PANIMALAR ENGINEERING COLLEGE

Department of Electronics and Communication Engineering IOT Assignment

**Topic:** Assignment on home automation using Arduino

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# Code:-

**int t=2;**

**int k=3;**

**void setup()**

**{**

**Serial.begin(9600);**

**pinMode(t,OUTPUT);**

**pinMode(k,INPUT);**

**pinMode(12,OUTPUT);**

**}**

**void loop()**

**{**

**//ultrasonic sensor**

**digitalWrite(t,LOW);**

**digitalWrite(t,HIGH);**

**delayMicroseconds(10);**

**digitalWrite(t,LOW);**

**float dur=pulseIn(k,HIGH);**

**float dis=(dur\*0.0343)/2;**

**Serial.print("Distance is: ");**

**Serial.println(dis);**

**//LED ON**

**if(dis>=100)**

**{**

**digitalWrite(8,HIGH);**

**digitalWrite(7,HIGH);**

**}**

**//Buzzer For ultrasonic Sensor**

**if(dis>=100)**

**{**

**for(int i=0; i<=30000; i=i+10)**

**{**

**tone(12,i);**

**delay(1000);**

**noTone(12);**

**delay(1000);**

**}**

**}**

**//Temperate Sensor**

**double a= analogRead(A0);**

**double t=(((a/1024)\*5)-0.5)\*100;**

**Serial.print("Temp Value: ");**

**Serial.println(t);**

**delay(1000);**

**//LED ON**

**if(t>=100)**

**{**

**digitalWrite(8,HIGH);**

**digitalWrite(7,HIGH);**

**}**

**//Buzzer for Temperature Sensor**

**if(t>=100)**

**{**

**for(int i=0; i<=30000; i=i+10)**

**{**

**tone(12,i);**

**delay(1000);**

**noTone(12);**

**delay(1000);**

**}**

**}**

**//LED OFF**

**if(t<100)**

**{**

**digitalWrite(8,LOW);**

**digitalWrite(7,LOW);**

**}**

**}**

**Output:-**

# 