_h \in H_0^1(\Omega)$ ,  $p_h \in M_h$

FINITE ELEMENT approximation

FIND  $\vec{u}_h \in \vec{v}_h$ ,  $p_h \in M_h$  such that

$$\begin{aligned} \int_{\Omega} \nabla \vec{u}_h : \nabla \vec{v} + \int_{\Omega} p_h \text{div } \vec{v} &= \int_{\Omega} \vec{F} \cdot \vec{v} \quad \forall \vec{v} \in \vec{v}_h \\ \int_{\Omega} (\text{div } \vec{u}_h) q &= 0 \quad \forall q \in M_h \end{aligned}$$

symmetric but not positive definite

Uniqueness

(uniqueness in a finite class  $\Rightarrow$  existence)

p.f) Let  $\vec{F} = 0$ ,  $\vec{v} = \vec{u}_h$

$$\|\nabla \vec{u}_h\|_{L^2(\Omega)} + \int_{\Omega} p_h \text{div } \vec{u}_h = 0$$

$$\|\nabla \vec{u}_h\|_{L^2(\Omega)} = 0$$

$$\Rightarrow \nabla \vec{u}_h = 0$$

$$\Rightarrow \vec{u}_h = \text{const. but vanishes at boundaries} \Rightarrow \vec{u}_h = 0$$

$$\vec{u}_h = 0 \Rightarrow \int_{\Omega} p_h \text{div } \vec{v} = 0 \quad \forall \vec{v} \in \vec{v}_h$$

If we can find  $\vec{v} \in \vec{v}_h$  so that  $\text{div } \vec{v} = p_h$ , then  $p_h = 0$

$$\vec{v}_h \xrightarrow{\text{div}} M_h$$

compatible condition

div map of onto가 E에 있을 때,  $p_h = 0 \Rightarrow$  uniqueness

eg)  $\vec{v}_h = \{\text{piecewise linear}\}$ ,  $M_h = \{\text{piecewise constant}\}$

or  $\vec{v}_h$  onto map of all  $\vec{v} \in H_0^1$  that can find the number of triangles  $\times 2$   $\Rightarrow$   $M_h$   $\Rightarrow$  uniqueness

Wrong, see next page

10/31

## Stokes FINITE Elements

$$\begin{cases} -\Delta \vec{u} - \nabla p = \vec{f} & \Omega \\ \operatorname{div} \vec{u} = 0 & \Omega \\ \vec{u} = 0 & \partial\Omega \end{cases}$$

$$\begin{aligned} \int \frac{\partial p}{\partial x} v &= \int p \frac{\partial v}{\partial x} \\ \int \frac{\partial p}{\partial y} v &= \int p \frac{\partial v}{\partial y} \\ \int \frac{\partial p}{\partial z} v &= \int p \frac{\partial v}{\partial z} \end{aligned}$$

$$p \in L^2(\Omega) = \{f \in L^2(\Omega) : \int_{\Omega} f \, dx = 0\}$$

• Weak form:

 $u \in H_0^1(\Omega), p \in L^2(\Omega)$  satisfies

$$(\nabla \vec{u}, \nabla \vec{v}) + (p, \operatorname{div} \vec{v}) = (\vec{f}, \vec{v})$$

$$(\operatorname{div} \vec{u}, f) = 0 \quad \text{for all } \vec{v} \in H_0^1(\Omega) \text{ and } f \in L^2(\Omega)$$

• Finite element approximation

$$\vec{u}_h \in \vec{V}_h, p_h \in M_h \quad (\vec{V}_h \in H_0^1(\Omega), M_h \in L^2(\Omega)) \quad \leftarrow \text{discrete spaces of } \vec{u} \text{ and } p$$

$$(1) \quad (\nabla \vec{u}_h, \nabla \vec{v}) + (p_h, \operatorname{div} \vec{v}) = (\vec{f}, \vec{v})$$

$$(2) \quad (\operatorname{div} \vec{u}_h, f) = 0 \quad \text{for all } \vec{v} \in \vec{V}_h \text{ and } f \in M_h$$

• There has to be a compatible condition satisfied between two spaces  $\vec{V}_h$  and  $M_h$ FE approximation of (well-posed (exist & unique) discrete condition for discrete spaces  
stable

## Start with Uniqueness

Assume  $\vec{f} = 0$ Let  $\vec{v} = \vec{u}_h$  in (1)

$$\Rightarrow (\nabla \vec{u}_h, \nabla \vec{u}_h) + (p_h, \operatorname{div} \vec{u}_h) = (\vec{f}, \vec{u}_h) = 0$$

$$\|\nabla \vec{u}_h\|_{L^2(\Omega)}^2 = - (p_h, \operatorname{div} \vec{u}_h)$$

Let  $f = p_h$  in (2)

$$\Rightarrow \|\nabla \vec{u}_h\|_{L^2(\Omega)}^2 = 0 \quad \Rightarrow \nabla \vec{u}_h = 0 \quad \Rightarrow \vec{u}_h = \text{const} \quad \begin{array}{l} \vec{u}_h = 0 \text{ on boundary} \\ \downarrow \\ \vec{u}_h = 0 \end{array}$$

 $\vec{u}_h = 0$  implies  $(p_h, \operatorname{div} \vec{v}) = 0$  for all  $\vec{v} \in \vec{V}_h$ 

We are going to assume the following:

There exists a constant  $\beta$  such that given  $f \in M_h$ , there exists a  $\vec{v} \in \vec{V}_h$ 

$$\beta \|f\|_{L^2(\Omega)} \leq \frac{(f, \operatorname{div} \vec{v})}{\|\vec{v}\|_{H^1(\Omega)}}$$

Let  $f = p_h$  in assumption. Then there exists  $\vec{v} \in \vec{V}_h$ 

$$\beta \|p_h\|_{L^2(\Omega)} \leq \frac{(p_h, \operatorname{div} \vec{v})}{\|\vec{v}\|_{H^1(\Omega)}} = 0$$

$$\Rightarrow \|p_h\|_{L^2(\Omega)} = 0$$

$$\Rightarrow p_h = 0$$

## Inf-sup stable spaces

saddle-point property

Def  $\vec{V}_h$  and  $M_h$  are a pair of inf-sup stable spaces as long as there exists a constant  $\beta > 0$  s.t.

$$\beta \|f\|_{L^2(\Omega)} \leq \sup_{\substack{\vec{v} \in \vec{V}_h \\ \vec{v} \neq 0}} \frac{(f, \operatorname{div} \vec{v})}{\|\vec{v}\|_{H^1(\Omega)}} \quad \forall f \in M_h$$

$$0 < \beta < \inf_{\substack{f \in M_h \\ f \neq 0}} \sup_{\substack{\vec{v} \in \vec{V}_h \\ \vec{v} \neq 0}} \frac{(f, \operatorname{div} \vec{v})}{\|f\|_{L^2(\Omega)} \|\vec{v}\|_{H^1(\Omega)}} \quad \text{or statement of inf-sup} \rightarrow \max \text{ of } \frac{(f, \operatorname{div} \vec{v})}{\|f\|_{L^2(\Omega)} \|\vec{v}\|_{H^1(\Omega)}} \text{ over } \vec{v} \text{ for fixed } f$$

or statement of inf-sup  $\rightarrow \max$  of  $\frac{(f, \operatorname{div} \vec{v})}{\|f\|_{L^2(\Omega)} \|\vec{v}\|_{H^1(\Omega)}}$  over  $\vec{v}$  for fixed  $f$   
if  $M_h$  and  $\vec{V}_h$  are finite spaces  $\Rightarrow$  max is attained  
if  $M_h$  contains  $\vec{V}_h$  (constant  $\beta$ ) then sup is



# Natural Choice of $\vec{V}_h$ & $M_h$

$$\vec{V}_h = \{ \vec{v} \in H_0^1(\Omega) : \vec{v}|_T \in \vec{P}_{k+1}(T), \forall T \in \mathcal{T}_h \}$$

$$M_h = \{ f \in L^2(\Omega) : f|_T \in P_k(T), \forall T \in \mathcal{T}_h \}$$

Given  $g \in M_h$ ,  $\exists \vec{v} \in \vec{V}_h$  s.t.  $\text{div } \vec{v} = g$  : Not true always (not satisfied by stable spaces)

div  $\vec{v}$  has one dimension less than  $M_h$  (not satisfied by stable spaces)

Example

$\vec{V}_h$  = the same as above

$$M_h = \{ m \in L^2(\Omega) : m|_T \in P_{k+1}(T), \forall T \in \mathcal{T}_h \}$$

$$(M_h) \text{ div } \vec{V}_h$$

이제

$\leftarrow V_h$ 를 increase 하는 것으로 볼 수 있음 이걸에 대한

size는 220

Lemma Given  $g \in L^2(\Omega)$ , there exists  $\vec{v} \in \vec{H}_0^1(\Omega)$  s.t.

$$\begin{cases} \text{div } \vec{v} = g \\ \|\vec{v}\|_{H^1(\Omega)} \leq C \|g\|_{L^2(\Omega)} \end{cases} \quad \text{the constant is independent of } g$$

Let  $g \in M_h$  By lemma, there exists  $\vec{v} \in \vec{H}_0^1(\Omega)$

$$\begin{cases} \text{div } \vec{v} = g \\ \|\vec{v}\|_{H^1(\Omega)} \leq C \|g\|_{L^2(\Omega)} \end{cases}$$

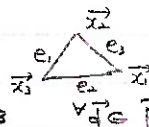
( $\vec{v} \in \vec{V}_h$  is better, but not x, project. of  $\vec{v} = \pi \vec{v} \in \vec{V}_h$  & satisfy  $\text{div } \pi \vec{v} = g$ )

Define  $\pi \vec{v}|_T \in \vec{P}_{k+1}(T)$

$$\text{s.t. } \pi \vec{v}(\vec{x}_i) = \vec{v}(\vec{x}_i) \text{ for } i=1,2,3$$

$$\int_{e_i} (\pi \vec{v}) \cdot \vec{a} \, ds = \int_{e_i} \vec{v} \cdot \vec{a} \, ds \text{ for } i=1,2,3$$

$$\int_T \pi \vec{v} \cdot \vec{w} \, dx = \int_T \vec{v} \cdot \vec{w} \, dx \quad \forall \vec{w} \in \vec{P}_{k+2}(T)$$



(HW - Prob 2)

(or you can use continuity of  $\pi$ )

$$\Rightarrow \pi \vec{v} \in \vec{V}_h$$

Part 1

Condition to get  $\pi$

$$(\text{div } \pi \vec{v} - \text{div } \vec{v}, r) = 0$$

$$= \int_{\Omega} \text{div}(\pi \vec{v} - \vec{v}) r \, dx = \sum_{T \in \mathcal{T}_h} \int_T \text{div}(\pi \vec{v} - \vec{v}) r \, dx = - \sum_{T \in \mathcal{T}_h} \int_T (\pi \vec{v} - \vec{v}) \cdot \nabla r \, dx + \sum_{T \in \mathcal{T}_h} \int_{\partial T} (\pi \vec{v} - \vec{v}) \cdot \vec{n} r \, ds$$

integrate by parts

by (2)

$$\Rightarrow (\text{div } \pi \vec{v}, r) = (\text{div } \vec{v}, r) = (g, r) \quad \forall r \in M_h$$

