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## 4.2 DIRECTED GRAPHS

---

- ▶ *introduction*
- ▶ *digraph API*
- ▶ *digraph search*
- ▶ *topological sort*
- ▶ *strong components*



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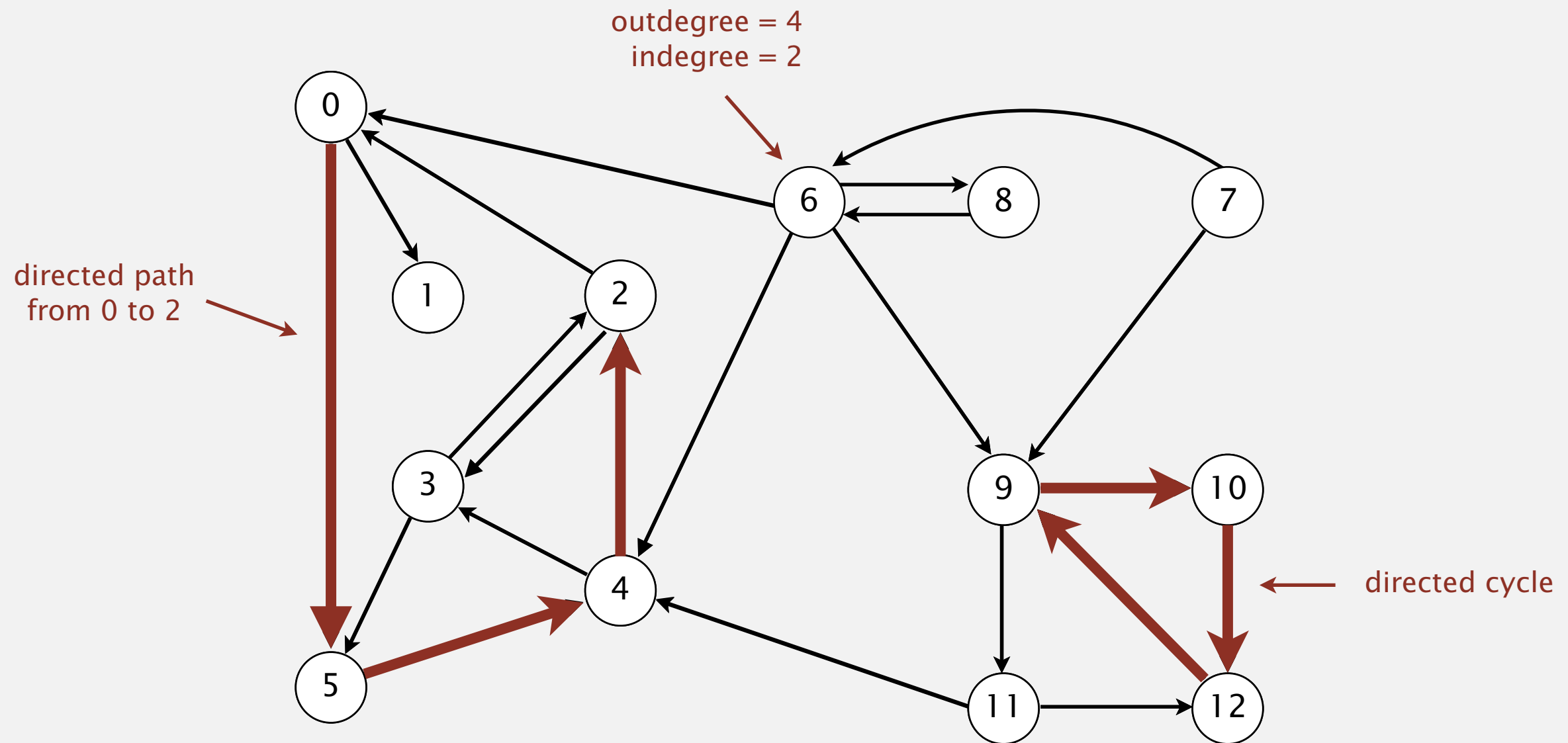
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# Directed graphs

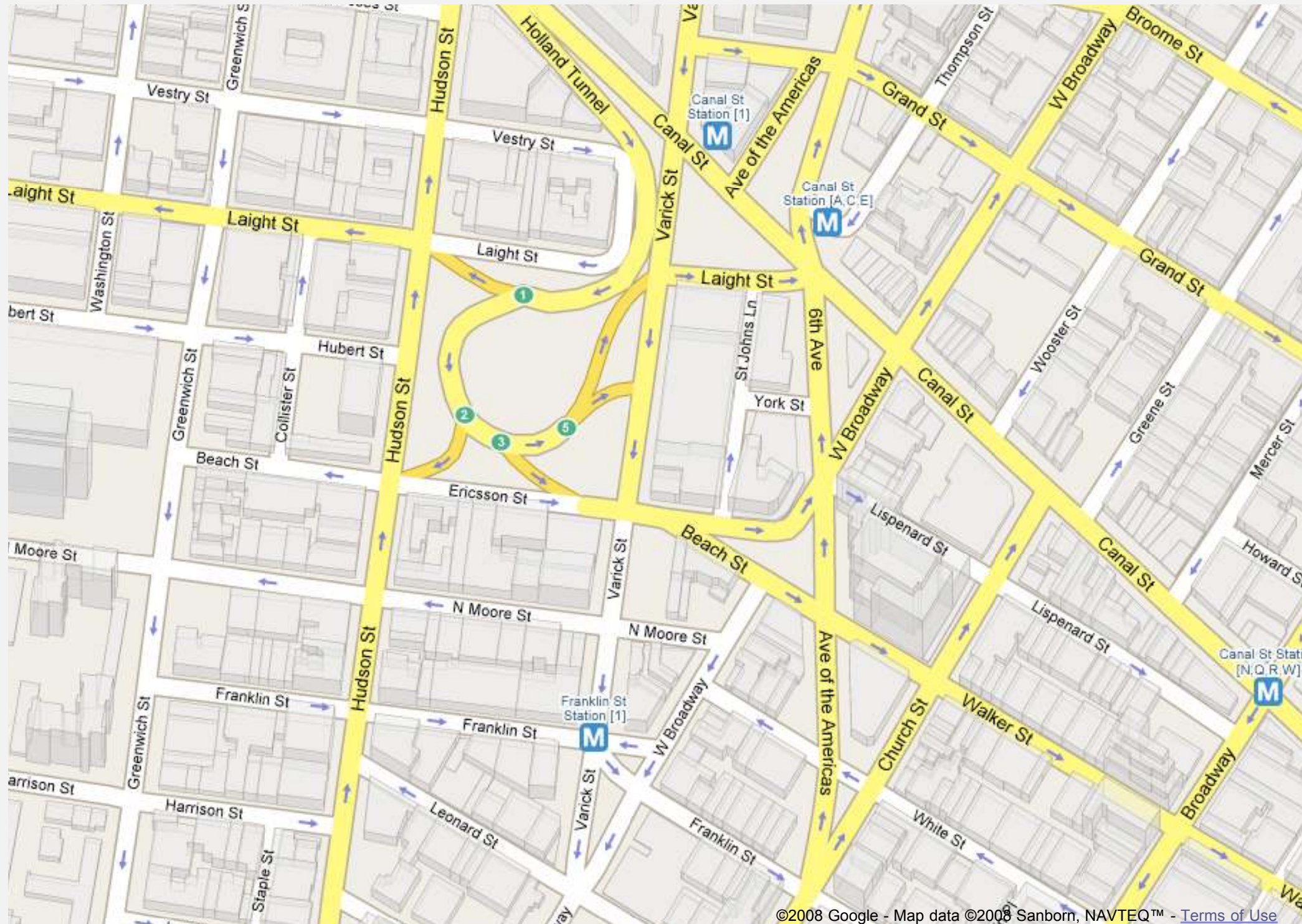
**Digraph.** Set of vertices connected pairwise by **directed** edges.





# Road network

Vertex = intersection; edge = one-way street.

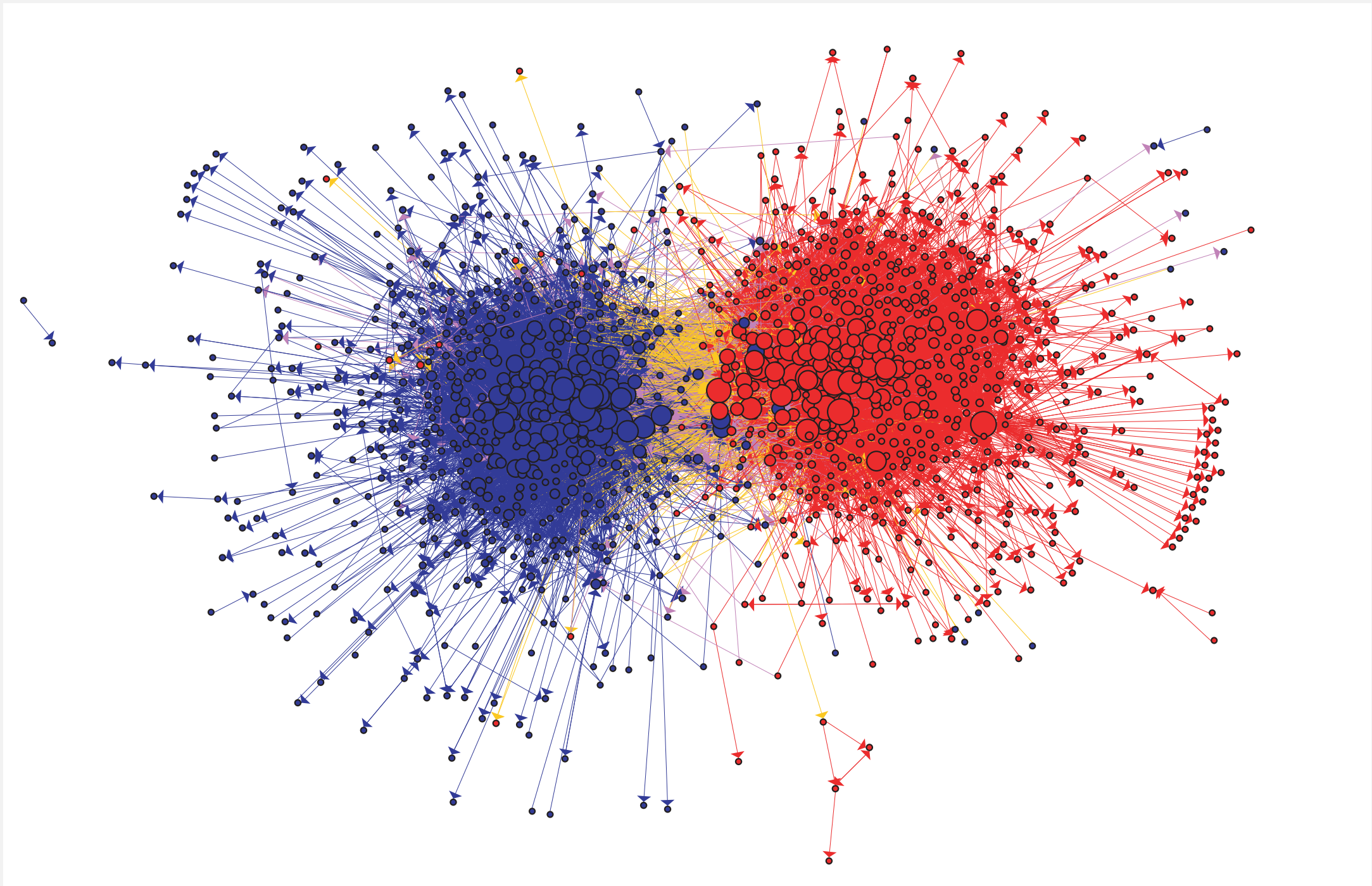




# Political blogosphere graph

---

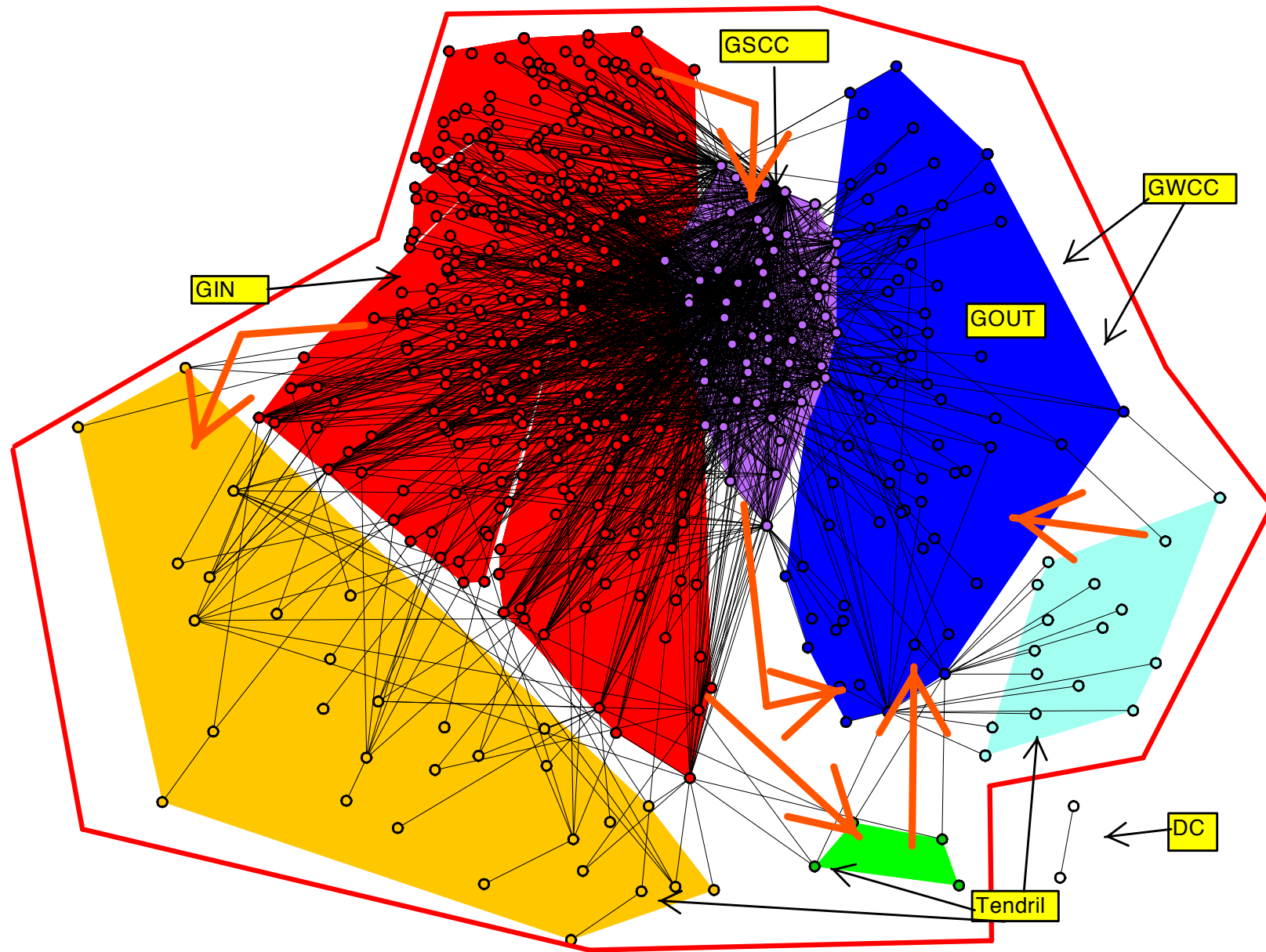
Vertex = political blog; edge = link.



**The Political Blogosphere and the 2004 U.S. Election: Divided They Blog, Adamic and Glance, 2005**

# Overnight interbank loan graph

Vertex = bank; edge = overnight loan.

