

数据结构实验 (4)

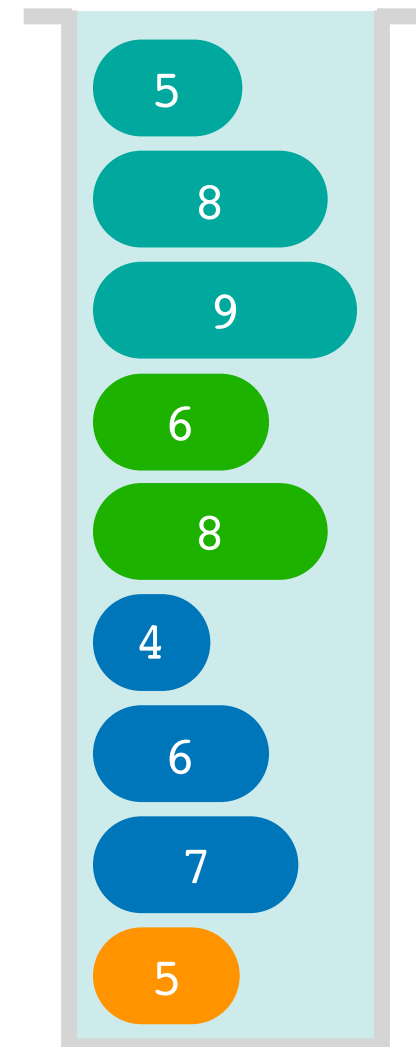
栈和队列 (二)

目录

- 栈与队列
 - 栈与队列的扩展
 - 栈 + get_max()
 - 使用栈模拟队列
 - 深度优先搜索

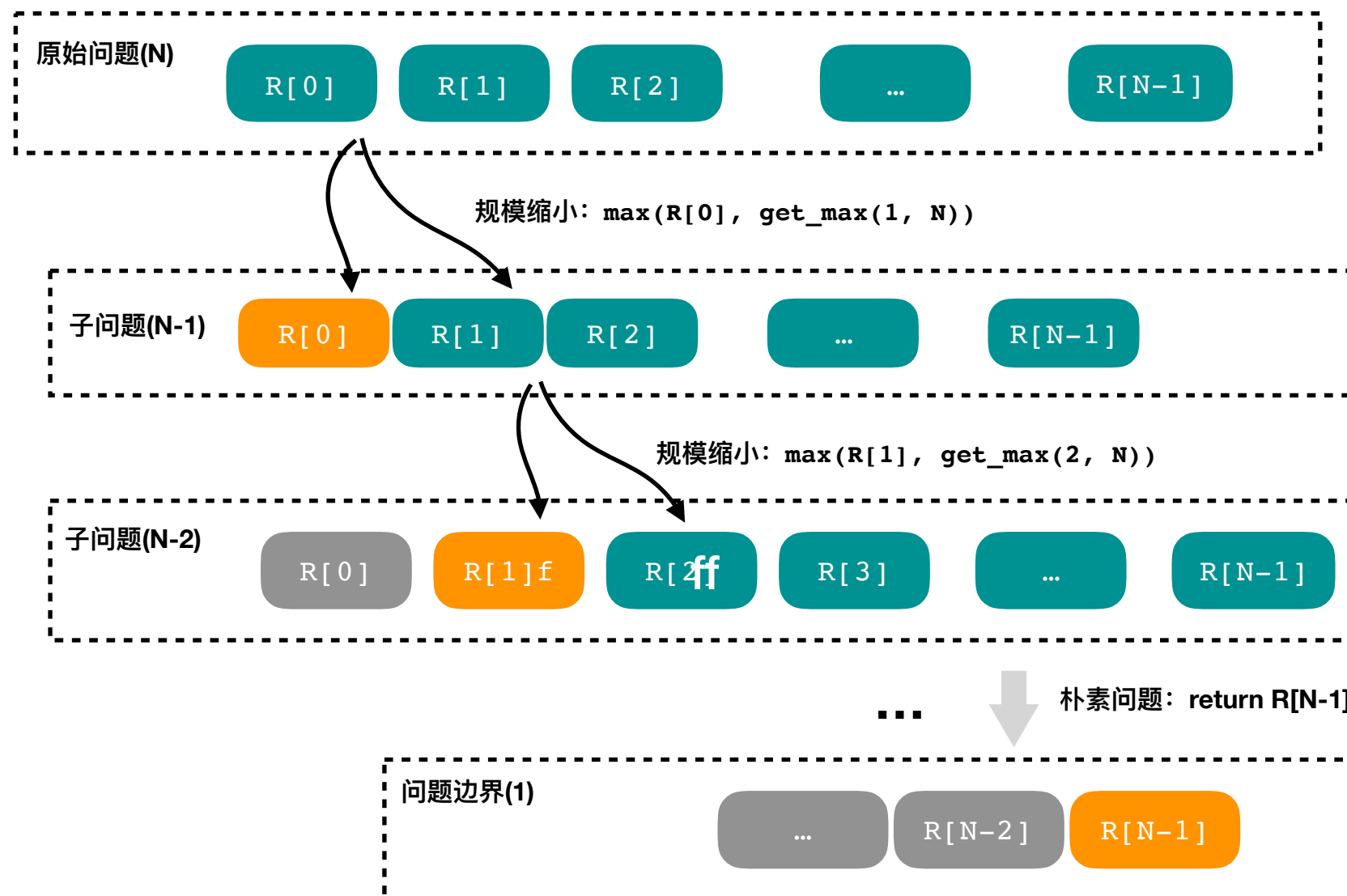
- 栈与队列的扩展
 - 栈 + get_max()

Stack



- 栈与队列的扩展
 - 栈 + get_max()

回顾递归思想求解线性表中元素的最大值:



Stack

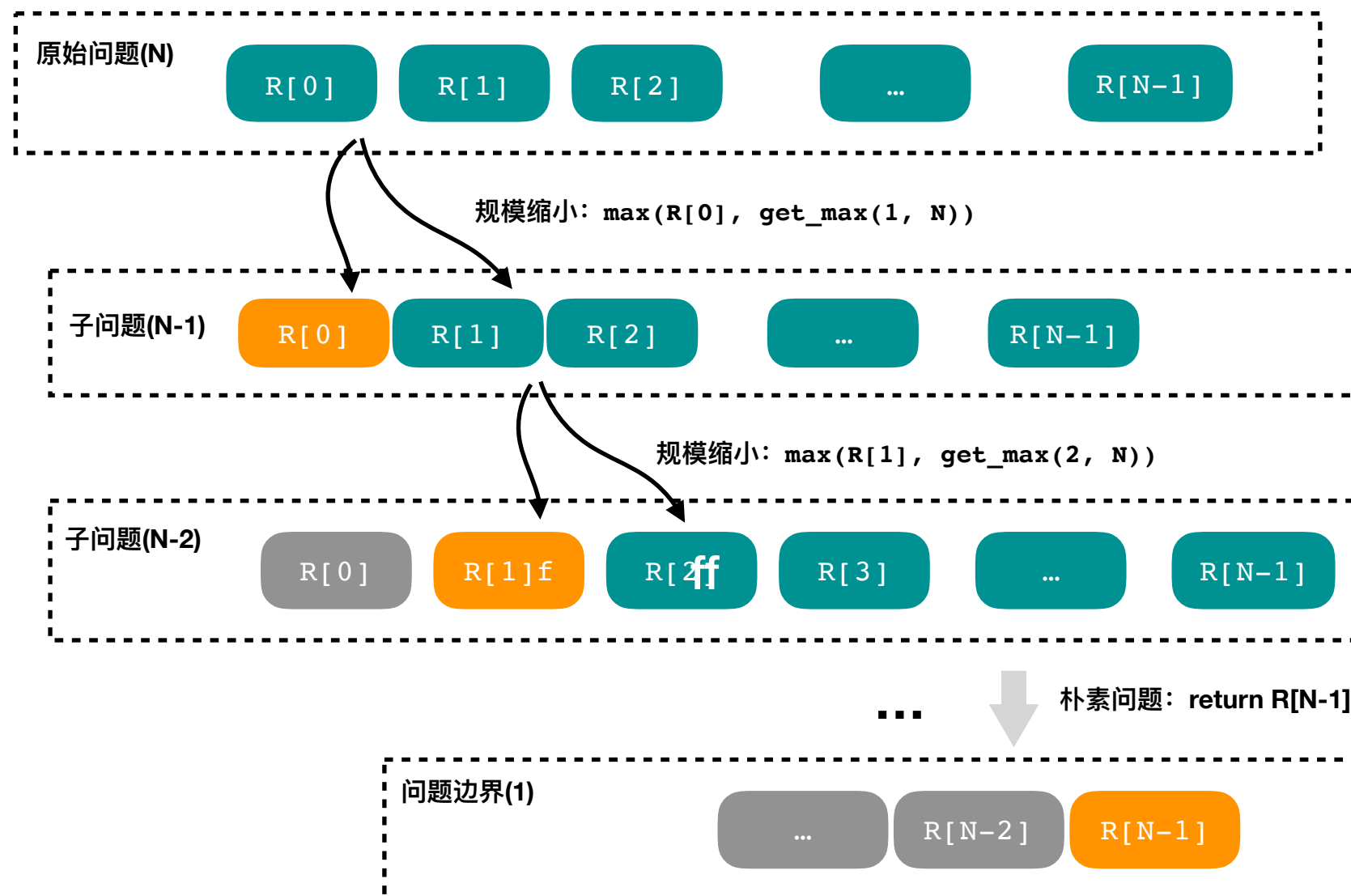


- 栈与队列的扩展

- 栈 + `get_max()`

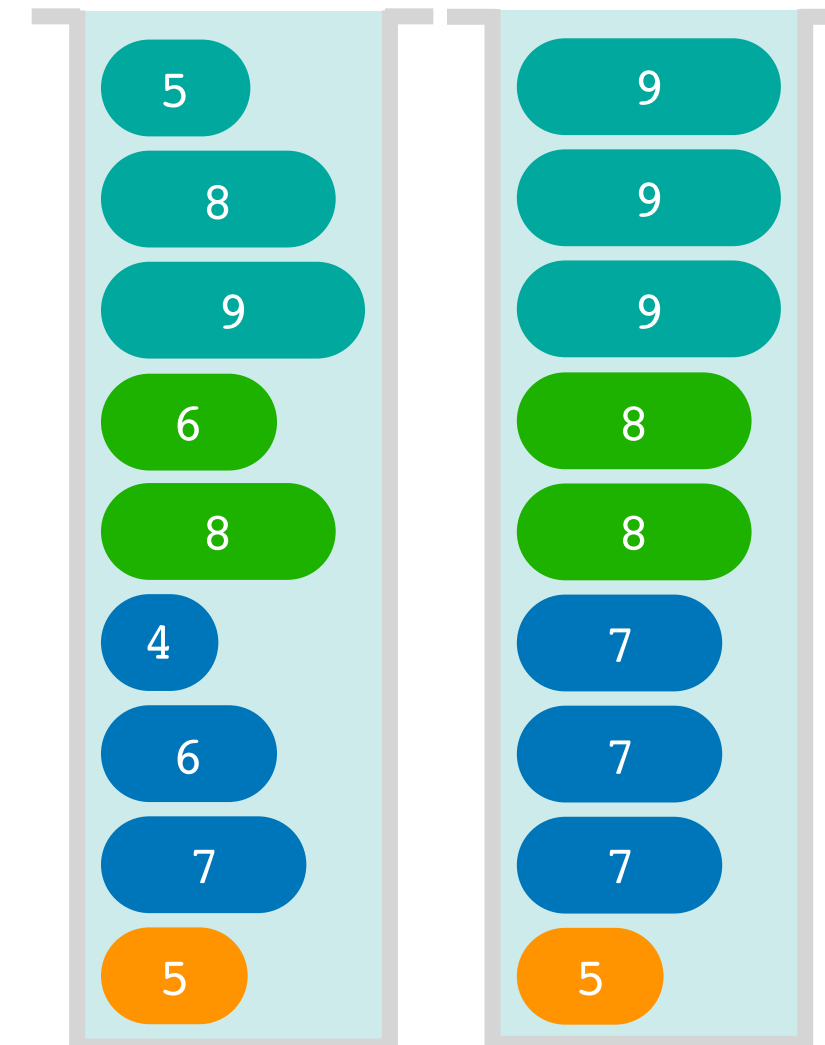
若使用一个线性表，其第 i 个元素的值为栈中头 i 个元素的最大值/最小值

回顾递归思想求解线性表中元素的最大值:



Stack

Heap



- 栈与队列的扩展
 - 栈 + get_max()