If  $r = g$ ,

$$\|g\|_{L^2(\Omega)}^2 = (g, g) = (\text{div } \pi \vec{v}, g)$$

$$\|g\|_{L^2(\Omega)}^2 = \frac{(\text{div } \pi \vec{v}, g)}{\|g\|_{L^2(\Omega)}} = \frac{(g, \text{div } \pi \vec{v})}{\|\pi \vec{v}\|_{H^1(\Omega)}}$$

$$\frac{\|\pi \vec{v}\|_{H^1(\Omega)}}{\|g\|_{L^2(\Omega)}}$$

Part 2

Find norm so we can bound

$$\text{Assume } \frac{\|\pi \vec{v}\|_{H^1(\Omega)}}{\|g\|_{L^2(\Omega)}} \leq \frac{1}{\beta} \quad (\beta > 0)$$

$\leftarrow$  need to prove

$$\text{Then, } \beta \|g\|_{L^2(\Omega)} \leq \frac{(g, \text{div } \pi \vec{v})}{\|\pi \vec{v}\|_{H^1(\Omega)}}$$

(satisfy  $\beta$ -up condition)

$$\text{Need to prove: } \|\pi \vec{v}\|_{H^1(\Omega)} \leq \frac{1}{\beta} \|g\|_{L^2(\Omega)}$$

$$\|\pi \vec{v}\|_{H^1(\Omega)} \leq C \|\vec{v}\|_{H^1(\Omega)} \leq C \|g\|_{L^2(\Omega)} \quad \text{take } \beta = \frac{1}{C}$$

이부분 증명 필요

what's this say?



$\Pi$  define 이 문제!

$\vec{V} \in H_0^1(\Omega)$  is continuity field  $\times \Rightarrow$  point value  $\rightarrow$  0.5 정도

$\Rightarrow \Pi \vec{V}(\vec{x}_i) = \vec{V}(\vec{x}_i)$  for  $i=1,2,3$  is 문제 있음



continuous 이면 이 point value 는 비슷한 부분  $\approx P_i$  average로 approximate 할 수 있겠지요 (다른 방법도 있겠지요)

edge에 있는 값을 average 할 수도

$$\Rightarrow R\vec{V}(\vec{x}_i) = \frac{1}{|P_i|} \int_{P_i} \vec{V}(\vec{x}_i) dx$$

★  $\Pi \vec{V}(\vec{x}_i) = R\vec{V}(\vec{x}_i)$  로 바꾸자

If  $\vec{x}_i \in \partial\Omega$ ,  $R\vec{V}(\vec{x}_i) = 0$  로 정함

$\Rightarrow$  이렇게 하면 example로 주어진 것이 inf-sup 만족

Clement, Scott-Zhang 등이 고안.

매우 중요! in FEM

There are many other inf-sup stable spaces.

For example,  $M_h \subseteq C_0(\Omega)$  [Taylor-Hood]

General Theory for stable pairs problems

$$\begin{cases} a(u,v) + b(p,v) = L_1(v) \\ b(q,u) = L_2(q) \end{cases}$$

equation이 변하면 inf-sup condition도 변한다 우리가 한 것은 for STOKES prob.

Then Let  $\vec{u} \in H_0^1(\Omega)$ ,  $p$  solve

$$-\Delta \vec{u} - \nabla p = f \quad \Omega$$

$$\operatorname{div} \vec{u} = 0 \quad \partial\Omega$$

$u, p$ 가 best approximation이 되는 의미!

$$\textcircled{*} \leq C(h^{k+1} \|\vec{u}\|_{H^{k+2}(\Omega)} + h^k \|p\|_{H^{k+1}(\Omega)})$$

or balanced  
unbalanced too much work  
balance 5:3 정도 되면

and let  $\vec{u}_h \in \vec{V}_h$ ,  $p_h \in M_h$  be finite element approximation where  $\vec{V}_h \in M_h$  are inf-sup stable pair of spaces

$$\text{Then, } \|\nabla(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)} + \|p - p_h\|_{L^2(\Omega)} \leq C \inf_{\substack{\vec{V} \in \vec{V}_h \\ q \in M_h}} (\|\nabla(\vec{u} - \vec{V})\|_{L^2(\Omega)} + \|p - q\|_{L^2(\Omega)}) \leq \textcircled{*}$$

$$\text{pf) } \|\nabla(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)}^2 = (\nabla(\vec{u} - \vec{u}_h), \nabla(\vec{u} - \vec{u}_h))$$

$$= (\nabla(\vec{u} - \vec{u}_h), \nabla(\vec{u} - \vec{V})) + (\nabla(\vec{u} - \vec{u}_h), \nabla(\vec{V} - \vec{u}_h)) \quad \text{where } \vec{V} \in \vec{V}_h$$

$$\text{weak form: } (\nabla \vec{u}, \nabla \vec{V}) + (p, \operatorname{div} \vec{V}) = (f, \vec{V}), \quad \text{finite-element app: } (\nabla \vec{u}_h, \nabla \vec{V}) + (p_h, \operatorname{div} \vec{V}) = (f, \vec{V})$$

$$(\operatorname{div} \vec{u}_h, q) = 0 \quad \forall \vec{V} \in \vec{V}_h(\Omega), q \in L_0^2(\Omega) \quad (\operatorname{div} \vec{u}_h, q) = 0 \quad \forall \vec{V} \in \vec{V}_h, q \in M_h$$

$$\Rightarrow (\nabla(\vec{u} - \vec{u}_h), \nabla \vec{V}) + (p - p_h, \operatorname{div} \vec{V}) = 0$$

$$(\operatorname{div}(\vec{u} - \vec{u}_h), q) = 0 \quad \text{for all } \vec{V} \in \vec{V}_h, q \in M_h$$

$$\Rightarrow \textcircled{*} (\nabla(\vec{u} - \vec{u}_h), \nabla(\vec{V} - \vec{u}_h)) = - (p - p_h, \operatorname{div}(\vec{V} - \vec{u}_h)) \quad \text{since } \vec{V} - \vec{u}_h \in \vec{V}_h$$

$$= - (p - p_h, \operatorname{div}(\vec{V} - \vec{u}_h)) - (p - p_h, \operatorname{div}(\vec{u} - \vec{u}_h))$$

$$= - (p - p_h, \operatorname{div}(\vec{V} - \vec{u}_h)) - (p - q, \operatorname{div}(\vec{u} - \vec{u}_h)) \quad \forall q \in M_h$$

$$\Rightarrow \|\nabla(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)}^2 \leq \|\nabla(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)} \|\nabla(\vec{u} - \vec{V})\|_{L^2(\Omega)} + \|p - p_h\|_{L^2(\Omega)} \|\operatorname{div}(\vec{V} - \vec{u}_h)\|_{L^2(\Omega)} \\ + \|p - q\|_{L^2(\Omega)} \|\operatorname{div}(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)}$$

$$\text{Assume for a second, } \|p - p_h\|_{L^2(\Omega)} \leq C \|\nabla(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)} + C \|p - q\|_{L^2(\Omega)} \quad (**)$$

$$\text{Then, } \|\nabla(\vec{u} - \vec{u}_h)\|_{L^2(\Omega)}^2 \leq C (\|\nabla(\vec{u} - \vec{V})\|_{L^2(\Omega)} + \|p - q\|_{L^2(\Omega)}) \quad \forall \vec{V} \in \vec{V}_h, q \in M_h$$

$$(*) \sqrt{a^2 + b^2 + c^2 + d^2} \leq C(a + b + c + d) \quad \text{이런 것들이 나오는데, 이걸로}$$

$$\begin{aligned}
 \|p - p_h\|_{L^2(\Omega)} &\leq \|p - \tilde{p}\|_{L^2(\Omega)} + \|\tilde{p} - p_h\|_{L^2(\Omega)} \\
 \Rightarrow \forall \nabla \in \tilde{V}_h \text{ so that } \beta \|\tilde{p} - p_h\|_{L^2(\Omega)} &\leq \frac{(\tilde{p} - p_h, \operatorname{div} \nabla)}{\|\nabla\|_{H^1(\Omega)}} = \frac{(\tilde{p} - p, \operatorname{div} \nabla)}{\|\nabla\|_{H^1(\Omega)}} + \frac{(p - p_h, \operatorname{div} \nabla)}{\|\nabla\|_{H^1(\Omega)}} \\
 &\quad \uparrow \text{inf-sup} \\
 &\leq \frac{\|\tilde{p} - p\|_{L^2(\Omega)} \|\operatorname{div} \nabla\|_{L^2}}{\|\nabla\|_{H^1(\Omega)}} + \frac{\|\nabla(\tilde{u} - u_h)\|_{L^2(\Omega)} \|\nabla(\nabla)\|_{L^2(\Omega)}}{\|\nabla\|_{H^1(\Omega)}} \\
 &\quad \text{Cauchy-Schwarz} \\
 &\leq \|\tilde{p} - p\|_{L^2(\Omega)} + \|\nabla(\tilde{u} - u_h)\|_{L^2(\Omega)} \\
 \Rightarrow \|p - p_h\|_{L^2(\Omega)} &\leq (1 + \frac{1}{\beta}) \|p - \tilde{p}\|_{L^2(\Omega)} + \frac{1}{\beta} \|\nabla(\tilde{u} - u_h)\|_{L^2(\Omega)}
 \end{aligned}$$

→ (44) in p23

(행방 이라 했을 때) ① upper bound를 찾고 ② inf-sup을 D를 bound

### Back to Elasticity

$$(\varepsilon(\tilde{u}), \varepsilon(\tilde{v})) + \frac{1}{\lambda} (\operatorname{div} \tilde{u}, \operatorname{div} \tilde{v}) = (\tilde{f}, \tilde{v})$$

Define  $p = \frac{1}{\lambda} \operatorname{div}(\tilde{u})$

$$(\varepsilon(\tilde{u}), \varepsilon(\tilde{v})) + (p, \operatorname{div} \tilde{u}) = (\tilde{f}, \tilde{v})$$

$$(\operatorname{div} \tilde{u}, q) - \lambda(p, q) = 0$$

$\lambda \rightarrow 0$  then STOKES problem

Let  $\tilde{V}_h$  and  $M_h$  be a stable inf-sup pair

Find  $\tilde{u}_h \in \tilde{V}_h, p_h \in M_h$  satisfying

$$(\varepsilon(\tilde{u}_h), \varepsilon(\tilde{v})) + (p_h, \operatorname{div} \tilde{u}_h) = (\tilde{f}, \tilde{v}) \quad \text{--- (44*)}$$

$$(\operatorname{div} \tilde{u}_h, q) - \lambda(p_h, q) = 0$$

$$\forall v \in \tilde{V}_h, q \in M_h$$

이 term의 양이만 같을 경우 양쪽 < 양쪽

$$\Rightarrow \|\nabla(\tilde{u} - \tilde{u}_h)\|_{L^2(\Omega)} + \|p - p_h\|_{L^2(\Omega)} \leq \inf_{\tilde{u} \in \tilde{V}_h, p \in M_h} (\|\nabla(\tilde{u} - u)\|_{L^2} + \|p - \tilde{p}\|_{L^2})$$

independent of  $\lambda$

이 method가 왜든 다 복잡하네...

$$(\operatorname{div} \tilde{u}_h - \lambda p_h, q) = 0 \quad \text{for all } q \in M_h$$

$$\text{Define } P: L^2(\Omega) \rightarrow M_h \quad \text{so} \quad (Pq, q) = (q, q) \quad \forall q \in M_h \quad (L^2 \text{ projection})$$

$$\Rightarrow P(\operatorname{div} \tilde{u}_h - \lambda p_h) = 0$$

$$\Rightarrow P(\operatorname{div} \tilde{u}_h) = P(\lambda p_h) = \lambda p_h$$

$$(44*) \Rightarrow (\varepsilon(\tilde{u}_h), \varepsilon(\tilde{v})) + \frac{1}{\lambda} (P \operatorname{div} \tilde{u}_h, P \operatorname{div} \tilde{v}) = (\tilde{f}, \tilde{v}) \quad \forall \tilde{v} \in \tilde{V}_h$$

and  $P$  is the  $L^2$  projection onto  $M_h$  and  $\tilde{V}_h$  and  $M_h$  is a stable inf-sup pair.

