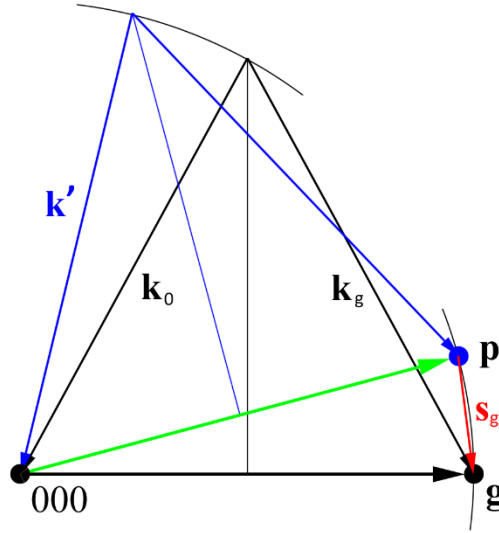


Technical note – calculation of deviation parameter s_g .



The above figure shows the Ewald sphere construction for an incident beam in the Bragg condition \mathbf{k}_0 and diffraction vector \mathbf{g} . For an incident beam in a general orientation \mathbf{k}' , the deviation parameter s_g is given by the vector linking point \mathbf{p} and \mathbf{g} . The problem is to find the magnitude of s_g , given \mathbf{k}' and \mathbf{g} . There are three conditions that define point \mathbf{p} .

1) The length of the vector \mathbf{p} (green) has magnitude g , i.e.

$$p_1^2 + p_2^2 + p_3^2 = g^2 \quad (1)$$

2) The vector \mathbf{k}' lies in the Bragg condition with relation to \mathbf{p} , i.e.

$$\mathbf{k}' \cdot \mathbf{p} = k'_1 p_1 + k'_2 p_2 + k'_3 p_3 = -\frac{g}{2} \quad (2)$$

3) The vectors \mathbf{k}' , \mathbf{p} and \mathbf{g} are co-planar, i.e.

$$(\mathbf{k} \times \mathbf{g}) \cdot \mathbf{p} = 0 \quad (3)$$

The algebra can be simplified by choosing a reference frame in which the y-components of \mathbf{k}' , \mathbf{p} and \mathbf{g} are zero and \mathbf{g} lies along the x-axis, i.e. $\mathbf{g} = [g, 0, 0]$. In this reference frame, \mathbf{k}_0 can be written as a vector \mathbf{m} given by

$$\mathbf{m} = \begin{bmatrix} \mathbf{k}_0 \cdot \hat{\mathbf{g}} & 0 & (k^2 - (\mathbf{k}_0 \cdot \hat{\mathbf{g}})^2)^{\frac{1}{2}} \end{bmatrix} = [m_1 \ 0 \ m_3] \quad (4)$$

where $\hat{\mathbf{g}}$ is a unit vector parallel to \mathbf{g} and the vector \mathbf{k}' can be written as a vector \mathbf{n} given by

$$\mathbf{n} = \begin{bmatrix} \mathbf{k}' \cdot \hat{\mathbf{g}} & 0 & (k'^2 - (\mathbf{k}' \cdot \hat{\mathbf{g}})^2)^{\frac{1}{2}} \end{bmatrix} = [n_1 \ 0 \ n_3] \quad (5)$$

Thus, equations 1 and 2 become

$$p_1^2 + p_3^2 = g^2 \quad (6)$$

$$\mathbf{n} \cdot \mathbf{p} = n_1 p_1 + n_3 p_3 = -\frac{g}{2} \quad (7)$$

i.e.

$$p_1 = -\frac{g}{2n_1} - \frac{n_3}{n_1} p_3 \quad (8)$$

Substituting into (6) gives

$$\left(\frac{g}{2} + n_3 p_3\right)^2 + n_1^2 p_3^2 = n_1^2 g^2 \quad (9)$$

Expanding

$$\frac{g^2}{4} + g n_3 p_3 + n_3^2 p_3^2 + n_1^2 p_3^2 = n_1^2 g^2 \quad (10)$$

Rearranging

$$p_3^2 (n_3^2 + n_1^2) + g n_3 p_3 + g^2 \left(\frac{1}{4} - n_1^2\right) = 0 \quad (11)$$

And since the vector \mathbf{n} has magnitude k we have

$$k^2 p_3^2 + g n_3 p_3 + g^2 \left(\frac{1}{4} - n_1^2\right) = 0 \quad (12)$$

With the usual quadratic equation solution, i.e.

$$p_3 = \frac{g}{2k^2} \left(n_3 \pm \sqrt{n_3^2 - k^2(1 - 4n_1^2)} \right) \quad (13)$$

Equation (6) can then be used to obtain p_1 . Finally, the magnitude of \mathbf{s}_g is

$$s_g = ((g - p_1)^2 + p_3^2)^{1/2} \quad (14)$$

There are two regimes for the calculation plus a singularity.

a) when $\mathbf{k}' \cdot \hat{\mathbf{g}} < 0$ the - solution in (13) is used.

c) when $\mathbf{k}' \cdot \hat{\mathbf{g}} > 0$ the + solution in (13) is used.

When $\mathbf{k}' \cdot \hat{\mathbf{g}} = 0$ equation (13) requires SQRT(ZERO), which can be avoided by using $s_g = g/2k$