

Some vector calc review

A. M. Early,

$$\nabla \times \nabla \phi = \epsilon_{ijk} \partial_j \partial_k \phi$$

$$= \frac{1}{2} (\varepsilon_{ijk} + \varepsilon_{ikj}) \partial x_j \partial x_k \phi$$

$$= 0$$

Thm Helmholtz - Hodge decomposition

Given a smooth vector field $F \in \mathbb{R}^d$
on a simply connected subset of \mathbb{R}^d

there exist unique ϕ, A

$$F = -\nabla\phi + \nabla \times A$$

↑
scalar potential
curl-free

↑
vector potential
div-free

PF

$$\nabla \cdot F = -\nabla \cdot \nabla \phi + \nabla \cdot \nabla \times A$$

Solve

$$\begin{cases} -\nabla^2 \phi = \nabla \cdot F \\ \partial_n \phi|_{\partial\Omega} = -F \cdot \hat{n} \end{cases}$$

← aka pure
neumann
Dirichlet
problem

Note that this problem has a constant vector in its null-space

i.e. for any C

$$\nabla^2(\phi r c) = \nabla^2 \phi$$

$$\partial_n(\phi + c) = \partial_n \phi$$

To maintain coercivity in Lax-Milgram, need to work in space orthogonal to kernel

$$V_h = \{ \text{CPWL functions } u \mid u \cdot \vec{1} = 0 \}$$

e.g.
$$\min_{\phi} \int_{\Omega} \frac{1}{2} |\nabla \phi|^2 - \phi \nabla \cdot F + \lambda (\phi \cdot \vec{1}) - \int_{\partial\Omega} F \phi \cdot dA$$

Would be a way to enforce w/ Lagrange Multiplier

- That gave ϕ , now to get A

$$\nabla \times F = - \cancel{\nabla \times \nabla \phi} + \nabla \times \nabla \times A$$

Now we have a more challenging null space

$$\text{For any } \varphi, \quad \nabla \times \nabla \times (A + \nabla \varphi) = \nabla \times \nabla \times A$$

So we'd like solutions orthogonal to $\text{grad } \varphi$, for any φ

$$(A, \nabla \varphi) = 0 \quad \forall \varphi$$

Applying Galerkin


$$\begin{aligned} (\nabla \times \nabla \times A, v) &= (\nabla \times F, v) \\ &= (\nabla \times A, \nabla \times v) + \underbrace{\int_{\partial\Omega} (\nabla \times u \times \hat{n}) \cdot v \, dA}_{\text{Natural BC}} = (\nabla \times F, v) \end{aligned}$$

Natural BC

$$\nabla \times u \times \hat{n} = \nabla \times F \times \hat{n}$$

We can enforce w/ Lagrange mth. again

$$\begin{aligned} (\nabla \times \nabla \times A, v) + (\nabla \lambda, v) &= (\nabla \times F, v) - \langle \nabla \times F \times \hat{n}, v \rangle \\ (A, \nabla^2 v) &= 0 \end{aligned}$$

It'd be more work to show, but this is a saddle point problem that we showed how to approach last week. 

The Hodge decomposition is a useful tool for projecting onto a div-free or curl-free space.

e.g. $\pi_{\text{div-free}} u = \nabla \times A$

$$\pi_{\text{curl-free}} u = -\nabla \phi$$

Ex fluid mechanics

Potential flow was an early model of fluids (w/ large, restrictive assumptions) that was used e.g. to design air foils in 20's - 40's

Assume
$$\begin{cases} u = -\nabla\phi \\ \nabla \cdot u = 0 \end{cases}$$

Gives lift,
not drag

Then
$$\begin{cases} -\nabla^2\phi = 0 \\ \partial_n\phi|_{\partial\Omega} = u \cdot \hat{n} \end{cases}$$

No FEM back then \rightarrow Laplace transforms etc.

You'll still get this in a graduate fluids course

Ex Fluid Mechanics

When solving Navier-Stokes w/ incompressibility

$$\rho \frac{du}{dt} + u \cdot \nabla u = -\nabla p + \nu \nabla^2 u$$

$$\nabla \cdot u = 0$$

The incompressibility constraint is annoying

- Makes system bigger
- How to choose inf-sup u, p ?
- Couples all points in domain

A popular scheme (Alexandre Chorin, 1968)

Called a splitting - scheme

$$\textcircled{1} \quad \frac{u^* - u^n}{\Delta t} = -u^n \cdot \nabla u^n + \nu \nabla^2 u^*$$

$$\textcircled{2a} \quad \begin{cases} \frac{u^{n+1} - u^*}{\Delta t} = -\nabla p^{n+1} \\ \nabla \cdot u^{n+1} = 0 \end{cases}$$

Taking div of $\textcircled{2a}$

$$\cancel{\nabla \cdot u^{n+1}} - \frac{\nabla \cdot u^*}{\Delta t} = -\nabla^2 p^{n+1}$$

or

$$\boxed{u^{n+1} - u^* = \Pi_{\text{div-free}} u^* - u^*}$$

pressure - projection

Back to graphs

We introduced grad/div as coboundary, codifferential pair

$$\langle v, \delta_0 u \rangle = \langle \delta_0^* v, u \rangle$$

Now for the formal def. so we can talk curls.

def k -chain $C^k = [v_1, \dots, v_k]_{v_i \in V}$ anti-symmetric w.r.t. swaps

def boundary $\partial_{k-1} : C^k \rightarrow C^{k-1}$

$$\partial_{k-1} [v_1, \dots, v_k] = \sum_{i=1}^k (-1)^{i-1} [v_1, \dots, \hat{v}_i, \dots, v_k]$$