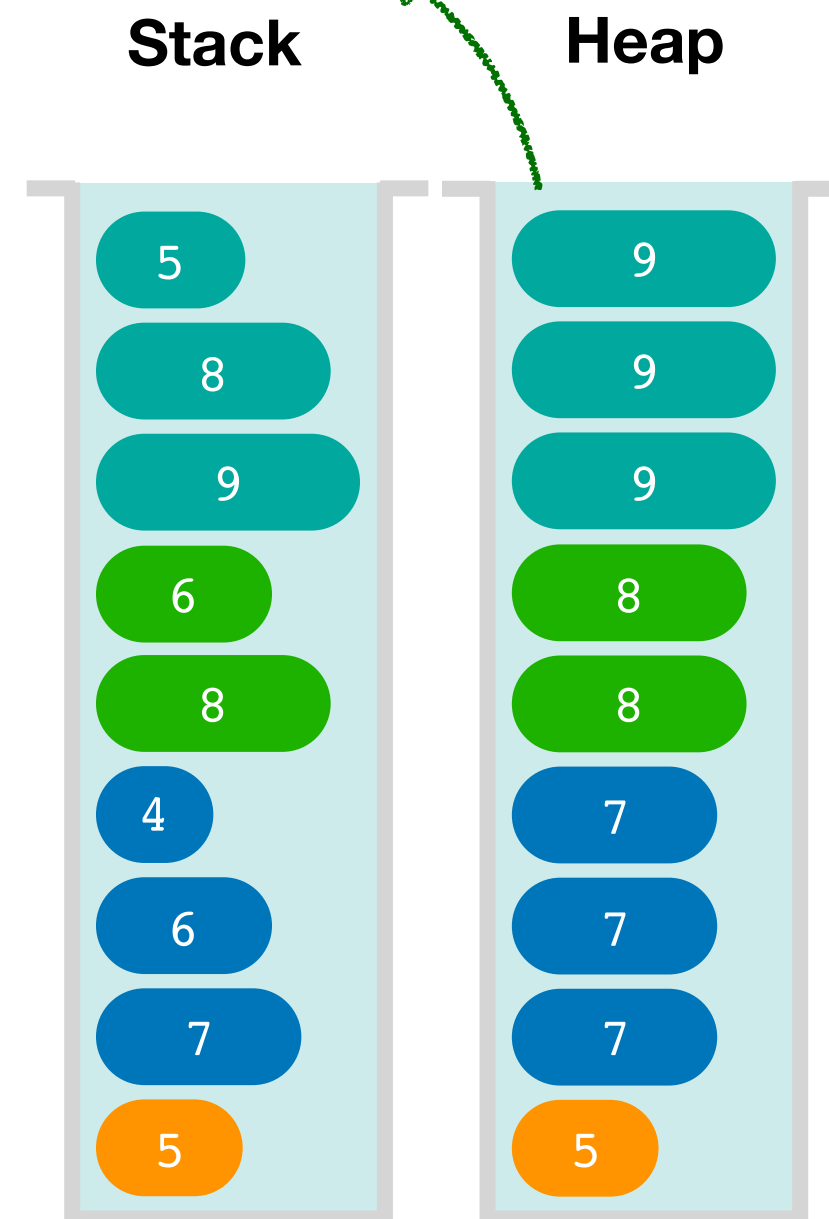
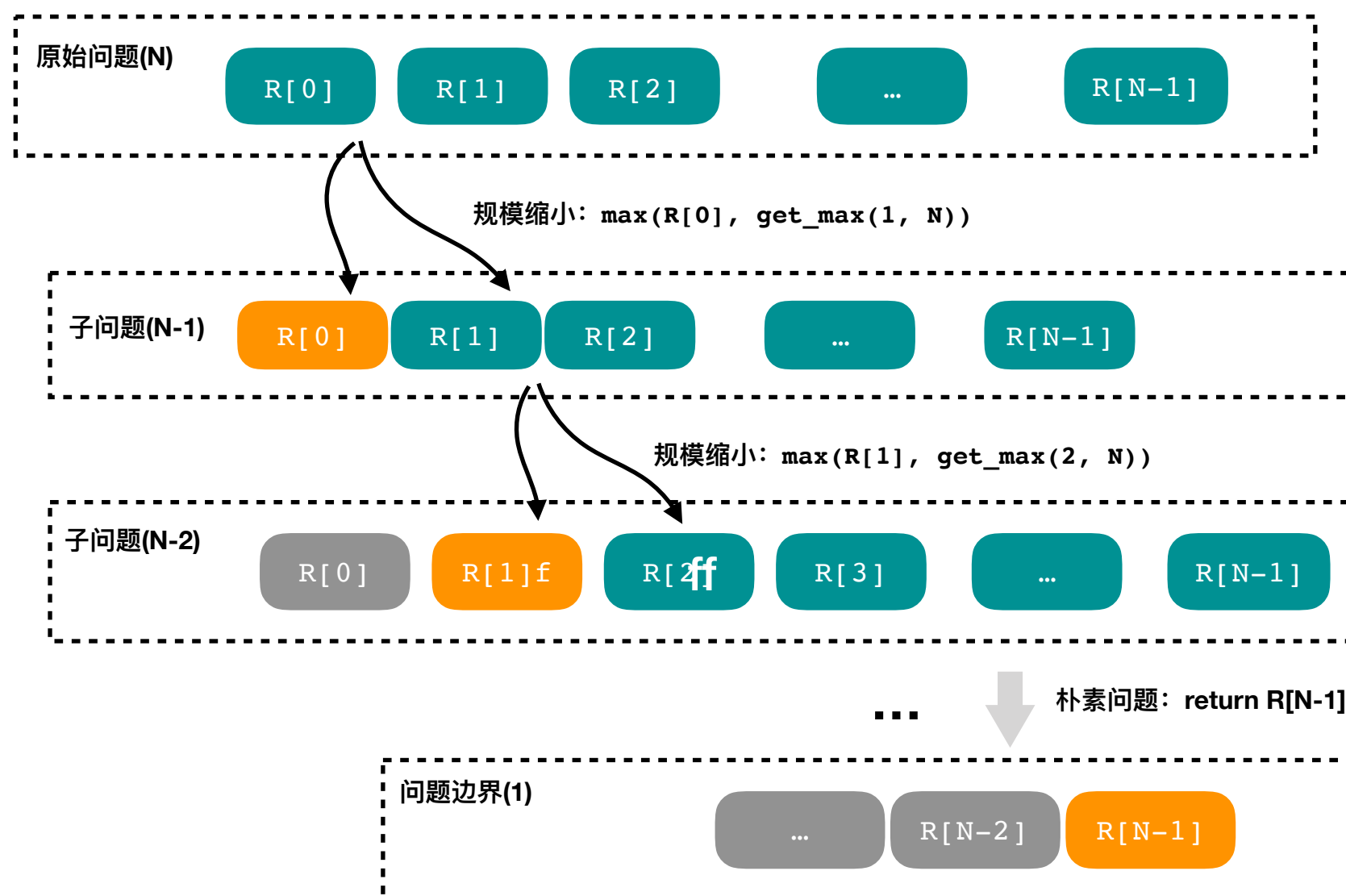
```

push(e) {
    stack.push(e);
    heap.push(max(heap.top(), e));
}

pop() {
    stack.pop();
    heap.pop();
}

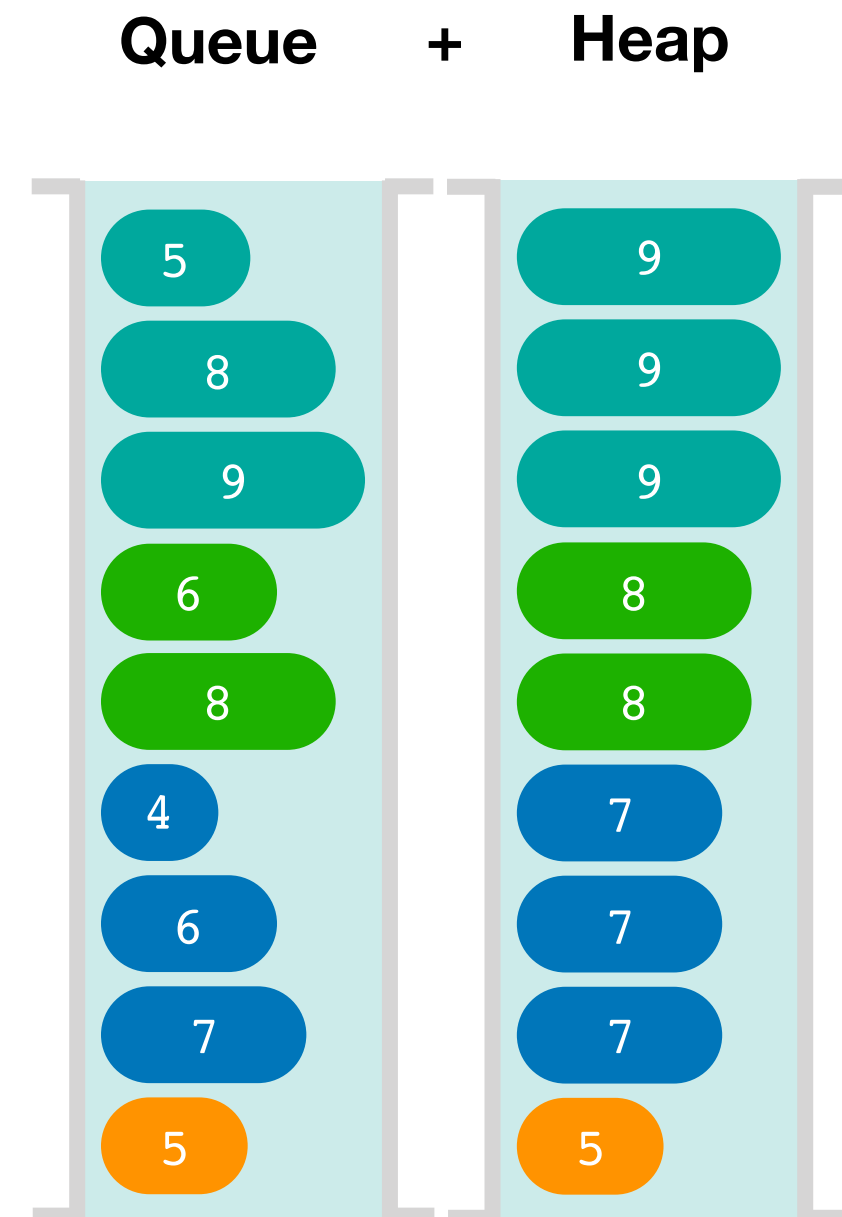
```

回顾递归思想求解线性表中元素的最大值:



- 栈与队列的扩展
 - 队列 + get_max()

如何实现?



目录

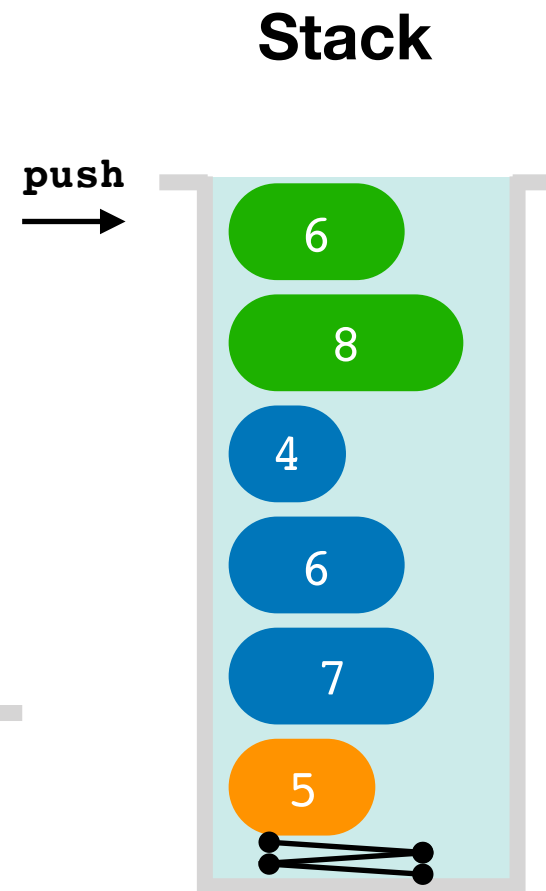
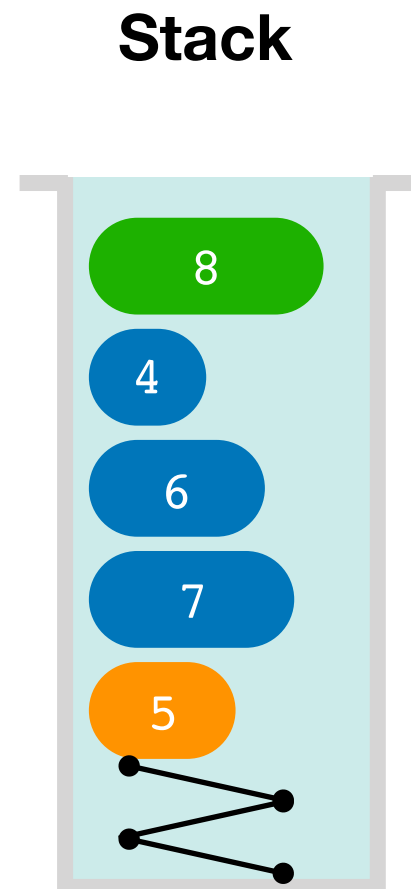
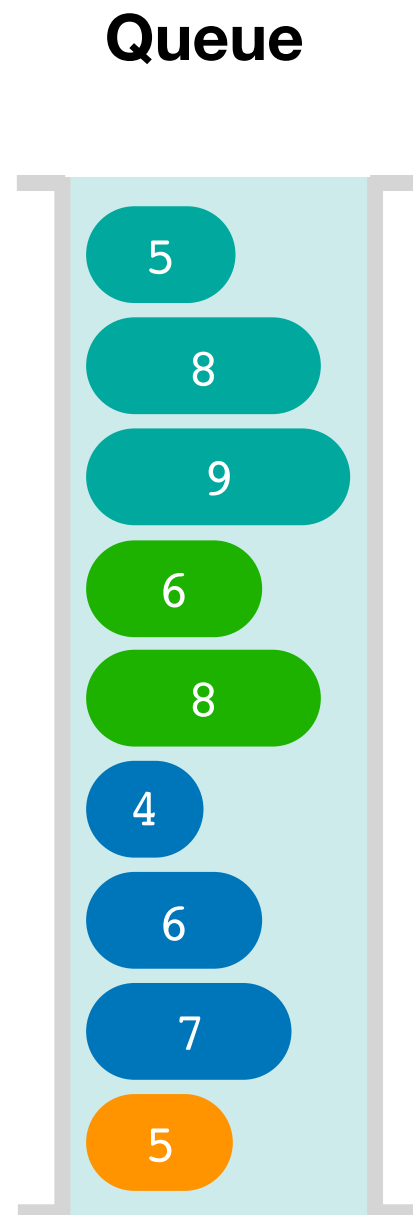
- 栈与队列
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 - 使用栈模拟队列