Projection method

$$(\varepsilon(\tilde{u}), \varepsilon(\tilde{v})) + \frac{1}{\lambda} (\operatorname{div} u, \operatorname{div} v) = 0$$

$$\tilde{V}_h = \{ \tilde{v} \in \tilde{V}_h, \tilde{v} \in P(\tau) \}$$

$$(\varepsilon(\tilde{u}_h), \varepsilon(\tilde{v})) + \frac{1}{\lambda} \frac{1}{|\tau|} \int_{\tau} (\operatorname{div} u) (\operatorname{div} \tilde{v}) dx = (\tilde{f}, \tilde{v})$$

$$(\varepsilon(\tilde{u}_h), \varepsilon(\tilde{v})) + \frac{1}{\lambda} \frac{1}{|\tau|} \int_{\tau} |\operatorname{div} u| |\operatorname{div} \tilde{v}| dx = (\tilde{f}, \tilde{v})$$

independent

midpoint rule under integration

not correct yet work

→  $L^2$  projection이랑 비슷

Under-integration method

$$\begin{cases} -\Delta u = f & \Omega \\ u = 0 & \partial\Omega \end{cases}$$

$\Omega$  is a polygon.

Let  $\{T_h\}_h$  is a family of triangulations of  $\Omega$ .

So far, we have only considered methods such that  $V_h \subseteq H_0^1(\Omega)$

Can we have that a method s.t.  $V_h \not\subseteq H_0^1(\Omega)$ ? Yes! (자랑하셔...)

why? int-sup important

Stokes

stability & error analysis

controlling p w/v etc

### Example of a non-conforming method (Crouzeix-Raviart 1973)

Let  $E_h$  = the collection of edges of  $T_h$

$$E_h = E_h^I \cup E_h^B$$

where  $E_h^I$  = all interior edges of  $T_h$

$E_h^B$  = all boundary edges of  $T_h$

C-R space  $V_h = \{v \in L^2(\Omega) : v|_T \in P_1(T) \ \forall T \in T_h$

$v$  is continuous at midpoint of all edges  $e \in E_h^I$   
and  $v = 0$  at midpoint of all edges  $e \in E_h^B$

(#(edges) > #(vertex) : Euler 공식이...)

$\Rightarrow V_h$ 의 dof의 edge # 보다 vertex #로 dof 결정하는 것은 가능한 것보다 dof이 크다.



$$v^+ = v|_{T^+}, \quad v^- = v|_{T^-}$$

$$v^+(x_m) = v^-(x_m)$$

(Yes)

$$\int_e v^+ ds = \int_e v^- ds$$

$$m(e) v^+(x_m) = m(e) v^-(x_m)$$

since  $v|_T \in P_1(T)$  linear이라

midpoint가 exact value

Non-conforming approximation  $u_h \in V_h$  satisfies

$$a(u_h, v) = (f, v) \quad \forall v \in V_h$$

where  $a(u_h, v) = \int_{\Omega} \nabla_h u_h \cdot \nabla_h v \, dx$ ,  $(f, v) = \int_{\Omega} f v \, dx$

$$\nabla_h v|_T = [\nabla(v|_T)]|_T$$

내부에서 ∇를 구할 것

derivative gradient across triangle

이런 것을 생각할 수 x  $\Rightarrow a(u_h, v)$ 의 새것은 정칙인

\* The method is well-posed (existence, uniqueness, the sol depends continuously on the data)

The system defining  $u_h$  is a square finite dimensional system.  $\Leftarrow$ ?

Therefore, it is enough to show uniqueness

Let  $f \equiv 0$ , we need to show that  $u_h \equiv 0$

Let  $v = u_h$ ,  $a(u_h, u_h) = 0$

$$\int_{\Omega} \nabla_h u_h \cdot \nabla_h u_h \, dx = 0 \Rightarrow \nabla_h u_h = 0$$

$$u_h|_T = \text{constant} \quad \forall T \in T_h$$

$\Rightarrow u_h \equiv C$  on  $\Omega$  by the continuity at midpoint

$\Rightarrow u_h \equiv 0$  since  $u_h$  vanishes at midpoint of the boundary

Note. uniqueness 증명에 midpoint에서 continuity를 가질 필요 x. 이는 원래의 정해에서 continuity를 주므로 ok  
accuracy의 영향

Inconsistency

Let  $u \in H_0^1(\Omega)$  solve  $-\Delta u = f$

Does it follow that

$$a(u, v) = (f, v) \quad \forall v \in V_h$$

→ Not true (was true when  $V_h \subseteq H_0^1(\Omega)$ )

Let  $v \in V_h$

$$\int_{\Omega} -\Delta u v \, dx = \int_{\Omega} f v \, dx$$

$$\sum_{T \in \mathcal{T}_h} (-\int_T \Delta u v \, dx) = \int_{\Omega} f v \, dx$$

$$-\int_T \Delta u v \, dx = \int_T \nabla u \cdot \nabla v - \int_{\partial T} \frac{\partial u}{\partial n} v \, ds$$

$$\rightarrow \sum_{T \in \mathcal{T}_h} \left\{ \int_T \nabla u \cdot \nabla v \, dx - \int_{\partial T} \frac{\partial u}{\partial n} v \, ds \right\} = \int_{\Omega} f v \, dx$$

$$a(u, v) - \sum_{T \in \mathcal{T}_h} \int_{\partial T} \frac{\partial u}{\partial n} v \, ds = (f, v)$$

additional term inconsistency but not important...  
variational CRIME.

Error Analysis

$$\| \nabla_h(u - u_h) \|_{L^2(\Omega)}^2 = a(u - u_h, u - u_h)$$

$$= a(u - u_h, u - v) + a(u - u_h, v - u_h) \quad \text{for any } v \in V_h$$

$$= a(u - u_h, u - v) + a(u, v - u_h) - a(u_h, v - u_h)$$

$$= a(u - u_h, u - v) + a(u, v - u_h) - (f, v - u_h) \quad \text{since } v - u_h \in V_h$$

$$\leq |a(u - u_h, u - v)| + \frac{|a(u, v - u_h) - (f, v - u_h)|}{\| \nabla_h(v - u_h) \|_{L^2(\Omega)}} \| \nabla_h(v - u_h) \|_{L^2(\Omega)}$$

$$\leq |a(u - u_h, u - v)| + \sup_{w \in V_h} \frac{|a(u, w) - (f, w)|}{\| \nabla_h w \|_{L^2(\Omega)}} \| \nabla_h(v - u_h) \|_{L^2(\Omega)}$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} \| \nabla_h(u - u_h) \|_{L^2(\Omega)} \| \nabla_h(u - v) \|_{L^2(\Omega)} + I \left( \| \nabla_h(v - u) \|_{L^2(\Omega)} + \| \nabla_h(u - u_h) \|_{L^2(\Omega)} \right)$$

$$\leq \| \nabla_h(u - u_h) \|_{L^2(\Omega)} \left( \| \nabla_h(u - v) \|_{L^2(\Omega)} + I \right) + I \| \nabla_h(v - u) \|_{L^2(\Omega)} \quad 2ab \leq a^2 + b^2$$

$$\leq \frac{1}{2} \| \nabla_h(u - u_h) \|_{L^2(\Omega)}^2 + \frac{1}{2} \left( \| \nabla_h(u - v) \|_{L^2(\Omega)} + I \right)^2 + I \| \nabla_h(v - u) \|_{L^2(\Omega)}$$

$$\frac{1}{2} \| \nabla_h(u - u_h) \|_{L^2(\Omega)}^2 \leq \frac{1}{2} \left( \| \nabla_h(u - v) \|_{L^2(\Omega)} + I \right)^2 + I \| \nabla_h(v - u) \|_{L^2(\Omega)}$$

$$\leq \| \nabla_h(u - v) \|_{L^2(\Omega)}^2 + I^2 + I \| \nabla_h(v - u) \|_{L^2(\Omega)} \leq \left( \| \nabla_h(u - v) \|_{L^2(\Omega)} + I \right)^2$$

$$\stackrel{\frac{1}{2}(a+b)^2 \leq a^2 + b^2}{\leq}$$

$$\| \nabla_h(u - u_h) \|_{L^2(\Omega)} \leq \sqrt{2} \| \nabla_h(u - v) \|_{L^2(\Omega)} + \sqrt{2} I \quad \text{for any } v \in V_h$$

$$\leq \sqrt{2} \inf_{v \in V_h} \| \nabla_h(u - v) \|_{L^2(\Omega)} + \sqrt{2} I$$

was zero for conforming methods

of term of conforming method is zero. how non-conforming

hw) One can show that  $\inf_{v \in V_h} \| \nabla_h(u - v) \|_{L^2(\Omega)} \leq Ch |u|_{H^1(\Omega)}$  and approximation properties of  $\frac{1}{2}$  is zero but with new  $V_h$

Also we will show

$$I \leq Ch |u|_{H^1(\Omega)}$$

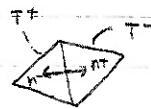
## Estimate for I

let  $w \in V_h$ 

$$|a(u, w) - (f, w)| = \left| \sum_{T \in \mathcal{T}_h} \int_{\partial T} \frac{\partial u}{\partial n} w \, ds \right|$$

If  $w$  is a scalar function $w$  define the jump on an edge  $e = T^+ \cap T^-$ 

$$\begin{aligned} [w] &= w|_{T^+} n^+ + w|_{T^-} n^- \\ &= n^+ (w|_{T^+} - w|_{T^-}) \end{aligned}$$



$$\begin{aligned} \sum_{T \in \mathcal{T}_h} \int_{\partial T} \frac{\partial u}{\partial n} w \, ds &= \sum_{e \in \mathcal{E}_h^i} \int_e \underbrace{[\nabla u] \cdot [w]}_{\text{average of } \nabla u \cdot (\vec{\sigma}|_e = \frac{1}{2}(\vec{\sigma}|_{T^+} + \vec{\sigma}|_{T^-}))} \, ds + \sum_{e \in \mathcal{E}_h^b} \int_e \nabla u \cdot (w \vec{n}) \, ds \\ \left( \int_{\partial T^+} \frac{\partial u}{\partial n} w + \int_{\partial T^-} \frac{\partial u}{\partial n} w \right) &= \int_e \nabla u \cdot n^+ w|_{T^+} + \int_e \nabla u \cdot n^- w|_{T^-} \\ &= \int_e \nabla u \cdot (n^+ w|_{T^+} + n^- w|_{T^-}) + \text{other edges} \end{aligned}$$

