In [1]: import pandas as pd import numpy as np import matplotlib.pyplot as plt import torch import torch.nn as nn import torch.optim as optim from torchvision import datasets, transforms import torchvision from torch.utils.data import DataLoader import random import string import os In [2]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu") Out[2]: device(type='cuda') 模型定义 1. AlexNet In [3]: class AlexNet(nn.Module): def __init__(self, num_classes=1000, dropout=0.5): super(AlexNet, self).__init__() self.features = nn.Sequential(# 论文中的输出通道数为96, pytorch官方为64 # nn.Conv2d(in_channels=3, out_channels=64, kernel_size=11, stride=4, padding=2), nn.Conv2d(in_channels=3, out_channels=96, kernel_size=11, stride=4, padding=2), nn.ReLU(inplace=True), nn.MaxPool2d(kernel_size=3, stride=2), # 论文中的输出通道数为256, pytorch官方为192 # nn.Conv2d(in_channels=64, out_channels=192, kernel_size=5, padding=2), nn.Conv2d(in_channels=96, out_channels=256, kernel_size=5, padding=2), nn.ReLU(inplace=True), nn.MaxPool2d(kernel_size=3, stride=2), # nn.Conv2d(in_channels=192, out_channels=384, kernel_size=3, padding=1), nn.Conv2d(in_channels=256, out_channels=384, kernel_size=3, padding=1), nn.ReLU(inplace=True), nn.Conv2d(in channels=384, out channels=384, kernel size=3, padding=1), nn.ReLU(inplace=True), nn.Conv2d(in_channels=384, out_channels=256, kernel_size=3, padding=1), nn.ReLU(inplace=True), nn.MaxPool2d(kernel_size=3, stride=2) # 这一操作是为了保证特征提取后的特征图大小为 6x6, 使得网络可以接受224x224以外尺寸的图像 self.avgpool = nn.AdaptiveAvgPool2d(output_size=(6, 6)) self.classifier = nn.Sequential(nn.Dropout(p=dropout), nn.Linear(256 * 6 * 6, 4096),nn.ReLU(inplace=True), nn.Dropout(p=dropout), nn.Linear(4096, 4096), nn.ReLU(inplace=True), nn.Linear(4096, num_classes) def forward(self, x): # 提取图像特征 x = self.features(x)x = self.avgpool(x)x = torch.flatten(x, start_dim=1) # 进行图像分类 x = self.classifier(x) return x In [4]: model_AlexNet = AlexNet(num_classes=10) inputs = torch.randn(1, 3, 224, 224)out = model_AlexNet(inputs) print(out.shape) torch.Size([1, 10]) 2. Mobilenetv3 In [5]: class HardSwish(nn.Module): def __init__(self, inplace=True): super(HardSwish, self).__init__() self.relu6 = nn.ReLU6(inplace=inplace) def forward(self, x): return x * self.relu6(x+3)/6class ConvBNActivation(nn.Sequential): def __init__(self, in_channel, out_channel, kernel_size, stride, groups, activate): padding = (kernel_size - 1) // 2 super(ConvBNActivation, self).__init__(nn.Conv2d(in_channels=in_channel, out_channels=out_channel, kernel_size=kernel_size, st nn.BatchNorm2d(out_channel), nn.ReLU6(inplace=True) if activate == 'relu' else HardSwish() class SqueezeAndExcite(nn.Module): def __init__(self, in_channel, out_channel, divide=4): super(SqueezeAndExcite, self).__init__() mid_channel = in_channel // divide self.pool = nn.AdaptiveAvgPool2d((1, 1)) self.SEblock = nn.Sequential(nn.Linear(in_features=in_channel, out_features=mid_channel), nn.ReLU6(inplace=True), nn.Linear(in_features=mid_channel, out_features=out_channel), HardSwish(),) def forward(self, x): b, c, h, w = x.size()out = self.pool(x)out = torch.flatten(out, start_dim=1) out = self.SEblock(out) out = out.view(b, c, 1, 1)return out * x class SEInverteBottleneck(nn.Module): def __init__(self, in_channel, mid_channel, out_channel, kernel_size, use_se, activate, stride) super(SEInverteBottleneck, self).