## 8 Aggregate risk

- 8.1 Coherent and convex risk measures
- 8.2 Law-invariant coherent risk measures
- 8.3 Risk measures for linear portfolios
- 8.4 Risk aggregation
- 8.5 Capital allocation

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## 8.1 Coherent and convex risk measures

- Consider a linear space  $\mathcal{M} \subseteq \mathcal{L}^0(\Omega, \mathcal{F}, \mathbb{P})$  (a.s. finite rvs).
- Each  $L \in \mathcal{M}$  (incl. constants) represents a loss over a fixed time horizon.
- A *risk measure* is a mapping  $\varrho : \mathcal{M} \to \mathbb{R}$ ;  $\varrho(L)$  gives the total amount of capital needed to back a position with loss L.
- $C \subseteq \mathcal{M}$  is *convex* if  $(1 \gamma)x + \gamma y \in C$  for all  $x, y \in C$ ,  $0 < \gamma < 1$ . C is a *convex cone* if, additionally,  $\lambda x \in C$  when  $x \in C$ ,  $\lambda > 0$ .
- Axioms for  $\varrho$  we consider are:

Monotonicity:  $L_1 \leq L_2 \Rightarrow \varrho(L_1) \leq \varrho(L_2)$ .

Translation invariance:  $\varrho(L+m)=\varrho(L)+m$  for all  $m\in\mathbb{R}$ .

**Subadditivity:**  $\varrho(L_1 + L_2) \leq \varrho(L_1) + \varrho(L_2)$  for all  $L_1, L_2 \in \mathcal{M}$ .

**Positive homogeneity:**  $\varrho(\lambda L) = \lambda \varrho(L)$  for all  $\lambda \geq 0$ .

Convexity:  $\varrho(\gamma L_1 + (1 - \gamma)L_2) \le \gamma \varrho(L_1) + (1 - \gamma)\varrho(L_2)$  for all  $0 \le \gamma \le 1$ ,  $L_1, L_2 \in \mathcal{M}$ .

## Definition 8.1 (Convex, coherent risk measures)

- A risk measure which satisfies monotonicity, translation invariance and convexity is called *convex*.
- A risk measure which satisfies monotonicity, translation invariance, subadditivity and positive homogeneity is called *coherent*.

A coherent risk measure is convex; the converse is not true, see below. On the other hand, for a positive-homogeneous risk measure, convexity and coherence are equivalent.

## 8.1.1 Risk measures and acceptance sets

## Definition 8.2 (Acceptance set)

For a monotone and translation-invariant risk measure  $\varrho$  the acceptance set of  $\varrho$  is  $A_{\varrho}=\{L\in\mathcal{M}:\varrho(L)\leq 0\}$  (so it contains the positions that are acceptable without any backing capital).

## **Proposition 8.3**

Let  $\varrho$  be monotone and translation-invariant with associated  $A_{\varrho}$ . Then

1)  $A_{\varrho} \neq \emptyset$  and  $A_{\varrho}$  satisfies

$$L \in A_{\varrho} \text{ and } \tilde{L} \leq L \Rightarrow \tilde{L} \in A_{\varrho}. \tag{35}$$

2)  $\varrho$  can be reconstructed from  $A_{\varrho}$  via

$$\varrho(L) = \inf\{m \in \mathbb{R} : L - m \in A_{\varrho}\}. \tag{36}$$

*Proof.* 1) is clear. For 2), note that  $\inf\{m: L-m \in A_{\varrho}\} = \inf\{m: \varrho(L-m) \leq 0\} = \inf\{m: \varrho(L)-m \leq 0\}$  and this is equal to  $\varrho(L)$ .  $\square$ 

#### **Proposition 8.4**

Suppose that A satisfies (35) and define

$$\varrho_A(L) = \inf\{m \in \mathbb{R} : L - m \in A\}. \tag{37}$$

Suppose  $\varrho_A(L)$  is finite for all  $L\in\mathcal{M}$ . Then  $\varrho_A$  is monotone and translation-invariant on  $\mathcal{M}$  and  $A_{\varrho_A}$  satisfies  $A_{\varrho_A}\supseteq A$ .

*Proof.* These properties of  $\varrho_A$  are easily checked.

## Example 8.5 (Value-at-risk)

For  $\alpha \in (0,1)$ , suppose we call  $L \in \mathcal{M}$  acceptable if  $\mathbb{P}(L>0) \leq 1-\alpha$ . Then (37) is given by

$$\varrho_{\alpha}(L) = \inf\{m \in \mathbb{R} : \mathbb{P}(L - m > 0) \le 1 - \alpha\}$$
$$= \inf\{m \in \mathbb{R} : \mathbb{P}(L \le m) \ge \alpha\} = \operatorname{VaR}_{\alpha}(L).$$

## **Proposition 8.6**

- 1) Let  $\varrho$  be monotone and translation-invariant. Then
  - 1.1)  $\varrho$  is convex if and only if  $A_{\varrho}$  is convex.
  - 1.2)  $\varrho$  is coherent if and only if  $A_{\varrho}$  is a convex cone.
- 2) More generally, consider a set of acceptable positions A and the associated risk measure  $\varrho_A$  (whose acceptance set may be larger than A). If A is convex, so is  $\varrho_A$ ; if A is a convex cone, then  $\varrho_A$  is coherent.

## Example 8.7 (Risk measures based on loss functions)

Consider a strictly increasing and convex loss function  $\ell:\mathbb{R}\to\mathbb{R}$  and some  $c\in\mathbb{R}$ . Assume that  $\mathbb{E}(\ell(L))$  is finite for all  $L\in\mathcal{M}$ . Define an acceptance set by

$$A = \{ L \in \mathcal{M} : \mathbb{E}(\ell(L)) \le \ell(c) \},\$$

and the associated risk measure by

$$\varrho_A = \inf\{m \in \mathbb{R} : \mathbb{E}(\ell(L-m)) \le \ell(c)\}.$$

- $\varrho_A$  is translation invariant and monotone by Proposition 8.4 since A satisfies (35).
- $\varrho_A$  is convex by Proposition 8.6; to see this consider acceptable positions  $L_1$  and  $L_2$  and observe that the convexity of  $\ell$  implies

$$\mathbb{E}(\ell(\gamma L_1 + (1 - \gamma)L_2)) \le \mathbb{E}(\gamma \ell(L_1) + (1 - \gamma)\ell(L_2))$$
  
$$\le \gamma \ell(c) + (1 - \gamma)\ell(c) = \ell(c),$$

where we have used that  $\mathbb{E}(\ell(L_i)) \leq \ell(c)$  for acceptable positions. Hence  $\gamma L_1 + (1 - \gamma)L_2 \in A$ , so A is convex.

■ Example:  $\ell(x) = \exp(\alpha x)$  for some  $\alpha > 0$ . Then

$$\varrho_{\alpha,c}(L) := \inf\{m : \mathbb{E}(e^{\alpha(L-m)}) \le e^{\alpha c}\} = \inf\{m : \mathbb{E}(e^{\alpha L}) \le e^{\alpha c + \alpha m}\}$$
$$= \frac{1}{\alpha} \log(\mathbb{E}(e^{\alpha L})) - c.$$

Note that  $\varrho_{\alpha,c}(0)=-c$ , so  $\varrho_{\alpha,c}$  cannot be coherent. For c=0 and

 $\lambda > 1$ , the *entropic risk measure*  $\varrho_{\alpha,0}$  satisfies

$$\varrho_{\alpha,0}(\lambda L) = \frac{1}{\alpha} \ln \{ \mathbb{E}(e^{\alpha \lambda L}) \} \ge \frac{1}{\alpha} \ln \{ \mathbb{E}(e^{\alpha L})^{\lambda} \} = \lambda \varrho_{\alpha,0}(L),$$

where the inequality is strict if L is non-degenerate. This shows that  $\varrho_{\alpha,0}$  is convex but not coherent. If L are insurance claims,  $\varrho_{\alpha,0}$  is known as exponential premium principle.

#### Example 8.8 (Stress test or worst case risk measure)

Given stress scenarios  $S\subseteq\Omega$ , a stress test risk measure can be defined by

$$\varrho(L) = \sup\{L(\omega) : \omega \in S\},\$$

that is, the worst loss on S. The associated acceptance set is

$$A_{\varrho} = \{L : L(\omega) \le 0 \text{ for all } \omega \in S\}.$$

The choice of S is often guided by the underlying probability measure  $\mathbb{P}$ .

## Example 8.9 (Generalized scenario risk measures)

Consider a set  $\mathcal Q$  of probability measures on  $(\Omega,\mathcal F)$  and a *penalty function*  $\gamma:\mathcal Q\to\mathbb R$  such that  $\inf\{\gamma(\mathbb Q):\mathbb Q\in\mathcal Q\}>-\infty.$  Suppose  $\sup_{\mathbb Q\in\mathcal Q}\mathbb E_\mathbb Q|L|<\infty$  for all  $L\in\mathcal M.$  The *generalized scenario risk measures*  $\varrho$  is defined by

$$\varrho(L) = \sup\{\mathbb{E}_{\mathbb{Q}}(L) - \gamma(\mathbb{Q}) : \mathbb{Q} \in \mathcal{Q}\}.$$
(38)

The corresponding acceptance set is given by

$$A_{\varrho} = \{ L \in \mathcal{M} : \sup \{ \mathbb{E}_{\mathbb{Q}}(L) - \gamma(\mathbb{Q}) : \mathbb{Q} \in \mathcal{Q} \} \le 0 \}.$$

- $A_{\rho}$  is convex, and thus so is  $\varrho$ .
- Every convex risk measure can be represented as (38); see Theorem 8.10.
- If  $\gamma(\cdot) \equiv 0$  on  $\mathcal{Q}$ ,  $\varrho$  is positive homogeneous and therefore coherent.
- The stress test risk measure of Example 8.8 is a special case of (38) in which  $\gamma \equiv 0$  and  $\mathcal Q$  is the set of all Dirac measures  $\delta_\omega(\cdot),\ \omega \in S$ , that is,  $\delta_\omega(B) = I_B(\omega)$  for arbitrary measurable sets  $B \subseteq \Omega$ .

