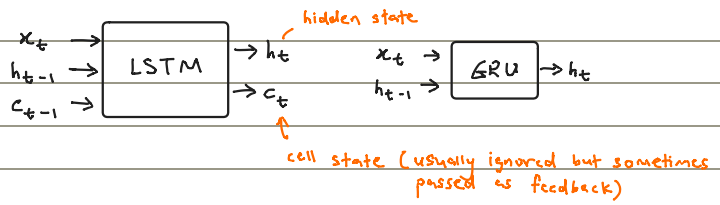
LSTM

- more complex than GRU
- more performant than GRU in recent research
- ML is experimentation, not theoreticizing
- LSTMs = GRU with more state vectors & gates



* Need 2 initial states h_0 & c_0

LSTM Equations

$f_t = \sigma(W_{xf}^T x_t + W_{hf}^T h_{t-1} + b_f)$: forget gate

$i_t = \sigma(W_{xi}^T x_t + W_{hi}^T h_{t-1} + b_i)$: input / update gate

$o_t = \sigma(W_{xo}^T x_t + W_{ho}^T h_{t-1} + b_o)$: output gate

} Acts as binary classifier — remember / forget

$c_t = f_t \odot c_{t-1} + i_t \odot f_c(W_{xc}^T x_t + W_{hc}^T h_{t-1} + b_c)$: cell state, similar concept to h_t in GRU

$h_t = o_t \odot f_h(c_t)$

f_c : Activation fn for Simple RNN

f_h : Activation (typically tanh)

h_t : hidden state

c_{t-1} : how much of c_{t-1} to forget

i_t : how much of Simple RNN to remember / forget

o_t : controls which values of cell state to pass through

$f_h(c_t)$: (squashed output of cell state)

* In TensorFlow, cannot customize f_c & f_h independently.

LSTM TensorFlow

```
input = Input(shape = (T, D))
x = LSTM(M)(input)        M = No. of hidden units
x = Dense(K)(x)           K = No. of output units
model = Model(input, x)
```

get $h_1, h_2 \dots h_T$ to calculate $y_1, y_2 \dots y_T$ eg: for language translation

```
x = LSTM(M, return_sequences = True)(input)
x = Dense(K)(x)
```

output will be N x T x M (All h_t; M = No. of hidden units)

output will be N x T x K (K = No. of output nodes)

Options for RNN units

```
SimpleRNN(M, return_state = True)
GRU(M, return_state = True)
```

} output o & hidden state h are same thing. h_T returned

```
LSTM(M, return_state = True)
```

Get both h_T & c_T (c_T : cell state)