__init__() self.use shortcut = stride == 1 and in channel == out channel self.use_se = use_se self.conv = ConvBNActivation(in_channel=in_channel, out_channel=mid_channel, kernel_size=1, self.depth_conv = ConvBNActivation(in_channel=mid_channel, out_channel=mid_channel, kernel) if self.use se: self.SEblock = SqueezeAndExcite(in_channel=mid_channel, out_channel=mid_channel) self.point_conv = ConvBNActivation(in_channel=mid_channel, out_channel=out_channel, kernel_ def forward(self, x): out = self.conv(x)out = self.depth_conv(out) if self.use_se: out = self.SEblock(out) out = self.point_conv(out) if self.use_shortcut: return x + out return out class MobileNetV3(nn.Module): def __init__(self, num_classes=1000, type='large'): super(MobileNetV3, self).__init__() self.type = type self.first_conv = nn.Sequential(nn.Conv2d(in_channels=3, out_channels=16, kernel_size=3, stride=2, padding=1, bias=Fals nn.BatchNorm2d(16), HardSwish(), if self.type == 'large': self.large_bottleneck = nn.Sequential(SEInverteBottleneck(in_channel=16, mid_channel=16, out_channel=16, kernel_size=3, u SEInverteBottleneck(in_channel=16, mid_channel=64, out_channel=24, kernel_size=3, u SEInverteBottleneck(in_channel=24, mid_channel=72, out_channel=24, kernel_size=3, u SEInverteBottleneck(in_channel=24, mid_channel=72, out_channel=40, kernel_size=5, ι SEInverteBottleneck(in_channel=40, mid_channel=120, out_channel=40, kernel_size=5, SEInverteBottleneck(in_channel=40, mid_channel=120, out_channel=40, kernel_size=5, SEInverteBottleneck(in_channel=40, mid_channel=240, out_channel=80, kernel_size=3, SEInverteBottleneck(in_channel=80, mid_channel=200, out_channel=80, kernel_size SEInverteBottleneck(in_channel=80, mid_channel=184, out_channel=80, kernel_size=3, SEInverteBottleneck(in_channel=80, mid_channel=184, out_channel=80, kernel_size=3, SEInverteBottleneck(in_channel=80, mid_channel=480, out_channel=112, kernel_size=3, SEInverteBottleneck(in_channel=112, mid_channel=672, out_channel=112, kernel_size=3 SEInverteBottleneck(in_channel=112, mid_channel=672, out_channel=160, kernel_size=5 SEInverteBottleneck(in_channel=160, mid_channel=960, out_channel=160, kernel_size=5 SEInverteBottleneck(in_channel=160, mid_channel=960, out_channel=160, kernel_size=5 self.large_last_stage = nn.Sequential(nn.Conv2d(in_channels=160, out_channels=960, kernel_size=1, stride=1, bias=False), nn.BatchNorm2d(960), HardSwish(), nn.AdaptiveAvgPool2d((1, 1)), nn.Conv2d(in_channels=960, out_channels=1280, kernel_size=1, stride=1, bias=False), HardSwish(), else: self.small_bottleneck = nn.Sequential(SEInverteBottleneck(in_channel=16, mid_channel=16, out_channel=16, kernel_size=3, d SEInverteBottleneck(in_channel=16, mid_channel=72, out_channel=24, kernel_size=3, u SEInverteBottleneck(in_channel=24, mid_channel=88, out_channel=24, kernel_size=3, u SEInverteBottleneck(in_channel=24, mid_channel=96, out_channel=40, kernel_size=5, d SEInverteBottleneck(in_channel=40, mid_channel=240, out_channel=40, kernel_size=5, SEInverteBottleneck(in_channel=40, mid_channel=240, out_channel=40, kernel_size=5, SEInverteBottleneck(in_channel=40, mid_channel=120, out_channel=48, kernel_size=5, SEInverteBottleneck(in_channel=48, mid_channel=144, out_channel=48, kernel_size=5, SEInverteBottleneck(in_channel=48, mid_channel=288, out_channel=96, kernel_size=5, SEInverteBottleneck(in_channel=96, mid_channel=576, out_channel=96, kernel_size=5, SEInverteBottleneck(in_channel=96, mid_channel=576, out_channel=96, kernel_size=5, self.small_last_stage = nn.Sequential(nn.Conv2d(in_channels=96, out_channels=576, kernel_size=1, stride=1, bias=False), nn.BatchNorm2d(576), HardSwish(), nn.AdaptiveAvgPool2d((1, 1)), nn.Conv2d(in_channels=576, out_channels=1280, kernel_size=1, stride=1, bias=False), HardSwish(), self.classifier = nn.Sequential(nn.Dropout(p=0.2), nn.Linear(in_features=1280, out_features=num_classes), # weight init for m in self.modules(): if isinstance(m, nn.Conv2d): nn.init.kaiming_normal_(m.weight, mode='fan_out') if m.bias is not None: nn.init.zeros_(m.bias) elif isinstance(m, nn.BatchNorm2d): nn.init.ones_(m.weight) nn.init.zeros_(m.bias) elif isinstance(m, nn.Linear): nn.init.normal_(m.weight, mean=0, std=0.01) nn.init.zeros_(m.bias) def forward(self, x): $x = self.first_conv(x)$ if self.type == 'large': x = self.large_bottleneck(x) x = self.large_last_stage(x) x = self.small bottleneck(x)x = self.small_last_stage(x) x = torch.flatten(x, start_dim=1) x = self.classifier(x)return x In [6]: inputs = torch.randn(1, 3, 224, 224) model_Mobilenetv3 = MobileNetV3(num_classes=10) out = model_Mobilenetv3(inputs) print(out.shape) torch.Size([1, 10]) 3. Shufflenetv2 In [7]: class ConvBNReLu(nn.Sequential): def __init__(self, in_channel, out_channel, kernel_size, stride, groups): padding = (kernel_size - 1) // 2 super(ConvBNReLu, self).__init__(nn.Conv2d(in_channels=in_channel, out_channels=out_channel, kernel_size=kernel_size, st padding=padding, groups=groups), nn.BatchNorm2d(out_channel), nn.ReLU6(inplace=True), class ConvBN(nn.Sequential): def __init__(self, in_channel, out_channel, kernel_size, stride, groups): padding = (kernel_size - 1) // super(ConvBN, self).__init__(nn.Conv2d(in_channels=in_channel, out_channels=out_channel, kernel_size=kernel_size, st padding=padding, groups=groups), nn.BatchNorm2d(out_channel), class HalfSplit(nn.Module): 实现channel split def __init__(self, dim=0, first_half=True): super(HalfSplit, self).__init__() self.first_half = first_half self.dim = dimdef forward(self, x): splits = torch.chunk(x, 2, dim=self.dim) return splits[0] if self.first_half else splits[1] class ChannelShuffle(nn.Module): def __init__(self, groups): super(ChannelShuffle, self).__init__() self.groups = groups def forward(self, x): # Channel shuffle: [N,C,H,W] -> [N,g,C/g,H,W] -> [N,C/g,g,H,w] -> [N,C,H,W] batch_size, num_channels, height, width = x.size() channels_per_group = num_channels // self.groups x = x.view(batch_size, self.groups, channels_per_group, height, width) x = torch.transpose(x, dim0=1, dim1=2).contiguous() $x = x.view(batch_size, -1, height, width)$ return x class ShuffleNetUnits(nn.Module): def __init__(self, in_channel, out_channel, stride, groups): super(ShuffleNetUnits, self).__init__() self.stride = stride if self.stride > 1: mid_channel = out_channel - in_channel else: mid_channel = out_channel // 2 in_channel = mid_channel self.first_split = HalfSplit(dim=1, first_half=True) self.second_split = HalfSplit(dim=1, first_half=False) # 论文中Fig.3.(d) 中的右半部分 self.bottleneck = nn.Sequential(# 1x1 Conv ConvBNReLu(in_channel=in_channel, out_channel=mid_channel, kernel_size=1, stride=1, grd ConvBN(in_channel=mid_channel, out_channel=mid_channel, kernel_size=3, stride=stride, g # 1x1 Conv ConvBNReLu(in_channel=mid_channel, out_channel=mid_channel, kernel_size=1, stride=1, gr if self.stride > 1: # 论文中Fig.3.