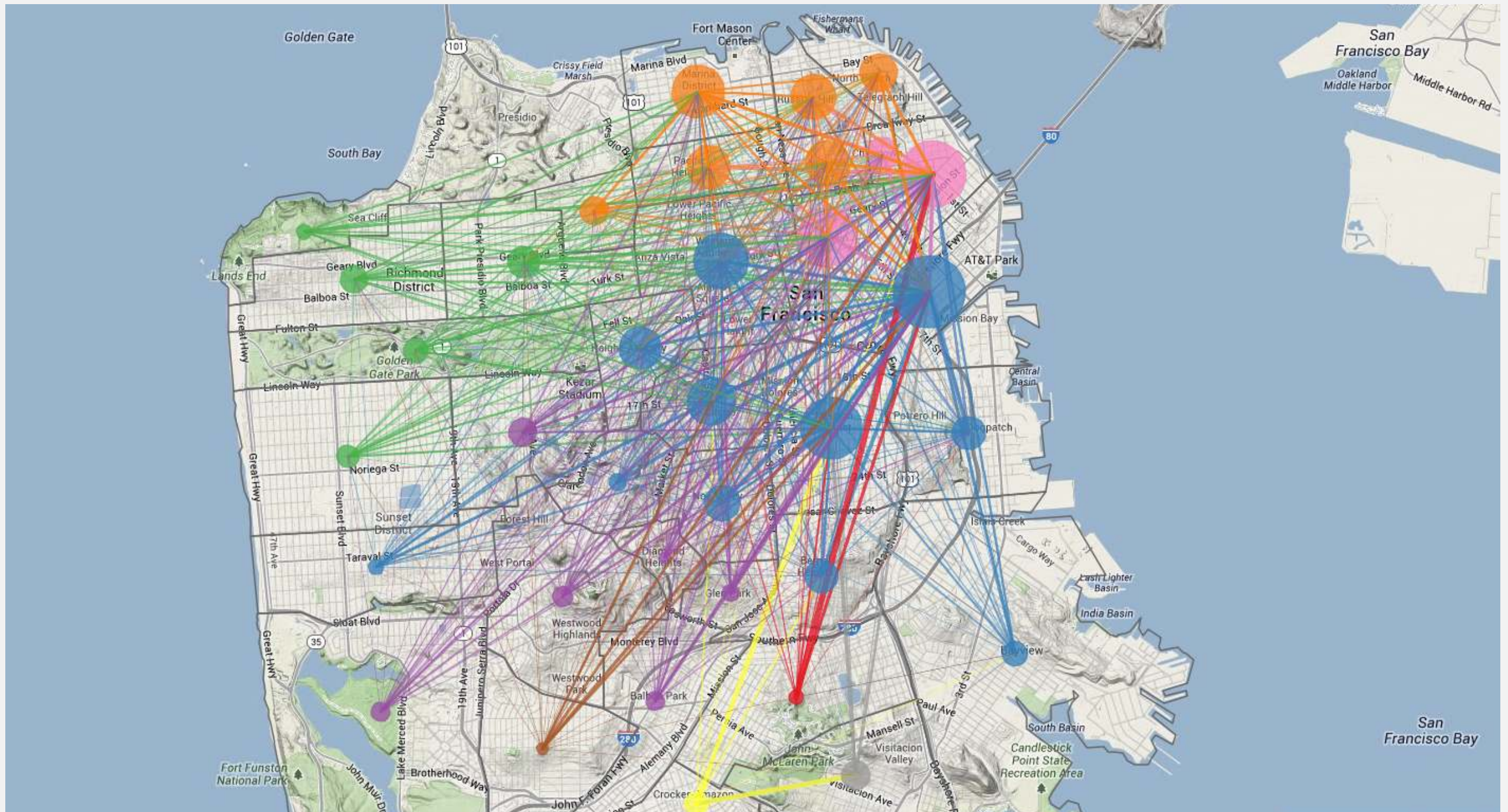


The Topology of the Federal Funds Market, Bech and Atalay, 2008



# Uber taxi graph

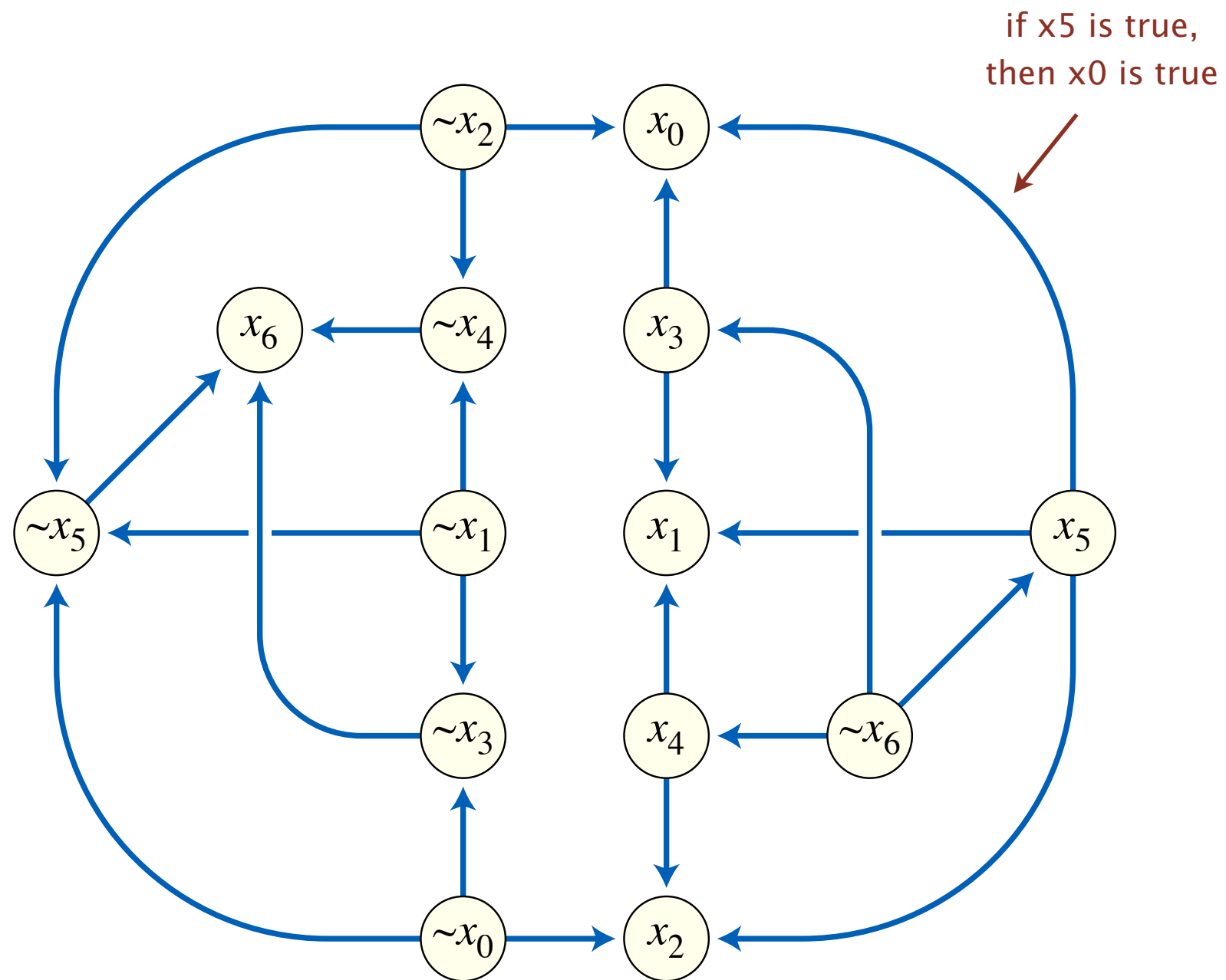
Vertex = taxi pickup; edge = taxi ride.



<http://blog.uber.com/2012/01/09/uberdata-san-franciscocomics/>

# Implication graph

Vertex = variable; edge = logical implication.

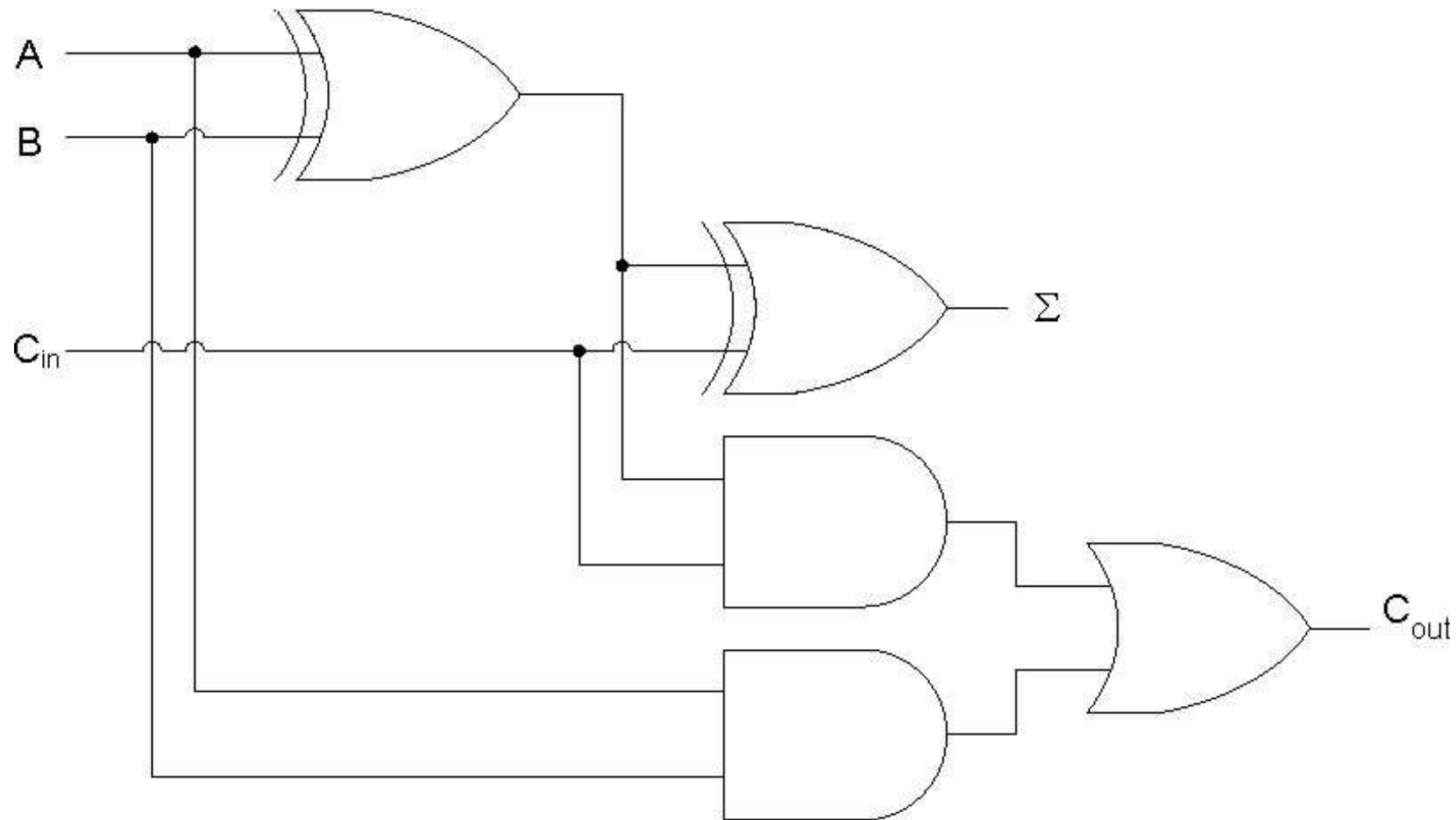




# Combinational circuit

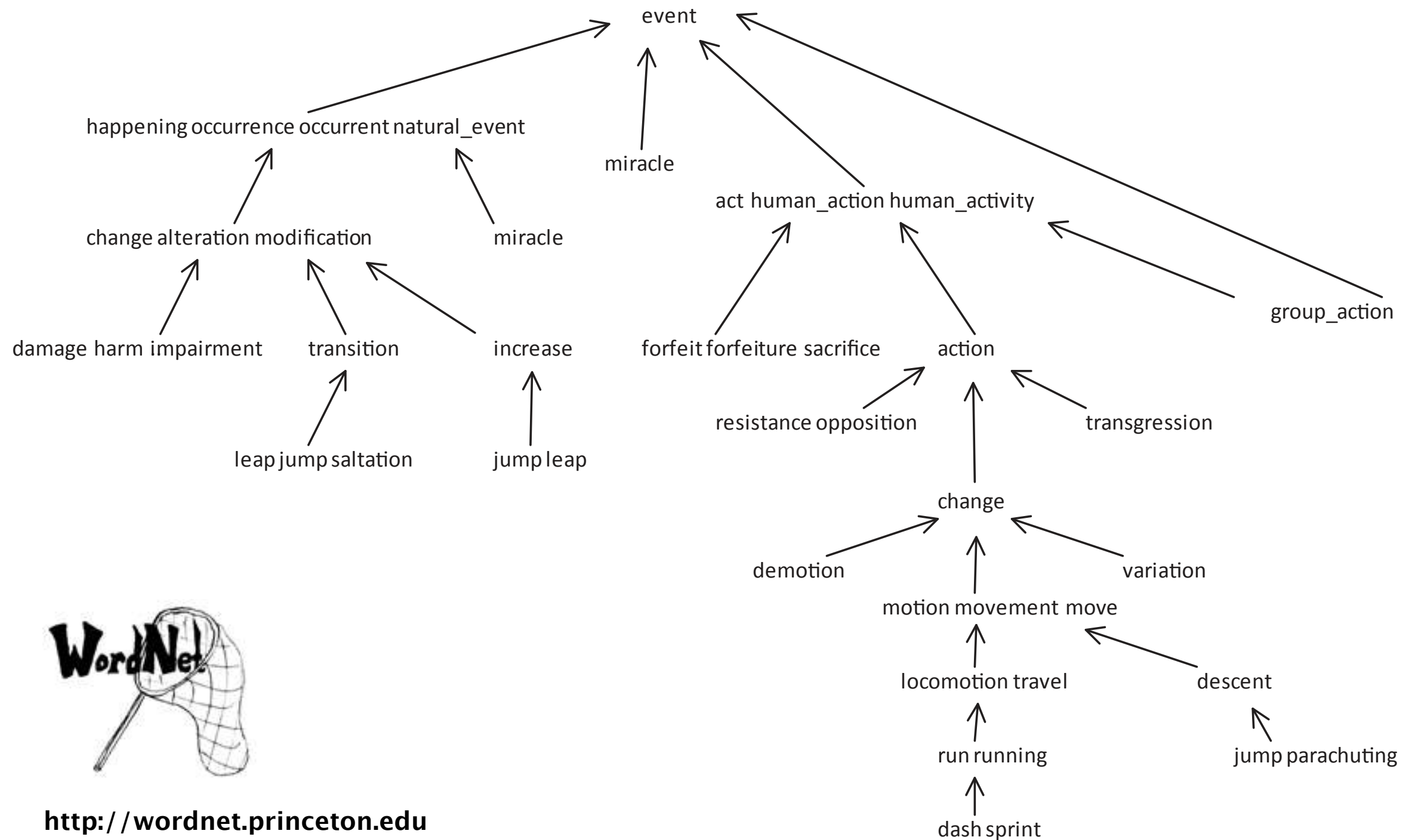
---

Vertex = logical gate; edge = wire.



# WordNet graph

Vertex = synset; edge = hypernym relationship.



<http://wordnet.princeton.edu>



# Digraph applications

---

digraph	vertex	directed edge
<b>transportation</b>	street intersection	one-way street
<b>web</b>	web page	hyperlink
<b>food web</b>	species	predator-prey relationship
<b>WordNet</b>	synset	hypernym
<b>scheduling</b>	task	precedence constraint
<b>financial</b>	bank	transaction
<b>cell phone</b>	person	placed call
<b>infectious disease</b>	person	infection
<b>game</b>	board position	legal move
<b>citation</b>	journal article	citation
<b>object graph</b>	object	pointer
<b>inheritance hierarchy</b>	class	inherits from
<b>control flow</b>	code block	jump

# Some digraph problems

---

problem	description
<b><math>s \rightarrow t</math> path</b>	<i>Is there a path from <math>s</math> to <math>t</math> ?</i>
<b>shortest <math>s \rightarrow t</math> path</b>	<i>What is the shortest path from <math>s</math> to <math>t</math> ?</i>
<b>directed cycle</b>	<i>Is there a directed cycle in the graph ?</i>
<b>topological sort</b>	<i>Can the digraph be drawn so that all edges point upwards?</i>
<b>strong connectivity</b>	<i>Is there a directed path between all pairs of vertices ?</i>
<b>transitive closure</b>	<i>For which vertices <math>v</math> and <math>w</math> is there a directed path from <math>v</math> to <math>w</math> ?</i>
<b>PageRank</b>	<i>What is the importance of a web page ?</i>





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- ▶ *strong components*

# Digraph API

---

Almost identical to Graph API.

```
public class Digraph
```

```
    Digraph(int V)
```

*create an empty digraph with V vertices*

```
    Digraph(In in)
```

*create a digraph from input stream*

```
    void addEdge(int v, int w)
```

*add a directed edge  $v \rightarrow w$*

```
    Iterable<Integer> adj(int v)
```

*vertices pointing from v*

```
    int V()
```

*number of vertices*

```
    int E()
```

*number of edges*

```
    Digraph reverse()
```

*reverse of this digraph*

```
    String toString()
```

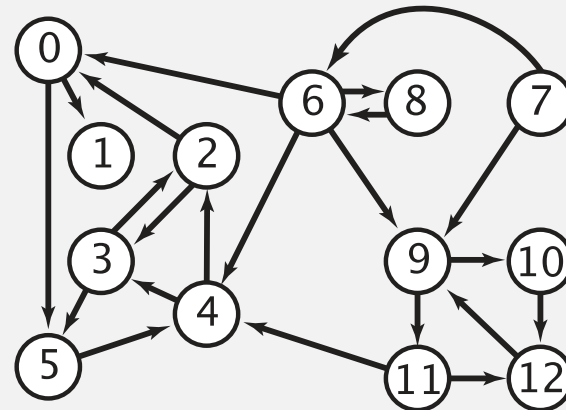
*string representation*



# Digraph API

tinyDG.txt

*V* → 13  
22 ← *E*  
4 2  
2 3  
3 2  
6 0  
0 1  
2 0  
11 12  
12 9  
9 10  
9 11  
7 9  
10 12  
11 4  
4 3  
3 5  
6 8  
8 6  
⋮



```
% java Digraph tinyDG.txt
```

```
0->5  
0->1  
2->0  
2->3  
3->5  
3->2  
4->3  
4->2  
5->4  
⋮  
11->4  
11->12  
12->9
```

```
In in = new In(args[0]);  
Digraph G = new Digraph(in);
```

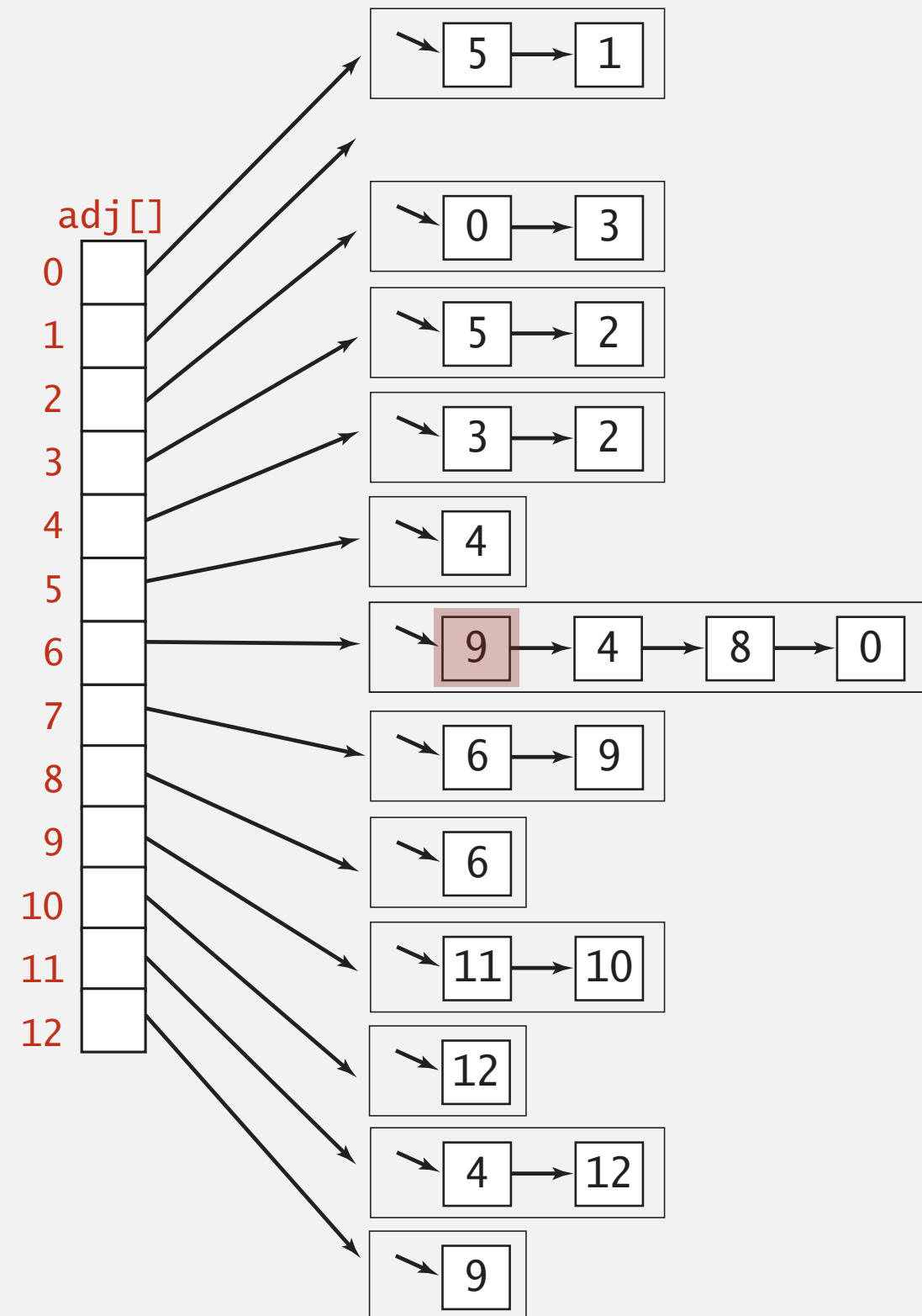
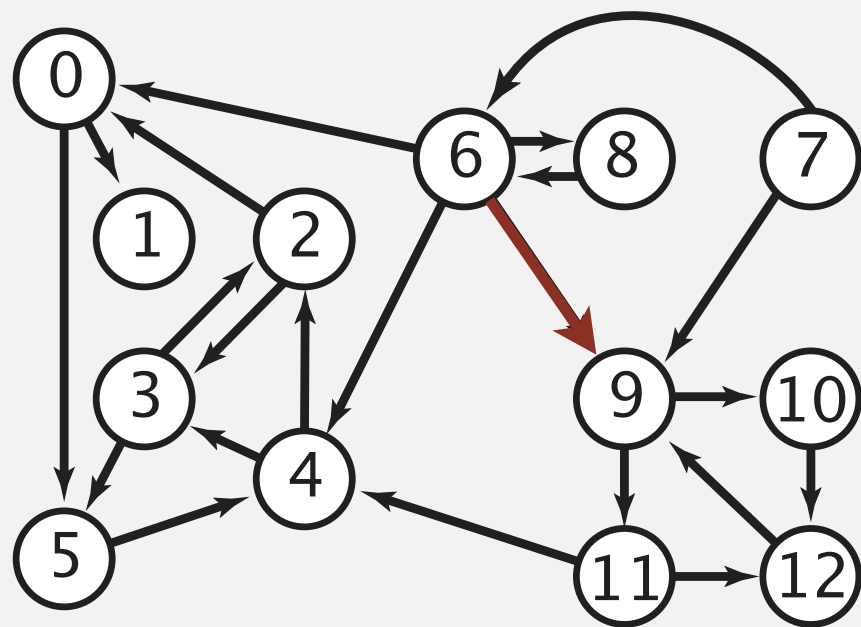
← read digraph from  
input stream

```
for (int v = 0; v < G.V(); v++)  
    for (int w : G.adj(v))  
        StdOut.println(v + "->" + w);
```

← print out each  
edge (once)

# Digraph representation: adjacency lists

Maintain vertex-indexed array of lists.





