# **Electronic Circuits Elektronik Devreler**

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# **Electronic systems**

- Introduction
- Electronic systems
- Distortion and noise
- System design.

#### Introduction

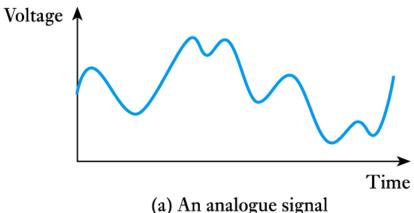
- The world in which we live is constantly changing.
- To survive, we need to respond to changes in our environment.
  - To respond we sense a changing quantity (the input).
  - And modify some other quantity (the **output**).
- We often use machines to respond on our behalf.
  - The nature of these machines is that they sense some input quantity, process the information, and then control some output quantity.

#### **Introduction (contd.)**

- The world about us is characterised by a number of physical properties or quantities.
  - e.g. temperature, pressure, humidity, etc.
- Physical quantities may be *continuous* or *discrete*.
- Continuous quantities change smoothly and can take an infinite number of values.
- Discrete quantities change abruptly from one value to another.
  - Most real-world quantities are continuous.
  - Many man-made quantities are discrete.

#### Introduction (contd.)

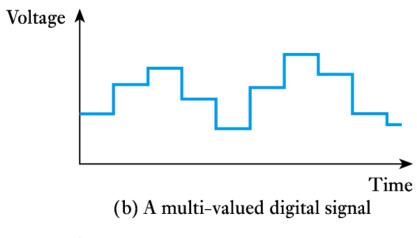
- It is often convenient to represent physical quantities by electrical signals. These can also be continuous or discrete.
- Continuous signals are often described as analogue.

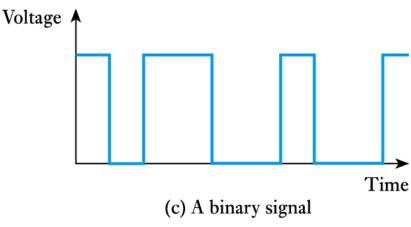


#### Introduction (contd.)

 Discrete signals are often described as digital signals.

 Many digital signals take only two values and are referred to as binary signals.





## **Electronic systems**

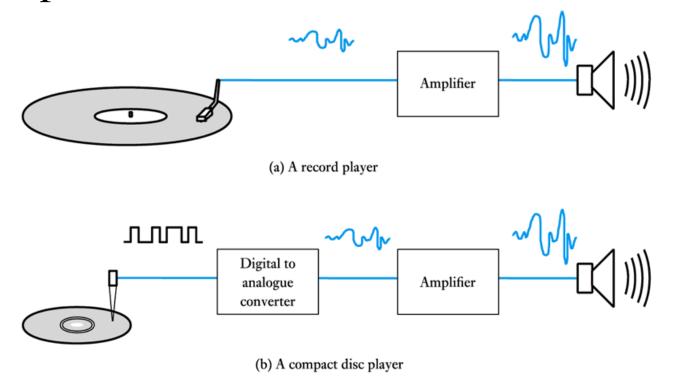
A system can be defined as

Any closed volume for which all the inputs and output are known.

- Examples include:
  - an engine management system
  - an automotive system
  - a transportation system
- Inputs and outputs will reflect the nature of the system.

## Electronic systems (contd.)

• Electronic systems can take many forms, for example.

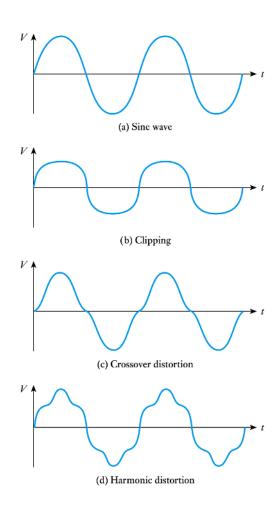


#### Electronic systems (contd.)

- Components that interact with the outside world are termed sensors and actuators.
  - In the previous examples the pickup or laser scanner represents a sensor.
  - In the previous examples the loudspeaker represents an actuator.
- We will look at sensors and actuators in more detail in later lectures.

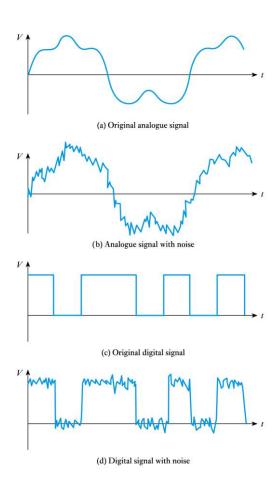
#### Distortion and noise

- All systems distort electrical signal to some extent
  - examples include clipping, crossover distortion and harmonic distortion.
- Distortion is systematic and is repeatable.



#### Distortion and noise (contd.)

- All systems also add noise to the signals that pass through them.
- Unlike distortion, noise is random and not repeatable.
- Noise can often be removed from digital signals but this is often impossible with analogue signals.



# System design

- The task of designing an electronic system can be simplified by adopting a methodical approach.
- Generally this involves a top-down approach.
  - Customer requirements
  - Top-level specification
  - Choice of technology
  - Top-level design
  - Detailed design
  - Module construction and testing
  - System testing.

# System design (contd.)

- Electronic design aids
  - schematic capture
  - circuit simulation
  - PCB or VLSI layout packages.
- Circuit simulation greatly assists our understanding of the operation of a circuit.
  - Common examples include PSpice and Multisim.

## **Key points**

- Systems interact with the world using sensors and actuators.
- Physical quantities can be either continuous or discrete.
- Physical quantities are often represented by signals.
- Useful electronic systems take input signals, process this information and produce appropriate outputs.
- Distortion and noise are always present.
- System design normally follows a top-down approach.
- Electronic design tools, such as simulators, are invaluable.