Since  $w \in V_h$ ,  $\int_e \vec{\sigma} \cdot [w] \, ds = 0$  for all  $e \in \mathcal{E}_h^i$  where  $\vec{\sigma} = \begin{bmatrix} \sigma_1 \\ \sigma_2 \end{bmatrix}$   
 (midpoint가 같을 때 jump integral은 0)

$$\sum_{T \in \mathcal{T}_h} \int_{\partial T} \frac{\partial u}{\partial n} w \, ds = \sum_{e \in \mathcal{E}_h^i} \int_e \{ \nabla u - \nabla_h v \} \cdot [w] \, ds + \sum_{e \in \mathcal{E}_h^b} \int_e \nabla_h(u-v) \cdot w \vec{n} \, ds \quad v \in V_h$$

$$\sum_{e \in \mathcal{E}_h^i} \int_e \{ \nabla u - \nabla_h v \} \cdot [w] \, ds \leq \sum_{e \in \mathcal{E}_h^i} \| \nabla u - \nabla_h v \|_{L^2(e)} \| [w] \|_{L^2(e)}$$

Recall Trace Inequality:  $\| \phi \|_{L^2(\partial \hat{T})} \leq C \| \phi \|_{H^1(\hat{T})}$  for  $\phi \in H^1(\hat{T})$   $\hat{T}$ : the reference triangle

$$\begin{aligned} \star \Rightarrow \| \phi \|_{L^2(\partial T)} &\leq C \left( \frac{1}{h_T^2} \| \phi \|_{L^2(\partial \hat{T})} + h_T^{\frac{1}{2}} \| \nabla \phi \|_{H^1(\hat{T})} \right) \\ &\quad \text{very important! in DCT method} \\ &\quad \text{check 1.1 semi norm?} \end{aligned}$$

$$\begin{aligned} \| \{ \nabla_h(u-v) \} \|_{L^2(e)} &= \left\| \frac{1}{2} \nabla_h(u-v)|_{T^+} + \frac{1}{2} \nabla_h(u-v)|_{T^-} \right\|_{L^2(e)} \quad \text{where } e = T^+ \cap T^- \\ &\leq \frac{1}{2} \| \nabla_h(u-v)|_{T^+} \|_{L^2(e)} + \frac{1}{2} \| \nabla_h(u-v)|_{T^-} \|_{L^2(e)} \\ &\leq \frac{1}{2} \| \nabla_h(u-v) \|_{L^2(\partial T^+)} + \frac{1}{2} \| \nabla_h(u-v) \|_{L^2(\partial T^-)} \\ &\stackrel{\text{Trace Ineq.}}{\lesssim} C \left( \frac{1}{h_T^2} \| \nabla_h(u-v) \|_{L^2(T^+ \cup T^-)} + h_T^{\frac{1}{2}} \| \nabla_h(u) \|_{H^1(T^+ \cup T^-)} \right) \end{aligned}$$

$$\begin{aligned} &\| [w] \|_{L^2(e)} \quad \text{Poincaré \& Inverse inequality} \\ &\leq C h_e \| \nabla_e [w] \|_{L^2(e)} \quad \text{where } \nabla_e \text{ is the gradient on edge } e \\ &\quad \uparrow \text{reference domain} \rightarrow \text{original triang} \quad h_e = |e| \quad \left( \begin{array}{l} h_e \leq h_{T^+}, h_e \leq h_{T^-} \\ h_{T^+} \leq C h_e, h_{T^-} \leq C h_e \end{array} \right. \text{by shape regularity} \end{aligned}$$

$$\begin{aligned} &\leq C h_e \| \nabla_e (w|_{T^+} n^+ + w|_{T^-} n^-) \|_{L^2(e)} \\ &\leq C h_e (\| \nabla_e (w|_{T^+} n^+) \|_{L^2(\partial T^+)} + \| \nabla_e (w|_{T^-} n^-) \|_{L^2(\partial T^-)}) \\ &\leq C h_e \| \nabla w \|_{L^2(\partial T^+)} + C h_e \| \nabla w \|_{L^2(\partial T^-)} \\ &\stackrel{\uparrow \text{trace}}{\leq} C h_e \left( \frac{1}{h_e^2} \| \nabla_h w \|_{L^2(T^+ \cup T^-)} + h_e^{\frac{1}{2}} \| \nabla_h w \|_{H^1(T^+ \cup T^-)} \right) = C h_e^{\frac{1}{2}} \| \nabla w \|_{L^2(T^+ \cup T^-)} \end{aligned}$$

$$\begin{aligned} \sum_{e \in \mathcal{E}_h} \int_e \{ \nabla_h(u-v) \} [w] ds &\leq \sum_{T \in \mathcal{T}_h} \left( \|\nabla_h(u-v)\|_{L^2(T)} \|\nabla_h w\|_{L^2(T)} + h|u|_{H^2(T)} \|\nabla_h w\|_{L^2(T)} \right) \\ &\stackrel{me}{\leq} (\|\nabla_h(u-v)\|_{L^2(\Omega)} + |u|_{H^2(\Omega)}) \|\nabla_h w\|_{L^2(\Omega)} \\ &\leq \|\nabla_h(w)\|_{L^2(T+UT)} \|\nabla_h(u-v)\|_{L^2(T+UT)} \leq (\|\nabla_h(w)\|_{L^2(T+)} + \|\nabla_h w\|_{L^2(T-)})(\|\cdot\|_{L^2(T+)} + \|\cdot\|_{L^2(T-)}) \end{aligned}$$

이제 전일이 OKOF,  $u \neq 0$  &  $u \neq 0$

$$\cdot \sum_{e \in \mathcal{E}_h} (\|\nabla_h(u-v)\|_{L^2(T+UT)} + |u|_{H^2(T+UT)}) \|\nabla_h w\|_{L^2(T+UT)}$$

$$\stackrel{?}{\leq} \left( \sum_{e \in \mathcal{E}_h} (\|\nabla_h(u-v)\|_{L^2(T+UT)} + |u|_{H^2(T+UT)})^2 \right)^{\frac{1}{2}} \left( \sum_{e \in \mathcal{E}_h} \|\nabla_h(w)\|_{L^2(T+UT)}^2 \right)^{\frac{1}{2}}$$

$$\begin{aligned} \cdot \sum_{e \in \mathcal{E}_h} \|\nabla_h(w)\|_{L^2(T+UT)}^2 &= \sum_{T \in \mathcal{T}_h} \int_{T+UT} (\nabla_h w)^2 dx \leq 3 \sum_{T \in \mathcal{T}_h} \int_T (\nabla_h w)^2 dx \\ &= \sum_{e \in \mathcal{E}_h} \left( \int_{T+} (\nabla_h w)^2 + \int_{T-} (\nabla_h w)^2 \right) \end{aligned}$$

$$\left| \sum_{T \in \mathcal{T}_h} \int_T \frac{\partial u}{\partial n} w ds \right| \leq (\|\nabla_h(u-v)\|_{L^2(\Omega)} + h|u|_{H^2(\Omega)}) \|\nabla_h w\|_{L^2(\Omega)}$$

$$\begin{aligned} \sup_{w \in V_h} \frac{\left| \sum_{T \in \mathcal{T}_h} \int_T \frac{\partial u}{\partial n} w ds \right|}{\|\nabla_h w\|_{L^2(\Omega)}} &\leq C(\|\nabla_h(u-v)\|_{L^2(\Omega)} + h|u|_{H^2(\Omega)}) \quad \text{for any } w \in V_h \\ &\leq C \inf_{v \in V_h} \|\nabla_h(u-v)\|_{L^2(\Omega)} + Ch|u|_{H^2(\Omega)} \end{aligned}$$

$$\Rightarrow \|\nabla_h(u-u_h)\|_{L^2(\Omega)} \leq \sqrt{2} \inf_{v \in V_h} \|\nabla_h(u-v)\|_{L^2(\Omega)} + \sqrt{2} \Gamma$$

$$\leq C \inf_{v \in V_h} \|\nabla_h(u-v)\|_{L^2(\Omega)} + Ch|u|_{H^2(\Omega)} \leq Ch|u|_{H^2(\Omega)}$$

우리가 바라본 final goal

불가능해요...

여기서도  $V_h \not\subset H_0^1(\Omega)$  이서 inconsistency 발생

실제 numerical implementation 이서 numerical integration 이서 inconsistency 발생.

accuracy 이 영향을 주지 않으면 integration 을 고차항까지 포함하여  
distinct integration 하여야 함.

## History

&lt;Elliptic problem&gt;

G. Baker (Biharmonic 70's)

Douglas Arnold (interior penalty method 79')

&lt;Transport problem&gt;

(Los Alamos inst 70's)

Cockburn - Le Floch 20's

Cockburn - Shu 20's

$$-\epsilon \Delta u + \beta \cdot \nabla u = f \quad \text{on } \Omega$$

Local DG [Cockburn - Shu early 90's]

In class

Many DG methods: "Interior penalty methods," Local discontinuous Galerkin method, ...

 $T_h$ : a triangulation

 $E_h$ : the collection of edges.

$$E_h = E_h^B \cup E_h^I$$

 where  $E_h^I$  interior edges

 $E_h^B$  boundary edges

 let  $\vec{V}$  be a vector

$$[\vec{V}]_e = \vec{V}_+ \cdot \vec{n}_+ + \vec{V}_- \cdot \vec{n}_-$$

$$\{\vec{V}\}_e = \frac{1}{2} \vec{V}_+ + \frac{1}{2} \vec{V}_- \quad e \in E_h^I$$

$$= \vec{V} \quad e \in E_h^B$$

$$e = T \cap T'$$


 let  $v$  be a scalar

$$[v]_e = \begin{cases} v_+ \cdot \vec{n}_+ + v_- \cdot \vec{n}_- & e \in E_h^I \\ v \cdot \vec{n} & e \in E_h^B \end{cases}$$

$$\{v\}_e = \begin{cases} \frac{1}{2} v_+ + \frac{1}{2} v_- & e \in E_h^I \\ v & e \in E_h^B \end{cases}$$

$$H^1(T_h) = \{v \in L^2(\Omega) : v|_T \in H^1(T), \forall T \in T_h\}$$

DG space:

$$V_h^k = \{v \in L^2(\Omega) : v|_T \in P^k(T), \forall T \in T_h\} \subseteq H^1(T_h)$$

$$\text{Problem: } \begin{aligned} -\Delta u &= f & \Omega \\ u &= 0 & \partial\Omega \end{aligned}$$

 What if  $v \in H^1(T_h)$  is my test fn.

$$\int_{\Omega} -\Delta u \cdot v = \int_{\Omega} f \cdot v$$

 integration by parts  $\int_{\partial T} \nabla u \cdot \vec{n} v \, ds$  because of discontinuity of  $v$ .

