# Multiple Linear Regression

Adam Lee

## I. Introduction

Our definition of linearity yields a significant amount of flexibility for our regression models. We can extend our definition for simple linear regression to form a regression model with multiple regressors each of which does not itself need to be linear but instead is accompanied by a linear coefficient. That is we can fit a model

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_n x_n + \varepsilon, \tag{1}$$

where y is our response variable and  $x_i$  for i = 1, ..., n are our regressors. It must be noted the term linear is used here since eq. (1) is a linear function of the unknown parameters  $\beta_i$ . This means we can choose our regressor terms freely. More complex models may allow for a polynomial fit.

Example 1: Consider the polynomial model

$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + \varepsilon. \tag{2}$$

If we let  $x_i := x^i$  then this model takes the form

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \varepsilon, \tag{3}$$

and is a linear regression model with three unknown regression coefficients and two regressors. It is still linear in our coefficients  $\beta_i$  however allows a much more flexible model.

We can extend our definition of a multiple linear regression model further to include interaction terms. For example, consider the model

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2. \tag{4}$$

If we rewrite this model such that  $\beta_{12}x_1x_2 = \beta_3x_3$  then we have a model of a familiar form

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3.$$

#### II. MULTIPLE LINEAR REGRESSION

Let us focus on the generic case with model

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_n x_n + \varepsilon. \tag{5}$$

This model describes an n+1 dimension hyperplane, as opposed to the regression line we constructed for the simple case. The parameters  $\beta_i$  are our regression coefficients and in practice these, as well as the variance of the error  $\epsilon$ , are unknown. The particular parameter  $\beta_j$  represents the expected change in y per unit change in  $x_j$  under the assumption that all other regressors  $x_k$ ,  $(k \neq j)$  are constant. Figure 1 provides graphic representation of a two-regressor, non-interacting model.

**Example 2:** Consider a model where our expected error is zero

$$E(y) = 10 + 15x_1 + 4x_2. (6)$$

We can examine the hyperplane this model describes.

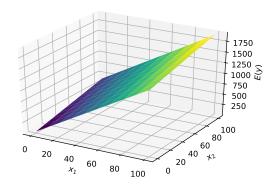


Fig. 1: Hyperplane plot for eq. (6)

## III. ESTIMATION OF PARAMETERS

#### A. Least-Squares Estimation

We have already come across the least-squares estimation of parameters for simple linear regression, and this method can be extended for multiple linear regression.

Let us assume we have a data-set  $\varkappa = \{y_i, x_{i1}, \dots, x_{in}\}_{i=0}^k$  where n > k. Here,  $y_i$  denotes the *i*-th observed response and  $x_{ij}$  denotes the observed value  $x_i$  for regressor  $x_j$ . Then, we have a system of model equations

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_n x_{in} \quad i = 0, \dots, k.$$
 (7)

We can then assume matrix notation for the entire set such that

$$\mathbf{y} = X\boldsymbol{\beta} + \boldsymbol{\varepsilon}.\tag{8}$$

where

$$\mathbf{y} = \begin{pmatrix} y_0 \\ y_1 \\ \vdots \\ y_k \end{pmatrix}, \tag{9}$$

$$X = \begin{pmatrix} 1 & x_{01} & \cdots & x_{0n} \\ 1 & x_{11} & \cdots & x_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{k1} & \cdots & x_{kn} \end{pmatrix}, \tag{10}$$

$$\boldsymbol{\beta} = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_n \end{pmatrix}, \tag{11}$$

and

$$\boldsymbol{\varepsilon} = \begin{pmatrix} \varepsilon_0 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_k \end{pmatrix}. \tag{12}$$

Clearly, this is a closed system so we can formulate arguments for all  $\beta$  with the information contained within this problem.