

CSC 791/495

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Optimization & Approximation

optimization problems

- instance \rightarrow solution w/ cost.

- goal: find a solution w/ min(max) cost.

objective: max/min cost. solution

$OPT(x) = \min/\max$ possible cost of a solution for x .

\uparrow instance

(valid/feasible)

Ex: Vertex Cover \rightarrow min. VC

Clique \rightarrow max Clique

Ind. Set \rightarrow max IS.

Makespan Scheduling (min)

\uparrow cost \neq soln size

NPO: (equiv of NP)

$\left\{ \begin{array}{l} \circ \text{ size of soln} \in P \\ \circ \text{ recognize instance/soln} \in P \\ \circ \text{ cost function} \in P \end{array} \right.$

decision problem: Is $OPT(x) \leq q?$ (min)

\uparrow NP

$OPT(x) \geq q?$ (max)

instance $\rightarrow \forall x$

Approximation We say ALG is a c-approximation for a problem if $\forall x$

$$\frac{\text{cost}(\text{ALG}(x))}{\text{cost}(\text{OPT}(x))} \leq c \quad (\min)$$

note: $c \geq 1$

$$\frac{\text{cost}(\text{ALG}(x))}{\text{cost}(\text{OPT}(x))} \geq c \quad (\max)$$

$c \leq 1$

usually require ALG to be poly-time.

Examples

① Vertex Cover:

Idea: greedy strategy. Not good to add all n , but what about one at a time?

Arbitrary order \rightarrow could devolve to \nearrow Star \Rightarrow probably high-deg is a good idea.

ALG: While $E(G_i) \neq \emptyset$, add v to cover C where v has max deg in G_i ; delete $v \rightarrow G_{i+1}$

(*) Goal: show that after OPT steps, $\geq \frac{1}{2}$ edges are covered (removed)

\Rightarrow run OPT $\Rightarrow \frac{1}{2}$ covered; run 2OPT $\Rightarrow \frac{1}{2} + \frac{1}{4} \dots$ run for $O(DPT \log n) \rightarrow 1$

If we show (*) $\Rightarrow O(\log n)$ -approx alg.

Exercise: show (*).

①b) greedily covering edges actually leads to a much better approximation.

ALG: while $E(G_i) \neq \emptyset$, pick an edge uv , add u and v to C . delete $u, v \rightarrow G_{i+1}$.

When considering edge uv , we know either $u \in C$ or $v \in C$. So by adding both, we could only have doubled the necessary size.

In-class Exercise

ALG 2: sort so $p_1 \geq p_2 \geq \dots$ then apply ALG 1. Show $3/2$ using similar analysis on last job.

Load balancing: Given jobs j_1, \dots, j_k w/ processing times p_1, \dots, p_k and two machines M_1, M_2 . Goal: assign jobs to machines so that makespan $(\max_{i=1,2} \sum_{j \rightarrow M_i} p_j)$ is minimized.

Goal: design a 2-approx. Improve it to $3/2$ -approx.

Observe: $\text{OPT} \geq \max \{p_i\}$.

Observation 2: $\text{OPT} \geq \frac{1}{2} \sum p_i \longrightarrow \text{ALGO: use 1 machine.}$

ALG 1: Assign a job $j_1 \rightarrow$ machine M_1 . Now assign jobs to M_2 until

$\sum_{j \rightarrow M_2} p_j > p_1$ (M_2 has more work) \Rightarrow assign another job to M_1 . repeat until it has more work. Let $w_j[i]$ = amount of work assigned to machine j

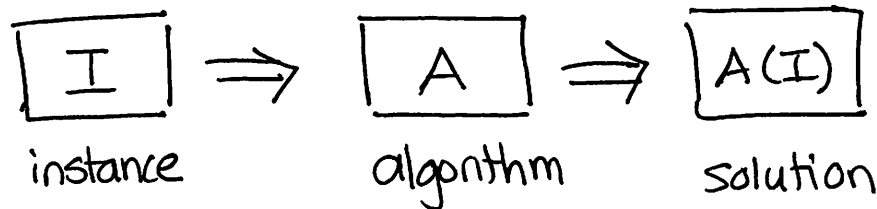
when job i is allocated.