- 栈与队列的扩展
 - 使用栈模拟队列

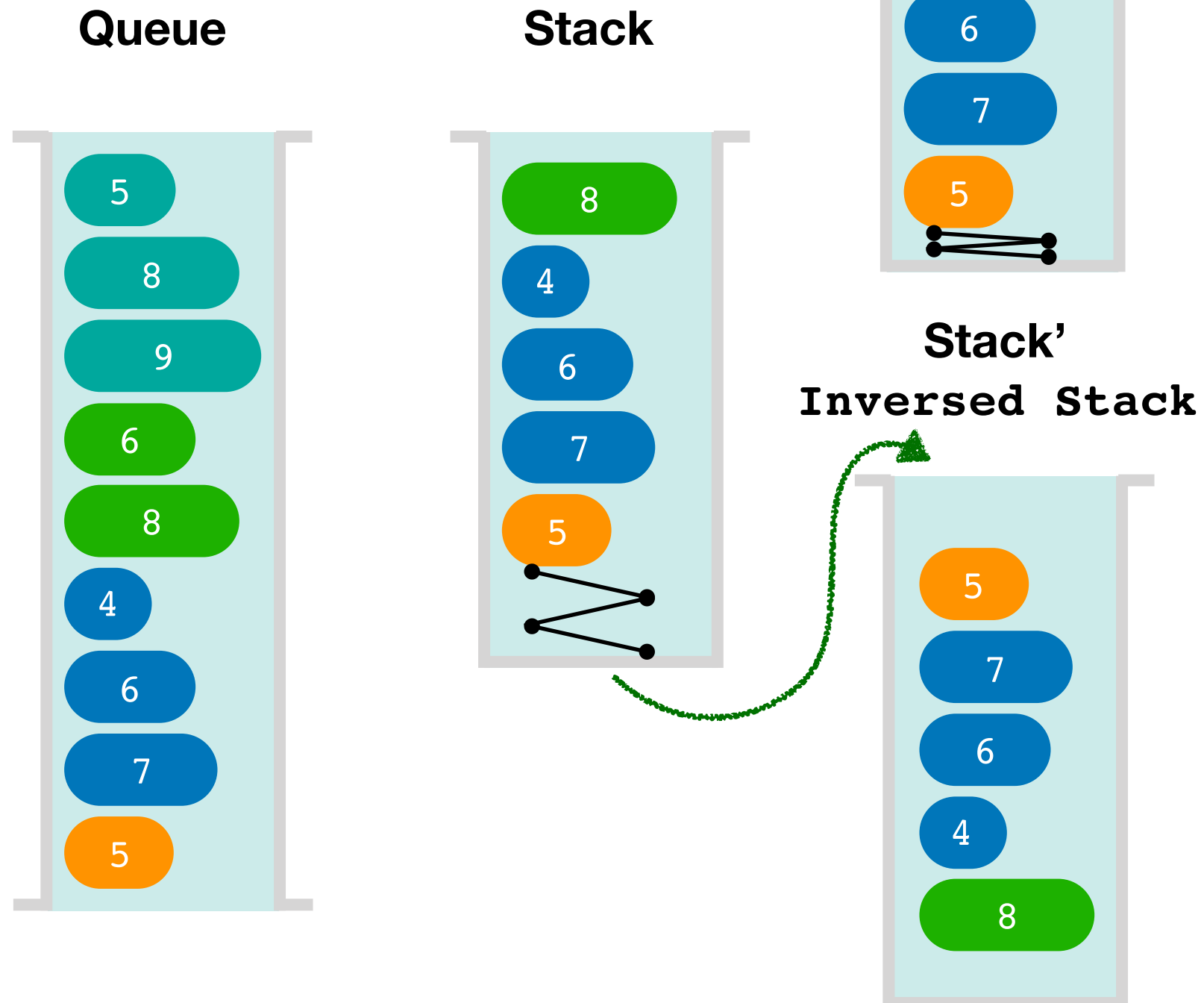
Queue



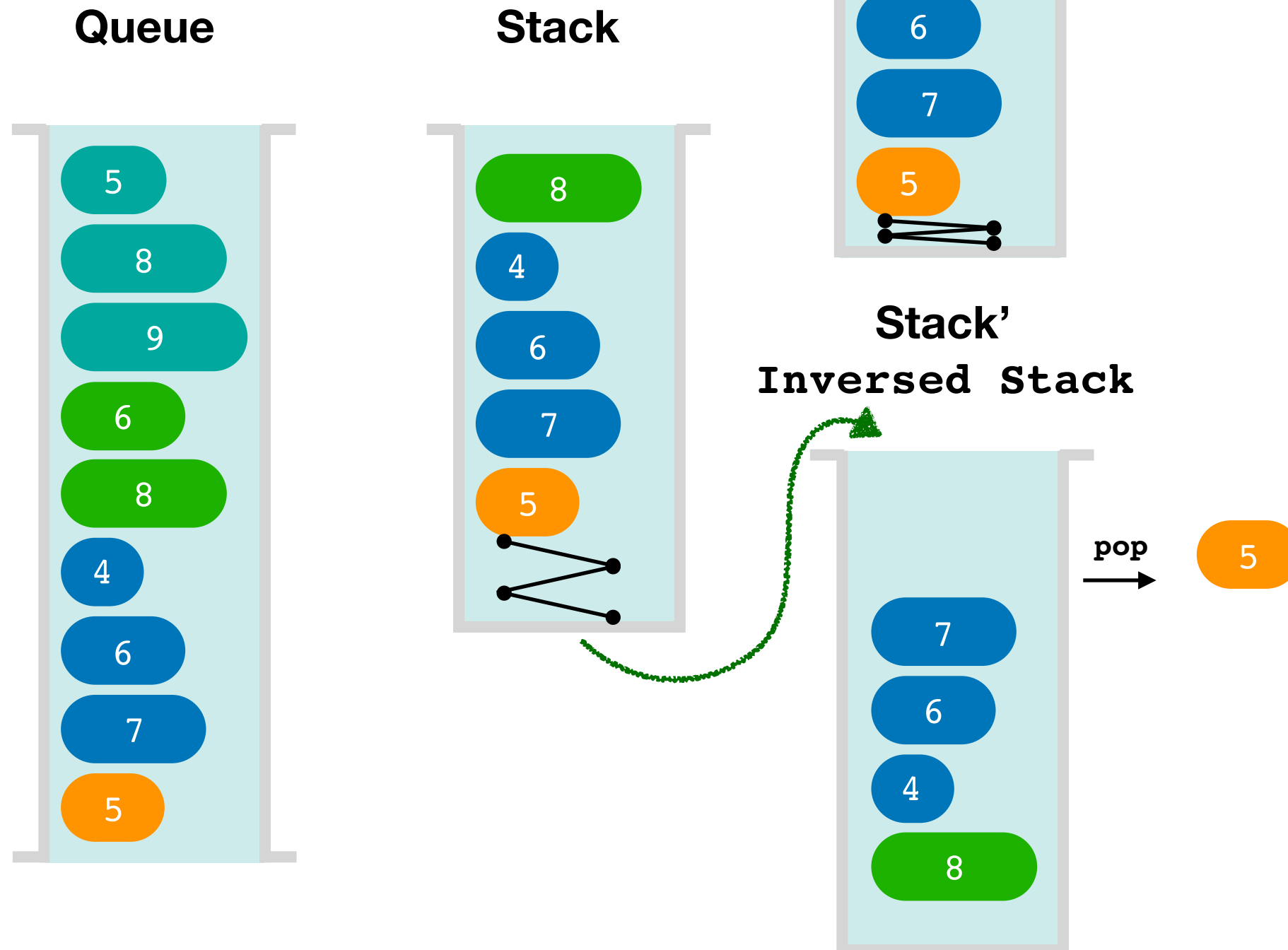
- 栈与队列的扩展
 - 使用栈模拟队列



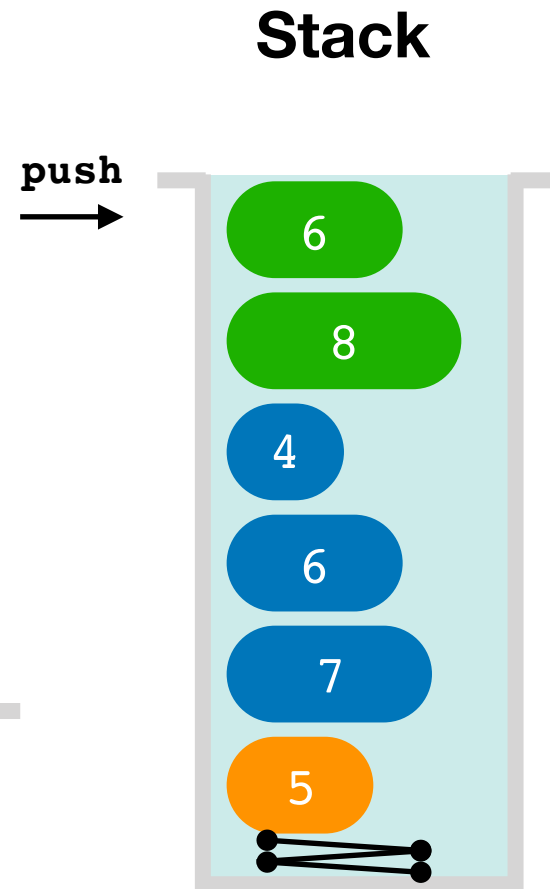
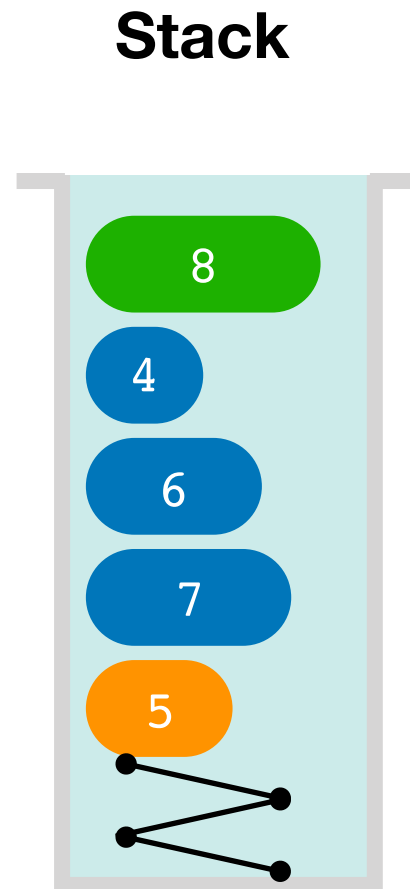
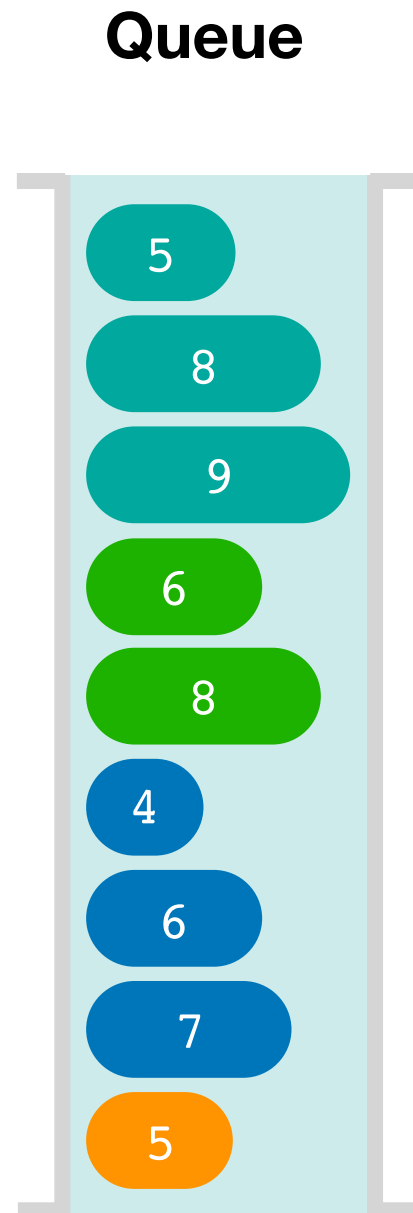
- 栈与队列的扩展
 - 使用栈模拟队列



- 栈与队列的扩展
 - 使用栈模拟队列

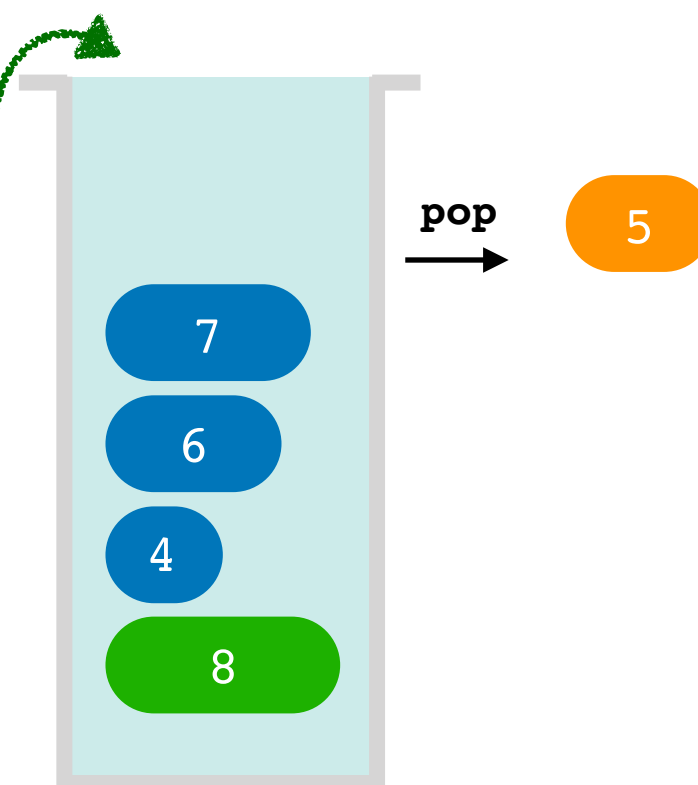


- 栈与队列的扩展
 - 使用栈模拟队列



```
push(e) {  
    stack.push(e);  
}  
pop() {  
    if (stack_.isEmpty()) {  
        while (!stack.isEmpty()) {  
            stack_.push(stack.pop());  
        }  
    }  
    Return stack_.pop();  
}
```

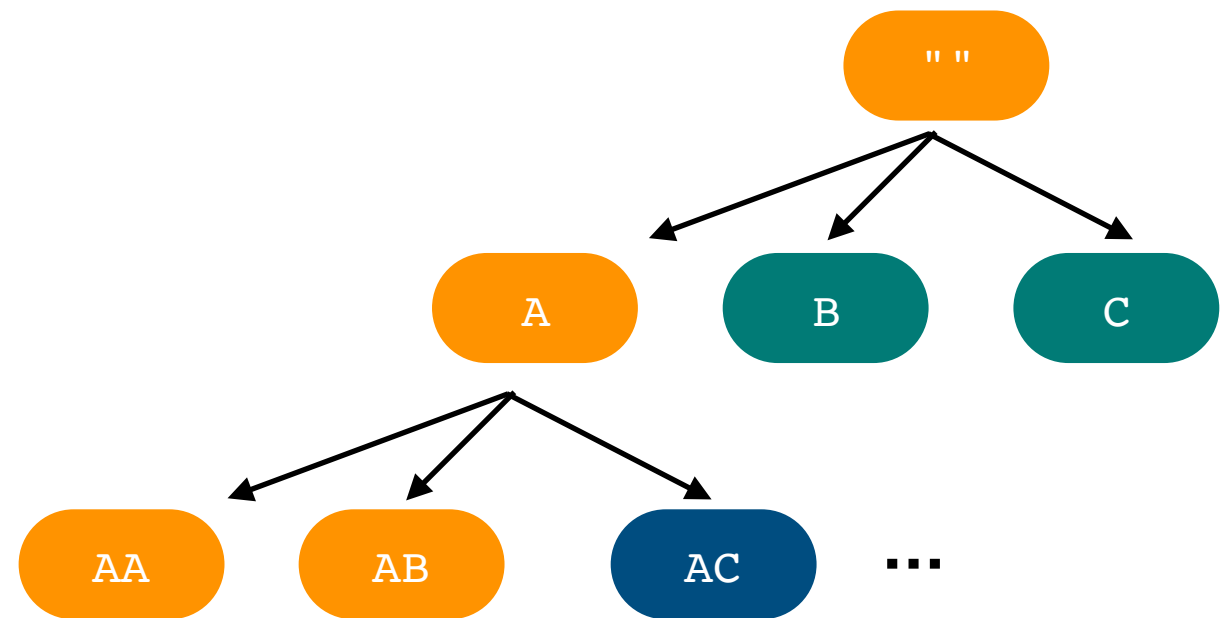
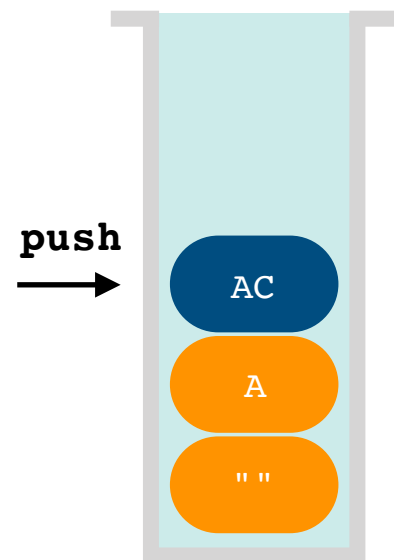
Stack'
Inversed Stack