## 8.1.2 Dual representation of convex measures of risk

## Theorem 8.10 (Dual representation for risk measures)

Suppose  $|\Omega|=n<\infty.$  Let  $\mathcal{F}=\mathcal{P}(\Omega)$  (power set) and  $\mathcal{M}:=\{L:\Omega\to\mathbb{R}\}.$  Then:

1) Every convex risk measure  $\varrho$  on  $\mathcal M$  can be written in the form

$$\varrho(L) = \max\{\mathbb{E}_{\mathbb{Q}}(L) - \alpha_{\min}(\mathbb{Q}) : \mathbb{Q} \in \mathcal{S}^1(\Omega, \mathcal{F})\},$$
 (39)

where  $\mathcal{S}^1(\Omega,\mathcal{F})$  denotes the set of all probability measures on  $\Omega$ , and where the penalty function  $\alpha_{\min}$  is given by  $\alpha_{\min}(\mathbb{Q}) = \sup\{\mathbb{E}_{\mathbb{Q}}(L): L \in A_{\varrho}\}.$ 

2) If  $\varrho$  is coherent, it has the representation

$$\varrho(L) = \max\{\mathbb{E}_{\mathbb{Q}}(L) \colon \mathbb{Q} \in \mathcal{Q}\}\$$

for some set  $\mathcal{Q} = \mathcal{Q}(\varrho) \subseteq \mathcal{S}^1(\Omega, \mathcal{F})$ .

One can show that  $\alpha_{\min}(\mathbb{Q}) = \sup_{L \in \mathcal{M}} \{ \mathbb{E}_{\mathbb{Q}}(L) - \varrho(L) \}.$ 

## 8.1.3 Examples of dual representations

## **Proposition 8.11 (ES formulas)**

For  $\alpha \in (0,1)$ ,

1) 
$$\operatorname{ES}_{\alpha}(L) = \frac{\mathbb{E}((L - F_L^{\leftarrow}(\alpha))_+)}{1 - \alpha} + F_L^{\leftarrow}(\alpha)$$

1) 
$$\operatorname{ES}_{\alpha}(L) = \frac{\mathbb{E}((L - F_{L}^{\leftarrow}(\alpha))_{+})}{1 - \alpha} + F_{L}^{\leftarrow}(\alpha);$$
2) 
$$\operatorname{ES}_{\alpha}(L) = \frac{\mathbb{E}(LI_{\{L > F_{L}^{\leftarrow}(\alpha)\}}) + F_{L}^{\leftarrow}(\alpha)(1 - \alpha - \bar{F}_{L}(F_{L}^{\leftarrow}(\alpha)))}{1 - \alpha}.$$

## Corollary 8.12 (ES formulas under continuous $F_L$ )

Let  $F_L$  be continuous at  $F_L^{\leftarrow}(\alpha)$ . Then

1) 
$$\mathrm{ES}_{\alpha}(L) = \frac{\mathbb{E}(LI_{\{L>F_L^{\leftarrow}(\alpha)\}})}{1-\alpha}$$

2) 
$$\mathrm{ES}_{lpha}(L) = \mathbb{E}(L \,|\, L > F_L^{\leftarrow}(lpha))$$
 (i.e. conditional VaR (CVaR))

With dual representations one can give a proof for  $ES_{\alpha}$  being subadditive; see the following result.

#### Theorem 8.13

For  $\alpha \in [0,1)$ ,  $\mathrm{ES}_{\alpha}$  is coherent on  $\mathcal{M} = \mathcal{L}^1(\Omega,\mathcal{F},\mathbb{P})$ . The dual representation is given by

$$ES_{\alpha}(L) = \max\{\mathbb{E}^{\mathbb{Q}}(L) : \mathbb{Q} \in \mathcal{Q}_{\alpha}\},\tag{40}$$

where  $\mathcal{Q}_{\alpha}$  is the set of all probability measures on  $(\Omega, \mathcal{F})$  that are absolutely continuous with respect to  $\mathbb{P}$  and for which the measure-theoretic density  $d\mathbb{Q}/d\mathbb{P}$  is bounded by  $1/(1-\alpha)$ .

## 8.2 Law-invariant coherent risk measures

#### 8.2.1 Distortion risk measures

Distortion risk measures are important coherent risk measures. We summarize important representations and investigate their properties.

## Representations of distortion risk measures

## **Definition 8.14 (Distortion risk measure)**

- 1) A convex distortion function D is a convex, increasing and absolutely continuous function on [0,1] satisfying D(0)=0 and D(1)=1.
- 2) The distortion risk measure associated with a convex distortion function D is defined by

$$\varrho(L) = \int_0^1 F_L^{\leftarrow}(u) \, dD(u). \tag{41}$$

- lacktriangledown A distortion risk measure is law-invariant (average of the L-quantiles).
- $D(u) = \int_0^u \phi(s) \, ds$  for an increasing, positive function  $\phi$  (the right-sided derivative of D), hence

$$\varrho(L) = \int_0^1 F_L^{\leftarrow}(u)\phi(u) \, du. \tag{42}$$

A risk measure of this form is known as spectral risk measure and  $\phi$  as spectrum.

■ For  $D_{\alpha}(u)=(1-\alpha)^{-1}(u-\alpha)^+$  one obtains expected shortfall. The spectrum is  $\phi(u)=(1-\alpha)^{-1}I_{\{u\geq\alpha\}}$  (equal weight is placed on all quantiles beyond the  $\alpha$ -quantile).

#### **Lemma 8.15**

The distortion risk measure  $\varrho$  associated with a convex distortion function D can be written in the form

$$\varrho(L) = \int_{\mathbb{R}} x \, dD \circ F_L(x), \tag{43}$$

where  $D \circ F_L(x) = D(F_L(x))$ .

*Proof.*  $G(x)=D\circ F_L(x)$  has quantile function  $G^\leftarrow=F_L^\leftarrow\circ D^\leftarrow$ . Thus (43) can be written as

$$\int_{\mathbb{R}} x \, dG(x) = \int_{0}^{1} G^{\leftarrow}(u) \, du = \int_{0}^{1} F_{L}^{\leftarrow} \circ D^{\leftarrow}(u) \, du = \mathbb{E}(F_{L}^{\leftarrow} \circ D^{\leftarrow}(U)),$$

$$\lim_{n \to \infty} H_{n}(0, 1) \quad \text{Note in tendency } H_{n}(0, 1) \quad \text{Provided to the leading of } H_{n}(0, 1) \quad \text{The surface of } H_{n}(0, 1) \quad \text{The surf$$

where  $U \sim \mathrm{U}(0,1).$  Now introduce  $V = D^{\leftarrow}(U) \sim D$  and note that

$$\int_{\mathbb{R}} x \, dD \circ F_L(x) = \mathbb{E}(F_L^{\leftarrow}(V)) = \int_0^1 F_L^{\leftarrow}(v) \, dD(v). \quad \Box$$

D distorts  $F_L$ . Since D is convex,  $D(u) \leq u$ , so  $G = D \circ F_L$  puts more mass on high values of L than  $F_L$ . Section 8.2.1

Distortion risk measure can be represented as a weighted average of expected shortfall; see the appendix for a proof.

## Proposition 8.16 (Distortion risk measures as weighted ES)

Let  $\varrho$  be a distortion risk measure associated with the convex distortion function D. Then, for a probability measure  $\mu$ ,

$$\varrho(L) = \int_0^1 \mathrm{ES}_{\alpha}(L) \, d\mu(\alpha).$$

## Properties of distortion risk measures

## **Definition 8.17 (Comonotone additivity)**

A risk measure  $\varrho$  on a space of random variables  $\mathcal M$  is said to be comonotone additive if  $\varrho(L_1+\cdots+L_d)=\varrho(L_1)+\cdots+\varrho(L_d)$  for comonotone  $L_1,\ldots,L_d$ .

Quantile functions (so value-at-risk) are comonotone additive. Comonotone additivity of distortion risk measures then follows from (41).

■ Distortion risk measures are coherent. Monotonicity, translation invariance and positive homogeneity are obvious. Subadditivity follows from Proposition 8.16 and subadditivity of  $\mathrm{ES}_{\alpha}$  (e.g., Theorem 8.13) by observing that

$$\varrho(L_1 + L_2) = \int_0^1 \mathrm{ES}_{\alpha}(L_1 + L_2) \, d\mu(\alpha)$$

$$\leq \int_0^1 \mathrm{ES}_{\alpha}(L_1) \, d\mu(\alpha) + \int_0^1 \mathrm{ES}_{\alpha}(L_2) \, d\mu(\alpha)$$

$$= \varrho(L_1) + \varrho(L_2).$$

- In summary, we have verified that distortion risk measures are law invariant, coherent and comonotone additive.
- It may also be shown that, on an atomless probability space (where there exists a continuous random variable), a law-invariant, coherent, comonotone-additive risk measure must be of the form (41) for some convex distortion function *D*.

 Parametric families of distortion risk measures can be based on convex distortion functions of the form

$$D_{\alpha}(u) = \Psi(\Psi^{-1}(u) + \ln(1 - \alpha)), \quad 0 \le \alpha < 1,$$

where  $\Psi$  is a continuous df on  $\mathbb{R}$ ; for  $\Psi(u) = 1 - \exp(-u)$ ,  $u \ge 0$ , one obtains the distortion function for ES.

