

Yapay Sinir Ağları

Sınıflandırma Teknikleri

- Uzaklık Temelli (Nearest-Neighbor) yöntemler
- Karar Ağacı(Decision Tree) yöntemleri
- Olasılık temelli yöntemler (Naïve Bayes)
- Support Vector Machines
- Yapay Sinir Ağları (Artificial Neural Networks)
- Ensemle Yöntemler (Bagging Boosting)
 - Rastgele Ormanlar (Random Forest)
 - AdaBoost ve XGBoost(eXtreme Gradient Boosting)

Artificial Neural Networks/Deep Learning

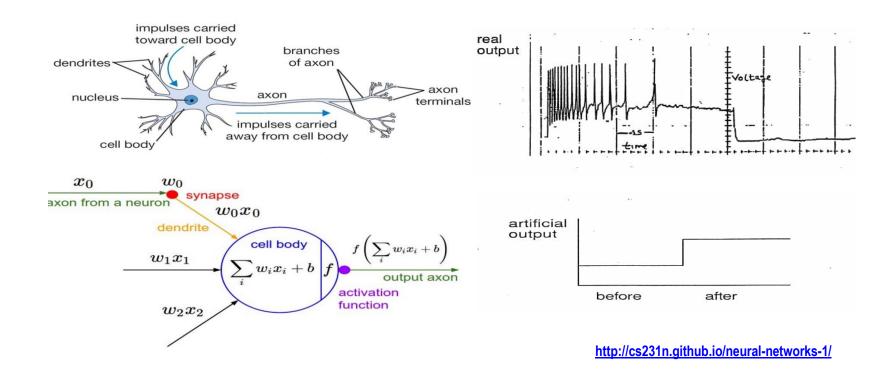
Neural Network Türleri

- Multi Layer Perceptron
- Recurrent neural network
- Convolutional neural network

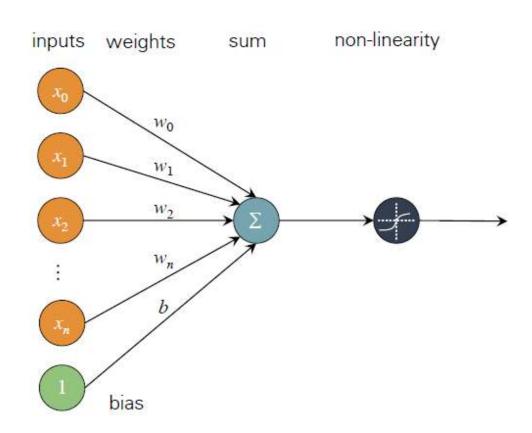
Neural Networks Uygulamaları

- El yazısı karakter tanımlama.
- Görüntü işleme.
- Borsa stok tahmini
- ve binlerce farklı uygulama

"Gerçek" ve Yapay Nöron



Perceptron



Perceptron Forward Pass

 Neuron pre-activation (or input activation)

$$a(\mathbf{x}) = b + \sum_{i} w_i x_i = b + \mathbf{w}^{\top} \mathbf{x}$$

Neuron output activation:

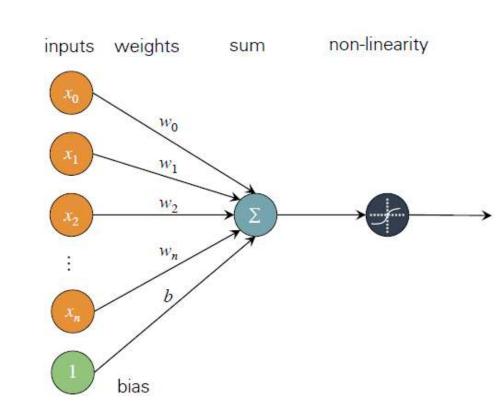
$$h(\mathbf{x}) = g(a(\mathbf{x})) = g(b + \sum_{i} w_i x_i)$$

where

w are the weights (parameters)

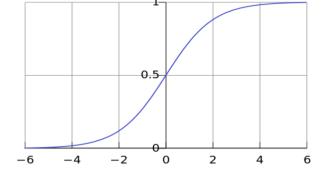
b is the bias term

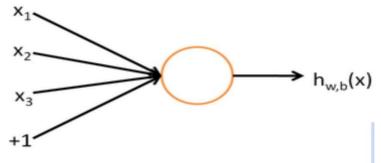
 $g(\cdot)$ is called the activation function