# Digraph representations

**In practice.** Use adjacency-lists representation.

- Algorithms based on iterating over vertices pointing from  $v$ .
- Real-world digraphs tend to be sparse.

↖ huge number of vertices,  
small average vertex degree

representation	space	insert edge from $v$ to $w$	edge from $v$ to $w$ ?	iterate over vertices pointing from $v$ ?
list of edges	$E$	1	$E$	$E$
adjacency matrix	$V^2$	$1^\dagger$	1	$V$
adjacency lists	$E + V$	1	$outdegree(v)$	$outdegree(v)$

$^\dagger$  disallows parallel edges

# Adjacency-lists graph representation (review): Java implementation

---

```
public class Graph  
{
```

```
    private final int V;
```

```
    private final Bag<Integer>[] adj;
```

← adjacency lists

```
    public Graph(int V)
```

```
    {
```

```
        this.V = V;
```

```
        adj = (Bag<Integer>[]) new Bag[V];
```

```
        for (int v = 0; v < V; v++)
```

```
            adj[v] = new Bag<Integer>();
```

```
    }
```

← create empty graph  
with V vertices

```
    public void addEdge(int v, int w)
```

```
    {
```

```
        adj[v].add(w);
```

```
        adj[w].add(v);
```

```
    }
```

← add edge v-w

```
    public Iterable<Integer> adj(int v)
```

```
    { return adj[v]; }
```

← iterator for vertices  
adjacent to v

```
}
```

# Adjacency-lists digraph representation: Java implementation

---

```
public class Digraph
{
```

```
    private final int V;
```

```
    private final Bag<Integer>[] adj;
```

← adjacency lists

```
    public Digraph(int V)
```

```
    {
```

```
        this.V = V;
```

```
        adj = (Bag<Integer>[]) new Bag[V];
```

```
        for (int v = 0; v < V; v++)
```

```
            adj[v] = new Bag<Integer>();
```

```
    }
```

← create empty digraph  
with V vertices

```
    public void addEdge(int v, int w)
```

```
    {
```

```
        adj[v].add(w);
```

```
    }
```

← add edge  $v \rightarrow w$

```
    public Iterable<Integer> adj(int v)
```

```
    { return adj[v]; }
```

```
}
```

← iterator for vertices  
pointing from v





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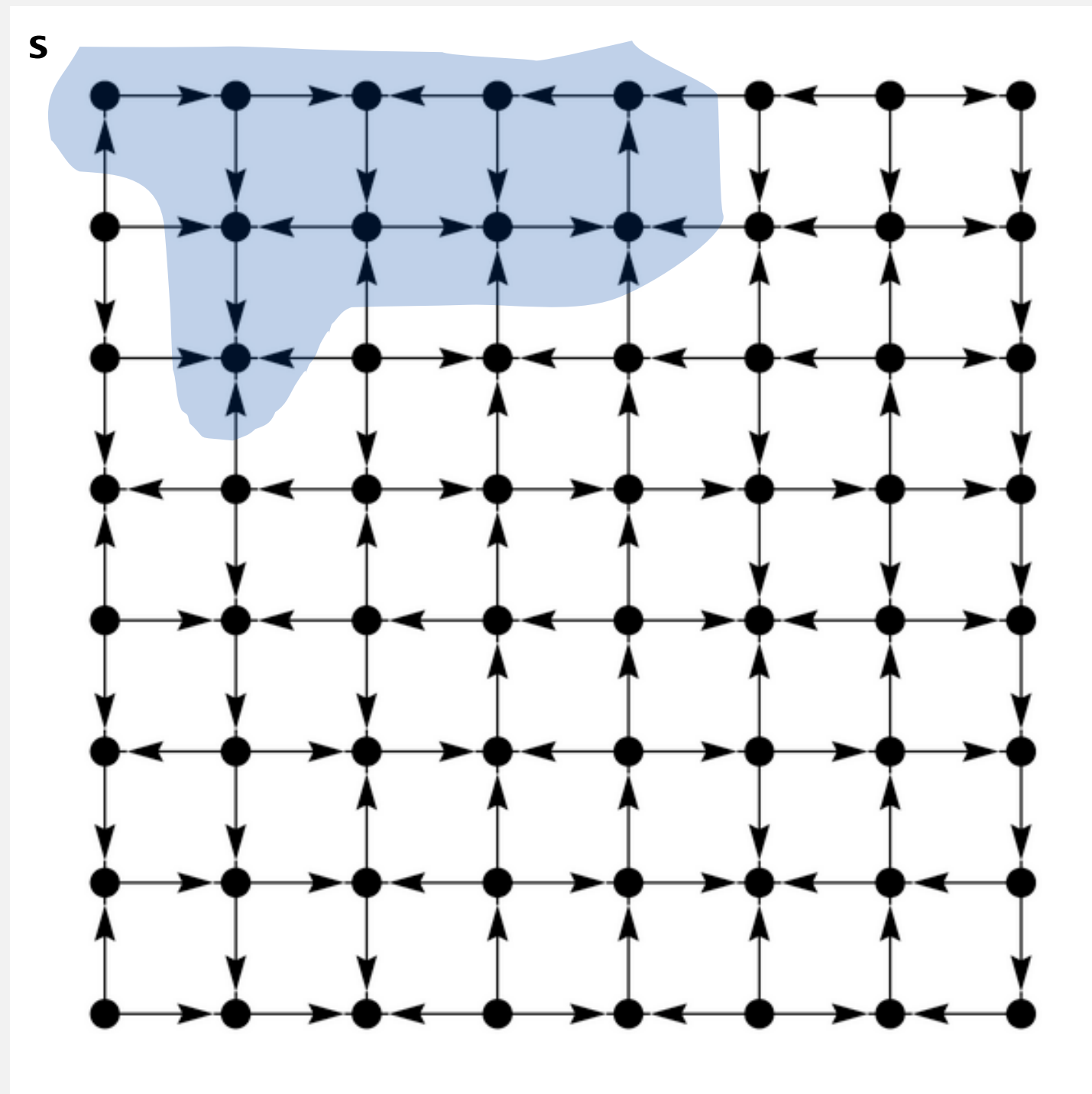
---

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- ▶ *strong components*

# Reachability

---

**Problem.** Find all vertices reachable from  $s$  along a directed path.



# Depth-first search in digraphs

---

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- DFS is a **digraph** algorithm.

**DFS** (to visit a vertex  $v$ )

---

Mark  $v$  as visited.

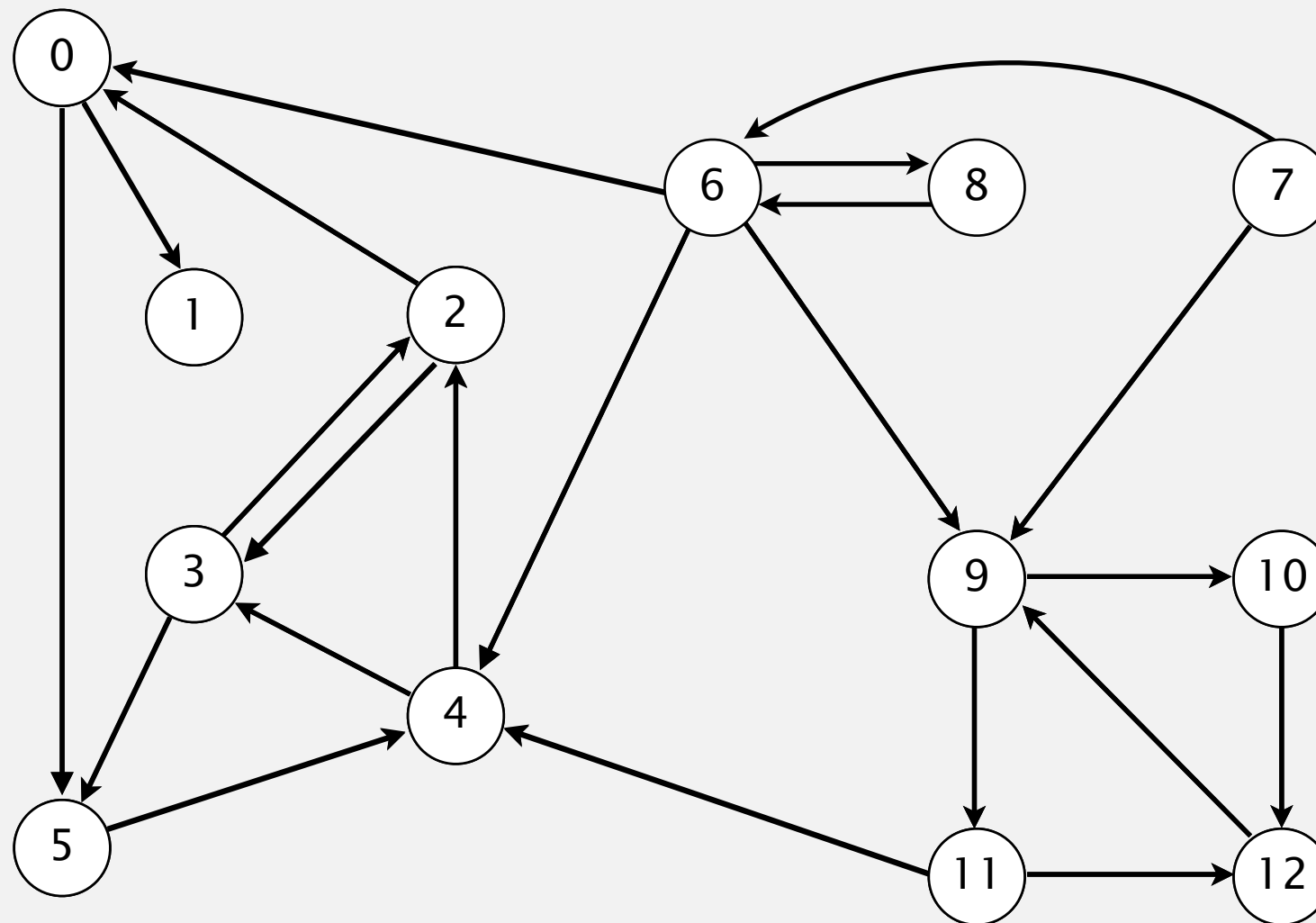
Recursively visit all unmarked  
vertices  $w$  pointing from  $v$ .

---

# Depth-first search demo

To visit a vertex  $v$ :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices pointing from  $v$ .



a directed graph

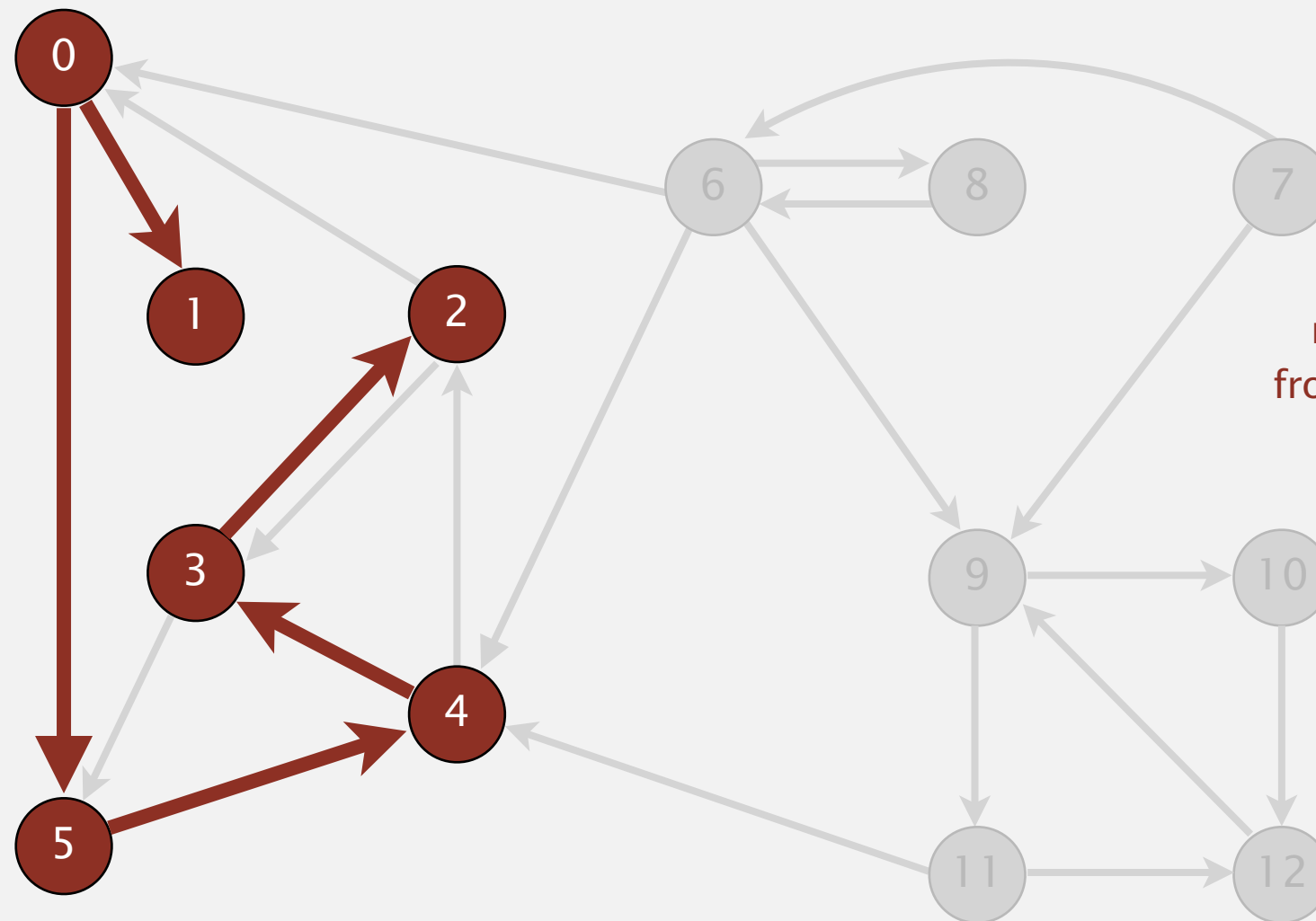
4→2  
2→3  
3→2  
6→0  
0→1  
2→0  
11→12  
12→9  
9→10  
9→11  
8→9  
10→12  
11→4  
4→3  
3→5  
6→8  
8→6  
5→4  
0→5  
6→4  
6→9  
7→6



# Depth-first search demo

To visit a vertex  $v$ :

- Mark vertex  $v$  as visited.
- Recursively visit all unmarked vertices pointing from  $v$ .



$v$	marked[]	edgeTo[]
0	T	—
1	T	0
2	T	3
3	T	4
4	T	5
5	T	0
6	F	—
7	F	—
8	F	—
9	F	—
10	F	—
11	F	—
12	F	—

reachable from 0

# Depth-first search (in undirected graphs)

---

Recall code for **undirected** graphs.

```
public class DepthFirstSearch  
{
```

```
    private boolean[] marked;
```

← true if connected to s

```
    public DepthFirstSearch(Graph G, int s)  
    {
```

```
        marked = new boolean[G.V()];  
        dfs(G, s);
```

← constructor marks  
vertices connected to s

```
    private void dfs(Graph G, int v)  
    {
```

```
        marked[v] = true;  
        for (int w : G.adj(v))  
            if (!marked[w]) dfs(G, w);
```

← recursive DFS does the work

```
    public boolean visited(int v)  
    { return marked[v]; }
```

← client can ask whether any  
vertex is connected to s

```
}
```

# Depth-first search (in directed graphs)

---

Code for **directed** graphs identical to undirected one.

[substitute Digraph for Graph]

```
public class DirectedDFS  
{
```

```
    private boolean[] marked;
```

← true if path from s

```
    public DirectedDFS(Digraph G, int s)  
    {  
        marked = new boolean[G.V()];  
        dfs(G, s);  
    }
```

← constructor marks  
vertices reachable from s

```
    private void dfs(Digraph G, int v)  
    {  
        marked[v] = true;  
        for (int w : G.adj(v))  
            if (!marked[w]) dfs(G, w);  
    }
```

← recursive DFS does the work

```
    public boolean visited(int v)  
    { return marked[v]; }  
}
```

← client can ask whether any  
vertex is reachable from s

# Reachability application: program control-flow analysis

Every program is a digraph.

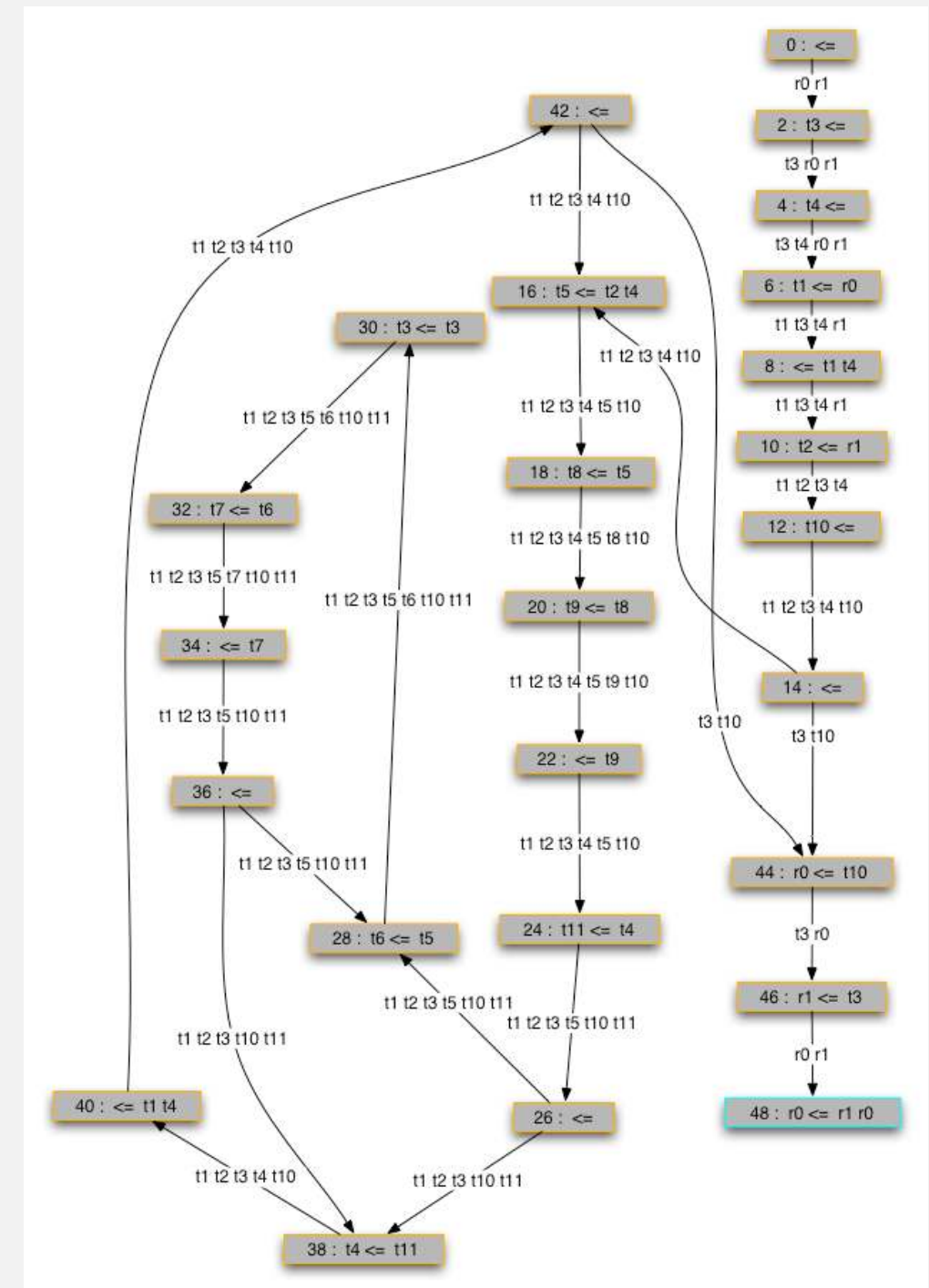
- Vertex = basic block of instructions (straight-line program).
- Edge = jump.