$\hat{}$ means leave this vertex out

ex For edge $[v_1, v_2] = -[v_2, v_1]$

$$\begin{aligned} \partial_0 [v_1, v_2] &= (-1)^0 [v_2] \\ &\quad + (-1)^1 [v_1] \\ &= v_2 - v_1 \end{aligned}$$

Thm Exact sequence property

$$\partial_{k-1} \circ \partial_k = 0$$

Pf Given $C \in C^{k+1}$

$$\partial_{k-1} \partial_k C = \sum_{i=1}^{k-1} (-1)^{i-1} \partial_k [n_1, \dots, \hat{n}_i, \dots, n_{k-1}]$$

$$= \sum_{i=1}^{k-1} \sum_j (-1)^{i-1} (-1)^{j-1} [n_1, \dots, \hat{n}_i, \dots, \hat{n}_j, \dots, n_k]$$

$$= \sum_{i,j} (-1)^{i+j-2} \alpha_{ij}$$

$$\alpha_{ij} = -\alpha_{ji}$$

anti-symmetric
if we exchange i, j

$$= 0$$

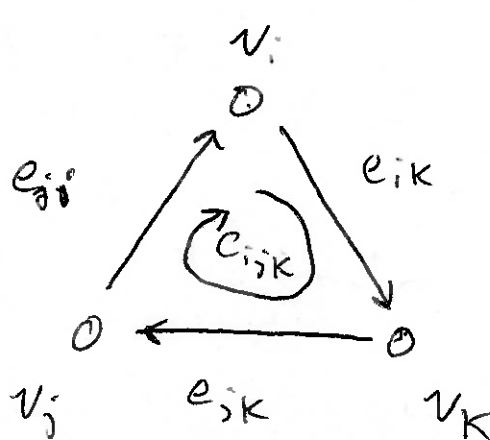


Illustrative sketch

$$C_{ijk} = [v_i, v_j, v_k]$$

$$\begin{aligned} \partial C_{ijk} &= e_{ji} + e_{ik} + e_{jk} \\ &= [v_j, v_i] + [v_k, v_i] \\ &\quad + [v_k, v_j] \end{aligned}$$

$$\begin{aligned} \partial \partial C_{ijk} &= v_j - v_i + v_i - v_k \\ &\quad + v_k - v_j \end{aligned}$$



$$v_i \begin{pmatrix} + \\ - \end{pmatrix}$$

$$v_j \begin{pmatrix} - \\ + \end{pmatrix}$$

$$v_k \begin{pmatrix} + \\ - \end{pmatrix}$$

To define the coboundary (div/grad/curl)
just swap chains w/ cochains

For $f \in C_k$

~~$$df(v_1, \dots, v_k) = \sum_i (-1)^i f(v_1, \dots, \hat{v}_i, \dots, v_k)$$~~

$$\delta_{k-1} f = \sum_i (-1)^i f(v_1, \dots, \hat{v}_i, \dots, v_k)$$

ex $\delta_0 \phi_{ij} = \phi_j - \phi_i$ graph gradient

$$\delta_1 A_{ijk} = A_{ij} + A_{jk} + A_{ki} \quad \text{graph curl}$$

$$\text{curl} \circ \text{grad} = 0$$

$$\begin{aligned} \delta_1 \delta_0 \phi &= \delta_0 \phi_{ij} + \delta_0 \phi_{jk} + \delta_0 \phi_{ki} \\ &= \phi_j - \phi_i + \phi_k - \phi_j + \phi_i - \phi_k \\ &= 0 \end{aligned}$$

If $\delta_1 \delta_0 = 0$, $\delta_0^* \delta_1^* = 0$ (div of curl = 0)

pf $\langle f, \delta_0^* \delta_1^* g \rangle$

$$= \langle \delta_0 f, \delta_1^* g \rangle$$

$$= \langle \delta_1 \delta_0 f, g \rangle$$

$$= 0$$

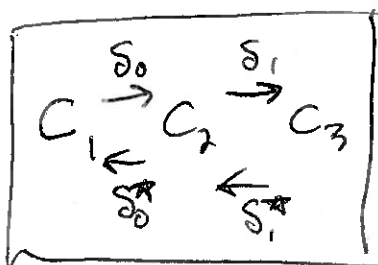
Recall

$$\delta_0 = \text{grad}$$

$$\delta_0^* = \text{div}$$

$$\delta_1 = \text{curl}$$

$$\delta_1^* = \text{curl}^*$$



Graph Hodge Decomposition

thm Given $f \in C_K$

$$f = \delta_0 \phi + \delta_1^* A$$

pf

$$\delta_0^* f = \delta_0^* \delta_0 \phi + \cancel{\delta_0^* \delta_1^* A}$$

$$\delta_1 f = \cancel{\delta_1 \delta_0 \phi} + \delta_1 \delta_1^* A$$

Given observations on some preferences y_{ij}^{data}

$$\min_S \sum_{i,j} w_{ij} (y_{ij}^{data} - \mathcal{L}(S_{ij}))^2$$

Take the variation of this (HW exercise)

$$\boxed{S_0^* W S_0 S = S_0^* W Y^{data}}$$

see papers on git, ①

Causality

Given a set of events X_i , a causal structural model is a

decomposition

$$P(x_1, \dots, x_N) = \prod_{i=1}^N P(x_i | \underset{\substack{\uparrow \\ \text{Parents}}}{Pa(x_i)}})$$

Define a score S_i

$$\text{flux } F = S_0 S$$

and parent $Pa(x_i) = \{x_j : F_{ij} \geq 0\}$

or a differentiable version

$$Pa(x_i) = \left\{ \text{ReLU} \left(\tanh \left(\frac{1}{\beta} F_{ij} \right) \right) \geq 0 \right\}$$