Tek bir nöron logistic regression oluşturur

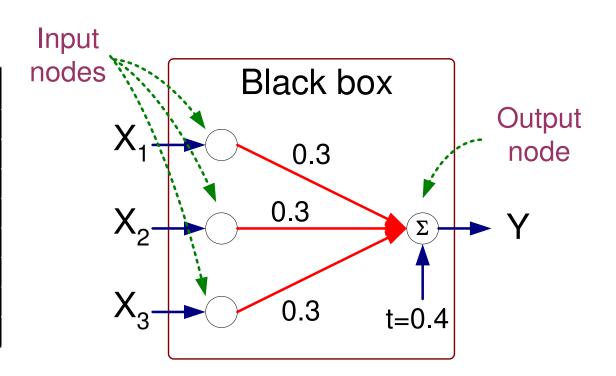
$$h_{w,b}(x) = f(w^{\mathsf{T}}x + b) \longleftarrow$$
$$f(z) = \frac{1}{1 + e^{-z}}$$





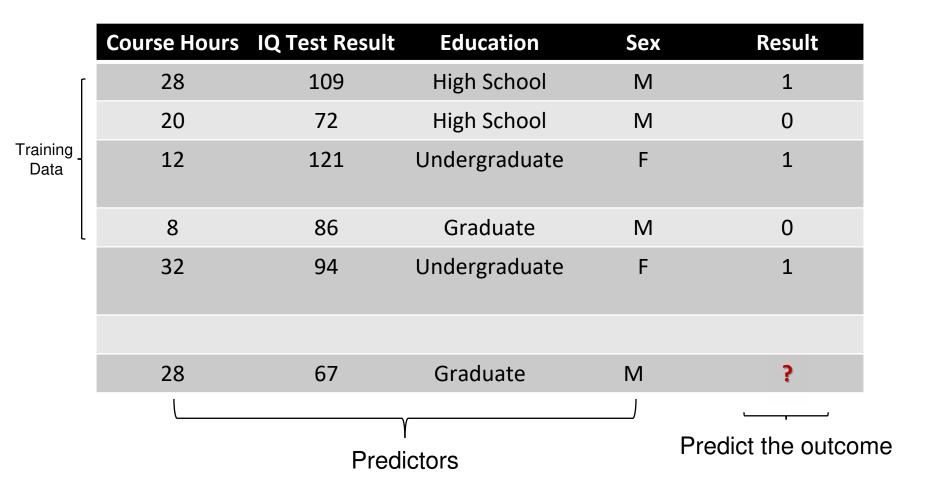
Artificial Neural Networks (ANN)

X ₁	X ₂	X ₃	Υ
1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1
0	0	1	0
0	1	0	0
0	1	1	1
0	0	0	0