- Such a family of convex distortion functions is strictly decreasing in  $\alpha$  for fixed u.
- ▶  $D_0(u) = u$  (corresponding to the risk measure  $\varrho(L) = \mathbb{E}(L)$ ) and  $\lim_{\alpha \to 1} D(u) = 1_{\{u=1\}}$ .
- For  $\alpha_1 < \alpha_2$  and 0 < u < 1 we have  $D_{\alpha_1}(u) > D_{\alpha_2}(u)$ , so that  $D_{\alpha_2}$  distorts the original probability measure more than  $D_{\alpha_1}$  and places more weight on outcomes in the tail.

## 8.2.2 The expectile risk measure

## Definition 8.18 (Expectiles)

Let  $L \in \mathcal{M} := L^1(\Omega, \mathcal{F}, \mathbb{P})$ , so  $\mathbb{E}|L| < \infty$ . Then, for  $\alpha \in (0,1)$ , the  $\alpha$ -expectile  $e_{\alpha}(L)$  is given by the unique solution y of

$$\alpha \mathbb{E}((L-y)^+) = (1-\alpha)\mathbb{E}((L-y)^-) \tag{44}$$

where  $x^+ = \max\{x, 0\}$  and  $x^- = \max\{-x, 0\}$ .

- Since  $x^+ x^- = x$ ,  $e_{0.5}(L) = \mathbb{E}(L)$  as  $\mathbb{E}(L y)^- = \mathbb{E}(L y)^+$  iff  $\mathbb{E}((L y)^+ (L y)^-) = 0$  iff  $\mathbb{E}(L y) = 0$ .
- $\blacksquare$   $\mathbb{E}(L^2)<\infty$ ,  $e_{lpha}(L)$  is the minimizer of

$$\min_{y \in \mathbb{R}} \mathbb{E}\left(S(y, L)\right) \tag{45}$$

for scoring function S(y,L). This could be relevant for the out-of-sample testing of expectile-estimates (so-called backtesting). The scoring func-

tion that yields the expectile is

$$S_{\alpha}^{e}(y,L) = |1_{\{L \le y\}} - \alpha | (L - y)^{2}.$$
(46)

In fact we can compute that  $\frac{d}{dy}\mathbb{E}\left(S_{\alpha}^{e}(y,L)\right)$  equals

$$\frac{d}{dy} \int_{-\infty}^{\infty} |1_{\{y \ge x\}} - \alpha|(y - x)^2 dF_L(x) 
= \frac{d}{dy} \int_{-\infty}^{y} (1 - \alpha)(y - x)^2 dF_L(x) + \frac{d}{dy} \int_{y}^{\infty} \alpha(y - x)^2 dF_L(x) 
= 2(1 - \alpha) \int_{-\infty}^{y} (y - x) dF_L(x) + 2\alpha \int_{y}^{\infty} (y - x) dF_L(x) 
= 2(1 - \alpha) \mathbb{E}((L - y)^-) - 2\alpha \mathbb{E}((L - y)^+)$$

and setting this equal to zero yields the definition of an expectile.

• One can show that the  $\alpha$ -quantile  $F_L^{\leftarrow}(\alpha)$  is also a minimizer of the form (45); consider the scoring function  $S_{\alpha}^q(y,L) = |1_{\{L \leq y\}} - \alpha| |L - y|$ .

The following result shows uniqueness of the  $\alpha$ -expectile and provides a helpful formula for computing expectiles of certain distributions; see the appendix for a proof.

#### **Proposition 8.19**

Let  $\alpha\in(0,1)$  and L a rv such that  $\mu:=\mathbb{E}(L)<\infty.$  Then  $e_{\alpha}(L)$  may be written as  $e_{\alpha}(L)=\tilde{F}_{L}^{-1}(\alpha)$  where

$$\tilde{F}_L(y) = \frac{yF_L(y) - \mu(y)}{2(yF_L(y) - \mu(y)) + \mu - y} \tag{47}$$

is a continuous df that is strictly increasing on its support and  $\mu(y):=\int_{-\infty}^y x\,dF_L(x).$ 

## Example 8.20 (Bernoulli)

Let  $L \sim \text{Be}(p)$  be a Bernoulli-distributed loss. Then

$$F_L(y) = \begin{cases} 0, & y < 0 \\ 1 - p, & 0 \le y < 1, \\ 1, & y \ge 1 \end{cases} \quad \mu(y) = \begin{cases} 0, & y < 1 \\ p, & y \ge 1 \end{cases}$$

from which it follows that  $\tilde{F}_L(y) = \frac{y(1-p)}{y(1-2p)+p}$ ,  $0 \le y \le 1$  and

$$e_{\alpha}(L) = \frac{\alpha p}{(1-\alpha) + p(2\alpha - 1)}.$$

Note that this can take any value in zero and one, whereas  $\mathrm{VaR}_{\alpha}(L) \in \{0,1\}$ ,  $\alpha \in (0,1]$ .

## Properties of expectiles

## Proposition 8.21 (Coherence of expectile risk measures)

 $\varrho=e_{\alpha}$  is a coherent risk measure on  $\mathcal{M}=L^{1}(\Omega,\mathcal{F},\mathbb{P})$  for  $\alpha\geq0.5$ .

- See the appendix for a proof.
- Expectiles are not comonotone additive and thus are not distortion risk measures.
- If  $L_1$  and  $L_2$  are comonotonic and of the same type (so that  $L_2=kL_1+m$  for some  $m\in\mathbb{R}$  and k>0) then we do have comonotone additivity (by translation invariance and positive homogeneity), but for comonotonic variables that are not of the same type one can find examples where  $e_{\alpha}(L_1+L_2)< e_{\alpha}(L_1)+e_{\alpha}(L_2)$  for  $\alpha>0.5$ .

## 8.3 Risk measures for linear portfolios

We now consider linear portfolios in

$$\mathcal{M} = \{ L : L = m + \lambda' X, \ m \in \mathbb{R}, \lambda \in \mathbb{R}^d \}, \tag{48}$$

for a fixed d-dimensional random vector X.

- Many standard approaches to risk aggregation and capital allocation are based on the assumption that losses have a linear relationship to underlying risk factor changes.
- It is common to use linear approximations for losses due to market risks over short time horizons.

#### 8.3.1 Coherent risk measures as stress tests

■ Let  $\varrho: \mathcal{M} \to \mathbb{R}$  be a positive-homogeneous risk measure. Define a risk-measure function  $r_{\varrho}(\lambda) = \varrho(\lambda' X)$  (function of portfolio weights).

 $\blacksquare$  If  $\varrho$  is translation-invariant, there is a one-to-one relationship between  $\varrho$  and  $r_\varrho$  given by

$$\varrho(m + \lambda' X) = m + r_{\varrho}(\lambda).$$

## Lemma 8.22 (Properties of $r_{\varrho}$ )

Consider a translation-invariant risk measure  $\varrho:\mathcal{M}\to\mathbb{R}$  with associated risk-measure function  $r_\varrho$ . Then

- 1)  $\varrho$  is a positive-homogeneous risk measure if and only if  $r_{\varrho}$  is a positive-homogeneous function, that is  $r_{\varrho}(t\lambda) = tr_{\varrho}(\lambda)$  for all t > 0,  $\lambda \in \mathbb{R}^d$ .
- 2) Suppose that  $\varrho$  is positive-homogeneous. Then  $\varrho$  is subadditive if and only if  $r_{\varrho}$  is convex.

The main result of this section is that coherent risk measures for linear portfolios are stress tests as in Example 8.8 where the scenario set is

$$S_{\varrho} := \{ \boldsymbol{x} \in \mathbb{R}^d \colon \boldsymbol{u}' \boldsymbol{x} \leq r_{\varrho}(\boldsymbol{u}) \text{ for all } \boldsymbol{u} \in \mathbb{R}^d \}.$$

# Proposition 8.23 (Coherent risk measures for linear portfolios as stress tests)

 $\varrho$  is a coherent risk measure on the set of linear portfolios  $\mathcal M$  in (48) if and only if for every  $L=m+\lambda' X\in \mathcal M$  we have the representation

$$\varrho(L) = m + r_{\varrho}(\lambda) = \sup\{m + \lambda' x : x \in S_{\varrho}\}.$$
 (49)

- $S_{\varrho}$  is an intersection of the half-spaces  $H_u = \{ \boldsymbol{x} \in \mathbb{R}^d \colon \boldsymbol{u}' \boldsymbol{x} \leq r_{\varrho}(\boldsymbol{u}) \}$ , so that  $S_{\varrho}$  is a closed convex set. The precise form of  $S_{\varrho}$  depends on the df of  $\boldsymbol{X}$  and on  $\varrho$ .
- If  $\varrho = \operatorname{VaR}_{\alpha}$ ,  $S_{\varrho}$  has an interpretation as a *depth set*. Suppose that  $\boldsymbol{u}'\boldsymbol{X}$  is continuously distributed for all  $\boldsymbol{u} \in \mathbb{R}^d \setminus \{\boldsymbol{0}\}$ . Then for  $H_u = \{\boldsymbol{x} \in \mathbb{R}^d : \boldsymbol{u}'\boldsymbol{x} \leq \operatorname{VaR}_{\alpha}(\boldsymbol{u}'\boldsymbol{X})\}$ ,  $\mathbb{P}(\boldsymbol{u}'\boldsymbol{X} \in H_u) = \alpha$  so that  $S_{\operatorname{VaR}_{\alpha}}$  is the intersection of all half-spaces with probability  $\alpha$ .