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 - 深度优先搜索

- 深度优先搜索
 - 深度优先搜索回顾



Tag #Depth-first Search in LeetCode
<https://leetcode.com/tag/depth-first-search/>

- 深度优先搜索
- 深度优先搜索 (1)

LeetCode 863. <All Nodes Distance K in Binary Tree>

<https://leetcode.com/problems/all-nodes-distance-k-in-binary-tree/>

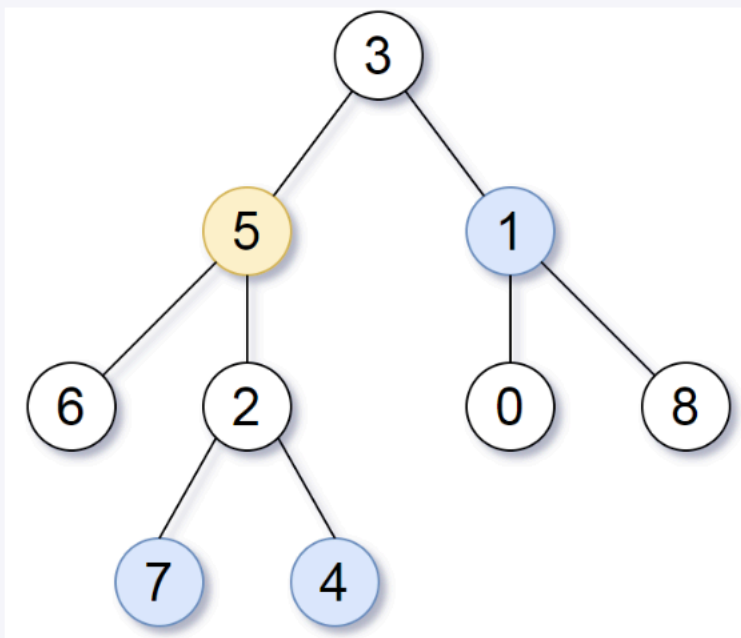
Example 1:

Input: root = [3,5,1,6,2,0,8,null,null,7,4], target = 5, K = 2

Output: [7,4,1]

Explanation:

The nodes that are a distance 2 from the target node (with value 5) have values 7, 4, and 1.



- 深度优先搜索
- 深度优先搜索 (1)

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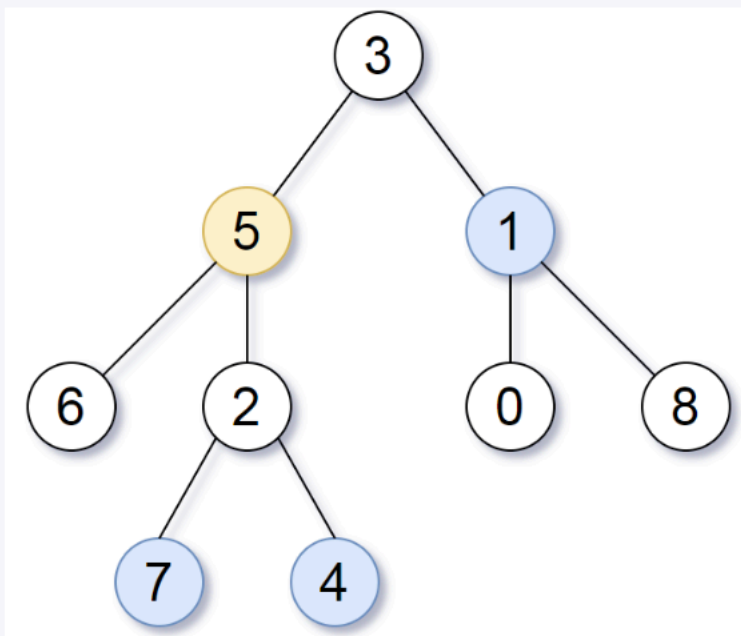
Example 1:

Input: root = [3,5,1,6,2,0,8,null,null,7,4], target = 5, K = 2

用线性表 $t[]$ 存储完全二叉树:

1) $t[0]$ 为 Root

2) 对于 $t[i]$, $t[i*2]$ 为左儿子, $t[i*2]+1$ 为右儿子



- 深度优先搜索
- 深度优先搜索 (1)

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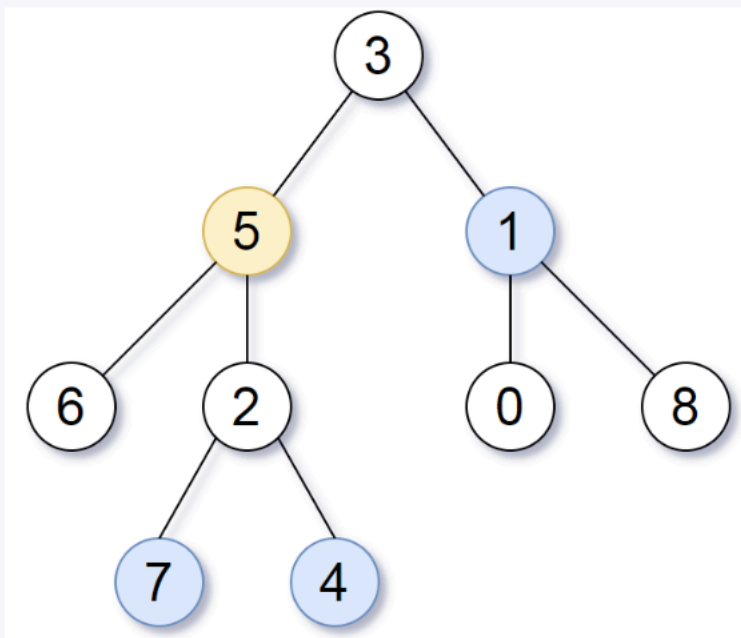
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Output: [7,4,1]

Explanation:

The nodes that are a distance 2 from the target node (with value 5) have values 7, 4, and 1.



思路:

- 1) 从起点开始深度优先遍历二叉树;
- 2) 遍历到深度为 K 的节点时停止遍历;

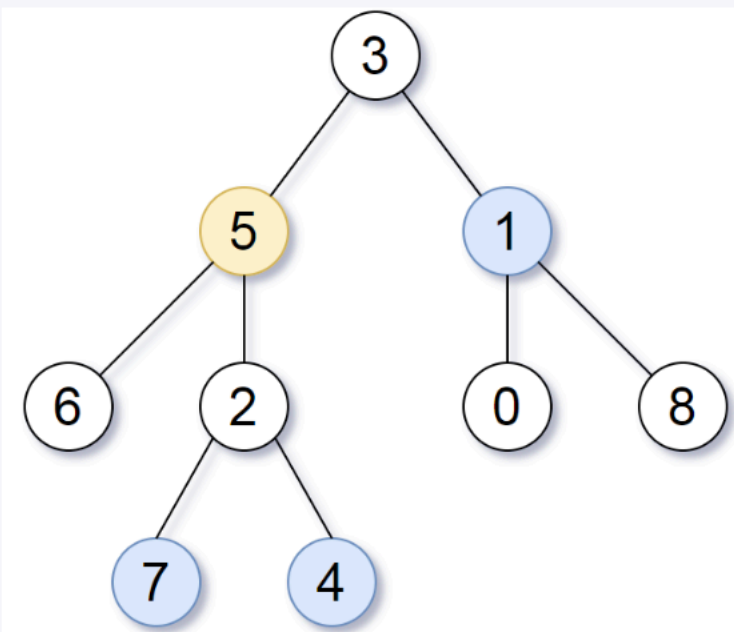
- 深度优先搜索
- 深度优先搜索 (1)

LeetCode 863. <All Nodes Distance K in Binary Tree>

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```
std::vector<int> dfs(const std::vector<int>& tree, int target, int K) {
    std::vector<int> result;
    if (target >= 0 && target < tree.size() && tree[target] >= 0) {
        // 若该节点合法
        if (K == 0) {
            // 若到达遍历深度，则停止遍历，记录当前节点
            result.push_back(target);
        } else {
            // 否则，遍历其父节点和左、右儿子节点，并保存遍历的结果
            std::vector<int> part_parent = dfs(tree, target / 2, K - 1);
            copy(part_parent.begin(), part_parent.end(), std::back_inserter(result));
            std::vector<int> part_left = dfs(tree, target * 2, K - 1);
            copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            std::vector<int> part_right = dfs(tree, target * 2 + 1, K - 1);
            copy(part_right.begin(), part_right.end(), std::back_inserter(result));
        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, K);
}
```



- 深度优先搜索
- 深度优先搜索 (1)

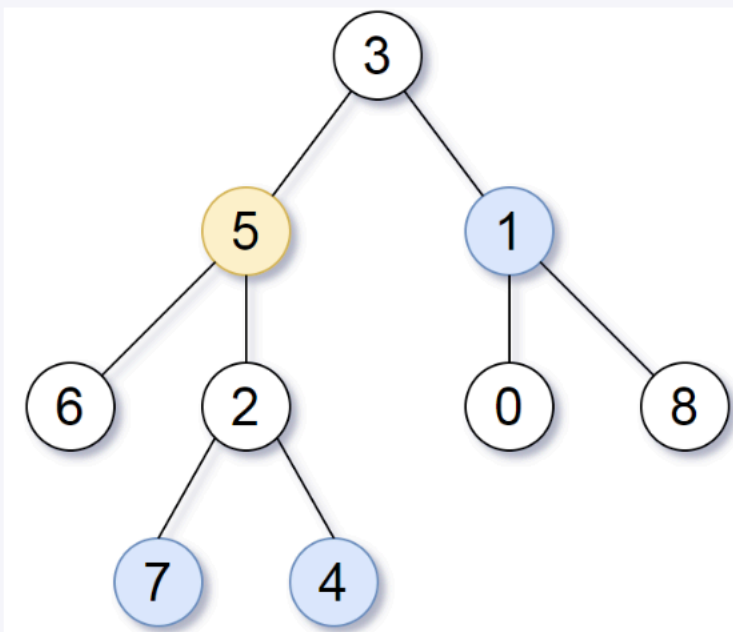
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std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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```

注意：这里我们用 std 实现了一个线性表的合并



- 深度优先搜索
- 深度优先搜索 (1)

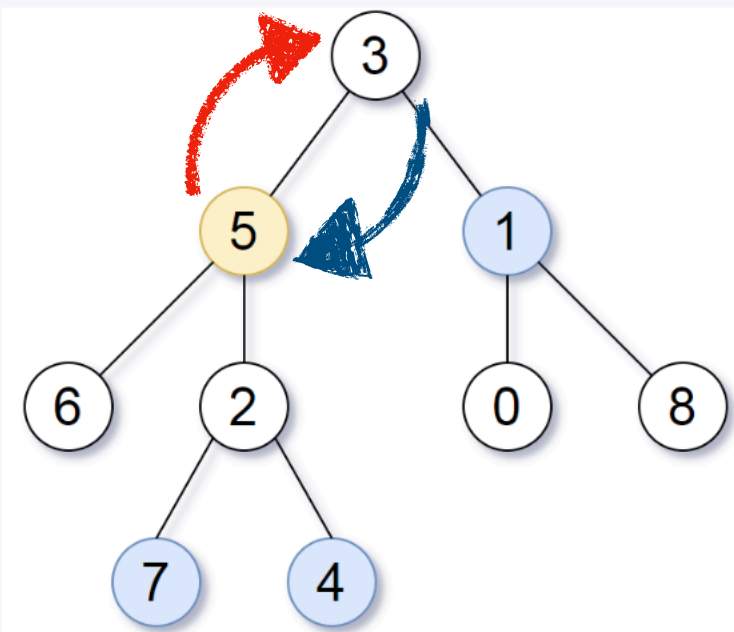
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        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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```

是否存在问题？
遍历存在环，要记录遍历过的节点



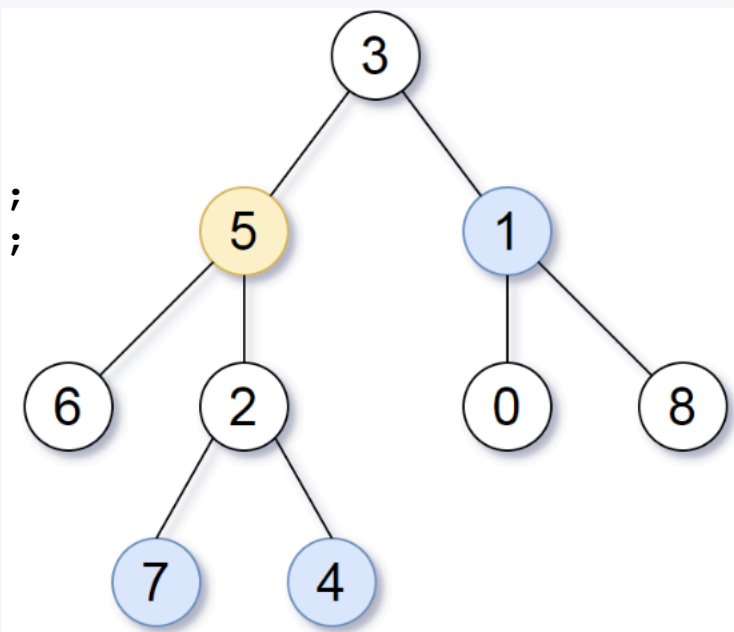
- 深度优先搜索
- 深度优先搜索 (1)

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            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
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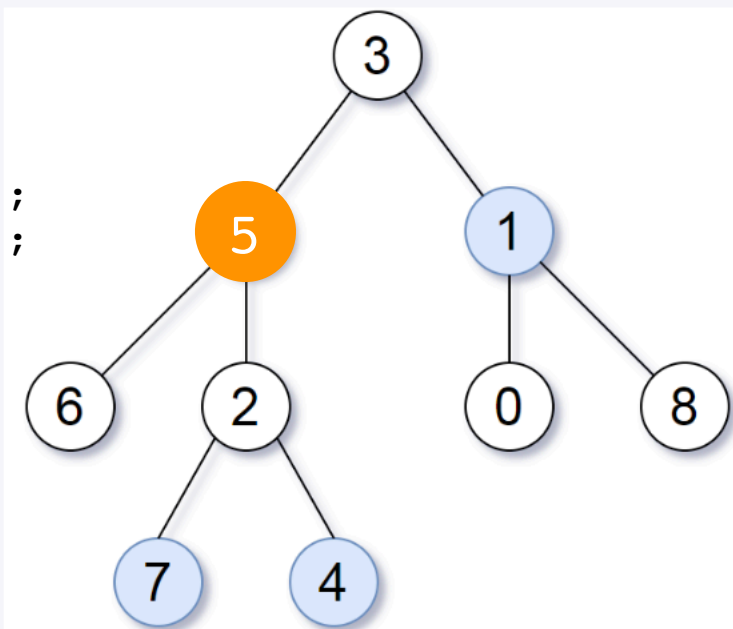
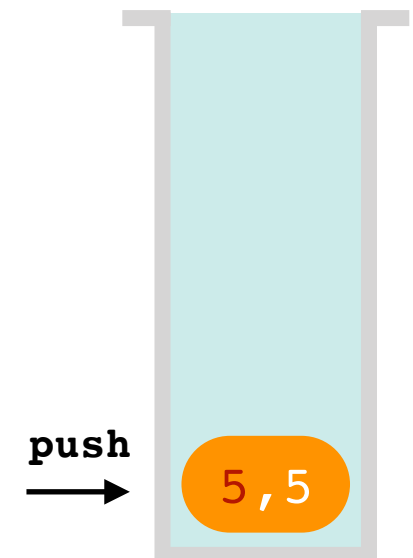


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                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}
```



```
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```

传入一个假的 parent

- 深度优先搜索
- 深度优先搜索 (1)

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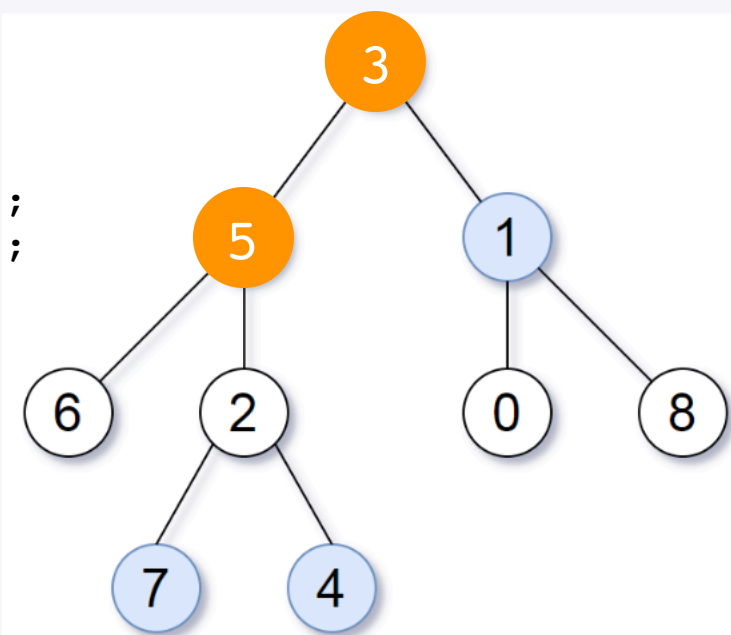
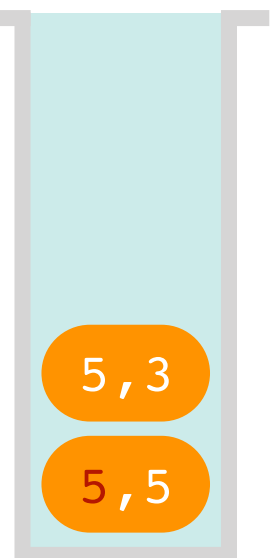
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            }
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                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
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            }
        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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}
```