$$-\int_{\Omega} \Delta u \cdot v = \sum_{T \in T_h} -\int_T \Delta u \cdot v \, dx = \sum_{T \in T_h} \left\{ \int_T \nabla u \cdot \nabla v \, dx - \int_{\partial T} \nabla u \cdot \vec{n} v \, ds \right\}$$

$$= (\nabla u, \nabla v) - \sum_{T \in T_h} \int_{\partial T} \nabla u \cdot \vec{n} v \, ds$$

defined in the last class

$$\sum_{T \in T_h} \int_{\partial T} (\nabla u \cdot \vec{n}) v \, ds = \sum_{e \in E_h} \int_e \{ \nabla u \} \cdot [v] \, ds + \sum_{e \in E_h^B} \int_e [\nabla u] \cdot \{v\} \, ds$$

$$= \sum_{e \in E_h} \int_e \frac{1}{2} (\nabla u_+ + \nabla u_-) \cdot (v_+ \vec{n}_+ + v_- \vec{n}_-) + \sum_{e \in E_h^B} \int_e (\nabla u \cdot \vec{n}) \frac{1}{2} (v_+ + v_-) \, ds + \dots$$



$$\int_e (\nabla u_+ \cdot \vec{n}_+ v_+ + \nabla u_- \cdot \vec{n}_- v_-) \, ds \quad \frac{1}{2} (\nabla u_+ \cdot \vec{n}_+ v_+ + \nabla u_- \cdot \vec{n}_- v_- + \nabla u_+ \cdot \vec{n}_- v_- + \nabla u_- \cdot \vec{n}_+ v_+)$$

 $e \in E_h^B$ 

$$+ \frac{1}{2} (\nabla u_+ \cdot \vec{n}_+ v_+ + \nabla u_- \cdot \vec{n}_- v_- + \nabla u_+ \cdot \vec{n}_- v_- + \nabla u_- \cdot \vec{n}_+ v_+)$$

equal

$(f, v)$

$$- \int \Delta u \cdot v = (\nabla_h u, \nabla_h v) - \langle \{\nabla_h u\}, [v] \rangle_{\mathcal{E}_h} - \langle [v], \{\nabla_h u\} \rangle_{\mathcal{E}_h} \quad \forall v \in H^1(\mathcal{T}_h)$$

$$\langle \vec{M}, \vec{g} \rangle_{\mathcal{E}_h} = \frac{1}{|\mathcal{E}_h|} \int_{\mathcal{E}_h} \vec{M} \cdot \vec{g} \, ds$$

$$\langle r, s \rangle_{\mathcal{E}_h} = \frac{1}{|\mathcal{E}_h|} \int_{\mathcal{E}_h} r s \, ds$$

$$\tilde{a}_h(u, v) = (\nabla_h u, \nabla_h v) - \langle \{\nabla_h u\}, [v] \rangle_{\mathcal{E}_h} - \langle [v], \{\nabla_h u\} \rangle_{\mathcal{E}_h}$$

$$\Rightarrow \tilde{a}_h(u, v) = (f, v) \quad \forall v \in H^1(\mathcal{T}_h) \quad \text{since } u \in H^2 \text{ by assumption } [\nabla u] = 0$$

positive definite  $\Leftrightarrow$  positive definite

$$\tilde{a}_h(u, v) = (\nabla_h u, \nabla_h v) - \langle \{\nabla_h u\}, [v] \rangle_{\mathcal{E}_h} + \langle \{\nabla_h v\}, [u] \rangle_{\mathcal{E}_h} + \langle [u], [v] \rangle_{\mathcal{E}_h}$$

$$\tilde{a}_h(v, v) = (\nabla_h v, \nabla_h v) + \langle [v], [v] \rangle_{\mathcal{E}_h} \Rightarrow \text{positive definite}$$

not symmetric  $\Rightarrow$  CG convergence  $\Rightarrow$  WZB.

$\frac{\alpha}{h}$ 를 추가하면 Nonsymmetric IP

### Interior Penalty method:

$$a_h(u, v) = (\nabla_h u, \nabla_h v) - \langle \{\nabla_h u\}, [v] \rangle_{\mathcal{E}_h} - \langle \{\nabla_h v\}, [u] \rangle_{\mathcal{E}_h} + \frac{\alpha}{h} \langle [u], [v] \rangle_{\mathcal{E}_h}$$

We assume for simplicity that we have a quasi-linear mesh.

$$\text{i.e. } \exists \text{ a constant } C_\alpha \text{ s.t. } \max_{T \in \mathcal{T}_h} h_T = h \leq C_\alpha h_T \quad \forall T \in \mathcal{T}_h$$

$\alpha$  is a parameter to be chosen by the users. (should be large enough to be PD)

Let  $\alpha T \Rightarrow$  ill-posed, closed to continuous Galerkin.

$$\text{Find } u_h \in V_h^k \text{ s.t. } a_h(u_h, v) = (f, v) \quad \forall v \in V_h^k$$

### Preliminaries

• Trace inequality:

$$\text{If } v \in H^1(\mathcal{T}), \quad \|v\|_{L^2(\partial \mathcal{T})} \leq C_{tr} \left( \frac{1}{h^{\frac{1}{2}}} \|v\|_{L^2(\mathcal{T})} + h^{\frac{1}{2}} \|\nabla v\|_{L^2(\mathcal{T})} \right)$$

• Inverse estimate:

$$1) \text{ If } v \in P^k(\mathcal{T}), \quad \|\nabla v\|_{L^2(\mathcal{T})} \leq \frac{C_i}{h} \|v\|_{L^2(\mathcal{T})}$$

finite dimension

$$2) \quad \|v\|_{L^2(\partial \mathcal{T})} \leq C_{inv} \frac{1}{h^{\frac{1}{2}}} \|v\|_{L^2(\mathcal{T})}$$

### Coercivity

Lemma  $\exists \beta > 0$  such that  $\beta \|v\|_{H_h^1(\Omega)}^2 \leq a_h(v, v) \quad \forall v \in V_h^k$  provided  $\alpha$  is large enough.

$$\text{Here } \|v\|_{H_h^1(\Omega)}^2 = (\nabla_h v, \nabla_h v) + h \langle \{\nabla_h v\}, [v] \rangle_{\mathcal{E}_h} + \frac{1}{h} \langle [v], [v] \rangle_{\mathcal{E}_h}$$

pf) Let  $v \in V_h^k$

$$a_h(v, v) = (\nabla_h v, \nabla_h v) - 2 \langle \{\nabla_h v\}, [v] \rangle_{\mathcal{E}_h} + \frac{\alpha}{h} \langle [v], [v] \rangle_{\mathcal{E}_h}$$

By Cauchy-Schwarz.

$$2 \langle \{\nabla_h v\}, [v] \rangle_{\mathcal{E}_h} \leq \sqrt{h \langle \{\nabla_h v\}, \{\nabla_h v\} \rangle_{\mathcal{E}_h}} \sqrt{\langle [v], [v] \rangle_{\mathcal{E}_h} \frac{1}{h}}$$

$$h \langle \{\nabla_h v\}, \{\nabla_h v\} \rangle_{\mathcal{E}_h} = h \frac{1}{|\mathcal{E}_h|} \int_{\mathcal{E}_h} |\nabla_h v|^2 \, ds \leq \frac{1}{|\mathcal{E}_h|} \int_{\mathcal{E}_h} \frac{1}{2} C_{inv}^2 \|\nabla_h v\|_{L^2(\mathcal{T})}^2 \leq \frac{1}{2} N C_{inv}^2 \sum_{T \in \mathcal{T}_h} \|\nabla_h v\|_{L^2(\mathcal{T})}^2 = \frac{1}{2} N C_{inv}^2 (\nabla_h v, \nabla_h v)$$



For each edge  $e$ , let  $\mathcal{N}(e)$  be the triangles that have  $e$  as an edge

$N_T$  = the number of edges  $T$  has from  $\mathcal{E}_h$

$$N = \max_{T \in \mathcal{T}_h} N_T$$



$$\begin{aligned}
a_h(v, v) &\geq (\nabla_h v, \nabla_h v) - \underbrace{\sqrt{\frac{1}{h}} \langle [\nabla_h v], [\nabla_h v] \rangle_{\mathcal{E}_h}}_b \underbrace{\sqrt{\frac{1}{2} N C_{inv}^2 (\nabla_h v, \nabla_h v)}}_a + \frac{\alpha}{h} \langle [v], [v] \rangle_{\mathcal{E}_h} \\
ab &= \sqrt{2(1-\varepsilon)} a \sqrt{\frac{b}{2(1-\varepsilon)}} \\
&\geq (\nabla_h v, \nabla_h v) - (1-\varepsilon) (\nabla_h v, \nabla_h v) - \frac{N C_{inv}^2}{4(1-\varepsilon)h} \langle [v], [v] \rangle_{\mathcal{E}_h} + \frac{\alpha}{h} \langle [v], [v] \rangle_{\mathcal{E}_h} \\
&= \varepsilon (\nabla_h v, \nabla_h v) + \frac{1}{h} \left( \alpha - \frac{N C_{inv}^2}{4(1-\varepsilon)} \right) \langle [v], [v] \rangle_{\mathcal{E}_h} \quad \left\{ \begin{array}{l} \text{Let } \varepsilon = \frac{1}{2} \end{array} \right. \\
&= \frac{1}{2} (\nabla_h v, \nabla_h v) + \frac{1}{h} \left( \alpha - \frac{N C_{inv}^2}{2} \right) \langle [v], [v] \rangle_{\mathcal{E}_h}
\end{aligned}$$

If  $\alpha \geq \frac{1}{2} N C_{inv}^2 + \frac{1}{2}$ , then

$$a_h(v, v) \geq \frac{1}{2} (\nabla_h v, \nabla_h v) + \frac{1}{2h} \langle [v], [v] \rangle_{\mathcal{E}_h}$$

$$\begin{aligned}
\|v\|_{H_h^1(\Omega)}^2 &\leq (\nabla_h v, \nabla_h v) + \frac{1}{2} N C_{inv}^2 (\nabla_h v, \nabla_h v) + \frac{1}{h} \langle [v], [v] \rangle_{\mathcal{E}_h} \\
&\leq \left(1 + \frac{1}{2} N C_{inv}^2\right) \left[ (\nabla_h v, \nabla_h v) + \frac{1}{h} \langle [v], [v] \rangle_{\mathcal{E}_h} \right] \leq \left(1 + \frac{1}{2} N C_{inv}^2\right) a_h(v, v) \\
\therefore \beta \|v\|_{H_h^1(\Omega)}^2 &\leq a_h(v, v) \quad \text{where} \quad \beta = \frac{1}{1 + \frac{1}{2} N C_{inv}^2}
\end{aligned}$$

Lemma (Continuity)  $a_h(u, v) \leq C_0 \|u\|_{H_h^1(\Omega)} \|v\|_{H_h^1(\Omega)} \quad \forall u, v \in H^2(\mathcal{T}_h) (\supset H_h^1(\Omega))$   
 p.f) Trace, Cauchy-Schwarz.