Dead-code elimination.

Find (and remove) unreachable code.

Infinite-loop detection.

Determine whether exit is unreachable.





# Reachability application: mark-sweep garbage collector

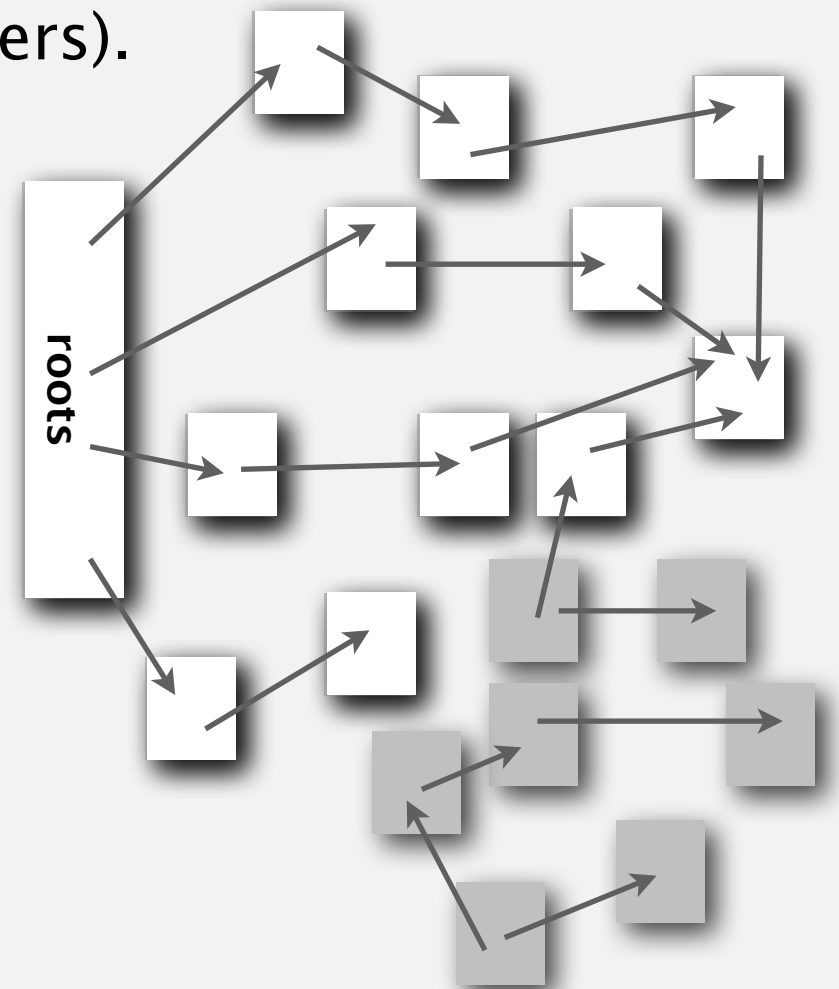
---

Every data structure is a digraph.

- Vertex = object.
- Edge = reference.

**Roots.** Objects known to be directly accessible by program (e.g., stack).

**Reachable objects.** Objects indirectly accessible by program (starting at a root and following a chain of pointers).



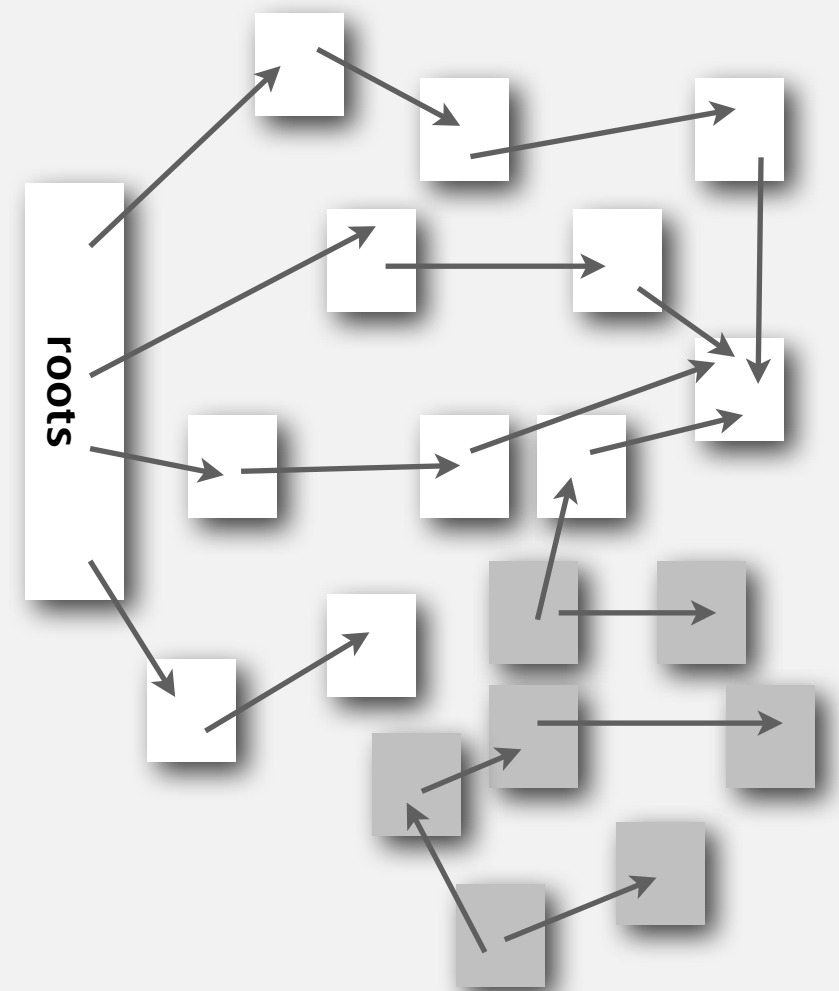
# Reachability application: mark-sweep garbage collector

---

Mark-sweep algorithm. [McCarthy, 1960]

- Mark: mark all reachable objects.
- Sweep: if object is unmarked, it is garbage (so add to free list).

Memory cost. Uses 1 extra mark bit per object (plus DFS stack).



# Depth-first search in digraphs summary

---

DFS enables direct solution of simple digraph problems.

- ✓ • Reachability.
- Path finding.
- Topological sort.
- Directed cycle detection.

Basis for solving difficult digraph problems.

- 2-satisfiability.
- Directed Euler path.
- Strongly-connected components.

SIAM J. COMPUT.  
Vol. 1, No. 2, June 1972

## DEPTH-FIRST SEARCH AND LINEAR GRAPH ALGORITHMS\*

ROBERT TARJAN†

**Abstract.** The value of depth-first search or “backtracking” as a technique for solving problems is illustrated by two examples. An improved version of an algorithm for finding the strongly connected components of a directed graph and an algorithm for finding the biconnected components of an undirect graph are presented. The space and time requirements of both algorithms are bounded by  $k_1V + k_2E + k_3$  for some constants  $k_1, k_2$ , and  $k_3$ , where  $V$  is the number of vertices and  $E$  is the number of edges of the graph being examined.

# Breadth-first search in digraphs

---

Same method as for undirected graphs.

- Every undirected graph is a digraph (with edges in both directions).
- BFS is a **digraph** algorithm.

**BFS** (from source vertex  $s$ )

---

Put  $s$  onto a FIFO queue, and mark  $s$  as visited.

Repeat until the queue is empty:

- remove the least recently added vertex  $v$
  - for each unmarked vertex pointing from  $v$ :  
add to queue and mark as visited.
- 

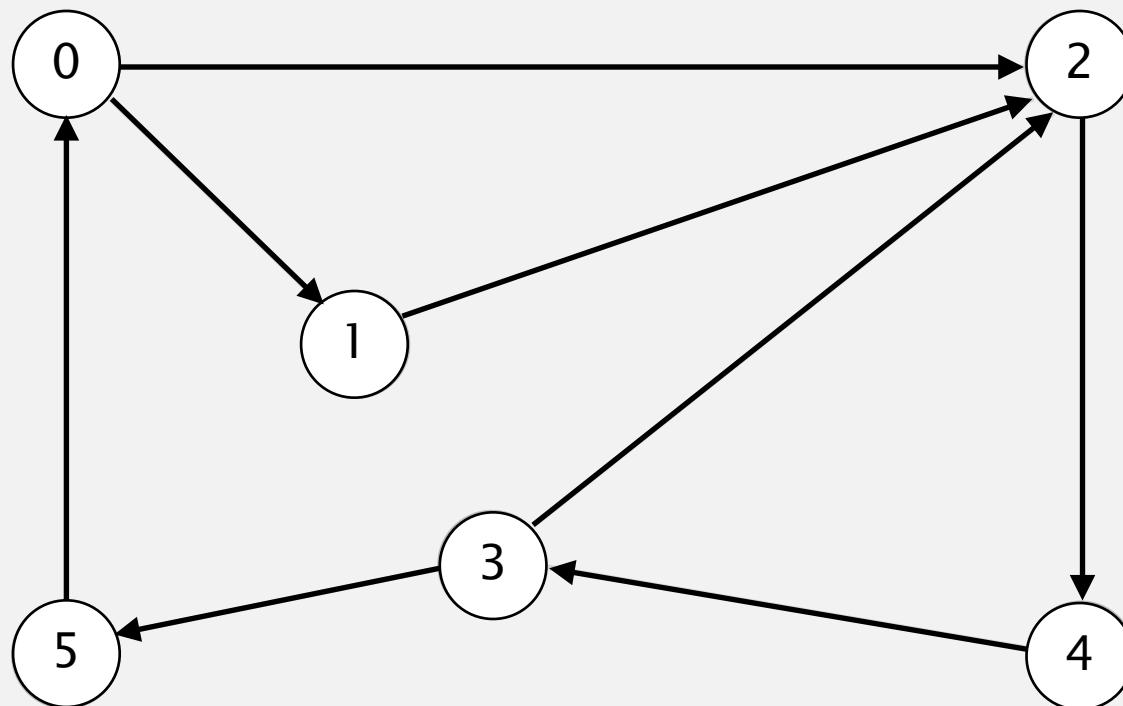
**Proposition.** BFS computes shortest paths (fewest number of edges) from  $s$  to all other vertices in a digraph in time proportional to  $E + V$ .



# Directed breadth-first search demo

Repeat until queue is empty:

- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices pointing from  $v$  and mark them.



**tinyDG2.txt**

V	E
6	
8	
5	0
2	4
3	2
1	2
0	1
4	3
3	5
0	2

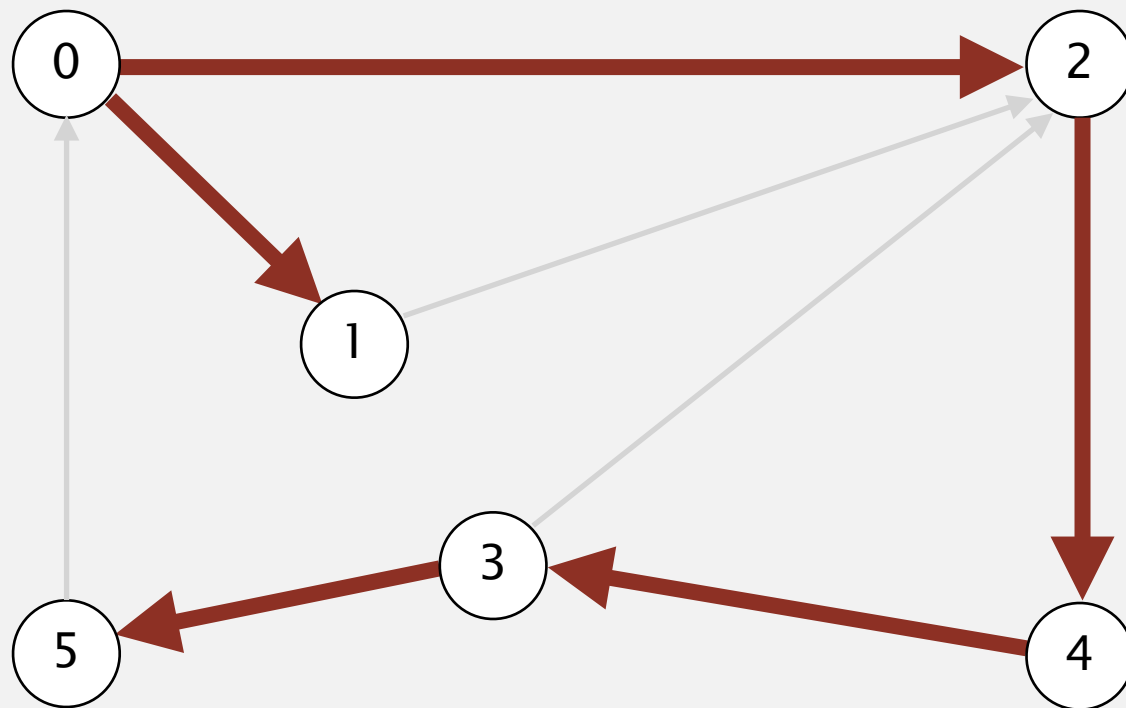
**graph G**

# Directed breadth-first search demo

---

Repeat until queue is empty:

- Remove vertex  $v$  from queue.
- Add to queue all unmarked vertices pointing from  $v$  and mark them.



$v$	edgeTo[]	distTo[]
0	–	0
1	0	1
2	0	1
3	4	3
4	2	2
5	3	4

done

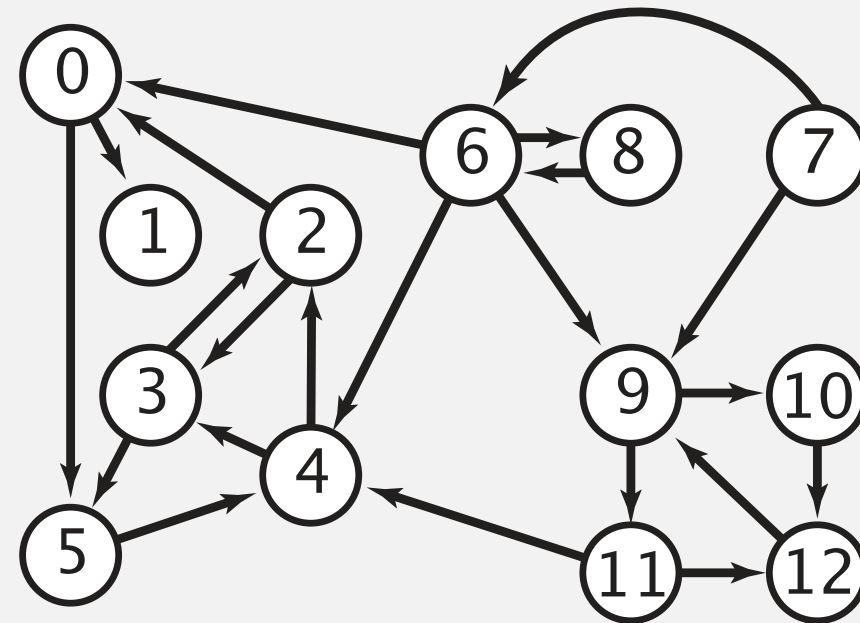
# Multiple-source shortest paths

---

**Multiple-source shortest paths.** Given a digraph and a **set** of source vertices, find shortest path from any vertex in the set to each other vertex.

**Ex.**  $S = \{ 1, 7, 10 \}$ .

- Shortest path to 4 is  $7 \rightarrow 6 \rightarrow 4$ .
- Shortest path to 5 is  $7 \rightarrow 6 \rightarrow 0 \rightarrow 5$ .
- Shortest path to 12 is  $10 \rightarrow 12$ .
- ...



**Q.** How to implement multi-source shortest paths algorithm?

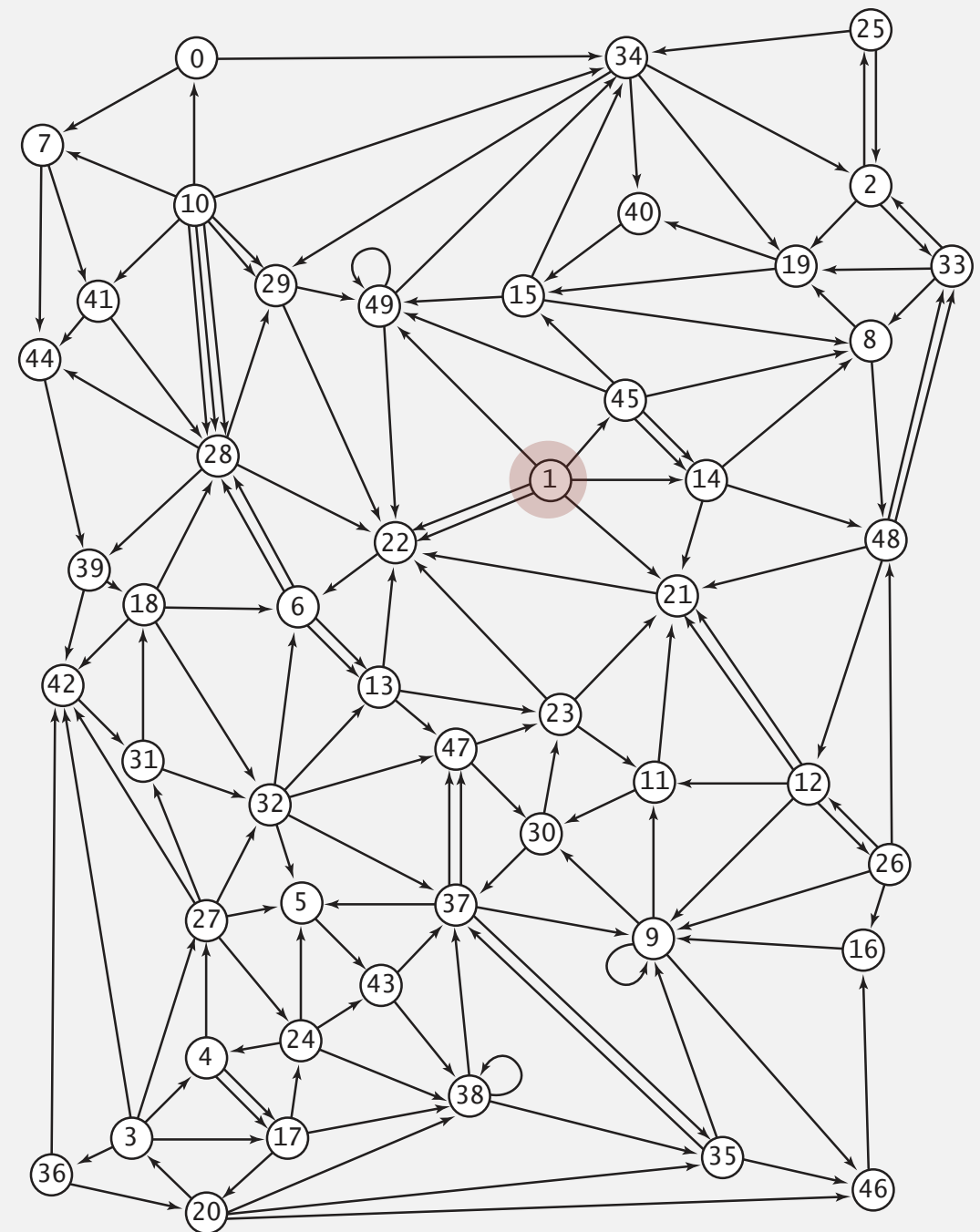
**A.** Use BFS, but initialize by enqueueing all source vertices.

# Breadth-first search in digraphs application: web crawler

**Goal.** Crawl web, starting from some root web page, say `www.princeton.edu`.

**Solution.** [BFS with implicit digraph]

- Choose root web page as source  $s$ .
- Maintain a Queue of websites to explore.
- Maintain a SET of discovered websites.
- Dequeue the next website and enqueue websites to which it links (provided you haven't done so before).