遍历其父节点

push
→



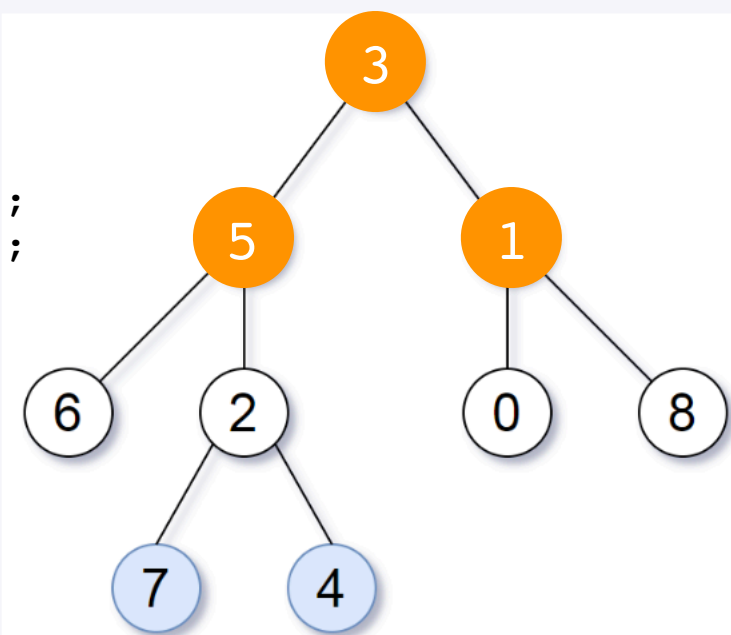
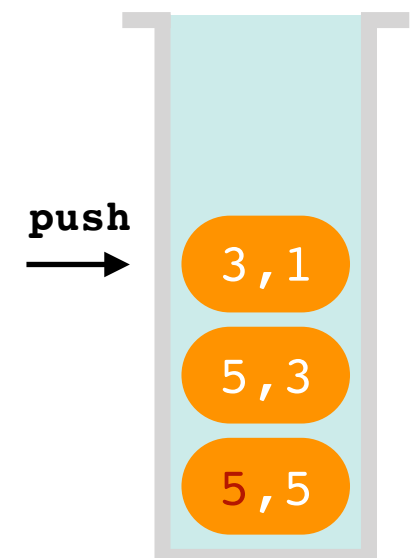
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            }
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                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}
```

其父节点为空，左节点已经遍历过，遍历其右儿子



```
std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```

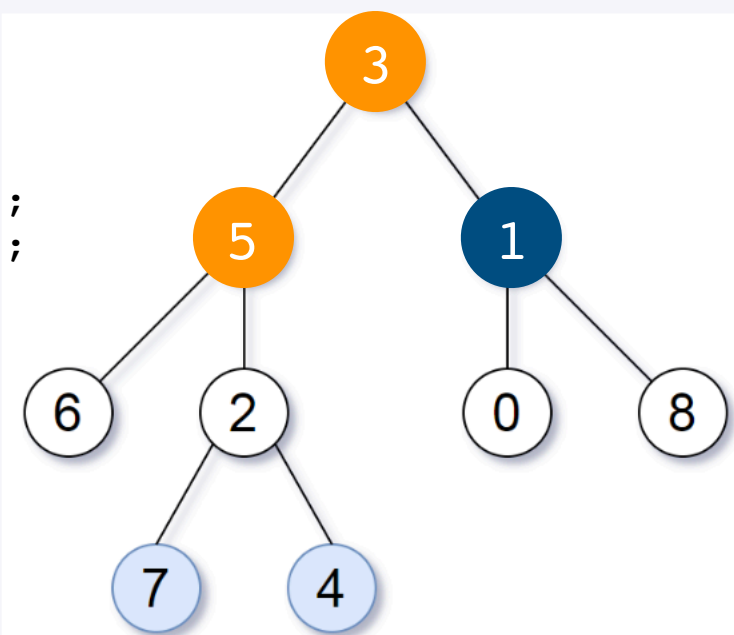
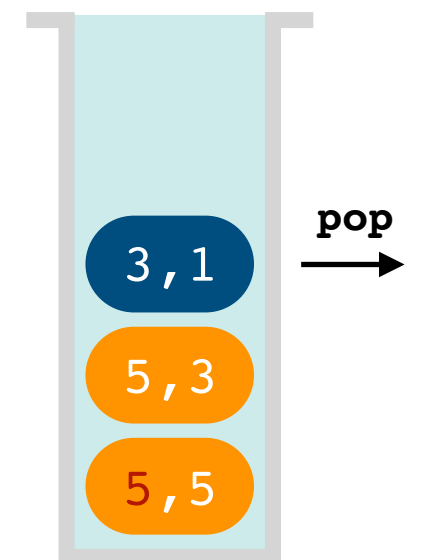
- 深度优先搜索
- 深度优先搜索 (1)

LeetCode 863. <All Nodes Distance K in Binary Tree>

<https://leetcode.com/problems/all-nodes-distance-k-in-binary-tree/>

```
std::vector<int> dfs(const std::vector<int>& tree, int parent, int target, int K) {
    std::vector<int> result;
    if (target >= 0 && target < tree.size() && tree[target] >= 0) {
        // 若该节点合法
        if (K == 0) {
            // 若到达遍历深度，则停止遍历，记录当前节点
            result.push_back(target);
        } else {
            // 否则，遍历其父节点和左、右儿子节点，并保存遍历的结果
            if (target / 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_parent = dfs(tree, target, target / 2, K - 1);
                copy(part_parent.begin(), part_parent.end(), std::back_inserter(result));
            }
            if (target * 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_left = dfs(tree, target, target * 2, K - 1);
                copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```



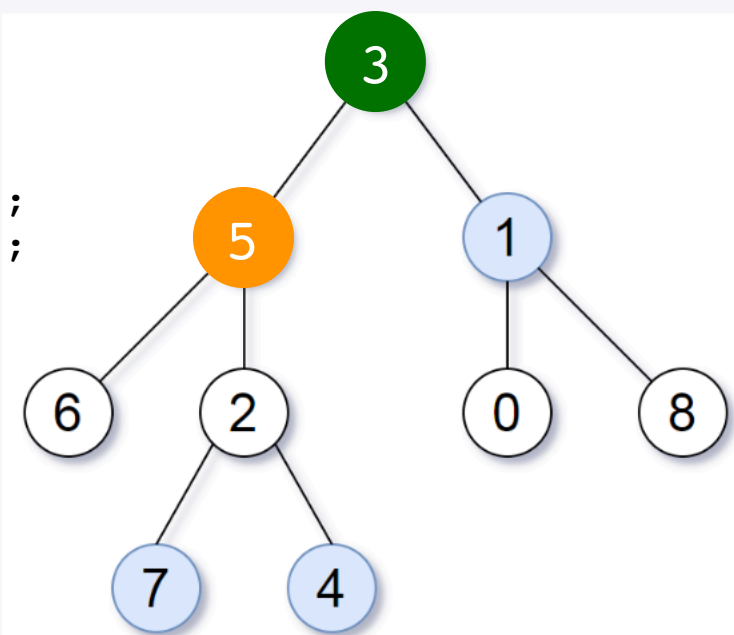
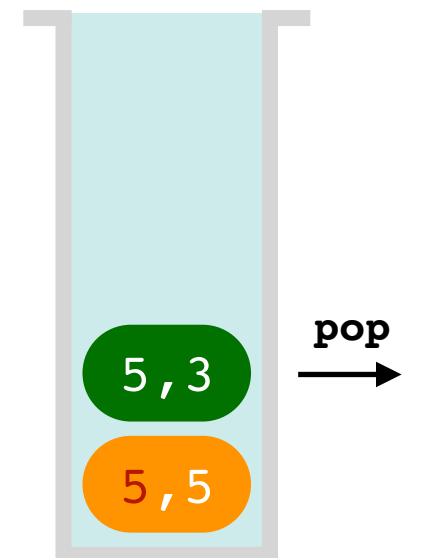
- 深度优先搜索
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                copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
        // 遍历结束
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```

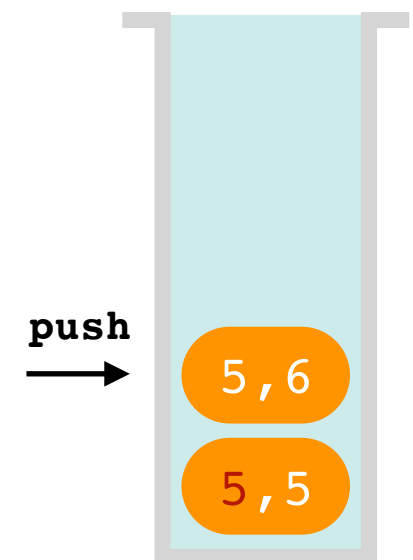


- 深度优先搜索
- 深度优先搜索 (1)

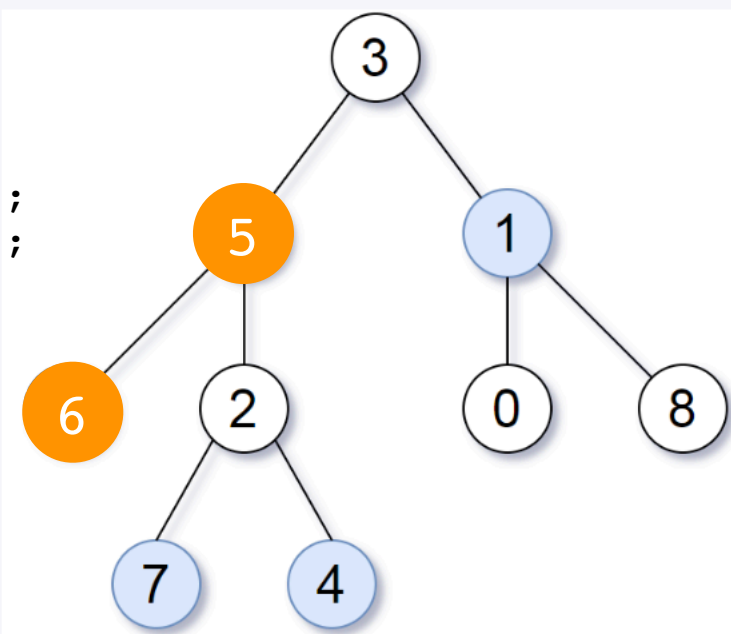
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            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}
```