Lemma (Galerkin Orthogonality)

If  $u$  satisfies  $-\Delta u = f \quad \Omega$   
 $u = 0 \quad \partial\Omega$

and  $u_h$  is the IPDG approximation, then

$$a_h(u - u_h, v) = 0 \quad \forall v \in V_h^k$$

(Interior Penalty Discontinuous Galerkin)  
 ← non-conforming finite element

Thm Assume previous results hold.

$$\|u - u_h\|_{H_h^1(\Omega)} \leq C \inf_{v \in V_h^k} \|u - v\|_{H_h^1(\Omega)}$$

p.f)  $\|u - u_h\|_{H_h^1(\Omega)} \leq \|u - v\|_{H_h^1(\Omega)} + \|v - u_h\|_{H_h^1(\Omega)} \quad \forall v \in V_h^k$

By coercivity,

$$\beta \|v - u_h\|_{H_h^1(\Omega)}^2 \leq a_h(v - u_h, v - u_h) = a(u - u_h, v - u_h) + a(v - u, v - u_h)$$

$$\leq C \|v - u\|_{H_h^1(\Omega)} \|v - u_h\|_{H_h^1(\Omega)} \quad \text{by continuity}$$

$$\|v - u_h\|_{H_h^1(\Omega)} \leq \frac{C}{\beta} \|v - u\|_{H_h^1(\Omega)}$$

$$\Rightarrow \|u - u_h\|_{H_h^1(\Omega)} \leq \left(1 + \frac{C}{\beta}\right) \|v - u\|_{H_h^1(\Omega)} \quad \forall v \in V_h^k$$

$$\leq \left(1 + \frac{C}{\beta}\right) \inf_{v \in V_h^k} \|u - v\|_{H_h^1(\Omega)} \leq C h^k |u|_{H^{k+1}(\Omega)}$$

True!

$$\|u-v\|_{H^1(\Omega)}^2 = (\nabla_0(u-v), \nabla_0(u-v)) + h \langle f \nabla_0(u-v), \nabla_0(u-v) \rangle_{\mathbb{R}^n} + \frac{1}{h} \langle [u-v], [u-v] \rangle_{\mathbb{R}^n}$$

$$\leq C \sum_{T \in \mathcal{T}_h} \left[ \frac{1}{h^2} \|u-v\|_{L^2(T)}^2 + \|\nabla(u-v)\|_{L^2(T)}^2 + h^2 \|D^2(u-v)\|_{L^2(T)}^2 \right]$$

Trace

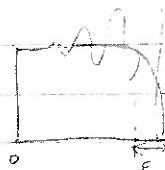
$$\leq C h^k |u|_{H^{k+1}(\Omega)}$$

Bram-Hilbert  
Take infimum

Potential Topics for next class...

$$-\varepsilon u'' + u' = 0 \quad [0,1]$$

$$u(0) = 1, \quad u(1) = 0.$$

 $\varepsilon$ : very small.continuous Galerkin  $\sim 10^{-8}$  $\varepsilon \sim 10^{-8}$  analyze  $\uparrow$ textbook on  $u \sim 10^{-8}$  $\rightarrow$  artificial/streamline diffusion (Thomas Hughes)

upwinding FD.

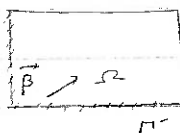
Discontinuous Galerkin

$$-(\varepsilon+h)\tilde{u}'' + \tilde{u}' = 0$$

smooth solution ( $\varepsilon \sim 10^{-8}$ ,  $h \sim 10^{-2}$ )

$$\begin{cases} u_p = f & \Omega \\ u = 0 & \Gamma \end{cases}$$

(\*)  $u_p + u = f$   
 or  $u_p = f - u$   
 in textbook



$$\Gamma^+ = \{x \in \partial\Omega: \vec{p} \cdot \vec{n} < 0\}$$

$$\Gamma^- = \{x \in \partial\Omega: \vec{p} \cdot \vec{n} > 0\}$$

$$u_p = \nabla u \cdot \vec{p} \quad \vec{p} \text{ is a fixed vector}$$

$$V_h = \{v \in H^1(\Omega): v|_T \in P(T) \quad v=0 \text{ on } \Gamma^-\}$$

$$\int u_p \cdot v = \int f \cdot v \quad \forall v \in L^2(\Omega)$$

Standard Galerkin method:

$$\text{Find } u_h \in V_h \text{ s.t. } \int_{\Omega} (u_h)_p \cdot v = \int_{\Omega} f \cdot v \quad \forall v \in V_h$$

$$a_h(u_h, v) = (f, v) \quad \forall v \in V_h$$

$$a_h(u_h, v) = \int_{\Omega} (u_h)_p \cdot v \, dx$$

??  
 squared system  $\Rightarrow$  uniqueness implicit well-posedness

Uniqueness: If  $f \equiv 0$ , want to show  $u_h \equiv 0$ 

$$\therefore a_h(u_h, v) = 0 \quad \forall v \in V_h$$

$$0 = a_h(u_h, u_h) = \int_{\Omega} (u_h)_p \cdot u_h = \frac{1}{2} \int_{\Omega} \partial_p (u_h)^2 = \frac{1}{2} \int_{\partial\Omega} u_h^2 \vec{p} \cdot \vec{n} = \frac{1}{2} \int_{\Gamma^+} u_h^2 |\vec{p} \cdot \vec{n}|$$

$$(u_h)_p \notin V_h \text{ s.t. } \forall v \in V_h \int_{\Omega} (u_h)_p \cdot v = 0$$

uniqueness  $\Rightarrow$   $\Rightarrow$  streamline diffusion method

## Streamline diffusion method

$$u_p = f$$

$$\int_{\Omega} u_p (v + h v_p) = \int_{\Omega} f (v + h v_p) \quad \forall v \in H^1$$

Find  $u_h \in V_h$ 

$$a(u_h, v) = (f, v + h v_p) \quad \forall v \in V_h$$

$$\text{where } a(u_h, v) = \int_{\Omega} [h(u_h)_p v_p + (u_h)_p v]$$

• Uniqueness

Let  $f=0$ 

$$0 = a_h(u_h, u_h) = h \int_{\Omega} (u_h)_p^2 + \int_{\Omega} (u_h)_p u_h = h \int_{\Omega} (u_h)_p^2 + \int_{\Gamma^+} (u_h)^2 |\beta \cdot n|$$

$$\Rightarrow (u_h)_p^2 |\beta \cdot n| = 0 \quad \Gamma^+$$

$$(u_h)_p = 0 \quad \Omega$$



$$u(x) = \underbrace{u(x_0)}_0 + \int_0^1 \underbrace{u_p}_0 ds \Rightarrow u(x) = 0 \text{ in } \Omega$$

$$\frac{1}{h} \beta \cdot n \neq 0 \Rightarrow \beta \cdot n > 0 \quad \forall T \in \mathcal{T}_h$$

Lemma  $\|u_h\| \leq C \|f\|_{L^2(\Omega)}$ 

"discrete ponce type inequality"

$$\text{p.f. } h \int_{\Omega} (u_h)_p^2 + \int_{\Gamma^+} u_h^2 |\beta \cdot n| = a_h(u_h, u_h) = (f, u_h + h(u_h)_p) \leq \|f\| (\|u_h\|_{L^2} + h \|(u_h)_p\|_{L^2})$$

$$\leq \frac{1}{\varepsilon} \|f\|^2 + \varepsilon C (h \int_{\Omega} u_p^2)$$

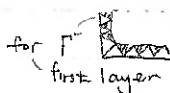
$$\|v\|_{L^2(\Omega)} \leq C (h \int_{\Omega} v_p^2 + \int_{\Gamma^+} v^2 |\beta \cdot n|)$$

Choose  $\varepsilon C < \frac{1}{2}$ ,

$$\Rightarrow \frac{1}{2} h \int_{\Omega} (u_h)_p^2 + \int_{\Gamma^+} u_h^2 |\beta \cdot n| \leq C \|f\|_{L^2(\Omega)}^2$$

$$(\|u_h\|_{\beta}^2 = h \int_{\Omega} u_p^2 + \int_{\Gamma^+} u^2 |\beta \cdot n|)$$

$$\|v\|_{L^2(\Omega)} \leq h \|v_p\|_{L^2(\Omega)}$$



second layer

$$\|v\|_{L^2(\Omega)} \leq h \|v_p\|_{L^2(\Omega)} + \frac{1}{h} \|v\|_{L^2(\Omega)}$$

OOI 이어서 추가...

문 이원식만은...

recap....

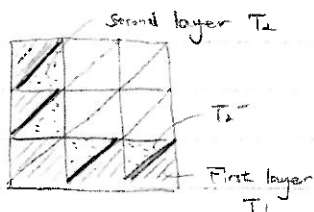
If  $v \in P^1|_T$  then

then

$$\|v\|_{L^2(T)} \leq C (h_T \|v_p\|_{L^2(T)} + h_T^{\frac{1}{2}} \|v\|_{L^2(T)})$$

→ reference triangle에서

동일 norm 이라는 것을 보여야한다

→ 각 triangle를 바꾸면서  $h_T$ 도 바뀌는. (scaling argument)

$$\|v\|_{L^2(T_1)} \leq C h_{T_1} \|v_p\|_{L^2(T_1)}$$

trace or inverse

$$\|v\|_{L^2(T_2)} \leq C (h_{T_2} \|v_p\|_{L^2(T_2)} + h_{T_2}^{\frac{1}{2}} \|v\|_{L^2(T_2)}) \leq C h_{T_2} \|v_p\|_{L^2(T_2)} + C h_{T_2}^{\frac{1}{2}} \|v\|_{L^2(T_2)}$$

$$\|v\|_{L^2(T_m)}$$

squared everything &amp; summation

$$M(T) = T_1 \cup T_2 \cup \dots \cup T_N$$

$$\sum_{T \in \mathcal{T}_h} \|v\|_{L^2(T)}^2 \leq \sum_{T \in \mathcal{T}_h} \sum_{T' \in M(T)} h_T^2 \|v_p\|_{L^2(T')}^2$$

$$\leq N \sum_{T \in \mathcal{T}_h} h_T^2 \|v_p\|_{L^2(T)}^2$$

first layer is  $N = \frac{1}{h^2}$  정도

$$= C \sum_{T \in \mathcal{T}_h} h_T \|v_p\|_{L^2(T)}^2 = C h \|v_p\|_{L^2(\Omega)}^2$$

$$a_h(u, v) = h \int (\varphi_p) \cdot \nabla p + \int \varphi_p \cdot \nabla v \quad \text{weak form}$$

$$u_p = f \rightarrow u_p - h u_{p,ss} = f \quad \text{이 form 이 weak form 으로 볼 수 있다.}$$

non-stationary  
diffusion term 이 동차 풀이! to stabilize problem.  
↑  
이런 것 많이 하죠

$$-\varepsilon \Delta u^\varepsilon + u^\varepsilon + (f(u^\varepsilon))_t = 0$$

adding term stabilize 하기 위해 artificial diffusion 을 넣어주고  $\rightarrow u^\varepsilon$

$$\text{and show } \|u^\varepsilon - u\|_{L^1} \leq \sqrt{\varepsilon} \quad u^\varepsilon \text{가 } u \text{와 가까운 것을 보여요.}$$