**Q.** Why not use DFS?

# Bare-bones web crawler: Java implementation

```
Queue<String> queue = new Queue<String>();  
SET<String> marked = new SET<String>();
```

← queue of websites to crawl  
← set of marked websites

```
String root = "http://www.princeton.edu";  
queue.enqueue(root);  
marked.add(root);
```

← start crawling from root website

```
while (!queue.isEmpty())  
{
```

```
    String v = queue.dequeue();  
    StdOut.println(v);  
    In in = new In(v);  
    String input = in.readAll();
```

← read in raw html from next  
website in queue

```
    String regexp = "http://(\\w+\\.)+(\\w+)";  
    Pattern pattern = Pattern.compile(regexp);  
    Matcher matcher = pattern.matcher(input);  
    while (matcher.find())  
    {
```

← use regular expression to find all URLs  
in website of form http://xxx.yyy.zzz  
[crude pattern misses relative URLs]

```
        String w = matcher.group();  
        if (!marked.contains(w))  
        {  
            marked.add(w);  
            queue.enqueue(w);  
        }
```

← if unmarked, mark it and put  
on the queue

```
    }  
}
```



# Web crawler output

---

## BFS crawl

```
http://www.princeton.edu
http://www.w3.org
http://ogp.me
http://giving.princeton.edu
http://www.princetonartmuseum.org
http://www.goprincetontigers.com
http://library.princeton.edu
http://helpdesk.princeton.edu
http://tigernet.princeton.edu
http://alumni.princeton.edu
http://gradschool.princeton.edu
http://vimeo.com
http://princetonusg.com
http://artmuseum.princeton.edu
http://jobs.princeton.edu
http://odoc.princeton.edu
http://blogs.princeton.edu
http://www.facebook.com
http://twitter.com
http://www.youtube.com
http://deimos.apple.com
http://qeprize.org
http://en.wikipedia.org
...
```

## DFS crawl

```
http://www.princeton.edu
http://deimos.apple.com
http://www.youtube.com
http://www.google.com
http://news.google.com
http://csi.gstatic.com
http://googlenewsblog.blogspot.com
http://labs.google.com
http://groups.google.com
http://img1.blogblog.com
http://feeds.feedburner.com
http://buttons.google syndication.com
http://fusion.google.com
http://insidesearch.blogspot.com
http://agoogleaday.com
http://static.googleusercontent.com
http://searchresearch1.blogspot.com
http://feedburner.google.com
http://www.dot.ca.gov
http://www.TahoeRoads.com
http://www.LakeTahoeTransit.com
http://www.laketahoe.com
http://ethel.tahoeguide.com
...
```



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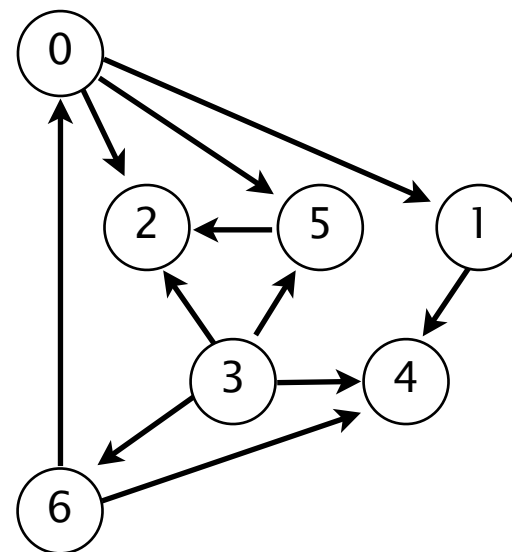
# Precedence scheduling

**Goal.** Given a set of tasks to be completed with precedence constraints, in which order should we schedule the tasks?

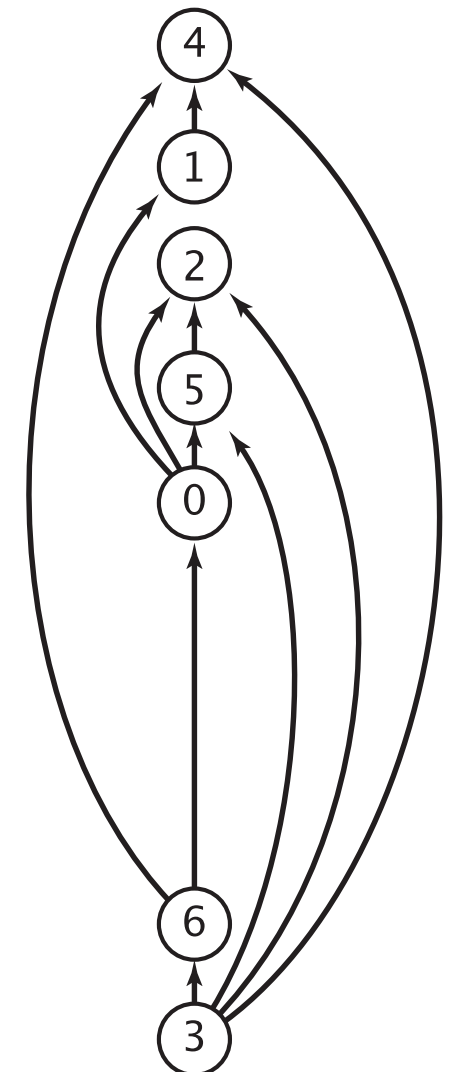
**Digraph model.** vertex = task; edge = precedence constraint.

- 0. Algorithms
- 1. Complexity Theory
- 2. Artificial Intelligence
- 3. Intro to CS
- 4. Cryptography
- 5. Scientific Computing
- 6. Advanced Programming

tasks



precedence constraint graph



feasible schedule

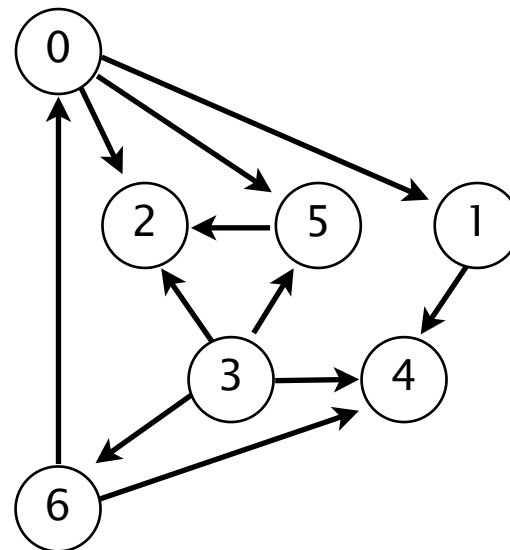
# Topological sort

**DAG.** Directed **acyclic** graph.

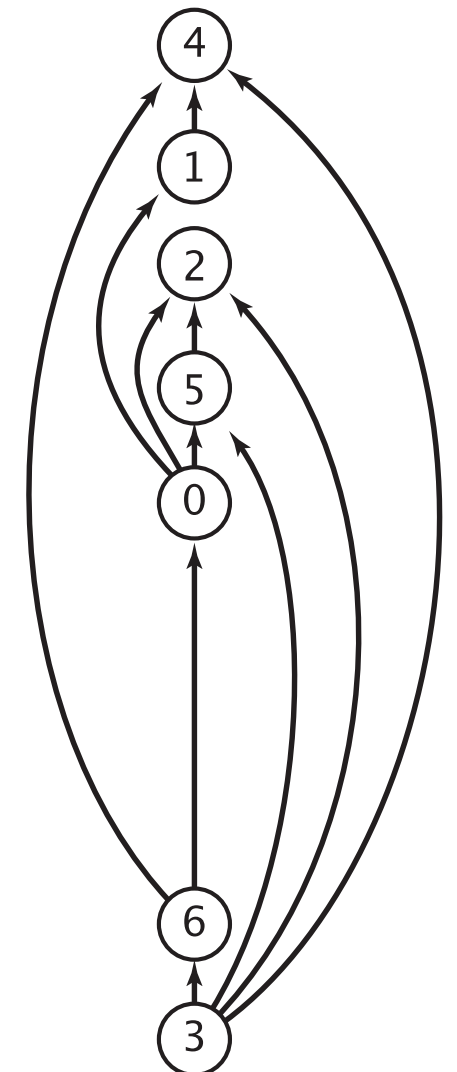
**Topological sort.** Redraw DAG so all edges point upwards.

$0 \rightarrow 5$	$0 \rightarrow 2$
$0 \rightarrow 1$	$3 \rightarrow 6$
$3 \rightarrow 5$	$3 \rightarrow 4$
$5 \rightarrow 2$	$6 \rightarrow 4$
$6 \rightarrow 0$	$3 \rightarrow 2$
$1 \rightarrow 4$	

directed edges



DAG

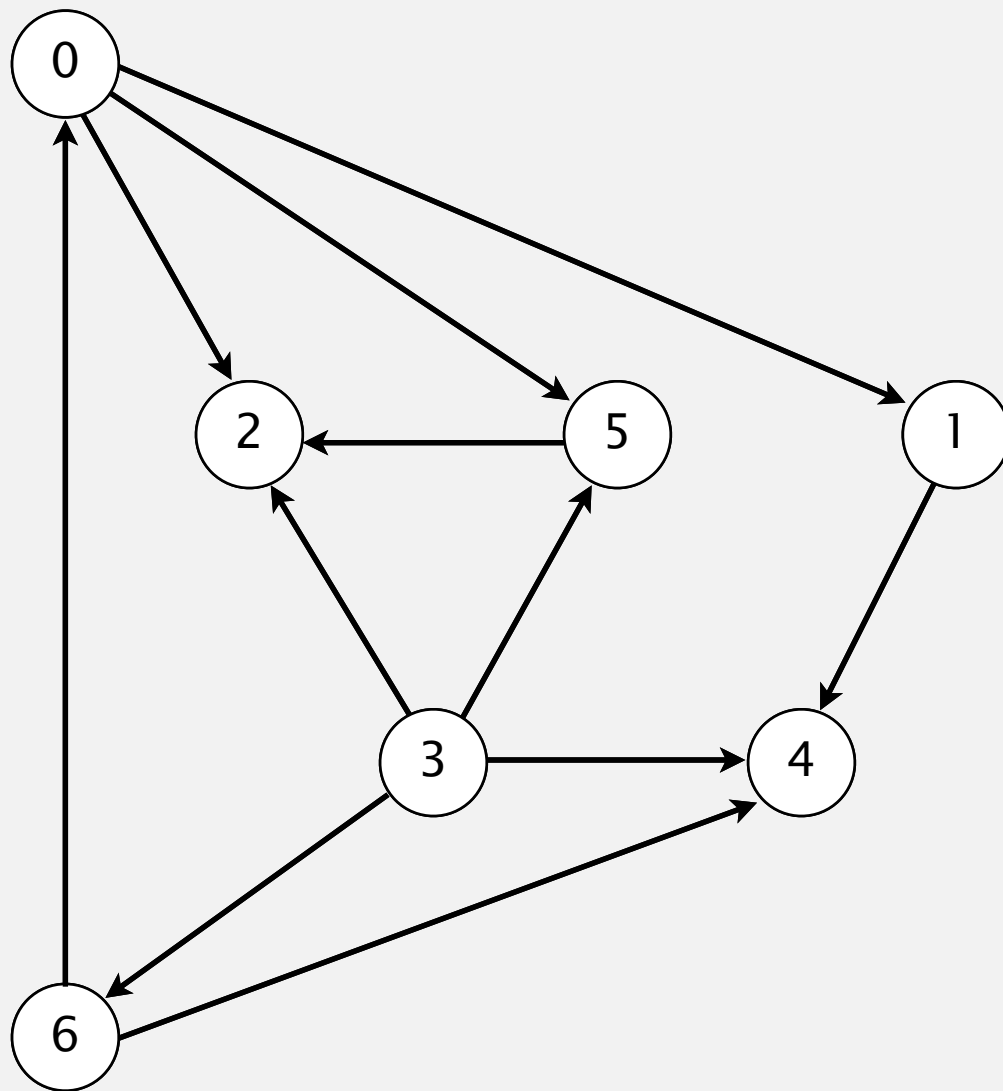


topological order

**Solution.** DFS. What else?

# Topological sort demo

- Run depth-first search.
- Return vertices in reverse postorder.



tinyDAG7.txt

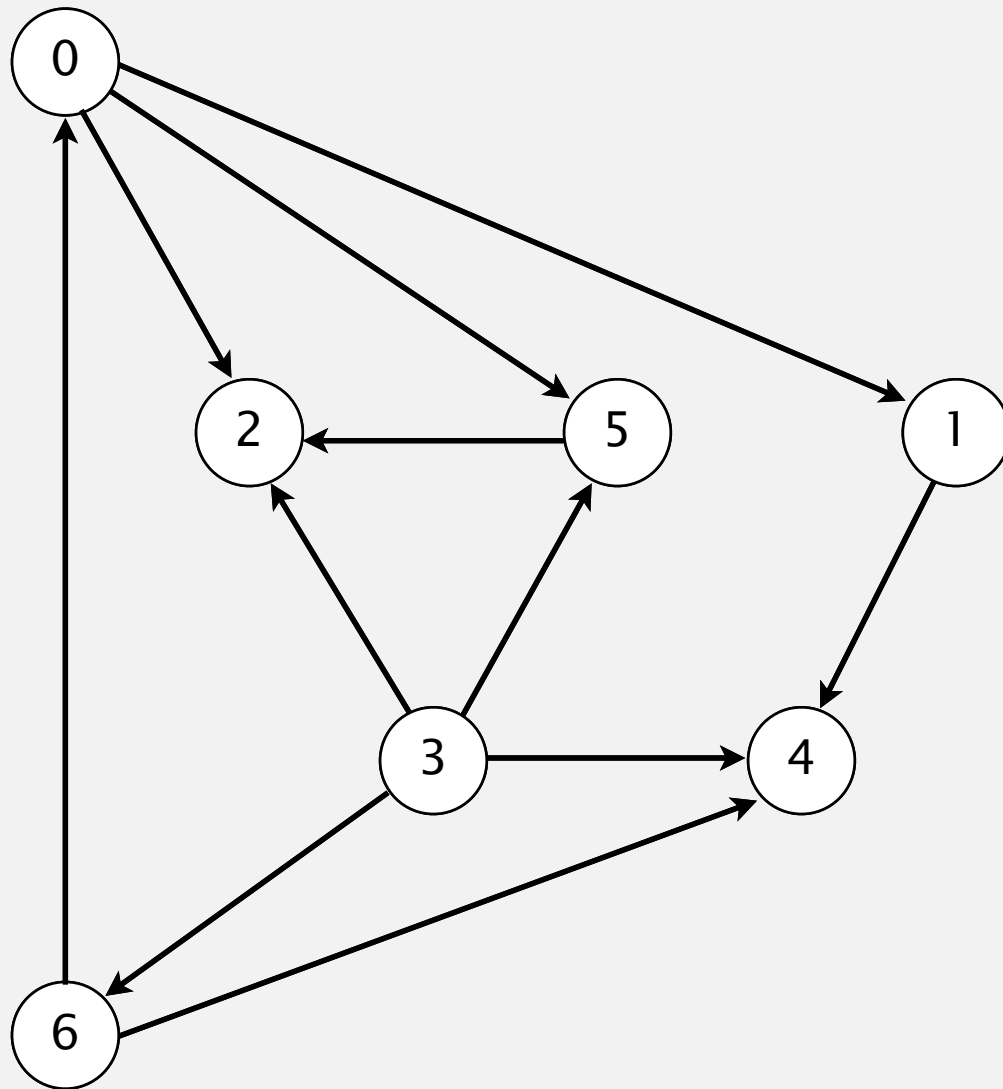
```
7
11
0 5
0 2
0 1
3 6
3 5
3 4
5 2
6 4
6 0
3 2
```

a directed acyclic graph

# Topological sort demo

---

- Run depth-first search.
- Return vertices in reverse postorder.



**postorder**

4 1 2 5 0 6 3

**topological order**

3 6 0 5 2 1 4

**done**



# Depth-first search order

---

```
public class DepthFirstOrder
{
    private boolean[] marked;
    private Stack<Integer> reversePostorder;

    public DepthFirstOrder(Digraph G)
    {
        reversePostorder = new Stack<Integer>();
        marked = new boolean[G.V()];
        for (int v = 0; v < G.V(); v++)
            if (!marked[v]) dfs(G, v);
    }

    private void dfs(Digraph G, int v)
    {
        marked[v] = true;
        for (int w : G.adj(v))
            if (!marked[w]) dfs(G, w);
        reversePostorder.push(v);
    }

    public Iterable<Integer> reversePostorder()
    { return reversePostorder; }
}
```

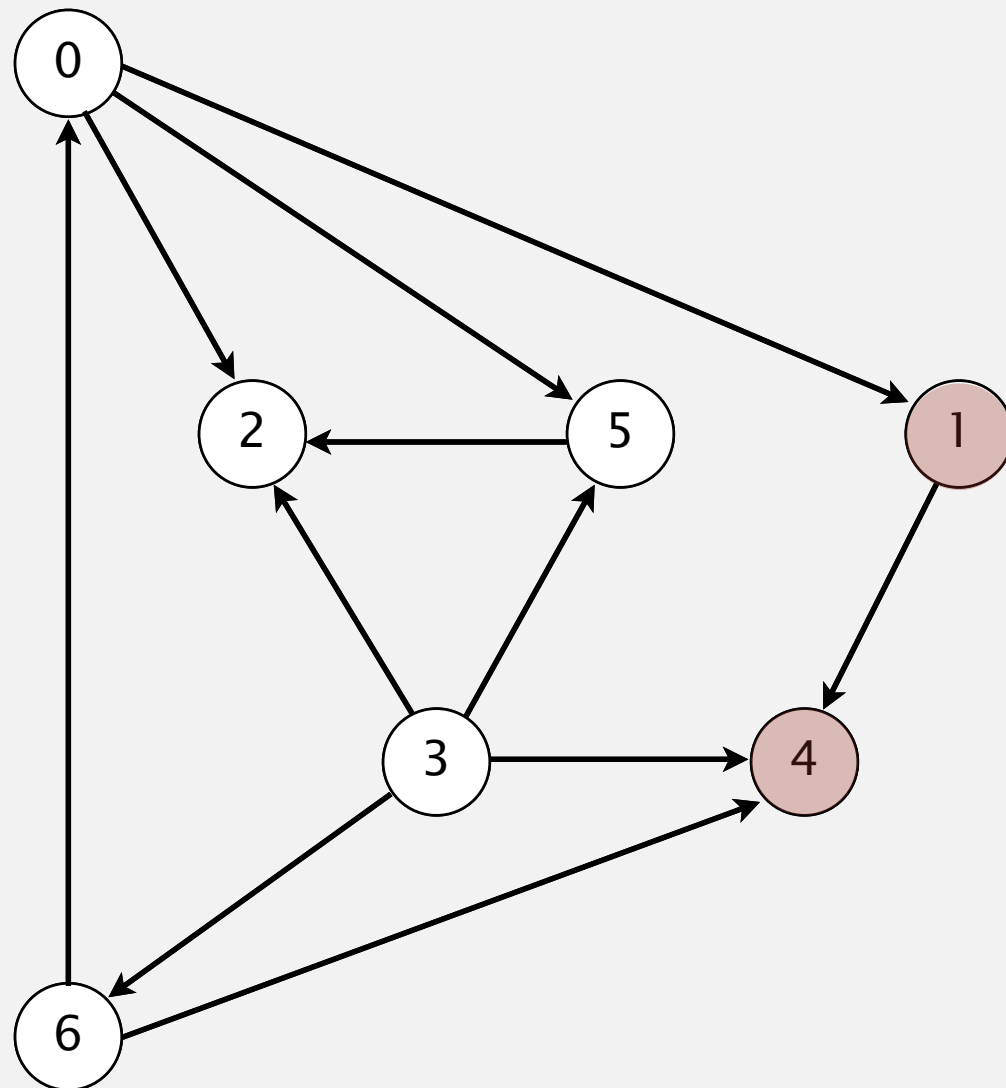
← returns all vertices in  
“reverse DFS postorder”

# Topological sort in a DAG: intuition

---

## Why does topological sort algorithm work?

- First vertex in postorder has outdegree 0.
- Second-to-last vertex in postorder can only point to last vertex.
- ...