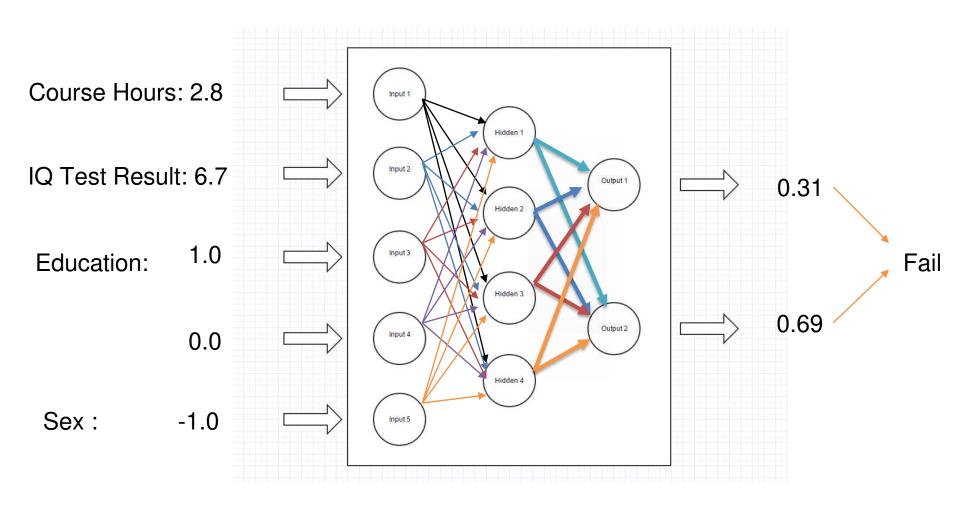


$$Y = I(0.3X_1 + 0.3X_2 + 0.3X_3 - 0.4 > 0)$$
where
$$I(z) = \begin{cases} 1 & \text{if } z \text{ is true} \\ 0 & \text{otherwise} \end{cases}$$

Neural Network



Network



Perceptron Forward Pass

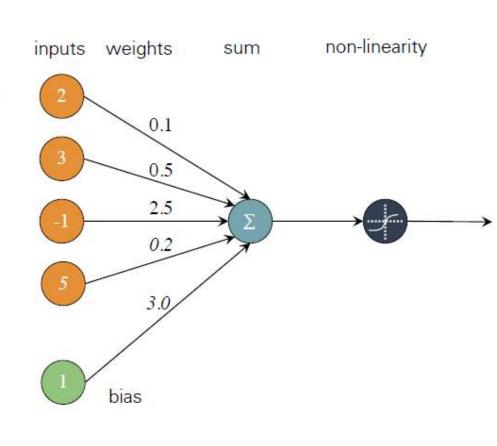
$$h(\mathbf{x}) = g(a(\mathbf{x})) = g(b + \sum_{i} w_{i}x_{i})$$

$$h(\mathbf{x}) = g(2*0.1) + (3*0.5) + (-1*2.5) + (5*0.2) + (1*3.0)$$

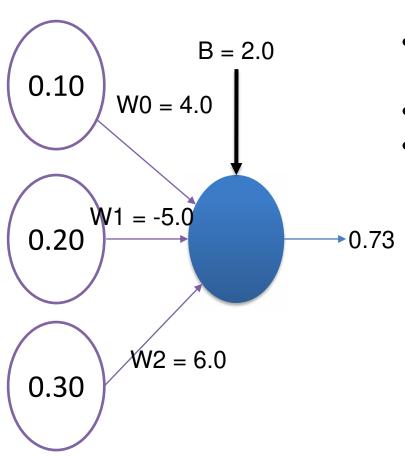
$$)$$

$$h(\mathbf{x}) = g(3.2) = \sigma(3.2)$$

$$\frac{1}{1 + e^{-3.2}} = 0.96$$



Feed-Forward ve Aktivasyon

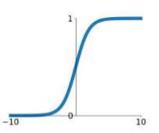


- 0.10*4.0 + 0.20*-5.0 + 0.30*6.0 + 2.0*1 = 3.2
- Activation(3.2) = 0.73
- Output = 0.73

Activation Functions

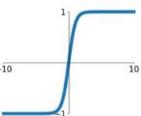
Sigmoid

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



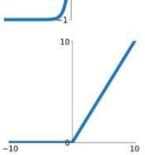
tanh

tanh(x)



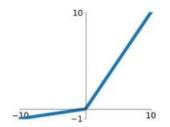
ReLU

 $\max(0,x)$



Leaky ReLU

 $\max(0.1x, x)$

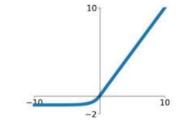


Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

ELU

$$\begin{cases} x & x \ge 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



Multi-Layer Perceptron(MLP)

Hidden layer pre-activation:

$$\mathbf{a}(\mathbf{x}) = \mathbf{b}^{(1)} + \mathbf{W}^{(1)}\mathbf{x}$$

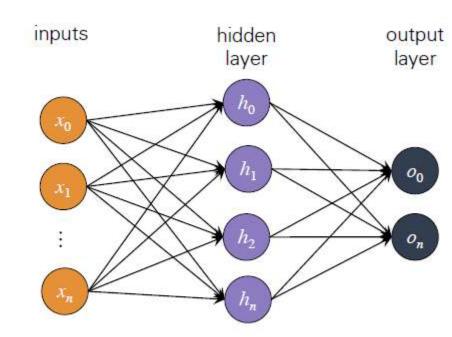
 $\left(a(\mathbf{x})_i = b_i^{(1)} + \sum_j W_{i,j}^{(1)} x_j\right)$