$$\text{Consider } -\varepsilon \Delta u + u_p = f \quad \Omega$$

$$u = 0 \quad \partial\Omega$$

$$V_h = \{v \in H_0^1(\Omega) : v|_T \in P^1(T)\}$$

$$\varepsilon \int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} u_p \cdot v = \int_{\Omega} f v$$

$$\text{Find } u_h \in V_h$$

$$a(u_h, v) = (f, v) \quad \forall v \in V_h$$

$$\text{where } a(v, v) = \varepsilon \int_{\Omega} \nabla v \cdot \nabla v + \int_{\Omega} u_p v$$

$$\text{stability : } a_h(u, u_h) = (f, u_h) \quad \|u_h\|_{L^2}^2 \leq c h \int (\varphi_p)^2 dx$$

$$\varepsilon \|\nabla u_h\|_{L^2(\Omega)}^2 + \frac{1}{2} \int_{\Gamma} u_h^2 |\rho \cdot n| = (f, u_h) \leq \|f\|_{L^2} \|u_h\|_{L^2} \leq \|f\|_{L^2(\Omega)} (c h^{\frac{1}{2}} \|\nabla u_h\|_{L^2(\Omega)})$$

$$\leq \frac{1}{2} \varepsilon \|\nabla u_h\|^2 + \frac{c h}{2 \varepsilon} \|f\|^2$$

$$\text{when } \varepsilon \rightarrow 0, \text{ not stable}$$

$$\varepsilon \ll h$$

$$\Rightarrow \text{Instead of } \varepsilon, \text{ USE } h$$

$$\int (-\varepsilon \Delta u + u_p)(v + h v_p) = \int f(v + h v_p)$$

continuous  
piecewise  
linear  $\Delta u|_T = 0$

$$\varepsilon \int_{\Omega} \nabla u_h \cdot \nabla v + h \int_{\Omega} (u_h)_p v_p + \int_{\Omega} (u_h)_p v - \int_{\Omega} \varepsilon \Delta u_h v_p = \int f(v + h v_p) \quad \forall v \in V_h$$

$$\varepsilon \|\nabla u_h\|_{L^2(\Omega)}^2 + h \|(u_h)_p\|_{L^2(\Omega)}^2 \leq c \|f\|_{L^2(\Omega)}^2$$

$$\|(u_h)_p\|_{L^2(\Omega)} \leq \left( \frac{c}{h} \|f\|_{L^2(\Omega)} \right)$$

h 가 0 이 되면 norm bound 를 위반 할 수 있습니다!

$$\sqrt{L \left( \frac{1}{h} \right)^2} = |L| \frac{1}{h} = \frac{1}{\sqrt{h}}$$

$$\sqrt{L \left( \frac{1}{h} \right)} = |L| \frac{1}{\sqrt{h}} = 1 \quad \rightarrow L^1 \text{ norm 을 이용하면 h 가 작아도}$$

~~h~~



$$\begin{cases} \dot{u} - \Delta u = f & \Omega \times (0, T] \\ u = 0 & \partial\Omega \times [0, T] \\ u(x, 0) = u^0(x) & \Omega \end{cases}$$

Let  $V = H_0^1(\Omega)$

Fix time  $0 < t \leq T$

$$\int_{\Omega} \dot{u}(t) v \, dx - \int_{\Omega} \Delta u(t) v \, dx = \int_{\Omega} f(t) v \, dx$$

$$\int_{\Omega} \dot{u}(t) v \, dx + \int_{\Omega} \nabla u(t) \cdot \nabla v \, dx = \int_{\Omega} f(t) v \, dx$$

$$(\dot{u}(t), v) + a(u(t), v) = (f(t), v) \quad \forall v \in V, \quad 0 < t \leq T$$

$$\text{where } a(u, v) = (\nabla u, \nabla v)$$

First we discretize in space only.

$$V_h \subseteq V$$

$$\text{eg } V_h = \{v \in C_0(\Omega) : v|_T \in P^k(T) \quad \forall T \in \mathcal{T}_h\}$$

Find  $u_h(t) \in V_h$  s.t.

$$(*) \begin{cases} (\dot{u}_h(t), v) + a(u_h(t), v) = (f(t), v) & \forall v \in V_h, \quad 0 < t \leq T \\ (u_h(0), v) = (u^0, v) & \forall v \in V_h \end{cases} \quad \leftarrow \text{IC.}$$

This turns out to be a system of ODE's

(\*) Any function  $v \in V_h$ ,  $v = \sum_{i=1}^M z_i \phi_i$  where  $\{\phi_i\}_{i=1}^M$  is a basis of  $V$

$$\Rightarrow u_h(t) = \sum_{i=1}^M z_i(t) \phi_i$$

: we need to find the functions  $z_i : [0, T] \rightarrow \mathbb{R}$ .

$$\dot{u}_h(t) = \sum_{i=1}^M \dot{z}_i(t) \phi_i$$

$$(*) \Rightarrow \left( \sum_{i=1}^M \dot{z}_i(t) \phi_i, \phi_j \right) + a \left( \sum_{i=1}^M z_i(t) \phi_i, \phi_j \right) = (f(t), \phi_j) \quad \forall j$$

$$\sum_{i=1}^M \left[ (\phi_i, \phi_j) \dot{z}_i(t) + a(\phi_i, \phi_j) z_i(t) \right] = (f(t), \phi_j)$$

$$\text{Let } B_{ij} = (\phi_i, \phi_j), \quad A_{ij} = a(\phi_i, \phi_j)$$

$$B = \begin{bmatrix} (\phi_1, \phi_1) & & \\ (\phi_2, \phi_1) & & \\ & \ddots & \\ (\phi_1, \phi_M) & & (\phi_M, \phi_M) \end{bmatrix}$$

$$\text{I.C. : } \sum_{i=1}^M z_i(0) (\phi_i, \phi_j) = (u^0, \phi_j)$$

$$B \vec{z}(0) = \vec{u}^0$$

$$\begin{cases} B \dot{\vec{z}}(t) + A \vec{z}(t) = \vec{F}(t) \\ \text{where } \vec{z}(t) = \begin{bmatrix} z_1(t) \\ \vdots \\ z_M(t) \end{bmatrix}, \quad \vec{F}(t) = \begin{bmatrix} (f(t), \phi_1) \\ \vdots \\ (f(t), \phi_M) \end{bmatrix} \\ B \vec{z}(0) = \vec{u}^0 \end{cases}$$

eigenvalues  $\leq 0$  or  $\leq 0$  or  $\leq 0$  steep  $\Rightarrow$  Runge-Kutta, Backward Euler... 등  
강 안정성.

Semi-discrete approximation

Stability (Assume  $f \equiv 0$ )

$$(\dot{u}_h(t), v) + a(u_h(t), v) = 0$$

Let  $v = u_h(t)$

$$(\dot{u}_h(t), u_h(t)) + a(u_h(t), u_h(t)) = \frac{1}{2} \int_{\Omega} \frac{d}{dt} (u_h^2) \, dx + a(u_h(t), u_h(t)) = 0$$

$$\frac{1}{2} \frac{d}{dt} \|u_h\|^2 + a(u_h(t), u_h(t)) = 0$$

$$\frac{1}{2} \int_0^t \frac{d}{dt} \|u_h(t)\|^2 + \int_0^t a(u_h(t), u_h(t)) \, dt = 0$$

$$\frac{1}{2} (\|u_h(t)\|^2 - \|u_h(0)\|^2) \leq 0$$

$$\|u_h(t)\| \leq \|u_h(0)\| \leq \|u^0\|$$

### Error estimate for semi-discrete scheme

We need to define the elliptic projection

Given  $w$ , define  $P_h w(t) \in V_h$

$$(\nabla(P_h w(t)), \nabla v) = (\nabla w(t), \nabla v) \quad \forall v \in V_h$$

$$-\Delta w = -\Delta(P_h w(t)) \quad \text{by def.}$$

$$\begin{aligned} \forall v \in V_h, (\nabla(\partial_t P_h w(t)), \nabla v) &= (\partial_t \nabla(P_h w(t)), \nabla v) = \partial_t (\nabla(P_h w(t)), \nabla v) \\ &= \partial_t (\nabla w(t), \nabla v) \\ &= (\nabla(\partial_t w(t)), \nabla v) \\ &= (\nabla(P_h(\partial_t w(t))), \nabla v) \end{aligned}$$

$$\Rightarrow \partial_t P_h w(t) = P_h(\partial_t w(t)) \quad (*)$$

$$\bullet \|\nabla(P_h w(t) - w(t))\|_{L^2(\Omega)} \leq Ch^k \|w(t)\|_{H^{k+1}(\Omega)}$$

$$\begin{aligned} (\bullet) \quad \|\cdot\|_{L^2(\Omega)}^2 &= (\nabla(P_h w(t) - w(t)), \nabla(P_h w(t) - w(t))) \\ &= (\nabla(P_h w(t) - w(t)), \nabla(Iw(t) - w(t))) \end{aligned}$$

$$\|\nabla(P_h w(t) - w(t))\|_{L^2(\Omega)} \leq \|\nabla(Iw(t) - w(t))\| \leq Ch^k \|w(t)\|_{H^{k+1}(\Omega)}$$

$$\bullet \|\nabla(P_h \dot{w}(t) - \dot{w}(t))\|_{L^2(\Omega)} \stackrel{\text{by } (*)}{=} \|\nabla(P_h \dot{w}(t) - \dot{w}(t))\|_{L^2(\Omega)} \leq Ch^k \|\dot{w}(t)\|_{H^{k+1}(\Omega)}$$

$$(\dot{u}_h(t), v) + a(u_h(t), v) = (f(t), v) \quad \forall v \in V_h$$

$$(\dot{u}(t), v) + a(u(t), v) = (f(t), v) \quad \forall v \in V$$

$$\Rightarrow (\dot{u}_h - \dot{u}, v) + a(u_h - u, v) = 0 \quad \forall v \in V_h$$

$$(u_h - [P_h u], v) + a(u_h - P_h u, v) = (u - P_h \dot{u}, v) + a(u - P_h u, v) \quad \forall v \in V_h$$

Define  $e_h(t) = u_h(t) - P_h u(t) \in V_h$

$$(\dot{e}_h, v) + a(e_h, v) = (u - P_h \dot{u})(t), v \quad \forall v \in V_h$$

Let  $v = e_h(t)$

$$(\dot{e}_h, e_h) + a(e_h, e_h) = ((u - P_h \dot{u})(t), e_h)$$

$$\frac{1}{2} \frac{d}{dt} \|e_h(t)\|_{L^2(\Omega)}^2 + a(e_h, e_h) \leq \| (u - P_h \dot{u})(t) \|_{L^2(\Omega)} \|e_h(t)\|_{L^2(\Omega)} \leq \frac{1}{2} C_P \|e_h(t)\|_{L^2(\Omega)}^2 + \frac{1}{2} \frac{1}{C_P} \|(\dot{u} - P_h \dot{u})(t)\|_{L^2(\Omega)}^2$$

$$\frac{1}{2} \frac{d}{dt} \|e_h(t)\|_{L^2(\Omega)}^2 + C_P \|e_h(t)\|_{L^2(\Omega)}^2 \leq \frac{1}{2} \frac{d}{dt} \|e_h(t)\|_{L^2(\Omega)}^2 + \underbrace{a(e_h, e_h)}_{\text{Poincaré}} = \int_{\Omega} \nabla e_h \cdot \nabla e_h$$

$$\frac{1}{2} \frac{d}{dt} \|e_h(t)\|_{L^2(\Omega)}^2 + \frac{1}{2} C_P \|e_h(t)\|_{L^2(\Omega)}^2 \leq \frac{1}{2 C_P} \|(\dot{u} - P_h \dot{u})(t)\|_{L^2(\Omega)}^2$$

$$\frac{d}{dt} \|e_h(t)\|_{L^2(\Omega)}^2 \leq -C_P \|e_h(t)\|_{L^2(\Omega)}^2 - \frac{1}{C_P} \|(\dot{u} - P_h \dot{u})(t)\|_{L^2(\Omega)}^2$$