## 8.3.2 Elliptically distributed risk factors

## Theorem 8.24 (Risk measurement for elliptical risk factors)

Let  $X \sim E_d(\mu, \Sigma, \psi)$  and  $\varrho$  be any positive-homogeneous, translation-invariant and law-invariant risk measure on  $\mathcal{M}$ . Then:

- 1) For any  $L=m+\lambda' X\in \mathcal{M}$ ,  $\varrho(L)=m+\lambda' \mu+\sqrt{\lambda' \Sigma \lambda} \varrho(Y_1)$  for  $Y_1\sim S_1(\psi)$ .
- 2) If  $\varrho(Y_1) \geq 0$ , then  $\varrho$  is subadditive on  $\mathcal{M}$  (e.g.,  $VaR_{\alpha}$  for  $\alpha \geq 0.5$ ).
- 3) If  $\mathbb{E} X$  exists then,  $\forall L = m + \lambda' X \in \mathcal{M}$  and  $\rho_{ij} = \wp(\Sigma)_{ij} = P_{ij}$ ,

$$\varrho(L - \mathbb{E}L) = \sqrt{\sum_{i=1}^{d} \sum_{j=1}^{d} \rho_{ij} \lambda_i \lambda_j \varrho(X_i - \mathbb{E}X_i) \varrho(X_j - \mathbb{E}X_j)}.$$

- 4) If  $\operatorname{cov}(\boldsymbol{X})$  exists and  $\varrho(Y_1)>0$  then, for every  $L\in\mathcal{M}$ ,  $\varrho(L)=\mathbb{E}(L)+k_\varrho\sqrt{\operatorname{var}(L)}$  for some  $k_\varrho>0$  depending on  $\varrho$ .
- $\text{5) If } \Sigma^{-1} \text{ ex., } \varrho(Y_1)>0 \text{ then } S_\varrho=\{\boldsymbol{x}: (\boldsymbol{x}-\boldsymbol{\mu})'\Sigma^{-1}(\boldsymbol{x}-\boldsymbol{\mu})\leq \varrho(Y_1)^2\}.$

Proof.

- 1) Let  $Y \sim S_k(\psi)$ ,  $AA' = \Sigma$ .  $L = m + \lambda' X \stackrel{\text{d}}{=} m + \lambda' \mu + \lambda' A Y$ . By Theorem 6.15 3),  $L \stackrel{\text{d}}{=} m + \lambda' \mu + \|A' \lambda\| Y_1$ . Thus  $\varrho(L) = m + \lambda' \mu + \|A' \lambda\| \varrho(Y_1) = m + \lambda' \mu + \sqrt{\lambda' \Sigma \lambda} \varrho(Y_1)$ .
- 2) Set  $L_1=m_1+\lambda_1'\boldsymbol{X}$  and  $L_2=m_2+\lambda_2'\boldsymbol{X}$ . Subadditivity follows from 1) and  $\|A'(\boldsymbol{\lambda}_1+\boldsymbol{\lambda}_2)\|\leq \|A'\boldsymbol{\lambda}_1\|+\|A'\boldsymbol{\lambda}_2\|$  and  $\varrho(Y_1)\geq 0$ .
- 3)  $\varrho(L \mathbb{E}L) = \varrho(L) \mathbb{E}(L) = \varrho(L) (m + \lambda'\mu) = \sqrt{\lambda'\Sigma\lambda}\varrho(Y_1)$ , so

$$\varrho(L - \mathbb{E}L) = \sqrt{\sum_{i=1}^{d} \sum_{j=1}^{d} \rho_{ij} \lambda_i \lambda_j \sigma_i \sigma_j \varrho(Y_1)},$$

where  $\sigma_j = \sqrt{\Sigma_{jj}}$  for  $j \in \{1, ..., d\}$ . For  $\lambda = e_j$ ,  $\varrho(X_j - \mathbb{E}X_j) = \varrho(e'_j X - \mathbb{E}(e'_j X)) = \sigma_j \varrho(Y_1)$ , from which the result follows.

4)  $\operatorname{cov}(\boldsymbol{X}) = c\Sigma$  for some c > 0. Since  $\operatorname{var}(L) = \operatorname{var}(\boldsymbol{\lambda}'\boldsymbol{X}) = \boldsymbol{\lambda}'c\Sigma\boldsymbol{\lambda}$ , 3) implies that  $\varrho(L) = \mathbb{E}(L) + \sqrt{\boldsymbol{\lambda}'\Sigma\boldsymbol{\lambda}}\varrho(Y_1) = \mathbb{E}(L) + \sqrt{\operatorname{var}(L)}\varrho(Y_1)/\sqrt{c}$ .

5) 2) implies that  $r_{\varrho}(\lambda) = \|A'\lambda\|\varrho(Y_1) + \lambda'\mu$  so that  $S_{\varrho}$  is

$$\begin{split} S_{\varrho} &= \left\{ \boldsymbol{x} \in \mathbb{R}^{d} \ : \ \boldsymbol{u}' \boldsymbol{x} \leq \boldsymbol{u}' \boldsymbol{\mu} + \|A' \boldsymbol{u}\| \ \varrho(Y_{1}) \ \forall \, \boldsymbol{u} \in \mathbb{R}^{d} \right\} \\ &= \left\{ \boldsymbol{x} \in \mathbb{R}^{d} \ : \ \boldsymbol{u}' A A^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) \leq \|A' \boldsymbol{u}\| \ \varrho(Y_{1}) \ \forall \, \boldsymbol{u} \in \mathbb{R}^{d} \right\} \\ &= \left\{ \boldsymbol{x} \in \mathbb{R}^{d} \ : \ \boldsymbol{v}' \frac{A^{-1} (\boldsymbol{x} - \boldsymbol{\mu})}{\varrho(Y_{1})} \leq \|\boldsymbol{v}\| \ \forall \, \boldsymbol{v} \in \mathbb{R}^{d} \right\}, \end{split}$$

where the last line follows because  $\mathbb{R}^d = \{A'\boldsymbol{u} : \boldsymbol{u} \in \mathbb{R}^d\}$ . Since  $\{\boldsymbol{y} \in \mathbb{R}^d : \boldsymbol{y}'\boldsymbol{y} \leq 1\}$  can be written as  $\{\boldsymbol{y} \in \mathbb{R}^d : \boldsymbol{v}'\boldsymbol{y} \leq \|\boldsymbol{v}\| \ \forall \ \boldsymbol{v} \in \mathbb{R}^d\}$ , we conclude that, for  $\boldsymbol{x} \in S_\varrho$ , the vectors  $\boldsymbol{y} = A^{-1}(\boldsymbol{x} - \boldsymbol{\mu})/\varrho(Y_1)$  describe the unit ball and therefore

$$S_{\varrho} = \{ \boldsymbol{x} \in \mathbb{R}^d : (\boldsymbol{x} - \boldsymbol{\mu})' \Sigma^{-1} (\boldsymbol{x} - \boldsymbol{\mu}) \le \varrho(Y_1)^2 \}.$$

- 2) gives a special case where VaR is subadditive and thus coherent. In particular, if  $(L_1, \ldots, L_d)$  is jointly elliptical,  $VaR_{\alpha}$  is subadditive for  $\alpha \geq 0.5$ .
- lacksquare 3) provides a useful interpretation of risk measures on  $\mathcal M$  in terms of the aggregation of stress tests.
- 4) is relevant to portfolio optimization. If we consider losses  $L \in \mathcal{M}$  for which  $\mathbb{E}(L)$  is fixed, the weights that minimize  $\varrho$  also minimize the variance. The portfolio minimizing  $\varrho$  is thus the same as the Markowitz variance-minimizing portfolio.
- lacksquare 5) shows that the scenario sets in the stress test representation of coherent risk measures are ellipsoids when X is elliptical. Different law-invariant coherent risk measures simply lead to ellipsoids of differing radius  $\varrho(Y_1)$ . Scenario sets of ellipsoidal form are often used in practice and this result provides a justification for this practice in the case of linear portfolios of elliptical risk factors.

## 8.4 Risk aggregation

A risk aggregation rule is a mapping

$$f(\mathrm{EC}_1,\ldots,\mathrm{EC}_d)=\mathrm{EC}$$

which maps the individual capital amounts  $EC_1, \ldots, EC_d$  to the aggregate capital EC (economic capital). Examples are:

- ▶ Simple summation  $EC = EC_1 + \cdots + EC_d$  (a special case of and upper bound for correlation adjusted summation)
- Correlation adjusted summation

$$EC = \sqrt{\sum_{i=1}^{d} \sum_{j=1}^{d} \rho_{ij} EC_i EC_j},$$
(50)

where  $\rho_{ij} \in [0,1]$  are parameters (referred to as *correlations*).

 Applying such rules without considering a multivariate model or risk measures is known as rules-based aggregation, otherwise, principlesbased aggregation; we focus on the latter.

In what follows we show that correlation adjusted summation is justified as a risk aggregation rule under various setups.

## 8.4.1 Aggregation based on loss distributions

■ Suppose that the overall loss is  $L=L_1+\cdots+L_d$  where  $L_1,\ldots,L_d$  are the losses arising from sub-units (e.g., business units, asset classes). Consider a translation-invariant  $\varrho$  and define

$$\underline{\varrho}^{\mathsf{mean}}(\cdot) = \underline{\varrho}(\cdot - \mathbb{E}(\cdot)) = \underline{\varrho}(\cdot) - \mathbb{E}(\cdot),$$

that is, the capital required to cover unexpected losses.

■ The capital requirements for the sub-units are

$$EC_j = \varrho^{\mathsf{mean}}(L_j), \quad j \in \{1, \dots, d\},$$

and the aggregate capital should be

$$EC = \varrho^{\mathsf{mean}}(L).$$

We require an aggregation rule f such that  $f(\mathrm{EC}_1,\ldots,\mathrm{EC}_d)=\mathrm{EC}$ . Section 8.4.