Hidden layer activation:

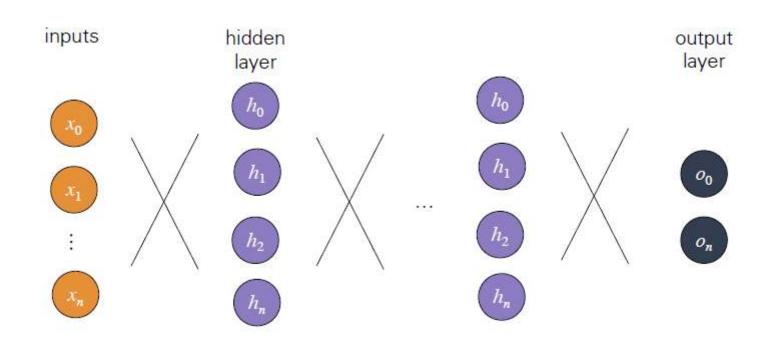
$$\mathbf{h}(\mathbf{x}) = \mathbf{g}(\mathbf{a}(\mathbf{x}))$$

Output layer activation:

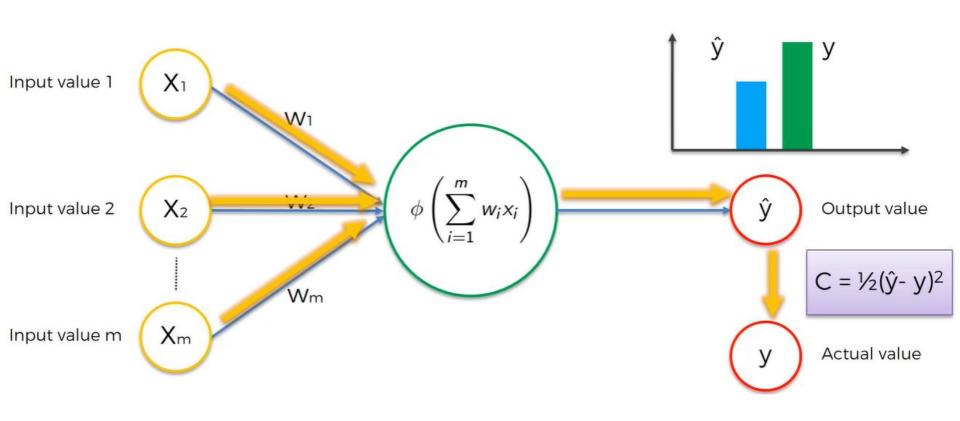
$$\mathbf{o}(\mathbf{x}) = \mathbf{o}\left(b^{(2)} + \mathbf{w}^{(2)}\mathbf{h}^{(1)}\mathbf{x}\right)$$



Deep Neural Networks (DNN)



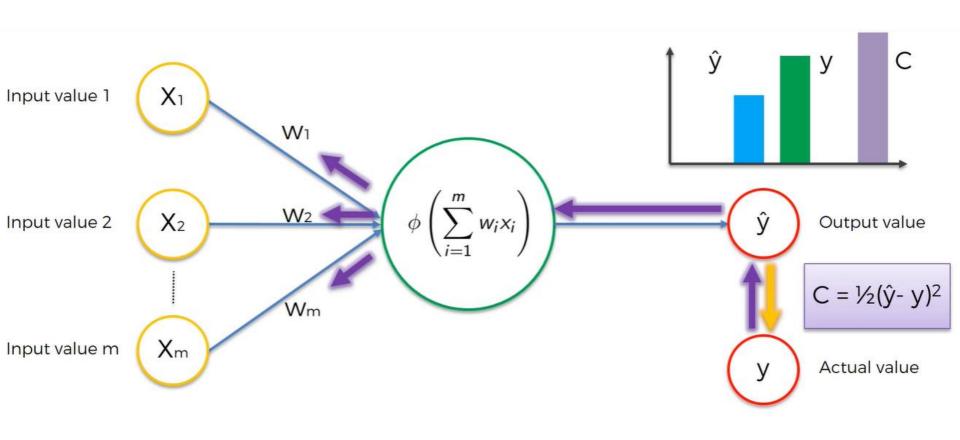
Training(Feed Forward)