(d) 中的左半部分 self.shortcut = nn.Sequential(# 3x3 DWConv ConvBN(in_channel=in_channel, out_channel=in_channel, kernel_size=3, stride=stride, ConvBNReLu(in_channel=in_channel, out_channel=in_channel, kernel_size=1, stride=1, self.channel_shuffle = ChannelShuffle(groups=groups) def forward(self, x): if self.stride > 1: x1 = self.bottleneck(x)x2 = self.shortcut(x)else: # channel split x1 = self.first_split(x) $x2 = self.second_split(x)$ x1 = self.bottleneck(x1)out = torch.cat([x1, x2], dim=1) out = self.channel_shuffle(out) return out class ShuffleNetV2(nn.Module): def __init__(self, planes, layers, groups, num_classes=1000): super(ShuffleNetV2, self).__init__() self.groups = groups self.stage1 = nn.Sequential(ConvBNReLu(in_channel=3, out_channel=24, kernel_size=3, stride=2, groups=1), nn.MaxPool2d(kernel_size=3, stride=2, padding=1), self.stage2 = self._make_layers(in_channel=24, out_channel=planes[0], block_num=layers[0], self.stage3 = self._make_layers(in_channel=planes[0], out_channel=planes[1], block_num=layε is_stage2=False) self.stage4 = self._make_layers(in_channel=planes[1], out_channel=planes[2], block_num=laye is_stage2=False) self.conv5 = ConvBNReLu(in_channel=planes[2], out_channel=planes[3], kernel_size=1, stride= self.globalpool = nn.AdaptiveAvgPool2d((1, 1)) self.fc = nn.Sequential(nn.Dropout(p=0.2), nn.Linear(in_features=planes[3], out_features=num_classes) for m in self.modules(): if isinstance(m, nn.Conv2d): nn.init.kaiming_normal_(m.weight) nn.init.constant_(m.bias, 0) elif isinstance(m, nn.BatchNorm2d) or isinstance(m, nn.Linear): nn.init.constant_(m.weight, 1) nn.init.constant_(m.bias, 0) def _make_layers(self, in_channel, out_channel, block_num, is_stage2): layers = []layers.append(ShuffleNetUnits(in_channel=in_channel, out_channel=out_channel, stride=2, groups=1 if is_stage2 else self.groups)) for _ in range(1, block_num): layers.append(ShuffleNetUnits(in_channel=out_channel, out_channel=out_channel, stride=1, groups=s return nn.Sequential(*layers) def forward(self, x): x = self.stage1(x)x = self.stage2(x)x = self.stage3(x)x = self.stage4(x)x = self.conv5(x)x = self.globalpool(x)x = torch.flatten(x, start_dim=1) x = self.fc(x)return x def shufflenet_v2_x1_5(**kwargs): planes = [176, 352, 704, 1024] layers = [4, 8, 4]model = ShuffleNetV2(planes=planes, layers=layers, groups=1, **kwargs) return model In [8]: inputs = torch.randn(1, 3, 224, 224) model_shufflenet = shufflenet_v2_x1_5(num_classes=10) out = model_shufflenet(inputs) print(out.shape) torch.Size([1, 10]) 绘图函数 plot_model_losses 函数可以将多个模型的loss训练过程绘画在一张图,便于展示结果。 In [9]: def plot_model_losses(train_losses, val_losses, names): nets = len(names)cols = 3rows = (nets + cols - 1) // cols # 计算行数,确保布局合理 # 创建一个符合网格布局的图形 fig, axes = plt.subplots(rows, cols, figsize=(cols * 6, rows * 5)) # if rows == 1:axes = [axes] # 如果只有一行,确保 axes 是一个列表 for i in range(nets): row = i // colscol = i % cols ax = axes[row][col] **if** rows > 1 **else** axes[col] # 确保 train_losses[i] 和 val_losses[i] 是一维数组或列表 ax.plot(train_losses[i], label='Train Loss') ax.plot(val_losses[i], label='Test Loss') ax.set_title(f'Model {names[i]} Losses') ax.set_xlabel('Epoch') ax.set_ylabel('Loss') ax.legend() plt.tight_layout() # 关闭空的子图 for j in range(i + 1, rows * cols): row = j // colscol = j % cols ax = axes[row][col] if rows > 1 else axes[col] ax.axis('off') plt.show() plot_val_acc 函数可以接受模型的验证准确率、模型名称、绘图样式,然后将所有模型的验证集准确率进行对比 In [10]: | def plot_val_acc(val_acc_list, model_names, styles=None, figsize=(15, 5), title='Model Accuracy', y if styles is None: styles = [':', '-.', '--', ':', '-.', '--', '-'] * (len(val_acc_list) // 