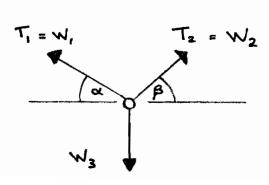
## 1A Structures: Examples paper 1 CRIB

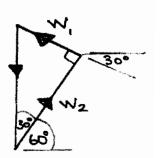
①



W<sub>3</sub>

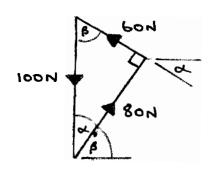
From triangle of forces: -

1001



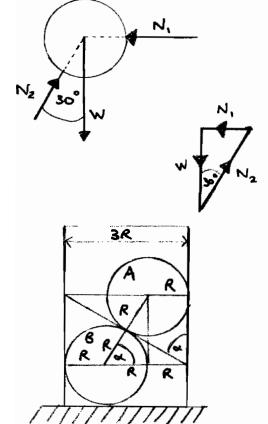
100N 141.4N

Tan & = 60/80 = 3/4



② (a) 
$$R(\uparrow) N_2 \cdot \sqrt{\frac{3}{3}} - W = 0$$

(ii) Signare A is subjected to some loads as in part (a)
$$\therefore N_1 = W | \sqrt{3}, N_2 = 2W | \sqrt{3}$$



(iii) Considering Free body  
diagram for sphere B  
$$R(-3)$$
  $N_3 = N_2/2$   $\therefore N_3 = W/\sqrt{3}$ 

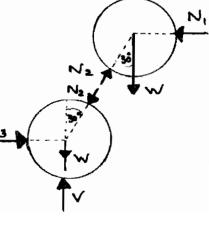
(c) Consider free body diagram
for tube.

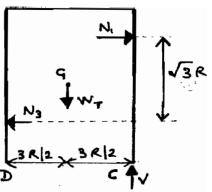
Table is smooth, so there are
no horizontal forces at CorD.

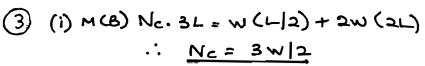
On point of topping, force
at D=0.

R (-1) N.= No (check v)

$$R (\Rightarrow) N_1 = N_3 (\text{check } \checkmark)$$
  
 $M(c). N_1. \sqrt{3} R = W_T (3R|2)$   
 $W_T = 2N_1 | \sqrt{3}$ 

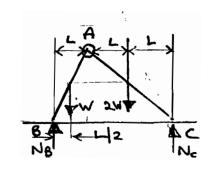






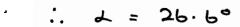
Ccheck M(c) Ng.3L=W(SL/2)+2WL
∴ Ng=3W/2

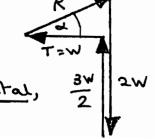
R(A) No + No = 3W Checksv]



(iii) From triangle of forces for rod AC

tan  $d = \frac{W12}{W1} = \frac{1}{2}$ 





.. R inclined at 26.6° to horizontal, upwards and left to right

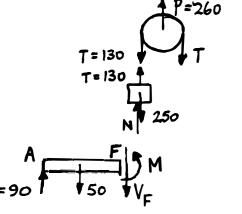
(4) (a) For bar, block, string & pulley together

$$M(E)$$
 R. 1.25 = 100.0.5 + 250.0.25

(b) 
$$R(\uparrow)$$
 P+90 = 100 + 250  
P = 260 N  
 $R(\uparrow)$  for pulley T = 130 N  
 $R(\uparrow)$  for block N = 250 - 130 = 120 N

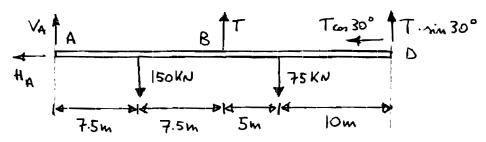
(c) 
$$R(1)$$
 for AF  $V = 90 - 50 = 40 \text{ N}$ 

$$M(F)$$
  $M = 90 \times 0.75 - 50 \times 0.375$   
= 48.75 (48.8N)