Error ve Accuracy

- Mean Squared Error
- $E_{total} = \sum_{i=1}^{1} (target output)^2$

Training(Back Propagation)



Training

$$J(\theta) = \arg\min_{\theta} \frac{1}{T} \sum_{t} l(f(\mathbf{x}^{(t)}; \theta), y^{(t)}) + \lambda \Omega(\theta)$$

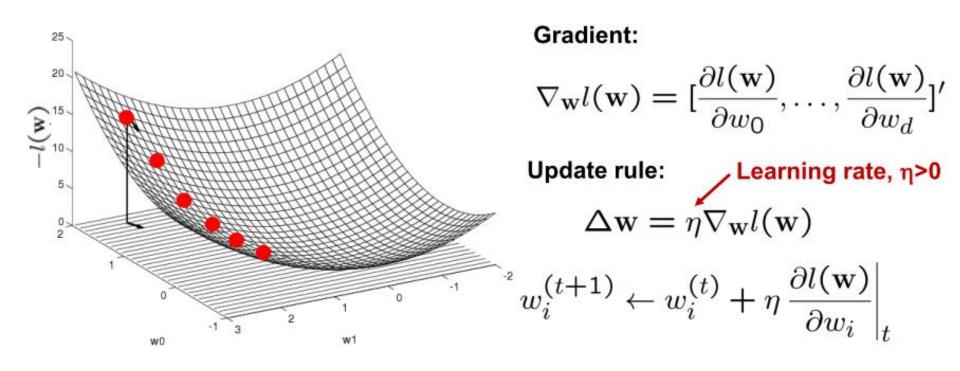
$$Loss function Regularizer$$

$$\theta = W_1, W_2...W_n$$

- Learning is cast as optimization.
 - For classification problems, we would like to minimize classification error
 - Loss function can sometimes be viewed as a surrogate for what we want to optimize (e.g. upper bound)

Gradient descent

Optimizing convex function: Gradient descent (convex)



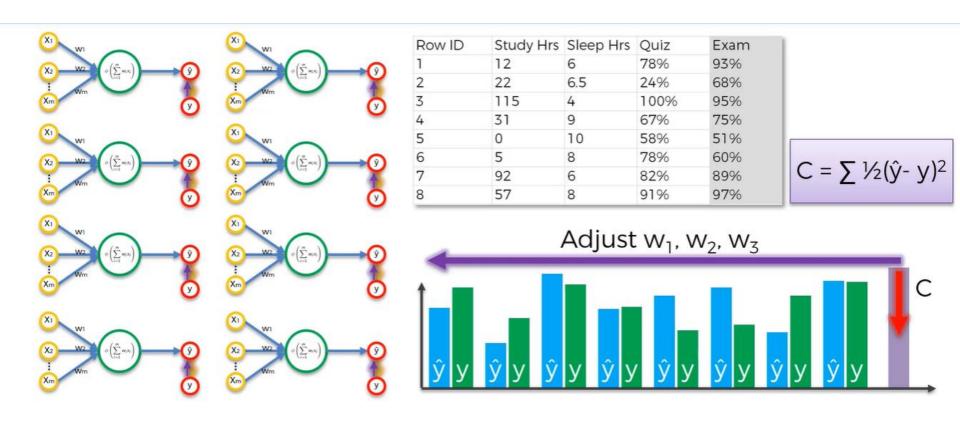
Training (Back Propagation)

W₁₀ ağırlık değerini değiştirmenin etkisini bulma

$$\frac{d E_{total}}{d W_{10}} = \frac{d E_{total}}{d out_{O_1}} * \frac{d out_{O_1}}{d in_{O_1}} * \frac{d in_{O_1}}{d W_{10}}$$