遍历其左儿子节点



```
std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```

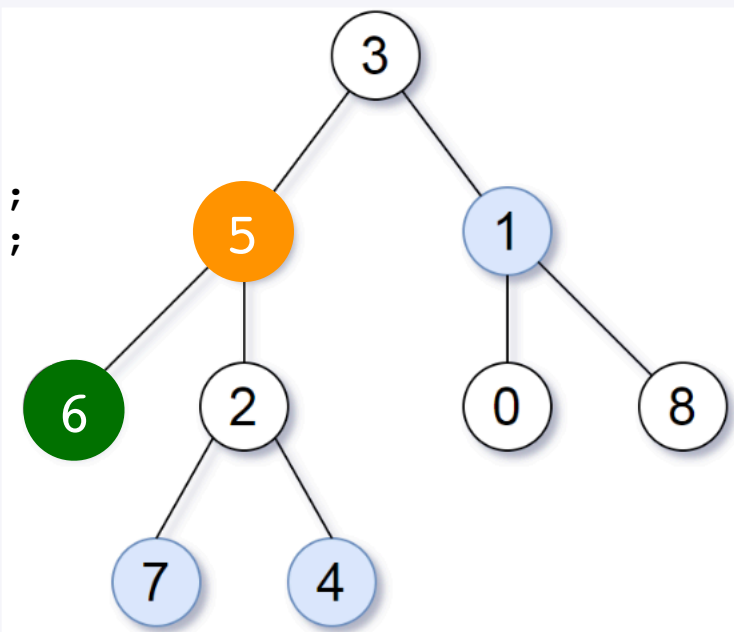
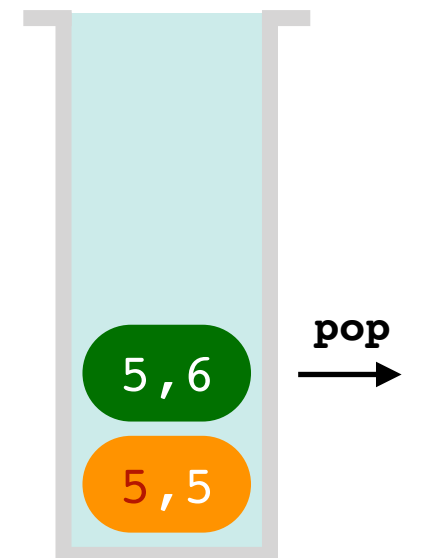
- 深度优先搜索
- 深度优先搜索 (1)

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    std::vector<int> result;
    if (target >= 0 && target < tree.size() && tree[target] >= 0) {
        // 若该节点合法
        if (K == 0) {
            // 若到达遍历深度，则停止遍历，记录当前节点
            result.push_back(target);
        } else {
            // 否则，遍历其父节点和左、右儿子节点，并保存遍历的结果
            if (target / 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_parent = dfs(tree, target, target / 2, K - 1);
                copy(part_parent.begin(), part_parent.end(), std::back_inserter(result));
            }
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                std::vector<int> part_left = dfs(tree, target, target * 2, K - 1);
                copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
        // 遍历结束
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```



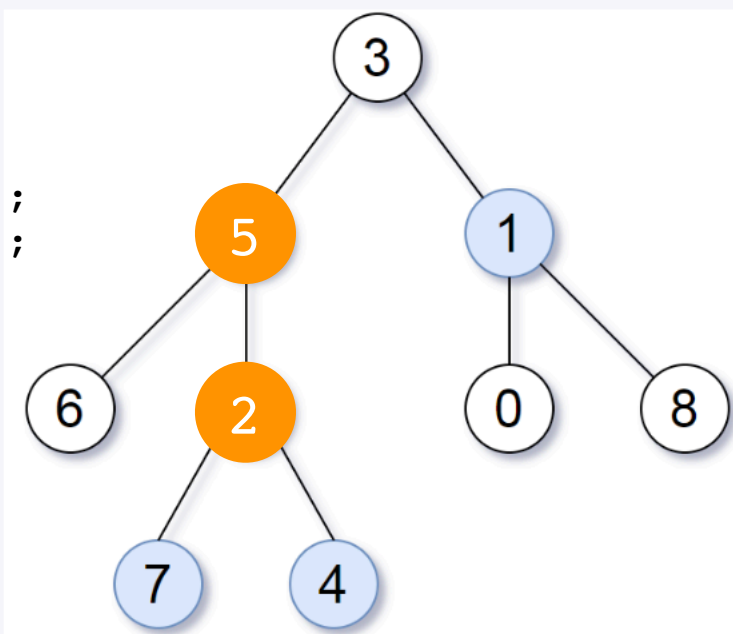
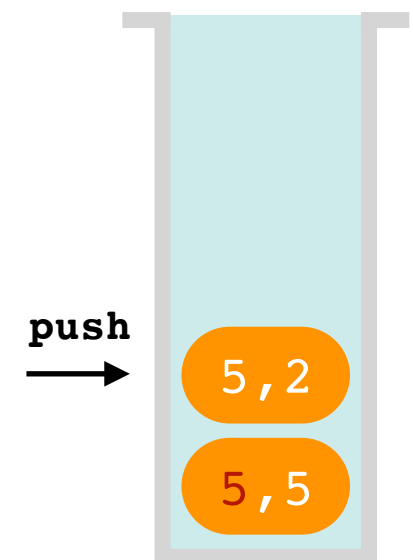
- 深度优先搜索
- 深度优先搜索 (1)

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            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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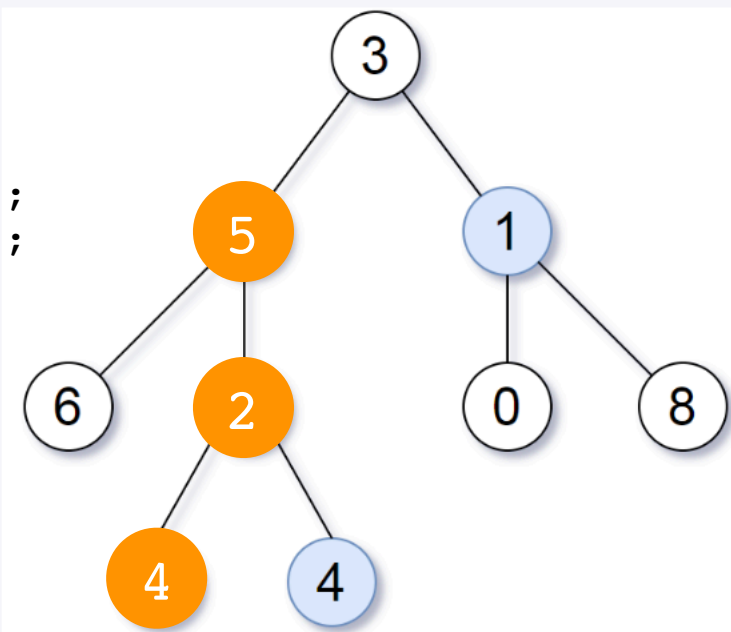
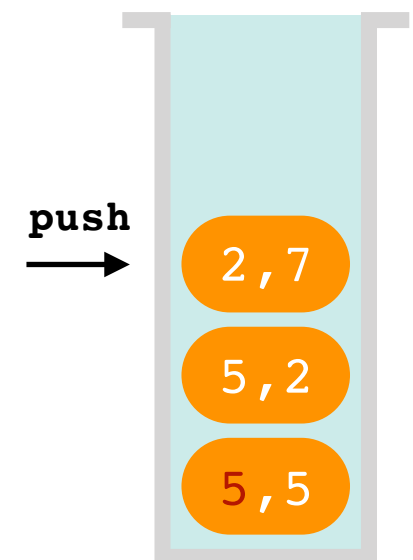
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                copy(part_parent.begin(), part_parent.end(), std::back_inserter(result));
            }
            if (target * 2 != parent) { // 判断目标节点是否已经被遍历过 遍历其左儿子节点
                std::vector<int> part_left = dfs(tree, target, target * 2, K - 1);
                copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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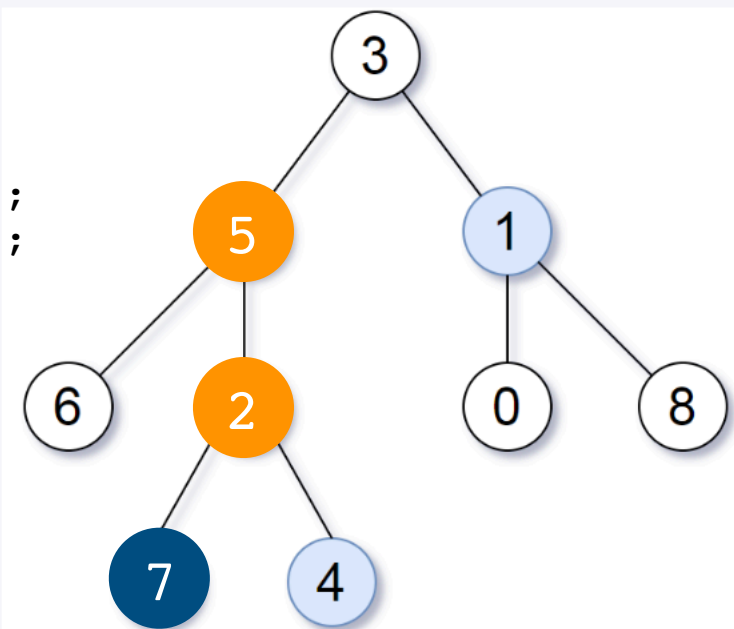
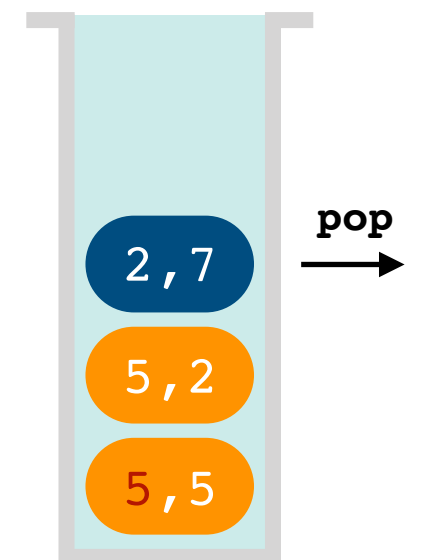
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                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}

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```

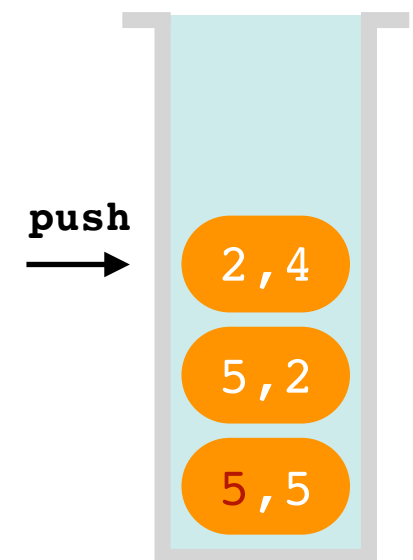


- 深度优先搜索
- 深度优先搜索 (1)

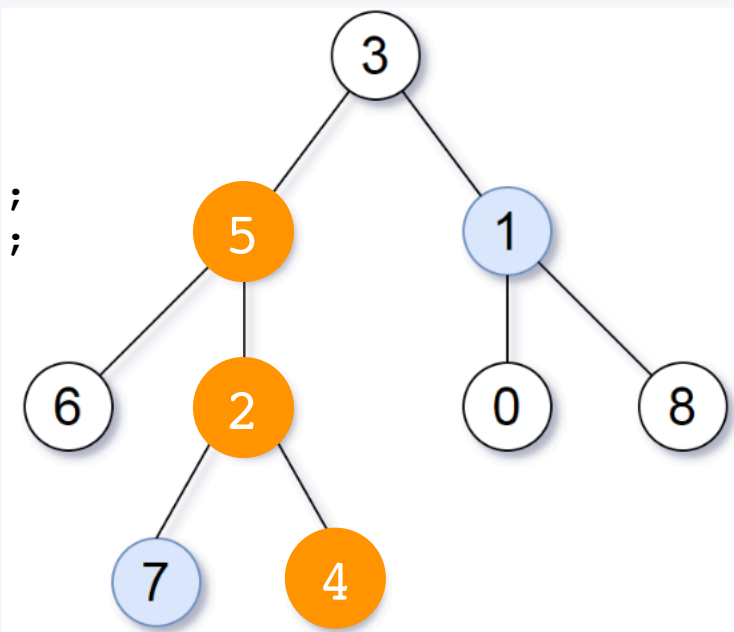
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            }
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                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}
```



遍历其右儿子节点



```
std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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```

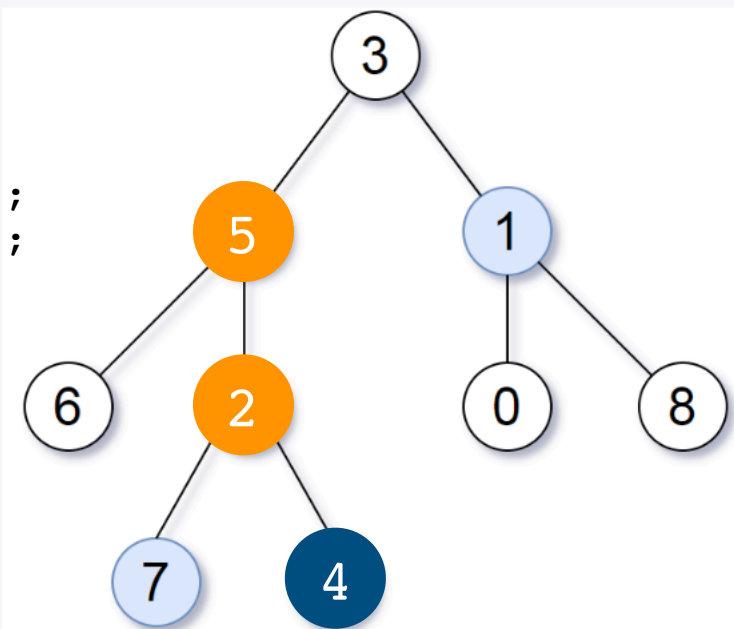
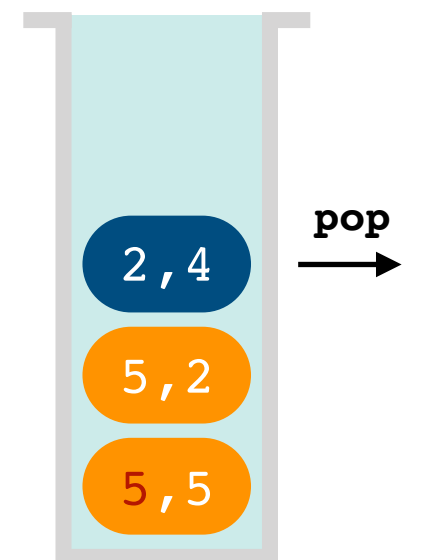
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            }
        }
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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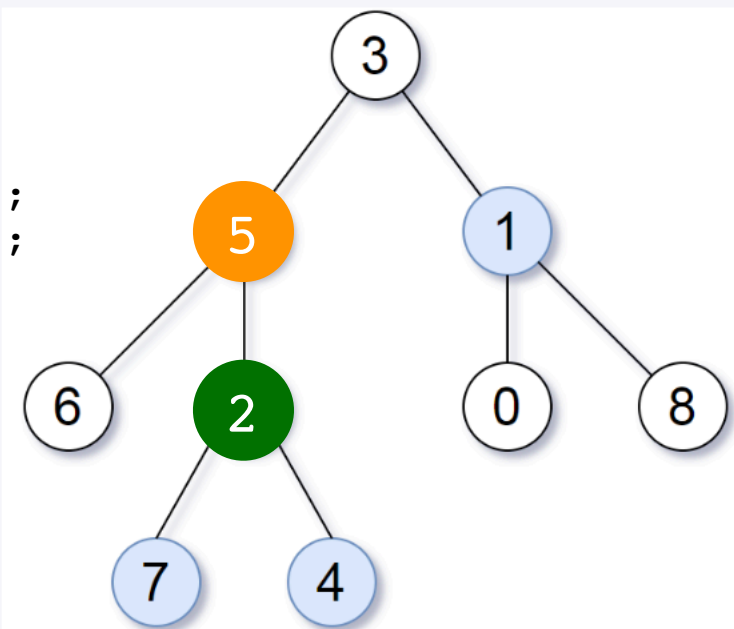
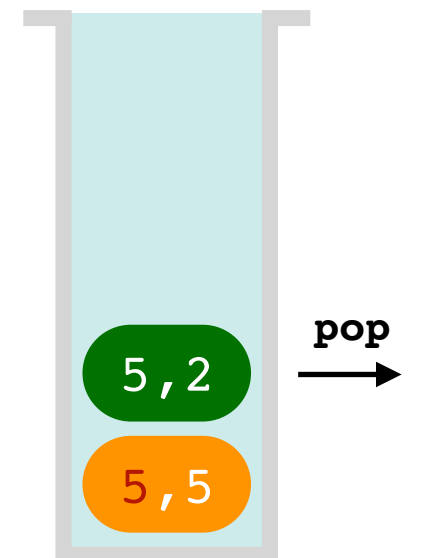
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                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
        // 遍历结束
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
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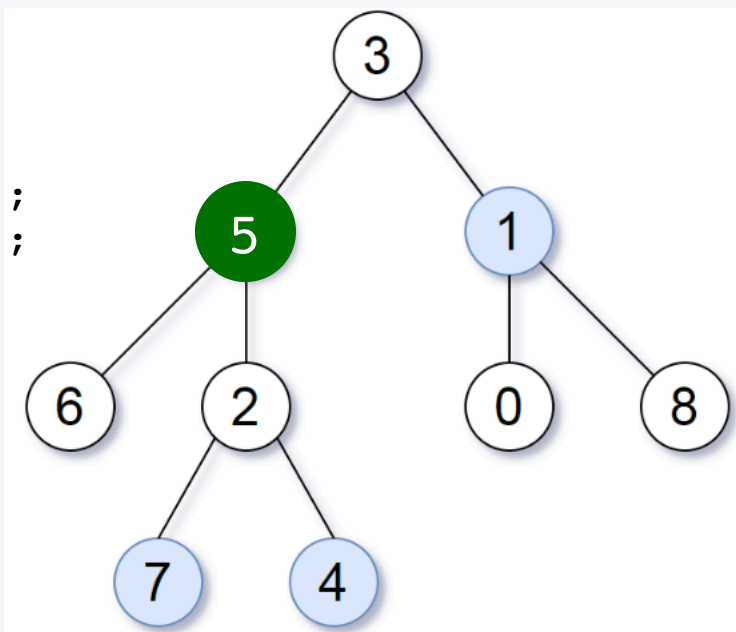
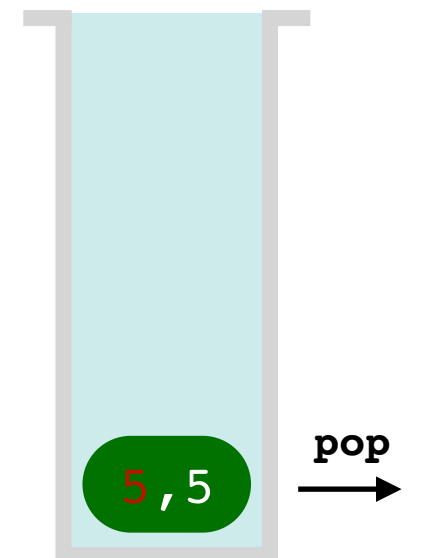
- 深度优先搜索
- 深度优先搜索 (1)

LeetCode 863. <All Nodes Distance K in Binary Tree>

<https://leetcode.com/problems/all-nodes-distance-k-in-binary-tree/>