Look @ machine v w/ longest runtime. Consider the last job v it was assigned.

$$w_1[k] \leq \frac{1}{2} \sum p_i \leq \text{OPT} \quad \text{ALG 1} \quad \boxed{w_1[k] \leq w_2[k]} \quad \text{step } k \quad p_k \leq \text{OPT} \quad \text{total} \leq 2 \cdot \text{OPT}$$

PTAS Strategies

o we know that our problem is likely hard to solve exactly.



if A is exact,
 $\text{cost}(A(I)) = \text{OPT}(I)$

solution: add "structure" that depends on ε . $\left(\begin{array}{l} \varepsilon \text{ big} \Rightarrow \text{lots} \\ \varepsilon \text{ small} \Rightarrow \text{little} \end{array} \right)$

Implies 3 strategies

- ① structure on input
 - ② structure on output
 - ③ structure during execution.
- ← } we'll talk about these

↑
more approx / PTAS
references:

both have free
PDFs
online ☺

- ① Design of Approximation Algorithms by Williamson & Shmoys
- ② Approximation Algorithms by Vazirani

Structuring Input

- (A) simplify $I \rightarrow I^*$ in poly. time.
- (B) solve on I^* in poly time. $\leftarrow I^*$ had better be nice!
- (C) translate solution back (exploit similarity)

Ex Load Balancing $\{p_1, \dots, p_k\}$ & two machines M_1, M_2 .
proc. times

Ideas for (A):

- rounding
- merging
- cutting
- aligning

define $L = \max(\frac{1}{2} \sum p_i, \max(p_i))$
 $L \leq \text{OPT}$

categorize jobs: big $p_i > \epsilon L$
small $p_i \leq \epsilon L$

(A): $I \rightarrow I^*$

big jobs remain the same. (I^* has $p_i \forall i$ w/ $p_i > \epsilon L$)

let $S = \sum_{\text{small job}} p_i \Rightarrow$ give I^* $\lfloor S/\epsilon L \rfloor$ jobs w/ cost ϵL each.

(B) key: how many jobs in I^* ? how big are I^* 's jobs? $> \epsilon L$

all jobs take $\leq 2L. \Rightarrow \# \text{jobs} \leq \frac{2L}{\epsilon L} = \frac{2}{\epsilon}$ brute force! $2^{2/\epsilon}$

Structuring Input, cont

(C) translation of jobs in I^* to I .

• obviously, schedule big jobs on same machine as in I^* .

• reserve $\begin{cases} S_1^* + 2\varepsilon L & \text{on } M_1 \\ S_2^* & \text{on } M_2 \end{cases}$ say $S_i^* = \underbrace{\sum \text{small jobs on } M_i^*}_{\varepsilon L}$ in I^*

greedily assign small jobs in I to M_1 until no more fit in the reserved space. Observe: $\geq S_1^* + \varepsilon L$ is filled

claim less than S_2^* total small jobs remain.

M_1 has $\leq \underbrace{B_1^* + S_1^*}_{\varepsilon L} + 2\varepsilon L$

M_2 has $\leq \underbrace{B_2^* + S_2^*}_{\varepsilon L}$

$$S \leq \underbrace{S_1^* + S_2^* + \varepsilon L}_{\text{threw away } \leq \varepsilon L \text{ time } I \rightarrow I^*}$$

$$\text{know: } S + B \leq 2L \leq 2OPT$$

$$\max(B_1^* + S_1^*, B_2^* + S_2^*) = OPT(I^*)$$

$$\text{claim: } OPT(I^*) \leq (1+\varepsilon)OPT(I).$$

$$\underbrace{OPT(I^*) \leq OPT(I) + \varepsilon L}_{\downarrow} \leq (1+\varepsilon)OPT$$

$(1+3\varepsilon)$ on entire scheme.