Recall (Gronwall's inequality)

$$\phi'(t) \leq \beta \phi(t) + f(t)$$

$$\phi(t) \leq e^{\beta t} (\phi(0) + \int_0^t f(s) ds)$$

$$(i) \quad e^{-\beta t} \phi(t) \leq e^{-\beta t} \beta \phi(t) + e^{-\beta t} f(t)$$

$$\text{Since } (e^{-\beta t} \phi)' = -\beta e^{-\beta t} \phi + e^{-\beta t} \phi',$$

$$(e^{-\beta t} \phi)' \leq e^{-\beta t} f(t)$$

$$\int_0^t (e^{-\beta s} \phi)'(s) ds \leq \int_0^t e^{-\beta s} f(s) ds$$

$$e^{-\beta t} \phi(t) - \phi(0) \leq \int_0^t e^{-\beta s} f(s) ds \leq 1 \quad \text{if } \beta > 0$$

$$\phi(t) \leq e^{\beta t} \phi(0) + \int_0^t e^{\beta(t-s)} f(s) ds$$

Apply Gronwall's ineq.

$$\begin{aligned} \|e_h(t)\|_{L^2(\Omega)}^2 &\leq e^{-c_P t} \|e_h(0)\|_{L^2(\Omega)}^2 + \frac{e^{-c_P t}}{c_P} \int_0^t e^{c_P s} \|(\dot{u} - P_h \dot{u})(s)\|_{L^2(\Omega)}^2 ds \leq e^{-c_P t} \|e_h(0)\|_{L^2(\Omega)}^2 + \frac{I}{c_P^2} (1 - e^{-c_P t}) \\ &\leq \frac{e^{-c_P t}}{c_P} \max_{0 \leq s \leq t} \|(\dot{u} - P_h \dot{u})(s)\|_{L^2(\Omega)}^2 \int_0^t e^{c_P s} ds = \frac{e^{-c_P t}}{c_P} I \left( \frac{1}{c_P} e^{c_P t} - \frac{1}{c_P} \right) \\ &= \frac{I}{c_P^2} (1 - e^{-c_P t}) \end{aligned}$$

$$\begin{aligned} \|u(t) - u_h(t)\|_{L^2(\Omega)} &\leq \|u(t) - P_h u(t)\|_{L^2(\Omega)} + \|e_h(t)\|_{L^2(\Omega)} \\ &\leq C h^{k+1} \|u(t)\|_{H^{k+1}(\Omega)} + e^{-\frac{c_P t}{2}} \|e_h(0)\|_{L^2(\Omega)} + \frac{C h^{k+1}}{c_P^2} \max_{0 \leq s \leq t} \|\dot{u}(s)\|_{H^{k+1}(\Omega)} \\ &\leq C h^{k+1} \|u(0)\|_{H^{k+1}(\Omega)} \quad (\text{equality implies } h^{k+1} \text{ is the best order}) \\ \|e_h(0)\|_{L^2} &= \|u(0) - P_h u(0)\|_{L^2} + \|u(0) - u_h(0)\|_{L^2(\Omega)} \\ &\leq C h^{k+1} \|u(0)\|_{H^{k+1}(\Omega)} \end{aligned}$$

### Fully discrete approximation

Start with backward Euler

The semi-discrete:  $(u_h, v) + a(u_h, v) = (f(t), v)$

$[0, T]$

$$0 = t_0 < t_1 < \dots < t_N = T, \quad t_i - t_{i-1} = K, \quad t_i = iK$$

$$\text{BE} \quad \left( \frac{u_h^n - u_h^{n-1}}{K}, v \right) + a(u_h^n, v) = (f(t_n), v) \quad \forall v \in V_h$$

where  $u_h^n \in V_h, \quad u_h^n = u(t_n, \cdot)$

$$\text{FE} \quad \left( \frac{u_h^n - u_h^{n-1}}{K}, v \right) + a(u_h^{n-1}, v) = (f(t_{n-1}), v) \quad \forall v \in V_h$$

$$u_h^n = \sum_{i=1}^N z_i^n \phi_i$$

$$\text{BE:} \quad B \vec{z}^n + K A \vec{z}^n = B \vec{z}^{n-1} + K \vec{F}^n \quad (B + K A) \vec{z}^n = B \vec{z}^{n-1} + K \vec{F}^n$$

$$\text{where} \quad \vec{z}^n = \begin{bmatrix} z_1^n \\ \vdots \\ z_N^n \end{bmatrix} \quad \vec{F}^n = \begin{bmatrix} f(t_n, \phi_1) \\ \vdots \\ f(t_n, \phi_N) \end{bmatrix}$$

$$\text{FE:} \quad B \vec{z}^n + K A \vec{z}^{n-1} = B \vec{z}^{n-1} + K \vec{F}^{n-1}$$

$$B \vec{z}^n = (B - K A) \vec{z}^{n-1} + K \vec{F}^{n-1}$$

eigenvalue of  $I - K A$  condition number가 중요하다 (21), 빨리 계산 가능

or mass lumping method (diagonal term만 남기는 방법) : error는 좀 증가하겠지만

distributed solution은



block diagonal matrix가 아니라

element들이 communicate하지 x → block을 invert하면 되니까

but more degree of freedom



Stability of BE. ( $f_n \equiv 0$ )

Let  $v = u_h^n$

might give better result

$$(u_h^n, u_h^n) + \kappa a(u_h^n, u_h^n) = (u_h^{n-1}, u_h^n)$$

$$\|u_h^n\|_{L^2(\Omega)}^2 \leq \|u_h^{n-1}\|_{L^2(\Omega)} \|u_h^n\|_{L^2(\Omega)}$$

$$\|u_h^n\|_{L^2(\Omega)} \leq \|u_h^{n-1}\|_{L^2(\Omega)} \quad \text{unconditionally stable}$$

prelim

FE \*

$$\|u_h^n\|_{L^2(\Omega)}^2 + \|u_h^n - u_h^{n-1}\|_{L^2(\Omega)}^2$$

$$= \|u_h^n\|_{L^2(\Omega)}^2 + (u_h^n, u_h^n) + (u_h^{n-1}, u_h^{n-1}) - 2(u_h^n, u_h^{n-1})$$

$$= 2(u_h^n, u_h^n) - 2(u_h^n, u_h^{n-1}) + (u_h^{n-1}, u_h^{n-1})$$

$$= 2(u_h^n, u_h^n - u_h^{n-1}) + (u_h^{n-1}, u_h^{n-1})$$

$$\downarrow \text{ since } (u_h^n, v) = -\kappa a(u_h^{n-1}, v) + (u_h^{n-1}, v)$$

$$= -2\kappa a(u_h^{n-1}, u_h^n - u_h^{n-1}) + 2(u_h^{n-1}, u_h^n - u_h^{n-1}) + (u_h^{n-1}, u_h^{n-1})$$

$$= -2\kappa a(u_h^{n-1}, u_h^n - u_h^{n-1}) - (u_h^{n-1}, u_h^{n-1}) + 2(u_h^{n-1}, u_h^n)$$

$$= -2\kappa a(u_h^{n-1}, u_h^n) + 2\kappa a(u_h^{n-1}, u_h^{n-1}) - (u_h^{n-1}, u_h^{n-1}) + 2(u_h^{n-1}, u_h^n)$$

$$\left. \begin{aligned} & (u_h^n, v) = -\kappa a(u_h^{n-1}, v) + (u_h^{n-1}, v) \quad \text{FE} \\ & \end{aligned} \right\}$$

$$= (u_h^{n-1}, u_h^{n-1}) - 2\kappa a(u_h^{n-1}, u_h^n)$$

$$\|u_h^n\|_{L^2(\Omega)}^2 + \|u_h^n - u_h^{n-1}\|_{L^2(\Omega)}^2 + \underbrace{2\kappa a(u_h^{n-1}, u_h^n)}_{2\kappa a(u_h^n, u_h^n) + 2\kappa a(u_h^{n-1} - u_h^n, u_h^n)} = (u_h^{n-1}, u_h^{n-1}) = \|u_h^{n-1}\|_{L^2(\Omega)}^2$$

$$\|u_h^n\|_{L^2(\Omega)}^2 + \|u_h^n - u_h^{n-1}\|_{L^2(\Omega)}^2 + 2\kappa a(u_h^n, u_h^n) = \|u_h^{n-1}\|_{L^2(\Omega)}^2 - 2\kappa a(u_h^{n-1} - u_h^n, u_h^n)$$

$$\leq \|u_h^{n-1}\|_{L^2(\Omega)}^2 + C_{inv} \frac{k}{h^2} \|u_h^{n-1} - u_h^n\|_{L^2(\Omega)}^2 + k \|\nabla u_h^n\|_{L^2(\Omega)}^2$$

$$- 2\kappa a(u_h^{n-1} - u_h^n, u_h^n) = -2\kappa (\nabla(u_h^{n-1} - u_h^n), \nabla u_h^n)$$

$$\leq \sqrt{2\kappa} \|\nabla(u_h^{n-1} - u_h^n)\|_{L^2(\Omega)} \sqrt{2\kappa} \|\nabla u_h^n\|_{L^2(\Omega)}$$

$$\leq \frac{C_{inv}}{h} \sqrt{2\kappa} \|u_h^{n-1} - u_h^n\|_{L^2(\Omega)} \sqrt{2\kappa} \|\nabla u_h^n\|_{L^2(\Omega)}$$

$$\leq \frac{C_{inv}^2}{2h^2} 2\kappa \|u_h^{n-1} - u_h^n\|_{L^2(\Omega)}^2 + \frac{2\kappa}{2} \|\nabla u_h^n\|_{L^2(\Omega)}^2$$

$$\rightarrow \|u_h^n\|_{L^2(\Omega)}^2 + (1 - C_{inv}^2 \frac{k}{h^2}) \|u_h^{n-1} - u_h^n\|_{L^2(\Omega)}^2 + k \|\nabla u_h^n\|_{L^2(\Omega)}^2 \leq \|u_h^{n-1}\|_{L^2(\Omega)}^2$$

$$C_{inv}^2 \frac{k}{h^2} \leq 1 \quad \text{so} \quad k \leq \frac{h^2}{C_{inv}^2}$$

big limitation.