**postorder**

4 1 2 5 0 6 3

**topological order**

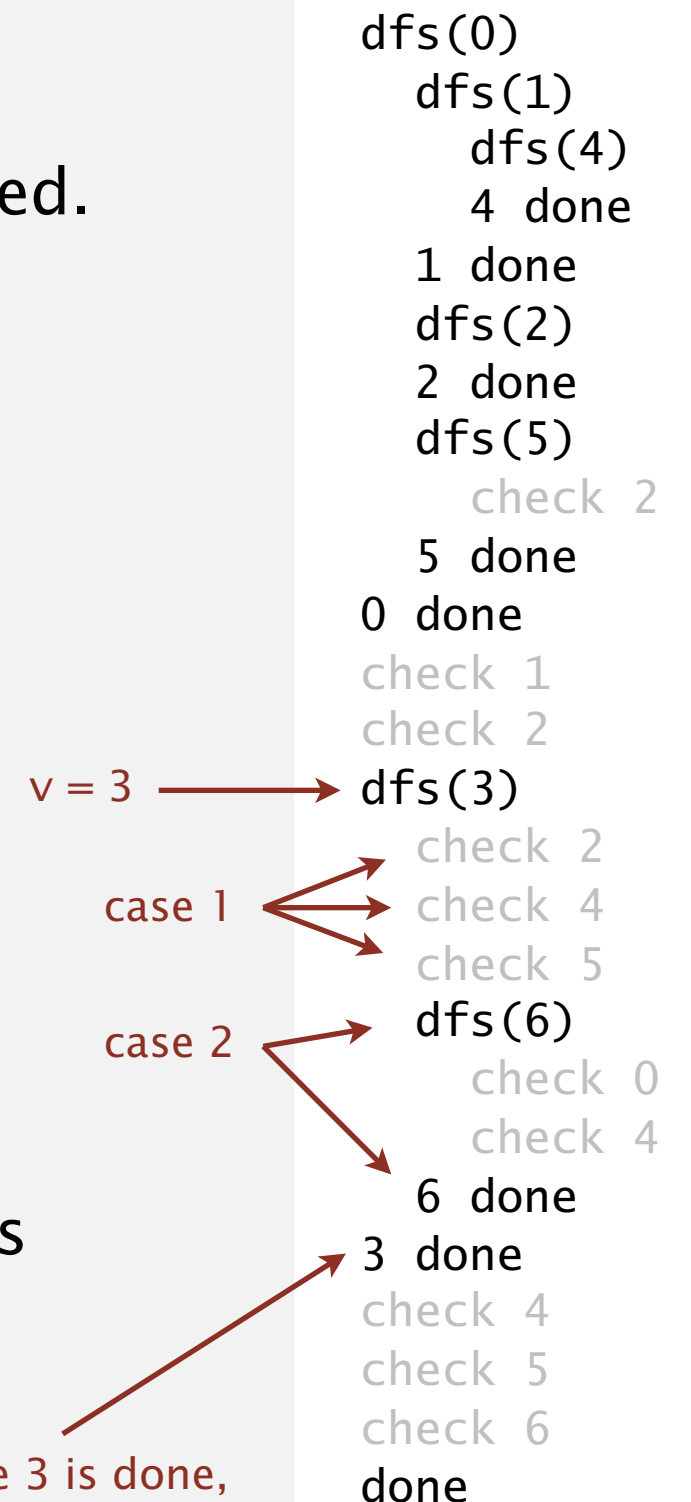
3 6 0 5 2 1 4

# Topological sort in a DAG: correctness proof

**Proposition.** Reverse DFS postorder of a DAG is a topological order.

**Pf.** Consider any edge  $v \rightarrow w$ . When  $\text{dfs}(v)$  is called:

- Case 1:  $\text{dfs}(w)$  has already been called and returned.  
Thus,  $w$  was done before  $v$ .
- Case 2:  $\text{dfs}(w)$  has not yet been called.  
 $\text{dfs}(w)$  will get called directly or indirectly  
by  $\text{dfs}(v)$  and will finish before  $\text{dfs}(v)$ .  
Thus,  $w$  will be done before  $v$ .
- Case 3:  $\text{dfs}(w)$  has already been called,  
but has not yet returned.  
Can't happen in a DAG: function call stack contains  
path from  $w$  to  $v$ , so  $v \rightarrow w$  would complete a cycle.



all vertices pointing from 3 are done before 3 is done,  
so they appear after 3 in topological order

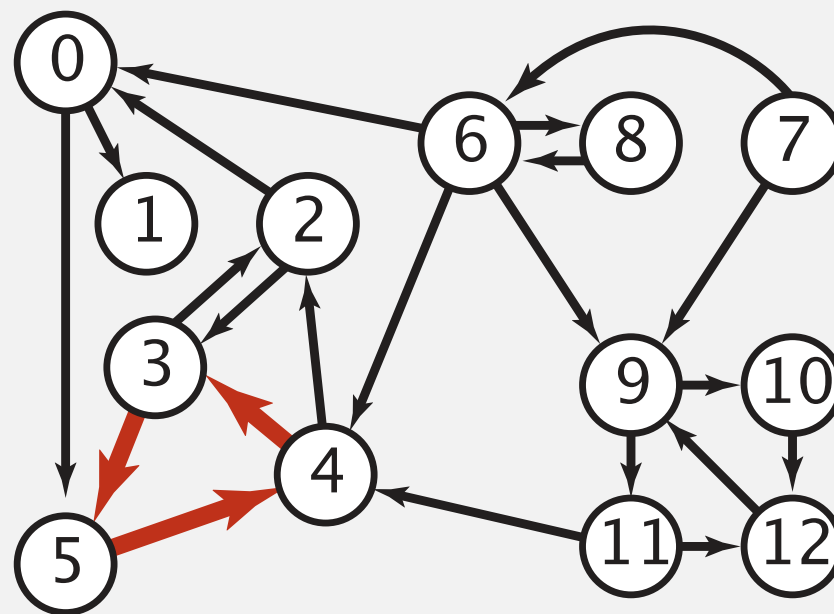
# Directed cycle detection

---

**Proposition.** A digraph has a topological order iff no directed cycle.

**Pf.**

- If directed cycle, topological order impossible.
- If no directed cycle, DFS-based algorithm finds a topological order.



a digraph with a directed cycle

**Goal.** Given a digraph, find a directed cycle.

**Solution.** DFS. What else? See textbook.

# Directed cycle detection application: precedence scheduling

---

**Scheduling.** Given a set of tasks to be completed with precedence constraints, in what order should we schedule the tasks?

PAGE 3

DEPARTMENT	COURSE	DESCRIPTION	PREREQS
COMPUTER SCIENCE	CPSC 432	INTERMEDIATE COMPILER DESIGN, WITH A FOCUS ON DEPENDENCY RESOLUTION.	CPSC 432

<http://xkcd.com/754>

**Remark.** A directed cycle implies scheduling problem is infeasible.

# Directed cycle detection application: cyclic inheritance

---

The Java compiler does cycle detection.

```
public class A extends B
{
    ...
}
```

```
public class B extends C
{
    ...
}
```

```
public class C extends A
{
    ...
}
```

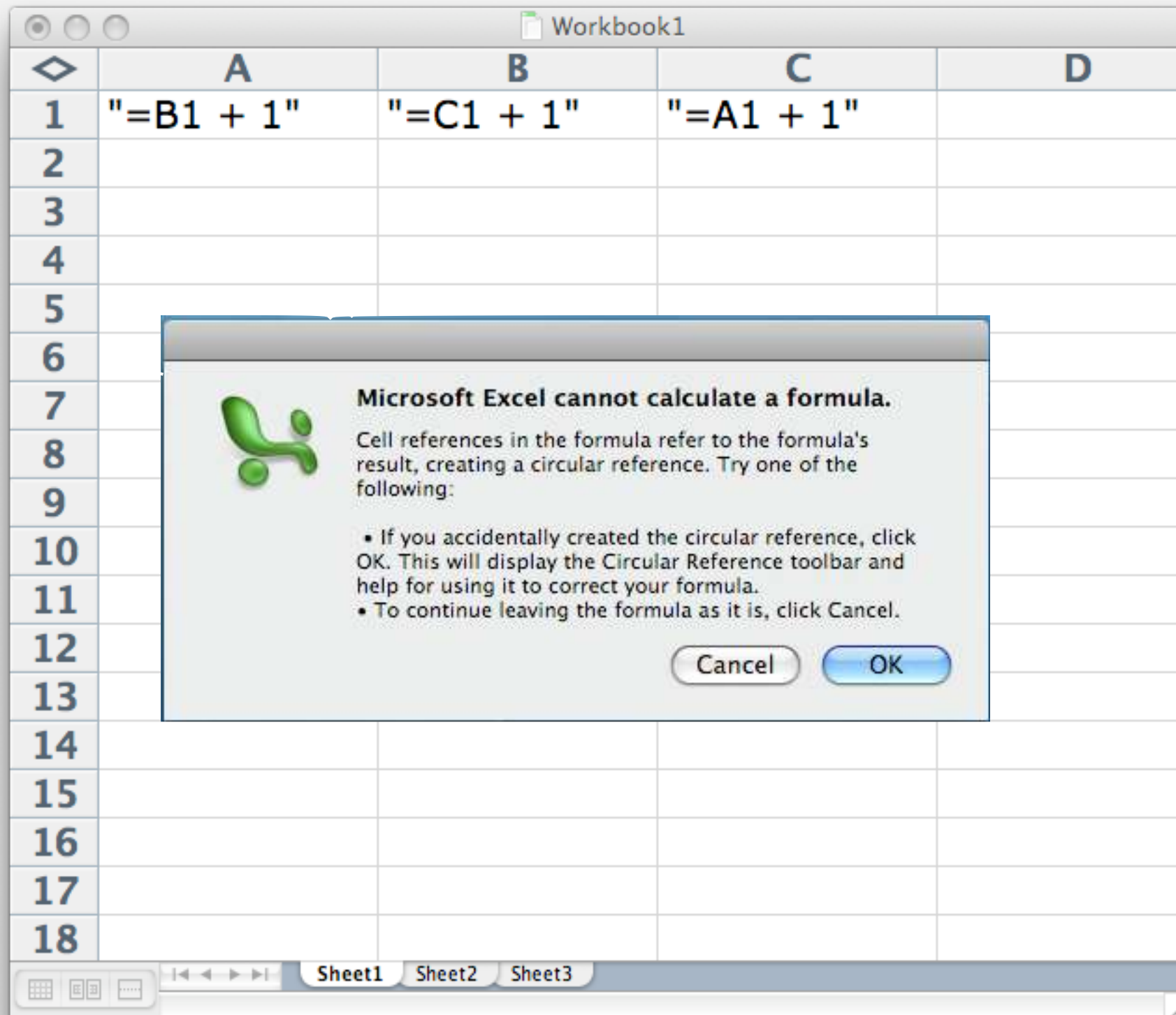
```
% javac A.java
A.java:1: cyclic inheritance
involving A
public class A extends B { }
                ^
1 error
```



# Directed cycle detection application: spreadsheet recalculation

---

Microsoft Excel does cycle detection (and has a circular reference toolbar!)



# Depth-first search orders

---

**Observation.** DFS visits each vertex exactly once. The order in which it does so can be important.

## Orderings.

- Preorder: order in which `dfs()` is called.
- Postorder: order in which `dfs()` returns.
- Reverse postorder: reverse order in which `dfs()` returns.

```
private void dfs(Graph G, int v)
{
    marked[v] = true;
    preorder.enqueue(v);
    for (int w : G.adj(v))
        if (!marked[w]) dfs(G, w);
    postorder.enqueue(v);
    reversePostorder.push(v);
}
```



<http://algs4.cs.princeton.edu>

## 4.2 DIRECTED GRAPHS

---

- ▶ *introduction*
- ▶ *digraph API*
- ▶ *digraph search*
- ▶ *topological sort*
- ▶ ***strong components***

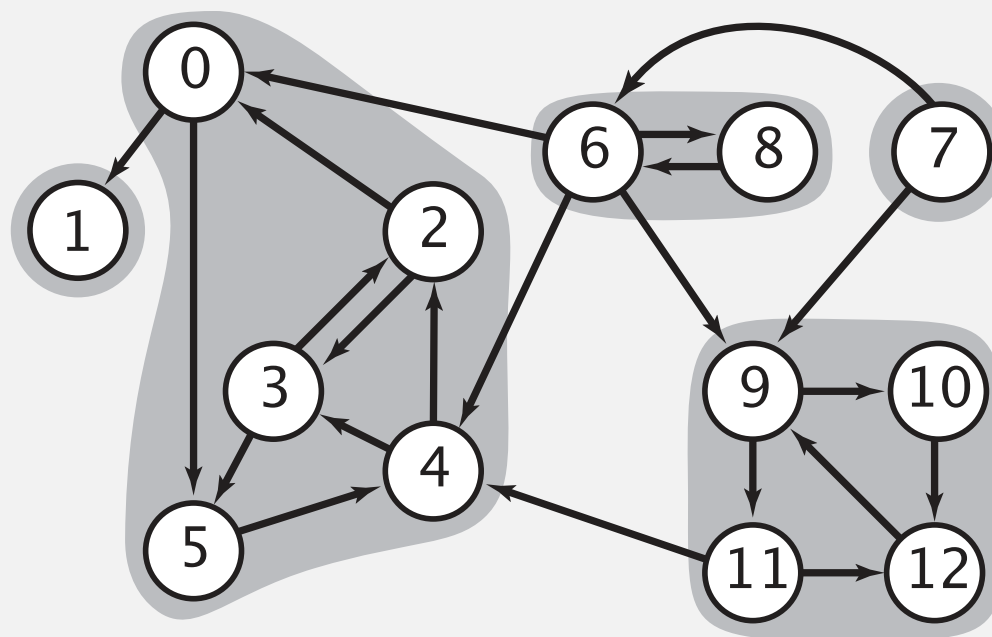
# Strongly-connected components

**Def.** Vertices  $v$  and  $w$  are **strongly connected** if there is both a directed path from  $v$  to  $w$  **and** a directed path from  $w$  to  $v$ .

**Key property.** Strong connectivity is an **equivalence relation**:

- $v$  is strongly connected to  $v$ .
- If  $v$  is strongly connected to  $w$ , then  $w$  is strongly connected to  $v$ .
- If  $v$  is strongly connected to  $w$  and  $w$  to  $x$ , then  $v$  is strongly connected to  $x$ .

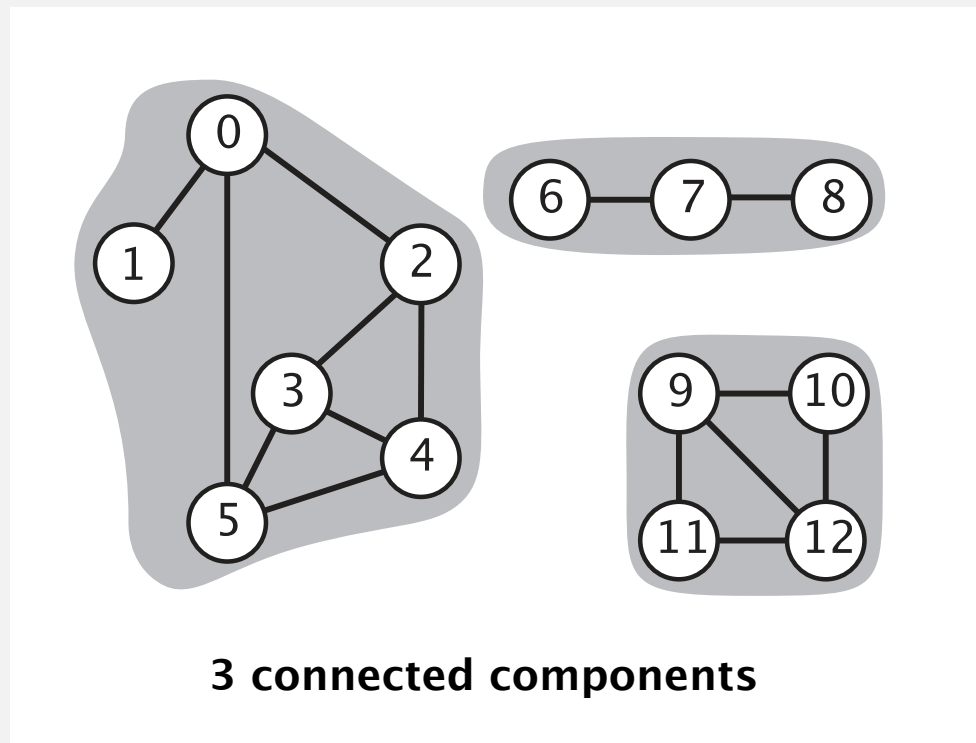
**Def.** A **strong component** is a maximal subset of strongly-connected vertices.



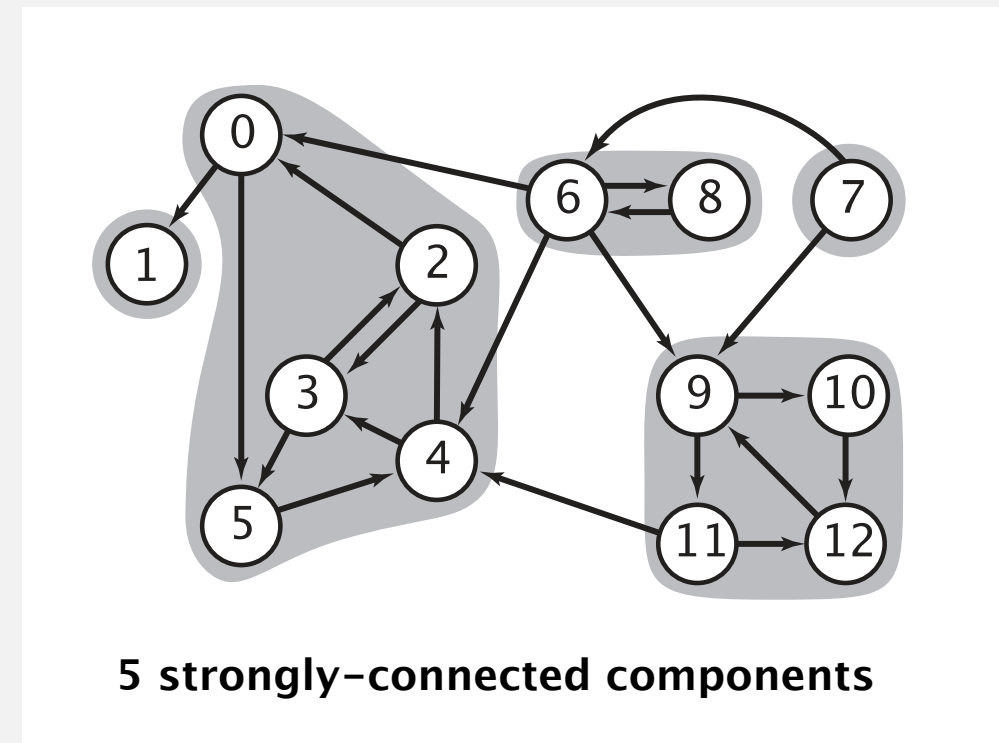
5 strongly-connected components

# Connected components vs. strongly-connected components

$v$  and  $w$  are **connected** if there is a path between  $v$  and  $w$



$v$  and  $w$  are **strongly connected** if there is both a directed path from  $v$  to  $w$  and a directed path from  $w$  to  $v$



connected component id (easy to compute with DFS)

	0	1	2	3	4	5	6	7	8	9	10	11	12
id[]	0	0	0	0	0	0	1	1	1	2	2	2	2

```
public boolean connected(int v, int w)
{ return id[v] == id[w]; }
```

constant-time client connectivity query

strongly-connected component id (how to compute?)