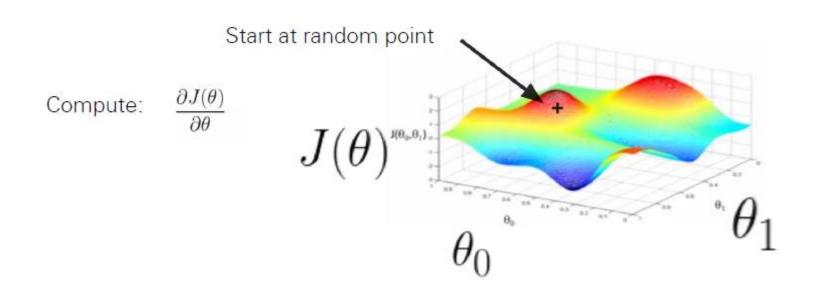
$$W_{11} \qquad \qquad W_{10} \qquad \qquad W_{10} \qquad \qquad W_{10} \qquad \qquad W_{10} \qquad \qquad W_{11} \qquad \qquad W_{11} \qquad \qquad W_{10} \qquad \qquad W_{11} \qquad \qquad W_{12} \qquad \qquad W_{13} \qquad \qquad W_{14} \qquad \qquad W_{15} \qquad \qquad W_{15}$$

Training(Back Propagation)



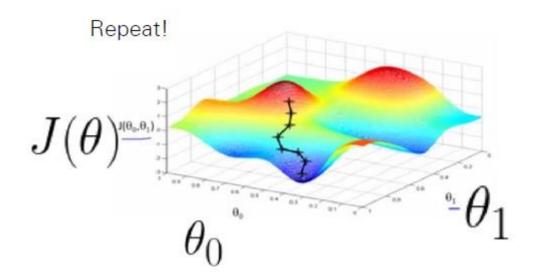
Training

Loss, modelin ağırlık parametreleri fonksiyonudur. Nasıl minimize edilir?



Stochastic Gradient Descent (SGD)

Loss, azalan yönde iterative şekilde ilerler



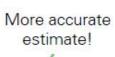
Stochastic Gradient Descent (SGD)

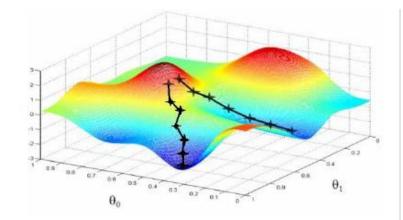
- Initialize θ randomly
- For N Epochs
 - For each training batch $\{(x_0, y_0), \dots, (x_B, y_B)\}$:
 - · Compute Loss Gradient:

$$\frac{\partial J(\theta)}{\partial \theta} = \frac{1}{B} \sum_{i}^{B} \frac{\partial J_{i}(\theta)}{\partial \theta}$$

• Update θ with update rule:

$$\theta := \theta - \eta \frac{\partial J(\theta)}{\partial \theta}$$





Advantages:

- More accurate estimation of gradient
 - Smoother convergence
 - Allows for larger learning rates
- · Minibatches lead to fast training!
 - Can parallelize computation + achieve significant speed increases on GPU's

Neural Network Sınıflandırıcı

Zayıflıkları

- Uzun eğitim süresi
- Ağ topolojisi veya "yapı" gibi tipik olarak en iyi deneysel olarak belirlenen bir dizi parametre gerektirir.
- Kötü yorumlanabilirlik: Öğrenilen ağırlıkların ve ağdaki "gizli birimlerin" arkasındaki sembolik anlamı yorumlamak zordur

Güçlü tarafları

- Noise verilere toleransı yüksek
- Eğitim setinde görülmemiş kalıpları sınıflandırma yeteneği
- Sürekli değerli girdi ve çıktılar için çok uygun
- Çok çeşitli gerçek dünya verileri üzerinde başarılı
- Algoritmalar doğası gereği paraleldir
- Sinir ağlarından kuralların çıkarılması için son zamanlarda teknikler geliştirilmiştir.

Deep learning kullanılmalı?

- Çok noise varsa ve sorunun yapısı basitse -> hayır kullanma
- Az noise varsa ve sorunun yapısı karmaşıksa-> evet, deep learning kullan
- İyi ve basit bir temel algoritma ile başlamak faydalı:
 - Hangi algoritmayı iyi biliyorsanız onunla başlayın
 - Logistic regression, SVM, boosted decision tree gayet iyi çalışan yöntemler