• If  $\varrho(L) = \mathbb{E}(L) + k \operatorname{sd}(L)$ , k > 0, and  $\mathbb{E}(L^2) < \infty$  then

$$\operatorname{sd}(L) = \sqrt{\operatorname{var}(\mathbf{1}'\boldsymbol{L})} = \sqrt{\mathbf{1}'\operatorname{cov}(\boldsymbol{L})\mathbf{1}} = \sqrt{\sum_{i=1}^{d}\sum_{j=1}^{d}\rho_{ij}\operatorname{sd}(L_{i})\operatorname{sd}(L_{j})},$$

where  $(\rho_{ij})_{i,j} = \operatorname{corr}(\boldsymbol{L})$ , so correlation adjusted summation follows by noting that  $\operatorname{sd}(L) = \varrho^{\operatorname{mean}}(L)/k = \operatorname{EC}/k$  (and  $\operatorname{sd}(L_i) = \operatorname{EC}_i/k$ ).

- If  $L_j = m_j + \lambda_j' X$  for  $X \sim E_d(\mu, \Sigma, \psi)$  with existing  $\operatorname{cov}(X)$ , then this formula and Theorem 8.24 4) imply that correlation adjusted summation is justified for any positive-homogeneous, translation-invariant and law-invariant risk measure  $\rho$ .
- As the following result shows, the assumption on  $cov(\boldsymbol{X})$  can be dropped.

Proposition 8.25 (Correlation adjusted sum. for linear portfolios)

Let  $X \sim E_k(\mu, \Sigma, \psi)$  with  $\mathbb{E}(X) = \mu$ . Let  $\mathcal{M} = \{L : L = m + \lambda' X, \ \lambda \in \mathbb{R}^k, \ m \in \mathbb{R}\}$  and  $\varrho$  be a pos.-hom., translation- and law-invariant risk measure on  $\mathcal{M}$ . For  $L_1, \ldots, L_d \in \mathcal{M}$ , let  $\mathrm{EC}_j = \varrho^{\mathrm{mean}}(L_j)$  and  $\mathrm{EC} = \varrho^{\mathrm{mean}}(L_1 + \cdots + L_d)$ . Then  $\mathrm{EC}, \ \mathrm{EC}_1, \ldots, \mathrm{EC}_d$  satisfy the correlation adjusted summation for  $P = \wp(\tilde{\Sigma}) = (\rho_{ij})_{ij}$  and  $\tilde{\Sigma}$  is the scale matrix of the (elliptical)  $(L_1, \ldots, L_d)$ .

*Proof.* Let  $L_j = m_j + \lambda_j' X$ . By Theorem 8.24 1),  $\mathrm{EC}_j = \varrho(L_j) - \mathbb{E}(L_j)$   $= \sqrt{\lambda_j' \Sigma \lambda_j} \varrho(Y_1)$  where  $Y_1 \sim S_1(\psi)$  and that

$$EC = \sqrt{(\lambda_1 + \dots + \lambda_d)' \Sigma (\lambda_1 + \dots + \lambda_d)} \varrho(Y_1)$$

$$= \sqrt{\sum_{i=1}^d \sum_{j=1}^d \lambda_i' \Sigma \lambda_j \varrho(Y_1)^2} = \sqrt{\sum_{i=1}^d \sum_{j=1}^d \frac{\lambda_i' \Sigma \lambda_j}{\sqrt{(\lambda_i' \Sigma \lambda_i)(\lambda_j' \Sigma \lambda_j)}}} EC_i EC_j.$$

The scale matrix  $\tilde{\Sigma}$  of  $(L_1,\ldots,L_d)$  is  $\tilde{\Sigma}=\Lambda\Sigma\Lambda'$  where  $\Lambda=(\boldsymbol{\lambda}_1,\ldots,\boldsymbol{\lambda}_d)'$ . Section 8.4.1

The corresponding  $P=(\rho_{ij})_{ij}$  has elements  $\lambda_i' \Sigma \lambda_j / \sqrt{(\lambda_i' \Sigma \lambda_i)(\lambda_j' \Sigma \lambda_j)}$  and thus

$$EC = \sqrt{\sum_{i=1}^{d} \sum_{j=1}^{d} \frac{\lambda_{i}' \Sigma \lambda_{j}}{\sqrt{(\lambda_{i}' \Sigma \lambda_{i})(\lambda_{j}' \Sigma \lambda_{j})}}} EC_{i} EC_{j} = \sqrt{\sum_{i=1}^{d} \sum_{j=1}^{d} \rho_{ij}} EC_{i} EC_{j}. \quad \Box$$

- Correlation adjusted summation can thus be justified under the mean-adjusted VaR or ES if L is elliptical.
- The formula requires the pairwise correlations  $\rho_{ij}$  between the losses  $L_1, \ldots, L_d$ . It is difficult to obtain estimates of  $\rho_{ij}$  (data is rather available for risk factors than losses). If they are chosen by *expert judgement*, there are compatibility requirements. If  $(L_1, \ldots, L_d)$  is non-elliptical, the limited range of attainable correlations for each pair  $(L_i, L_j)$  is also a relevant constraint; see Chapter 7.
- lacksquare No obvious way to incorporate tail dependence between  $L_1,\ldots,L_d$ .
- Simple summation only offers a conservative upper bound if  $\rho$  is coherent.

## 8.4.2 Aggregation based on stressing risk factors

- Correlation adjusted summation is used in the aggregation of capital contributions  $EC_1, \ldots, EC_d$  computed by stressing individual risk factors (example: Standard formula approach to Solvency II).
- Let  $x=X(\omega)$  be a scenario defined in terms of changes in risk factors and L(x) the corresponding loss. Assume L(x) is known and componentwise increasing.
- The d risk factors are stressed individually by amounts  $k_1, \ldots, k_d$ . Capital contributions for each risk factor are computed by

$$EC_j = L(k_j e_j) - L(\mathbb{E}(X_j) e_j)$$

where  $k_j > \mathbb{E}(X_j)$  so that  $\mathrm{EC}_j > 0$  (interpreted as the loss incurred by stressing risk factor j by  $k_j$  relative to the impact of stressing it by its expected change); an example is  $k_j = q_\alpha(X_j)$  for large  $\alpha$ .

■ The following justifies correlation adjusted summation as a risk aggregation rule if  $k_j = \varrho(X_j)$  for elliptical X and  $L(X) = m + \lambda' X$ .

Proposition 8.26 (Justification for correlation adjusted summation) Let  $X \sim E_d(\mu, \Sigma, \psi)$  with  $\mathbb{E}(X) = \mu$ . Let  $\mathcal{M}$  be the space of linear portfolios (48) and  $\varrho$  be a pos. hom., translation- and law-invariant risk measure on  $\mathcal{M}$ . Then, for any  $L = L(X) = m + \lambda' X \in \mathcal{M}$ ,

$$\mathrm{EC} = \varrho(L - \mathbb{E}(L)) = \sqrt{\sum_{i=1}^d \sum_{j=1}^d 
ho_{ij} \, \mathrm{EC}_i \, \mathrm{EC}_j},$$

where  $EC_j = L(\varrho(X_j)e_j) - L(\mathbb{E}(X_j)e_j)$  and  $\rho_{ij} = \wp(\Sigma)_{i,j}$ .

*Proof.* Note that  $\mathrm{EC}_j = m + \lambda_j \varrho(X_j) - (m + \lambda_j \mathbb{E} X_j) = \lambda_j \varrho(X_j - \mathbb{E} X_j)$  and plug this into Theorem 8.24 3) to see that the claim holds.  $\square$ 

- Thus under linearity of the losses in jointly elliptical risk-factor changes, we can aggregate the effects of single-risk-factor stresses to an aggregate capital; this applies to VaR, ES or distortion risk measures. This idea underscores correlation adjusted summation in Solvency II.
- For market risk factors (returns on prices), the data may be available to estimate the  $\rho_{ij}$ s. For other risk factors (e.g. mortality and policy of the other prices) Section 8.4.2

lapse rates in Solvency II), they are set by expert judgement (see issues mentioned earlier).

# 8.4.3 Modular versus fully integrated aggregation approaches

- The approaches of Sections 8.4.1 and 8.4.2 are *modular approaches*. In Sections 8.4.1 the *modules* (or *silos*) are business units or asset classes; in Section 8.4.2 they were individual risk factors; the former approach is more natural because losses are additive (and it is possible to remove risks from the enterprise by selling parts of the business).
- The aggregation approaches involved correlations and the correlation adjusted summation; however, correlations give only a partial description of dependence. It is natural to consider using copulas in aggregation.
- Consider simple summation and suppose we know/have estimated the marginal distributions  $F_1, \ldots, F_d$  for each of the modules (necessary

for computing  $\mathrm{EC}_j = \varrho(L_j) - \mathbb{E}(L_j)$ ). In the margins-plus-copula approach, we could attempt to choose a suitable copula C for  $L \sim F(x) = C(F_1(x_1), \ldots, F_d(x_d))$ ; see the converse of Sklar's Theorem. Computing the aggregate capital is then typically done by simulation and estimating the risk measures empirically.

- Problems: (Mis)specification of the copula C (dependence uncertainty);
  Data from L is typically sparse.
- It is generally easier to follow a *fully integrated approach* by building a margins-plus-copula model or more dynamic models (*economic scenario generators*) for the risk-factor changes  $\boldsymbol{X}=(X_1,\ldots,X_k)$  (more data exists) and for the functionals  $g_j:\mathbb{R}^k\mapsto\mathbb{R}$  which give the losses  $L_j=g_j(\boldsymbol{X}),\ j\in\{1,\ldots,d\}$ , for the different portfolios/business units. Risk measures are then derived from the distribution of  $L=g_1(\boldsymbol{X})+\cdots+g_d(\boldsymbol{X})$ .