	0	1	2	3	4	5	6	7	8	9	10	11	12
id[]	1	0	1	1	1	1	3	4	3	2	2	2	2

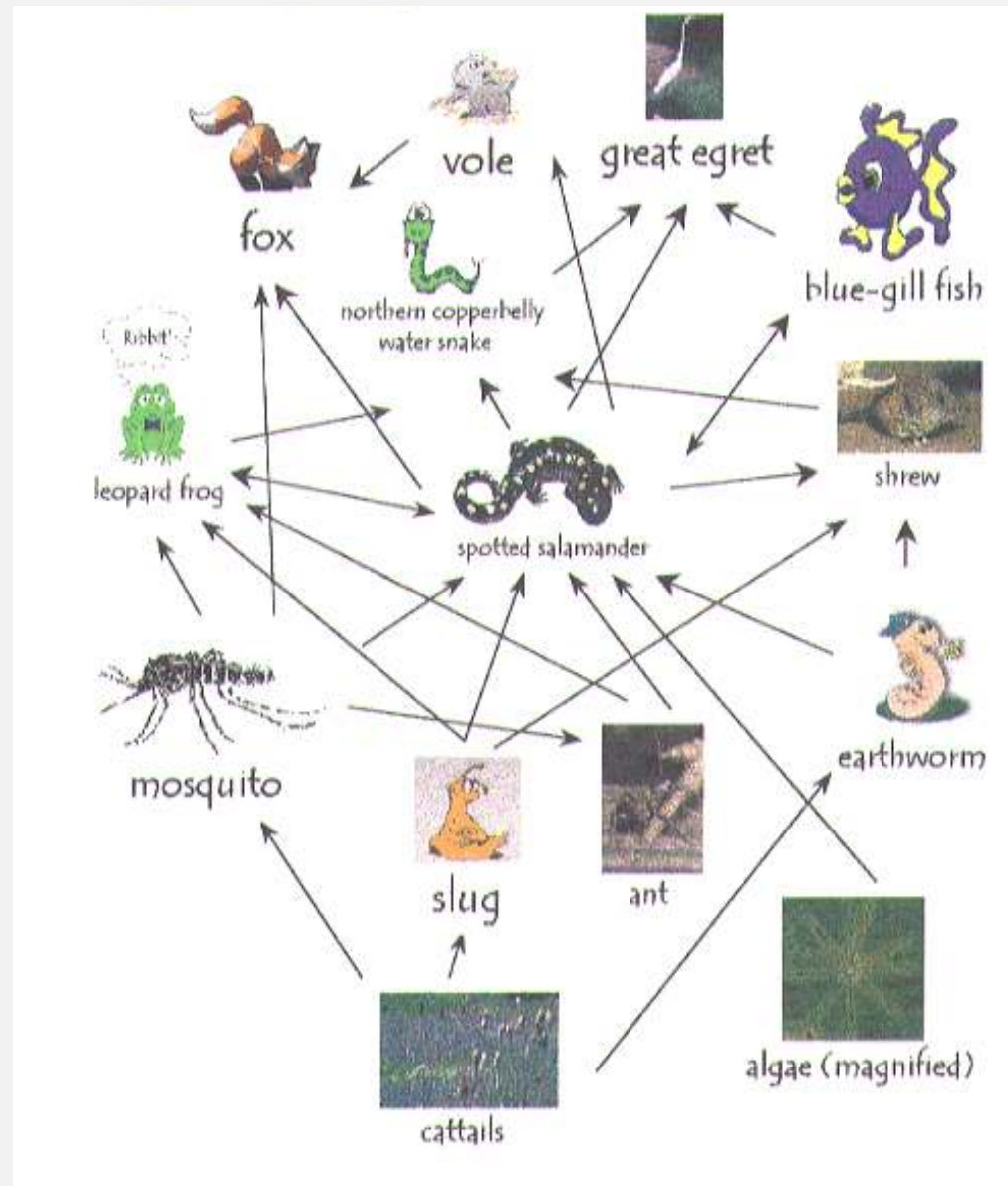
```
public boolean stronglyConnected(int v, int w)
{ return id[v] == id[w]; }
```

constant-time client strong-connectivity query

# Strong component application: ecological food webs

---

**Food web graph.** Vertex = species; edge = from producer to consumer.



<http://www.twingroves.district96.k12.il.us/Wetlands/Salamander/SalGraphics/salfoodweb.gif>

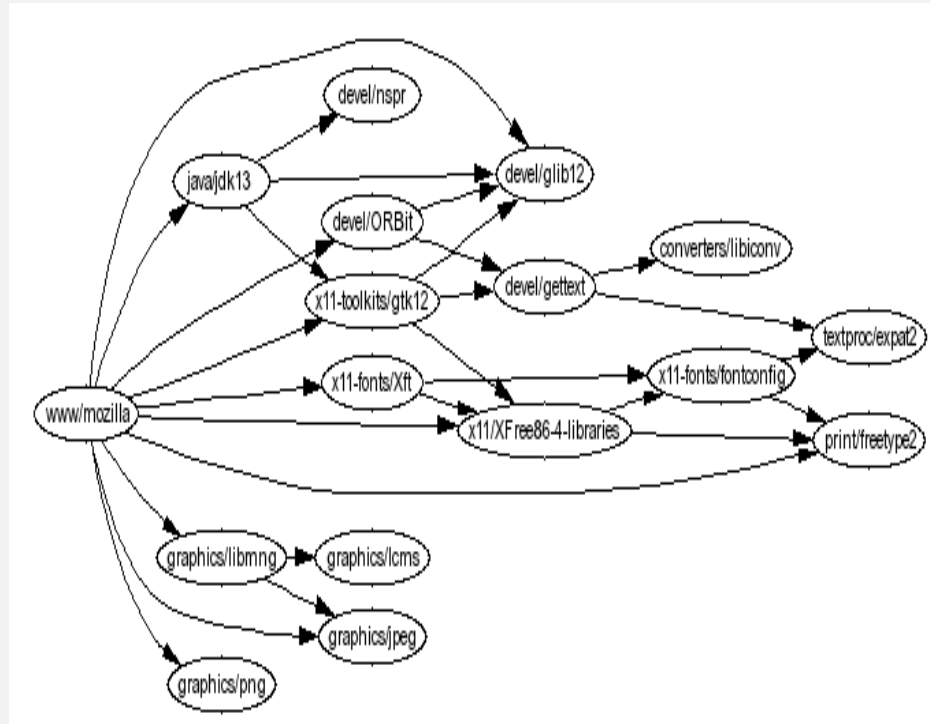
**Strong component.** Subset of species with common energy flow.



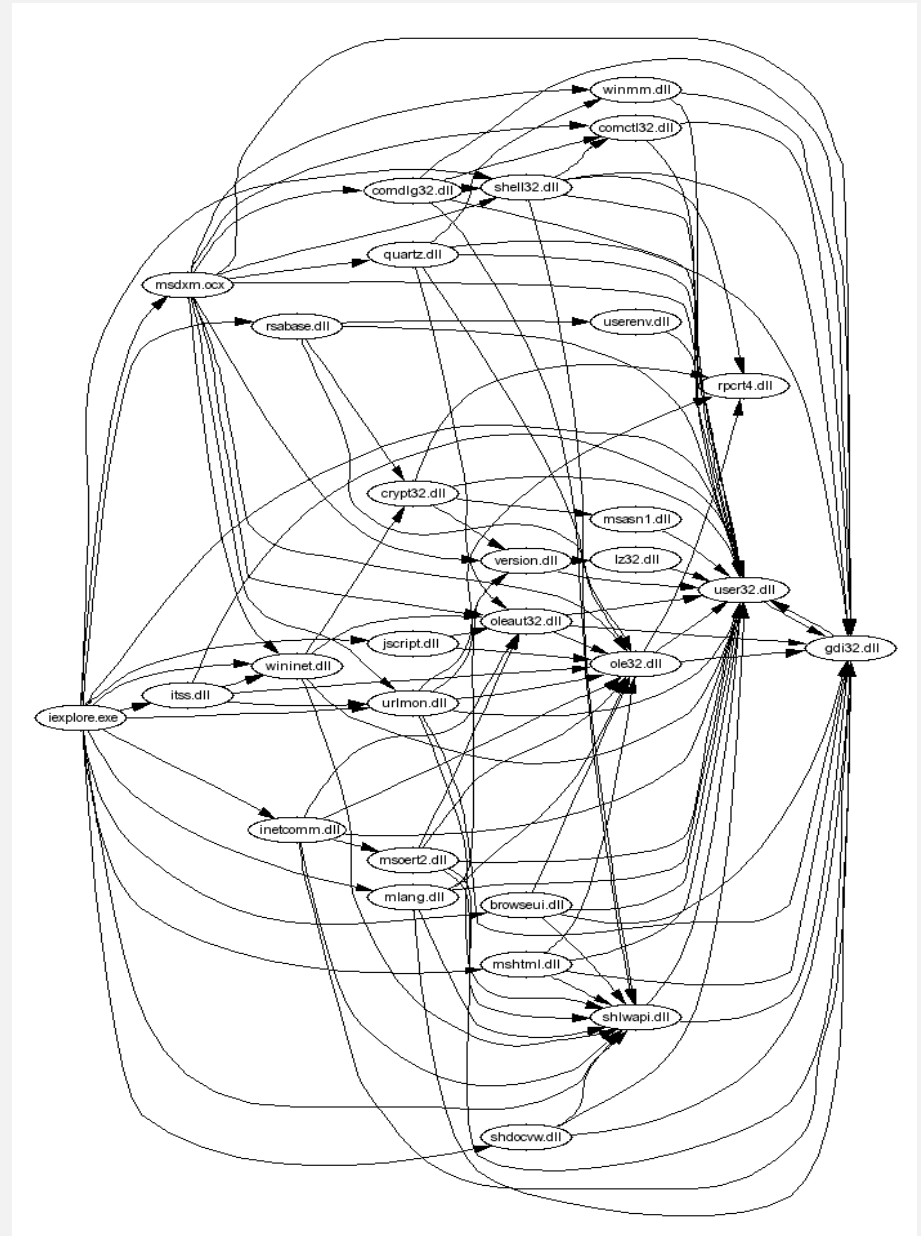
## Strong component application: software modules

# Software module dependency graph.

- Vertex = software module.
- Edge: from module to dependency.



# Firefox



## Internet Explorer

**Strong component.** Subset of mutually interacting modules.

## Approach 1. Package strong components together.

## Approach 2. Use to improve design!

# Strong components algorithms: brief history

---

## 1960s: Core OR problem.

- Widely studied; some practical algorithms.
- Complexity not understood.

## 1972: linear-time DFS algorithm (Tarjan).

- Classic algorithm.
- Level of difficulty: Algs4++.
- Demonstrated broad applicability and importance of DFS.

## 1980s: easy two-pass linear-time algorithm (Kosaraju-Sharir).

- Forgot notes for lecture; developed algorithm in order to teach it!
- Later found in Russian scientific literature (1972).

## 1990s: more easy linear-time algorithms.

- Gabow: fixed old OR algorithm.
- Cheriyan-Mehlhorn: needed one-pass algorithm for LEDA.

# Kosaraju-Sharir algorithm: intuition

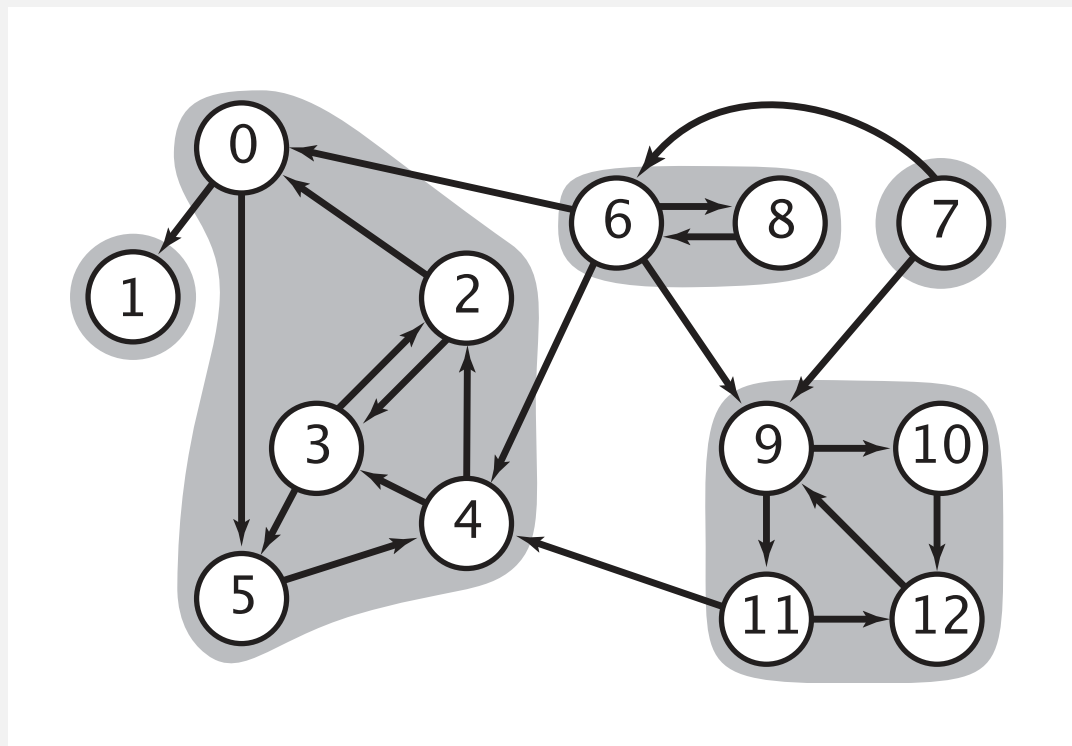
**Reverse graph.** Strong components in  $G$  are same as in  $G^R$ .

**Kernel DAG.** Contract each strong component into a single vertex.

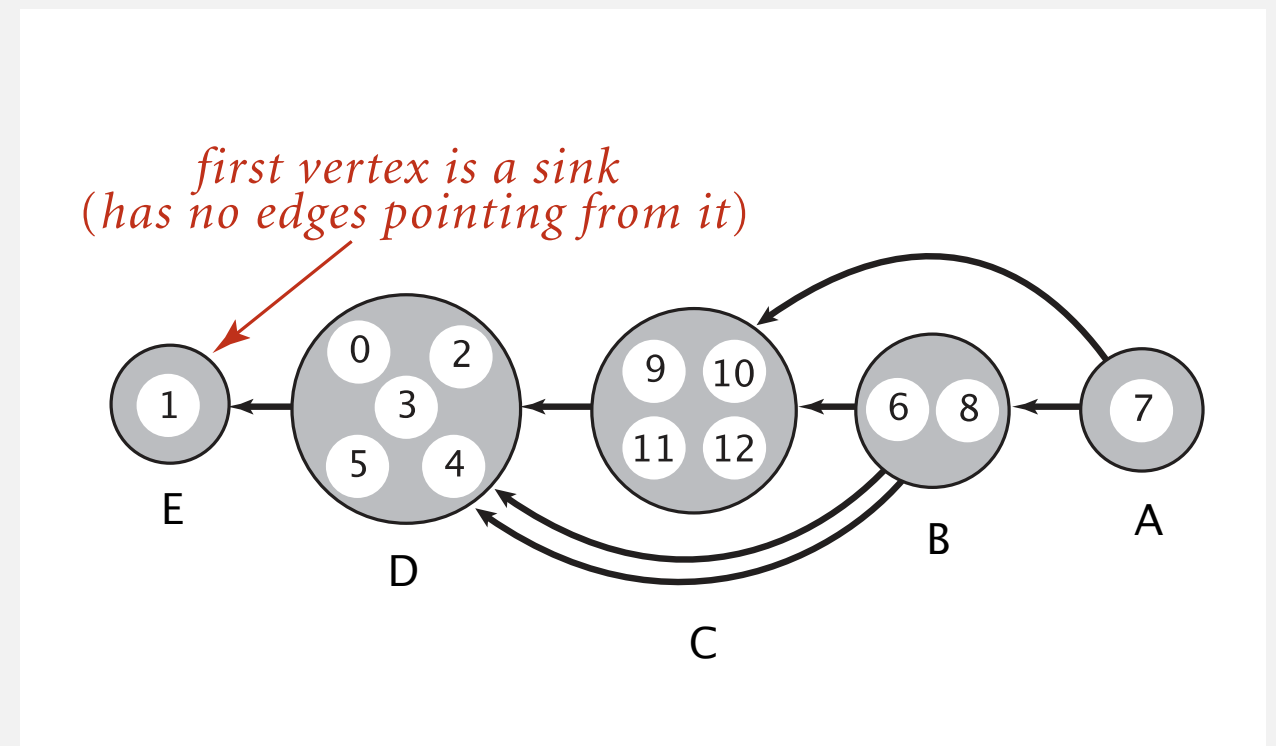
**Idea.**

- Compute topological order (reverse postorder) in kernel DAG.
- Run DFS, considering vertices in reverse topological order.

how to compute?  
↙



digraph  $G$  and its strong components



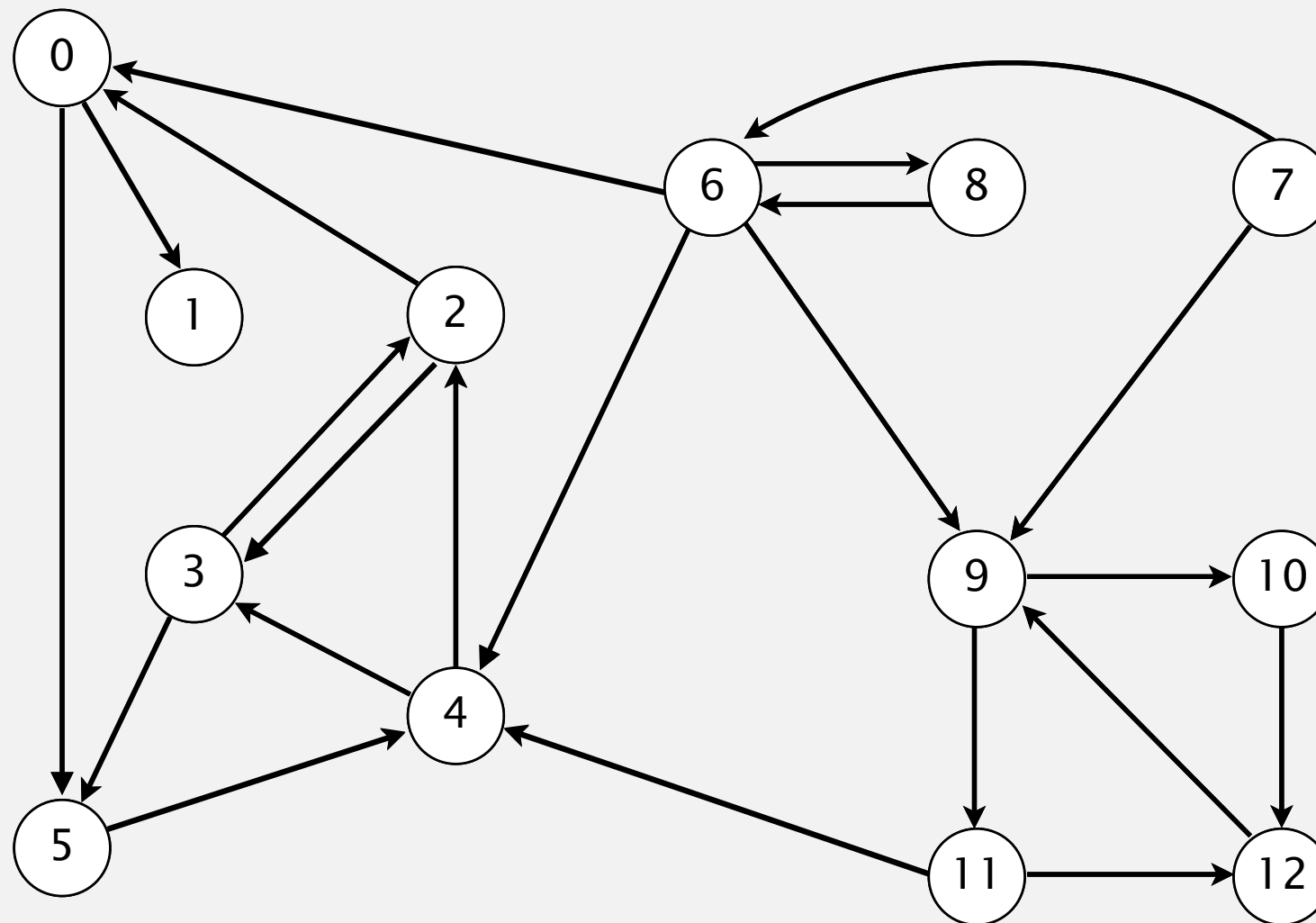
kernel DAG of  $G$  (topological order: A B C D E)

# Kosaraju-Sharir algorithm demo

---

Phase 1. Compute reverse postorder in  $G^R$ .