```
std::vector<int> dfs(const std::vector<int>& tree, int parent, int target, int K) {
    std::vector<int> result;
    if (target >= 0 && target < tree.size() && tree[target] >= 0) {
        // 若该节点合法
        if (K == 0) {
            // 若到达遍历深度，则停止遍历，记录当前节点
            result.push_back(target);
        } else {
            // 否则，遍历其父节点和左、右儿子节点，并保存遍历的结果
            if (target / 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_parent = dfs(tree, target, target / 2, K - 1);
                copy(part_parent.begin(), part_parent.end(), std::back_inserter(result));
            }
            if (target * 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_left = dfs(tree, target, target * 2, K - 1);
                copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
        // 遍历结束
    }
    return std::move(result);
}

std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```

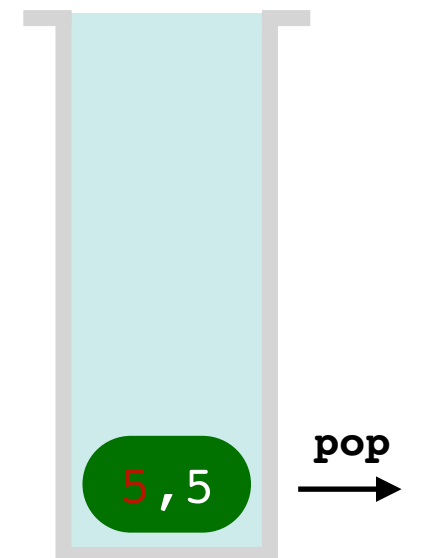


- 深度优先搜索
- 深度优先搜索 (1)

LeetCode 863. <All Nodes Distance K in Binary Tree>

<https://leetcode.com/problems/all-nodes-distance-k-in-binary-tree/>

```
std::vector<int> dfs(const std::vector<int>& tree, int parent, int target, int K) {
    std::vector<int> result;
    if (target >= 0 && target < tree.size() && tree[target] >= 0) {
        // 若该节点合法
        if (K == 0) {
            // 若到达遍历深度，则停止遍历，记录当前节点
            result.push_back(target);
        } else {
            // 否则，遍历其父节点和左、右儿子节点，并保存遍历的结果
            if (target / 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_parent = dfs(tree, target, target / 2, K - 1);
                copy(part_parent.begin(), part_parent.end(), std::back_inserter(result));
            }
            if (target * 2 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_left = dfs(tree, target, target * 2, K - 1);
                copy(part_left.begin(), part_left.end(), std::back_inserter(result));
            }
            if (target * 2 + 1 != parent) { // 判断目标节点是否已经被遍历过
                std::vector<int> part_right = dfs(tree, target, target * 2 + 1, K - 1);
                copy(part_right.begin(), part_right.end(), std::back_inserter(result));
            }
        }
    }
    return std::move(result);
}
```



总结：

- 1) 完全二叉树的线性表表示；
- 2) 深度优先遍历“树”结构；
- 3) 在函数栈中，记录深度信息 (K) 和父节点信息；

```
std::vector<int> distanceK(const std::vector<int>& tree, int target, int K) {
    return dfs(tree, target, target, K);
}
```

- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

Example 1:

```
    2
   / \
  1   3
```

Input: [2,1,3]

Output: true

Example 2:

```
    5
   / \
  1   4
     / \
    3   6
```

Input: [5,1,4,null,null,3,6]

Output: false

Explanation: The root node's value is 5 but its right child's value is 4.

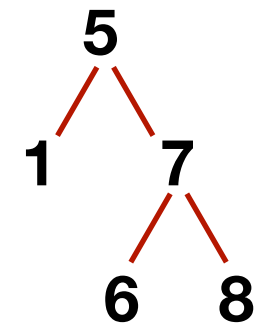
- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

思路一：

- 1) 递归访问二叉树；
- 2) 对于每个节点，判断其左儿子是否小于该节点；
- 3) 对于每个节点，判断其右儿子是否大于该节点；



[5, 1, 7, N, N, 6, 8]

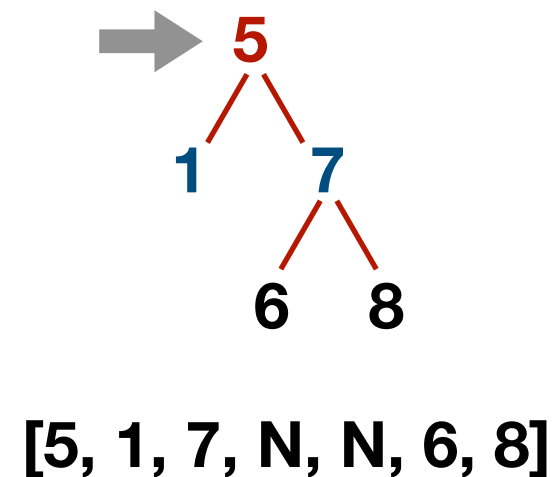
- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

思路一：

- 1) 递归访问二叉树；
- 2) 对于每个节点，判断其左儿子是否小于该节点；
- 3) 对于每个节点，判断其右儿子是否大于该节点；



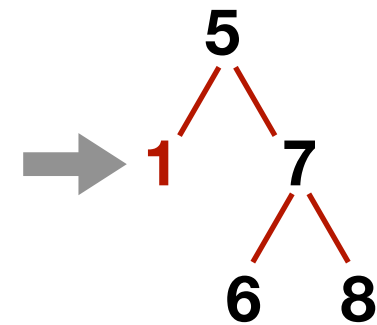
- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

思路一：

- 1) 递归访问二叉树；
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- 3) 对于每个节点，判断其右儿子是否大于该节点；



[5, 1, 7, N, N, 6, 8]

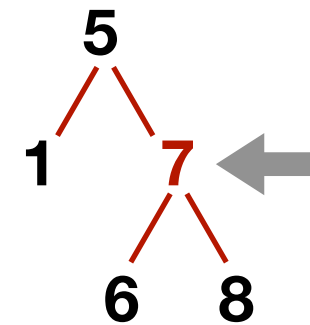
- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

思路一：

- 1) 递归访问二叉树；
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- 3) 对于每个节点，判断其右儿子是否大于该节点；



[5, 1, 7, N, N, 6, 8]

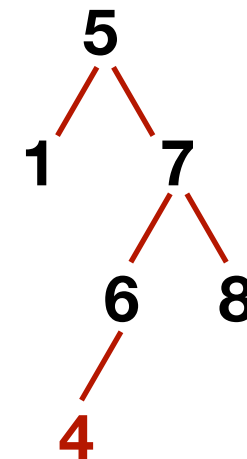
- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

思路一：

- 1) 递归访问二叉树；
- 2) 对于每个节点，判断其左儿子是否小于该节点；
- 3) 对于每个节点，判断其右儿子是否大于该节点；



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]

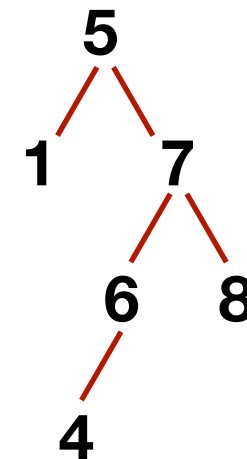
- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

思路二：

- 1) 递归访问二叉树；
- 2) 对于每个节点，若其左儿子存在，则先遍历左儿子；否则，遍历该节点；最后，若其右儿子存在，则先遍历右儿子；
- 3) 判断依次遍历的节点是否递增。



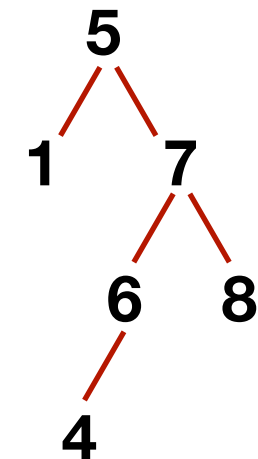
[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]

- 深度优先搜索
- 深度优先搜索 (2)

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

```
bool isValidBST(const std::vector<int>& tree, int root, int* prev_min) {  
    if (root < tree.size() && tree[root] < 0) { // tree[root] is NULL  
        return true;  
    }  
    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值  
    if (!isValidBST(tree, root * 2, prev_min)) {  
        return false;  
    }  
    // 判断该节点的值是否超过左测的最大值  
    if (tree[root] > *prev_min) {  
        *prev_min = tree[root];  
    } else {  
        return false;  
    }  
    // 遍历右儿子, 若该节点右儿子存在, 则判断其右测子树是否为 BST, 并返回右测最大值  
    if (!isValidBST(tree, root * 2 + 1, prev_min)) {  
        return false;  
    }  
    return true;  
}
```



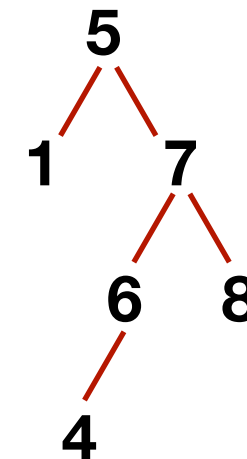
[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]

- 深度优先搜索
- 深度优先搜索 (2)

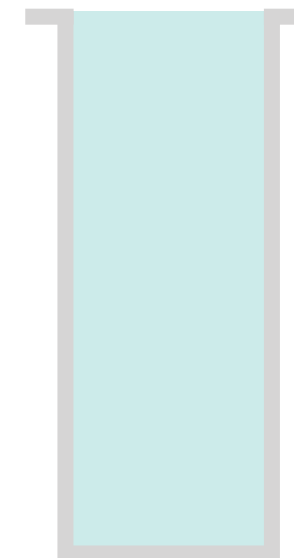
LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

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bool isValidBST(const std::vector<int>& tree, int root, int* prev_min) {
    if (root < tree.size() && tree[root] < 0) { // tree[root] is NULL
        return true;
    }
    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值
    if (!isValidBST(tree, root * 2, prev_min)) {
        return false;
    }
    // 判断该节点的值是否超过左测的最大值
    if (tree[root] > *prev_min) {
        *prev_min = tree[root];
    } else {
        return false;
    }
    // 遍历右儿子, 若该节点右儿子存在, 则判断其右测子树是否为 BST, 并返回右测最大值
    if (!isValidBST(tree, root * 2 + 1, prev_min)) {
        return false;
    }
    return true;
}
```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



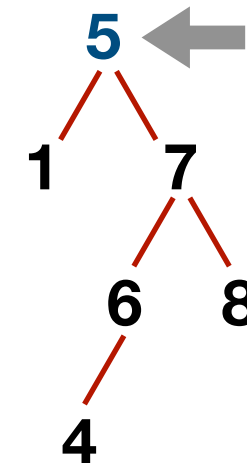
prev_min = LONG_MIN

- 深度优先搜索
- 深度优先搜索 (2)

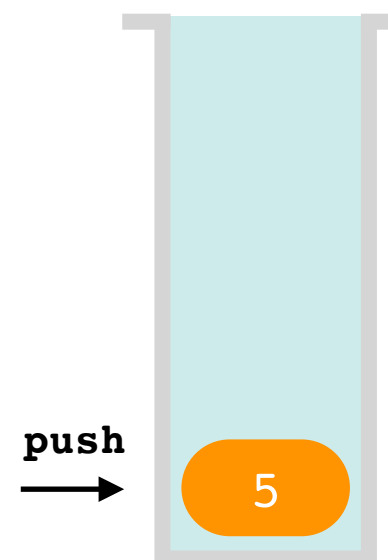
LeetCode 98. <Validate Binary Search Tree>

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        return true;
    }
    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值
    if (!isValidBST(tree, root * 2, prev_min)) {
        return false;
    }
    // 判断该节点的值是否超过左测的最大值
    if (tree[root] > *prev_min) {
        *prev_min = tree[root];
    } else {
        return false;
    }
    // 遍历右儿子, 若该节点右儿子存在, 则判断其右测子树是否为 BST, 并返回右测最大值
    if (!isValidBST(tree, root * 2 + 1, prev_min)) {
        return false;
    }
    return true;
}
```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