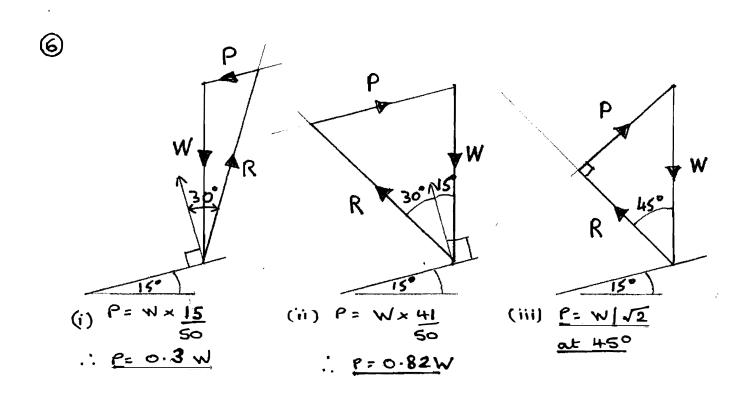
100 250

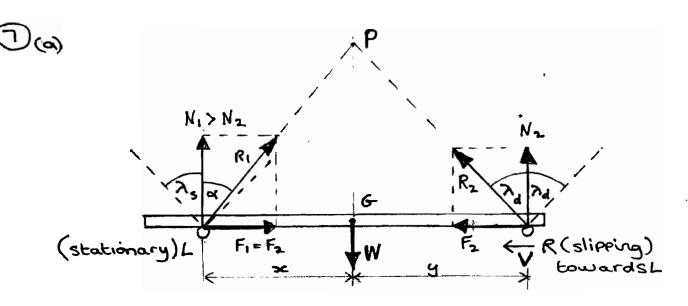
(5) Let T be the cable tension. Free body diagram for AD



Koments about A ( )+):

$$T = \frac{150.7.5 + 75.20}{30} = 87.5 \text{ KN}$$





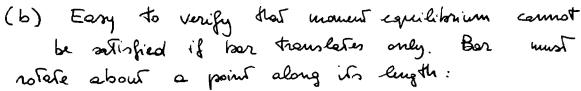
Consider free body digram of stationery ruler with finger L stationary and finger R slipping towards L.

R (=) F. = F2

M(q) Nix = N2y .. Ni > N2 for y >x Hence for y > x, R2 subtends the angle of dynamic Friction' 28 to the vestical, and R, subtends a smaller orgle & < \lambdas.

If hs = hd, then the 2 fingers will more symmetrically together once x=y, coming to rest under G. In reality  $\lambda_s > \lambda_d$  and thus lingers tend to move alternately.

Note the three forces meet at P.



L(1-d)

Displacements:

Forces:

1 pw/L 1 pt pw/L 1 pw/L (1-d) pw P

Resultants:

Resolving 1: dpw-(1-d)pw+P=0 :: P=pw(1-2d)

 $P = \mu W (1-2d)$ 

However about left-hand end of hor:

dpw. dl - (1-d)pw. (dl + (1-d) L) + PL = 0

Substitute expression for P and Tidy up:

$$d^2 - (1-d^2) + 2(1-2d) = 0$$

: 
$$2d^2 - 4d + 1 = 0$$
 :  $d = 1 \pm \frac{1}{\sqrt{2}}$ 

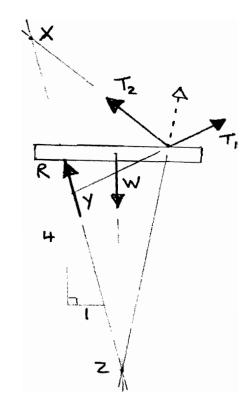
Becouse d<1, d=1-1/v2 : P= mw (v2-1)

Either take moments about X to eliminate R and T2, giving T, in terms of W

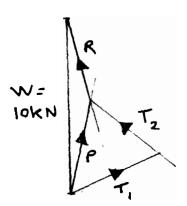
. . T = 5.1 KN approx.

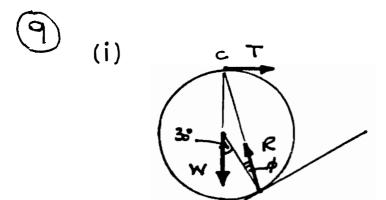
similarly, moments about Y give

T2 = 4.1 KN approx.



or resultant Pof T, and T<sub>2</sub>
must pass through the
intersection Z of R and W.
Hence measure T, and T<sub>2</sub>
from Force polygon.





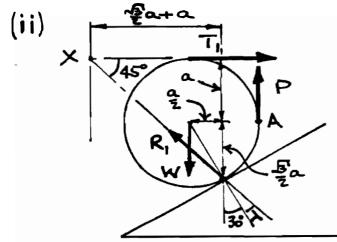
FORCES ACTING

R is the total reaction at the point of contact.

The cylinder is in equilibrium under the action of three forces, so the three lines of action pars through a single point, C.

Suice the friction is limiting, the augle  $\phi$ , between R and the normal at the point of contact, must be equal to the friction angle.

: Friction augle = 15° = h



Let radius of cylinder = a

A vertical force P is applied at A as shown. Since the cylinder is now on the point of slipping up the plane, the new reaction force R, acts in the direction shown.

Take Moments about X:  $(a + \frac{1}{2}a - \frac{a}{2})W = (a + \frac{1}{2}a + \frac{a}{2})P$   $\therefore P = \frac{1}{3}$ 