Phase 2. Run DFS in  $G$ , visiting unmarked vertices in reverse postorder of  $G^R$ .



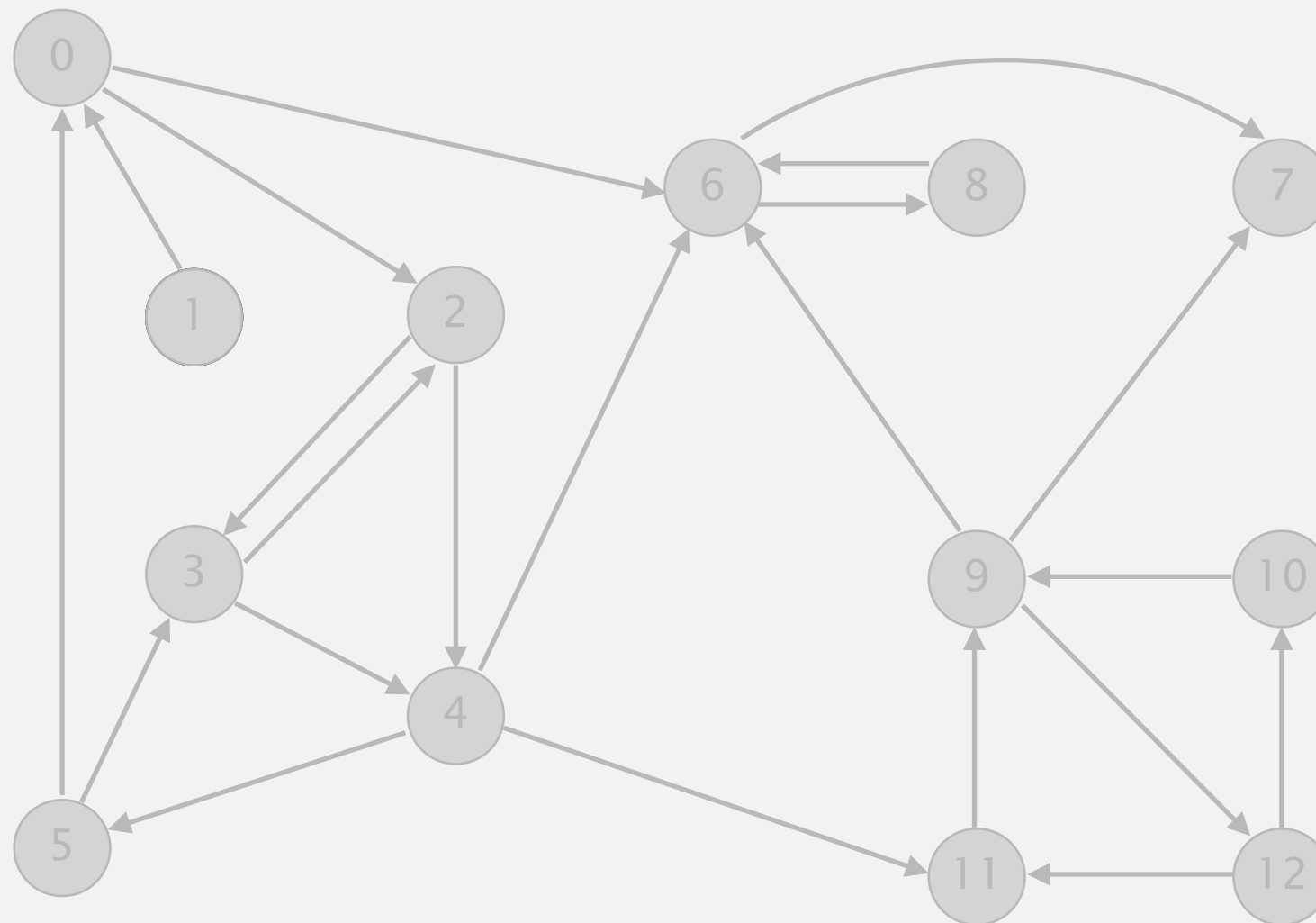
**digraph G**

# Kosaraju-Sharir algorithm demo

---

Phase 1. Compute reverse postorder in  $G^R$ .

1 0 2 4 5 3 11 9 12 10 6 7 8

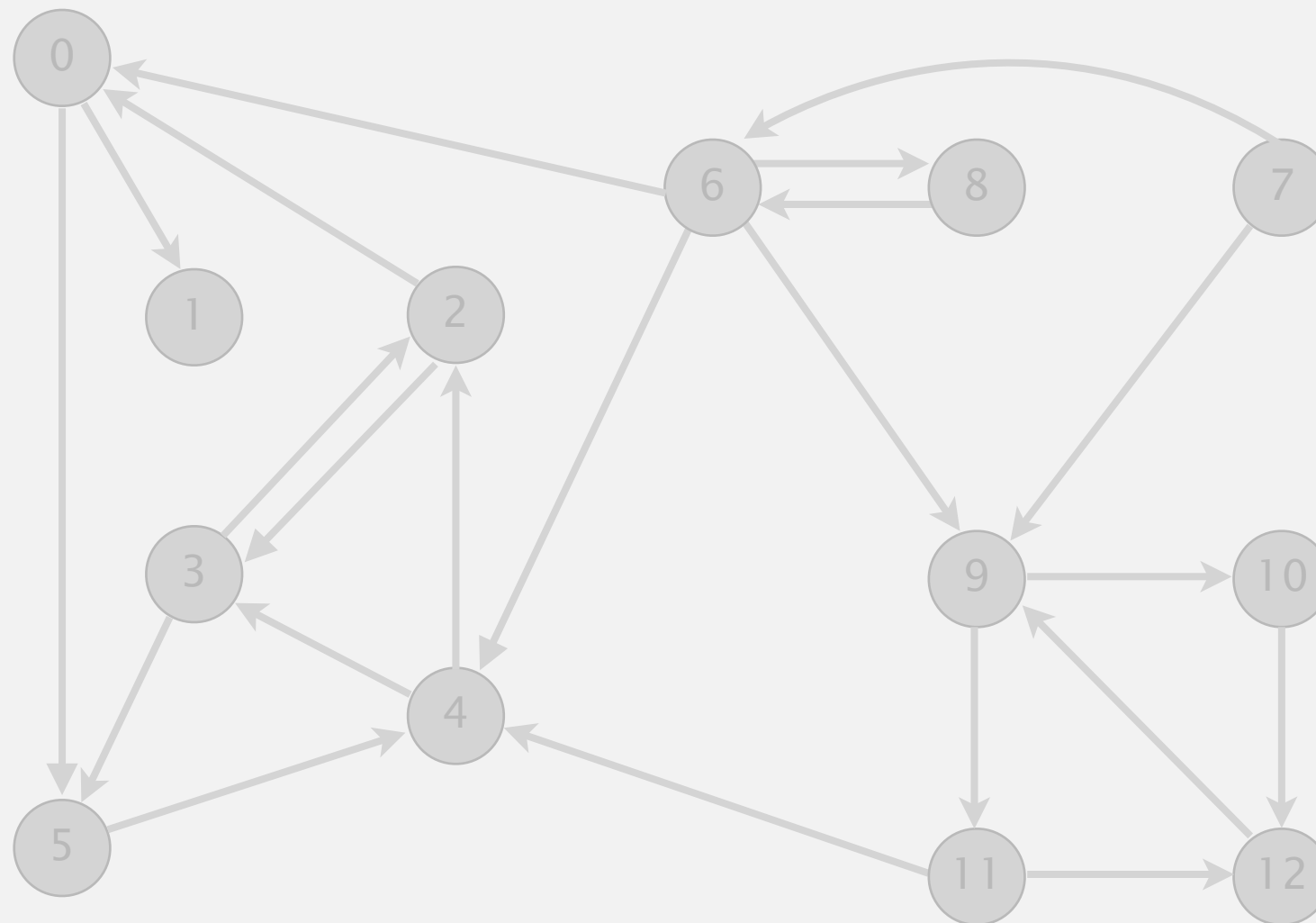


reverse digraph  $G^R$

# Kosaraju-Sharir algorithm demo

**Phase 2.** Run DFS in  $G$ , visiting unmarked vertices in reverse postorder of  $G^R$ .

1 0 2 4 5 3 11 9 12 10 6 7 8



v	id[]
0	1
1	0
2	1
3	1
4	1
5	1
6	3
7	4
8	3
9	2
10	2
11	2
12	2

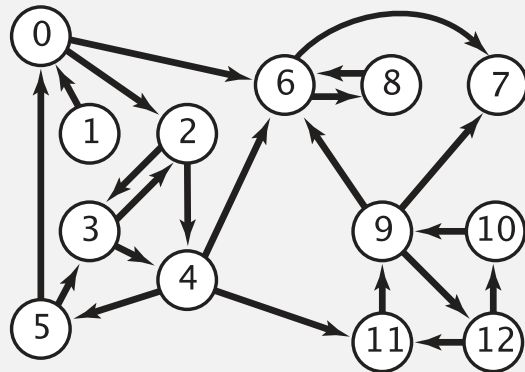
done

# Kosaraju-Sharir algorithm

Simple (but mysterious) algorithm for computing strong components.

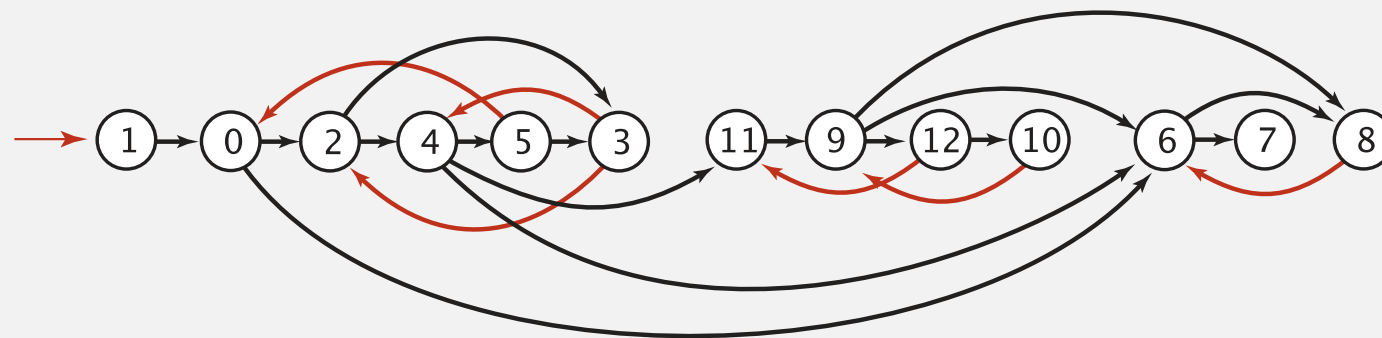
- Phase 1: run DFS on  $G^R$  to compute reverse postorder.
- Phase 2: run DFS on  $G$ , considering vertices in order given by first DFS.

## DFS in reverse digraph $G^R$



check unmarked vertices in the order

0 1 2 3 4 5 6 7 8 9 10 11 12



```
reverse postorder for use in second dfs()
1 0 2 4 5 3 11 9 12 10 6 7 8
```

```
dfs(0)
  dfs(6)
    dfs(8)
      | check 6
      8 done
    dfs(7)
      7 done
  6 done
  dfs(2)
    dfs(4)
      dfs(11)
        dfs(9)
          dfs(12)
            | check 11
            dfs(10)
              | check 9
              10 done
            12 done
          check 7
        check 6
```

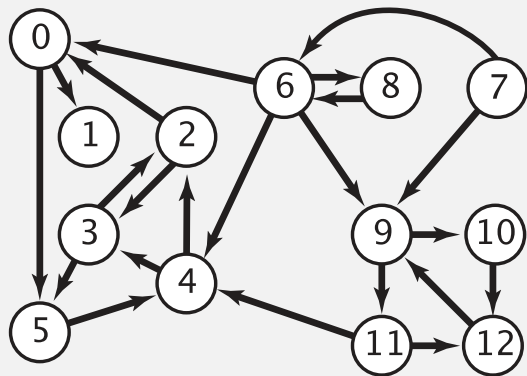


# Kosaraju-Sharir algorithm

Simple (but mysterious) algorithm for computing strong components.

- Phase 1: run DFS on  $G^R$  to compute reverse postorder.
- Phase 2: run DFS on  $G$ , considering vertices in order given by first DFS.

DFS in original digraph  $G$



check unmarked vertices in the order

1 0 2 4 5 3 11 9 12 10 6 7 8

↑↑

↑

↑↑

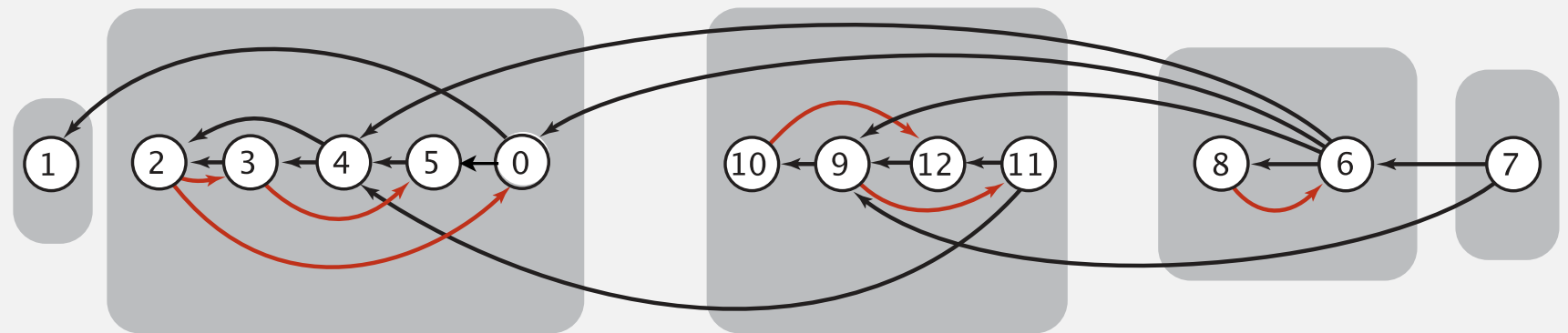
dfs(1)  
1 done

```
dfs(0)
  dfs(5)
    dfs(4)
      dfs(3)
        check 5
        dfs(2)
          check 0
          check 3
          2 done
        3 done
        check 2
        4 done
        5 done
        check 1
      0 done
      check 2
      check 4
      check 5
      check 3
```

```
dfs(11)
  check 4
  dfs(12)
    dfs(9)
      check 11
      dfs(10)
        check 12
        10 done
      9 done
    12 done
  11 done
  check 9
  check 12
  check 10
```

```
dfs(6)
  check 9
  check 4
  dfs(8)
    check 6
    8 done
  check 0
  6 done
```

```
dfs(7)
  check 6
  check 9
  7 done
  check 8
```



# Kosaraju-Sharir algorithm

---

**Proposition.** Kosaraju-Sharir algorithm computes the strong components of a digraph in time proportional to  $E + V$ .

**Pf.**

- Running time: bottleneck is running DFS twice (and computing  $G^R$ ).
- Correctness: tricky, see textbook (2<sup>nd</sup> printing).
- Implementation: easy!

# Connected components in an undirected graph (with DFS)

---

```
public class CC
{
    private boolean marked[];
    private int[] id;
    private int count;

    public CC(Graph G)
    {
        marked = new boolean[G.V()];
        id = new int[G.V()];

        for (int v = 0; v < G.V(); v++)
        {
            if (!marked[v])
            {
                dfs(G, v);
                count++;
            }
        }
    }

    private void dfs(Graph G, int v)
    {
        marked[v] = true;
        id[v] = count;
        for (int w : G.adj(v))
            if (!marked[w])
                dfs(G, w);
    }

    public boolean connected(int v, int w)
    { return id[v] == id[w]; }
}
```

# Strong components in a digraph (with two DFSs)

---

```
public class KosarajuSharirSCC
{
    private boolean marked[];
    private int[] id;
    private int count;

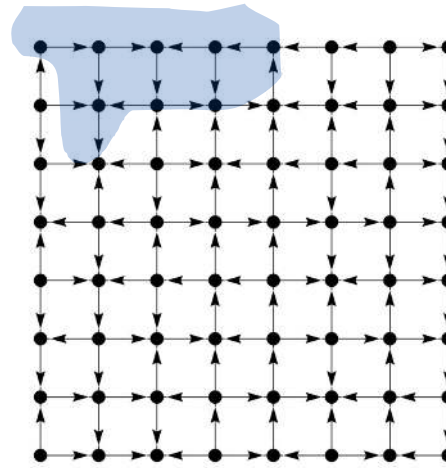
    public KosarajuSharirSCC(Digraph G)
    {
        marked = new boolean[G.V()];
        id = new int[G.V()];
        DepthFirstOrder dfs = new DepthFirstOrder(G.reverse());
        for (int v : dfs.reversePostorder())
        {
            if (!marked[v])
            {
                dfs(G, v);
                count++;
            }
        }
    }

    private void dfs(Digraph G, int v)
    {
        marked[v] = true;
        id[v] = count;
        for (int w : G.adj(v))
            if (!marked[w])
                dfs(G, w);
    }

    public boolean stronglyConnected(int v, int w)
    { return id[v] == id[w]; }
}
```

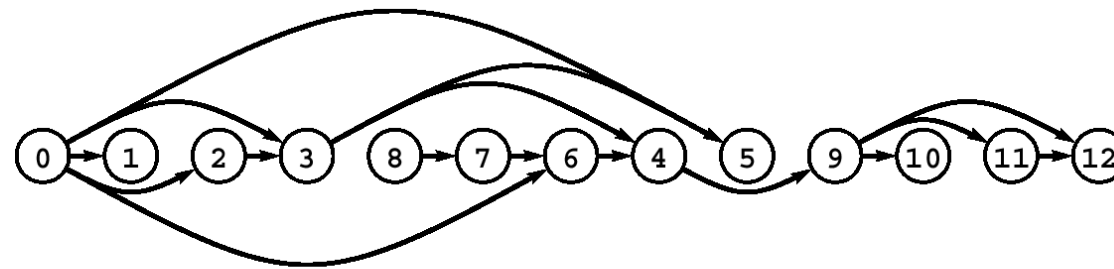
# Digraph-processing summary: algorithms of the day

**single-source  
reachability  
in a digraph**



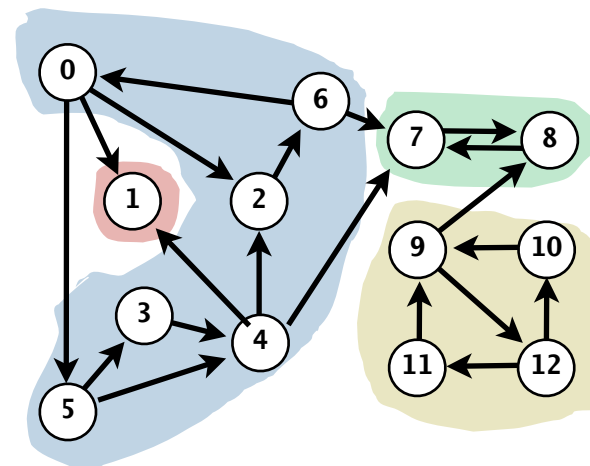
DFS

**topological sort  
in a DAG**



DFS

**strong  
components  
in a digraph**



Kosaraju-Sharir  
DFS (twice)