4 + 1) plt.figure(figsize=figsize) for i, val_acc in enumerate(val_acc_list): plt.plot(val_acc, linestyle=styles[i % len(styles)], label=model_names[i]) plt.title(title) plt.ylabel(ylabel) plt.xlabel(xlabel) plt.legend(loc='upper left') axes = plt.gca() axes.set_ylim(ylim) plt.show() 模型训练函数 In [11]: def train_model(model, train_loader, test_loader, epochs=20, device="cpu", model_name=''): criterion = nn.CrossEntropyLoss() optimizer = optim.Adam(model.parameters(), lr=0.001) train_acc = [] $val_acc = []$ train_loss = [] $val_loss = []$ model.to(device) while True: folder_path = "./weight_" + model_name + '_' + ''.join(random.choices(string.ascii_lowercas if not os.path.exists(folder_path): os.makedirs(folder_path) break print(f"weights are saved to {folder_path} ") for epoch in range(epochs): # Training phase model.train() correct = 0 total = 0 running_loss = 0.0 for images, labels in train_loader: images, labels = images.to(device), labels.to(device) optimizer.zero_grad() outputs = model(images) loss = criterion(outputs, labels) loss.backward() optimizer.step() running_loss += loss.item() _, predicted = torch.max(outputs.data, 1) total += labels.size(0) correct += (predicted == labels).sum().item() train_loss.append(running_loss / len(train_loader)) train_acc.append(correct / total) # Validation phase model.eval() correct = 0 total = 0running_loss = 0.0with torch.no grad(): for images, labels in test_loader: images, labels = images.to(device), labels.to(device) outputs = model(images) loss = criterion(outputs, labels) running_loss += loss.item() _, predicted = torch.max(outputs.data, 1) total += labels.size(0) correct += (predicted == labels).sum().item() val_loss.append(running_loss / len(test_loader)) val_acc.append(correct / total) # 保存模型 model_file = os.path.join(folder_path, f"epoch_{epoch+1}.pth") torch.save(model.state_dict(), model_file) print(f"Saved model at epoch {epoch+1} to {model_file}") print(f"Epoch {epoch+1}/{epochs}, Train Loss: {train_loss[-1]:.4f}, Train Accuracy: {train_ return train_loss, train_acc, val_loss, val_acc 数据集导入 In [12]: # 强力的数据增强组合,只应用于训练集 train_transform = transforms.Compose([transforms.Resize(size=224), transforms.RandomHorizontalFlip(), # 随机水平翻转,保持不变 transforms。RandomRotation(10), # 随机旋转角度减小, 从15度减少到5度 transforms.RandomResizedCrop(224, scale=(0.85, 1.0)), # 随机裁剪, transforms.ColorJitter(brightness=0.1, contrast=0.1, saturation=0.1, hue=0.1), # 随机调整颜色幅度 transforms.ToTensor(), transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5)) # 归一化]) # 仅进行标准化的转换,应用于测试集 test_transform = transforms.Compose([transforms.Resize(size=224), transforms.ToTensor(), transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5)) # 归一化]) # 加载CIFAR-10数据集 train_dataset = datasets.CIFAR10(root="./data", train=True, download=True, transform=train_transfor test_dataset = datasets.CIFAR10(root="./data", train=False, download=True, transform=test_transform train_loader = DataLoader(train_dataset, batch_size=64, shuffle=True) test_loader = DataLoader(test_dataset, batch_size=64, shuffle=False) Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz to ./data/cifar-10-python.tar.g 100% | 170498071/170498071 [00:03<00:00, 49241583.26it/s] Extracting ./data/cifar-10-python.tar.gz to ./data Files already downloaded and verified In [13]: def plotsample(data): fig, axs = plt.subplots(1,5,figsize=(10,10)) #建立子图 for i in range(5): num = random.randint(0,len(data)-1) #首先选取随机数,随机选取五次 #抽取数据中对应的图像对象,make_grid函数可将任意格式的图像的通道数升为3,而不改变图像原始的数据 #而展示图像用的imshow函数最常见的输入格式也是3通道 npimg = torchvision.utils.make_grid(data[num][0]).numpy() nplabel = data[num][1] #提取标签 #将图像由(3, weight, height)转化为(weight, height, 3),并放入imshow函数中读取 axs[i].imshow(np.transpose(npimg, (1, 2, 0))) axs[i].set_title(nplabel) #给每个子图加上标签 axs[i].axis("off") #消除每个子图的坐标轴 In [14]: plotsample(train_dataset) 6 7 5 6 In [15]: plotsample(test_dataset) 3 6 训练 In [16]: model_name_list = ['alex', 'Mobilenetv3', 'shufflenet'] train_loss_list, train_acc_list, val_loss_list, val_acc_list = [], [], [], In [17]: train_loss, train_acc, val_loss, val_acc = train_model(model=model_AlexNet, train_loader=train_load train_loss_list.append(train_loss) train acc list.append(train acc) val loss list.append(val loss) val_acc_list.append(val_acc) weights are saved to ./weight_alex_zdujejk25c Saved model at epoch 1 to ./weight_alex_zdujejk25c/epoch_1.pth Epoch 1/15, Train Loss: 1.8127, Train Accuracy: 0.3208, Validation Loss: 1.5210, Validation Accurac Saved model at epoch 2 to ./weight_alex_zdujejk25c/epoch_2.pth Epoch 2/15, Train Loss: 1.5238, Train Accuracy: 0.4433, Validation Loss: 1.3262, Validation Accurac y: 0.5190 Saved model at epoch 3 to ./weight_alex_zdujejk25c/epoch_3.pth Epoch 3/15, Train Loss: 1.4113, Train Accuracy: 0.4925, Validation Loss: 1.2323, Validation Accurac y: 0.5522 Saved model at epoch 4 to ./weight_alex_zdujejk25c/epoch_4.pth Epoch 4/15, Train Loss: 1.3306, Train Accuracy: 0.5251, Validation Loss: 1.1336, Validation Accurac y: 0.6066 Saved model at epoch 5 to ./weight_alex_zdujejk25c/epoch_5.pth Epoch 5/15, Train Loss: 1.2715, Train Accuracy: 0.5472, Validation Loss: 1.1187, Validation Accurac y: 0.6047 Saved model at epoch 6 to ./weight_alex_zdujejk25c/epoch_6.pth Epoch 6/15, Train Loss: 1.2211, Train Accuracy: 0.5689, Validation Loss: 1.0880, Validation Accurac Saved model at epoch 7 to ./weight_alex_zdujejk25c/epoch_7.pth Epoch 7/15, Train Loss: 1.1844, Train Accuracy: 0.5837, Validation Loss: 1.0370, Validation Accurac y: 0.6381 Saved model at epoch 8 to ./weight_alex_zdujejk25c/epoch_8.pth Epoch 8/15, Train Loss: 1.1505, Train Accuracy: 0.5954, Validation Loss: 1.0525, Validation Accurac y: 0.6286 Saved model at epoch 9 to ./weight_alex_zdujejk25c/epoch_9.pth Epoch 9/15, Train Loss: 1.1293, Train Accuracy: 0.6054, Validation Loss: 0.9614, Validation Accurac Saved model at epoch 10 to ./weight_alex_zdujejk25c/epoch_10.pth Epoch 10/15, Train Loss: 1.0973, Train Accuracy: 0.6175, Validation Loss: 0.9591, Validation Accura cy: 0.6657 Saved model at epoch 11 to ./weight_alex_zdujejk25c/epoch_11.pth Epoch 11/15, Train Loss: 1.0824, Train Accuracy: 0.6214, Validation Loss: 0.9518, Validation Accura Saved model at epoch 12 to ./weight_alex_zdujejk25c/epoch_12.pth Epoch 12/15, Train Loss: 1.0629, Train Accuracy: 0.6295, Validation Loss: 0.9808, Validation Accura cy: 0.6542 Saved model at epoch 13 to ./weight_alex_zdujejk25c/epoch_13.pth Epoch 13/15, Train Loss: 1.0421, Train Accuracy: 0.6373, Validation Loss: 0.9384, Validation Accura cy: 0.6824 Saved model at epoch 14 to ./weight_alex_zdujejk25c/epoch_14.pth Epoch 14/15, Train Loss: 1.0254, Train Accuracy: 0.6451, Validation Loss: 0.9043, Validation Accura Saved model at epoch 15 to ./weight_alex_zdujejk25c/epoch_15.pth Epoch 15/15, Train Loss: 1.0169, Train Accuracy: 0.6469, Validation Loss: 0.9034, Validation Accura cy: 0.6846 In [18]: train_loss, train_acc, val_loss, val_acc = train_model(model=model_Mobilenetv3, train_loader=train_ train_loss_list.append(train_loss) train_acc_list.append(train_acc) val_loss_list.append(val_loss) val_acc_list.append(val_acc) weights are saved to ./weight_Mobilenetv3_2qxxfmfpu8 Saved model at epoch 1 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_1.pth Epoch 1/15, Train Loss: 1.7753, Train Accuracy: 0.3233, Validation Loss: 1.3833, Validation Accurac Saved model at epoch 2 to ./weight Mobilenetv3 2gxxfmfpu8/epoch 2.pth Epoch 2/15, Train Loss: 1.3119, Train Accuracy: 0.5239, Validation Loss: 1.1854, Validation Accurac y: 0.5834 Saved model at epoch 3 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_3.pth Epoch 3/15, Train Loss: 1.1775, Train Accuracy: 0.5795, Validation Loss: 1.0460, Validation Accurac v: 0.6235 Saved model at epoch 4 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_4.pth Epoch 4/15, Train Loss: 0.9733, Train Accuracy: 0.6572, Validation Loss: 0.8541, Validation Accurac Saved model at epoch 5 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_5.pth Epoch 5/15, Train Loss: 0.8226, Train Accuracy: 0.7094, Validation Loss: 0.7359, Validation Accurac y: 0.7421 Saved model at epoch 6 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_6.pth Epoch 6/15, Train Loss: 0.7740, Train Accuracy: 0.7314, Validation Loss: 0.6752, Validation Accurac Saved model at epoch 7 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_7.pth Epoch 7/15, Train Loss: 0.8168, Train Accuracy: 0.7172, Validation Loss: 0.6989, Validation Accurac y: 0.7593 Saved model at epoch 8 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_8.pth Epoch 8/15, Train Loss: 0.7635, Train Accuracy: 0.7348, Validation Loss: 0.6534, Validation Accurac y: 0.7751 Saved model at epoch 9 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_9.pth Epoch 9/15, Train Loss: 0.6526, Train Accuracy: 0.7768, Validation Loss: 0.6795, Validation Accurac Saved model at epoch 10 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_10.pth Epoch 10/15, Train Loss: 0.6269, Train Accuracy: 0.7831, Validation Loss: 0.5647, Validation Accura cy: 0.8092 Saved model at epoch 11 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_11.pth Epoch 11/15, Train Loss: 0.5904, Train Accuracy: 0.7946, Validation Loss: 0.6045, Validation Accura Saved model at epoch 12 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_12.pth Epoch 12/15, Train Loss: 0.5607, Train Accuracy: 0.8065, Validation Loss: 0.5082, Validation Accura cy: 0.8299 Saved model at epoch 13 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_13.pth Epoch 13/15, Train Loss: 0.5082, Train Accuracy: 0.8245, Validation Loss: 0.5450, Validation Accura cy: 0.8206 Saved model at epoch 14 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_14.pth Epoch 14/15, Train Loss: 0.4691, Train Accuracy: 0.8376, Validation Loss: 0.4634, Validation Accura Saved model at epoch 15 to ./weight_Mobilenetv3_2qxxfmfpu8/epoch_15.pth Epoch 15/15, Train Loss: 0.4358, Train Accuracy: 0.8495, Validation Loss: 0.5034, Validation Accura cy: 0.8286 In [19]: train_loss, train_acc, val_loss, val_acc = train_model(model=model_shufflenet, train_loader=train_l train_loss_list.append(train_loss) train_acc_list.append(train_acc) val_loss_list.append(val_loss) val_acc_list.append(val_acc)

模型训练

alexnet

导入库

2. mobilenetv33. shufflenetv2

本 notebook 是 任庆桦 老师在江苏大学 24fall 专业实践小组作业的模型训练部分。

本部分实现并训练了三个模型用于 cifar10 数据集的分类:

