

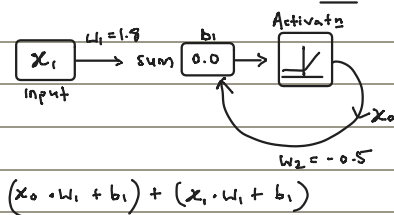
## Recurrent Neural Network

- Designed for processing sequential data
- Output of node depends on current input & all previous outputs (implicitly all previous inputs)
- Useful for tasks requiring context / temporal dependence → Time Series Forecasting / Language Modelling
- Defining feature = hidden state / memory → capture temporal rls in sequential data.
- Eg Input: stock mkt prices collected over time
  - ↳ yesterday price  $y_0$
  - Today price  $y_i$
  - Tmr price TBP
- Foundation for Long Short-Term Memory Networks & Transformers.
- Fundamental for NLP, Time Series Analysis & Computer Vision

### How RNN works

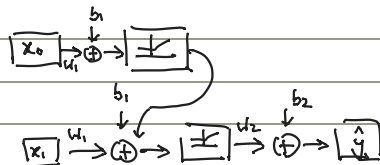
Suppose we know  $x_0$  &  $x_1$  & model takes in single input

- 1) Input  $x_0$  as input
- 2) At output of hidden layer → output layer as prediction  
→ feedback loop
- 3) Go through feedback loop
- 4) pass in  $x_1$  as next input & sum



### Unrolling of RNN as conceptualization

- Does not create multiple physical copies of network
- Same weights & biases used across all networks
- No. of "copies" dependent on how many data points needed for prediction  
↳ eg yesterday + today to predict tomorrow  
 $1 + 1 = 2$  "copies"



- Weights & bias remains similar.
- More unrolling = harder to train (vanishing / exploding gradient)
  - ↳ if weight  $x2$  & memory = 50, output =  $2^{50} \rightarrow \infty$   
Soln: limit weights to below 1.
  - Problem: vanishing gradient  
if weight  $x0.5$  & memory = 50, output =  $0.5^{50} \rightarrow 0$
- Solution: Long Short-term memory networks.

## RNN Math

$\hat{y}_t = w_o \cdot h_t + \beta_o$  (Output Weight, Output bias)  
 $h_t = \sigma(w_h \cdot h_{t-1} + w_x \cdot x_t + \beta_h)$  (Weight of hidden layer, Input, Bias of hidden layer)  
 hidden state from previous time step

$$h_t = \sigma(w_h \cdot h_{t-1} + w_x \cdot x_t + \beta_h)$$

$$\hat{y}_t = w_o h_t + \beta_o$$

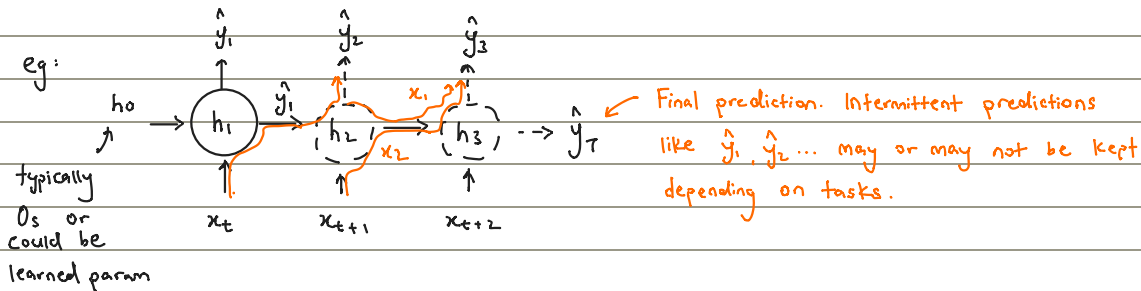
$$h_{t+1} = \sigma(w_h \cdot h_t + w_x \cdot x_{t+1} + \beta_h)$$

$$\hat{y}_{t+1} = w_o h_{t+1} + \beta_o$$

⋮

### Hidden state $h_t$

- captures memory of sequence up to that point
- Prediction made with current input & past inputs



$$p(\hat{y}_1 = k | x_1)$$

$$p(\hat{y}_L = k | x_1, x_L)$$

$$p(\hat{y}_T = k | x_1, \dots, x_T)$$

### Hidden Layer / Hidden state of RNN

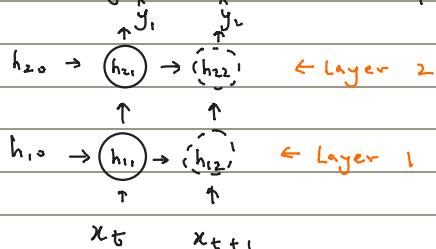
#### 1) Single Hidden Layer

hidden state updated at each timestep based on input & previous hidden state

- common for time-series prediction or sequence classification

- stock price forecast
- Economic Indicators
- Demand forecasting
- sentiment analysis
- Speech recognition
- NLP.

#### 2) Multi Layer Hidden state (Deep RNN)



Allows model to learn more abstract and hierarchical features of sequence data

### Input Dimensions for RNN

$N \times T \times D$  (samples x time steps x feature dimensions)

Stock Price eg:

$N = 30$  companies

$T = 30$  days of price

$D = 4$  features (OHLC)

$30 \times 30 \times 4$

Healthcare:

$N = 100$  patients

$T = 24$  hours (data / hour)

$D = 3$  features (heart rate, blood pressure, Temp.)

$100 \times 24 \times 3$

\* In TensorFlow,  $T$  is constant size (pad if needed) Input shape =  $(T \times D)$

$M$ : No. of hidden units

$K$ : No. of output units : Regression can also be multidimensional

## Simple RNN in TensorFlow

input = Input(shape = (T, D))

\* For Regression task, don't need  
activation fn

x = SimpleRNN(<No-hidden-nodes>)(input)

x = Dense(<No-output-nodes>)(x)

model = Model(input, x)

↑      ↑      ↑ output tensor  
Input tensor → shape & type of Input

• Keras functional API

• specify inputs & outputs in NN

model.summary() : See all layers & relevant details

model.layers[<layer-no>].get\_weights()

↳ print shape, can unpack as needed.

↳ 3 layers = 3 to unpack.

Input Dim - D x H - Hidden Dim

H x H

H x O - output Dim