# 8.4.4 Risk aggregation and Fréchet problems

- Consider the margins-plus-copula approach where  $L_j \sim F_j$ ,  $j \in \{1, \dots, d\}$ , are treated as known (estimated or postulated) and C is unknown.
- Consider  $L = L_1 + \cdots + L_d$ . Due to the unknown C (dependence uncertainty), risk measures can no longer be computed explicitly.
- Our goal is to find bounds on  $VaR_{\alpha}$  and  $ES_{\alpha}$  under all possible C. Let

$$S_d := S_d(F_1, \dots, F_d) := \left\{ L = \sum_{j=1}^d L_j : L_j \sim F_j, \ j = 1, \dots, d \right\}$$

and consider

$$\overline{\varrho}(L) := \overline{\varrho}(\mathcal{S}_d) := \sup\{\varrho(L) : L \in \mathcal{S}_d(F_1, \dots, F_d)\} \quad \text{(worst } \varrho)$$

$$\underline{\varrho}(L) := \underline{\varrho}(\mathcal{S}_d) := \inf\{\varrho(L) : L \in \mathcal{S}_d(F_1, \dots, F_d)\} \quad \text{(best } \varrho)$$

If  $\varrho = \mathrm{ES}_{\alpha}$ ,  $\overline{\mathrm{ES}}_{\alpha}(L) = \sum_{j=1}^{d} \mathrm{ES}_{\alpha}(L_{j})$  (subadditivity, com. additivity).  $\underline{\mathrm{ES}}_{\alpha}$ ,  $\underline{\mathrm{VaR}}_{\alpha}$ ,  $\underline{\mathrm{VaR}}_{\alpha}$  depend on whether the portfolio is *homogeneous* (that is,  $F_{1} = \cdots = F_{d}$ ).

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# Summary of existing results

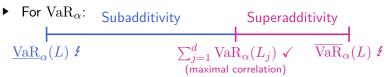
d=2: Fully solved analytically

 $d \geq 3$ : Here we distinguish:

- ▶ Homogeneous case  $(F_1 = \cdots = F_d)$ :
  - $\underline{\mathrm{ES}}_{lpha}(L)$  solved analytically for decreasing densities (e.g. Pareto, Exponential)
  - $\underline{\mathrm{VaR}}_{\alpha}(L)$ ,  $\overline{\mathrm{VaR}}_{\alpha}(L)$  solved analytically for tail-decreasing densities (e.g. Pareto, Log-normal, Gamma)
- ► Inhomogeneous case:
  - Few analytical results: current research
  - Numerical methods: (Adaptive/Block) Rearrangement Algorithm

# The general problem

- We have one-period risks  $L_1 \sim F_1, \ldots, L_d \sim F_d$  with given (estimated or postulated)  $F_1, \ldots, F_d$ . The copula C is unknown.
- We need to find the dependence uncertainty gaps  $(\underline{\operatorname{VaR}}_{\alpha}(L), \overline{\operatorname{VaR}}_{\alpha}(L))$  (or  $(\underline{\operatorname{ES}}_{\alpha}(L), \overline{\operatorname{ES}}_{\alpha}(L))$ ) for  $L = L_1 + \dots + L_d$ .
- The dependence uncertainty spreads can be visualized as follows.



▶ For  $ES_{\alpha}$ :

$$\underline{\mathrm{ES}}_{\alpha}(L) \not \in \overline{\mathrm{ES}}_{\alpha}(L_j) \checkmark$$

The Rearrangement Algorithm (RA) can find approximate solutions to the "#" cases.

# Proposition 8.27 ( $VaR_{\alpha}$ in the homogeneous case)

Let  $F:=F_1=\cdots=F_d$  with decreasing density on  $[b,\infty).$  Then, for  $\alpha\in [F(b),1)$  and  $X\sim F$ ,

$$\overline{\operatorname{VaR}}_{\alpha}(\mathcal{S}_d) = d\mathbb{E}(X \mid X \in [F^{-1}(\alpha + (d-1)c, F^{-1}(1-c)]),$$

where c is the smallest number in  $[0,(1-\alpha)/d]$  such that

$$\int_{\alpha+(d-1)c}^{1-c} F^{-1}(t) dt \ge \frac{1-\alpha-dc}{d} ((d-1)F^{-1}(\alpha+(d-1)c) + F^{-1}(1-c)).$$

If the density f of F is decreasing on its support, then for  $\alpha \in (0,1)$  ,

$$\underline{\mathrm{VaR}}_{\alpha}(\mathcal{S}_d) = \max\{(d-1)F^{-1}(0) + F^{-1}(\alpha), \ d\mathbb{E}(X \mid X \leq F^{-1}(\alpha))\}.$$

Proof. See Wang et al. (2013) and Bernard et al. (2014).

 The underlying numerics are non-trivial; see Hofert et al. (2015) and qrmtools::VaR\_bounds\_hom().

## Proposition 8.28 ( $\underline{\mathrm{ES}}_{\alpha}$ in the homogeneous case)

Let  $F:=F_1=\cdots=F_d$  with finite first moment and decreasing density on its support. Then, for  $\alpha\in[1-dc,1)$ ,  $\beta=(1-\alpha)/d$ , and  $X\sim F$ ,

$$\underline{\mathrm{ES}}_{\alpha}(\mathcal{S}_d) = \frac{1}{\beta} \int_0^{\beta} ((d-1)F^{-1}((d-1)t) + F^{-1}(1-t)) dt$$
$$= (d-1)^2 \, \mathrm{LES}_{(d-1)\beta}(X) + \mathrm{ES}_{1-\beta}(X),$$

where c is the smallest number in  $\left[0,1/d\right]$  such that

$$\int_{(d-1)c}^{1-c} F^{-1}(t) dt \ge \frac{1-dc}{d} ((d-1)F^{-1}((d-1)c) + F^{-1}(1-c))$$

and 
$$LES_{\alpha}(X) = \frac{1}{\alpha} \int_{0}^{\alpha} VaR_{u}(X) du = -ES_{1-\alpha}(-X)$$
 (lower ES).

Proof. See Bernard et al. (2014).

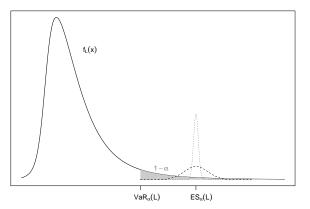
# The Rearrangement Algorithm (RA)

Two columns a,b are oppositely ordered if  $(a_i-a_j)(b_i-b_j) \leq 0 \ \forall i,j.$  Introduce the minimum row-sum operator  $s(X) = \min_{1 \leq i \leq N} \sum_{1 \leq j \leq d} x_{ij}.$ 

# Algorithm 8.29 (RA for computing $\overline{\mathrm{VaR}}_{\alpha}(L)$ )

- 1) Fix  $\alpha\in(0,1)$ ,  $F_1^\leftarrow,\ldots,F_d^\leftarrow$ ,  $N\in\mathbb{N}$  (# of discr. points),  $\varepsilon\geq0$  (tol.)
- 2) Compute the lower bound  $\underline{s}_N$ :
  - 2.1) Define the (N,d)-matrix  $\underline{X}^{\alpha} = \left(F_{j}^{\leftarrow}(\alpha + \frac{(1-\alpha)(i-1)}{N})\right)_{i,j}$ .
  - 2.2) Permute randomly each column of  $\underline{X}^{\alpha}$  (to avoid  $\overline{s}_N \overset{\sim}{\underline{s}_N} \nrightarrow 0$ )
  - 2.3) Set  $\underline{Y}^{\alpha} = \underline{X}^{\alpha}$ . For  $1 \leq j \leq d$ , rearrange the jth column of  $\underline{Y}^{\alpha}$  so that it becomes oppositely ordered to the sum of all others.
  - 2.4) While  $s(\underline{Y}^{\alpha}) s(\underline{X}^{\alpha}) > \varepsilon$ , set  $\underline{X}^{\alpha}$  to  $\underline{Y}^{\alpha}$  and repeat Step 2.3).
  - 2.5) Set  $\underline{s}_N = s(\underline{Y}^\alpha)$ .
- 3) Similarly, compute  $\overline{s}_N=s(\overline{Y}^\alpha)$  based on  $\overline{X}^\alpha=\left(F_j^\leftarrow(\alpha+\frac{(1-\alpha)i}{N})\right)_{i,j}$ .
- 4) Return  $(\underline{s}_N, \overline{s}_N)$  (rearrangement range; taken as bounds on  $\overline{\mathrm{VaR}}_{\alpha}(L)$ )

**Intuition:** The RA is based on the idea of joint mixability. The dfs  $F_1,\ldots,F_d$  are *jointly mixable* if there exists a  $c\in\mathbb{R}$  such that  $\mathbb{P}(L_1+\cdots+L_d=c)=1$  where  $L_1\sim F_1,\ldots,L_d\sim F_d$ . This is a notion of negative dependence and can be illustrated as follows.



 $\Rightarrow$  Minimizing the variance of  $L \mid L > F_L^{\leftarrow}(\alpha)$  increases  $VaR_{\alpha}(L)$ .