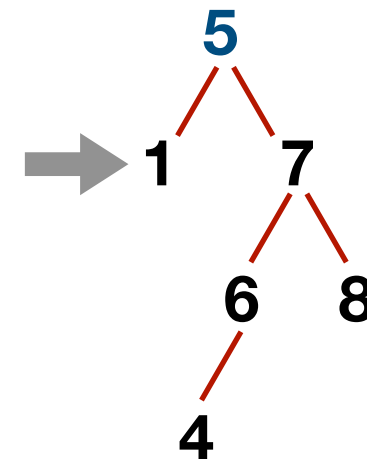
prev_min = LONG_MIN

- 深度优先搜索
- 深度优先搜索 (2)

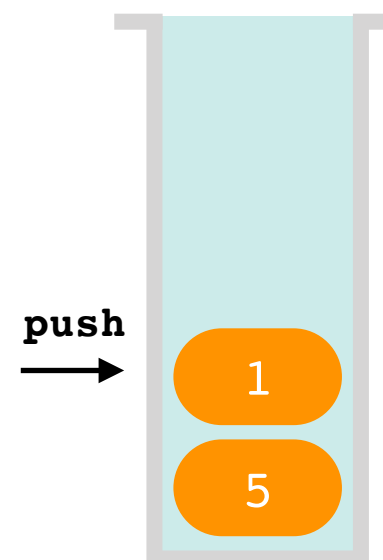
LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

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    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值
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        return false;
    }
    // 判断该节点的值是否超过左测的最大值
    if (tree[root] > *prev_min) {
        *prev_min = tree[root];
    } else {
        return false;
    }
    // 遍历右儿子, 若该节点右儿子存在, 则判断其右测子树是否为 BST, 并返回右测最大值
    if (!isValidBST(tree, root * 2 + 1, prev_min)) {
        return false;
    }
    return true;
}
```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



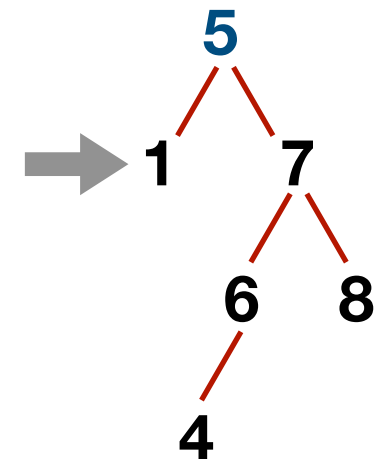
prev_min = LONG_MIN

- 深度优先搜索
- 深度优先搜索 (2)

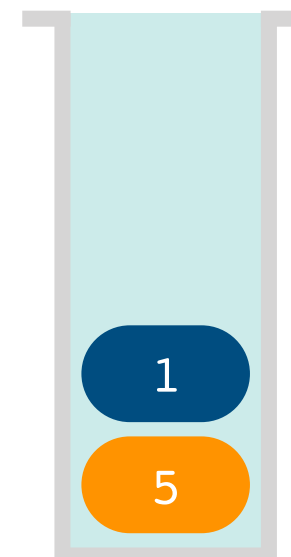
LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

```
bool isValidBST(const std::vector<int>& tree, int root, int* prev_min) {
    if (root < tree.size() && tree[root] < 0) { // tree[root] is NULL
        return true;
    }
    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值
    if (!isValidBST(tree, root * 2, prev_min)) {
        return false;
    }
    // 判断该节点的值是否超过左测的最大值
    if (tree[root] > *prev_min) {
        *prev_min = tree[root];
    } else {
        return false;
    }
    // 遍历右儿子, 若该节点右儿子存在, 则判断其右测子树是否为 BST, 并返回右测最大值
    if (!isValidBST(tree, root * 2 + 1, prev_min)) {
        return false;
    }
    return true;
}
```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



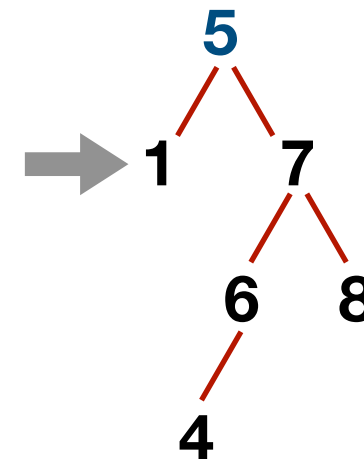
prev_min = 1

- 深度优先搜索
- 深度优先搜索 (2)

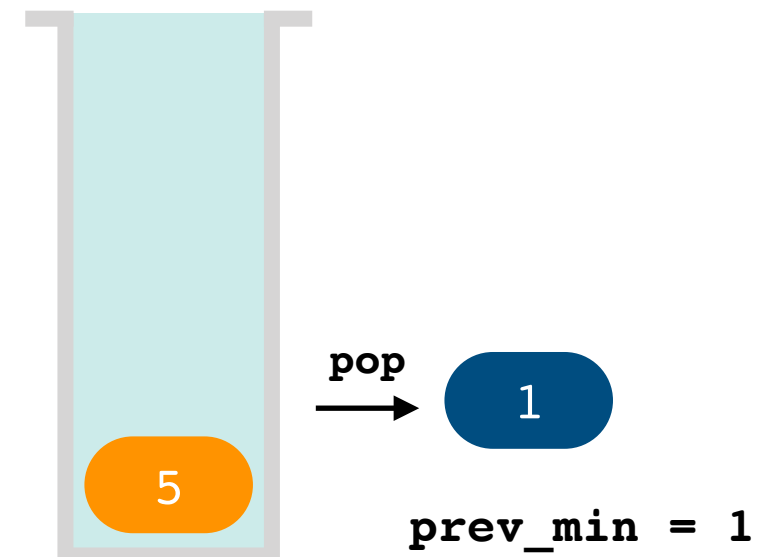
LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

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    if (root < tree.size() && tree[root] < 0) { // tree[root] is NULL
        return true;
    }
    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值
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        return false;
    }
    // 判断该节点的值是否超过左测的最大值
    if (tree[root] > *prev_min) {
        *prev_min = tree[root];
    } else {
        return false;
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        return false;
    }
    return true;
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```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]

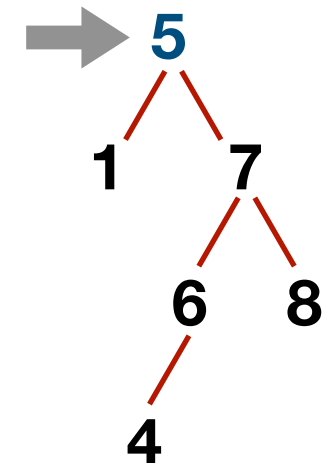


- 深度优先搜索
- 深度优先搜索 (2)

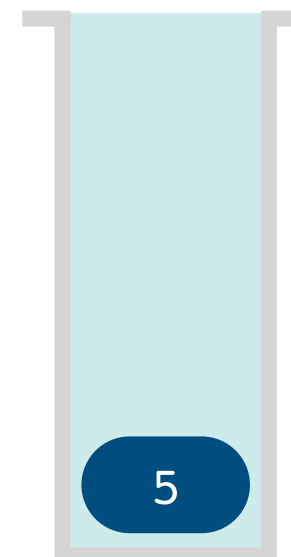
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    }
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    } else {
        return false;
    }
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    if (!isValidBST(tree, root * 2 + 1, prev_min)) {
        return false;
    }
    return true;
}
```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



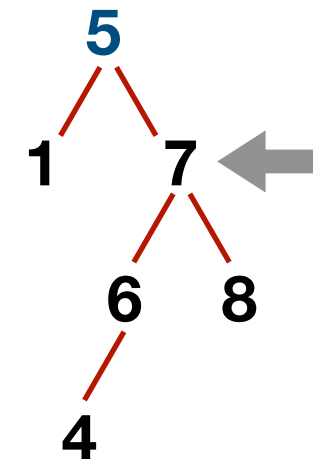
prev_min = 5

- 深度优先搜索
- 深度优先搜索 (2)

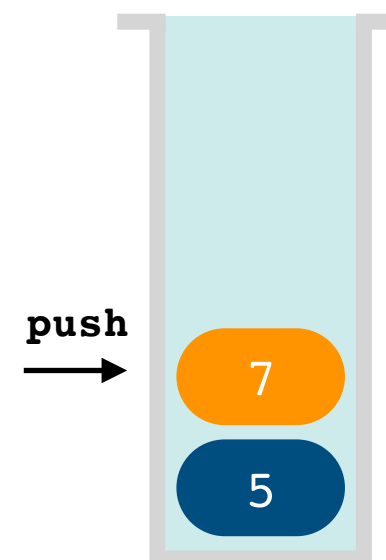
LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

```
bool isValidBST(const std::vector<int>& tree, int root, int* prev_min) {
    if (root < tree.size() && tree[root] < 0) { // tree[root] is NULL
        return true;
    }
    // 遍历左儿子, 若该节点左儿子存在, 则判断其左测子树是否为 BST, 并返回左测最大值
    if (!isValidBST(tree, root * 2, prev_min)) {
        return false;
    }
    // 判断该节点的值是否超过左测的最大值
    if (tree[root] > *prev_min) {
        *prev_min = tree[root];
    } else {
        return false;
    }
    // 遍历右儿子, 若该节点右儿子存在, 则判断其右测子树是否为 BST, 并返回右测最大值
    if (!isValidBST(tree, root * 2 + 1, prev_min)) {
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    }
    return true;
}
```



[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



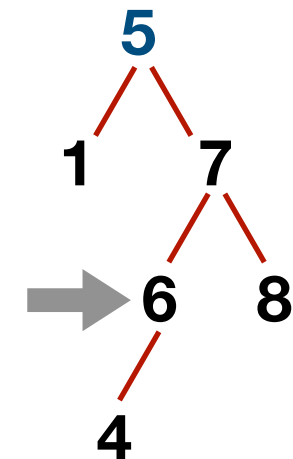
prev_min = 5

- 深度优先搜索
- 深度优先搜索 (2)

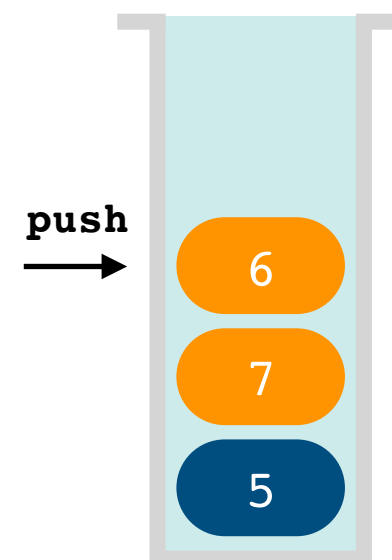
LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

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bool isValidBST(const std::vector<int>& tree, int root, int* prev_min) {
    if (root < tree.size() && tree[root] < 0) { // tree[root] is NULL
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[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



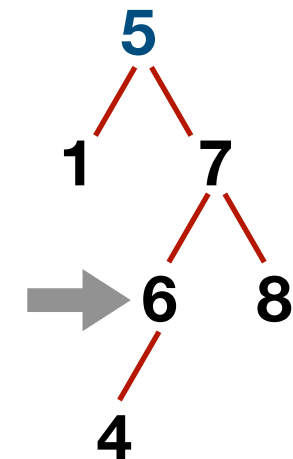
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- 深度优先搜索
- 深度优先搜索 (2)

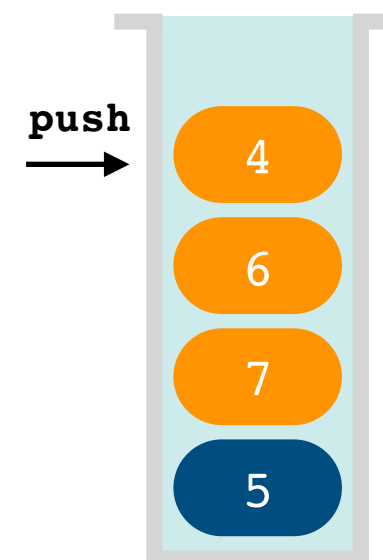
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[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



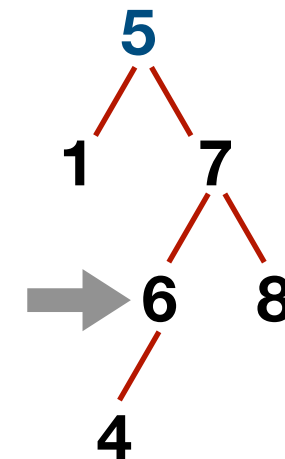
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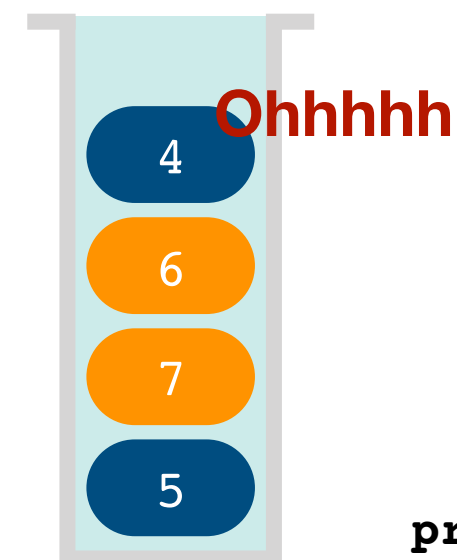
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[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]



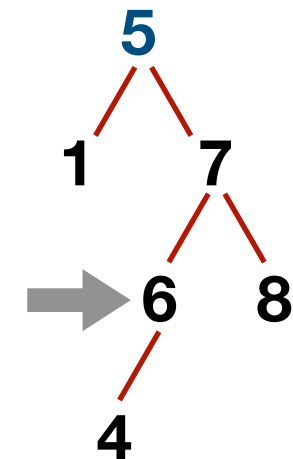
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[5, 1, 7, N, N, 6, 8, N, N, N, N, 4, N, N, N]

总结:

- 1) 理解 二叉排序树 的性质;
- 2) 理解二叉树的先序遍历;

扩展练习

LeetCode 863. <All Nodes Distance K in Binary Tree>

<https://leetcode.com/problems/all-nodes-distance-k-in-binary-tree/>

LeetCode 98. <Validate Binary Search Tree>

<https://leetcode.com/problems/validate-binary-search-tree/>

LeetCode 127. <Word Ladder>

<https://leetcode.com/problems/word-ladder/>