# Example 8.30 (How the RA works)

1) Where it works (to compute the maximal minimal row sum):

$$\begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 2 \\ 3 & 5 & 4 \\ 4 & 7 & 8 \end{pmatrix} \xrightarrow{\sum_{-1} = \begin{pmatrix} 5 \\ 9 \\ 15 \end{pmatrix}} \begin{pmatrix} 4 & 1 & 1 \\ 3 & 3 & 2 \\ 2 & 5 & 4 \\ 1 & 7 & 8 \end{pmatrix} \xrightarrow{\text{here: stable}} \begin{pmatrix} 4 & 5 & 1 \\ 3 & 7 & 2 \\ 2 & 3 & 4 \\ 1 & 1 & 8 \end{pmatrix} \xrightarrow{\sum_{-1} = \begin{pmatrix} 5 \\ 9 \\ 15 \end{pmatrix}} \begin{pmatrix} 4 & 5 & 2 \\ 2 & 3 & 4 \\ 1 & 1 & 8 \end{pmatrix} \xrightarrow{\sum_{-1} = \begin{pmatrix} 9 \\ 10 \\ 5 \\ 2 \end{pmatrix}}$$

$$\begin{pmatrix} 4 & 5 & 2 \\ 2 & 7 & 1 \\ 4 & 3 & 4 \\ 1 & 1 & 8 \end{pmatrix} \xrightarrow{\sum_{-1} = \begin{pmatrix} 7 \\ 8 \\ 7 \end{pmatrix}} \begin{pmatrix} 3 & 5 & 2 \\ 2 & 7 & 1 \\ 4 & 3 & 4 \\ 1 & 1 & 8 \end{pmatrix} \xrightarrow{\sum_{-1} = \begin{pmatrix} 10 \\ 10 \\ 11 \\ 10 \end{pmatrix}} \xrightarrow{\widehat{\text{VaR}}_{\alpha}(L^{+})} \approx 10$$

2) The RA can also fail:

$$\begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{pmatrix} \Longrightarrow_{\sum_{-1} = \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix}} \begin{pmatrix} 3 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 3 & 3 \end{pmatrix} \quad \checkmark \Longrightarrow_{\sum = \begin{pmatrix} 5 \\ 6 \\ 7 \end{pmatrix}} \widehat{\overline{\mathrm{VaR}}}_{\alpha}(L^{+}) \approx 5 < 6$$

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# Example 8.31 ( $Par(\theta)$ margins)

Let  $L_j \sim \operatorname{Par}(\theta)$  with  $\bar{F}_j(x) = (1+x)^{-\theta}$ ,  $j \in \{1, \ldots, d\}$  (homogeneous case) and  $\alpha = 0.999$ . One obtains:

	d = 8		d = 56	
	$\theta = 2$	$\theta = 0.8$	$\theta = 2$	$\theta = 0.8$
$\overline{\operatorname{VaR}}_{\alpha}(L)$	465	300 182	3454	4 683 172
$\operatorname{VaR}_{\alpha}^{+}(L) = d \operatorname{VaR}_{\alpha}(L_{1})$	245	44 979	1715	314 855
$\operatorname{VaR}_{\alpha}^{\perp}(L)$	96	75 877	293	862 855
$\underline{\operatorname{VaR}}_{\alpha}(L)$	31	5622	53	5622
$\overline{\mathrm{ES}}_{\alpha}(L) = d  \mathrm{ES}_{\alpha}(L_1)$	498	_	3486	_
$\mathrm{ES}_{lpha}^{\perp}(L)$	184	-	518	_
$\underline{\mathrm{ES}}_{lpha}(L)$	178	-	472	-

- The "+" and " $\pm$ " denote the comonotonic and independent case, resp.
- $\frac{\overline{\mathrm{ES}}_{\alpha}(L)}{\overline{\mathrm{VaR}}_{\alpha}(L)} \approx 1$  can be explained; see McNeil et al. (2015, Prop. 8.36).
- The dependence uncertainty spread  $\overline{\mathrm{VaR}}_{\alpha}(L) \underline{\mathrm{VaR}}_{\alpha}(L) \geq \overline{\mathrm{ES}}_{\alpha}(L) \underline{\mathrm{ES}}_{\alpha}(L)$  can be explained; see McNeil et al. (2015, Prop. 8.37).

#### Remark 8.32

- The RA finds approximate solutions to maximin (for  $\overline{\mathrm{VaR}}_{\alpha}(L)$ ) and minimax (for  $\underline{\mathrm{VaR}}_{\alpha}(L)$ ) problems and is thus of wider interest (e.g., in Operations Research).
- For  $\underline{\mathrm{ES}}_{\alpha}(L)$ , discretize the whole support of each margin, rearrange, and approximate  $\underline{\mathrm{ES}}_{\alpha}(L)$  by the nonparametric  $\mathrm{ES}_{\alpha}$  estimate of the row sums.
- The Adaptive Rearrangement Algorithm (ARA)
  - uses relative (instead of absolute) individual tolerances;
  - uses a relative joint tolerance to guarantee that  $\underline{s}_N$  and  $\overline{s}_N$  are close;
  - chooses N adaptively to reach the joint tolerance; and
  - determines convergence after each rearranged column.

■ The Block Rearrangement Algorithm rearranges blocks of columns.

# Proposition 8.33 (Asymptotic equivalence of $\overline{\mathrm{VaR}}_{\alpha}$ , $\overline{\mathrm{ES}}_{\alpha}$ )

Suppose that  $L_j \sim F_j$ ,  $j \geq 1$  and that

- i) for some k>1,  $\mathbb{E}(|L_j-\mathbb{E}(L_j)|^k)$  is uniformly bounded, and
- ii) for some  $\alpha \in (0,1)$ ,  $\liminf_{d \to \infty} \frac{1}{d} \sum_{j=1}^d \mathrm{ES}_{\alpha}(L_j) > 0$ .

Then, as 
$$d \to \infty$$
,  $\frac{\mathrm{ES}_{\alpha}(\mathcal{S}_d)}{\overline{\mathrm{VaR}}_{\alpha}(\mathcal{S}_d)} = 1 + O(d^{\frac{1}{k}-1}).$ 

Proposition 8.34 (Dependence uncertainty spread of  $VaR_{\alpha}$  vs  $ES_{\alpha}$ )

Let  $0 < \alpha_1 \leq \alpha_2 < 1$ , assume Proposition 8.33 i) to hold and that

$$\liminf_{d\to\infty}\frac{1}{d}\sum_{j=1}^d\mathrm{LES}_{\alpha_1}(X_j)>0 \text{ and } \limsup_{d\to\infty}\frac{\sum_{j=1}^d\mathbb{E}(X_j)}{\sum_{j=1}^d\mathrm{ES}_{\alpha_1}(X_j)}<1. \text{ Then }$$

$$\liminf_{d\to\infty} \frac{\overline{\mathrm{VaR}}_{\alpha_2}(\mathcal{S}_d) - \underline{\mathrm{VaR}}_{\alpha_2}(\mathcal{S}_d)}{\overline{\mathrm{ES}}_{\alpha_1}(\mathcal{S}_d) - \underline{\mathrm{ES}}_{\alpha_1}(\mathcal{S}_d)} \ge 1$$

# 8.5 Capital allocation

How can the overall capital requirement may be disaggregated into additive contributions/units/investments? Motivation: How can we measure the risk-adjusted performance of different investments?

# 8.5.1 The allocation problem

 The performance of investments is usually measured using a RORAC (return on risk-adjusted capital) approach by considering

$$\frac{\text{expected profit of investment } j}{\text{risk capital for investment } j}.$$

■ The risk capital of investment j with loss  $L_j$  can be computed as follows: Compute  $\varrho(L) = \varrho(L_1 + \cdots + L_d)$ . Then allocate  $\varrho(L)$  to the investments according to a capital allocation principle such that

$$\varrho(L) = \sum_{j=1}^{a} AC_j,$$

where the risk contribution  $AC_j$  is the capital allocated to investment j.

### The formal set-up

lacksquare Consider an open set  $1\in\Lambda\subseteq\mathbb{R}^d\setminus\{\mathbf{0}\}$  of portfolio weights and define

$$L(\lambda) = \lambda' L = \sum_{j=1}^{d} \lambda_j L_j, \quad \lambda \in \Lambda.$$

■ For a risk measure  $\varrho$ , define the associated risk-measure function

$$r_{\varrho}(\lambda) = \varrho(L(\lambda)),$$

so that  $r_{\varrho}(\mathbf{1}) = \varrho(L)$ .

## 8.5.2 The Euler principle and examples

If  $r_{\varrho}$  is positive homogeneous and differentiable at  $\lambda \in \Lambda$ , Euler's rule (see the appendix)implies that

$$r_{\varrho}(\boldsymbol{\lambda}) = \sum_{i=1}^{d} \lambda_{i} \frac{\partial r_{\varrho}}{\partial \lambda_{i}}(\boldsymbol{\lambda}) \quad \text{so} \quad \varrho(L) = r_{\varrho}(\mathbf{1}) = \sum_{i=1}^{d} \frac{\partial r_{\varrho}}{\partial \lambda_{i}}(\mathbf{1}).$$

Note that  $r_{\rho}$  is positive homogeneous if  $\varrho$  is.

## Definition 8.35 (Euler capital allocation principle)

If  $r_{\varrho}$  is a pos.-hom. risk-measure function and differentiable at  $\lambda=1$ , then the *Euler capital allocation principle* has risk contributions

$$AC_j = AC_j^{\varrho} := \frac{\partial r_{\varrho}}{\partial \lambda_j}(1), \quad j \in \{1, \dots, d\}.$$

# **Examples**

# 1) Standard deviation and the covariance principle

• Consider  $r_{SD}(\lambda) = \sqrt{\mathrm{var}(L(\lambda))} = \sqrt{\lambda' \Sigma \lambda}$  where  $\Sigma$  is the covariance matrix of  $(L_1, \ldots, L_d)$ . Therefore

$$AC_j^{\varrho} = \frac{\partial r_{SD}}{\partial \lambda_j}(\mathbf{1}) = \frac{(\Sigma \mathbf{1})_j}{r_{SD}(\mathbf{1})} = \frac{\sum_{k=1}^d \text{cov}(L_j, L_k)}{r_{SD}(\mathbf{1})} = \frac{\text{cov}(L_j, L)}{\sqrt{\text{var}(L)}}.$$

This formula is known as covariance principle.

■ If we consider the more general  $\varrho(L)=\mathbb{E}(L)+\kappa\operatorname{SD}(L)$  for some  $\kappa>0$  we get

$$r_{\varrho}(\lambda) = \lambda' \mathbb{E}(L) + \kappa r_{\mathsf{SD}}(\lambda)$$

and hence

$$AC_j^{\varrho} = \mathbb{E}(L_j) + \kappa \frac{\text{cov}(L_j, L)}{\sqrt{\text{var}(L)}}.$$

# 2) VaR and VaR contributions

Suppose that  $r_{\sf VaR}^{\alpha}(\pmb{\lambda}) = q_{\alpha}(L(\pmb{\lambda}))$ . In this case it can be shown (non-trivial) that, subject to technical conditions,

$$AC_j^{\varrho} = \frac{\partial r_{\mathsf{VaR}}^{\alpha}}{\partial \lambda_i}(\mathbf{1}) = \mathbb{E}(L_j \mid L = F_L^{\leftarrow}(\alpha)), \quad j \in \{1, \dots, d\}.$$

# 3) Expected shortfall and shortfall contributions

Now consider  $r_{\mathrm{ES}}^{\alpha}(\lambda) = \mathbb{E}(L \mid L \geq q_{\alpha}(L(\lambda)))$ . Then

$$r_{\mathsf{ES}}^{\alpha}(\boldsymbol{\lambda}) = \frac{1}{1-\alpha} \int_{\alpha}^{1} r_{\mathsf{VaR}}^{u}(\boldsymbol{\lambda}) \, du,$$

Assuming the differentiability of  $r_{\mathsf{VaR}}^u(\pmb{\lambda})$ , the Euler principle implies that

$$\frac{\partial r_{\mathsf{ES}}^{\alpha}}{\partial \lambda_{j}}(\mathbf{1}) = \frac{1}{1-\alpha} \int_{\alpha}^{1} \frac{\partial r_{\mathsf{VaR}}^{u}}{\partial \lambda_{j}}(\mathbf{1}) \, du = \frac{1}{1-\alpha} \int_{\alpha}^{1} \mathbb{E}(L_{j} \, | \, L = F_{L}^{\leftarrow}(u)) \, du.$$

If  $F_L$  has a differentiable inverse,

$$\frac{\partial r_{\mathsf{ES}}^{\alpha}}{\partial \lambda_{j}}(\mathbf{1}) = \frac{1}{1-\alpha} \int_{F_{L}^{\leftarrow}(\alpha)}^{\infty} \mathbb{E}(L_{j} \mid L = v) f_{L}(v) \, dv = \frac{\mathbb{E}(L_{j}; L \ge F_{L}^{\leftarrow}(\alpha))}{1-\alpha}.$$

Hence the Euler capital allocation takes the form

$$AC_j^{\varrho} = \mathbb{E}(L_j \mid L \ge VaR_{\alpha}(L)), \quad L := L(1);$$

 $\mathrm{AC}_j^\varrho$  is known as the *expected shortfall contribution* of investment j. This is a popular allocation principle in practice.

# 4) Euler allocation for elliptical loss distributions

The following result shows that allocation is very simple in the case of  $L \sim E_d(\mathbf{0}, \Sigma, \psi)$ : Calculate the total risk capital and then use a simple partitioning formula (regardless of the pos.-hom. risk measure).

## Corollary 8.36 (Euler allocation under ellipticality)

Assume that  $r_{\varrho}$  is the risk-measure function of a positive-homogeneous and law invariant  $\varrho$ . Let  $L \sim E_d(\mathbf{0}, \Sigma, \psi)$ . Then, under an Euler allocation,

$$\frac{\mathrm{AC}_{j}^{\varrho}}{\mathrm{AC}_{k}^{\varrho}} = \frac{\sum_{l=1}^{d} \Sigma_{jl}}{\sum_{l=1}^{d} \Sigma_{kl}}, \quad j, k \in \{1, \dots, d\}.$$

Proof. The proof of Theorem 8.24 implies that, by positive homogeneity,

$$r_{\varrho}(\lambda) = \varrho(L(\lambda)) = \varrho\left(\sum_{j=1}^{d} \lambda_{j} L_{j}\right) = \sqrt{\lambda' \Sigma \lambda} \, \varrho(Y_{1}),$$

where  $Y_1$  is the first component of  ${\bf Y} \sim S_d(\psi).$  For the Euler allocation we get

$$AC_j^{\varrho} = \frac{\partial r_{\varrho}}{\partial \lambda_j}(\mathbf{1}) = \frac{\sum_{k=1}^d \sum_{jk}}{\sqrt{\mathbf{1}'\Sigma \mathbf{1}}} \varrho(Y_1)$$

from which the result follows.

# 8.5.3 Economic properties of the Euler principle

- We show that the Euler principle has good economic properties.
- Assume that  $r_{arrho}$  is continuously differentiable in  $\mathbb{R}^d\setminus\{\mathbf{0}\}$  and by

$$AC_j^{\varrho} = \frac{\partial r_{\varrho}}{\partial \lambda_j}(\mathbf{1}), \quad j \in \{1, \dots, d\},$$

denote the associated risk contributions under the Euler principle.

# Compatibility with a RORAC approach

■ The RORAC (return on risk adjusted capital) is defined as

$$RORAC(L) := \frac{\mathbb{E}(-L)}{\varrho(L)}$$

and the portfolio-related RORAC of investment j is defined as

$$RORAC(L_j | L) := \frac{\mathbb{E}(-L_j)}{AC_j^{\varrho}}.$$

- The Euler principle is compatible with a RORAC approach: If investment j performs better than the overall portfolio L in the RORAC metric, then the latter is increased if one increases the weight of unit j. Hence the Euler principle gives correct signals for investment decisions.
- $\blacksquare$  In mathematical terms, RORAC compatibility means that there is some  $\varepsilon>0$  such that for all  $0< h\leq \varepsilon$

$$RORAC(L_j | L) > RORAC(L) \Rightarrow RORAC(L + hL_j) > RORAC(L).$$

Proof. 
$$\frac{d}{dh} \operatorname{RORAC}(L + hL_j)|_{h=0}$$

$$= \frac{d}{dh} \frac{\mathbb{E}(-(L + hL_j))}{r_{\varrho}(\mathbf{1} + h\mathbf{e}_j)} \Big|_{h=0} = \frac{1}{r_{\varrho}(\mathbf{1})^2} \Big( \mathbb{E}(-L_j)r_{\varrho}(\mathbf{1}) - \mathbb{E}(-L) \frac{\partial r_{\varrho}(\mathbf{1})}{\partial \lambda_j} \Big),$$

$$= \frac{1}{r_{\varrho}(\mathbf{1})^2} \Big( \mathbb{E}(-L_j)\varrho(L) - \mathbb{E}(-L)\operatorname{AC}_j^{\varrho} \Big) > 0$$

if 
$$\frac{\mathbb{E}(-L_j)}{\mathrm{AC}_i^\varrho} = \mathrm{RORAC}(L_j \mid L) > \mathrm{RORAC}(L) = \frac{\mathbb{E}(-L)}{\varrho(L)}$$
.

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#### **Diversification benefit**

- For a subadditive  $\varrho$ ,  $\sum_{j=1}^{d} \varrho(L_j) \varrho(L) > 0$  is known as *diversification* benefit.
- It is reasonable to require that each business unit profits from the diversification benefit in the sense that

$$AC_j^{\varrho} \le \varrho(L_j), \quad j \in \{1, \dots, d\}.$$

We now show that the Euler principle does indeed satisfy this inequality.

*Proof.* Let  $f: \mathbb{R}^d \to \mathbb{R}$  be convex, pos.-hom. and continuously differentiable in  $\mathbb{R}^d \setminus \{\mathbf{0}\}$ . By convexity,

$$f(\boldsymbol{y}) \geq f(\boldsymbol{x}) + \sum_{j=1}^{d} (y_j - x_j) \frac{\partial f}{\partial x_j}(\boldsymbol{x}), \quad \text{for all } \boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^d, \ \boldsymbol{x} \neq \boldsymbol{0}.$$

By Euler's rule,  $f(x) = \sum_{j=1}^d x_j \frac{\partial f}{\partial x_j}(x)$  and hence

$$f(\boldsymbol{y}) \ge \sum_{j=1}^d y_j \frac{\partial f}{\partial x_j}(\boldsymbol{x}).$$

For  $oldsymbol{y} = oldsymbol{\lambda}$  and  $oldsymbol{x} = oldsymbol{\lambda} + ilde{oldsymbol{\lambda}}$ , we obtain

$$f(\lambda) \ge \sum_{j=1}^d \lambda_j \frac{\partial f}{\partial \lambda_j}(\lambda + \tilde{\lambda}) \quad \text{for all } \lambda, \tilde{\lambda} : \lambda \ne -\tilde{\lambda}.$$

Apply this inequality with  $f=r_{\varrho}$  (which is convex as  $\varrho$  is pos.-hom. and subadditive),  $\pmb{\lambda}=\pmb{e}_j$  and  $\tilde{\pmb{\lambda}}=\pmb{1}-\pmb{e}_j$  to obtain

$$\varrho(L_j) = r_\varrho(\boldsymbol{e}_j) \ge \frac{\partial r_\varrho}{\partial \lambda_i}(\mathbf{1}) = AC_j^\varrho.$$

 From a practical point of view, expected shortfall and expected shortfall contributions are typically a reasonable choice in many applications.